Project Report for Automated Software Engineering a semi-supervised learner built on sway

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I. INTRODUCTION

Machine learning is an area with fast-growing research, with broad applications ranging from image processing to chatbots such as chatGPT. Machine learning classifiers rely on data to extract heuristics and patterns. Classical machine learning is mostly supervised learning, where the data is labeled. However, in real-world scenarios, it can be costly to label all data, hence the use of semi-supervised learning. Our approach is based off of the sway method proposed by Chen et al [2].

In our report, we describe how we extended sway, and what datasets and experiments were conducted. Section III discusses our modified approach of sway and the datasets we used. Section IV provides results and insight we gained from our experiments.

II. RELATED WORK

The algorithm used in this paper, Sway [2], is a method for search-based software engineering. Search based software engineering (SBSE) was first proposed by Harman and Jones [3] in 2001. SBSE transforms a software engineering problem to a search problem to apply metaheuristic search. A software engineering problem can be reformed as a search problem by defining the following: a representation of the problem, a fitness function, and a set of manipulation operators. Common algorithms include random search, simulated annealing, genetic algorithms.

The advantage of metaheuristic algorithms is that they can explore multiple objectives simultaneously. Multiple-objective evolutionary algorithms (MOEA) are used in SBSE to help achieve multi-objective optimization (MOO). In multi-objective problems, there usually isn't a single optimal solution [4], a set of optimal points, such as the pareto frontier, is determined.

A. Random Projection

Random projection is a method used to reduce the dimensionality of the data while preserving the relative distances between data points. Dimension reduction can be used on various kinds of data. One of the most well known methods is principal component analysis [1]. Principal component analysis finds axis along which data displays the most variance to preserve the maximum amount of information.

B. Semi-Supervised Learning

Semi supervised learning is a hybrid of supervised and unsupervised learning. Supervised learning consists of labeled data, learners or classifiers extract patterns based on the labels. Methods such as decision trees or support vector machines are categorized as supervised learning. Unsupervised learning consists of data without labels. Semi supervised learning combines both labeled and unlabeled data to build classifiers [5]. This can be useful when it is costly to generate labels for all data. Semi supervised learning can achieve better performance and accuracy compared to unsupervised learning.

III. METHODS

Sway recursively splits the dataset in half and finds the best cluster using a *split* function. The *split* function picks a random point and the two points with the largest Euclidean distance from it. The two furthest points form a line, which split all other points into two halves by calculating the distance of the x columns (the columns that are not objectives). Then one point from each of the two halves are compared through the *better* function, to determine which point has better objectives (y columns). The *split* function is then executed on the better half. This process repeats until we reach a certain cluster size, by then we would have the best cluster.

Our new proposed method built on top of sway is to add randomness when splitting data into two halves. The *half()* splits data into two halves in sway, it first sorts all data according to the x columns. These x columns provide a basis for us to cluster similar data together. We do not compare the y columns when splitting data since we assume that in real-world scenarios it would be costly to acquire such values. However, we do don't know the exact relation between the x columns (characteristics) and the y columns (objectives). Thus, we propose adding randomness, so we don't fully rely on unknown patterns in the data. We hope that the introduced randomness will help us find better objective values. In the following sections, we refer to the original sway as sway1, and sway2 as our new method.

We next describe the main implementation of randomness in our code. The `dist` function in the data class calculates the distance of the x columns for two rows. We use a random coefficient (`RAND` in the pseudocode below), to vary the distance by a certain percentage. In our experiments, we set

this percentage to 15%. This means a distance of 1 would return a value ranging from -0.85 to 1.15.

```
def dist(row1, row2):
    n = 0
    d = 0
    for col in x_columns:
        n += 1
        d += col.dist(row1[col_index],
               row2[col_index])^constant
    d = d * (1+ random_num(-RAND, RAND))
    return (d/n)**(1/dist_coefficient)
```

We then applied sway to the *xpln* method. The *xpln* method takes the best cluster from sway and another random sample of data and tries to find a rule that would most effectively distinguish between the two. Xpln1 would be sway1 applied to xpln, and xpln2 is sway2 applied to xpln.

The *top* method goes through all data in the dataset to compare and sort based on a *better* metric. The *better* metric compares the y columns of the data. As we compared each pair of data points, this resulted in $O(n^2)$ time. As some datasets had a large number of rows, we did not run the *top* method for certain datasets due to time concerns.

A. Data

Our data consists of ten datasets, each has two types of columns. Columns with string values and columns with numeric values. Some columns have a plus or minus sign, this means they are the objectives, a minus sign means we try to minimize this value, while a plus sign means we try to maximize the value. Table I shows statistics on these objective columns, which we use as a baseline to compare the results from our experiments.

