

# Ellie Kung

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## EDUCATION

<b>Olin College of Engineering</b> <i>BS in Mechanical Engineering</i> Relevant Coursework: Modeling & Simulation, Mechanics of Solids & Structures, Thermodynamics, Software Design, Environment Technology & Society, Principles of Integrated Engineering	<b>Needham, MA</b> Aug 2024 – May 2028
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## PROJECTS

<b>Soil Sensing Snake</b> Principles of Integrated Engineering Project	<b>Needham, MA</b> Oct 2025 – Dec 2025
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- Led a team of four to design a snake robot that slithers and senses soil moisture in forests
- Manufacture a waterproof skin based on origami pattern design iteration
- Code a six degree of freedom snake that uses biomimicry to traverse its environment

<b>Climate Robotics and Expeditionary Science Technology (CREST) Research Lab</b> Underwater ROV	<b>Needham, MA</b> Sept 2025 – Current
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- Leading a team of 3 to design an underwater ROV using OnShape
- Performing CFD using Ansys to minimize energy consumption

<b>Autonomous Kayak Restoration</b>	Jan 2025 – May 2025
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- Restored and modernized a 10+ year old robotic kayak by redesigning its electro-mechanical system
- Developed and integrated a new sensor payload to enable autonomous coastal research

<b>Olin Baja SAE (Building an off-road car)</b> Chassis Lead	<b>Needham, MA</b> April 2025 - Current
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- Organized onboarding program for 10+ new members, improving retention and CAD proficiency in OnShape
- Planned out fabrication cycle with other team leads, reducing expected build time by one semester
- Researching and designing a lighter, safer chassis for the next competition cycle

<b>Chassis Engineer</b>	Aug 2024 – April 2025
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- Designed and manufactured roll cage and safety-critical structures, compliant with SAE standards
- Presented designs to senior engineers, driving technical discussions and team collaboration

<b>3D Scanner</b> Principles of Integrated Engineering Project	<b>Needham, MA</b> Sept 2025
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- Coded an Arduino to read distance from an infrared sensor mounted on a custom pan tilt mechanism, designed using SolidWorks.

<b>Olin Public Interest Technology</b> Eduponics Sub-team	<b>Needham, MA</b> Aug 2024 – May 2025
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- Designed hydroponic units and plant housing for 40 plants using SolidWorks.
- Wired and coded sensors using Arduino to track water quality, nutrients, and light for plants to grow

## SKILLS

- **Technical:** SolidWorks, MATLAB, OnShape, Python, JavaScript, Git, Arduino, Figma
- **Fabrication:** Wood tools, Mill, Lathe, 3D printing, Laser cutting, TIG Welding
- **Other:** Conversational Mandarin