



ELISA
Enabling **Linux** in
Safety Applications

WORKSHOP

NASA Goddard

F Prime and Linux

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Introduction



About the Speaker

- Flight Software Engineer at NASA Jet Propulsion Laboratory
- Community Manager of the F Prime Flight Software Product Line
- Open-Source advocate
- Downlink and Tools lead for the Ingenuity Mars Helicopter



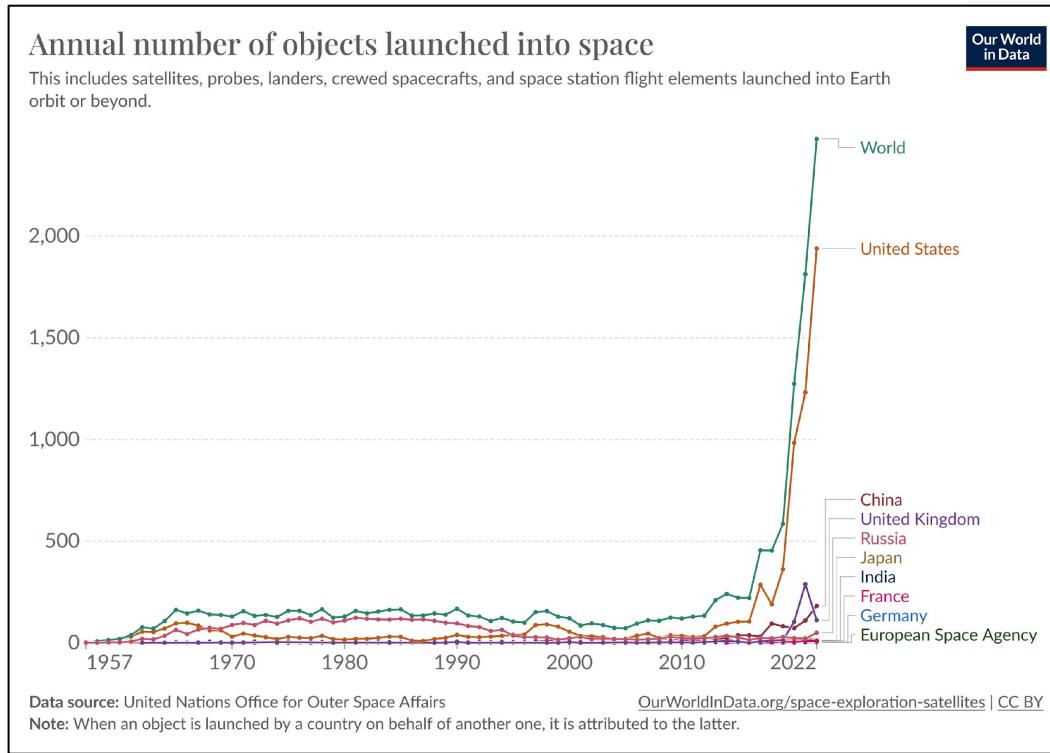
Agenda

- What is F Prime?
 - A New Paradigm for Space
 - The F Prime Product Line
 - What is F Prime?
 - F Prime Streamlines Flight Software Development
- F Prime and Linux
 - F Prime and Operating Systems
 - F Prime and Linux: Ingenuity Mars Helicopter
 - Ingenuity System Design
- Linux Lessons Learned
 - Linux Supports Efficient Development
 - Plan for Robustness
 - Remember Its Linux!
- Questions

What is F Prime?



A New Paradigm for Space



The F Prime Product Line

The F Prime Software Product Line targets flight missions



- Flight systems
- Particularly well suited for small-scale flight systems, i.e. CubeSats or SmallSats



- Flight instruments and/or sensors requiring software developed for a dedicated processing platform



- Flight “deployables” – freely operating spaceborne flight systems deployed by spacecraft in support of a mission
- Ex. A planetary lander or helicopter

Additionally, F Prime supports



- Simulation and SSE development requiring embedded software



- Software technology development with intended path to flight

F Prime is Open-Source!

What is F Prime?



