

Computer Vision

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Women in Science Japan

July 26th, 2025, Tokyo

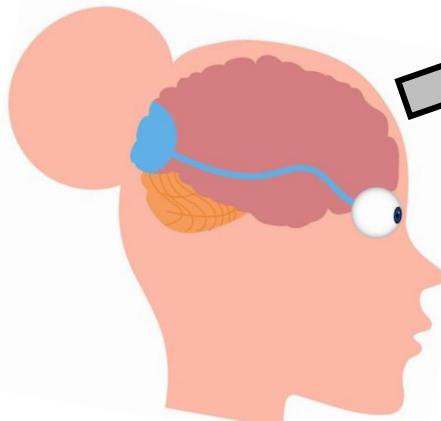




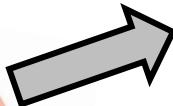
- ❑ Computer Vision
- ❑ History
- ❑ Tasks
- ❑ Applications
- ❑ Current models
- ❑ Limitations of deep learning
- ❑ Our recent research



- Looking at picture and visual interpretation



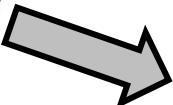
Human



Complex functions in brain



Machine



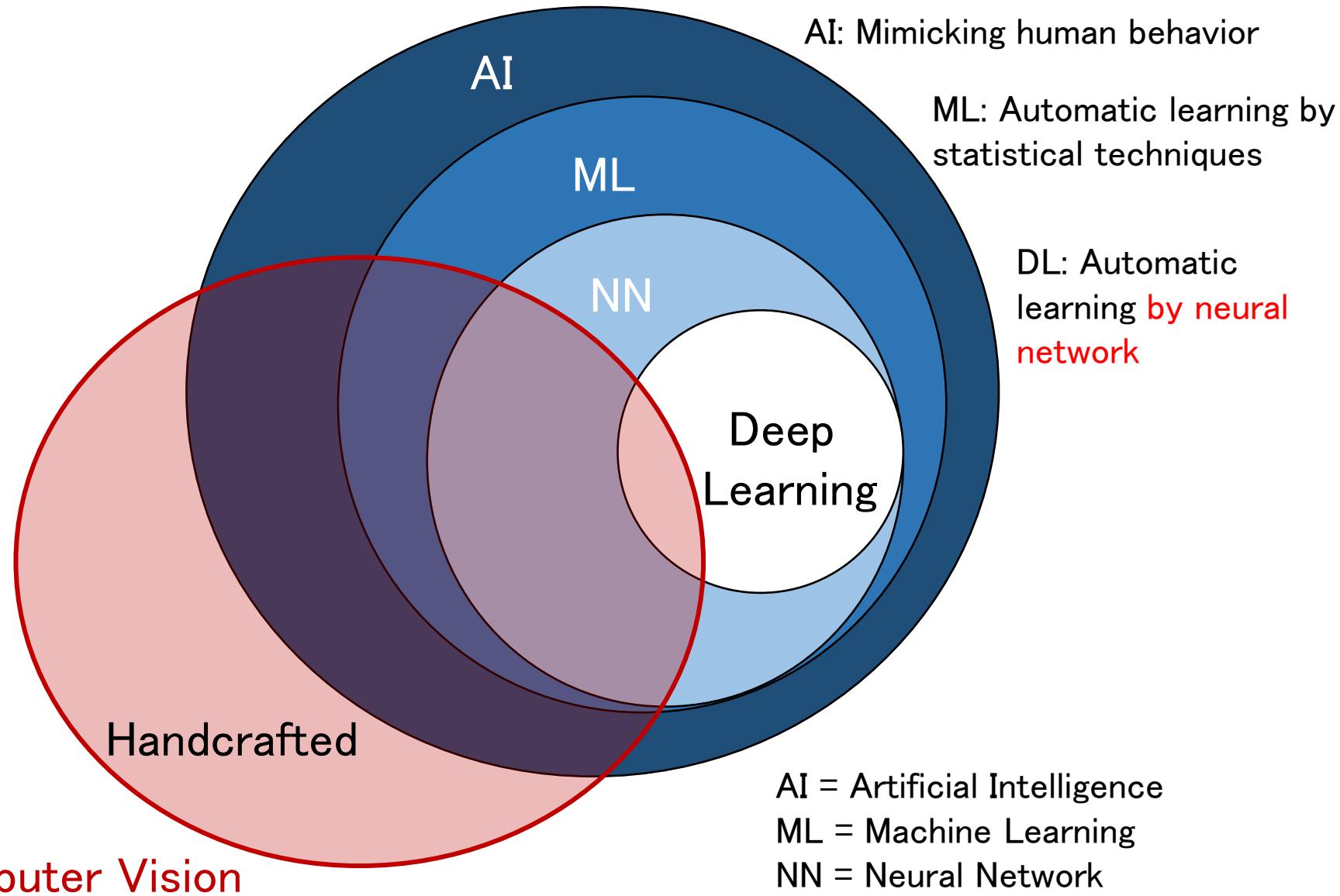
Various image processing algorithms
Computer Vision



Picture



❑ Algorithms

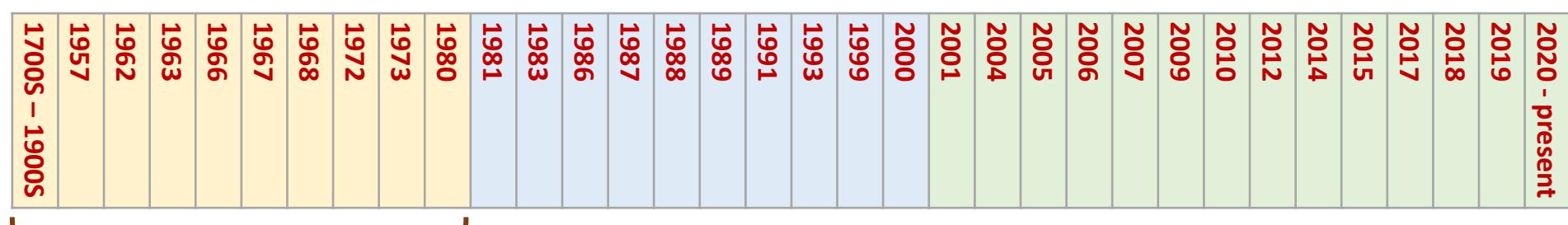




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□ Years of groundbreaking works in computer vision



1700S-1900S

1962

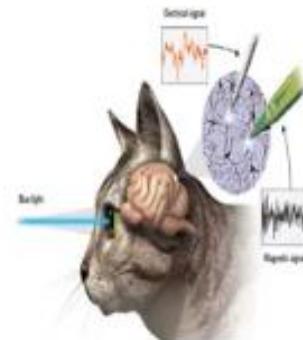
1966

1972

1980



Early development
in field of light and
vision



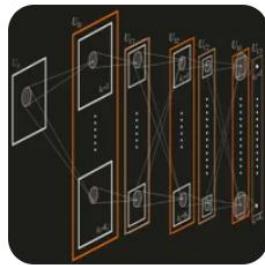
Research on
visual cortex



Summer vision
project



Hough Transform

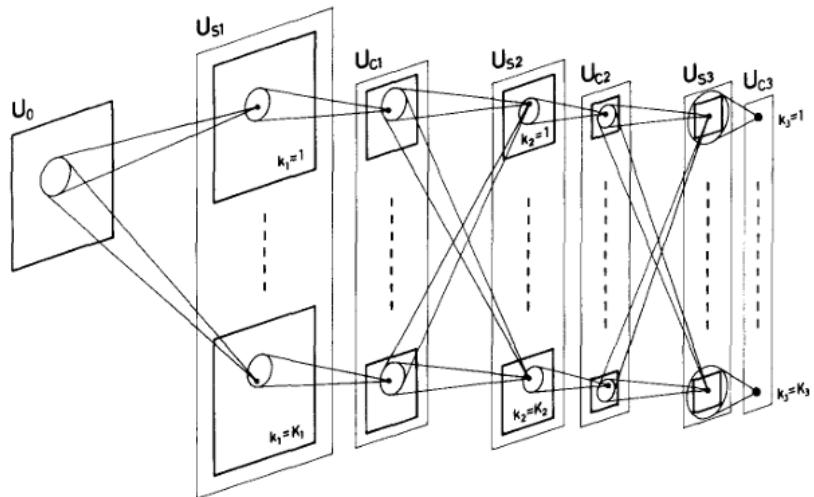


NeoCognitron

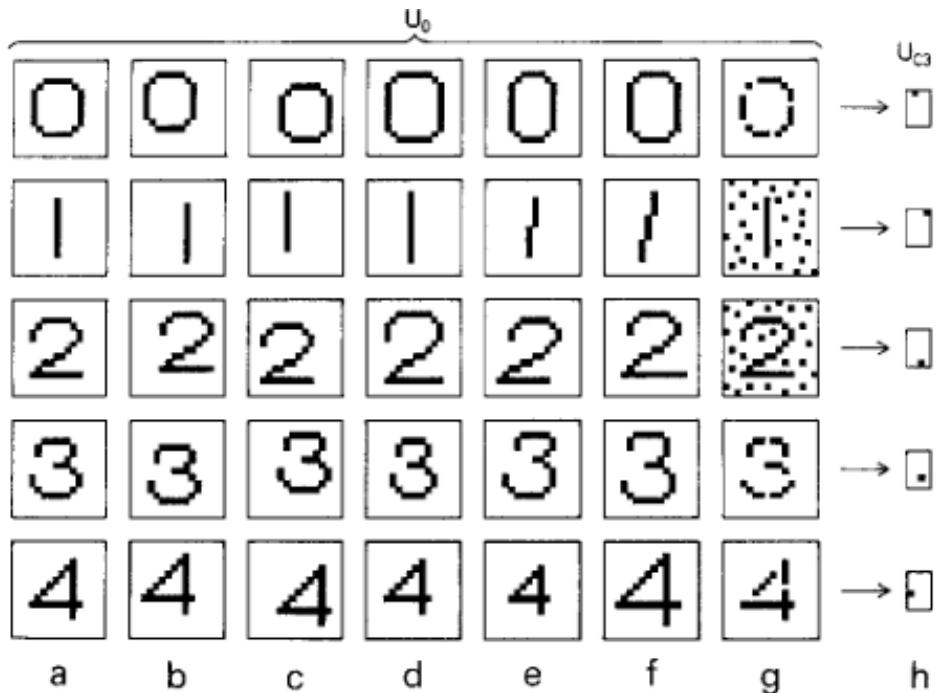


❑ NeoCognitron

A mechanism of visual pattern recognition by [neural network](#)



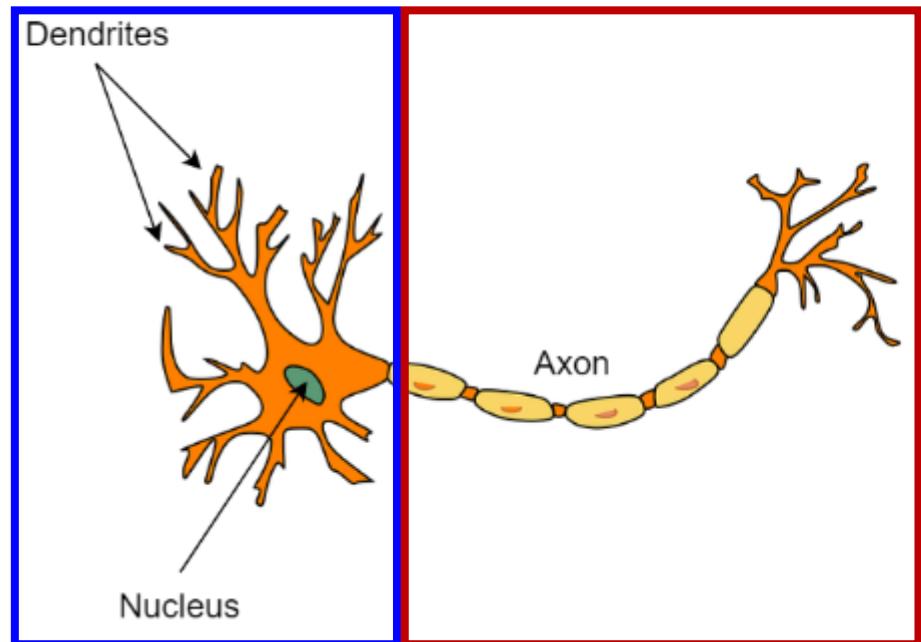
Network architecture



Example of correctly recognized pattern



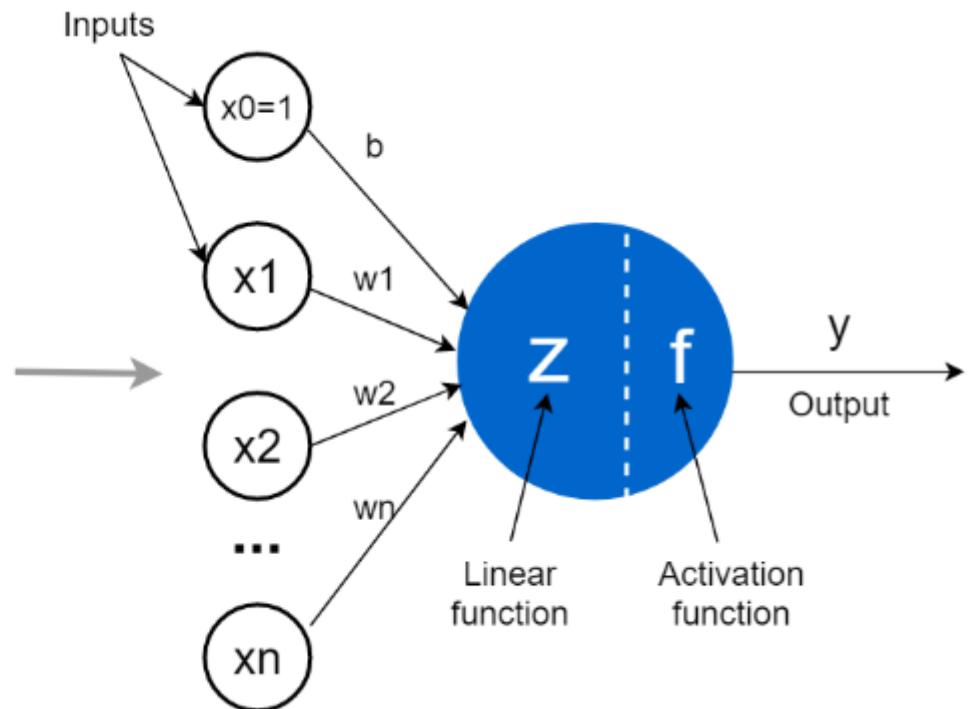
□ Concept of neuron (perceptron)



Linear function

Activation and output

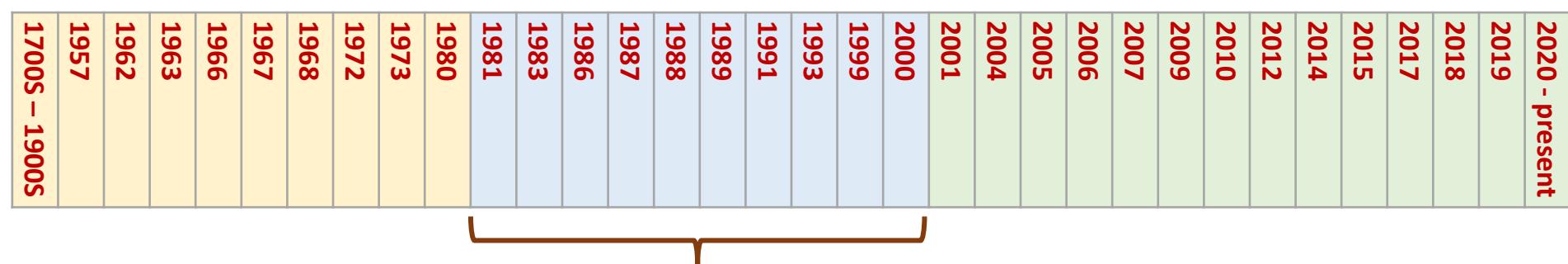
Neuron in living body



Neuron in neural network



Years of groundbreaking works in computer vision



1981

1983

1986

1991

1999

2000



Lucas-Kanade
Optical Flow
algorithm



Vision By
David Marr



3D shape
recovery
from
images



Eigenfaces
algorithm



SIFT



OpenCV



❑ OpenCV

Open-source computer vision software contains 2500 optimized algorithms

The screenshot shows the OpenCV University website's homepage. The header features the OpenCV logo and navigation links for Library, Forum, OpenCV University (which is highlighted), New Course, Free Courses, Services, Face Recognition, Contribute, and Resources. A search icon is also present. The main title 'About' is prominently displayed in white text against a blue background.

