Intro to Databases (COMP\_SCI 339)

Index Concurrency Control



#### **ADMINISTRIVIA**

Project #2 is due Sunday 2/4 @ 11:59pm

Project #3 will be released tonight and is due Sunday 2/18 @ 11:59pm

## **OBSERVATION**

We assumed all the data structures we have discussed so far are single-threaded.

But a DBMS should allow multiple threads to concurrently access data structures to take advantage of additional CPU cores and hide disk I/O stalls.

## CONCURRENCY CONTROL

A <u>concurrency control</u> protocol is the method that the DBMS uses to ensure "correct" results for concurrent operations on a shared object.

- A protocol's correctness criteria can vary:
- → Logical Correctness: Can a thread see the data that it is supposed to see?
- → Physical Correctness: Is the internal representation of the object sound?

# CONCURRENCY CONTROL

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## TODAY'S AGENDA

Latches Overview
Hash Table Latching
B+Tree Latching
Leaf Node Scans

#### LOCKS VS. LATCHES

#### Locks

- → Protect the database's logical contents from other transactions.
- → Held for transaction duration.
- → Need to be able to rollback changes.

#### Latches

- → Protect the critical sections of the DBMS's internal data structure from other threads.
- → Held for operation duration.
- → Do not need to be able to rollback changes.

# LOCKS VS. LATCHES

Locks	Latches
Separate User Transactions	Threads
Protect Database Contents	In-Memory Data Structures
<b>During</b> Entire Transactions	Critical Sections
Modes Shared, Exclusive, Update, Intention	Read, Write
Deadlock Detection & Resolution	Avoidance
by Waits-for, Timeout, Aborts	Coding Discipline
Kept in Lock Manager	Protected Data Structure

Source: Goetz Graefe

## LOCKS VS. LATCHES

#### Locks

**Separate...** User Transactions

**Protect...** Database Contents

**During...** Entire Transactions

Modes... Shared, Exclusive, Update,

Intention

**Deadlock** Detection & Resolution

...by... Waits-for, Timeout, Aborts

Kept in... Lock Manager

#### Latches

**Threads** 

In-Memory Data Structures

**Critical Sections** 

Read, Write

Avoidance

Coding Discipline

Protected Data Structure

#### LATCH MODES

#### **Read Mode**

- → Multiple threads can read the same object at the same time.
- → A thread can acquire the read latch if another thread has it in read mode.

#### **Write Mode**

- → Only one thread can access the object.
- → A thread cannot acquire a write latch if another thread has it in any mode.

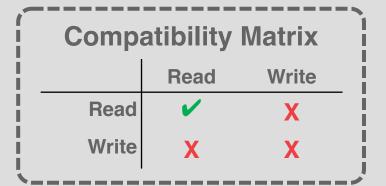
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# **Approach #1: Blocking OS Mutex**

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OS Latch

**A** Userspace Latch

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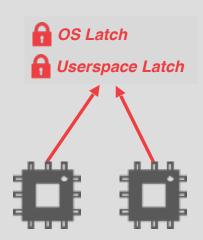






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- → Can be implemented on top of spinlocks.
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# **Approach #2: Reader-Writer Latches**

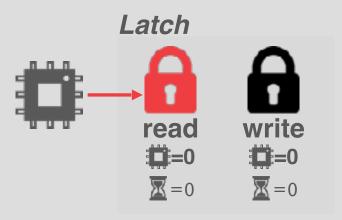
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- → Example: std::shared\_mutex → pthread\_rwlock

