Distribution of Generated Features *Dataset: 1,000 Samples, 5 Features (0 Cont, 5 Disc)*

Perturbation: feature_0 (Noise) scaled by 1.5x; feature_1 (Noise) by -0.5σ; feature_2 (Noise) by +0.5σ; feature_3 (Noise) scaled by -1.5x; feature_4 (Noise) scaled by 1.5x | Std. Separation: 1.84