OpenCV (Open Source Computer Vision Library) is an open source computer vision and machine learning software library. OpenCV was built to provide a common infrastructure for computer vision applications and to accelerate the use of machine perception in the commercial products. Being an Apache 2 licensed product, OpenCV makes it easy for businesses to utilize and modify the code.

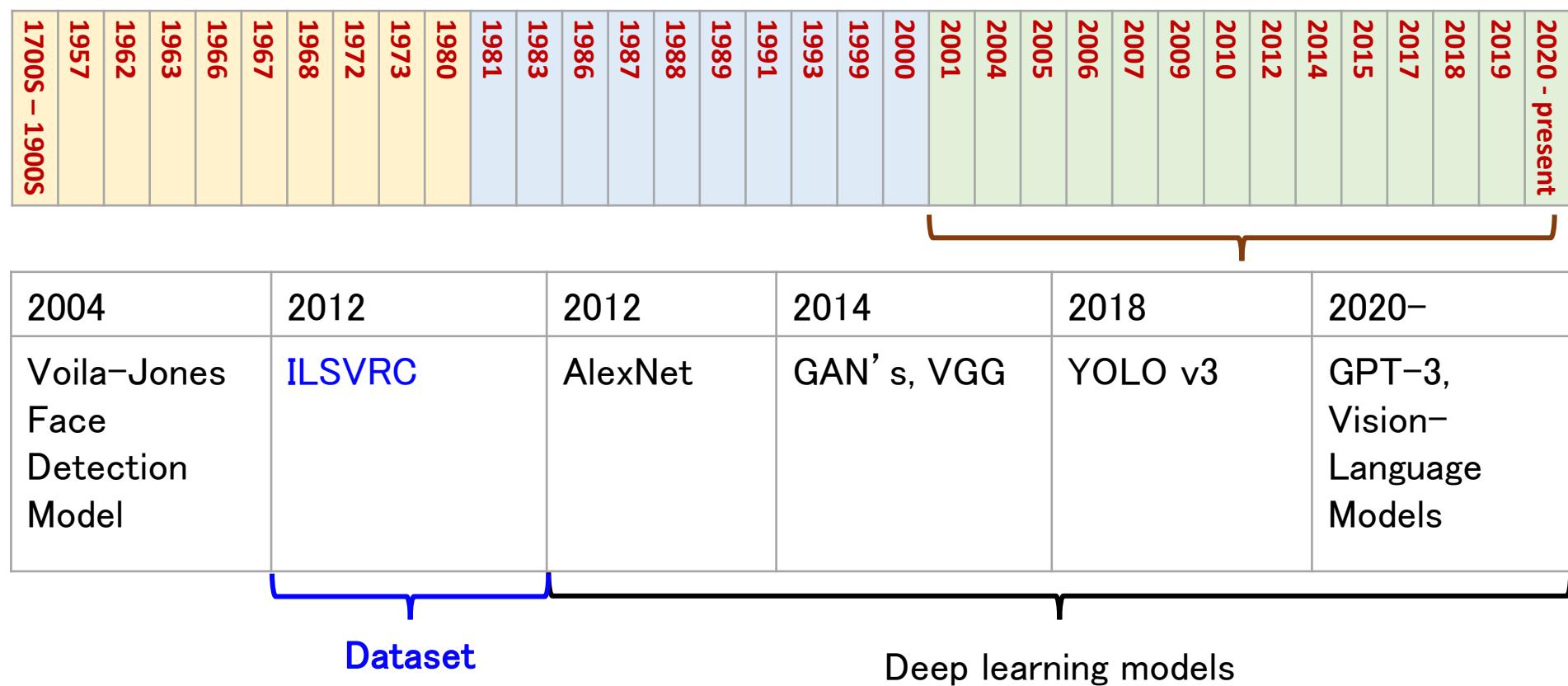
The library has more than 2500 optimized algorithms, which includes a comprehensive set of both classic and state-of-the-art computer vision and machine learning algorithms. These algorithms can be used to detect and recognize faces, identify objects, classify human actions in videos, track camera movements, track moving objects, extract 3D models of objects, produce 3D point clouds from stereo cameras, stitch images together to produce a high resolution image of an entire scene, find similar images from an image database, remove red eyes from images taken using flash, follow eye movements, recognize scenery and establish markers to overlay it with augmented reality, etc. OpenCV has more than 47 thousand people of user community and estimated number of downloads exceeding [18 million](#). The library is used extensively in companies, research groups and by governmental bodies.

Along with well-established companies like Google, Yahoo, Microsoft, Intel, IBM, Sony, Honda, Toyota that employ the library, there are many startups such as Applied Minds, VideoSurf, and Zeitera, that make extensive use of OpenCV. OpenCV's deployed uses span the range from stitching streetview images together, detecting intrusions in surveillance video in Israel, monitoring mine equipment in China, helping robots navigate and pick up objects at Willow Garage, detection of swimming pool drowning accidents in Europe, running interactive art in Spain and New York, checking runways for debris in Turkey, inspecting labels on products in factories around the world on to rapid face detection in Japan.

It has C++, Python, Java and MATLAB interfaces and supports Windows, Linux, [Android](#) and Mac OS. OpenCV leans mostly towards real-time vision applications and takes advantage of MMX and SSE instructions when available. A full-featured [CUDA](#) and [OpenCL](#) interfaces are being actively developed right now. There are over 500 algorithms and about 10 times as many functions that compose or support those algorithms. OpenCV is written natively in C++ and has a templated interface that works seamlessly with STL containers.



Years of groundbreaking works in computer vision





☐ ILSVRC: A pivotal benchmark in computer vision



14,197,122 images, 21841 synsets indexed
Home Download Challenges About

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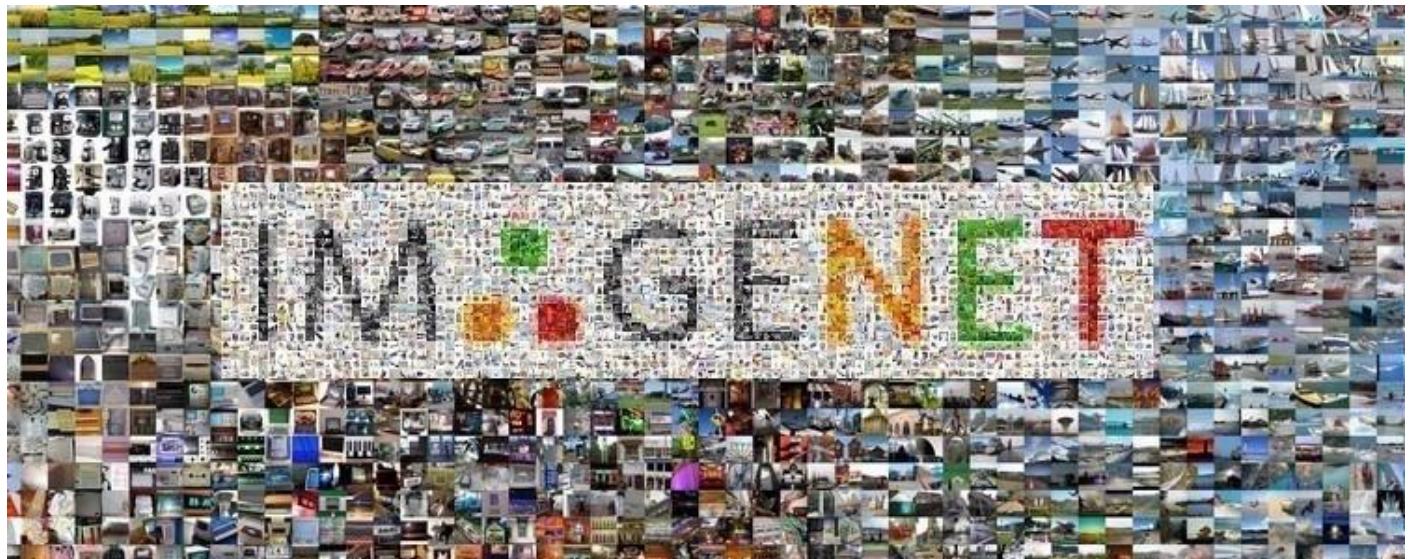
ImageNet Large Scale Visual Recognition Challenge (ILSVRC)

Competition

The ImageNet Large Scale Visual Recognition Challenge (ILSVRC) evaluates algorithms for object detection and image classification at large scale. One high level motivation is to allow researchers to compare progress in detection across a wider variety of objects -- taking advantage of the quite expensive labeling effort. Another motivation is to measure the progress of computer vision for large scale image indexing for retrieval and annotation.

For details about each challenge please refer to the corresponding page.

- [ILSVRC 2017](#)
- [ILSVRC 2016](#)
- [ILSVRC 2015](#)
- [ILSVRC 2014](#)
- [ILSVRC 2013](#)
- [ILSVRC 2012](#)
- [ILSVRC 2011](#)
- [ILSVRC 2010](#)



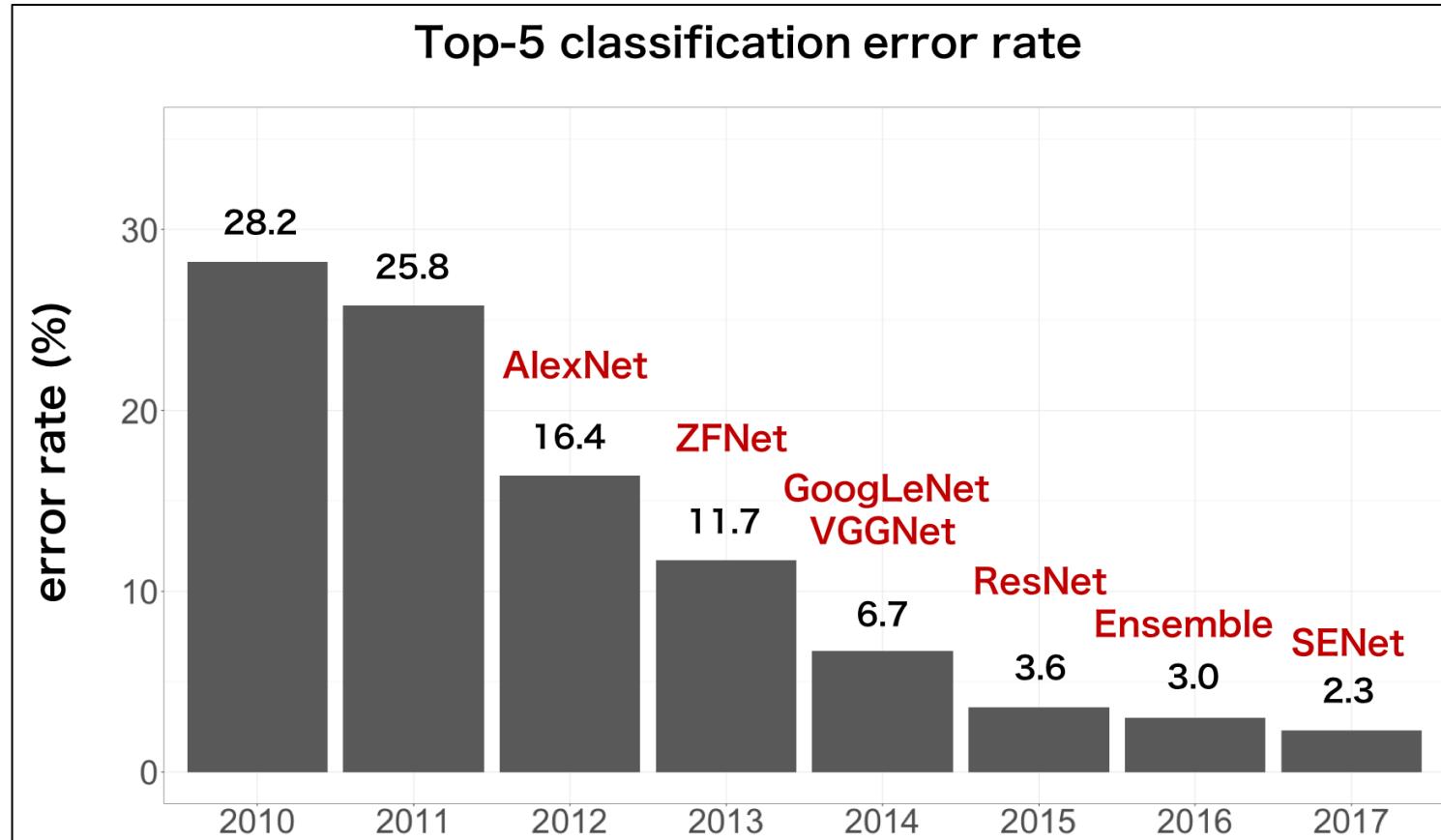
Sources:

<https://www.image-net.org/challenges/LSVRC/index.php>

<https://deargen.blog/2016/12/23/deargen-won-at-ilsvrc-2016-imagenet-large-scale-visual-recognition-challenge/>



