### Neural Nets II

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## Tuning NN Hyperparameters

- Number of hidden layers:
  - having a single hidden layer will generally give decent results.
    - more layers with fewer neurons can recover hierarchical relations and complex functions
    - for text classification, try one or two hidden layers as a baseline.
- Number of neurons:
  - a common practice is to set neuron counts like a funnel, with fewer and fewer neurons at each level
  - or just pick 150 neurons per layer
  - overall, better to have too many neurons, and use regularization
- Activation functions:
  - ReLU works well for hidden layers
  - softmax is good for the output layer in classification tasks

#### Xavier and He Initialization

Activation function	Uniform distribution [-r, r]	Normal distribution
Logistic	$r = \sqrt{\frac{6}{n_{\rm inputs} + n_{\rm outputs}}}$	$\sigma = \sqrt{\frac{2}{n_{\rm inputs} + n_{\rm outputs}}}$
Hyperbolic tangent	$r = 4\sqrt{\frac{6}{n_{\rm inputs} + n_{\rm outputs}}}$	$\sigma = 4 \sqrt{\frac{2}{n_{\rm inputs} + n_{\rm outputs}}}$
ReLU (and its variants)	$r = \sqrt{2} \sqrt{\frac{6}{n_{\rm inputs} + n_{\rm outputs}}}$	$\sigma = \sqrt{2} \sqrt{\frac{2}{n_{\rm inputs} + n_{\rm outputs}}}$

 Connection weights should be initialized randomly according to a uniform distribution or normal distribution, as indicated in the table (see Geron Chapter 11).

model.add(Dense(64, kernel\_initializer='he\_normal')
model.add(Dense(64, kernel\_initializer='he\_uniform'

### Other Activation Functions

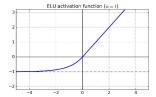
► Leaky ReLU

$$\max(\alpha z, z)$$

where  $\alpha$  is set to a small number, such as .01, or learned in training.

Exponential linear unit

$$\mathsf{ELU}(z) = \begin{cases} \alpha(\exp(z) - 1) & z < 0 \\ z & z \ge 0 \end{cases}$$



▶ In general, ELU has had the best performance so far, but it is slower than ReLU.

#### Batch normalization

- Another trick to speed up training:
  - in between layers, zero-center and normalize the inputs to variance one.
  - normally done before a non-linear activation function

```
\label{eq:from_series} \begin{array}{ll} from & keras.layers.normalization & import & BatchNormalization \\ model.add(Dense(64, use\_bias=False)) \\ model.add(BatchNormalization()) \\ model.add(Activation('elu')) \end{array}
```

# Regularization for Sparse Models

As with linear models, neural network parameters can be regularized with an L1 and/or L2 penalty to push weak neurons to zero and produce a sparse model.

### Dropout

- Another major advance in neural nets is dropout.
  - ▶ at every training step, every neuron has some probability *p* (typically .5) of being temporarily dropped out, so that it will be ignored at this step.
  - after training, neurons dont get dropped any more.
- Neurons trained with dropout:
  - cannot co-adapt with neighboring neurons and must be independently useful.
  - cannot rely excessively on just a few input neurons, they have to pay attention to all input neurons.
    - this makes your model less sensitive to slight changes in the inputs.
- If a model is over-fitting, increase dropout. Dropout can be higher for large layers and lower for small layers.

from keras.layers import Dropout model.add (Dropout (0.5))

## Optimizers and loss functions

Choice of optimization algorithm is the topic of active research, which has shown that it can have a big impact on model performance.

```
model.compile(optimizer='adam', loss='binary_crossentropy')
model.compile(optimizer='sgd', loss='binary_crossentropy')
```

- A good starting choice is Adam (adaptive moment estimation), which is fast and usually works well. For robustness, can also try SGD.
- Loss functions:

Prediction Task	Loss Function to Use	
binary classification	binary_crossentropy	
multi-class classification	categorical_crossentropy	
regression	mean_squared_error	

# Early stopping

A popular/efficient regularization method is to continually evaluate your model at regular intervals, and then to stop training when the test-set accuracy starts to decrease.

## **Practical Guidelines**

Table 11-2. Default DNN configuration		
He initialization		
ELU		
Batch Normalization		
Dropout		
Adam		
None		

## Batch Training with Large Data

If data sets don't fit in memory, one can load the data in batches from disk.

can also continuously update a saved model.

#### Grid search for model choice

- ▶ The flexibility of DNNs is a blessing and a curse.
  - in general, one should make a complex model that allows regularization.
- ▶ But still, there are many choices to be made.
  - to choose the number of hidden layers, for example, one can use cross-validation grid search (as we did with standard scikit-learn models).

# Grid search for model choice (code)

```
from keras.wrappers.scikit_learn import KerasClassifier
from sklearn.model selection import GridSearchCV
# instantiate KerasClassifier with build function
def create_model(hidden_layers=1):
    model = Sequential()
    model.add(Dense(16, input_dim=num_features))
    for i in range(hidden_layers):
        model.add(Dense(8, activation='relu'))
    model.add(Dense(1, activation='sigmoid'))
    model.compile(loss='binary_crossentropy',
                optimizer='adam'.
                metrics= ['accuracy'])
    return model
clf = KerasClassifier(create_model)
# set oup grid search CV to select number of hidden layers
params = {'hidden_layers' : [0,1,2,3]}
grid = GridSearchCV(clf, param_grid=params)
grid. fit (X,Y)
grid.best params
```