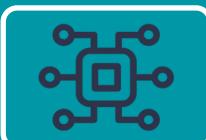
Software Architecture

- Provides modular components with well-defined interfaces that communicate over ports
- Enables rapid development, portability, high performance, reusability, analyzability, testability



C++ Framework

- Implements the F' architecture
- Provides basic features such as message queues, threading, and OS abstraction



Component Library

- Provides generic components for common capabilities, e.g., command dispatch
- Usable without modification in new software projects



Tool Suite

- Tools for specifying components and connections, automatically generating code
- Tools for FSW unit and integration testing, including a lightweight ground data system

F Prime Streamlines Flight Software Development

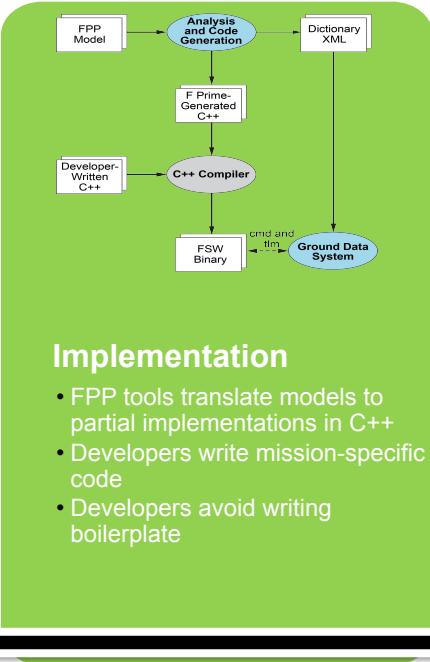
```
1 passive component TcpClient {  
2   output port $recv: Drv.ByteStringRecv  
3 }
```

```
1 connections Uplink {  
2   comm.$recv -> uplink.framedIn  
3 }
```



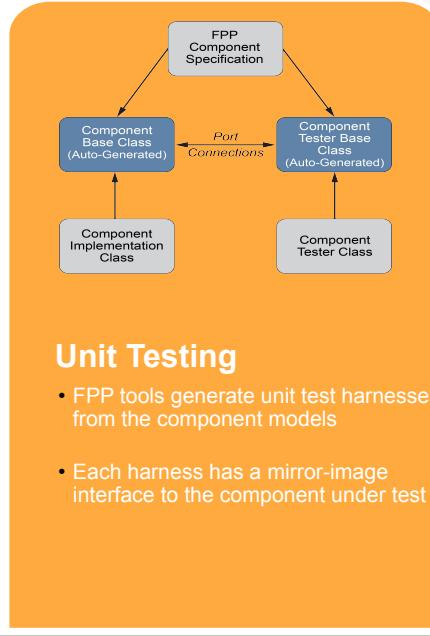
Design

- Developers model F Prime using the F Prime Prime (FPP) domain-specific language
- FPP tools check models for correctness
- Companion tools visualize topology graphs



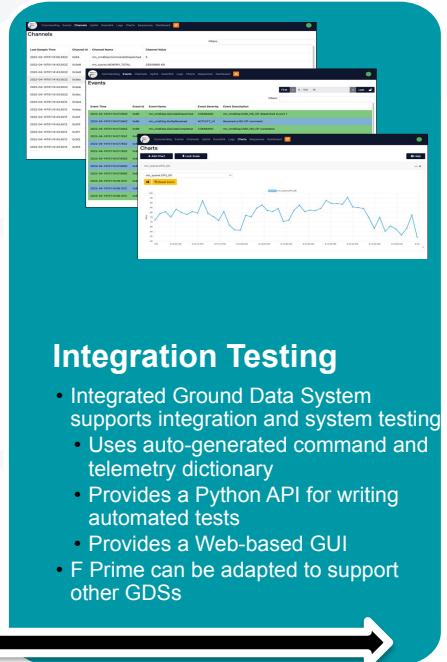
Implementation

- FPP tools translate models to partial implementations in C++
- Developers write mission-specific code
- Developers avoid writing boilerplate



