

# Query-by-Example Image Retrieval using Visual Dependency Representations

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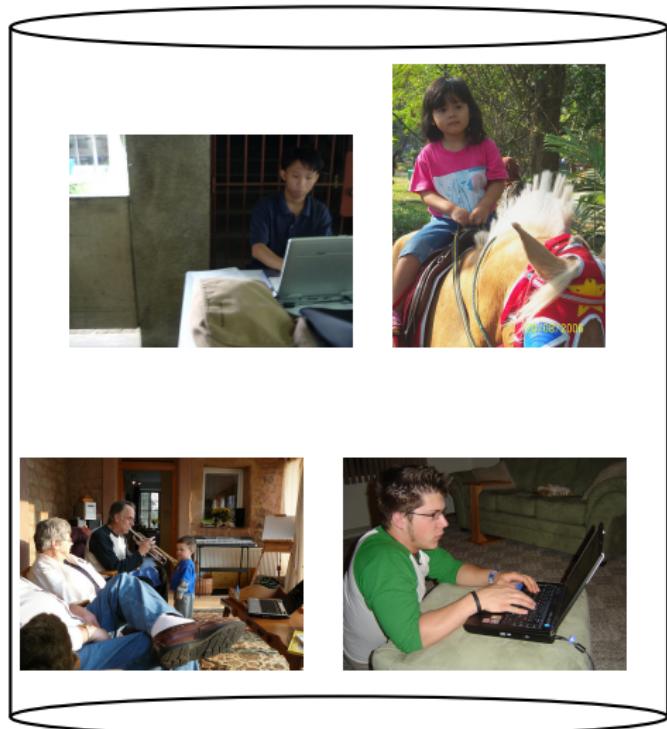


In this talk, similar means same action

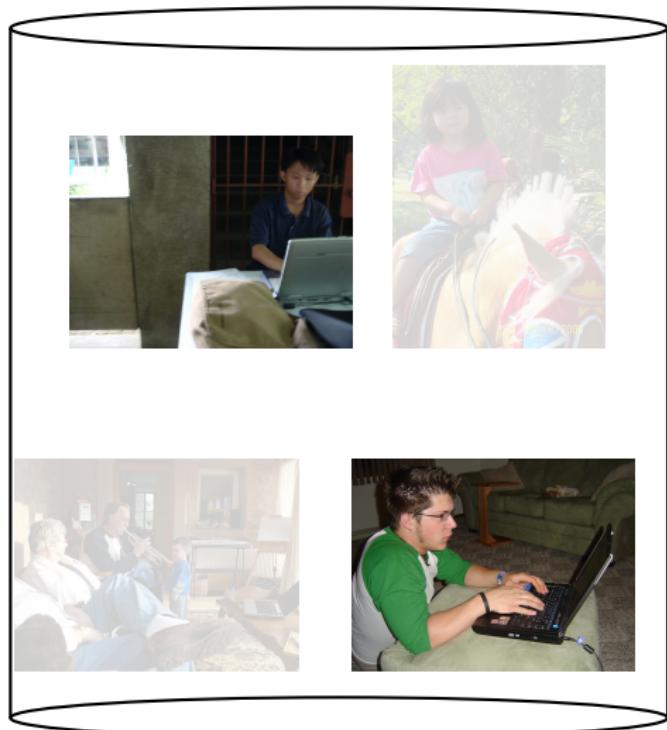
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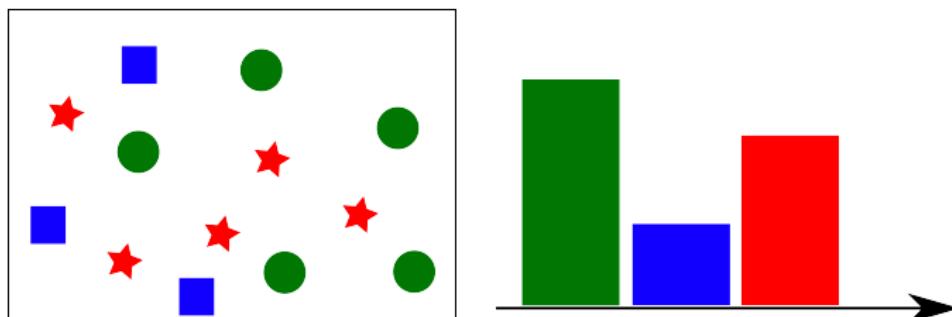


# Query-by-Example Image Retrieval



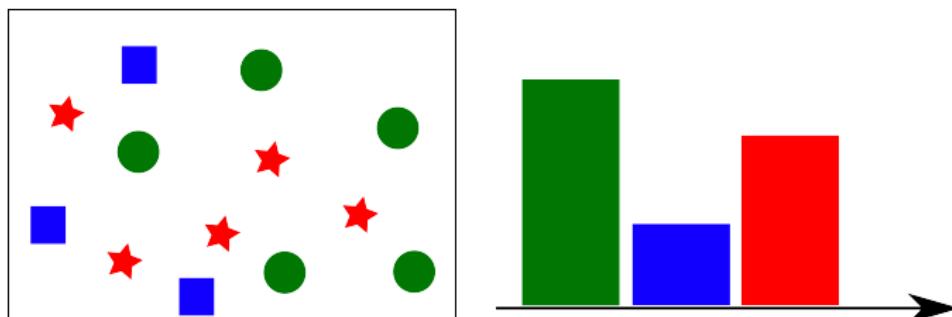
# Typical Approaches to Image Retrieval

- ▶ Represent images as automatically extracted bag-of-visual-words (*visterns*)
  - ▶ SIFT, HoG, etc...



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  - ▶ SIFT, HoG, etc...



- ▶ Large heterogenous data sets
  - ▶ Corel 5K (5K images)
  - ▶ CIFAR-10 (60K images)
  - ▶ TinyImages (100K images)
  - ▶ ...

