



Elk Workshop NAMM 2020

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Docs

Code

Community Plugins

Website

Forum

https://elk-audio.github.io/elk-docs

https://github.com/elk-audio

https://elk-audio.github.io/elk-community

https://elk.audio

https://forum.elk.audio



Outline

- 1 Connection and board test
- 2 Elk Overview
- 3 Simple examples
- 4 Analyzing plugin issues
- 5 Q&A



Requirements

- 1 Terminal with SSH.
- 2 Headphones with 3.5mm plug.



Connect to your board over WiFi

Connect your PC

WiFi: Elk_Workshop

PW: elk_at_adc

On your board, there is a sticker with a name elkpi-X.

\$ ssh mind@elkpi-X.local

Pwd: elk



Running and controlling plugin: file transfer

OSX: connect to samba folder with shortcut cmd-K from Finder.

Ubuntu: "Files" window, "Other Locations", and in "Connect to Server"

field, enter: smb://elkpi-X.local/

Win 10: right-click this PC. "Add a network location". ... in field

"//elkpi-X.local".

For all: User: mind PW: elk

If Samba doesn't work:

\$ scp yourfile.so mind@elkpi-X.local:/udata



Make some noise with SUSHI

```
$ cd /udata/elk_namm2020_workshop
$ sushi -r -c configs/sushi_config_arp.json
```

You should hear a Cello-like synth in a repeating pattern

CTRL+C to stop





Technology

Custom Linux Distribution Xenomai realtime Kernel ARM & x86 Connectivity: WiFi, BLE

Plugin support: VST2, VST3, LV2

CV & Gate I/O

Ableton Link

Hardware



Elk Development Kit

Elk Pi Hat
Open-Source Hardware
Optional control-board
SDK

6 analog In / 8 analog out CV in/out & gate/triggers 16 sensor analog ins 32 in/out GPIOs





Supported CPUs

Intel Atom



Intel Atom X5-Z8350 @ 1.92 GHz Quad Core

Intel Atom E39XX

(any Intel SOC trivial to support)

Raspberry Pi 3



Elk Pi Hat for Raspberry Pi 3 Broadcom BCM2837 4 x ARM Cortex A53 @ 1.2 GHz Open Source Dev Kit 6 Audio I/O

RPi 4 support 2020 4 x ARM Cortex A72 @ 1.5 GHz

See elk.audio for complete specs

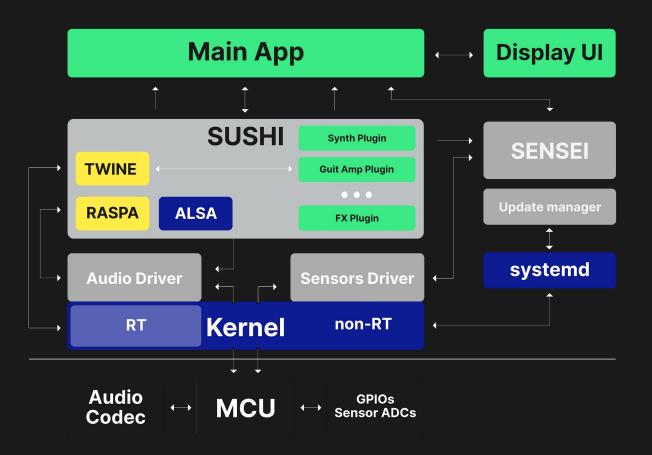
iMX 7/8



NXP i.MX8M Mini SoC 4 x ARM Cortex A53 @ 1.8-2 GHz 1 x ARM M4

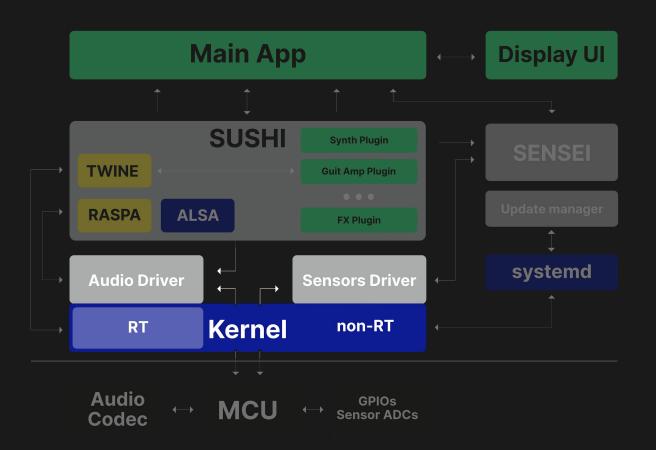
STM32MP1 in alpha i.MX8M Nano support 2020





