

Table 1.3: Data structures

| Data structure | Key points |
|---------------------|--|
| Primitive types | Know how <code>int</code> , <code>char</code> , <code>double</code> , etc. are represented in memory and the primitive operations on them. |
| Arrays | Fast access for element at an index, slow lookups (unless sorted) and insertions. Be comfortable with notions of iteration, resizing, partitioning, merging, etc. |
| Strings | Know how strings are represented in memory. Understand basic operators such as comparison, copying, matching, joining, splitting, etc. |
| Lists | Understand trade-offs with respect to arrays. Be comfortable with iteration, insertion, and deletion within singly and doubly linked lists. Know how to implement a list with dynamic allocation, and with arrays. |
| Stacks and queues | Recognize where last-in first-out (stack) and first-in first-out (queue) semantics are applicable. Know array and linked list implementations. |
| Binary trees | Use for representing hierarchical data. Know about depth, height, leaves, search path, traversal sequences, successor/predecessor operations. |
| Heaps | Key benefit: $O(1)$ lookup find-max, $O(\log n)$ insertion, and $O(\log n)$ deletion of max. Node and array representations. Min-heap variant. |
| Hash tables | Key benefit: $O(1)$ insertions, deletions and lookups. Key disadvantages: not suitable for order-related queries; need for resizing; poor worst-case performance. Understand implementation using array of buckets and collision chains. Know hash functions for integers, strings, objects. |
| Binary search trees | Key benefit: $O(\log n)$ insertions, deletions, lookups, find-min, find-max, successor, predecessor when tree is height-balanced. Understand node fields, pointer implementation. Be familiar with notion of balance, and operations maintaining balance. |

of the input size. Specifically, the run time of an algorithm on an input of size n is $O(f(n))$ if, for sufficiently large n , the run time is not more than $f(n)$ times a constant.

As an example, searching for a given integer in an unsorted array of integers of length n via iteration has an asymptotic complexity of $O(n)$ since in the worst-case, the given integer may not be present.

Complexity theory is applied in a similar manner when analyzing the space requirements of an algorithm. The space needed to read in an instance is not included; otherwise, every algorithm would have $O(n)$ space complexity. An algorithm that uses $O(1)$ space should not perform