# This Talk

- ▶ Represent images as annotated regions
  - ▶ Tighter connection to language than a *vi* term



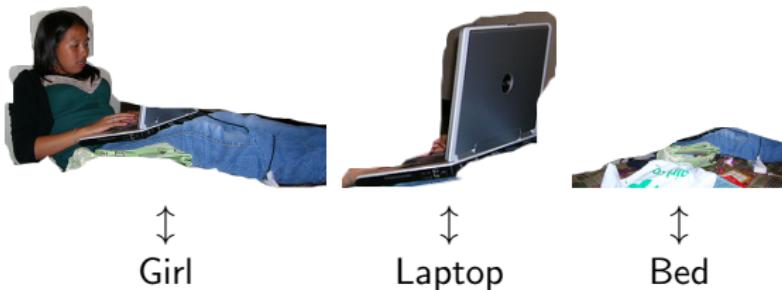
↑  
↓  
Girl

↑  
↓  
Laptop

↑  
↓  
Bed

# This Talk

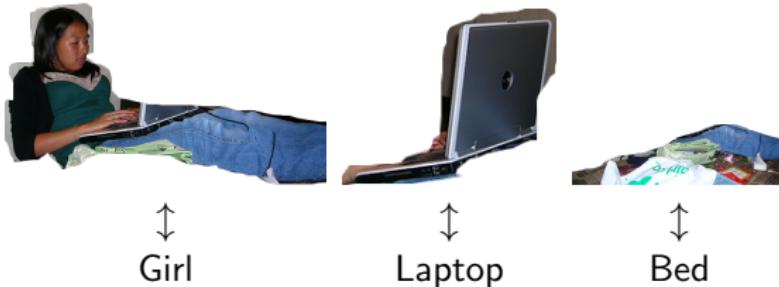
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  - ▶ Tighter connection to language than a *visterm*



- ▶ Smaller data set: 341 images depicting **actions**
  - ▶ Explore the effect of action types on accuracy

# This Talk

- ▶ Represent images as annotated regions
  - ▶ Tighter connection to language than a *vi* term



- ▶ Smaller data set: 341 images depicting **actions**
  - ▶ Explore the effect of action types on accuracy
- ▶ Focus on encoding the **spatial** relationships between regions

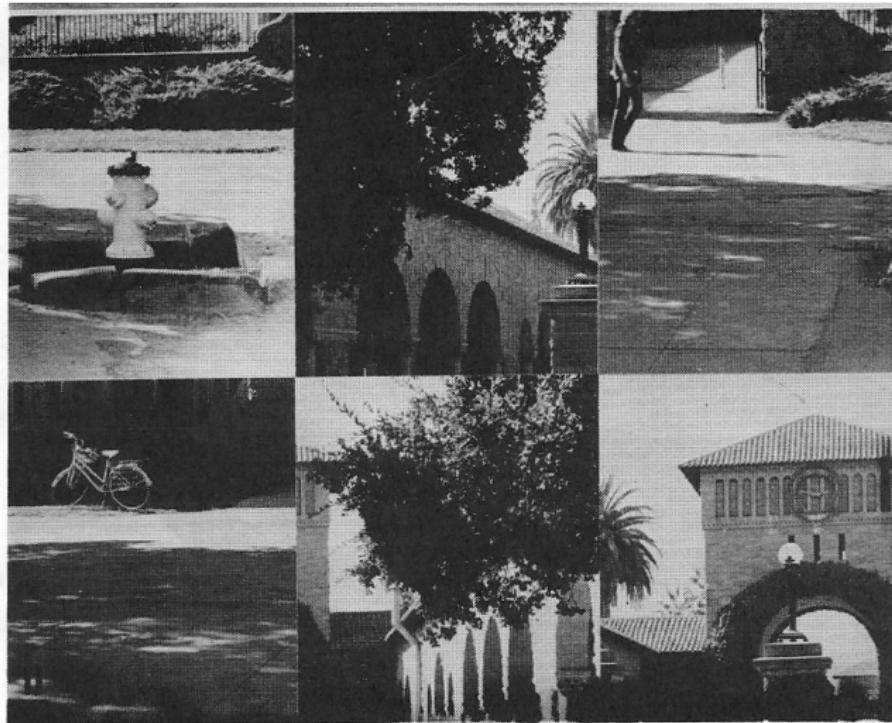
# Humans benefit from consistent spatial relationships

Biederman (1972)



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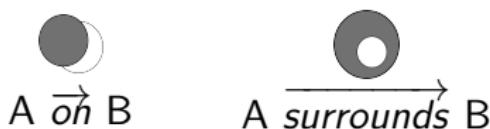


## Visual Dependency Representation (Elliott and Keller, 2013)

- ▶ Novel structured representation over image regions
  - ▶ Captures salient region-region relationships
  - ▶ Guided by the written description of the image
- ▶ Proved useful for describing actions in Elliott and Keller (2013)
- ▶ Inspired by dependency-syntax of language (Tesnière, 1953)
  - ▶ Tokens: image regions
  - ▶ Grammar: spatial relationships

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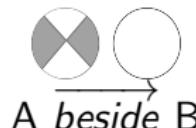
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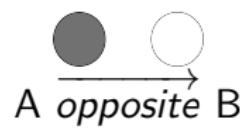
A  $\overrightarrow{on}$  B



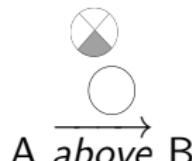
A  $\overrightarrow{surrounds}$  B



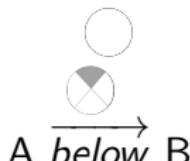
A  $\overrightarrow{beside}$  B



A  $\overrightarrow{opposite}$  B



A  $\overrightarrow{above}$  B



A  $\overrightarrow{below}$  B

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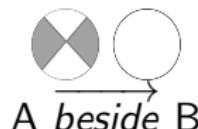
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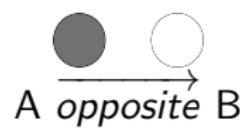
A  $\overrightarrow{on}$  B



