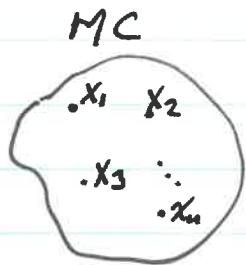


Chapter 2: Markov chain Monte Carlo

2.1 Introduction



$$p(x_1, x_2, \dots, x_n) = p(x_1)p(x_2|x_1)\cdots p(x_n|x_{n-1})$$

Independent samples

$$S_L = \{x_i\}_{i=1}^L$$

Histogram(S) $\approx p$

Sample p directly

$$p(x_1, x_2, \dots, x_n) = p(x_1)p(x_2|x_1)\cdots p(x_n|x_{n-1})$$

Markov samples: $P(X \rightarrow X') = p(x'|x)$

$$S_L = \{x_i\}_{i=1}^L \text{ 'trajectory'}$$

Histogram(S_L) $\approx p$

Choose transition probability $P(X \rightarrow X')$
to sample p

2.2. Markov chains

Def: $(X_i)_{i=1}^n$ is a discrete-time Markov chain (MC) if

$$P(X_n = x_n | X_1 = x_1, X_2 = x_2, \dots, X_{n-1} = x_{n-1}) = P(X_n = x_n | X_{n-1} = x_{n-1})$$

for all $n \geq 1$ and all x_1, x_2, \dots, x_n .
 all sequences all values

transition probability

$$\Rightarrow P(X_1, X_2, \dots, X_n) = P(X_1)P(X_2|X_1)\cdots P(X_n|X_{n-1})$$

$$X_1 \rightarrow X_2 \rightarrow \dots \rightarrow X_n$$

Assumptions/restrictions:

$X_i \in \mathcal{X}$ discrete/ countable state space

$P(X_n = b | X_{n-1} = a)$ doesn't depend on n

Time

$$\Rightarrow P(X_n = b | X_{n-1} = a) = P(X_2 = b | X_1 = a) \quad \forall n$$

Time-invariant, time-independent, homogeneous

Transition matrix

$$P(X_n = j \mid X_{n-1} = i) = P(i \rightarrow j) = \pi_{ij} \quad \text{or} \quad p_{ij}$$

- $|X| \times |X|$ matrix

- $0 \leq \pi_{ij} \leq 1 \quad \forall i, j$
 - $\sum_j \pi_{ij} = 1 \quad \forall i$
- } Stochastic matrix

$$\Pi = (\pi_{ij}) = \begin{pmatrix} \pi_{11} & \pi_{12} & \pi_{13} & \dots \\ \pi_{21} & \pi_{22} & \pi_{23} & \dots \\ \vdots & \ddots & & \end{pmatrix} \quad \text{row sum = 1}$$

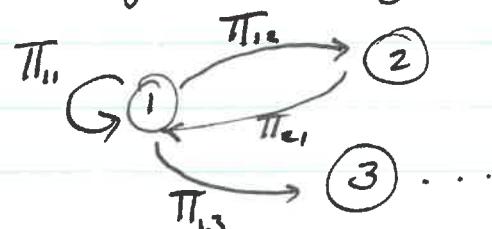
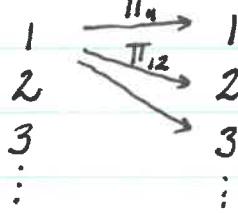
row column

Rem: Different convention (used in physics)

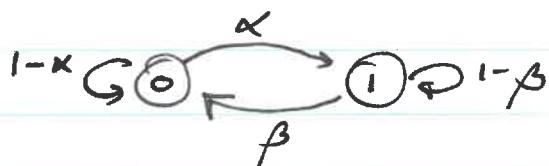
$$P(i \rightarrow j) = \tilde{\pi}_{ji} \quad \sum_j \tilde{\pi}_{ji} = 1 \quad \forall i$$

$$\tilde{\Pi} = \Pi^T$$

- Graphical representation: $\pi_{ij} = P(i \rightarrow j)$

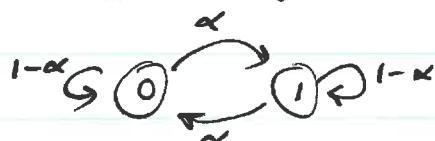


- Example: 2-state MC



$$\Pi = \begin{pmatrix} 1-\alpha & \alpha \\ \beta & 1-\beta \end{pmatrix} \quad \begin{array}{l} \rightarrow \sum_{i,j} = 1 \\ \rightarrow \sum_{i,j} = 1 \end{array}$$