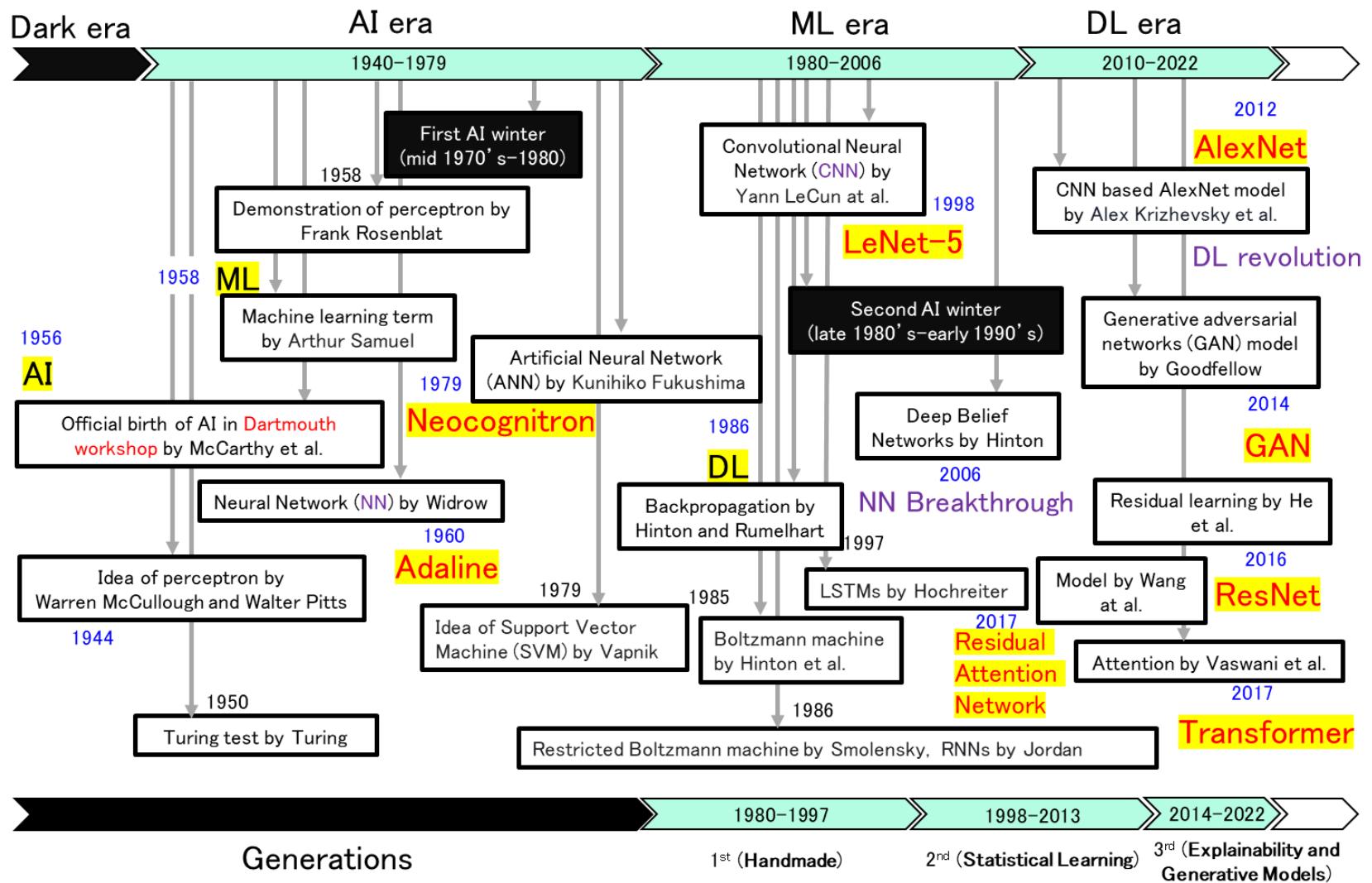
❑ Performance of models on ILSVRC challenge



- **ImageNet dataset** is widely used for pre-training deep learning networks, particularly in computer vision tasks
- Dataset plays a crucial roles in training deep learning models



Timeline of Deep learning

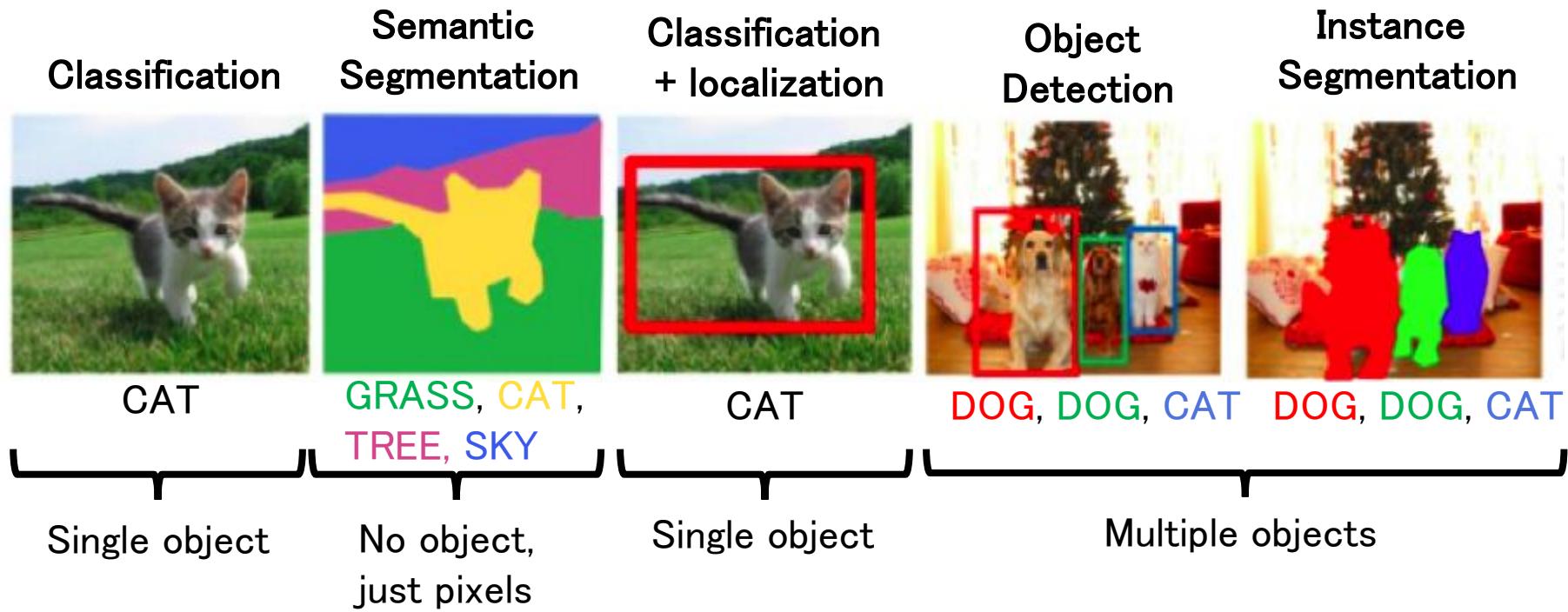




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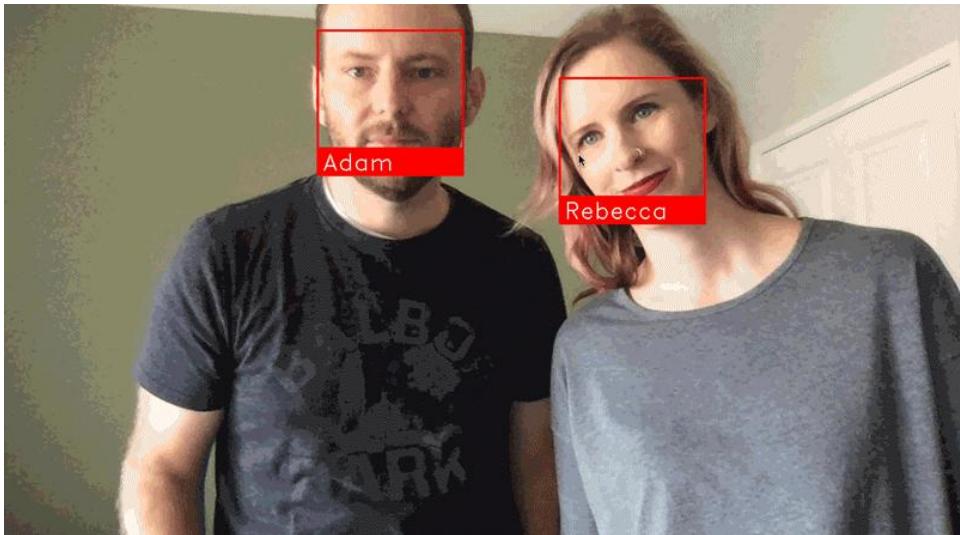
❑ Popular computer vision tasks





❑ Popular computer vision tasks

Face and person recognition



Video motion analysis



❑ Others

- Edge detection
- Image restoration
- Matching scene reconstruction

Image source: https://github.com/ageitgey/face_recognition

Video source: https://www.youtube.com/watch?v=oA_C040vLZs&t=1s&ab_channel=OpenCVAI



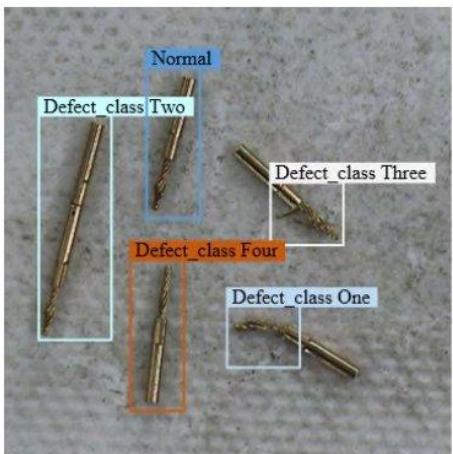
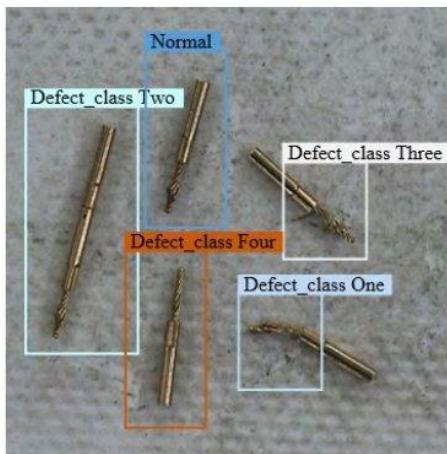
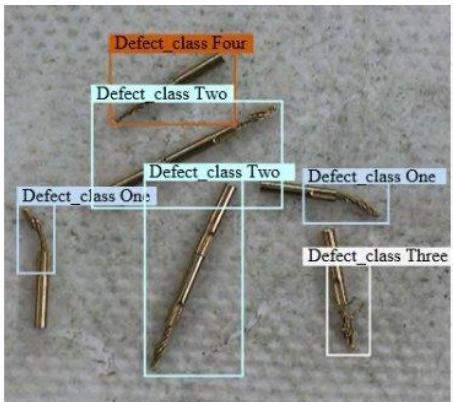
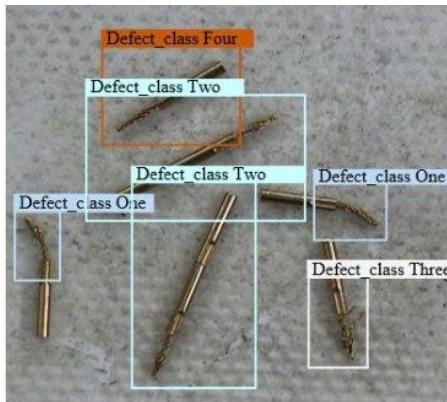
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Applications

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Manufacture



Agriculture



3 erosomyia_sp

3 erosomyia_sp	93%
2 erosomyia_sp	4%
2 procontarinia_rubus	1%

3 erosomyia_sp

3 erosomyia_sp	97%
2 erosomyia_sp	2%
3 apoderus_javanicus	0%

2 ischnaspis_longirostris

2 ischnaspis_longirostris	99%
1 ischnaspis_longirostris	0%
3 erosomyia_sp	0%

1 apoderus_javanicus

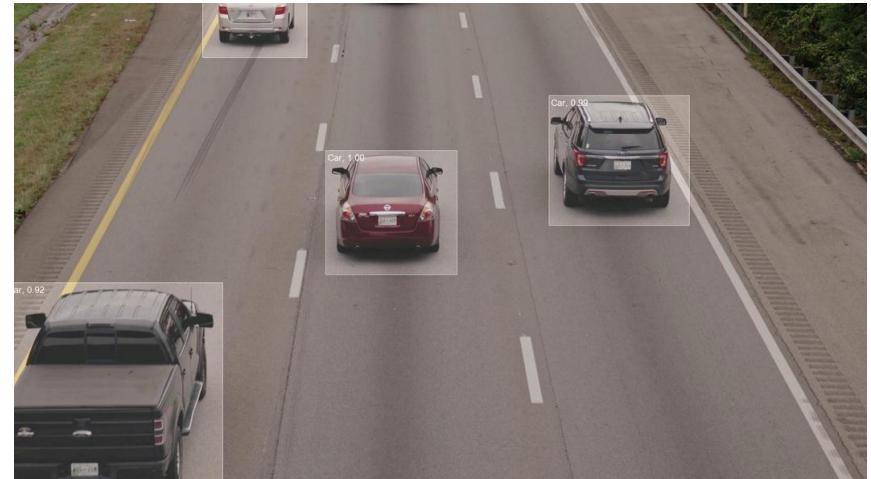
1 apoderus_javanicus	99%
2 apoderus_javanicus	1%
3 apoderus_javanicus	0%

Applications

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Autonomous



Healthcare



Sports



Surveillance & Security



Image sources:

<https://viso.ai/applications/computer-vision-applications/>

<https://viso.ai/applications/computer-vision-in-healthcare/>

<https://www.superannotate.com/blog/computer-vision-in-security-and-surveillance>

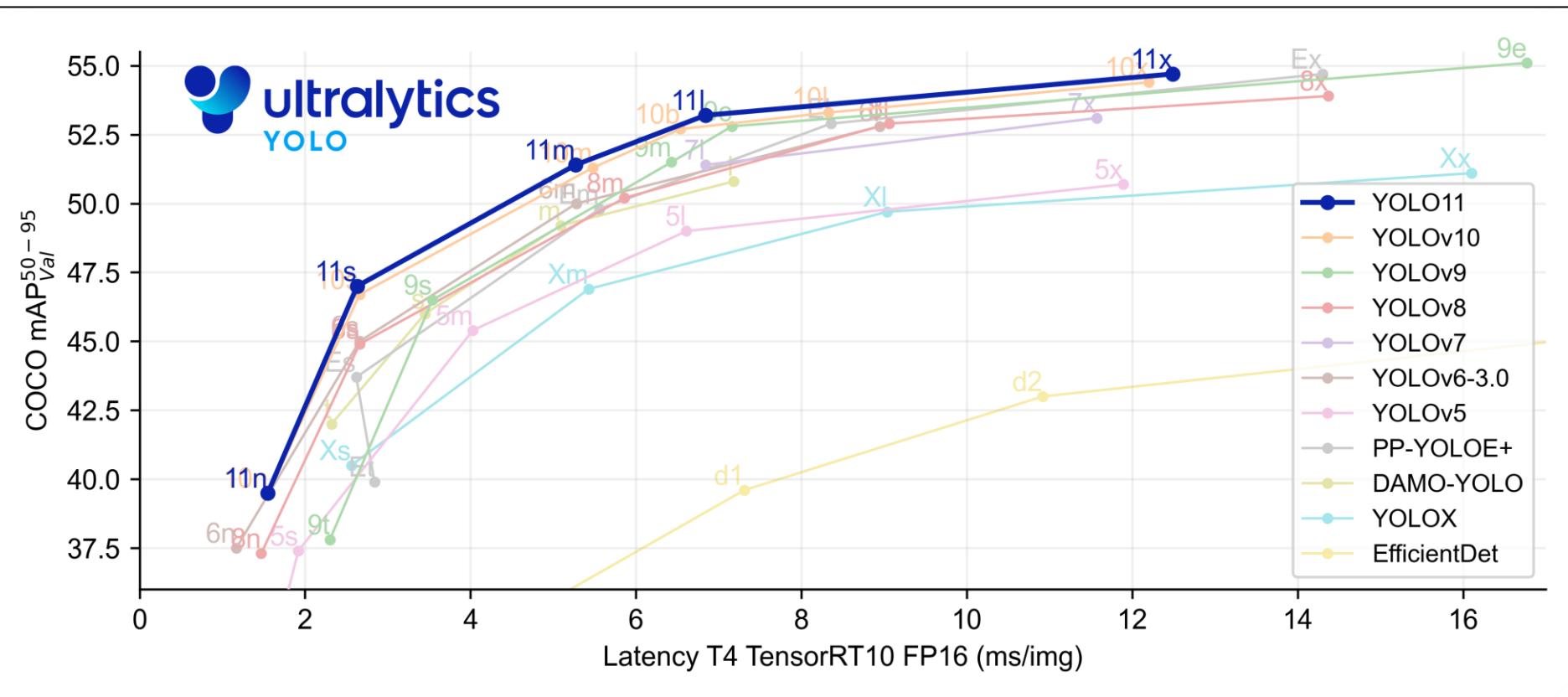


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□ Deep Learning–Powered Algorithms: Object detection