To understand the data, let us take auto2 as an example, the auto2 dataset has a total of twenty-three columns, which includes four objectives, or y columns: *CityMPG+, HighwayMPG+, Weight-, Class-*. The remaining nineteen columns, *type, engine_size, horsepower, etc.*, are x columns. Our methods would cluster data based on the nineteen x columns and choose data from each cluster to most effectively maximize or minimize the values of the objectives.

B. Experiments

We ran our model on samples of size 10, 25, 50, 100, 200, 500, and 1000. For each sample size, we ran 20 repeated runs with different seeds and calculated the average of the values we collected. The source code and experiment outputs can be found in the GitHub repository.

IV. RESULTS

In this section, we discuss results of our experiments. We specifically discuss our results from a sample size of 500 out of the many sample sizes. Table II-VIII shows some of our results. For more results, please refer to the GitHub repository.

A. Sway1 vs. Sway2

We observe that adding randomness in our model achieved mixed results. In most cases, sway2 performs slightly worse or similarly to sway1. However, there are certain cases where sway2 performs better. For example, sway2 performs better when we try to maximize *Kloc* for the *nasa93dem* dataset. We indicate objectives where sway2 performs better than as red in our tables. As sway2 introduces randomness, we can infer that for these objectives, closely clustered data points based on the x columns do not necessarily relate to similar values for the objectives. For example, in table IV, closely clustered x columns for coc1000 may not have similar values for the *Effort* objective. The same can be seen in table V and VIII. Results labeled top are results yielded from comparing all data. Logically, this returned the best results, however it is also the most time-consuming method. Comparing sway to top, we observe that there is a noticeable decrease in performance, this is often referred to as the *sampling tax*. This shows we sacrifice the optimal values for in exchange for time when implementing sway.

B. Xpln

We applied sway1 and sway2 to xpln, which we labeled as xpln1 and xpln2 in our tables. As shown from the tables, for most cases, xpln performs slightly worse than sway along. This loss in performance is the *explanation tax*. This is due to the fact that xpln uses simpler rules to distinguish the data points. However, there are cases in which xpln performs better than sway, we infer that this shows that data for certain features can be clustered using simpler rules. We highlighted cases where xpln performs better than sway in blue in tables II, IV, VIII. Understanding phenomenon like this could be useful where we would conduct future studies, as we discuss in section VII.

C. Sample size

We also conducted experiments with different sample sizes in an attempt to achieve better results with more samples. However, we did not observe a clear correlation between sample sizes and the objectives. Table IX shows varying sample sizes for the *nasa93dem* dataset. Upon receiving these results, we went back to check how sample size was implemented in the code. Sample size has an effect when selecting the two points when splitting data into two halves. The first point is selected at random, and the second point is selected from a group of data that is of sample size. However, that is the extent of which sample size has an effect. Thus, we infer that sample size does not have enough effect in our code to influence the results.

D. Effect size and Significance tests

With results from different models, we conducted the effect size test using cliff's delta and the significance test using bootstrap. The effect size test tests for relationship between two sets of data. We set the threshold to 0.4 for medium effects. The confidence for the significance test is set to 0.05. The conjunction of the two test between different results is

dataset	characteristic	mean	median	mode	standard deviation
auto2	CityMPG+	22.37	21	18	5.62
	HighwayMPG+	29.09	28	26	5.33
	Weight-	3072.9	3040	3470	589.9
	Class-	19.51	17.7	15.9	9.69
auto93	Lbs-	2970.42	2803.5	2130	846.84
	Acc+	15.57	15.5	14.5	2.76
	Mpg+	23.84	20	20	8.34
china	N_effort-	4277.64	2098	296	7071
coc1000	LOC+	1013.05	1060.5	720	571.35
	AEXP-	2.97	3	2	1.2
	RISK-	6.68	5	0	6.37
	EFFORT-	30807.5	19642	33906	33883.81
coc10000	Loc+	1009.04	1012	100	574.75
	Risk-	6.59	5	0	6.04
	Effort-	30506.37	19697.5	4509	35435.43
health...0001-hard	MRE-	82.32	75.04	199	12.45
	ACC+	5.15	7.14	0	3.82
	PRED40+	22.1	25	25	13.52
health...0011-easy	MRE-	92.3	119.33	0	48.43
	ACC+	-8.53	-12.24	0	5.71
	PRED40+	17.79	0	0	34.13
nasa93dem	Kloc+	94.02	47.5	100	133.6
	Effort-	624.41	252	60	1135.93
	Defects-	3761.76	2007	2077	6145.06
	Months-	24.18	21.4	13.6	12.97
pom	Cost-	369.99	327.32	0	204.40
	Completion+	0.87	0.9	1	0.13
	Idle-	0.24	0.23	0	0.2
SSM	NUMBERITERATIONS-	30.94	7	5	94.53
SSN	PSNR-	44.53	45.91	45.98	6.47
	Energy-	1658	1258.09	0	1610.66