# Latch read write p=0 x=0 x=0

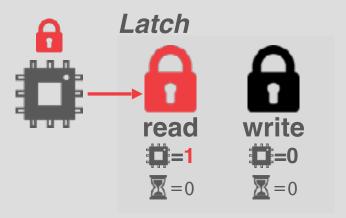
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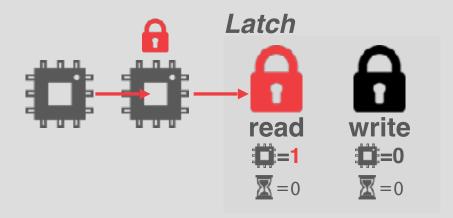
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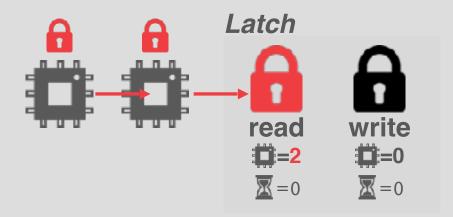
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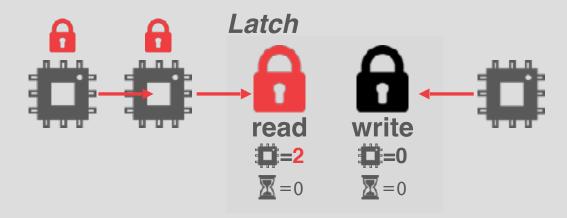
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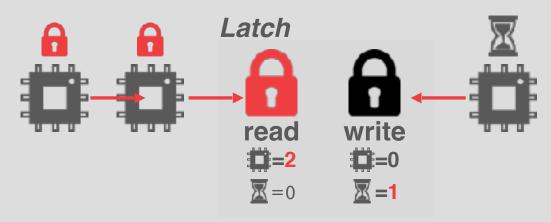
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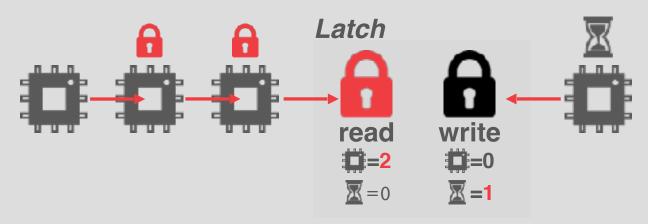
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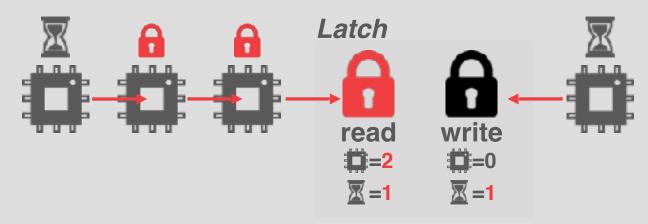
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#### COMPARE-AND-SWAP

Atomic instruction that compares contents of a memory location M to a given value V

- → If values are equal, installs new given value V' in M
- → Otherwise, operation fails

M 20

\_sync\_bool\_compare\_and\_swap(&<mark>M</mark>, 20, 30)

#### COMPARE-AND-SWAP

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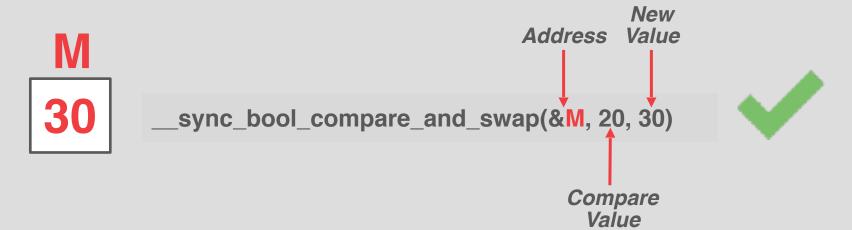
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#### HASH TABLE LATCHING

Easy to support concurrent access due to the limited ways threads access the data structure.

- → All threads move in the same direction and only access a single page/slot at a time.
- → Deadlocks are not possible.

To resize the table, take a global write latch on the entire table (e.g., in the header page).

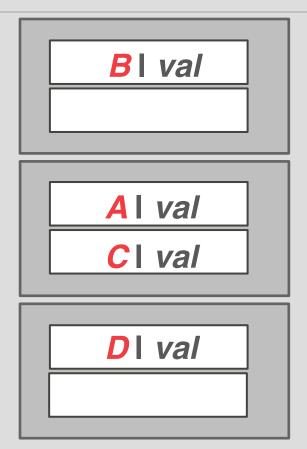
## HASH TABLE LATCHING

# **Approach #1: Page Latches**

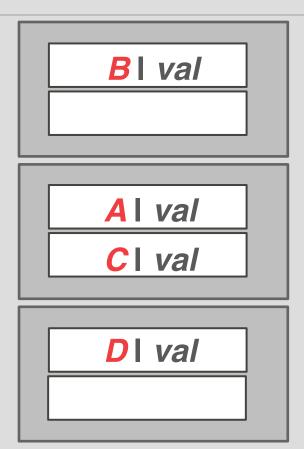
- → Each page has its own reader-writer latch that protects its entire contents.
- → Threads acquire either a read or write latch before they access a page.