- $\beta = \alpha$: Symmetric MC

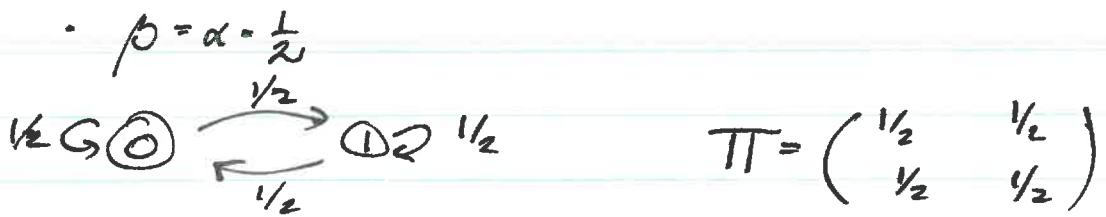


$$\Pi = \begin{pmatrix} 1-\alpha & \alpha \\ \alpha & 1-\alpha \end{pmatrix}$$

- $\alpha \approx 0$: 000... 111... 0010...

- $\alpha \approx 1$: 0101... 001101...

long sequences of 0's, 1's
periodic
anti-periodic
alternating bits



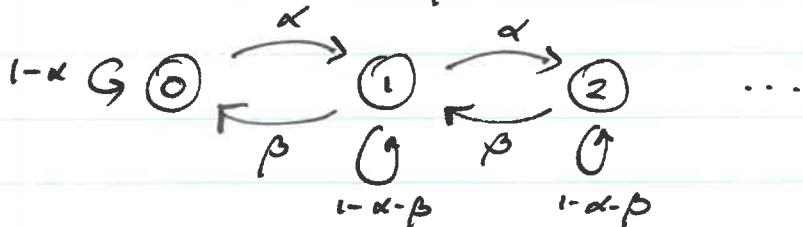
Coin tossing. No correlation

Rem: Independent MC if Π_{ij} doesn't depend on i :
 $P(i \rightarrow j) = P(j)$ all rows the same

$$\Rightarrow P(X_1 X_2 \dots X_n) = P(X_1) P(X_2) \dots P(X_n) \quad \text{iid model}$$

Example: Population model / birth-death process

- $X_i \in \{0, 1, 2, \dots\}$
- $P(i \rightarrow i+1) = \alpha$ births
- $P(i \rightarrow i-1) = \beta$ deaths



2.3 Probability propagation

$$X_1 \rightarrow X_2 \rightarrow \dots \rightarrow X_n$$

$$P(X_1) \qquad \qquad \qquad P(X_n) ?$$

$$P(X_1, X_2) = P(X_1) P(X_2 | X_1)$$

$$\Rightarrow P(X_2 = j) = \sum_i P(X_1 = i, X_2 = j)$$

$$= \sum_i P(X_1 = i) P(X_2 = j | X_1 = i)$$

$$\Rightarrow P(X_{n+1} = j) = \sum_i P(X_n = i) P(X_{n+1} = j | X_n = i)$$

$$= \sum_i P(X_n = i) \Pi_{ij}$$

- Matrix notation:

$$\bar{P}_n \quad (\bar{P}_n)_{ii} = \bar{P}_n(i) = P(X_n = i) \quad \sum_i P_n(i) = 1$$

$$\Pi \quad (\Pi)_{ij} = P(X_{n+1} = j | X_n = i) \quad \sum_j \Pi_{ij} = 1$$

- Propagation formula:

$$\bar{P}_{n+1} = \bar{P}_n \Pi \quad \text{Chapman-Kolmogoroff equation}$$

row vector row matrix

$$(p_{n+1}(1) \ p_{n+1}(2) \dots) = (p_n(1) \ p_n(2) \dots) \begin{pmatrix} \Pi \end{pmatrix}$$