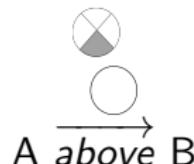
A  $\overrightarrow{surrounds}$  B



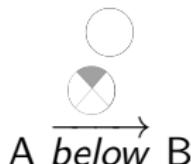
A  $\overrightarrow{beside}$  B



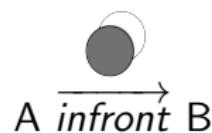
A  $\overrightarrow{opposite}$  B



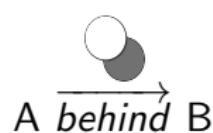
A  $\overrightarrow{above}$  B



A  $\overrightarrow{below}$  B



A  $\overrightarrow{infront}$  B



A  $\overrightarrow{behind}$  B

## Gold Standard Example



“A girl is using a laptop. She is sitting on a bed.”



Girl



Laptop



Bed

## Gold Standard Example



“A girl is using a laptop. She is sitting on a bed.”



ROOT

Girl



Laptop



Bed

## Gold Standard Example



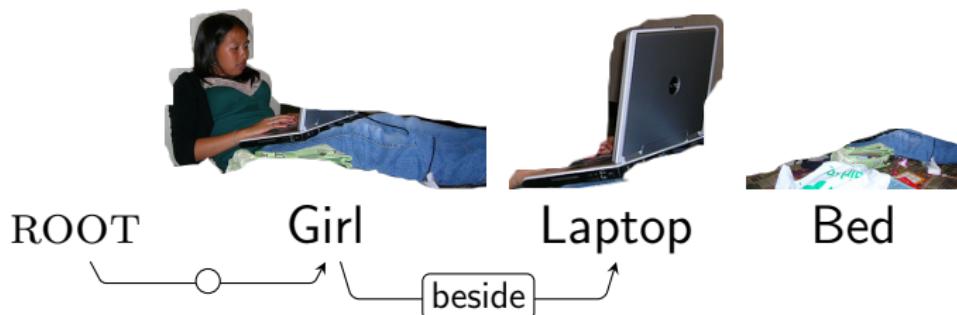
“A **girl** is using a laptop. She is sitting on a bed.”



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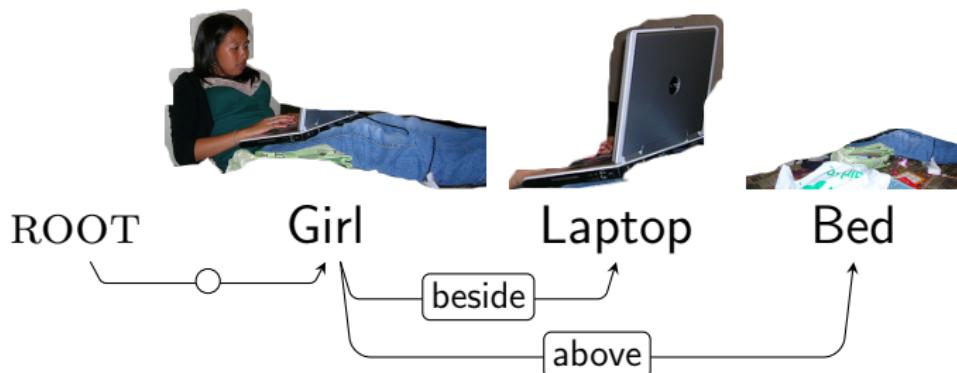
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## Gold Standard Example



“A girl is using a laptop. **She** is sitting on a **bed**.”



# Data



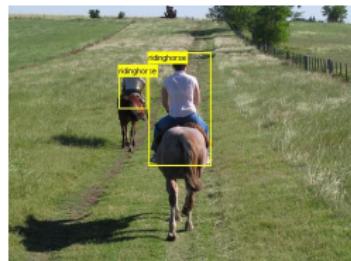
341 images  
from PASCAL VOC  
Action Recognition  
gold action labels

# Data: 341 Images

- ▶ 10 types of actions



Reading



Ride horse



Phoning



Ride bike



Play instrument

# Data: 341 Images

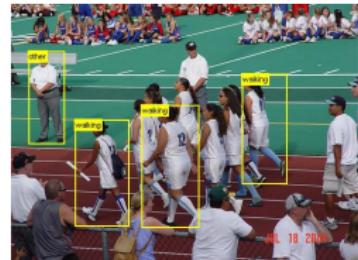
- ▶ 10 types of actions



Jumping



Running



Walking

# Data: 341 Images

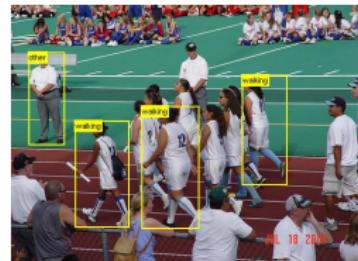
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Jumping



Running



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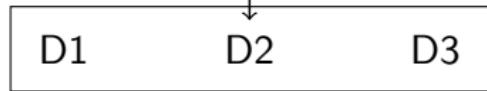