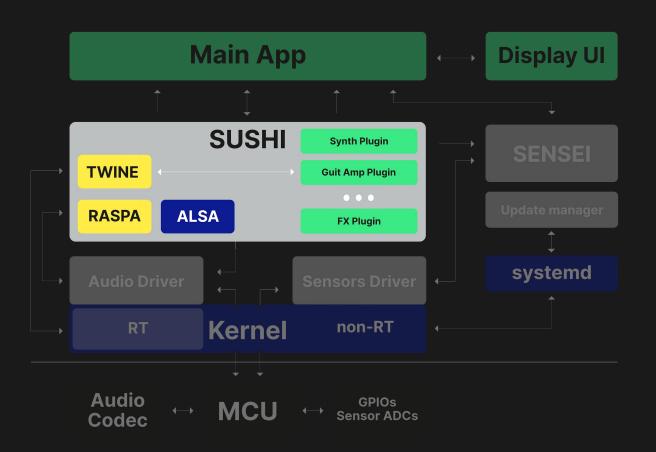


Dual Kernel



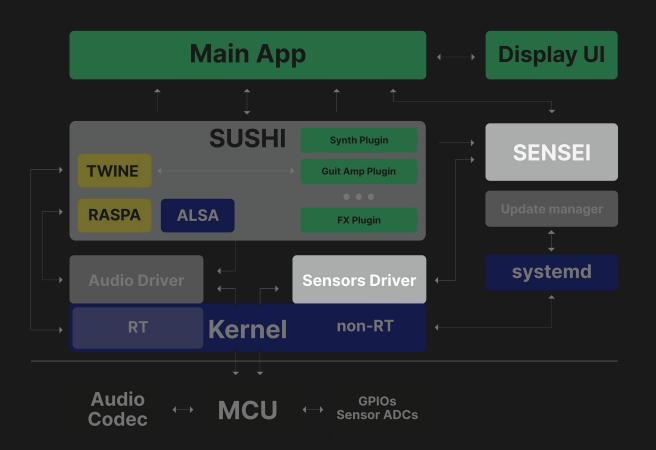


Dual Kernel Plugin Host



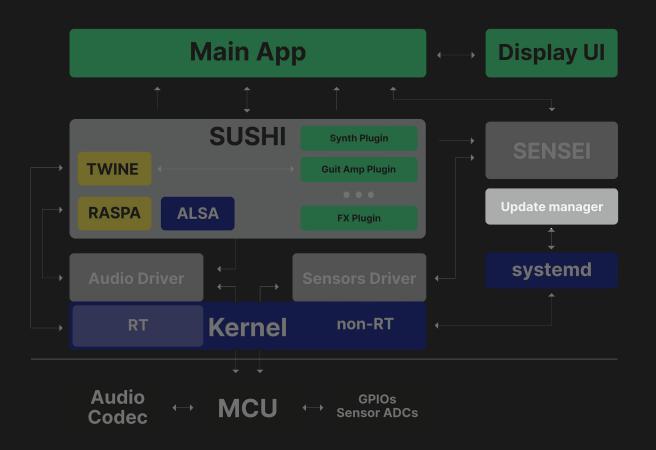


Dual Kernel
Plugin Host
Sensor Daemon



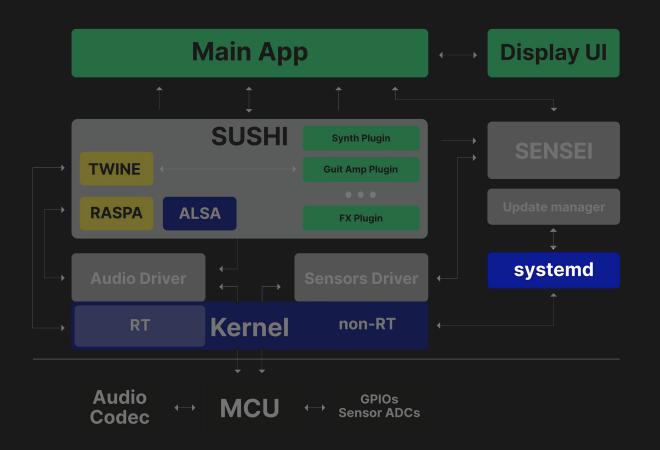


Dual Kernel
Plugin Host
Sensor Daemon
Software Update



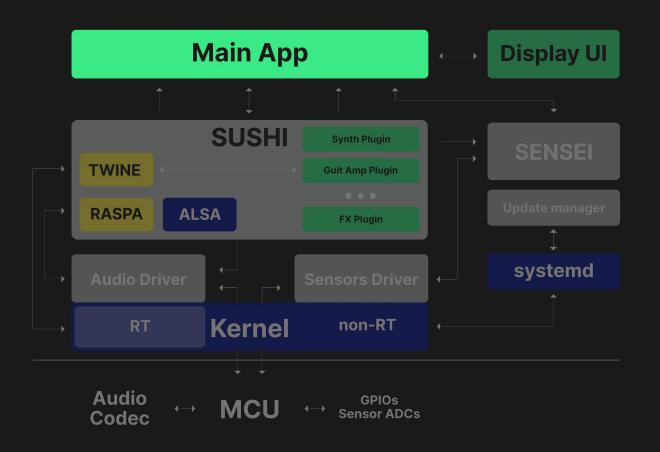


Dual Kernel
Plugin Host
Sensor Daemon
Software Update
Systemd



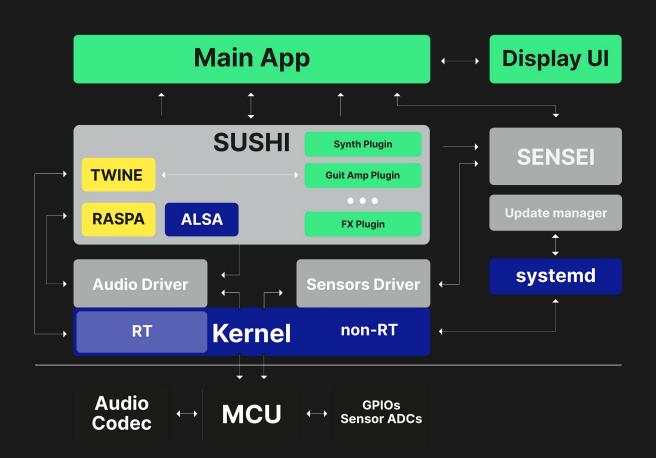


Dual Kernel
Plugin Host
Sensor Daemon
Software Update
Systemd
Main App





Dual Kernel
Plugin Host
Sensor Daemon
Software Update
Systemd
Main App



Working with Elk



Plugin Example

VST 2.4 plugin built with JUCE using example classes

Chain: Sampler Synth -> VCF -> Reverb

Relevant file: Source/SynthProcessor.h



Running and controlling plugin: Sensei & Python

```
$ sushi -r -c configs/sushi_config.json &
$ sensei -f configs/sensei_config.json &
```

Start python glue program

```
$ ./apps/main_app_minimal
```

Ctrl-C to kill main app when done playing.

```
$ killall -2 sushi
$ killall -2 sensei
```

(otherwise, use multiple SSH terminals or tmux)



Sensei and creating a simple App

Configuration files:

SUSHI, SENSEI, Python application



More complex application

```
$ sushi -r -c configs/sushi_config.json &
$ sensei -f configs/sensei_config.json &