$$\bar{P}_2 = \bar{P}_1 \Pi$$

$$\bar{P}_3 = \bar{P}_2 \Pi = \bar{P}_1 \Pi \Pi = \bar{P}_1 \Pi^2$$

⋮

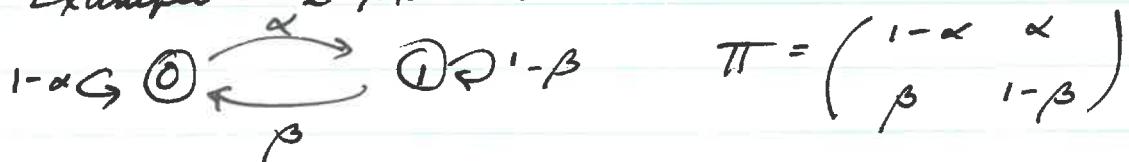
$$\bar{P}_n = \bar{P}_{n-1} \Pi = \bar{P}_1 \underbrace{\Pi}_{n-1 \text{ steps}}^{n-1}$$

n-1 steps transition prob.

$$\begin{aligned} P(X_n = j) &= \sum_i P(X_1 = i) (\Pi^n)_{ij} \\ &= \sum_i P(X_1 = i) \underbrace{P(X_n = j | X_1 = i)}_{n-1 \text{ steps}} \end{aligned}$$

$$\begin{array}{ccccc} X_1 & \xrightarrow{\Pi} & X_2 & \xrightarrow{\Pi} & \dots \xrightarrow{\Pi} X_n \\ P(X_1) & & & & P(X_n) \end{array}$$

- Example: 2-state MC



$$(p_{n+1}(0) \ p_{n+1}(1)) = (p_n(0) \ p_n(1)) \begin{pmatrix} 1-\alpha & \alpha \\ \beta & 1-\beta \end{pmatrix}$$

$$\begin{aligned} p_{n+1}(0) &= (1-\alpha) p_n(0) + \beta p_n(1) \\ p_{n+1}(1) &= \alpha p_n(0) + (1-\beta) p_n(1) \end{aligned}$$

Rem: Column vector convention

$$\begin{pmatrix} 1 \\ p_{n+1} \\ \vdots \end{pmatrix} = (\tilde{\pi}) \begin{pmatrix} \bar{p}_n \end{pmatrix} \quad \text{vs} \quad \begin{pmatrix} p_{n+1} \\ \vdots \end{pmatrix} = \begin{pmatrix} p_n \end{pmatrix} \begin{pmatrix} \pi \end{pmatrix}$$

2.4. Ergodic Markov chains

- Stationary distribution:

$$P^* = P^* \pi$$

$$\text{Fixed point of } \pi: P_1 = P^* \rightarrow P_2 = P_1 \pi$$

$$= P^* \pi$$

$$= P^*$$

$$\Rightarrow P_n = P^* \quad \forall n$$

Eigenvector of π with eigenvalue 1 (left eigenvect)

π can have many stationary dist.

- limiting distribution:

$$P_\infty = \lim_{n \rightarrow \infty} P_n = \lim_{n \rightarrow \infty} P_1 \pi^{n-1}$$

Might not exist

Might depend on P_1 choice of initial condition

- Ergodic Markov chain:

P_∞ exists

P_∞ independent of P_1

$P_\infty = P^*$

Grimmett + Stirzaker
Secs 6.3
6.4

Proposition: If $(X_i)_{i=1}^n$ is an aperiodic and irreducible Markov chain, then $\lim_{n \rightarrow \infty} P_n = P^*$ for any P_1 .