Use computer



Take photo

# Data



341 images  
from PASCAL VOC  
Action Recognition  
with action labels

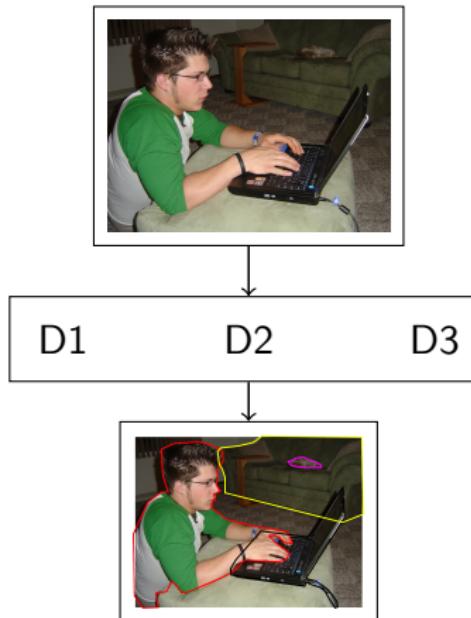
3 descriptions/image

# Data: 1,023 Descriptions from Mechanical Turk



1. A teenage **girl** is using a **laptop**. She is sitting on a **bed**.
2. A **girl** is using a **laptop**. There is a **lamp** beside her.
3. A **girl** is using a **computer**. There is a **picture** behind her.

# Data

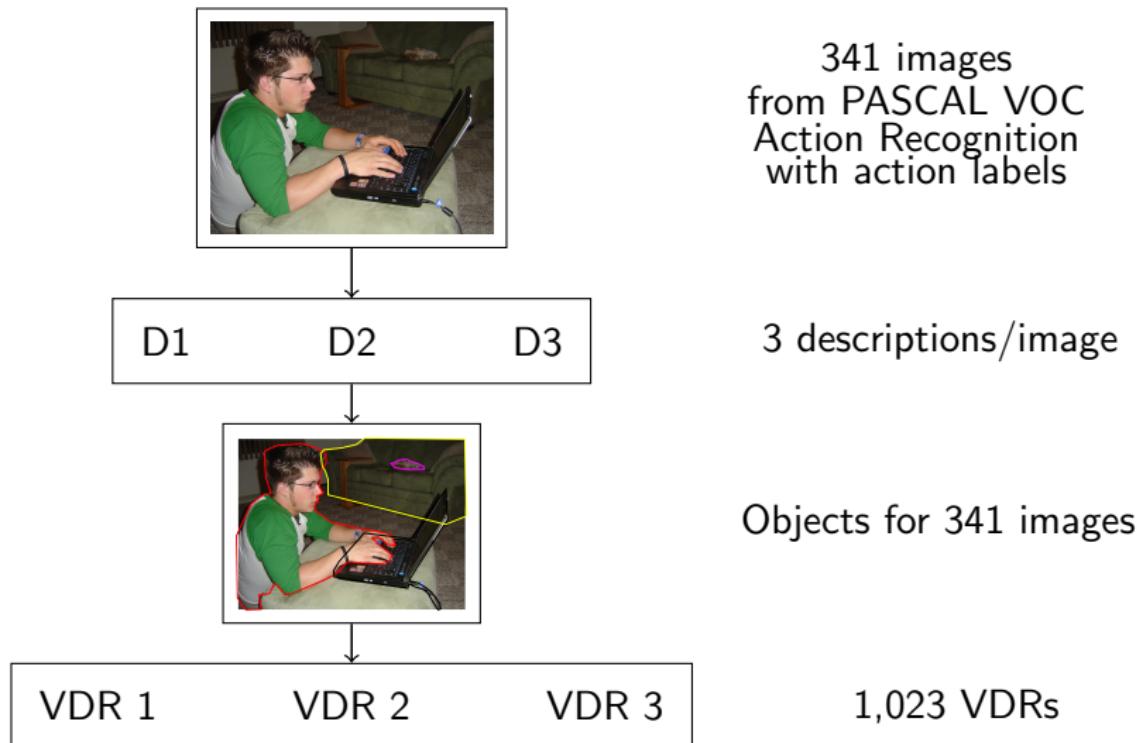


341 images  
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3 descriptions/image

Objects for 341 images

# Data

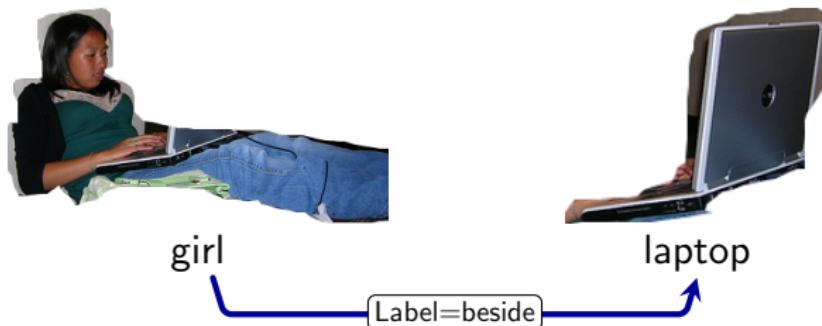


## Automatic VDR Prediction

- ▶ Framed as a dependency parsing task
  - ▶ MaltParser (Nivre et al., 2004) seems unsuitable because it is incremental
- ▶ Construct a complete graph between all regions using MSTParser (McDonald et al., 2005)
  - ▶ Remove all features that encode the linear order of the input
  - ▶ Extract features from the image regions

