

# Reinforcement Learning for the Asymmetric Traveling Salesperson Problem with Precedence Constraints

Elisabeth Bankl

April 3, 2025

# Problem Statement 1

- ▶ A set of tasks that need to be completed after another
- ▶ Some tasks need to be finished before starting others (precedence constraints)
- ▶ The execution time of a task depends on the task before it (transition time)
- ▶ Objective: Find the best order to execute the tasks that minimizes the total execution time and follows all precedence constraints
- ▶ Asymmetric Travelling Salesperson Problem with Precedence Constraints: nodes represent tasks, distances represent transition times

# Problem Statement 1

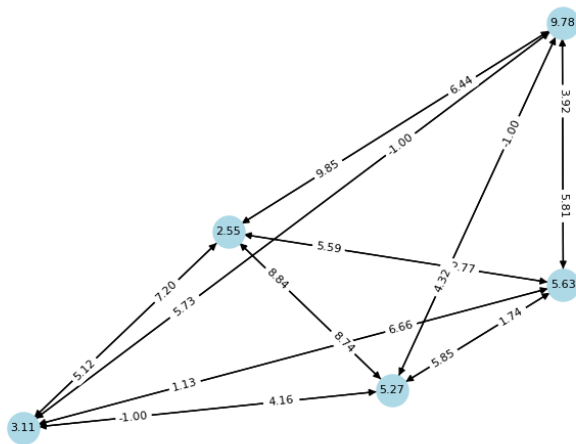


Figure: Graph visualization of the problem

# MDP Formulation

- ▶ **State Space:** The state includes:
  - ▶ **Distance Matrix ( $D$ ):** Represents the distances between nodes.
  - ▶ **Precedence Matrix ( $P$ ):** Indicates which nodes must be visited before others.
  - ▶ **Cost Matrix ( $C$ ):** Contains the cost of starting at a node and the cost of traveling between nodes.
  - ▶ **Visited Nodes Vector ( $V$ ):** A binary vector indicating which nodes have been visited.
- ▶ **Action Space:** The actions are the nodes that the agent can visit next. However, actions are restricted:
  - ▶ Nodes with unfulfilled precedence constraints are not allowed.
  - ▶ Nodes that have already been visited are not allowed.
- ▶ **Reward Function:** The reward is calculated based on the action taken:
  - ▶ If the action violates precedence constraints, a large negative reward is given.
  - ▶ If the action is valid, the reward is the negative of the distance between the current node and new node.

# Reinforcement Learning Algorithm

- ▶ **Algorithm:** Proximal Policy Optimization (PPO)
- ▶ **Network Architecture:** MLP

# Dataset

- ▶ Problem instances randomly generated during training
- ▶ Randomly sample distances between nodes, precedence constraints and node costs

# Reward Curve for RL Agent

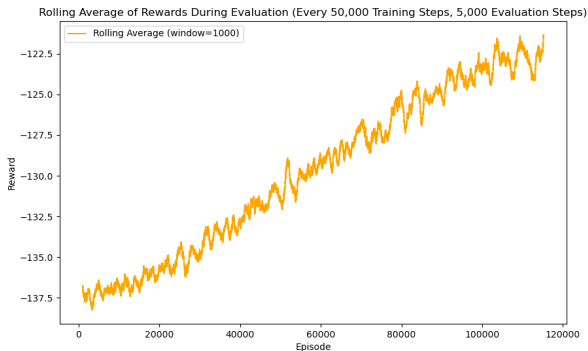


Figure: Reward curve for the reinforcement learning agent during training

# Current Limitations

Maximum problem size: 25 nodes



# Comparison with simple algorithms

Algorithm	Average Reward
Random Algorithm	-137.5
Greedy Algorithm	-85
Reinforcement Learning Agent	-123

Table: Performance comparison of different algorithms