Example: 2-state MC $1 \xrightarrow{\alpha} 0 \xrightarrow{\beta} 1 \xleftarrow{\alpha} 0$

$$\cdot 0 < \alpha, \beta < 1 : \text{Ergodic } \bar{P}^+ = \begin{pmatrix} \beta & \alpha \\ \alpha + \beta & \alpha \end{pmatrix}$$

$\cdot \alpha = \beta = 0 : \text{Not ergodic } 0 \circlearrowright 1 \circlearrowleft$
 Any P_i is stationary
 Reducible Markov chain

$\cdot \alpha = \beta = 1 : \text{Not ergodic } 0 \xrightarrow{1} 1$
 Periodic Markov chain

$$P_1 = (a \ b)$$

$$P_2 = (b \ a)$$

$$P_3 = (a \ b)$$

:

$$P = \left(\frac{1}{2} \ \frac{1}{2} \right) \text{ stationary but not a limiting distribution}$$

• Ergodic theorem: If $(X_i)_{i=1}^n$ is an ergodic Markov chain, then

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n g(X_i) = E_{P^*}[g(X)] \quad \text{in probability}$$

estimate stationary expectation
 time average
 $\hat{\gamma}_n$ γ

$$\lim_{n \rightarrow \infty} P(|\hat{\gamma}_n - \gamma| > \varepsilon) = 0$$

• Generalization of law of large numbers (LLN) to Markov chains.

$$X_i \sim p^* \text{ iid} \quad (X_i)_{i=1}^n \text{ MC}$$

$$\frac{1}{n} \sum_{i=1}^n g(X_i) \rightarrow E_{P^*}[g(X)] \quad \text{in prob.} \quad \frac{1}{n} \sum_{i=1}^n g(X_i) \rightarrow E_{P^*}[g(X)] \quad \text{in prob.}$$

• Empirical occupation:

$$\hat{P}_n(j) = \frac{1}{n} \sum_{i=1}^n \delta_{X_i, j} = \text{fraction of time spent in } j$$

$$d_{i,j} = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

$$\hat{P}_n(j) \xrightarrow{n \rightarrow \infty} p^*(j) \quad \text{in prob.}$$

• Interpretations of p^* :

- 1- Distribution of X_n as $n \rightarrow \infty$
- 2- Long time (stationary) occupation

2.5. Stationary distribution

$$\hat{P}^* = P^* \pi$$

1- Direct calculation

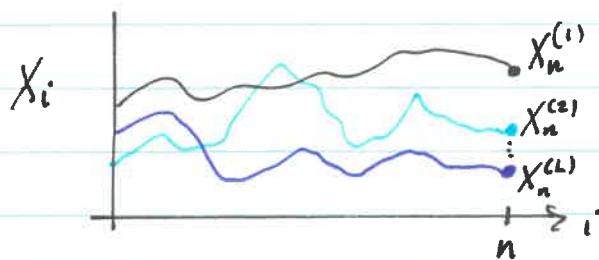
- Input: π
- Output: left eigenvector of π with eigenvalue 1
- Normalization: $\sum_i p^*(i) = 1$

• Code:

```
import scipy.linalg as la
pimat = np.array([ [a,b,c], [...], [...] ])
eigvals, eigvecs = la.eig(np.transpose(pimat))
```

$\in \mathbb{R}^{n \times n}$ Why?

2- Parallel simulations



- Simulate L copies / realizations / trajectories

$$\left\{ \left(X_i^{(j)} \right)_{i=1}^n \right\}_{j=1}^L$$

$L = \text{sample size / no traj.}$

$n = \text{final time}$

- Keep last state at time n : $\left\{ X_n^{(j)} \right\}_{j=1}^L$

- Histogram: $\hat{P}_{n,L}(i) \approx p_n(i)$ All final states (CLLN)

- Convergence: $\hat{P}_{n,L}(\cdot) \xrightarrow[L \rightarrow \infty]{n \rightarrow \infty} P^*(\cdot)$

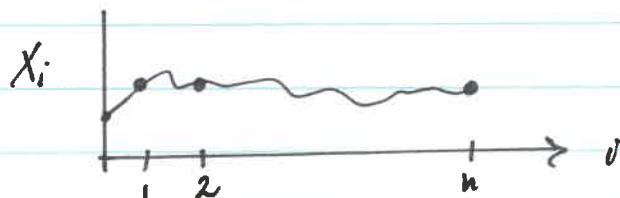
Code:

- $n = 100$
- $L = 10^{4+5}$
- $x_{\text{sample}} = []$
- $\text{for } j=1:L$
 - $x = \text{initial value}$ ← deterministic or random
 - $\text{for } i=1:n$
 - generate new x
 - append x to x_{sample}
- $\text{histogram}(x_{\text{sample}})$

