

Segmenter::findShapes

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graph LR; A[Segmenter::findShapes] --> B[Segmenter::findSeeds]; A --> C[Segmenter::findLineMarkers]; A --> D[Segmenter::growSeedsIntoInitialShapes]; A --> E[Segmenter::findVerticallyOverlappedShape]; A --> F[Segmenter::joinVerticallyOverlappedShapes]; B --> G[Clip::width]; B --> H[Clip::height]; C --> G; C --> H; D --> I[Clip::size];
```

The diagram illustrates the dependencies of the `Segmenter::findShapes` function. It is a central node on the left, with five outgoing arrows pointing to other functions: `Segmenter::findSeeds`, `Segmenter::findLineMarkers`, `Segmenter::growSeedsIntoInitialShapes`, `Segmenter::findVerticallyOverlappedShape`, and `Segmenter::joinVerticallyOverlappedShapes`. The first two functions, `Segmenter::findSeeds` and `Segmenter::findLineMarkers`, have arrows pointing to `Clip::width` and `Clip::height`. The `Segmenter::growSeedsIntoInitialShapes` function has an arrow pointing to `Clip::size`.

Segmenter::findSeeds

Clip::width

Segmenter::findLineMarkers

Clip::height

Segmenter::growSeedsIntoInitialShapes

Clip::size

Segmenter::findVerticallyOverlappedShape

Segmenter::joinVerticallyOverlappedShapes