TABLE I
DATASET STATISTICS

	CityMPG+	Class-	HighwayMPG+	Weight-
sway1	26.02	13.75	32.38	2661.03
xpln1	27.07	16.17	33.14	2632.12
sway2	24.363	16.86	31.25	2845.97
xpln2	25.26	16.72	25	2781.65
top	37.16	9.26	41.75	2040.98

TABLE II
RESULTS FOR AUTO2.CSV

	LOC+	AEXP-	PLEX-	RISK-	Effort-
sway1	1027.74	3.05	2.88	5.08	29321.05
xpln1	913.11	2.67	2.73	5.7	27416.45
sway2	999.59	2.92	3.02	6.12	28323.93
xpln2	918.43	2.66	2.73	6.0	26910.59
top	1571.43	1.62	1.39	4.7	35116.16

TABLE IV
RESULTS FOR COC1000.CSV

	Lbs-	Acc+	Mpg+
sway1	2240.94	16.80	29.51
xpln1	2416.26	15.44	26.40
sway2	2319.56	16.62	29.72
xpln2	2456.19	14.49	23.57
top	1998.07	19.77	40.76

TABLE III
RESULTS FOR AUTO93.CSV

	Kloc+	Effort-	Defects-	Months-
sway1	70.52	428.92	2811.09	20.86
xpln1	72.85	450.05	2894.04	21.40
sway2	85.92	524.90	3289.46	22.04
xpln2	84.24	542.82	3374.83	22.59
top	4.59	18.29	143.51	8.24

TABLE V
RESULTS FOR NASA93DEM.CSV

shown in table X. For those where the conjunction is =, this means both tests return true, which we can infer to meaning the two results are similar. We observe that results from sway1 are similar to results from sway2. However, both results from sway are not similar to results from top, due to sampling tax. It can also be seen from the table that xpln returns slightly different results from sway.

V. DISCUSSION AND CONCLUSION

As sway is the current state-of-the-art method, we spent the majority of our time unpacking and understanding sway.

	MRE-	ACC+	PRED40+
sway1	74.71	7.40	19.215
xpln1	75.03	7.28	19.18
sway2	75.37	7.32	18.23
xpln2	75.03	7.27	19.24

TABLE VI
RESULTS FOR HEALTHCLOSEISSES12MTHS0001-HARD.CSV

	MRE-	ACC+	PRED40+
sway1	31.37	-0.39	57.53
xpln1	35.96	-0.46	53.85
sway2	26.03	-0.46	62.11
xpln2	35.96	-0.46	53.85

TABLE VII

RESULTS FOR HEALTHCLOSEISSES12MTHS0011-EASY.CSV

	LOC+	RISK-	EFFORT-
sway1	1004.94	5.22	26372.00
xpln1	604.81	4.02	17308.46
sway2	1006.16	4.57	24570.96
xpln2	454.17	2.71	13859.63

TABLE VIII

RESULTS FOR COC10000.CSV

We did not want to completely reinvent the wheel, thus our new method builds on top of it. Future work can be done on further extending and fine-tuning to sway to achieve better performance.

We would want to further explore how sample size in sway effects the results. Our current results do not show a positive correlation between the objectives and sample size, which is contrary to our intuition. As discussed in section IV-C, we belive the current implementation does not take full use of different sample sizes. For future work, we would like to modify this so that results are in line with the sampling tax assumption.

A. Threats to validity

Our method was based off of sway, we were given sample code of sway and had to implement it in our own code. While we made the best effort to implement it, there might be small details where we missed or misunderstood. This could result in our experiments and results being slightly inaccurate.

VI. BONUS: REQUIREMENTS STUDY

For our requirements study, we collected five reqgrids with a common theme of TV shows. We asked the participants to come up with TV shows and characteristics and rate the shows based on them. An example of the output for clustering the TV shows can be seen in listing 1. The outputs of each grid can be found in the GitHub repository. A common characteristic many people came up with was whether the show was easy to watch or full of suspense. From the results, we observe that this was often also the most significant feature that separated shows. We could infer that the story and tone of the show

could have a great influence on viewers' rating of the show. Other less significant feature included whether the show was realistic, episode length, connection to previous seasons, etc. We might conclude from the results that these characteristics have less of an effect on how the audience rates the show.