$n \rightarrow \infty, L \rightarrow \infty$

2 loops

3- Ergodic simulation



- Simulate 1 trajectory $(X_i)_{i=1}^n$
- Empirical occupation:

$$\hat{P}_n(j) = \frac{1}{n} \sum_{i=1}^n \delta_{X_i, j}$$

Histogram of all states
in time

- Convergence: $\hat{P}_n(j) \xrightarrow{n \rightarrow \infty} p^*(j)$

Ergodic theorem

Code:

- $n = 10^{4+5}$
- $x_{\text{sample}} = []$
- $x = \text{initial value}$ ← deterministic or random
- $\text{for } i=1:n$
 - generate new x
 - append x to x_{sample}

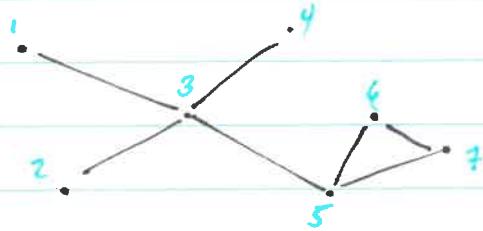
1 loop!

$\text{histogram}(x_{\text{sample}})$

$n \rightarrow \infty$

Trade off n vs $n \times L$

2.6. Application: Random walk on graphs



- Graph: $G = (V, E)$
 - Undirected
 - Connected
- vertices
nodes
edges

- Adjacency matrix: $A_{ij} = \begin{cases} 1 & \text{if } j \text{ is } i \\ 0 & \text{if } j \neq i \end{cases}$
- $|V| \times |V|$ matrix
- Symmetric $A = A^T$ $i \sim j \Rightarrow j \sim i$ reflexive

- Node degree: $k_i = \# \text{ links to node } i$
 $= \sum_j A_{ij}$
- Degree list: $\bar{k} = (k_1, k_2, k_3, \dots, k_{|V|})$
- Number of edges: $M = \frac{1}{2} \sum_i k_i = \frac{1}{2} \sum_{ij} A_{ij}$
- Uniform random walk (URW):
 - Start at node $X_0 = i$
 - Choose node connected to i , random uniform
 k_i of them $\Rightarrow P(i \rightarrow j) = \frac{1}{k_i} \quad j \sim i$
 - Repeat

- Transition matrix: $\Pi_{ij} = P(i \rightarrow j) = \frac{A_{ij}}{k_i}$
- $0 \leq \Pi_{ij} \leq 1 \quad \forall i, j$
- $\sum_j \Pi_{ij} = \frac{1}{k_i} \sum_j A_{ij} = 1 \quad \forall i$
- Π ergodic if G connected

- Stationary/ergodic distribution: $p^*(i) = \frac{k_i}{2M} \propto k_i$
- Normalization: $\sum_i p^*(i) = \frac{1}{2M} \sum_i k_i = 1$
- Occupation $\hat{p}_n(i) \rightarrow p^*(i) \propto k_i$
- Basis of Google PageRank

2.7. Metropolis-Hastings algorithm

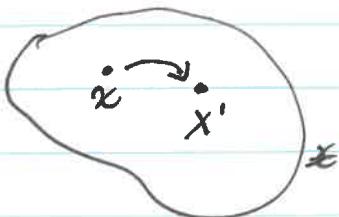
(1948)

- hiu Chap.5
- Refs: • Metropolis, Rosenbluth², Teller², 1953 M(RT)²
• Hastings 1970

- Top 10 algo of 20th century by SIAM

- Goal: • Generate variates/values $X \sim f$ target distribution
 - $x \in \mathcal{X}$ state space \hookrightarrow known, calculable
 - $\sum_x f(x) = 1$

- Idea: Simulate ergodic Markov chain that has f as its stationary distribution.