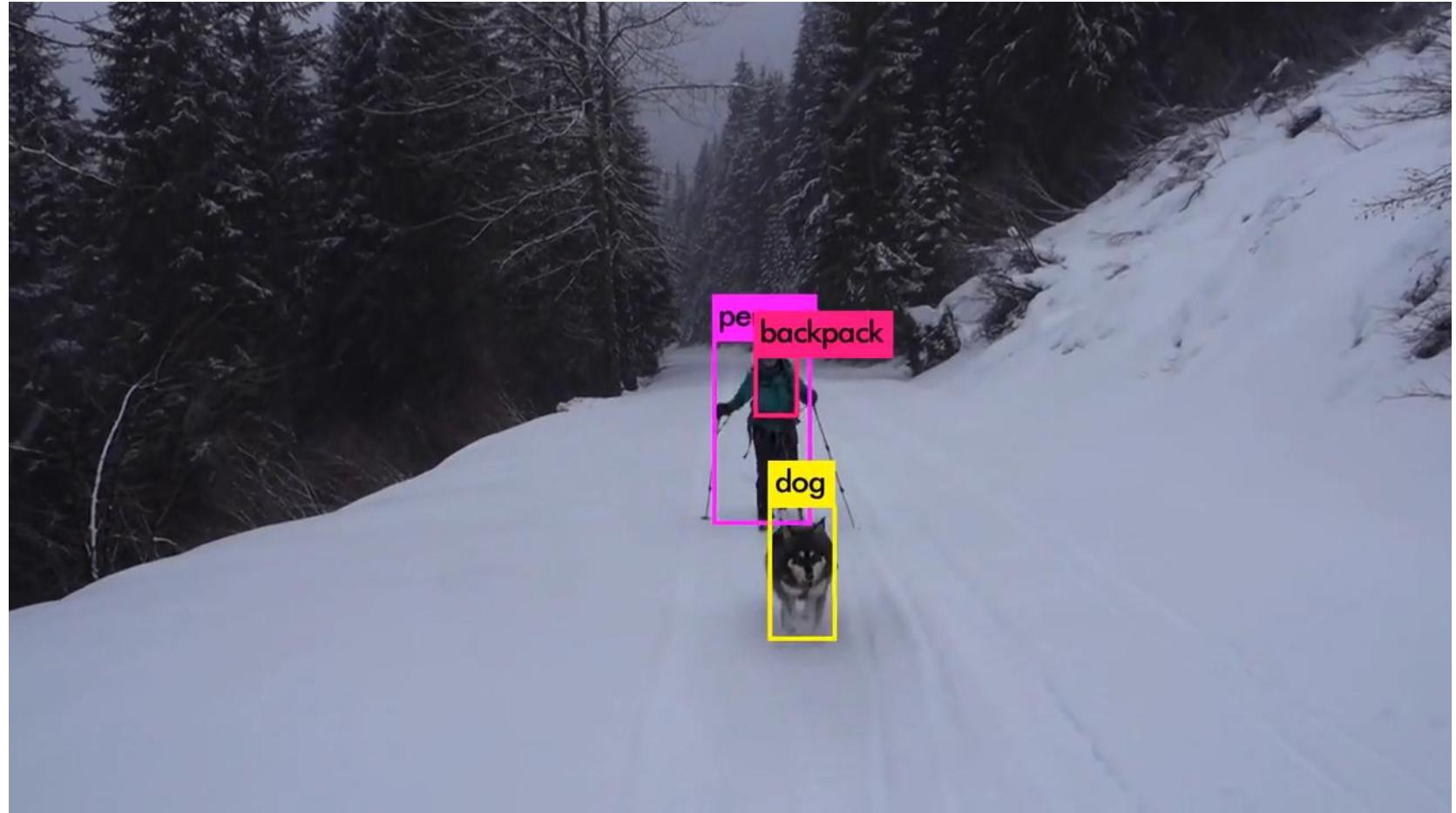
➤ YOLO (You Only Look Once)





□ Deep Learning–Powered Algorithms: Object detection

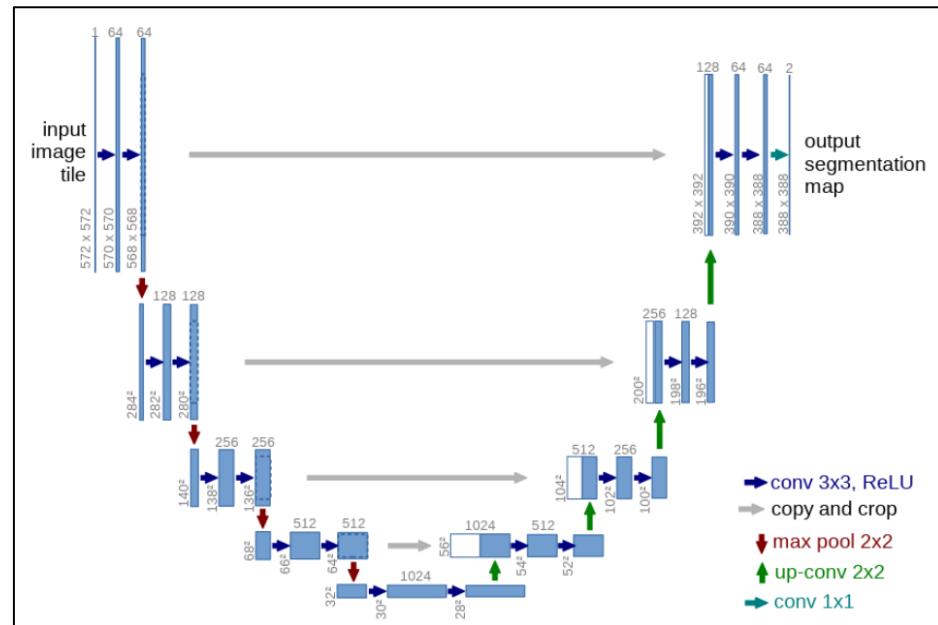
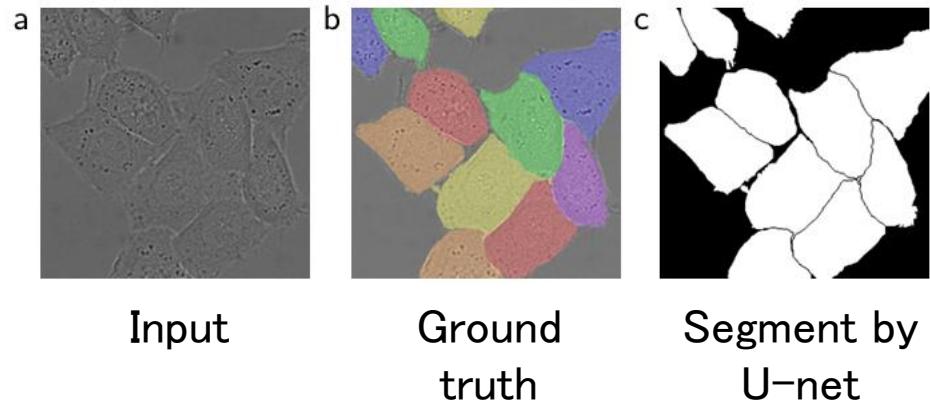
➤ YOLO (You Only Look Once)





□ Deep Learning–Powered Algorithms: Segmentation

➤ U-net (2012)



HeLa cell segmentation

Architecture

Source: Ronneberger, Olaf, Philipp Fischer, and Thomas Brox. "U-net: Convolutional networks for biomedical image segmentation." Medical image computing and computer-assisted intervention—MICCAI 2015: 18th international conference, Munich, Germany, October 5–9, 2015, proceedings, part III 18. Springer international publishing, 2015.



□ Deep Learning–Powered Algorithms: Segmentation

➤ SAM (Segment Anything Model)

Segment Anything
Research by Meta AI

Home Demo Dataset Blog Paper 

When hovering over the image, SAM is running in the browser.

Tools

Upload Gallery

Hover & Click

Click an object one or more times.
Shift-click to remove regions.

+ Add Mask - Remove Area

Reset Undo Redo

Multi-mask Cut out object

Box

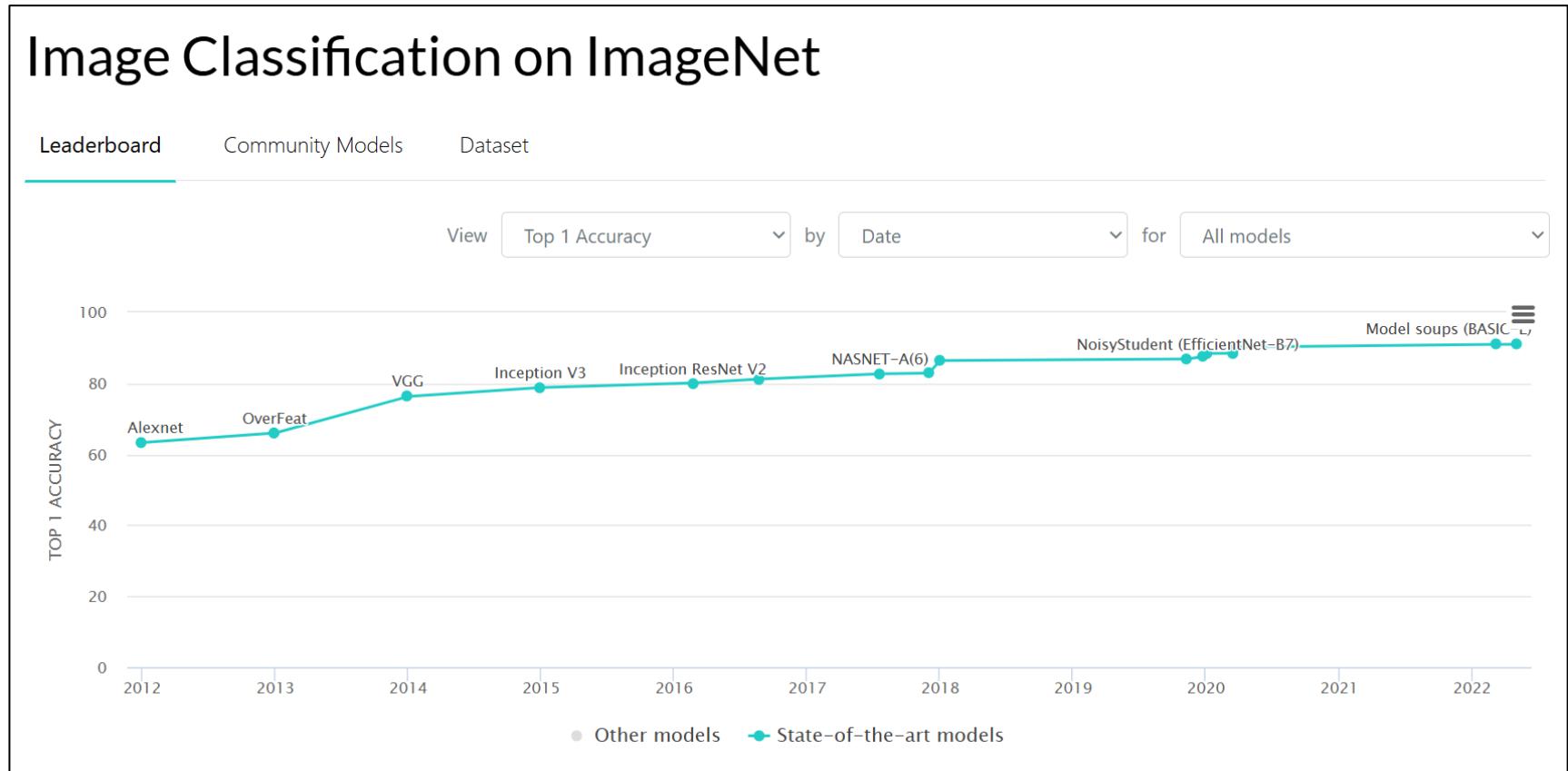
Everything

Cut-Outs



□ Deep Learning–Powered Algorithms: Classification

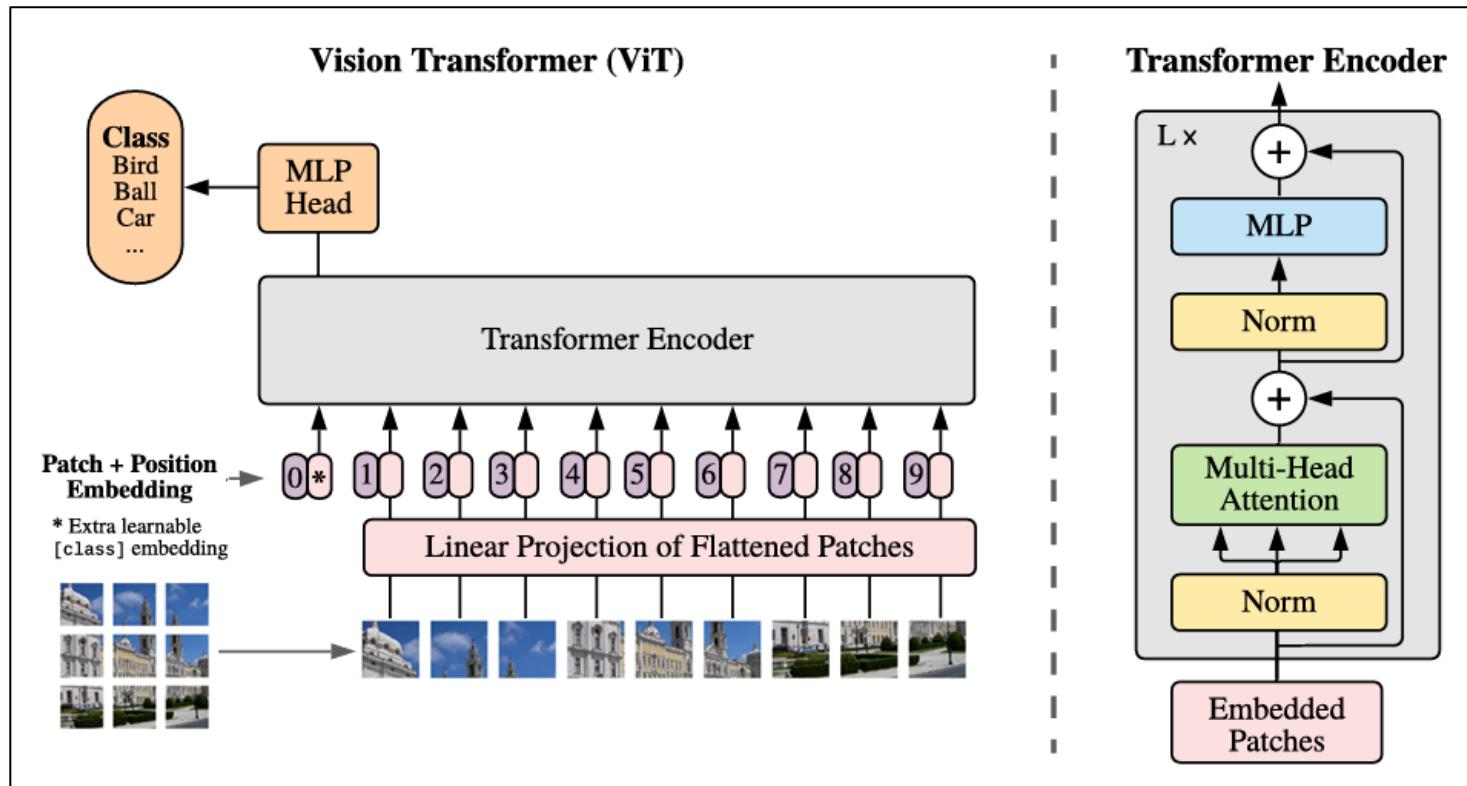
➤ State-of-the-art–models





□ Deep Learning–Powered Algorithms: Classification

➤ Vision Transformer (ViT)