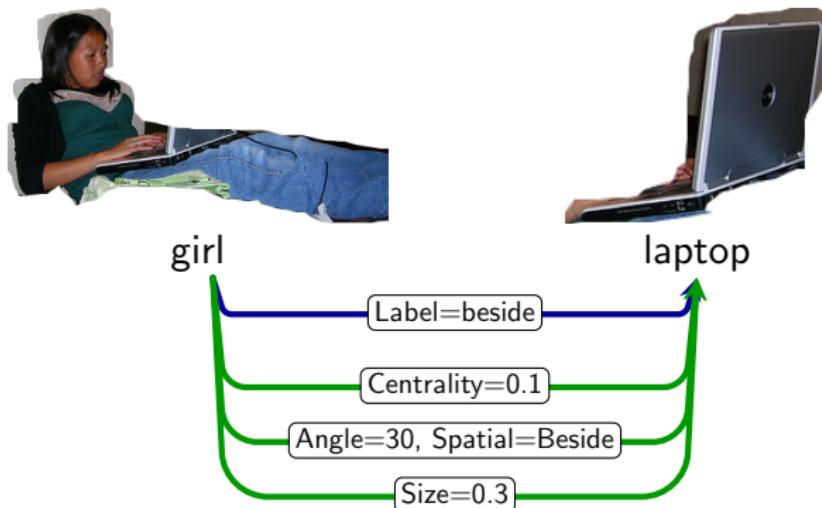
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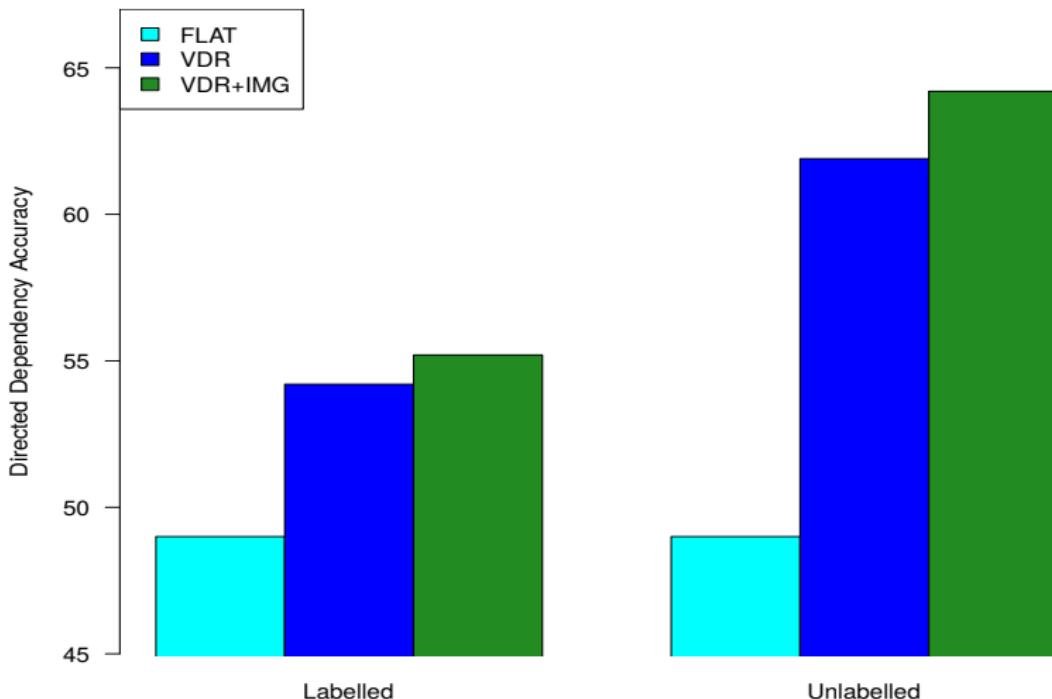
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# VDR Parsing Experiment

- ▶ Task
  - ▶ Predict VDR over region-annotated image
- ▶ Data
  - ▶ 1,023 VDR data set
  - ▶ 10 fold cross-validation
- ▶ Evaluation
  - ▶ Unlabelled/labelled directed attachment accuracy
- ▶ Models
  - ▶ FLAT is a bag-of-regions baseline
  - ▶ VDR uses only input features
  - ▶ VDR+IMG also uses visual features

# VDR Parsing Results



# Query-by-Example Image Retrieval

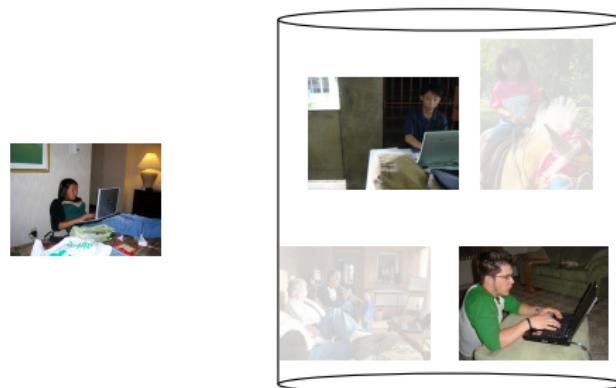
- ▶ Given a query example, find images of the same action



- ▶ Matching function: cosine with *tf-idf* weighting

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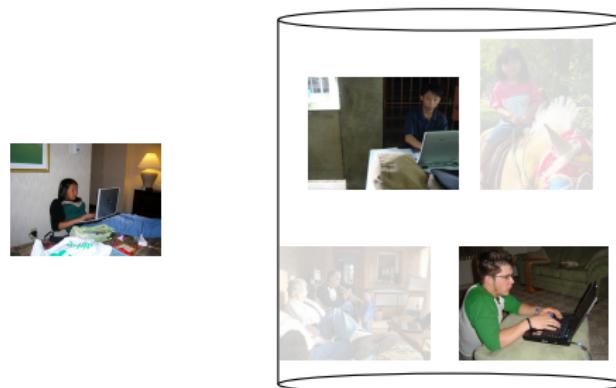
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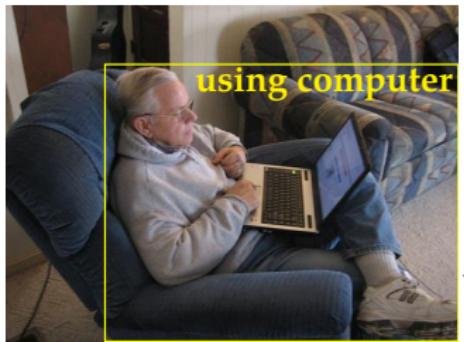
- ▶ Matching function: cosine with *tf-idf* weighting
- ▶ Evaluate with Mean Average Precision and Precision@10
  - ▶ Relevance means same action annotation
- ▶ Models:
  - ▶ Bag-of-Regions representation
  - ▶ Visual Dependency Representation
  - ▶ Both use gold-standard object annotations