- Steps:

1- Initialize: $X_0 = x$ deterministic or random

2- Generate move/proposal:

$x \rightarrow x'$ with probability $q(x'|x)$

$$x' \sim q(\cdot|x)$$

3- Accept proposal with probability

$$\rho = \min \left\{ 1, \frac{q(x|x')f(x')}{q(x'|x)f(x)} \right\}$$

Metropolis-Hastings ratio

That is, $u \sim U[0,1]$ P_{MH}

if $u < \rho$ then

$X_2 = x'$ accept

else

$X_2 = x$ reject

4- Repeat

- Metropolis-Hastings MC:

$$\pi(x'|x) = P(x \rightarrow x') = \begin{cases} p & x \neq x' \\ 1-p & x = x \end{cases}$$

- Ergodic MC

- Stationary distribution: $f(x)$

See CW2

- Remarks:

- Free to choose $g(x'|x)$ possible moves
- Propose moves x' such that $f(x') > 0$
- $\text{Supp}(f) \subseteq \bigcup_x \text{Supp}(g(\cdot|x))$
- Move accepted for move if $q(x|x')f(x') > q(x'|x)f(x)$
Move accepted with probability p otherwise
- Implementation: if $p_{\text{MH}} > 1$ or $u < p_{\text{MH}}$ then accept
check first pares possibly generation of u
- On: if $\log p_{\text{MH}} > 0$ or $\log u < \log p_{\text{MH}}$
- $f(x)$ needed only up to normalization factor: $f(x) = c g(x)$
 $\Rightarrow p_{\text{MH}} = \frac{q(x|x') g(x')}{q(x'|x) g(x)}$
- Choose q such that accepted fraction $\approx \frac{1}{2}$
acceptance ratio

• Particular cases :

1- Independent random walk : $q(x'|x) = q(x')$

$$\Rightarrow \rho_{MH} = \frac{q(x)f(x')}{q(x')f(x)}$$

2- Metropolis algorithm : $q(x'|x) = q(x/x')$ symmetric

$$\Rightarrow \rho_M = \frac{f(x')}{f(x)} \quad \rho = \min \left\{ 1, \frac{f(x')}{f(x)} \right\}$$

• Accept move x' for sure if $f(x') \geq f(x)$

• Accept with prob. ρ if $f(x') < f(x)$

• Reversible : $f(x)P(x \rightarrow x') = f(x')P(x' \rightarrow x)$ CW2
 high low low high

3- Metropolis random walk :

• Move : $X' = X + \delta X$

• Displacement : $\delta X \sim p$ symmetric

$$\Rightarrow q(x'|x) = q(x|x')$$

$$q(x'|x) = q(x \rightarrow x') = p(\delta x)$$

$$q(x|x') = q(x' \rightarrow x) = p(-\delta x)$$

4- Heat bath algorithm :

$$\cdot \text{Target} : f(x) = \frac{e^{-\beta U(x)}}{Z}$$

• $x \in \mathbb{R}^d \cap \mathcal{X}$

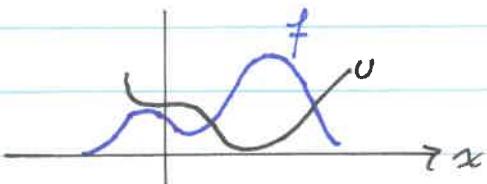
• $U : \mathcal{X} \rightarrow \mathbb{R}$ potential

• $\beta \in \mathbb{R}$ usually $\beta > 0$ inverse temperature

$$\Rightarrow \rho_H = \frac{e^{-\beta U(x')}}{e^{-\beta U(x)}} = e^{-\beta \Delta U}$$

$$\Delta U = U(x') - U(x)$$

potential change



- ⇒ More accepted jumps if $\Delta U \leq 0$: $U(x') \leq U(x)$
- " " with prob. p_H if $\Delta U > 0$: $U(x') > U(x)$
- Potential minimization (not greedy)
- Sample where $f(x)$ is large $\Leftrightarrow |U(x)|$ is low
- Example: $f \sim N(\mu, \sigma^2)$

$$n = 10^{+3}$$

MC steps

$$x_{\text{sample}} = []$$

x = initial value

deterministic or random

for $i=1:n$

$$\text{disp} \sim U[-a, a]$$

Symmetric, $a = \pi \sigma$

$$x_p = x + \text{disp}$$

$$p_H = f(x_p) / f(x)$$

if $p_H > 1$ or $\text{rand}() < p_H$ then

$$x = x_p$$

accept
← no else

append x to x_{sample}

same x added/kept
if x_p not accepted

See demo

• MCMC optimization: $E_f[g(X)] = \gamma$

• Trajectory: $(X_i)_{i=1}^n$

• Estimator: $\hat{\gamma}_n = \frac{1}{n} \sum_{i=1}^n g(X_i)$

• Ergodic thm: $\hat{\gamma}_n \rightarrow \gamma$ in prob. as $n \rightarrow \infty$