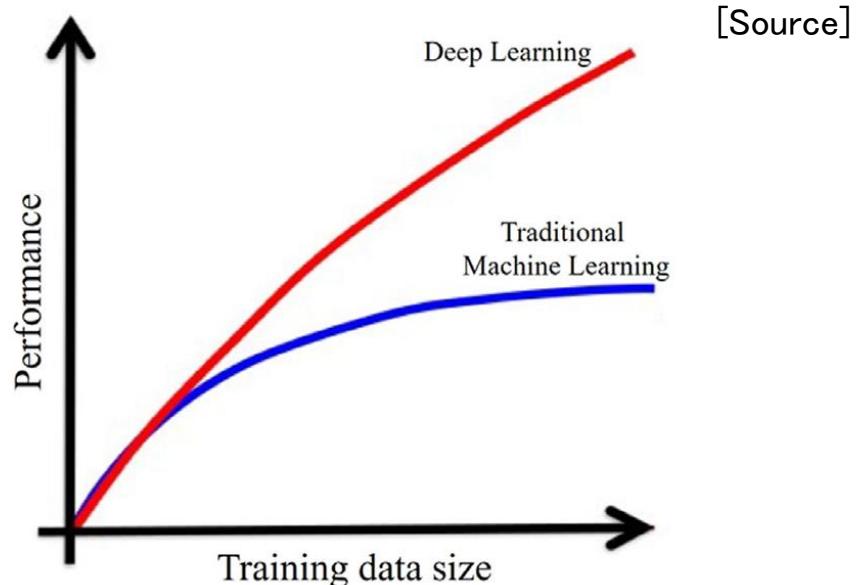
Architecture



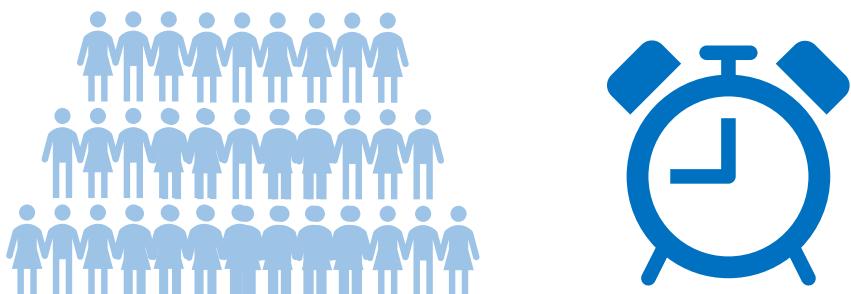
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- ❑ Our recent research



1. Dataset size: Requires large scale dataset



2. Data annotation: Laborious and time-consuming



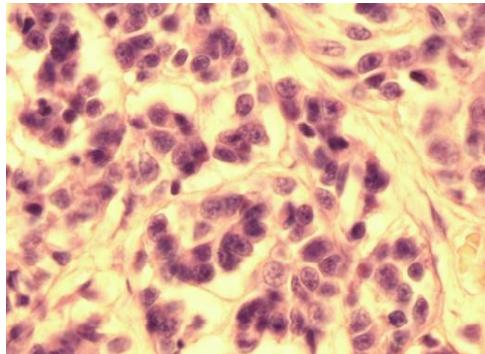
Source: Alyafeai, Z., & Ghouti, L. (2020). A fully-automated deep learning pipeline for cervical cancer classification. *Expert Systems with Applications*, 141, 112951.



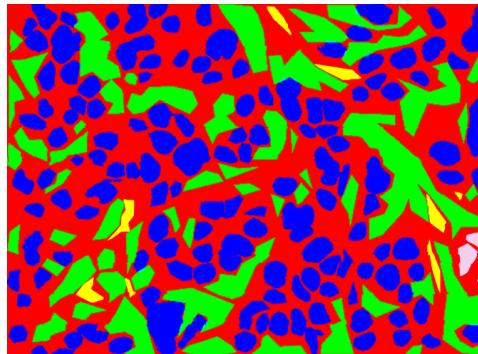
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1. Cancer cytoplasm segmentation^[Source 1]



Image



Segmentation

1. Train detection^[Source 2]



Source 1: R. Sultana, H. Horibe, T. Murakami, and I. Shimizu, "Cancer Cytoplasm Segmentation from Cell Image Based on Transfer Learning", 2024 6th International Conference on Image, Video and Signal Processing, 2024.

Source 2: Y. Inoue, R. Sultana, Y. Nishino, and I. Shimizu, "Enhancing Daytime Train Image Detection with YOLOv8 through Data Augmentation Techniques", 2024 6th Asia Digital Image Processing Conference (ADIP 2024), 2024.

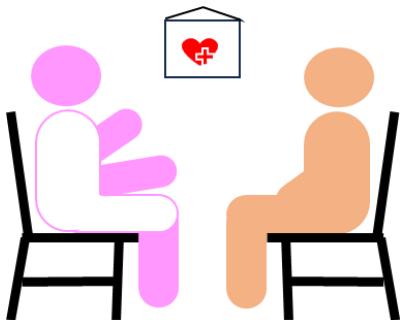
1. Cancer cytoplasm segmentation

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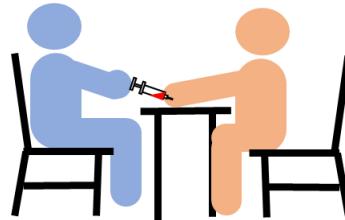


Pathology diagnosis

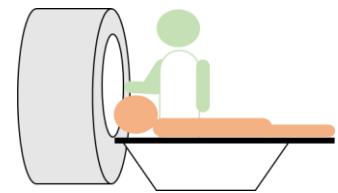
- 1 Consult with doctor



- 2 Various clinical tests

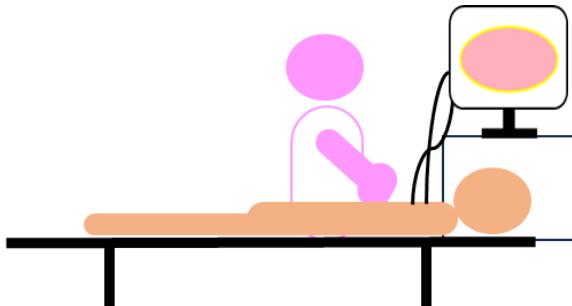


Blood sample

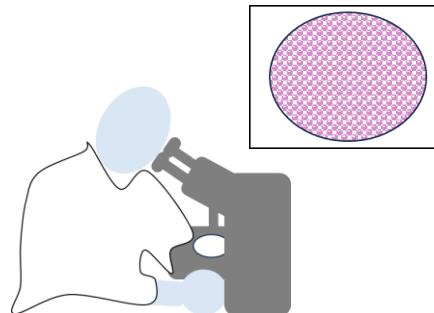


MRI

- 3 Biopsy in critical situation



- 4 Pathological examination



➤ Delaying the decision-making can cause significant loss to patient

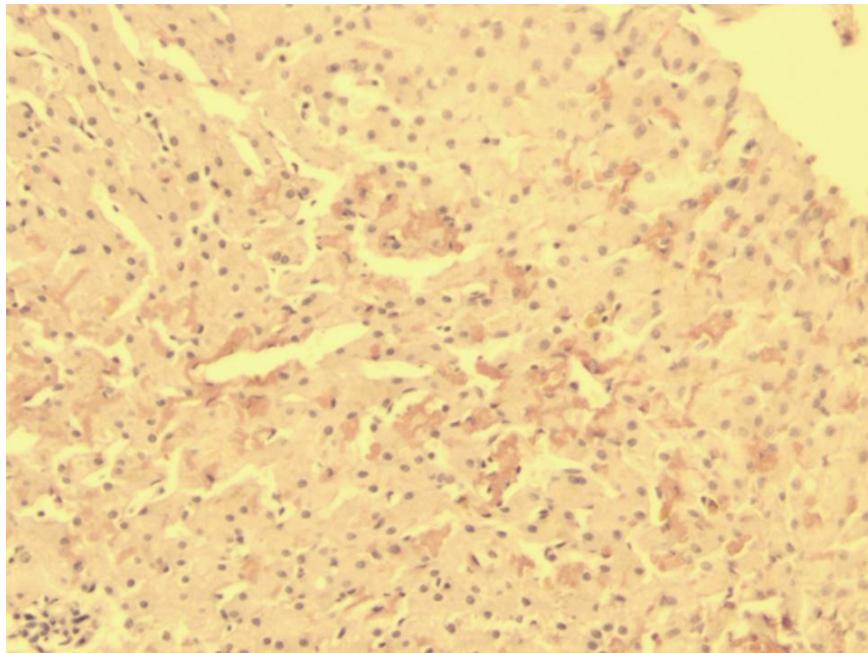
1. Cancer cytoplasm segmentation

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Issues with pathology examination system

1. Shortage of pathologists (Two pathologist for 100 thousand people in Japan)^[Source]
2. Difficult to identify cancer due to irregular shape of cancer cell with naked eye



Cancer cell image

- Digital pathology could support early-stage decision-making to reduce the burden on pathologists

1. Cancer cytoplasm segmentation

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❑ Methods used in digital pathology

- ❑ Digital image analysis [Ruifrok+, 2001]
- ❑ Machine learning algorithm [Ludovic+, 2013]
- ❑ Deep learning models [Arbelle+, 2012]

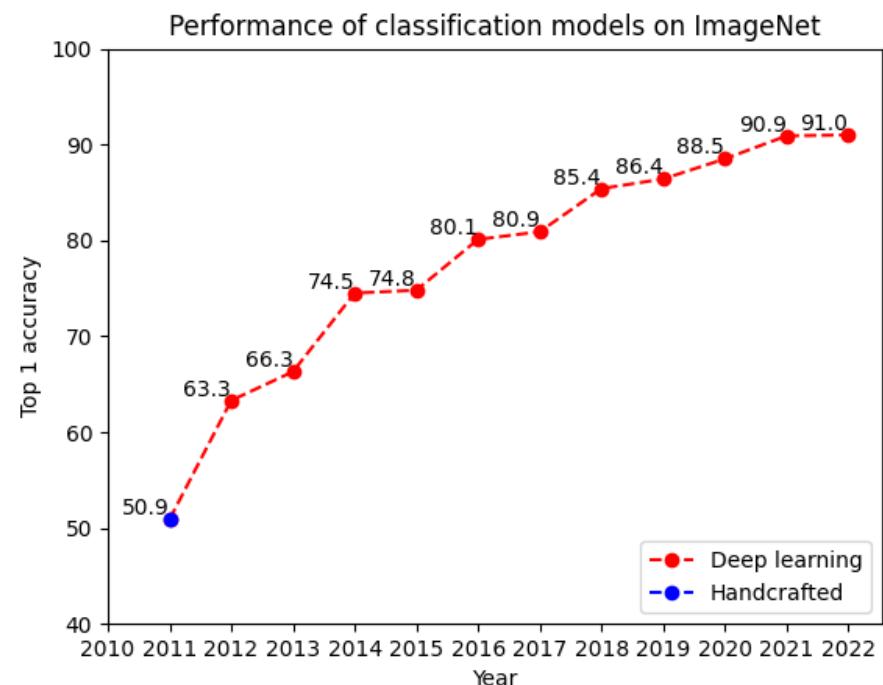


Recent works due to outperformance of deep learning over conventional models

ImageNet dataset [Krizhevsky+, 2012]



Classification of 1000 categories

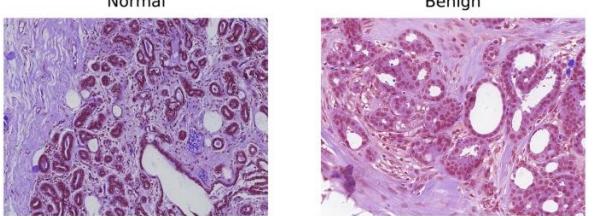
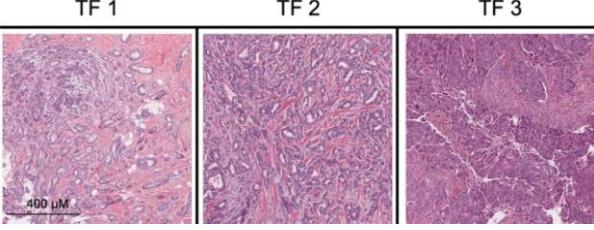
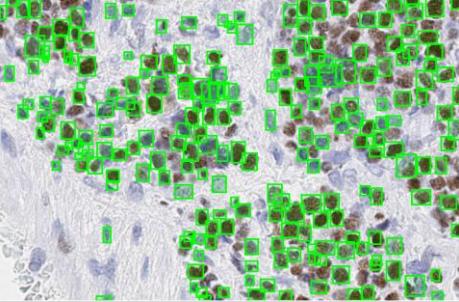
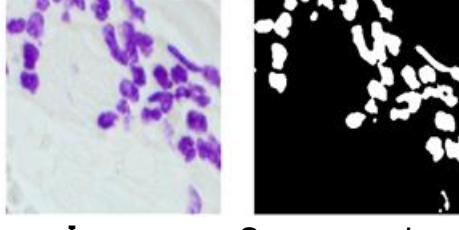


1. Cancer cytoplasm segmentation

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❑ Tasks in pathology image using deep learning

Cell image classification		[Hameed+ 2022]
Cancer grading (Nottingham grading system)	 TF 1 TF 2 TF 3	[Jaroensri+ 2022]
Nuclear detection		[Source]
Nuclear segmentation	 Image Segmented map	[Aydin+2022]

Source: <https://www.kitware.com/cell-nuclei-detection-on-whole-slide-histopathology-images-using-histomicstk-and-faster-r-cnn-deep-learning-models/>

1. Cancer cytoplasm segmentation

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Challenge in pathology image analysis task using deep learning

- Lack of dataset for various tasks

Example of histopathological dataset

Dataset	Task
MoNuSeg	Nuclear segmentation
TNBC	
UCSB	
BreakHis	Cancer classification
ARCH	Multiple instance captioning

Cancer cytoplasm is one of the important elements for cancer type identification in pathology



To the best of our knowledge, no dataset is available for cancer cytoplasm detection research



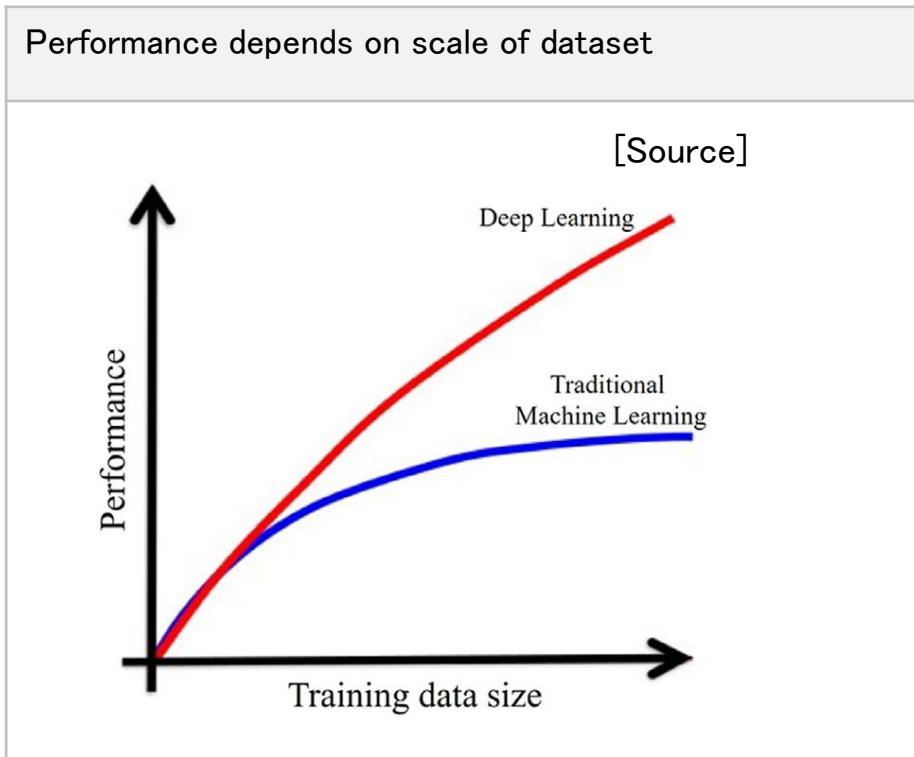
We introduce deep learning to the cancer cytoplasm segmentation of cell images

1. Cancer cytoplasm segmentation

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Important factors in training deep learning



■ How to learn deep learning model with small dataset?

