

Linear Algebra 2101

D. Szyld

(1)

Homework #8

Exercise 4.2.5. A $n \times n$

(a) If $R(A) = \mathbb{R}^n$, explain why A must be nonsingular.

$$R(A) = \{y \mid Ax = y\} = \mathbb{R}^n$$

This means that for every right hand side b
 $Ax = b$ has a solution

(it is always consistent)

$$\text{Rank } A = n \quad (n \text{ pivots})$$

$$\Rightarrow A \text{ nonsingular}$$

$Ax = b$ has unique solution

In particular $Ax = 0$ has only $x = 0$ solution

$$\text{i.e. } N(A) = \{0\}$$

(b) Four fundamental subspaces

$$R(A) = \mathbb{R}^n \quad N(A) = \{0\}, A \text{ nonsingular, } A^T \text{ also}$$

A^T nonsingular

(2)

$A^T x = b$ has always a unique solution

$$\Rightarrow R(A^T) = \mathbb{R}^n$$

$$N(A^T) = \{0\} \quad \text{since } A^T x = 0 \\ \Rightarrow x = 0$$

2. (a) Prove that $R(AB) \subseteq R(A)$

$$R(A) = \{y \mid \exists x \text{ with } Ax = y\}$$

$$R(AB) = \{y \mid \exists w \text{ with } ABw = y\}$$

Then if $y \in R(AB)$, $\exists w$ with $ABw = y$

$$\text{let } x = Bw, \text{ then } Ax = ABw = y$$

$$\Rightarrow y \in R(A)$$

so that $R(AB) \subseteq R(A)$.

(3)

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 3 \end{bmatrix}$$

$R(A)$ = linear combination of the
columns
= linear combination of basic
columns

LU or Gaussian elimination

$$\begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 2 \\ 0 & -1 & -1 \\ 0 & -1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 2 \\ 0 & -1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

Two basic columns (Rank 2)

basic columns $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

$$R(A) = \left\{ x = \alpha_1 \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} + \alpha_2 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\} \quad \alpha_1, \alpha_2 \in \mathbb{R}$$

for $R(AB)$, Compute

$$A \cdot B = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 2 & 1 & 3 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 4 \\ 0 & 2 \\ 0 & 6 \end{bmatrix}$$

$$R(AB) = \left\{ \gamma \begin{bmatrix} 4 \\ 2 \\ 6 \end{bmatrix}, \gamma \in \mathbb{R} \right\}$$

(4)

$$\begin{vmatrix} 4 \\ 2 \\ 6 \end{vmatrix} = 2 \begin{vmatrix} 1 \\ 1 \\ 2 \end{vmatrix} + 2 \begin{vmatrix} 1 \\ 0 \\ 1 \end{vmatrix}$$

so that $R(AB) \subsetneq R(A)$

$R(AB)$ ~~is~~ subspace of $R(A)$

(in this example a proper subspace)