

# CMPEN 454 PROJECT-3

## Writeup

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### Part 1 Theory Questions

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#### Q1.1: Calculating the Jacobian

Assuming the affine warp model defined in Equation 3, derive the expression for the Jacobian Matrix  $\mathbf{J}$  in terms of the warp parameters  $\mathbf{p} = [p_1, p_2, p_3, p_4, p_5, p_6]'$ .

$$\begin{aligned} & \text{equation 2 and 3} \\ \mathbf{W}(\mathbf{x}; \mathbf{p}) &= \begin{bmatrix} \mathbf{W}_x \\ \mathbf{W}_y \\ \mathbf{W}_1 \end{bmatrix} \begin{bmatrix} u \\ v \\ 1 \end{bmatrix} = \begin{bmatrix} 1 + p_1 & p_3 & p_5 \\ p_2 & 1 + p_4 & p_6 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} u \\ v \\ 1 \end{bmatrix} \text{ and,} \\ & \mathbf{p} = [p_1 \quad p_2 \quad p_3 \quad p_4 \quad p_5 \quad p_6]^T \end{aligned}$$

$$\frac{\partial \mathbf{W}}{\partial \mathbf{p}} = \begin{bmatrix} \frac{\partial \mathbf{W}_u}{\partial p_1} & \cdots & \frac{\partial \mathbf{W}_u}{\partial p_6} \\ \frac{\partial \mathbf{W}_v}{\partial p_1} & \cdots & \frac{\partial \mathbf{W}_v}{\partial p_6} \end{bmatrix} = \begin{bmatrix} u & 0 & v & 0 & 1 & 0 \\ 0 & u & 0 & v & 0 & 1 \end{bmatrix}$$

$$L = \sum_{\mathbf{x}} [\mathbf{T}(\mathbf{x}) - \mathbf{I}(\mathbf{W})]^2$$

$$\begin{aligned} \mathbf{J} &= \frac{\partial L}{\partial \mathbf{p}} = \frac{\partial L}{\partial \mathbf{I}(\mathbf{W})} \frac{\partial \mathbf{I}(\mathbf{W})}{\partial \mathbf{W}} \frac{\partial \mathbf{W}}{\partial \mathbf{p}} \\ &= -2 \sum_{\mathbf{x}} [\mathbf{T}(\mathbf{x}) - \mathbf{I}(\mathbf{W})] \begin{bmatrix} \frac{\partial \mathbf{I}}{\partial u} & \frac{\partial \mathbf{I}}{\partial v} \end{bmatrix} \begin{bmatrix} u & 0 & v & 0 & 1 & 0 \\ 0 & u & 0 & v & 0 & 1 \end{bmatrix} \end{aligned}$$

#### Q1.2: Computational complexity

## Initialization step

First calculate  $\nabla \mathbf{T}$ , which the runtime is  $O(n)$ , then calculate  $\mathbf{J} = \frac{\partial \mathbf{W}}{\partial \mathbf{p}}$  at  $\mathbf{p} = \mathbf{0}$ . To calculate the  $\nabla \mathbf{T} \cdot \frac{\partial \mathbf{W}}{\partial \mathbf{p}}$ , since  $\nabla \mathbf{T}$  is of dimension  $(m \times 2)$  and  $\frac{\partial \mathbf{W}}{\partial \mathbf{p}}$  is of dimension  $(2 \times 6)$ , this multiplication should be  $O(n)$ . To calculate the Hessian matrix  $\mathbf{H} = \mathbf{J}^T \mathbf{J}$ , since  $\mathbf{J}$  is of dimension  $(m \times 6)$ , this multiplication should be  $O(n^2)$ .

Thus the initialization cost will be  $O(n + n^2) = O(n^2)$ .

## Incremental step

First, calculate the  $\mathbf{I}(\mathbf{W}(\mathbf{x}; \mathbf{p}))$  cost should be  $O(n)$ . Then calculate the cost of  $[\mathbf{I}(\mathbf{W}(\mathbf{x}; \mathbf{p})) - \mathbf{T}] = O(n)$ .

Then calculate the cost of  $\sum_{\mathbf{x}} (\nabla \mathbf{T} \frac{\partial \mathbf{W}}{\partial \mathbf{p}})^T [\mathbf{I}(\mathbf{W}(\mathbf{x}; \mathbf{p})) - \mathbf{T}(\mathbf{x})] = O(n)$ , multiply the previous result with the inverse of Hessian to get  $\Delta \mathbf{p} = O(n^3)$ . Then update the warp function, which is  $O(n^2)$ .

The total time complexity is  $O(n + n^3) = O(n^3)$ .

## Part 2 Lucas-Kanade Tracker

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Best The best comes from the Lucas Kanade tracker.