1. Pre-training/ fine-tuning → Also known as transfer learning
2. Data augmentation

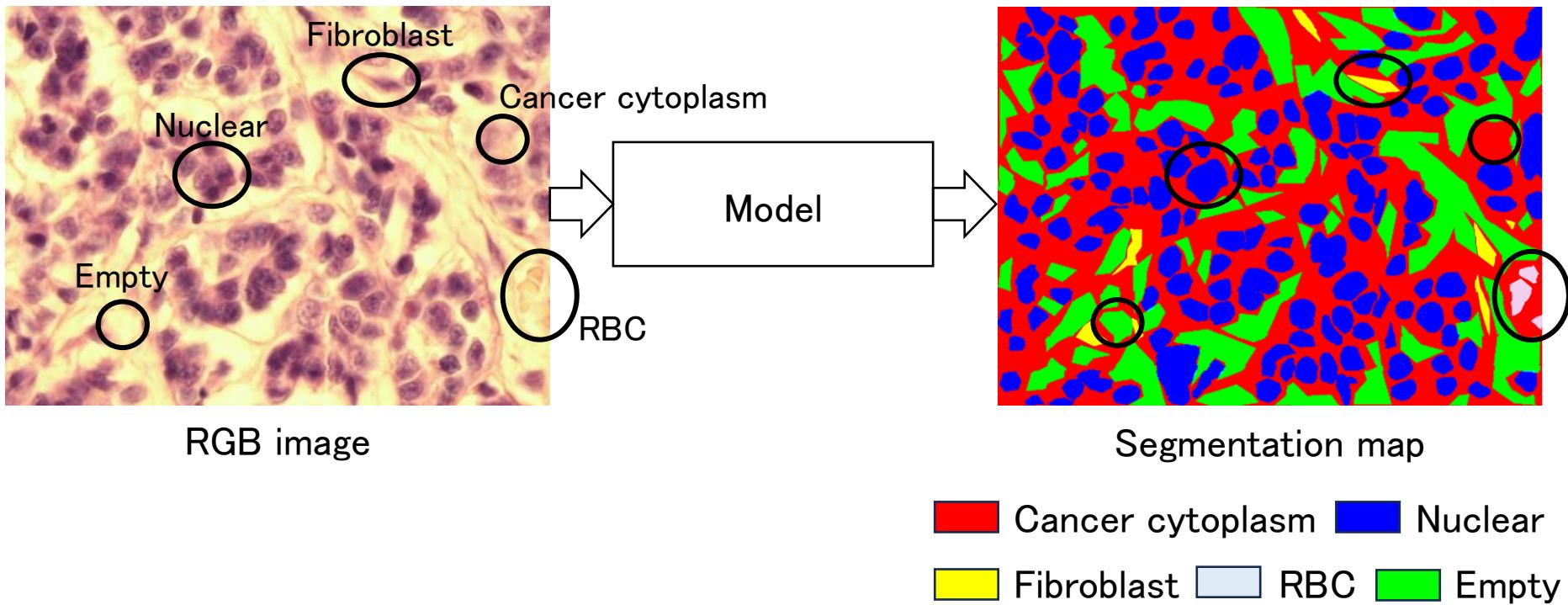
1. Cancer cytoplasm segmentation

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Purpose

Segmentation of cancer cytoplasm in RGB cell images using deep learning model with transfer learning approach



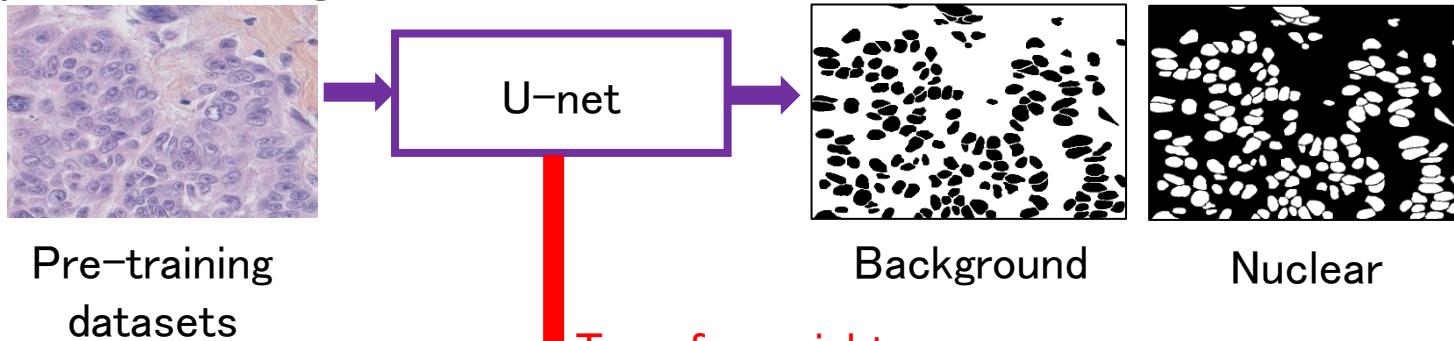
1. Cancer cytoplasm segmentation

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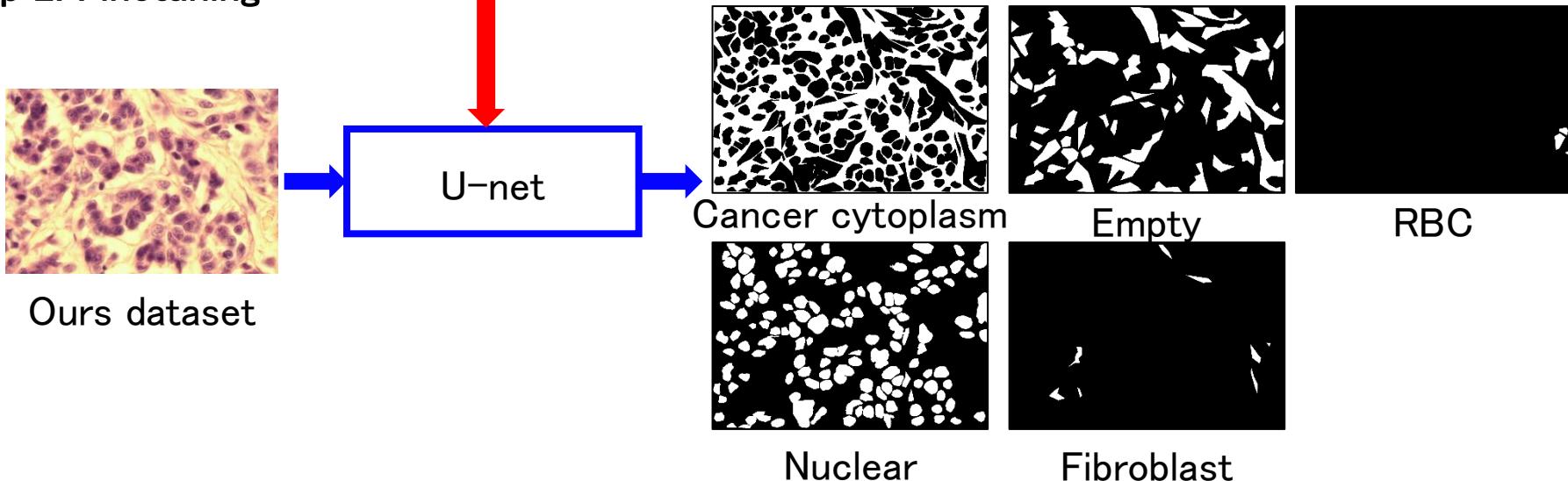


Proposed method

Step 1: Pre-training



Step 2: Finetuning

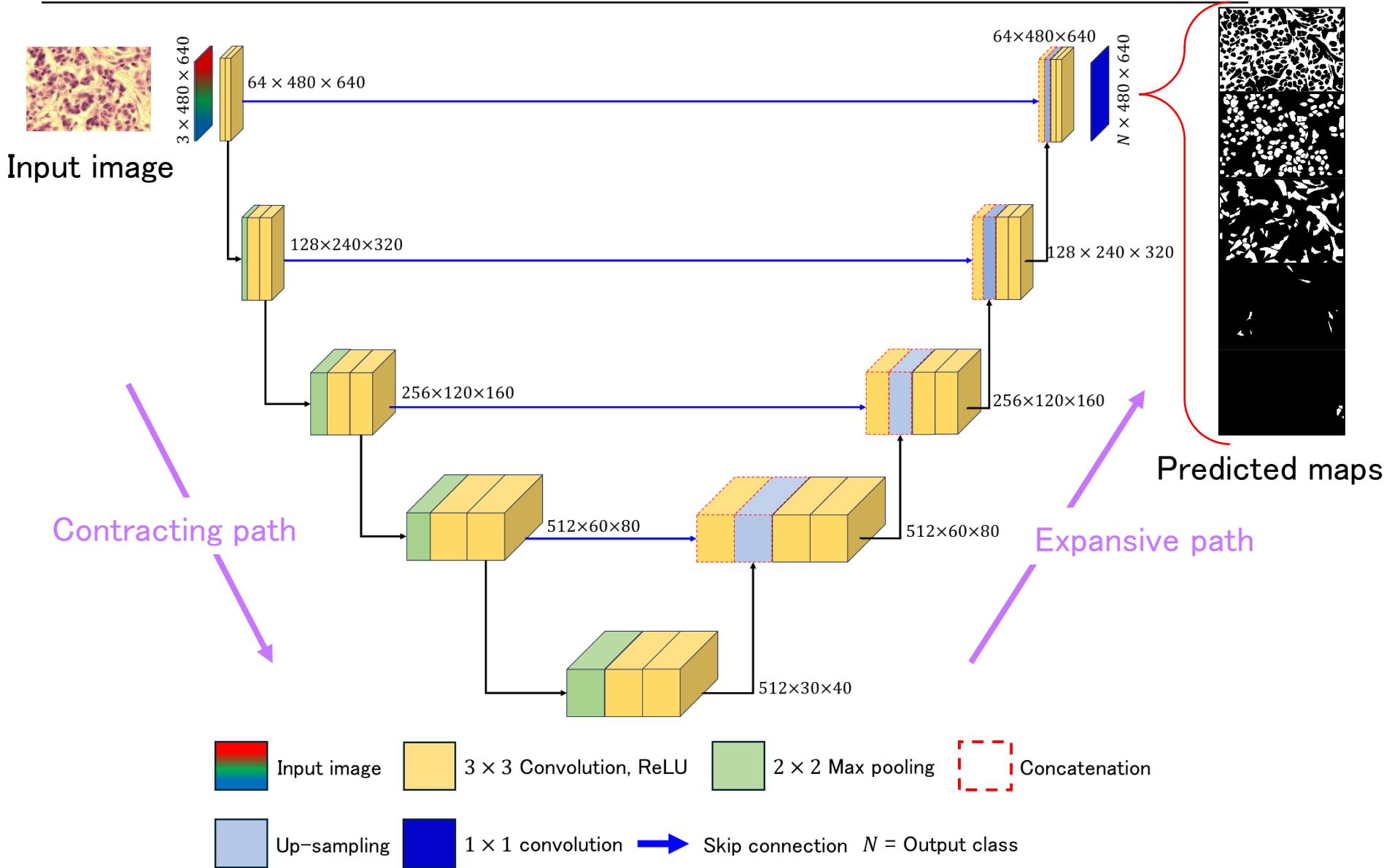


1. Cancer cytoplasm segmentation



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❑ U-net architecture is selected due to it's effectiveness in different tasks



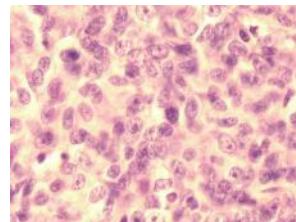
1. Cancer cytoplasm segmentation

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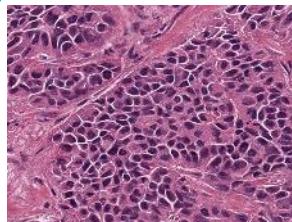


❑Dataset

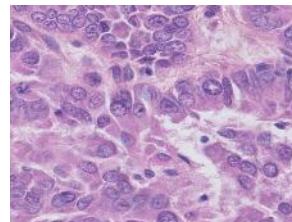
Dataset	Images	Segment class	Type	Capture technique		
Ours	44	5 (cytoplasm, nuclear, fibroblast, RBC, empty)	Cancer	H&E stained		
MoNuSeg	37	2 (nuclear, background)				
TNBC	50					
UCSB	58					
Fluo-N2DH-GOWT1	184	2 (nuclear, background)	–	Fluorescence		
Fluo-C2DL-MSC	96		Tropism			
fluocells	283		–			
DIC-C2DH-HeLa	168	2 (nuclear, background)	Cancer	Differential Interference Contrast		
PhC-C2DH-U373	230			Phase contrast		



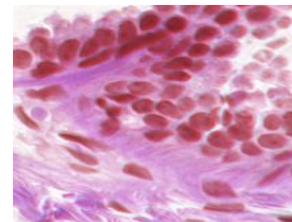
Ours



MoNuSeg



TNBC



UCSB

Fine-tuning dataset

Pre-training datasets

1. Cancer cytoplasm segmentation

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Training condition

➤ Dataset

Dataset	Images	Segmented objects						Total
		Cancer cytoplasm	Nuclear	Background/ Empty	Fibroblast	RBC		
Ours	Train: 24 Valid: 6 Test: 14	343	10526	5344	260	34	16507	
MoNuSeg	37	–	34774	147	–	–	34921	47029
TNBC	50	–	8052	110	–	–	8162	
UCSB	58	–	3783	163	–	–	3946	