$ ./apps/main app full
```



Analyzing plugin RT performance

\$ sushi --timing-statistics -r -c configs/sushi_config.json &

Rough analysis with Xenomai scheduler statistics:

\$ watch cat /proc/xenomai/sched/stat

Detailed analysis using SUSHI's timings queried over gRPC:

\$./apps/benchmark-synth -p elk_juce_example



Analyzing Xenomai mode-switches

Let's do something bad in the RT processing callback:

```
// ...
if (! midiMessages.isEmpty() )
{
    dontAllocateMeinRt = new float[4096];
    // leaks... but we don't care for this example
}
synth.renderNextBlock (buffer, midiMessages, 0, buffer.getNumSamples());
// ...
```



Analyzing Xenomai mode-switches (2)

```
$ sushi -r -c configs/sushi_config_msw.json &
$ watch cat /proc/xenomai/sched/stat
```

Look at the column MSW when playing Notes

```
$ gdb --args sushi_b64 --debug-mode-sw -r -c configs/sushi_config_msw.json
$ (gdb) catch signal SIGXCPU
$ (gdb) run
# ... should break on mode-switch
$ (gdb) bt
```



Cross-Compilation

If you modify the example plugin, zip the Source folder contents, and upload it to this page: http://elkbuild.local:5000/

Add your board address and target path root@elkpi-X.local:/target/path

That server will cross-compile it, and directly place it on your board in the location you've selected.