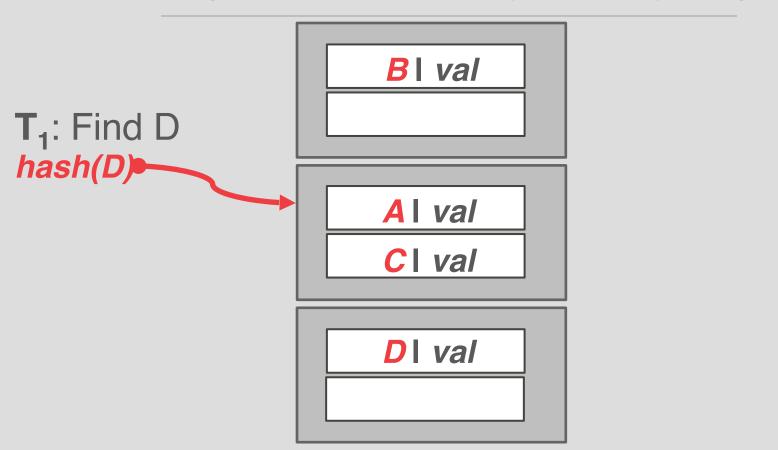
# **Approach #2: Slot Latches**

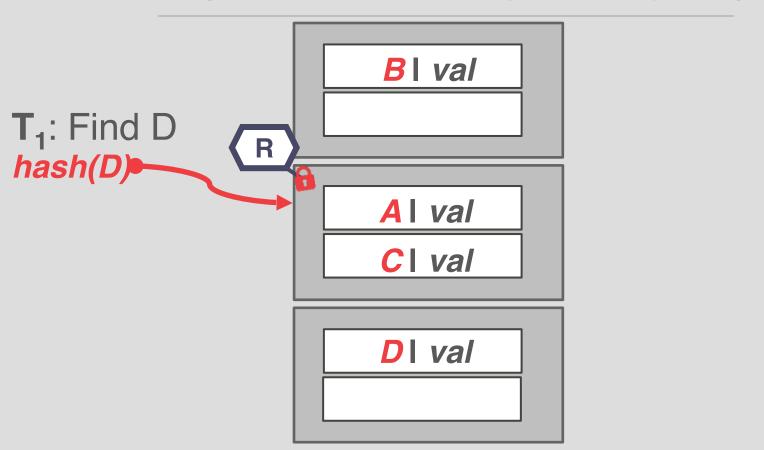
- → Each slot has its own latch.
- → Can use a single-mode latch to reduce meta-data and computational overhead.

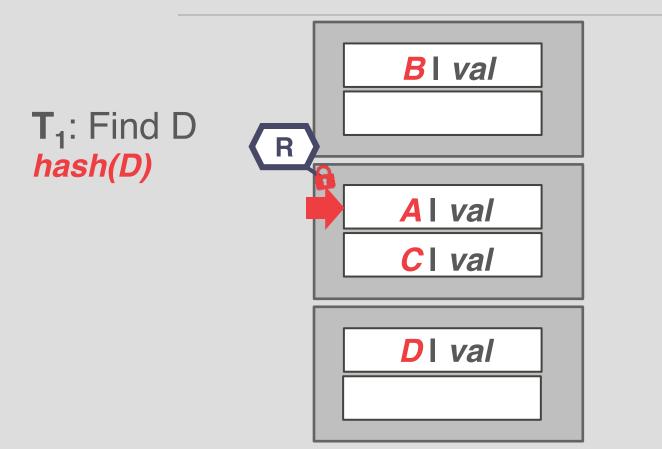


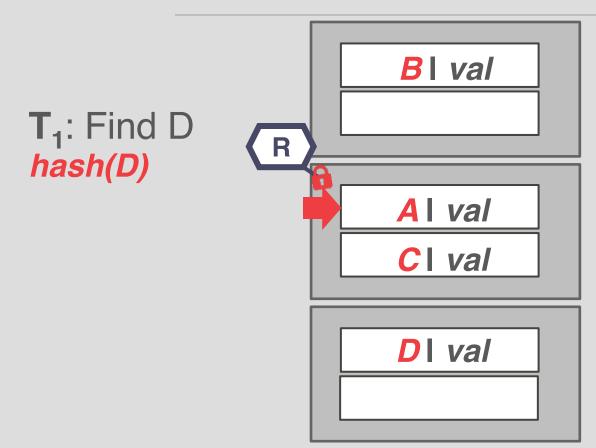
T<sub>1</sub>: Find D hash(D)