Unit Testing

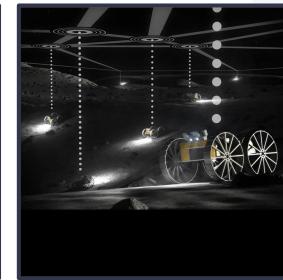
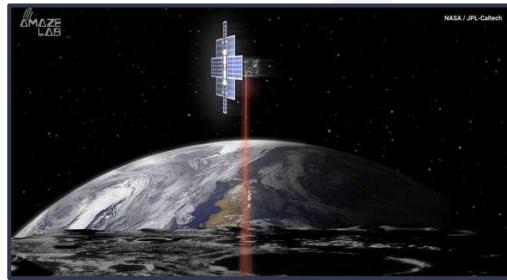
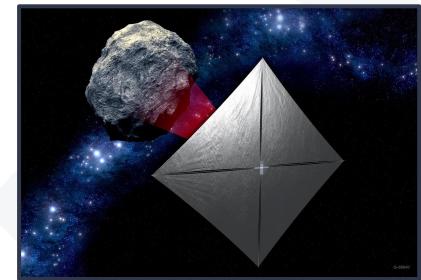
- FPP tools generate unit test harnesses from the component models
- Each harness has a mirror-image interface to the component under test



Integration Testing

- Integrated Ground Data System supports integration and system testing
 - Uses auto-generated command and telemetry dictionary
 - Provides a Python API for writing automated tests
 - Provides a Web-based GUI
- F Prime can be adapted to support other GDSs

F Prime is Flight Proven!



A dark gray background featuring a complex network graph composed of numerous small white dots connected by thin white lines, creating a sense of data connectivity and complexity.

F Prime and Linux



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F Prime and Operating Systems

F Prime Software

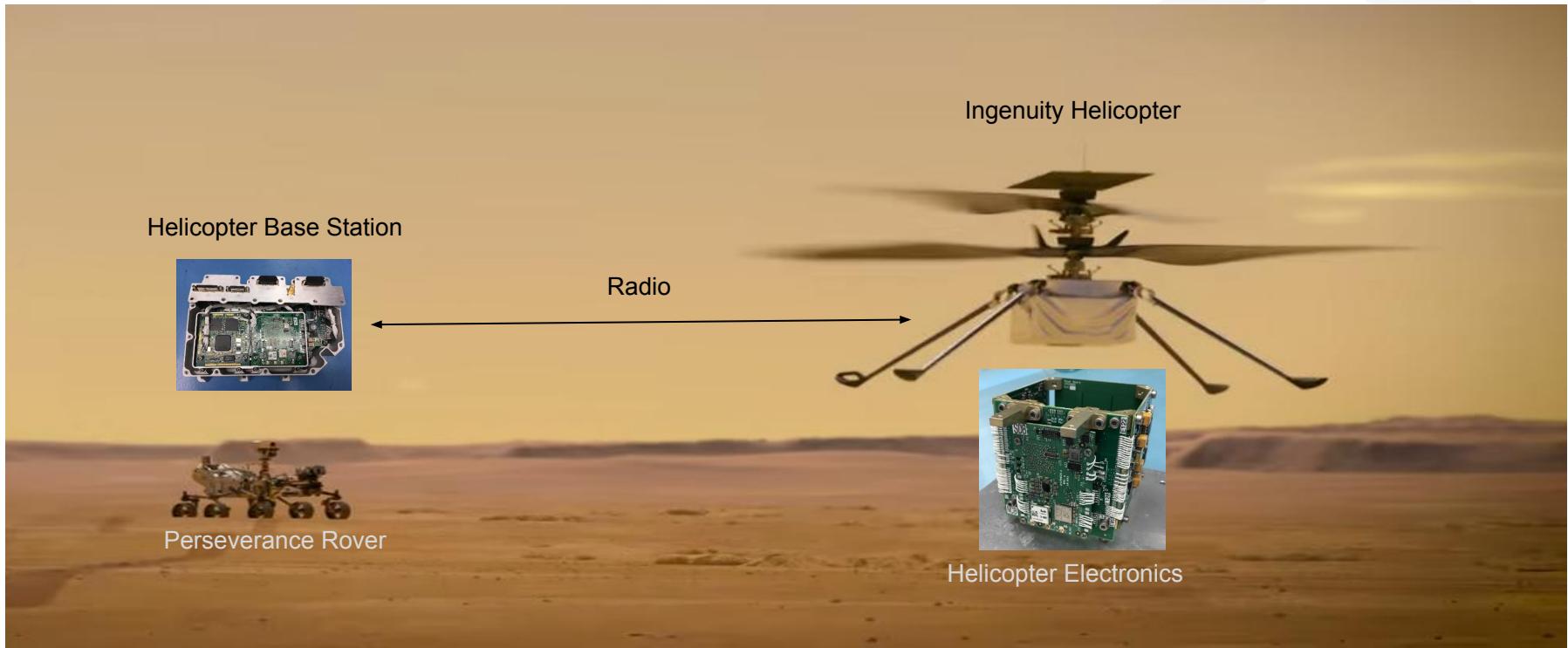
Operating System Abstraction Layer
(OSAL)