## Bag-of-Regions Representation

$$\cos(a, b) = \frac{a \cdot b}{\|a\| \|b\|}$$

# Bag-of-Regions Representation

$$\cos\left( \text{, } \begin{array}{c} \text{using computer} \\ \text{using computer} \end{array} \right)$$



# Bag-of-Regions Representation



$$\cos(\text{,}) =$$

---

*<person,laptop>·<person,laptop>*

# Bag-of-Regions Representation



$$\cos(\text{,}) =$$

---

$\langle \text{person}, \text{laptop} \rangle \cdot \langle \text{person}, \text{laptop} \rangle$

$\text{person}, \text{laptop}, \dots$

$\text{person}, \text{laptop}, \dots$

# Bag-of-Regions Representation

$$\cos \left( , \right)$$



# Bag-of-Regions Representation



$$\cos(\text{,}) =$$

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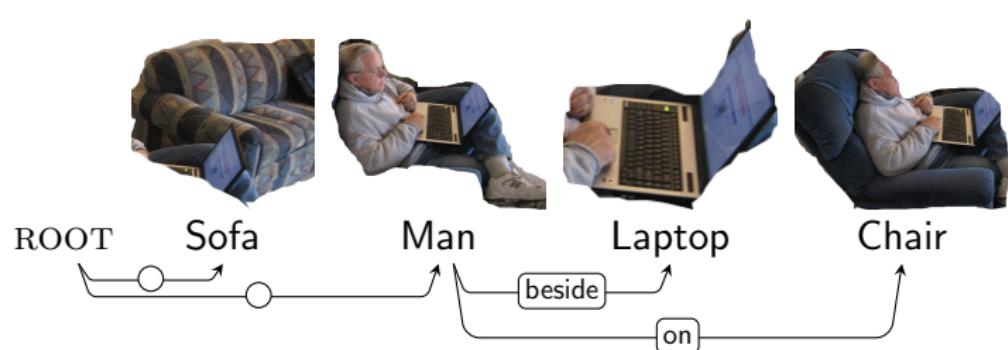
$\langle \text{person}, \text{laptop} \rangle \cdot \langle \text{person}, \text{laptop} \rangle$

$\text{person}, \text{laptop}, \dots$

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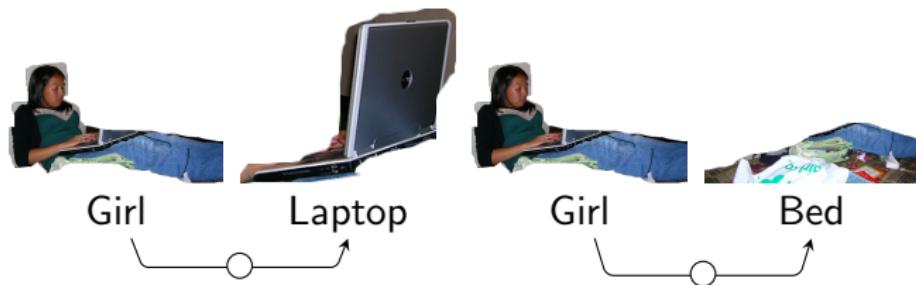
# Visual Dependency Representation

- ▶ How to compare two trees?



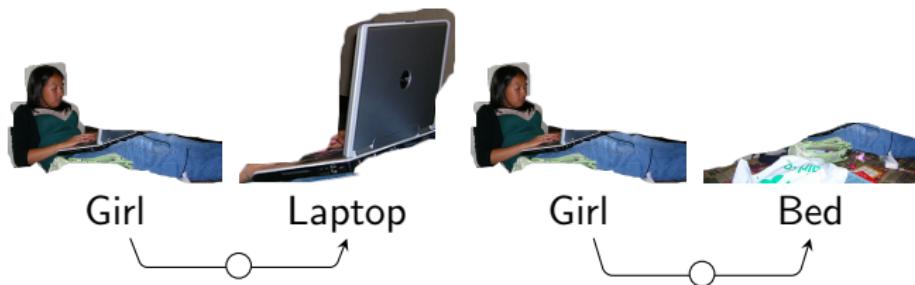
# Visual Dependency Representation

- ▶ How to compare two trees?
  - ▶ Decompose all edges into bigrams and trigrams



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    - ▶ Decompose all edges into bigrams and trigrams

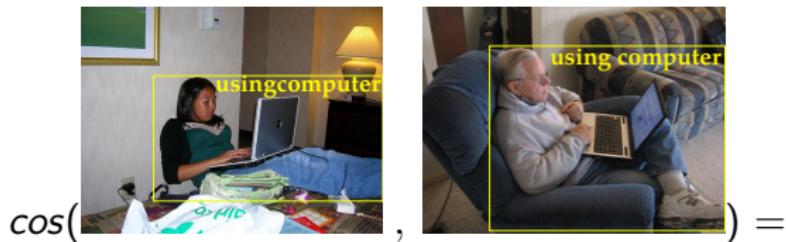


# Visual Dependency Representation



$$\cos(( , ) =$$

# Visual Dependency Representation



$\langle \text{Girl Laptop} \rangle \cdot \langle \text{Man Laptop} \rangle$

beside

beside

# Visual Dependency Representation



$\langle \text{Girl Laptop} \rangle \cdot \langle \text{Man Laptop} \rangle$

beside

beside

Girl Laptop , Girl Bed ...

