MA 2073 Midterm 1

February 3, 2014

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Name:	SOLUTIONS	!		
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Student N	umber:			

You have 50 minutes to complete this exam.

Examination rules and instructions:

- closed book
- no calculators or cell phones are permitted

Question	Mark
1	
2	
3	
4	
5	
6	
7	
Total	/40

Question 1 (8 marks). TRUE FALSE: Circle T for true, or F for false. Each correct answer is worth 1 mark.

- a) T /F Every matrix with 1's down its diagonal is invertible.
- b) (T) / F If A is invertible, then A^{-1} and A^2 are invertible.
- c) T / F Every set of four non-zero vectors in \mathbb{R}^4 is a basis.
- d) (T)/F If the rows of A are independent, and the columns of A are independent, then A is a square matrix.
- e) T / F The column space of A is the set of all solutions of Ax = b.
- f) T / F The vectors b that are *not* in the column space of A form a subspace.
- g) (T)/F An $m \times n$ matrix has no more than n pivot variables.
- h) T / F If A is not a square matrix, then the row vectors of A must be dependent.

Question 2 (6 marks).

- a) Let A be an $n \times n$ matrix. Define A^{-1} .
- b) Use the definition of the inverse of a matrix to prove that an $n \times n$ matrix with a column of zeros cannot have an inverse.

b) Let
$$A$$
 be a matrix with a column of zeros.

consider $BA = \begin{bmatrix} \vec{b}_1 \\ \vec{b}_2 \\ \vdots \\ \vec{b}_n \end{bmatrix} \begin{bmatrix} \vec{a}_1 \dots \vec{a}_{j-1} \vec{0} & a_{j+1} \dots \vec{a}_n \end{bmatrix}$ The j^{th} column of $\vec{b}_1 \vec{0} = \begin{bmatrix} \vec{b}_1 \vec{0} \\ \vec{b}_2 \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \\ \vdots \\ \vec{b}_n \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{0} \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 \\ \vec{b}_2 & \vec{b}_2 \end{bmatrix} =$

Question 3 (6 marks). Find the complete solution to the following system of equations:

$$x+y+z=4$$

$$x-y+z=4$$

$$\begin{cases} 1 & 1 & 1 & 4 \\ 1-1 & 1 & 4 \end{cases} \longrightarrow \begin{bmatrix} 1 & 1 & 1 & 4 \\ 0 & -2 & 0 & 0 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 1 & 4 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$\frac{1}{2} \text{ is free.}$$

$$\text{For } \overrightarrow{X_P} \text{ let } z=0 \text{ . We know } y=0 \text{ (from eqn 2).}$$

$$x=4-z=4$$

$$\text{So } \overrightarrow{X_P} = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix}$$

$$\text{For } \overrightarrow{X_n} \text{ , we have } \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -2 \\ 0 \\ z \end{bmatrix} = Z \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \text{ . Hence the complete sol}^2$$

$$\overrightarrow{X_P} = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} + Z \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$\overrightarrow{X_P} = \begin{bmatrix} 4 \\ 0 \\ 0 \end{bmatrix} + Z \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

Question 4 (4 marks). What matrix E puts A into upper triangular form EA = U? Multiply by $E^{-1} = L$ to factor A into LU:

$$A = \left[\begin{array}{ccc} 2 & 1 & 0 \\ 0 & 4 & 2 \\ 6 & 3 & 0 \end{array} \right]$$

$$E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}$$

$$E_{31} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}$$

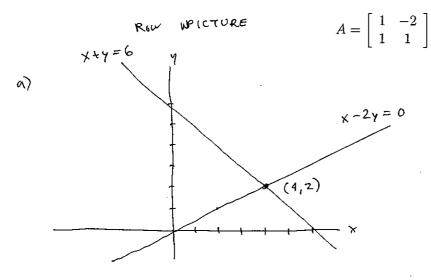
$$E_{31}A = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 4 & 2 \\ 0 & 0 & 0 \end{bmatrix} = U, \text{ which is upper } \Delta | \text{ar.}$$

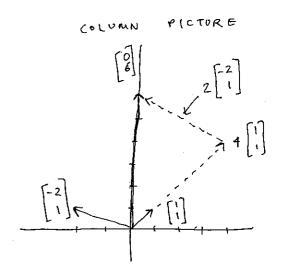
So
$$E = E_{31}$$
, and $L = E^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}$

$$So \quad A = LU = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 & 0 \\ 0 & 4 & 2 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 4 & 2 \\ 6 & 3 & 0 \end{bmatrix}$$

Question 5 (6 marks).

- a) Draw the row and column pictures for the equations x 2y = 0, x + y = 6.
- b) What is the nullspace of the matrix A?





Question 6 (5 marks).

- a) Is \mathbb{R}^k a subspace of \mathbb{R}^n when k < n? Why or why not?
- b) Describe geometrically all subspaces of \mathbb{R}^3 , and list their dimensions.

b)
$$\mathbb{R}^3$$
 itself, dim 3.
through origin, dim 2
lines ", dim 1
 $z = \{\vec{o}\}$, dim 0

Question 7 (5 marks).

- a) Find a basis for the subspace of \mathbb{R}^4 consisting of all vectors whose components are equal.
- b) The cosine space F_3 contains all combinations

$$y(x) = A\cos x + B\cos 2x + C\cos 3x.$$

Find a basis for the subspace of $\mathbf{F_3}$ with y(0) = 0 (recall that $\cos(0) = 1$).

a) a basis is just
$$(1,1,1,1)$$
. It is independent, and we may write any vector $(l,l,l,l) = l(1,1,1,1)$.

b) If
$$y(0) = 0$$
, then $A + B + C = 0$.

Then
$$A\cos x + B\cos 2x + C\cos 3x = (-B-C)\cos x + B\cos 2x + C\cos 3x$$

= $B(\cos 2x - \cos x) + C(\cos 3x - \cos x)$

This exam has 5 pages (including the cover sheet) and 7 problems, worth a total of 40 marks.