• Comparison:

Standard MC

- iid samples
- No correlation
- Difficult in high dim
- Clever method needed

MCMC

- MC variates
- Correlated samples
- Efficient in high dim
- Generic "black box"

Bailey-Jones Chap 8, 9 2.8 MCMC inference

- Probabilistic model: $P(x|\theta)$

$x \in \mathcal{X}$ state
 $\theta \in \mathcal{N}$ parameters

- Parameter posterior:

$$P(\theta|D) = \frac{P(D|\theta) P(\theta)}{P(D)}$$

likelihood prior
data evidence

- likelihood: $P(D|\theta) = P(x_1, x_2, \dots, x_n | \theta)$
 $= \prod_i P(x_i | \theta)$

Naive Bayes

- Evidence:

$$P(D) = \int d\theta P(D|\theta) P(\theta)$$

- Tasks:

1- Parameter inference: See EWZ

- $P(\theta|D)$ not known in closed form

- Sample from $P(\theta|D)$

- Propose move $\theta \rightarrow \theta'$

- Accept with prob. $p = \min\left\{1, \frac{P(\theta'|D)}{P(\theta|D)}\right\}$

- Data given

Under Metropolis

$$= \min\left\{1, \frac{P(D|\theta') P(\theta')}{P(D|\theta) P(\theta)}\right\}$$

No $P(D)$

2- Data generation

- Find best θ^* from D (e.g. most probable)

- Sample from $P(D|\theta^*)$

- Propose move $D \rightarrow D'$

- Used to complete missing data

3- Evidence calculation / model comparison

- Estimate integral $P(D) = \int d\theta P(D|\theta) P(\theta)$
- MC or MCMC

2.9. Error analysis

Expectation: $\bar{g} = E_g[g(x)]$ $X \sim f$ target distribution

Estimator: $\hat{g}_n = \frac{1}{n} \sum_{i=1}^n g(X_i)$ $(X_i)_{i=1}^n$ ergodic MC

Error:

$$\hat{g}_n \pm \sigma_n \quad \text{ci } 68\%$$

$$\hat{g}_n \pm 2\sigma_n \quad \text{ci } 95\%$$

$$\sigma_n = \sigma(\hat{g}_n) = \sqrt{\text{Var}(\hat{g}_n)}$$

$$\text{Var}(\hat{g}_n) \sim \frac{1}{n} \quad \text{but } \neq \frac{\sigma^2(g(x))}{n}$$

iid variance/naiive variance

Methods:

1- Independent simulations / runs

Simulate L independent MCs: $\{(X_i^{(j)})_{i=1}^n\}_{j=1}^L$

Sample of estimators: $\{\hat{g}_n^{(j)}\}_{j=1}^L = S$

Mean estimator: $\hat{\bar{g}}_{n,L} = \frac{1}{L} \sum_{j=1}^L \hat{g}_n^{(j)}$

Error: $\sigma_n = \sqrt{\text{Var}(S)}$

Variance: $\text{Var}(S) = \frac{1}{L-1} \sum_{j=1}^L (\hat{g}_n^{(j)} - \hat{\bar{g}}_{n,L})^2$

Standard iid Variance

2- Ergodic simulation

Simulate 1 trajectory: $(X_i)_{i=1}^n$

Estimator: $\hat{g}_n = \frac{1}{n} \sum_{i=1}^n g(X_i)$

$\text{Var}(\hat{g}_n)$?