beside

above

Man Laptop ...

beside

# Visual Dependency Representation

$$\cos( \text{, } ) =$$



# Visual Dependency Representation

$$\cos\left( \text{, } \begin{array}{c} \text{using computer} \\ \text{playing instrument} \end{array} \right) =$$

---

<>

# Visual Dependency Representation



$$\cos(($$

<>

Girl Laptop , Girl Bed ...

beside

above

Man Trumpet ...

beside

## Results

---

|                | MAP   | P@10  |
|----------------|-------|-------|
| Bag-of-Regions | 0.467 | 0.415 |

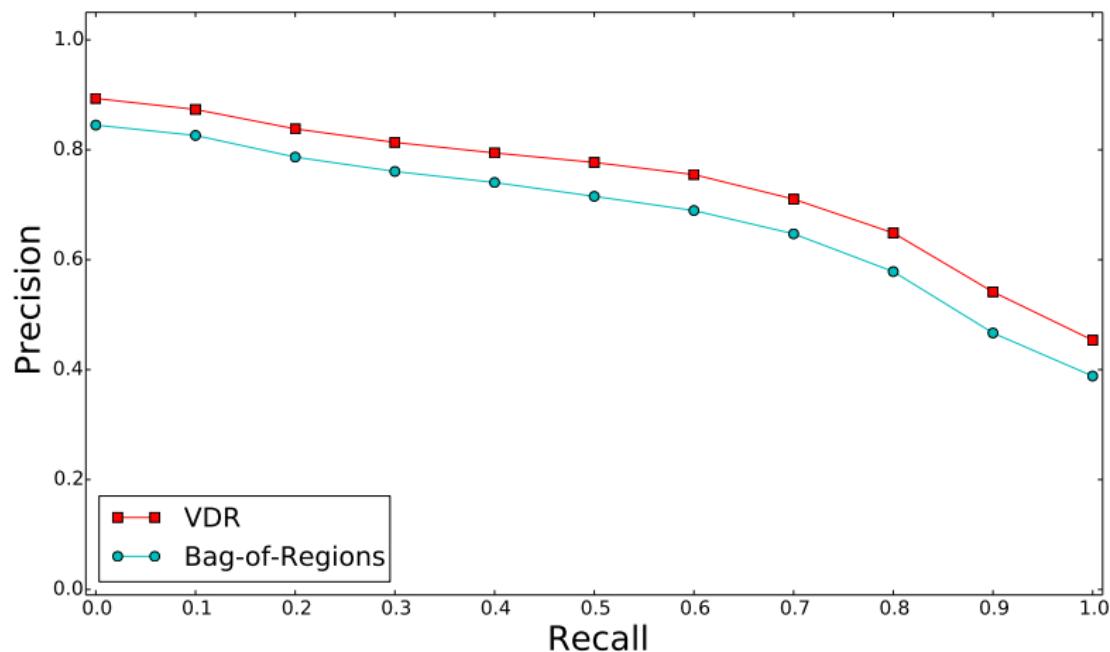
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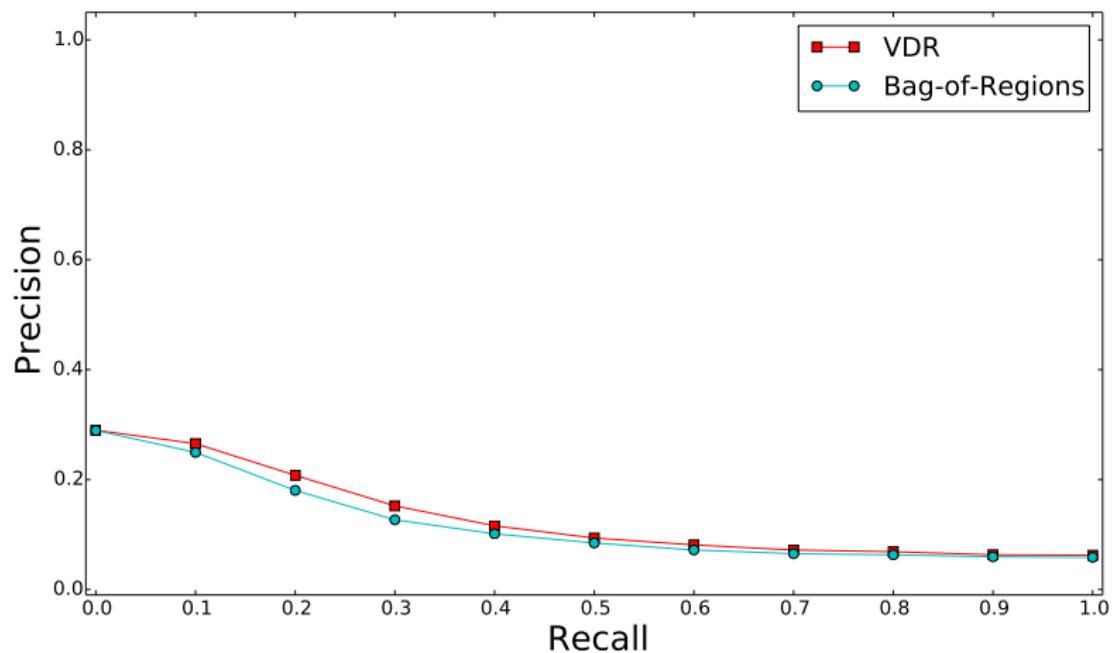
|                | MAP    | P@10   |
|----------------|--------|--------|
| Bag-of-Regions | 0.467  | 0.415  |
| VDR            | 0.508* | 0.451* |

