Math189R SU17 Homework 1 Wednesday, May 17, 2017

Feel free to work with other students, but make sure you write up the homework and code on your own (no copying homework *or* code; no pair programming). Feel free to ask students or instructors for help debugging code or whatever else, though. The starter code for problem 2 part c and d can be found under the Resource tab on course website.

*Note:* You need to create a Github account for submission of the coding part of the homework. Please create a repository on Github to hold all your code and include your Github account username as part of the answer to problem 2.

1 (Linear Transformation) Let y = Ax + b be a random vector. show that expectation is linear:

$$\mathbb{E}[\mathbf{y}] = \mathbb{E}[A\mathbf{x} + \mathbf{b}] = A\mathbb{E}[\mathbf{x}] + \mathbf{b}.$$

Also show that

$$\operatorname{cov}[\mathbf{y}] = \operatorname{cov}[A\mathbf{x} + \mathbf{b}] = A\operatorname{cov}[\mathbf{x}]A^{\top} = A\Sigma A^{\top}.$$

First show for expectation value

E[Ax+b] = S(Ax+b) S(x) dx = SAx8(x) dx + 6 SE(x) dx = AE[x]+6
where S(x) is the probability density function for X
and b is a constant vector

Nex+ show for covariance

COU [Ax+b] = E[(Ax+b-E(Ax+b)) (Ax+b-E[Ax+b])]

=E[(Ax+b-AE[x]-b)(Ax+b-AE[x]-b)]

= AE[(x-E[x])(x-E(x))]AT

= A \( \) AT

where \( \xi = cou(x) \) and A is a constant matrix

- **2** Given the dataset  $\mathcal{D} = \{(x,y)\} = \{(0,1),(2,3),(3,6),(4,8)\}$ 
  - (a) Find the least squares estimate  $y = \theta^{\top} x$  by hand using Cramer's Rule.
  - (b) Use the normal equations to find the same solution and verify it is the same as part (a).
  - (c) Plot the data and the optimal linear fit you found.
  - (d) Find randomly generate 100 points near the line with white Gaussian noise and then compute the least squares estimate (using a computer). Verify that this new line is close to the original and plot the new dataset, the old line, and the new line.

bd) see attached code

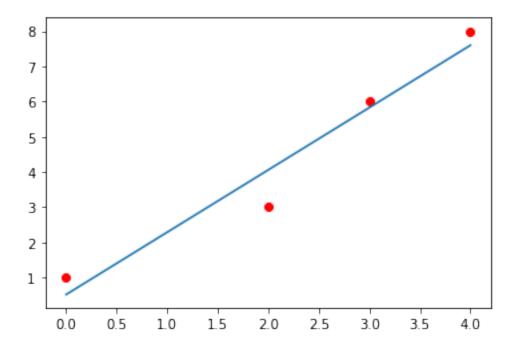
## hw1pr2

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b) Perform the linear regression using the normal equation

[26]: [<matplotlib.lines.Line2D at 0x1121b0320>]

```
[9]: import numpy as np
      X = np.array([[0,1],
                     [2,1],
                     [3,1],
                     [4,1]])
      Y = np.array([1,3,6,8])
[16]: theta = np.linalg.inv(X.T@X)@X.T@Y
      print(theta)
     [1.77142857 0.51428571]
     Now let's verify that's the same as on paper
[18]: 62/35
[18]: 1.7714285714285714
[19]: 18/35
[19]: 0.5142857142857142
     yayyyyy!
       c) Plot the data and the linear fit
[20]: import matplotlib.pyplot as plt
[26]: plt.scatter(X[:,0],Y,c='r')
      x = np.linspace(0,4,100)
      y = 62*x/35 + 18/35
      plt.plot(x,y)
```



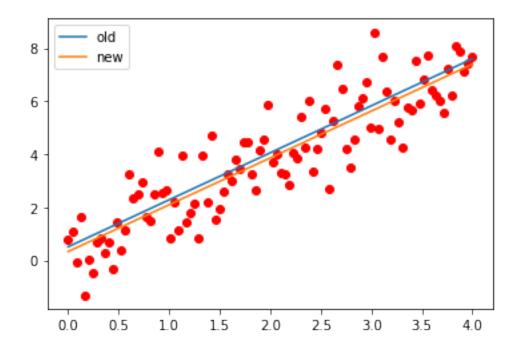
Looks decent to me.

d) generate 100 points with white gaussian noise and get a new least squares estimate. I'm using a variance of 1

```
[36]: noise = np.random.normal(0,1,100)
    X_noise = np.hstack((x.reshape(100,1),np.ones(100).reshape(100,1)))
    Y_noise = y+noise
    theta_noise = np.linalg.inv(X_noise.T@X_noise)@X_noise.T@Y_noise

[39]: plt.scatter(x,Y_noise,c='r')
    y_pred_noise = x*theta_noise[0]+theta_noise[1]
    plt.plot(x,y)
    plt.plot(x,y_pred_noise)
    plt.legend(('old','new'))
```

[39]: <matplotlib.legend.Legend at 0x112114518>



Indeed it does look close to the original fit