

§ 4.1.2 Homogeneous Equations

Def: p. 121 Homogeneous vs. nonhomogeneous

From this point forward,

Assume \cdot $a_i(x)$ and $g(x)$ are continuous
(on I), $i = 0, 1, 2, \dots, n$.

\cdot $a_n(x) \neq 0$, $\forall x$ in the interval.

Operator : Takes a function and converts
it to another function

$$\text{eg } (f(x))' = f'(x)$$

A linear operator is s.t.

$$L\{f+g\}(x) = L\{f\}(x) + L\{g\}(x)$$

$$L\{c f(x)\} = c L\{f(x)\}$$

Differential operator :

$$\frac{dy}{dx} = D_y$$

$$\frac{d^2 y}{dx^2} = D_y^2 \text{ etc...}$$

$$\text{eg } D(\cos 4x) = -4 \sin(4x)$$

In general, n^{th} order differential operator is defined to be

$$L = a_n(x) D^n + a_{n-1}(x) D^{n-1} + \dots + a_1(x) D + a_0(x).$$

$$\text{eg } y'' + 5y' + 6y = 5x - 3$$

can be written

$$D^2 y + 5 D y + 6 y = 5x - 3$$

Putting it all together:

Homogeneous n^{th} order DE can be written compactly as $L(y) = 0$.

non hom: $L(y) = g(x)$.

Theorem 4.1.2 ^{er} Supposition Principle.
- Homog. DE. p. 121

Summary y_1, \dots, y_k solutions \Rightarrow
 $y = c_1 y_1 + \dots + c_k y_k$
is also a solution to the DE.

P.T. : $k=2$

Let y_1, y_2 be solutions of the homog.

$$L. DE \quad L(y) = 0 \quad \Rightarrow \quad L(y_1) = 0 \\ L(y_2) = 0$$

$$\text{Let } y = c_1 y_1 + c_2 y_2$$

$$\begin{aligned} \text{So } L(c_1 y_1 + c_2 y_2) &= c_1 L(y_1) + c_2 L(y_2) \\ &= 0 + 0 \\ &= 0 \end{aligned}$$

Corollary to T 4.1.2

(A) A constant multiple $y = C, y_1(x)$ of a solution $y_1(x)$ of a homo. linear DE is also a solution. (B) see book

The set of two functions $f_1(x)$ and $f_2(x)$ are linearly independent

\iff they are NOT constant multiples of each other.

Pg. in Book

Does a linear combination of n solutions give you all the solutions to a n^{th} order HLOE?

Only if $W \neq 0$ where p. 124

Def: 4.1.2 Wronskian

$$W(y_1, y_2, \dots, y_n) = \begin{vmatrix} y_1 & y_2 & \dots & y_n \\ y_1' & y_2' & \dots & y_n' \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n-1)} & y_2^{(n-1)} & \dots & y_n^{(n-1)} \end{vmatrix}$$

$\neq 0$

If $W(y_1, \dots, y_n) \neq 0$, then
 $\{y_1, \dots, y_n\}$ is the fundamental
 set of solutions to H L D E and
 any solution is a linear combination
 of these n functions. i.e.
 General solution of the H L D E is

$$y = c_1 y_1 + c_2 y_2 + \dots + c_n y_n.$$

T. 4.1.3 Criterion for Linearly Independent
 Solutions ... $W \neq 0$

p. 124

Def 4.13 Fund'l Set of Solutions. p. 125
 $\{y_1, \dots, y_n\}$ LI

T. 4.1.4 Existence of n p. 125

T. 4.1.5 General Solution p. 126

HW = 23, 25, 26, 27, 28, 29

eg $y_1 = e^{3x}$, $y_2 = e^{-3x}$ are

Solutions to $y'' - 9y = 0$ on $(-\infty, \infty)$.

$$W(y_1, y_2) = \begin{vmatrix} e^{3x} & e^{-3x} \\ 3e^{3x} & -3e^{-3x} \end{vmatrix} = -3e^0 - 3e^0 \\ = -6 \neq 0, \\ \forall x \in (-\infty, \infty)$$

So y_1, y_2 form a fund'l set of solutions to the H L D E and

the general solution is

$$y = C_1 e^{3x} + C_2 e^{-3x}$$

of H L D E on $(-\infty, \infty)$