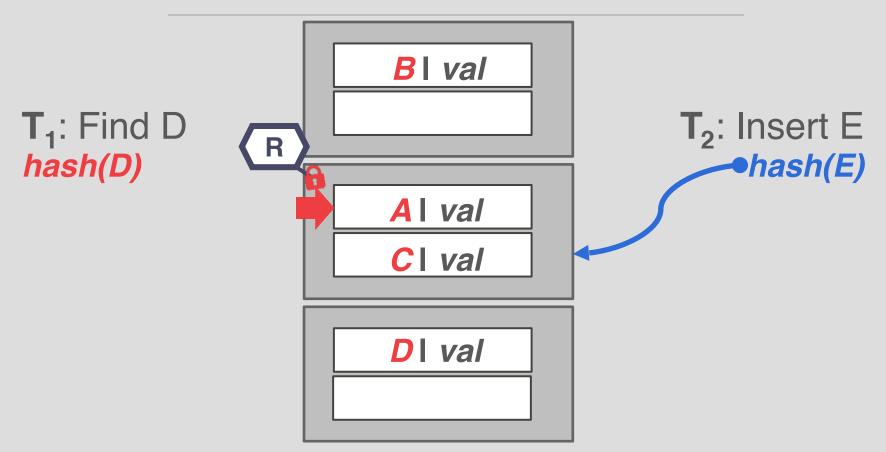


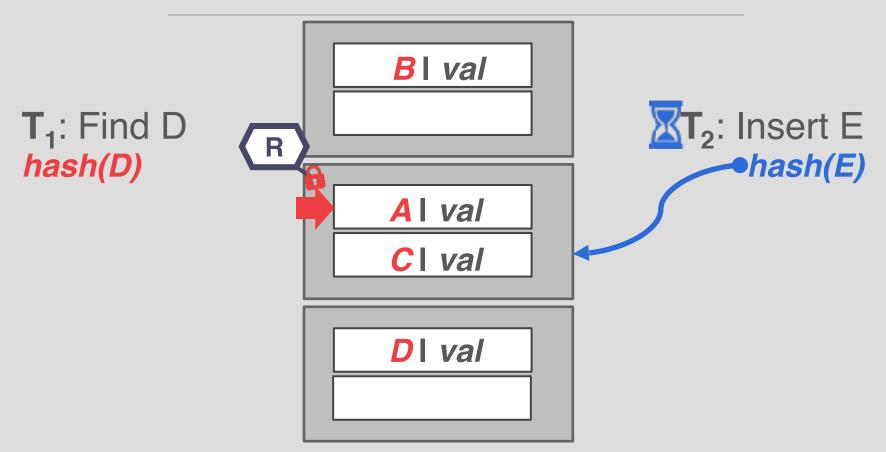


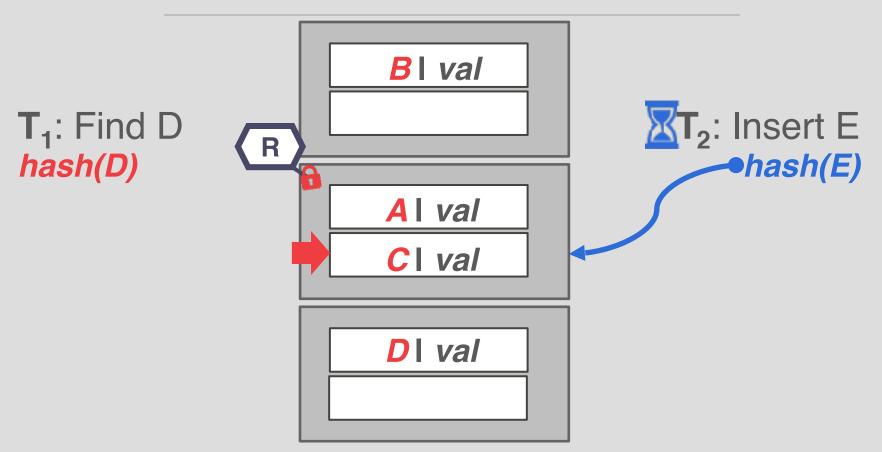


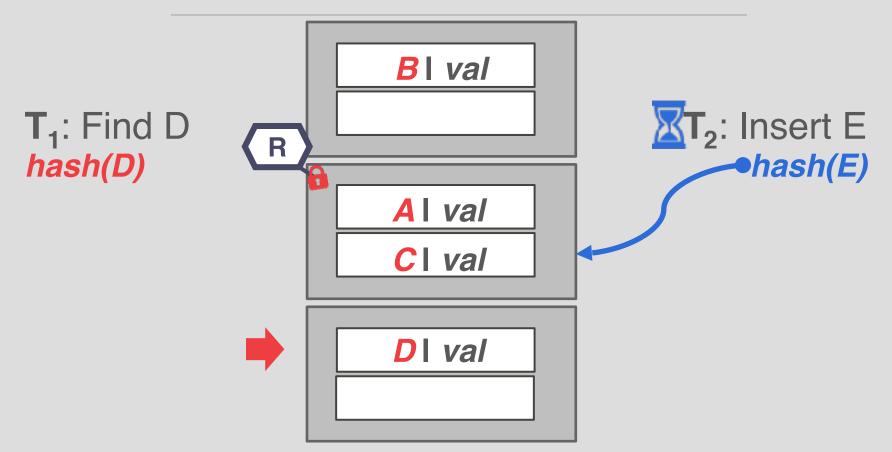


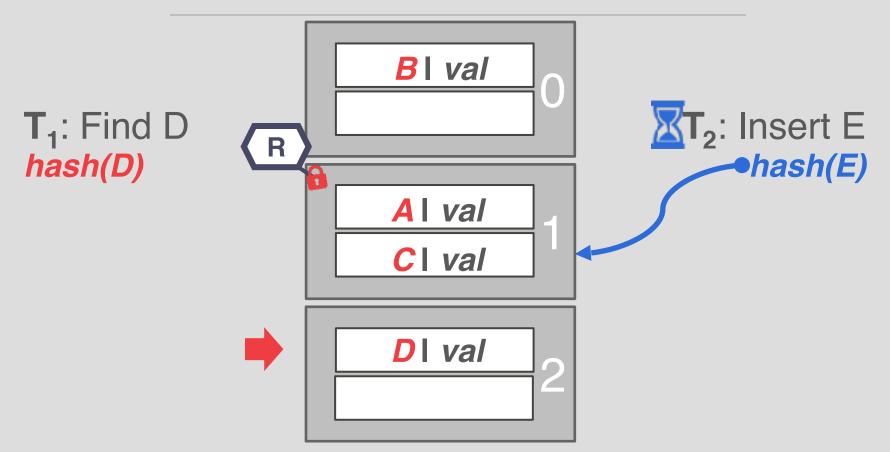


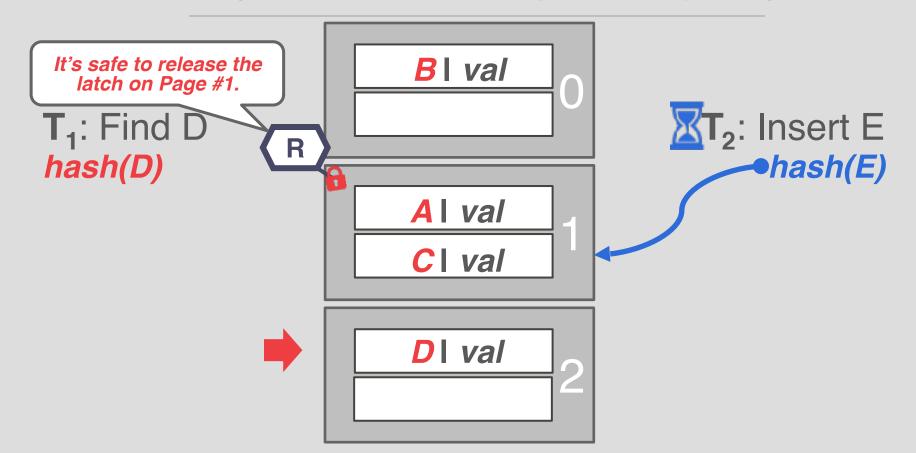






