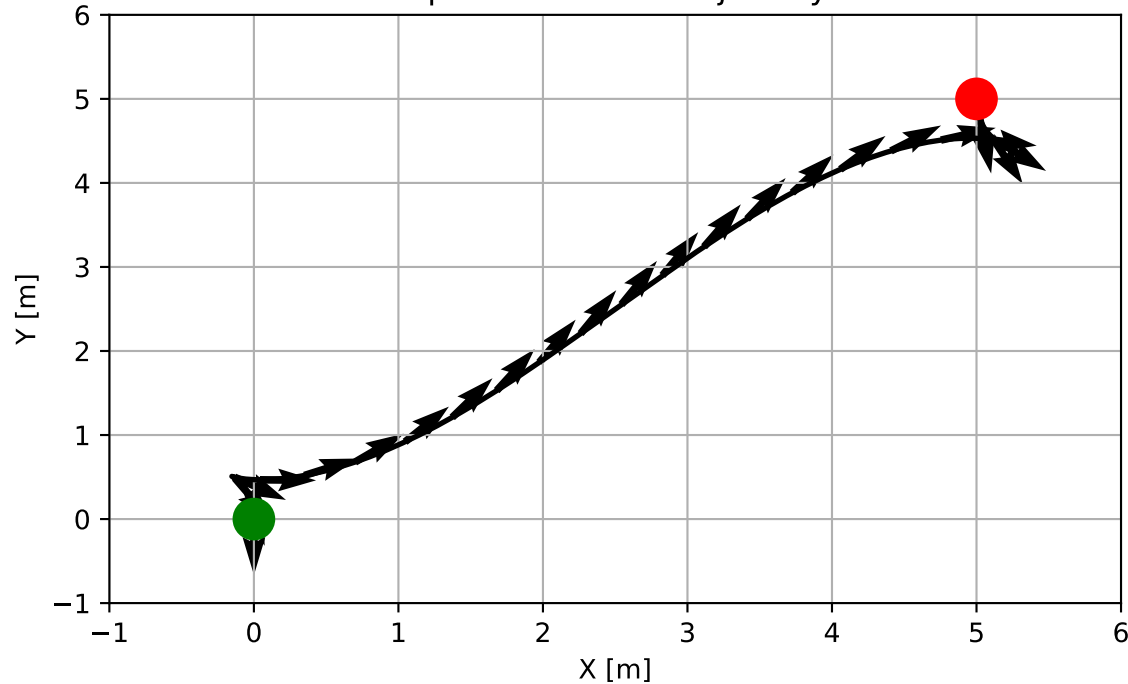


Optimal Control Trajectory



Optimal control sequence