1. Cancer cytoplasm segmentation

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Training condition

➤ Environment

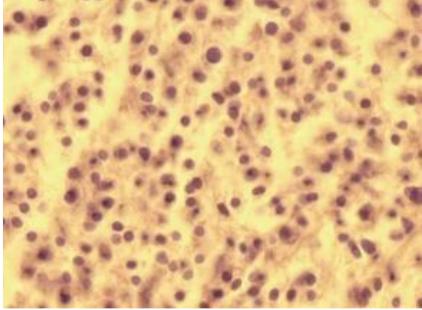
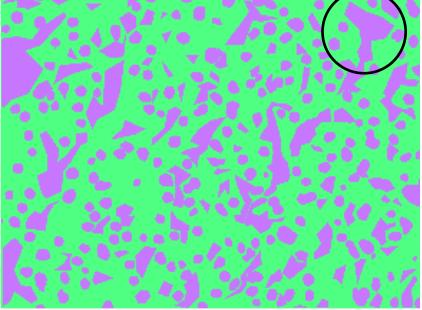
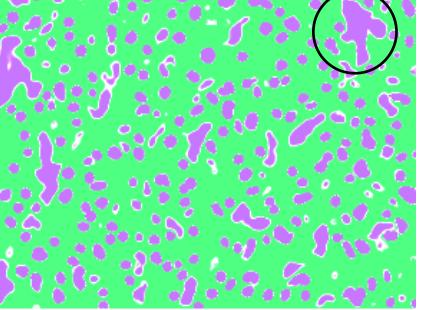
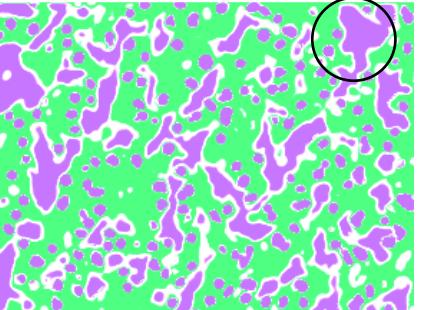
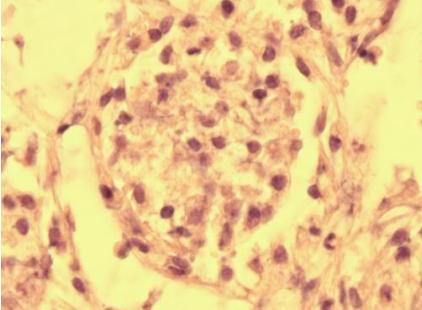
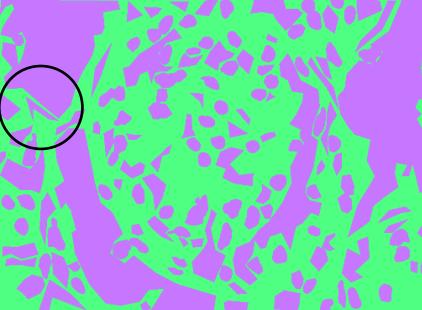
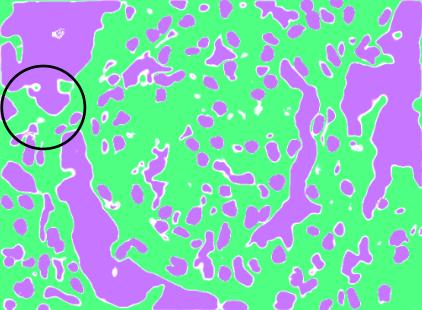
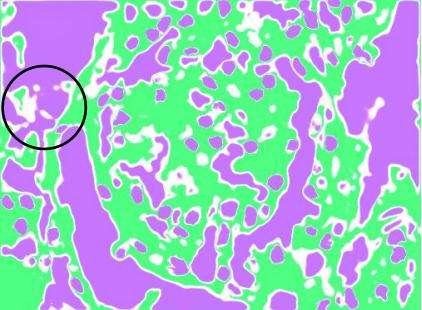
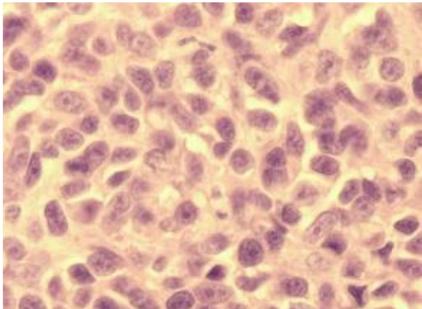
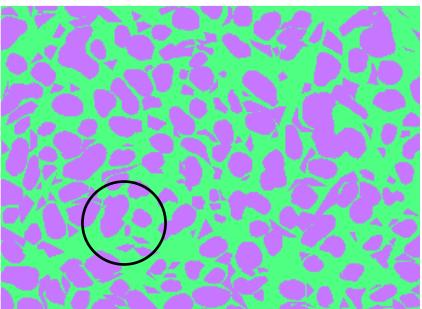
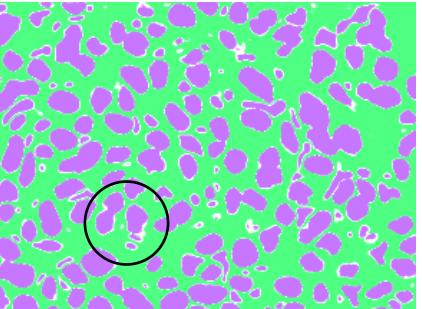
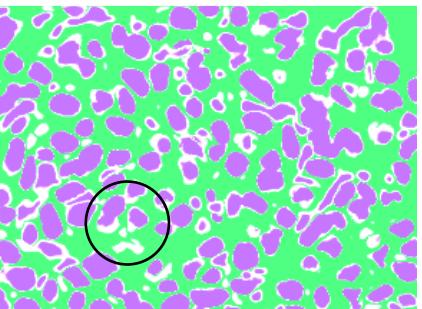
CPU	Intel® CoreTM i9-10900K CPU @ 3.70GHz 32GB
GPU	NVIDIA GeForce RTX 3090 24GB GPU
Image size	640×480
Epoch	Pre-training: 400 Finetuning: 100
Evaluation metrics	IoU, dice coefficient
Optimizer	RMSprob
Learning rate	0.0001
Framework	PyTorch
Programming language	Python

1. Cancer cytoplasm segmentation

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Qualitative results

Image	Ground truth	Proposed method (with pre-training)	Comparison method (without pre-training)
			
			
			

█ Cancer cytoplasm █ Other area █ Overlapped area of cancer cytoplasm and other area

1. Cancer cytoplasm segmentation

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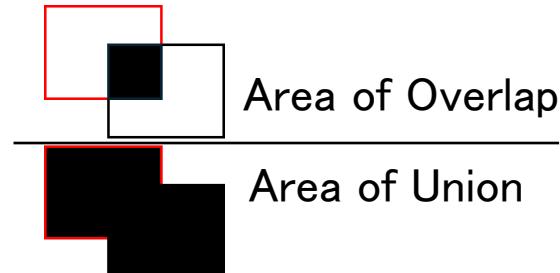


☐ Quantitative results

Method	Transfer learning	IoU (↑)	Dice coefficient (↑)
Proposed	✓	69.02 (+14%)	80.45 (+2%)
Comparison	✗	60.56	78.85

IoU = Measure of segmentation accuracy
Dice coefficient = Balanced evaluation of segmentation performance
↑ = the higher the score is the better the model performance is

Intersect Over Union (IoU) =



 Target object
 Predicted object

Dice coefficient

$$= \frac{2 \times \text{Area of Overlap}}{\text{Total area}}$$

The diagram shows the same red-outlined target object and white-outlined predicted object from the IoU diagram. The overlapping area is shaded black and labeled 'Area of Overlap'. Below it is a rectangle divided into two equal halves: the left half is red-outlined (Target object), and the right half is white-outlined (Predicted object). The total width of the rectangle is labeled 'Total area'.

1. Cancer cytoplasm segmentation

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❑ Ablation analysis

➤ Evaluation class

Method	Classes		With pre-training		Without pre-training	
	Training	Evaluation	IoU (↑)	Dice coefficient (↑)	IoU (↑)	Dice coefficient (↑)
1	5	2 (proposed)	69.02	80.45	60.56	71.85
		5	44.58	50.93	43.95	50.30
2	2	2	67.31	79.10	61.77	74.32

➤ Image pattern matching

Method	Train set	Test set	Pre-training	IoU (↑)	Dice coefficient (↑)
1	Ours	Ours	×	61.77	74.32
2	UCSB + MoNuSeg+ TNBC	Ours	×	10.85	17.24

↑ indicates the higher the score is the better the model performance is

1. Cancer cytoplasm segmentation

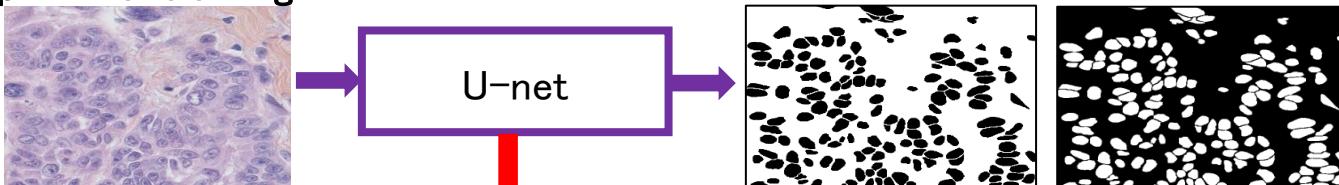
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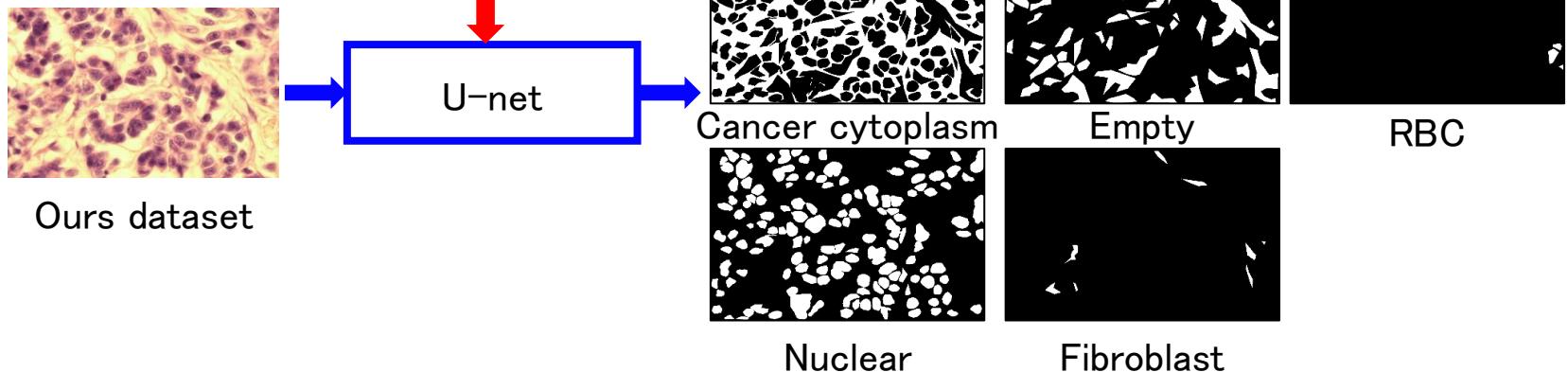
Task overview

- Cancer cytoplasm area is segmented in cancer cell image using transfer learning.

Step 1: Pre-training

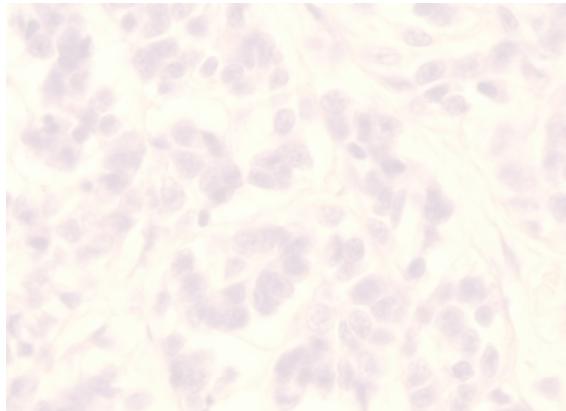


Step 2: Finetuning

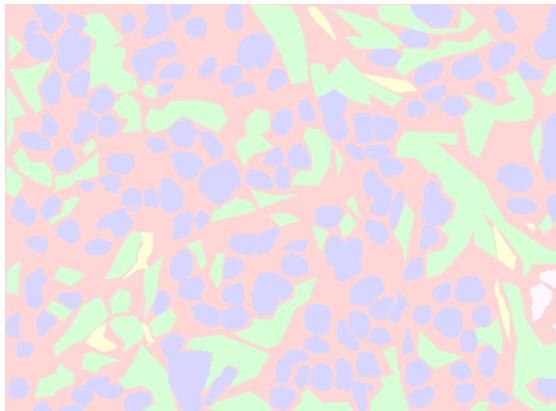




1. Cancer cytoplasm segmentation

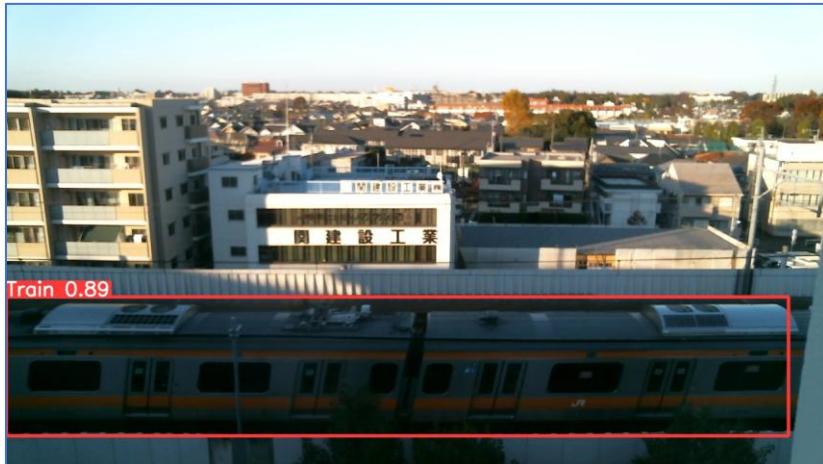


Image



Segmentation

2. Train detection

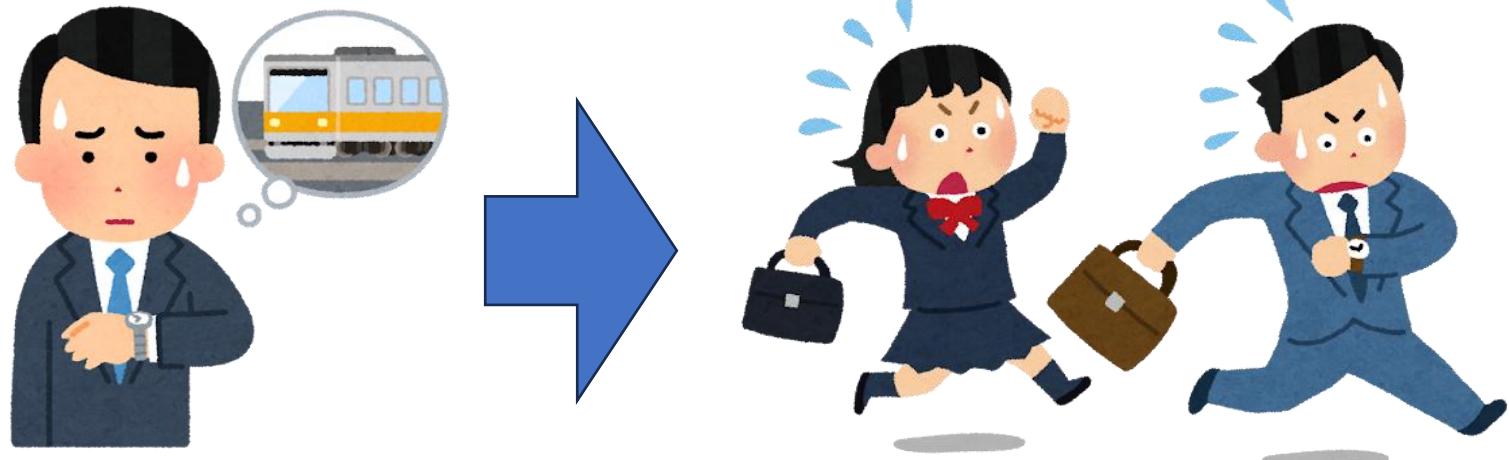




□ Research background

- In Japan: Train rarely delays.
→ If the train is a little late...