Listing 1. example of repgrid output

```
90
|..69
|..|..41
|..|..|..Schitts Creek
|..|..|..New Girl
|..|..65
|..|..|..Narcos
|..|..|..Ted Lasso
|..84
|..|..61
|..|..|..The Last of Us
|..|..|..Beef
|..|..84
|..|..|..Loki
|..|..|..84
|..|..|..|..Greys Anatomy
|..|..|..|..Moonknight
80
|..50
|..|..Easy to watch:Full of Suspense
|..|..60
|..|..|..not much diversity:diverse
|..|..|..Family Friendly:violent
|..72
|..|..short:long total length
|..|..42
|..|..|..poor:good visual effects
|..|..|..normal:good looking characters
```

VII. BONUS: FEBRUARY STUDY

For our february study, we take a look back at our results for xpln. As xpln picks a rule to best distinguish between the best and rest data returned by sway. We could make use of results and rules from a previous study to help in future studies. Xpln performs better than sway in certain datasets, which we highlighted in blue in the tables. If we were to minimize risk in the dataset *coc10000*, we could filter data first according to the rule given by xpln. In one of our runs of experiments on *coc10000*, the rule `{data ['n']}` chosen by xpln yielded better results than sway. For future studies, we could collect a set of rules that xpln performs better on, and preprocess the data using those rules to get better results.

VIII. BONUS: ABLATION STUDY

For our ablation study, we used the auto2 dataset. We removed one of the x columns each time and ran sway on the new data. This would help us in identifying which features are more important than others. We listed the features that had made a noticeable difference in the objective values when removed in table XI. Features that were not listed did not yield noticeable difference when we ran our experiments. As shown in the table, we can infer that three of the features: the maker of the car, the luggage capacity, and whether manual

	Kloc+	Effort-	Defects-	Months-
10	70.52	329.06	2038.96	19.09
25	47.925	250.97	1743.88	17.87
50	64.64	311.22	2427	20.08
100	62.24	314.84	2325.34	19.14
200	94.33	602.88	3629.39	24.35
500	86.29	489.42	3323.69	22.12
1000	106.19	635.1	4117.55	25.47

TABLE IX

RESULTS FOR DIFFERENT SAMPLE SIZE FOR NASA93DEM.CSV

dataset	characteristic	all			sway1			sway2	
		all	sway1	sway2	sway2	xpln1	top	xpln2	top
auto2	CityMPG+	=	≠	≠	=	=	≠	=	≠
	HighwayMPG+	=	≠	≠	=	=	≠	=	≠
	Weight-	=	≠	≠	=	=	≠	=	≠
	Class-	=	≠	≠	≠	=	≠	=	≠
auto93	Lbs-	=	≠	≠	=	=	≠	≠	≠
	Acc+	=	≠	≠	=	≠	≠	≠	≠
	Mpg+	=	≠	≠	=	≠	≠	≠	≠
china	N_effort-	=	≠	≠	=	≠	≠	=	≠
coc1000	LOC+	=	=	=	=	=	≠	=	≠
	AEXP-	=	≠	=	=	=	≠	=	≠
	PLEX-	=	≠	=	=	=	≠	=	≠
	RISK-	=	≠	=	=	=	=	=	=
	EFFORT-	=	≠	≠	=	=	≠	=	≠
coc10000	Loc+	=	=	=	=	≠	n/a	≠	n/a
	Risk-	=	≠	≠	=	=	n/a	≠	n/a
	Effort-	=	≠	≠	=	≠	n/a	≠	n/a
health...0001-hard	MRE-	=	≠	≠	=	=	n/a	≠	n/a
	ACC+	=	≠	≠	=	≠	n/a	=	n/a
	PRED40+	=	≠	≠	=	=	n/a	=	n/a
health...0011-easy	MRE-	=	≠	≠	=	=	n/a	≠	n/a
	ACC+	=	≠	≠	=	≠	n/a	=	n/a
	PRED40+	=	≠	≠	=	=	n/a	≠	n/a
nasa93dem	Kloc+	=	=	=	=	=	≠	=	≠
	Effort-	=	≠	=	=	=	≠	=	≠
	Defects-	=	≠	=	=	=	≠	=	≠
	Months-	=	=	=	=	=	≠	=	≠
pom	Cost-	=	≠	≠	=	=	n/a	≠	n/a
	Completion+	=	=	=	=	≠	n/a	≠	n/a
	Idle-	=	≠	=	=	≠	n/a	≠	n/a
SSM	NUMBERITERATIONS-	=	≠	≠	=	≠	n/a	≠	n/a
SSN	PSNR-	=	=	=	=	=	n/a	=	n/a
	Energy-	=	≠	=	=	≠	n/a	=	n/a

TABLE X

RESULTS FOR EFFECT SIZE TEST AND SIGNIFICANCE TEST

Removed features	CityMPG+	HighwayMPG+	Weight-	Class-
none	26.02	32.38	2661.03	13.75
luggage	25.69	32.05	2702.21	14.92
manual transmission	25.22	31.82	2689.13	14.23
maker	25.11	31.53	2812.98	16.59

TABLE XI

REMOVED FEATURES AND MODEL PERFORMANCE IN ABLATION STUDY

transmission was available were important in maximizing or minimizing the objectives.

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