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```
from google.colab import drive
drive.mount("/content/gdrive")
```

```
!pwd
```

```
Mounted at /content/gdrive
/content
```

```
%cd "/content/gdrive/MyDrive/7mo Semestre/Modulo 2/Titanic"
```

```
!ls
```

```
/content/gdrive/MyDrive/7mo Semestre/Modulo 2/Titanic
X_test.txt X_train.txt Y_test.txt Y_train.txt
```

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt
```

```
x_tn = pd.read_csv("X_train.txt")
y_tn = pd.read_csv("Y_train.txt")
```

```
x_tt = pd.read_csv("X_test.txt")
y_tt = pd.read_csv("Y_test.txt")
```

```
x_tn.head()
```

	<b>Id</b>	<b>Pclass</b>	<b>Sex</b>	<b>Age</b>	<b>SibSp</b>	<b>Parch</b>	<b>Fare</b>	<b>Embarked</b>
<b>0</b>	0	3	0	22.0	1	0	7.2500	1
<b>1</b>	1	1	1	38.0	1	0	71.2833	0
<b>2</b>	2	3	1	26.0	0	0	7.9250	1
<b>3</b>	3	1	1	35.0	1	0	53.1000	1
<b>4</b>	4	3	0	35.0	0	0	8.0500	1



```
y_tn.head()
```

	Id	Survived
0	0	0
1	1	1
2	2	1

x\_tt.head()

	Id	Pclass	Sex	Age	SibSp	Parch	Fare	Embarked
0	0	3	0	34.5	0	0	7.8292	2
1	1	3	1	47.0	1	0	7.0000	1
2	2	2	0	62.0	0	0	9.6875	2
3	3	3	0	27.0	0	0	8.6625	1
4	4	3	1	22.0	1	1	12.2875	1

y\_tt.head()

	Id	Survived
0	0	0
1	1	1
2	2	0
3	3	0
4	4	1

```
x_tn = x_tn.drop("Id", axis = 1)
y_tn = y_tn.drop("Id", axis = 1)
x_tt = x_tt.drop("Id", axis = 1)
y_tt = y_tt.drop("Id", axis = 1)
```

```
x_tn = x_tn.values
y_tn = y_tn.values
x_tt = x_tt.values
y_tt = y_tt.values
```

```
x_tn = x_tn.T
y_tn = y_tn.reshape(1,x_tn.shape[1])
x_tt = x_tt.T
y_tt = y_tt.reshape(1,x_tt.shape[1])
```

```

def sigmoid(x):
    return 1/(1 + np.exp(-x))

def model(X, Y, learning_rate, iterations):
    x0 = x_tn.shape[1]
    x1 = x_tn.shape[0]
    P = np.zeros((x1,1))
    O = 0
    cost_list = []
    for i in range(iterations):
        Q = np.dot(P.T, X) + O
        R = sigmoid(Q)
        cost = -(1/x0)*np.sum( Y*np.log(R) + (1-Y)*np.log(1-R)) # cost function
        # Gradient Descent
        dP = (1/x0)*np.dot(R-Y, X.T)
        dO = (1/x0)*np.sum(R - Y)
        P = P - learning_rate*dP.T
        O = O - learning_rate*dO
        # Keeping track of our cost function value
        cost_list.append(cost)
        if(i%(iterations/10) == 0):
            print("iterations: ", i, "cost: ", cost)
    return P, O, cost_list

iterations = 100000
learning_rate = 0.0015
P, O, cost_list = model(x_tn, y_tn, learning_rate = learning_rate, iterations = iterations)

iterations: 0 cost: 0.6931471805599454
iterations: 10000 cost: 0.49652777693895306
iterations: 20000 cost: 0.46674868550666
iterations: 30000 cost: 0.45687787762434423
iterations: 40000 cost: 0.45288994293089646
iterations: 50000 cost: 0.4509326025222643
iterations: 60000 cost: 0.4497708749009468
iterations: 70000 cost: 0.4489640829216279
iterations: 80000 cost: 0.44834126966124827
iterations: 90000 cost: 0.44783045246935776

plt.plot(np.arange(iterations), cost_list)
plt.show()

```





```
def accuracy(X, Y, P, O):  
    Q = np.dot(P.T, X) + O  
    R = sigmoid(Q)  
    R = R > 0.5  
    R = np.array(R, dtype = 'int64')  
    acc = (1 - np.sum(np.absolute(R - Y))/Y.shape[1])*100  
    print("Accuracy of the model is : ", round(acc, 2), "%")
```

```
accuracy(x_tt, y_tt, P, O)
```

Accuracy of the model is : 91.39 %

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