Desktop
Linux

RTOS

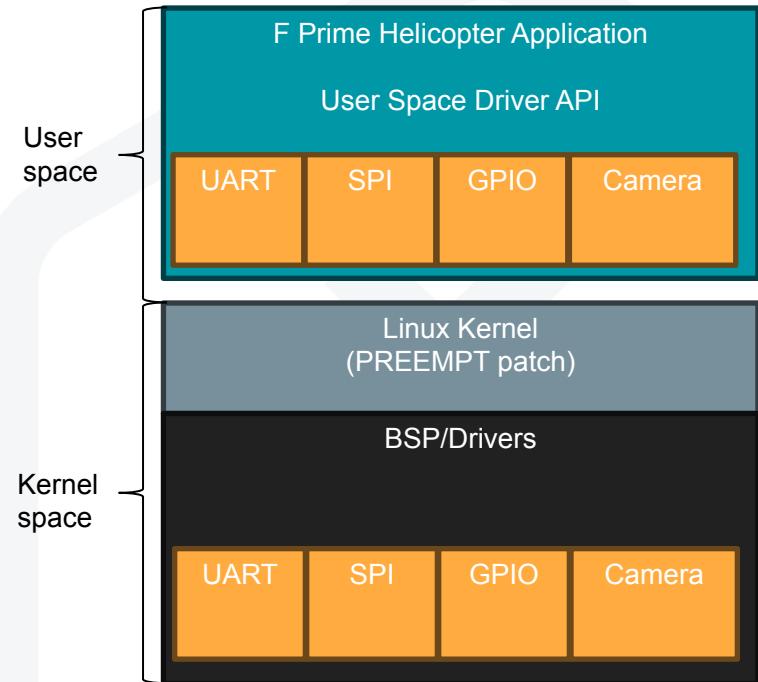
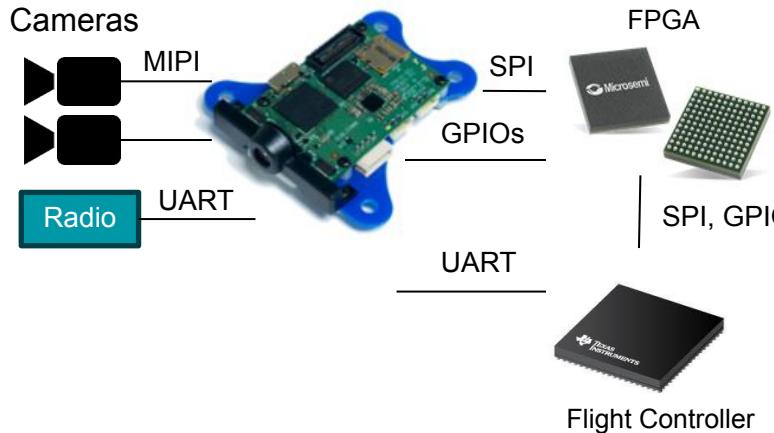
Embedded
Linux