\*: significantly better than Bag-of-Regions at  $p < 0.01$

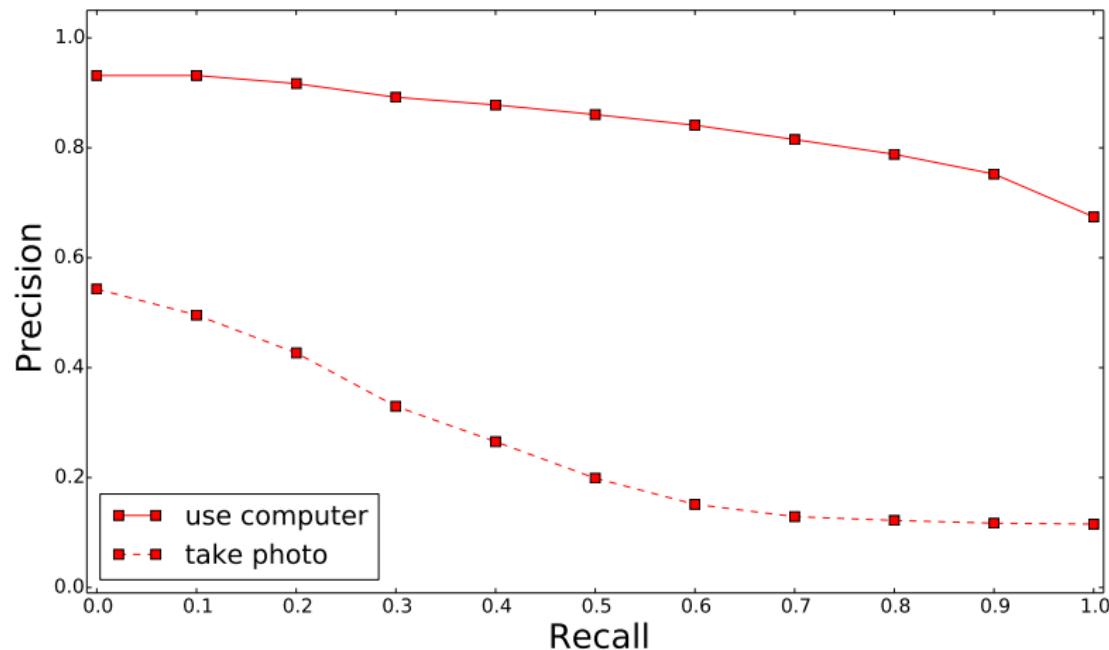
## Transitive actions



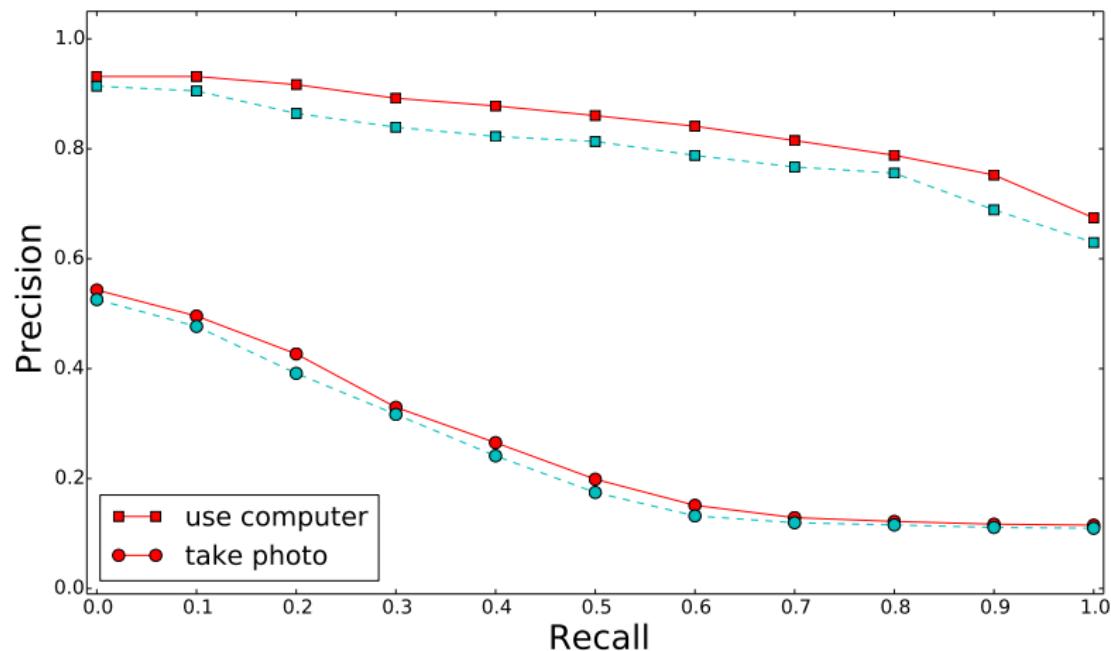
## Intransitive actions



## “Light” actions - use computer / take photo



## “Light” actions - use computer / take photo



## Conclusions

- ▶ VDR increases the accuracy of query-by-example image retrieval compared to a bag-of-regions baseline
- ▶ Improvement depends on the type of action:
  - ▶ Most pronounced for transitive verbs
  - ▶ Least pronounced when no object is required for the action
- ▶ Future work:
  - ▶ Scaling to larger data sets
  - ▶ Different matching paradigms, e.g. RankSVM
  - ▶ Explore the effect of other languages on actions

## Questions?

- ▶ VDRParser: <http://github.com/elliottd/vdrparser>
- ▶ Data: <http://homepages.inf.ed.ac.uk/s0128959/dataset/>
- ▶ <http://homepages.inf.ed.ac.uk/s0128959/>
- ▶ [d.elliott@ed.ac.uk](mailto:d.elliott@ed.ac.uk) // @delliott

## References

- Biederman, I. (1972). Perceiving real-world scenes. *Science*, 177(4043):77–80.
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