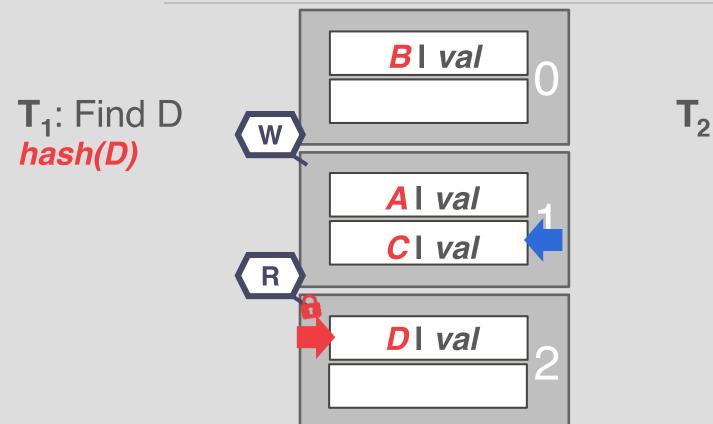






**B**| val T<sub>2</sub>: Insert E T<sub>1</sub>: Find D hash(D) ◆hash(E) A | val CI val R DI val

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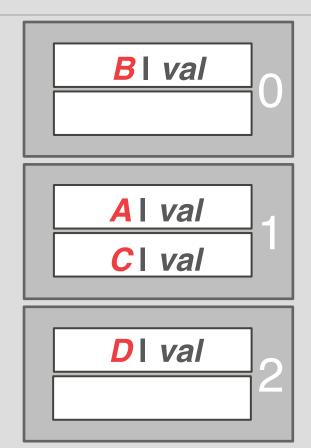
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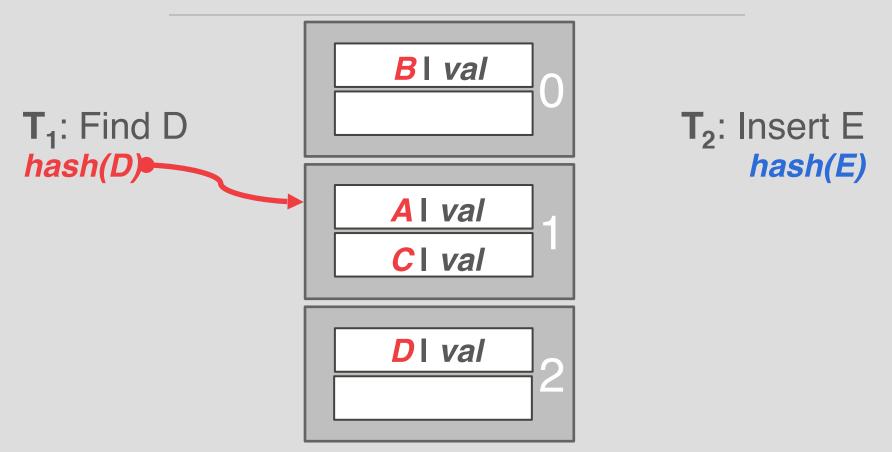