F Prime and Linux: Ingenuity Mars Helicopter

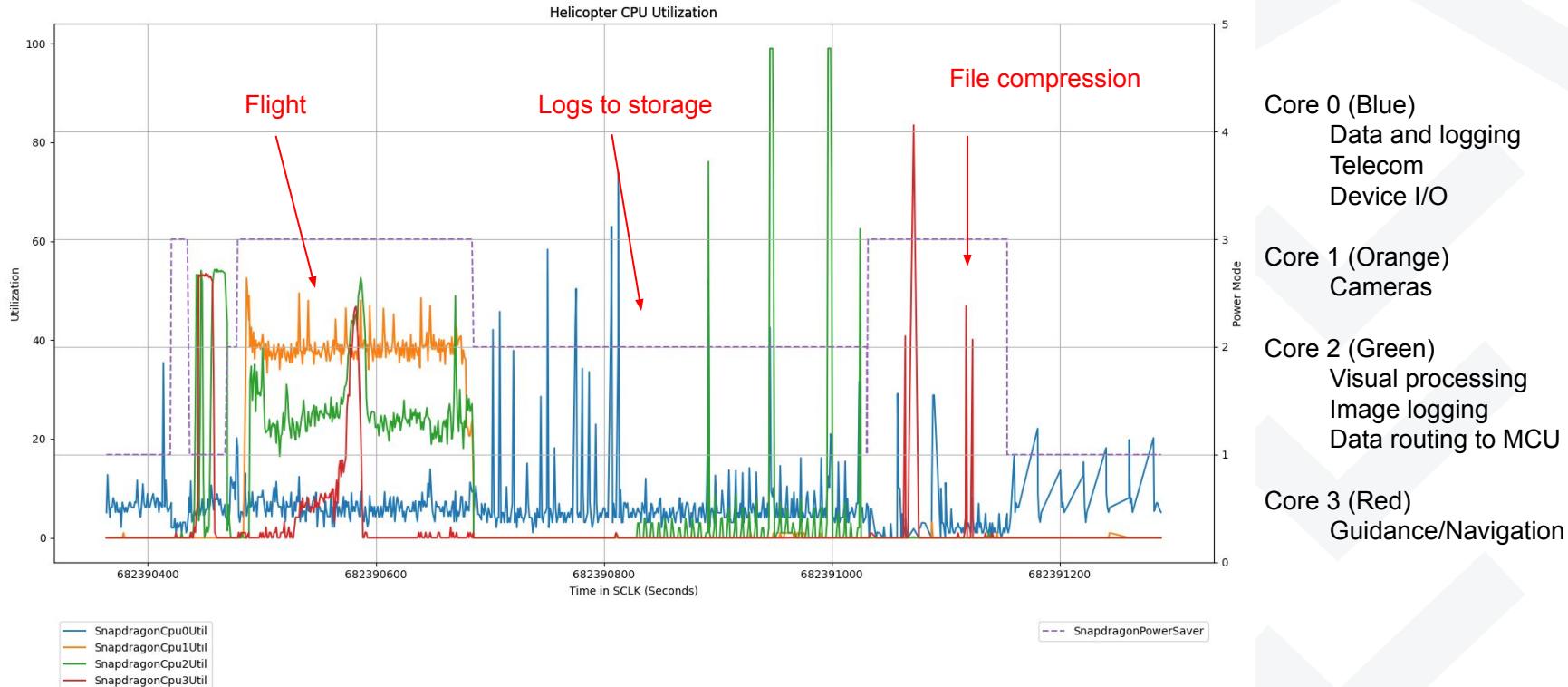


Ingenuity System Design

Qualcomm Snapdragon 801



How Did It Work Out?



Linux Lessons Learned



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Linux Supports Efficient Development

- Development stations and commodity hardware (Raspberry PIs) can be used to test most code without flat-sat hardware
- Standard user space APIs allow efficient sharing of code between deployments and between projects
- Standard board features like WiFi, USB, Ethernet, etc. made working with the testbed much more efficient

Plan for Robustness

- Not real-time, no RT patch
 - Software designed to handle slips
- File I/O had a performance impact
 - Cache data while flying; persist to disk once on the ground
- Abrupt power-off can cause file corruption
 - Dedicated read-only partition for kernel, golden software images, and launch scripts

Remember Its Linux!

- Shell and Android debugger available for development and testing
- `system()` calls could be used to extend mission functionality
- User space commands are available: bzip2, md5sum, ls, python, rm...



NASA/JPL-Caltech

Questions?



NASA/KSC

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