

## Math 2041: Summary 4.1, 4.3, 4.4

**Section 4.1:** Linear Homogeneous DE:  $a_2(x)y'' + a_1(x)y' + a_0(x)y = 0$

**Uniqueness and Existence (restated) :** Let  $a_2(x)$ ,  $a_1(x)$ , and  $a_0(x)$  be continuous functions on an open interval  $I$  that contains the point  $x_0$ , with  $a_2(x) \neq 0$  for all  $x$  in  $I$ . Then the initial value problem

$a_2(x)y'' + a_1(x)y' + a_0(x)y = 0$ ,  $y(x_0) = y_0$ ,  $y'(x_0) = y'_0$  has exactly one solution that exists throughout  $I$ .

**Principle of Superposition:** If  $y_1$  and  $y_2$  are two solutions to the Linear Homogenous Differential Equation

$$a_2(x)y'' + a_1(x)y' + a_0(x)y = 0,$$

then the linear combination  $c_1y_1 + c_2y_2$  is also a solution for any values of the constants  $c_1$  and  $c_2$ .

**Theorems:** Consider the initial value problem

$$a_2(x)y'' + a_1(x)y' + a_0(x)y = 0, y(x_0) = y_0, y'(x_0) = y'_0.$$

Then it is possible to find the constants  $c_1$  and  $c_2$  such that  $y = c_1y_1 + c_2y_2$  is the solution to the initial value problem for any  $y_0$  and  $y'_0$  if and only if the Wronskian  $W = y_1y'_2 - y'_1y_2 \neq 0$  at  $x_0$ . This implies that on an interval that contains  $x_0$  on which the Existence and Uniqueness theorem holds, every solution to the differential equation is of the form  $y = c_1y_1 + c_2y_2$ .

This pair,  $y_1$  and  $y_2$ , is called a fundamental set of solutions to  $a_2(x)y'' + a_1(x)y' + a_0(x)y = 0$ .

**Section 4.3:** Linear homogeneous equations with constant coefficients:

$$ay'' + by' + cy = 0$$

Auxiliary equation:  $am^2 + bm + c = 0$

Case 1: The solutions of the auxiliary equation are two real, distinct roots,  $m_1$  and  $m_2$ . Then the general solution of the differential equation is given by

$$y = c_1e^{m_1x} + c_2e^{m_2x}.$$

Case 2: The solution of the auxiliary equation is given by one root with multiplicity two,  $m_1 = m$ . Then the general solution of the differential equation is given by

$$y = c_1e^{mx} + c_2xe^{mx}.$$

Case 3: The solutions of the auxiliary equation are two complex roots,  $m = \alpha \pm \beta i$ . Then the general solution of the differential equation is given by

$$y = c_1e^{\alpha x} \cos(\beta x) + c_2e^{\alpha x} \sin(\beta x).$$

**Section 4.4:** Linear nonhomogeneous equations with constant coefficients:

$$ay'' + by' + cy = g(x).$$

Solution:  $y = y_h + y_p$ , where  $y_h$  is the general solution to the homogeneous differential equation  $ay'' + by' + cy = 0$  and  $y_p$  is a specific solution to the nonhomogeneous differential equation  $ay'' + by' + cy = g(x)$ .

## Method of Undetermined coefficients

$g(x)$	Form of $y_p$ (See modification – last line)
$P_n(x)$ , a polynomial of degree $n$	$y_p = A_n x^n + A_{n-1} x^{n-1} + \cdots A_1 x + A_0$
$ke^{\alpha x}$	$y_p = Ae^{\alpha x}$
$k_1 \sin \beta x + k_2 \cos \beta x$	$y_p = A \sin \beta x + B \cos \beta x$
Sums of the above e.g. $g(x) = e^{2x} + x$	Use superposition of particular solutions. e.g. $y_{p1} = Ae^{2x}; y_{p2} = Bx + C$ $y_p = y_{p1} + y_{p2}$
Products of the above e.g. $g(x) = e^{\alpha x} P_n(x) \sin \beta x$	$y_p =$ Products of the above, combining constants. e.g. $y_p = e^{\alpha x} \sin \beta x (A_n x^n + \cdots A_1 x + A_0) +$ $e^{\alpha x} \cos \beta x (B_n x^n + \cdots B_1 x + B_0)$
<b>Modification:</b> If part of $y_p$ is the same as $y_c$ (so do not have linear independence), then multiply $y_p$ by $x^r$ for the $r$ that does give linear independence. For Second order equations, $r \leq 2$ .	

## Differential Operator:

$$\begin{aligned}
 D[e^{\alpha x} y] &= e^{\alpha x} y' + \alpha e^{\alpha x} y = e^{\alpha x} (y' + \alpha y) \\
 &= e^{\alpha x} (D + \alpha)[y]
 \end{aligned}$$

$$P(D)[e^{\alpha x} y] = e^{\alpha x} P(D + \alpha)[y],$$

where  $P(D)$  is a polynomial in  $D$ ,