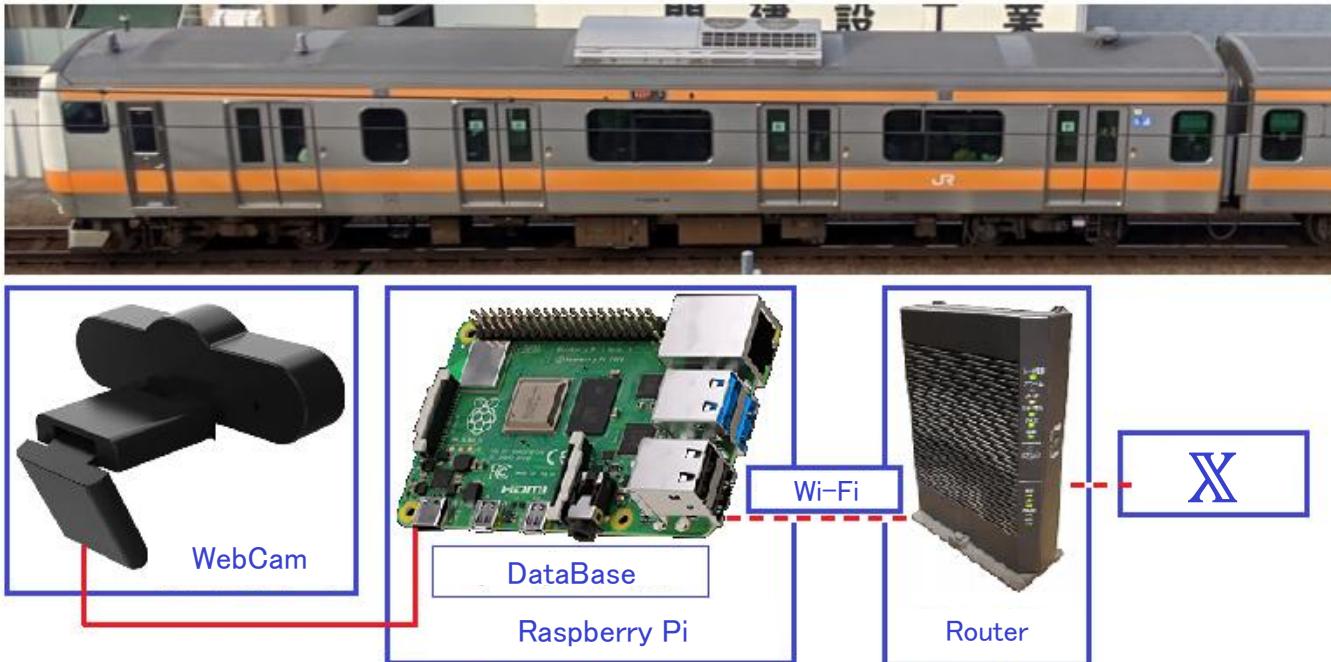
Public transportation delays → Significant Disruption





□ Previous research

Camera-based train delay management and information system



2. Train detection



❑ Problem in previous research

Method of Previous Research



Color-based masking

Significant drop in detection accuracy
during evening and night

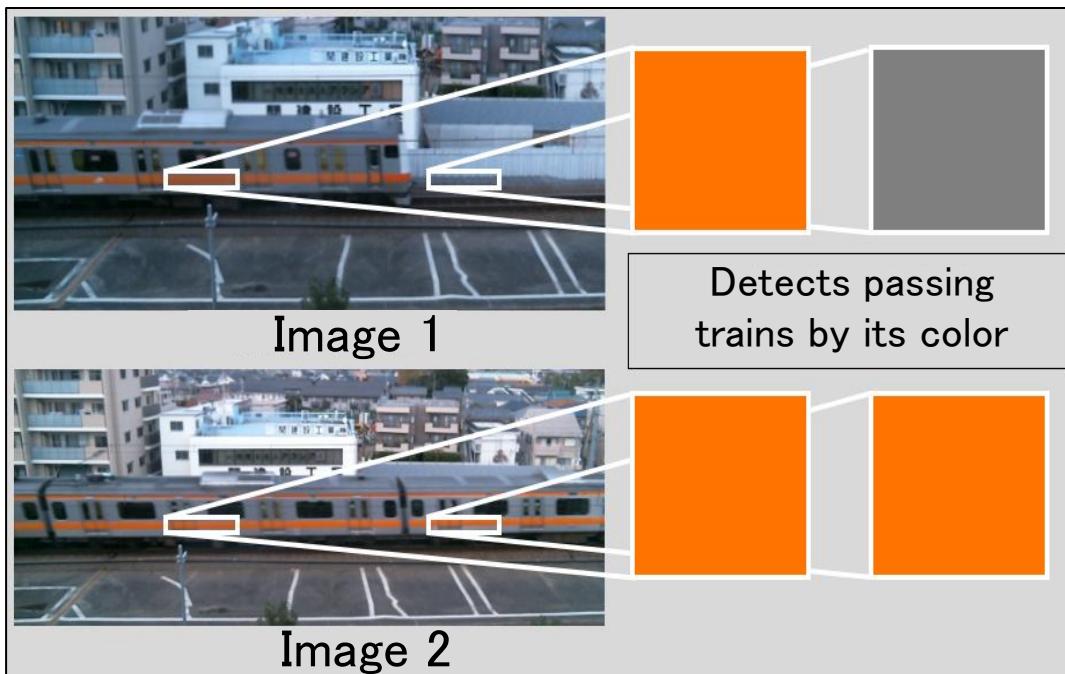




Image recognition models

- Example of image detection model
 - **RetinaNet**
 - **CenterNet**
 - **EfficientNet**
 - **CornerNet**
 - **YOLO**





Purpose

- Image Recognition models

**Utilize YOLOv8
for train detection**

YOLOv8: Able to process 45 frames per second



suitable for
real-time object detection



Proposed method

Data Augmentation

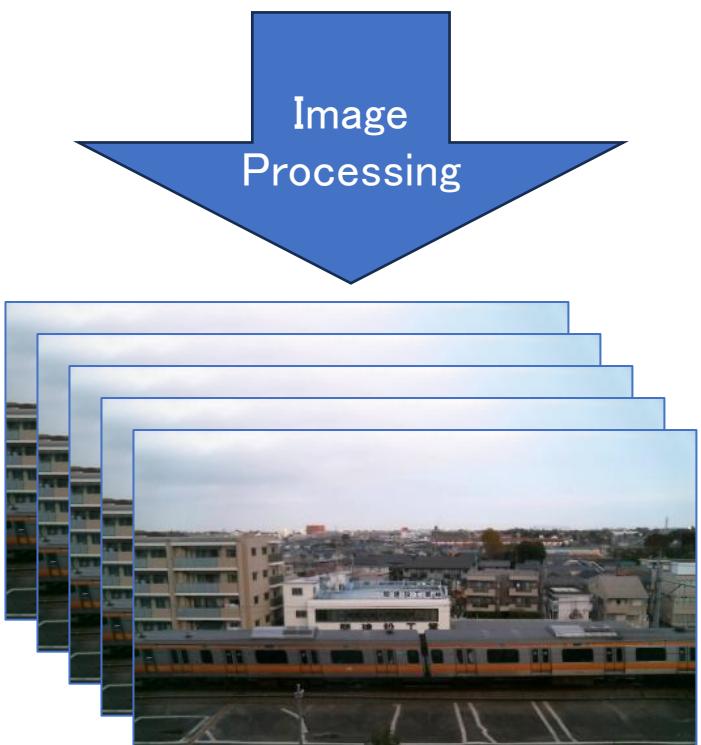
- Treating 5 kinds of editing

1. RandomRain
2. Blur
3. MedianBlur
4. CLAHE
5. ImageCompression

Original
Image



5
Augmented
Images



2. Train detection

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Proposed method

Data Augmentation



Original Image

RandomRain



MedianBlur



CLAHE



Augment data by processing one photo into multiple versions.

2. Train detection

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Proposed method



RandomRain

create an ideal representation of rainy weather conditions



MedianBlur

addresses the issue of image blurriness, which can result from high train speeds



CLAHE

enhancing the structural details of the train in the image

2. Train detection

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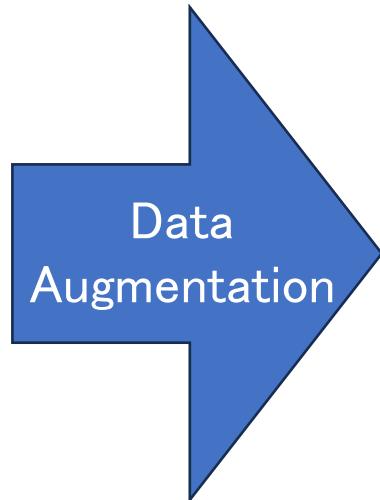
Experiment

Datasets

For Training: Annotated



Original Image: 30



Augmented Image: 150



2. Train detection

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Experiment

For Prediction: Not Annotated

- Taken in November, evening
- Total: 701





Experiment

- Utilize YOLOv8



- Training Condition

Epoch: 500

Batch size: 4

GPU: NVIDIA GeForce RTX 2060 × 1

2. Train detection



❑ Experiment

- Vary the number of training data
- Compare those models each other

Method	Data augmentation	Original image	Augmented image
Proposed	✓	30	150
Comparison	✗	30	✗
Handcrafted	✗	✗	✗

2. Train detection



❑ Experiment

- Ablation models

Method	Original image	Images for training					Data augmentation	Image compression		
		Random Rain	Blur	Median blur	CLAHE					
Proposed	✓	✓	✓	✓	✓	✓	✓	✓		
①	✓	✓	✓	✓	✓	✓	✓	✗		
②	✓	✓	✓	✓	✓	✗	✓	✓		
③	✓	✓	✓	✗	✗	✓	✓	✓		
④	✓	✓	✗	✓	✓	✓	✓	✓		
⑤	✓	✗	✓	✓	✓	✓	✓	✓		



2. Train detection

❑ Experiment

- Proposed method marked the highest accuracy.

Method	Data augmentation	Original image	Augmented image	Accuracy (%)
Proposed	✓	30	150	<u>99.672</u>
Comparison	✗	30	✗	74.893
Handcrafted	✗	✗	✗	9.985

2. Train detection



❑ Experiment

- Compare those models each other

Method	Images for training							Accuracy (%)	
	Original image	Data augmentation							
		Random Rain	Blur	Median blur	CLAHE	Image compression			
Proposed	✓	✓	✓	✓	✓	✓	✓	99.672	
①	✓	✓	✓	✓	✓	✓	✗	97.860	
②	✓	✓	✓	✓	✓	✗	✓	<u>84.736</u>	
③	✓	✓	✓	✓	✗	✓	✓	99.287	
④	✓	✓	✓	✗	✓	✓	✓	99.429	
⑤	✓	✗	✓	✓	✓	✓	✓	<u>75.749</u>	

2. Train detection

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Experiment

Comparison of Proposed & ②

Method	Images for training							Accuracy (%)	
	Original image	Data augmentation							
		Random Rain	Blur	Median blur	CLAHE	Image compression			
Proposed	✓	✓	✓	✓	✓	✓	✓	<u>99.672</u>	
②	✓	✓	✓	✓	✓	✗	✓	84.736	

- CLAHE significantly improves recognition accuracy



Proposed



②



Experiment

Comparison of Proposed & ②

Method	Images for training							Accuracy (%)	
	Original image	Data augmentation							
		Random Rain	Blur	Median blur	CLAHE	Image compression			
Proposed	✓	✓	✓	✓	✓	✓	✓	<u>99.672</u>	
②	✓	✓	✓	✓	✓	✗	✓	84.736	

- CLAHE significantly improves recognition accuracy



Proposed



②

2. Train detection

65/70



Experiment

Comparison of Proposed & ⑤

Method	Images for training							Accuracy (%)	
	Original image	Data augmentation							
		Random Rain	Blur	Median blur	CLAHE	Image compression			
Proposed	✓	✓	✓	✓	✓	✓	✓	<u>99.672</u>	
⑤	✓	✗	✓	✓	✓	✓	✓	75.749	

- RandomRain enhances recognition accuracy considerably



Proposed



⑤

2. Train detection

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Experiment

Comparison of Proposed & ⑤

Method	Images for training							Accuracy (%)	
	Original image	Data augmentation							
		Random Rain	Blur	Median blur	CLAHE	Image compression			
Proposed	✓	✓	✓	✓	✓	✓	✓	<u>99.672</u>	
⑤	✓	✗	✓	✓	✓	✓	✓	75.749	

- RandomRain enhances recognition accuracy considerably



Proposed



⑤

2. Train detection

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Experiment

Comparison of Proposed & ⑤

Method	Images for training							Accuracy (%)	
	Original image	Data augmentation							
		Random Rain	Blur	Median blur	CLAHE	Image compression			
Proposed	✓	✓	✓	✓	✓	✓		<u>99.672</u>	
⑤	✓	✗	✓	✓	✓	✓		75.749	

- RandomRain enhances recognition accuracy considerably



Proposed



⑤

2. Train detection



Experiment

Comparison of Proposed & ②,⑤

Method	Original image	Images for training					Accuracy (%)	
		Data augmentation						
		Random Rain	Blur	Median blur	CLAHE	Image compression		
Proposed	✓	✓	✓	✓	✓	✓	<u>99.672</u>	
②	✓	✓	✓	✓	✗	✓	84.736	
⑤	✓	✗	✓	✓	✓	✓	75.749	

Random
Rain



Accuracy can be improved by training on
photos with
different brightness

CLAHE





YOLOv8



Data Augmentation



Improve train detection accuracy

**A practical train delay information provision
system was realized.**

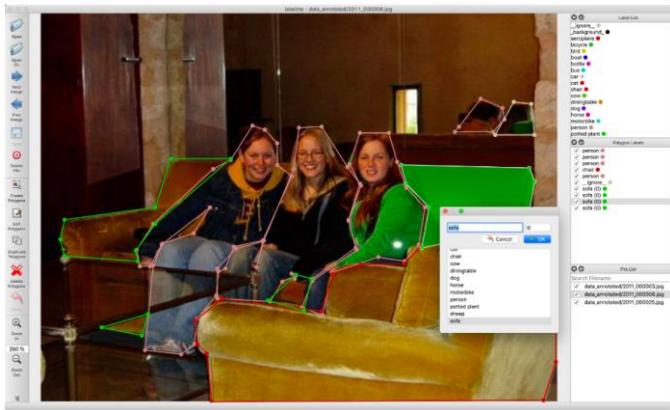
Important links for data annotation

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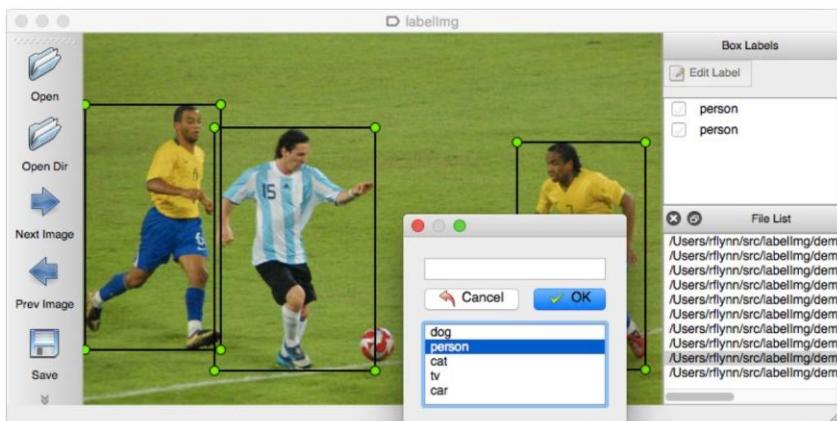
❑ Software for segmentation

<https://github.com/wkentaro/labelme>



❑ Software for detection

<https://github.com/HumanSignal/labelImg>



Thank you very much for your kind attention.