$$\begin{aligned}\text{var}(\hat{\delta}_n) &= \text{var}\left(\frac{1}{n} \sum_{i=1}^n g(X_i)\right) \\ &= \frac{1}{n^2} \text{var}\left(\sum_{i=1}^n g(X_i)\right) \quad \neq \sum_i \text{var}(g(X_i)) \\ &= \frac{1}{n^2} \sum_{i,j=1}^n \text{cov}(g(X_i), g(X_j))\end{aligned}$$

$$\begin{aligned}\text{cov}(X, Y) &= E[(X - E[X])(Y - E[Y])] \quad \text{Covariance} \\ \text{cov}(X, X) &= \text{var}(X) \quad \text{Variance}\end{aligned}$$

$$\begin{aligned}\text{var}(\hat{\delta}_n) &= \frac{1}{n^2} \left(\sum_{i=1}^n \text{var}(g(X_i)) + \sum_{i \neq j} \text{cov}(g(X_i), g(X_j)) \right) \\ &= \frac{1}{n^2} \left(\sum_{i=1}^n \text{var}(g(X_i)) + 2 \sum_{1 \leq j < k \leq n} \text{cov}(g(X_j), g(X_k)) \right)\end{aligned}$$

$\cdot (X_i)_{i=1}^n$ ergodic so $P_n(j) = P(X_n=j) \rightarrow f(j)$ as $n \rightarrow \infty$.

$$\begin{aligned}\Rightarrow \text{var}(\hat{\delta}_n) &\sim \frac{1}{n^2} \left[n \underbrace{\text{var}_f(g(x))}_{\text{naive variance}} + 2n \sum_{k=1}^{\infty} \underbrace{\text{cov}_f(g(X_1), g(X_{1+k}))}_{\substack{\text{MC started at } f}} \right] \\ &= \frac{\text{var}_f(g(x))}{n} \left[1 + 2 \sum_{k=1}^{\infty} \underbrace{\text{corr}(g(X_1), g(X_{1+k}))}_{\substack{\text{auto correlation} \quad \tau(g)}} \right]\end{aligned}$$

$$\text{corr}(X, Y) = \frac{\text{cov}(X, Y)}{\sigma_X \sigma_Y}$$

$$\begin{aligned}\Rightarrow \text{var}(\hat{\delta}_n) &= \frac{\text{var}_f(g(x))}{n} \tau(g) \\ &= \frac{\sigma_f^2(g(x))}{n_{\text{eff}}} \quad \begin{array}{l} \sim \text{naive variance} \\ \sim \text{effective number of samples} \end{array}\end{aligned}$$

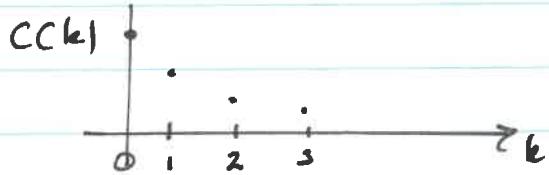
$$n_{\text{eff}} = \frac{n}{\tau(g)}$$

$\tau(g) \sim$ time scale of exponential decay of correlation

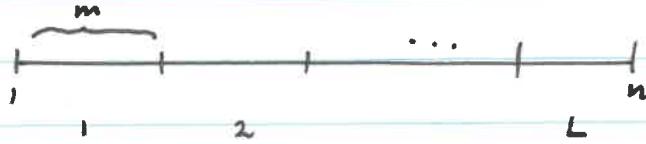
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Example: $\text{corr}(g(X_1), g(X_{1+k})) = C(k) = \rho^k$, $\rho \in (0, 1)$

$$\Rightarrow 1 + 2 \sum_{k=1}^{\infty} C(k) = \frac{1+\rho}{1-\rho}$$



3 - Batch means



- n samples
 - L batches/blocks of m points $L \times m = n$
 - Block average: $\hat{y}_j^m = \frac{1}{m} \sum_{j^{\text{th}} \text{ block}} g(X_k)$
 - Estimate: $\hat{\delta}_n = \frac{1}{L} \sum_{j=1}^L \hat{y}_j^m$
 - $n \rightarrow \infty$, $L \rightarrow \infty$ while $m \rightarrow \infty$, blocks became independent
- $\Rightarrow \text{var}(\hat{\delta}_n) = \text{naive var}(\{\hat{y}_j^m\})$