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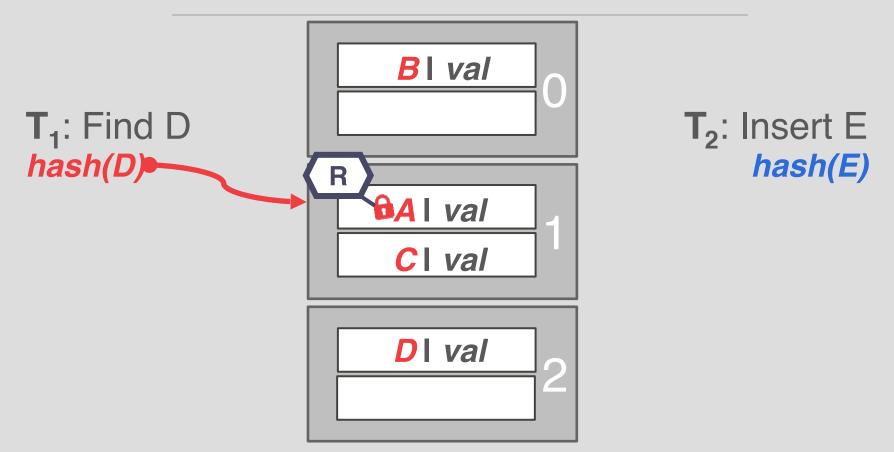
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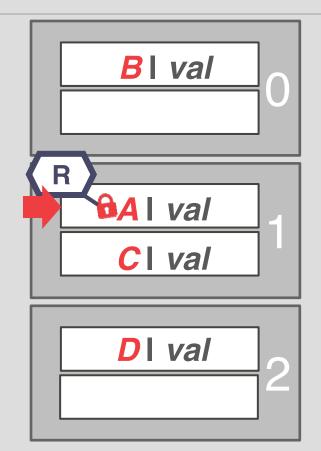
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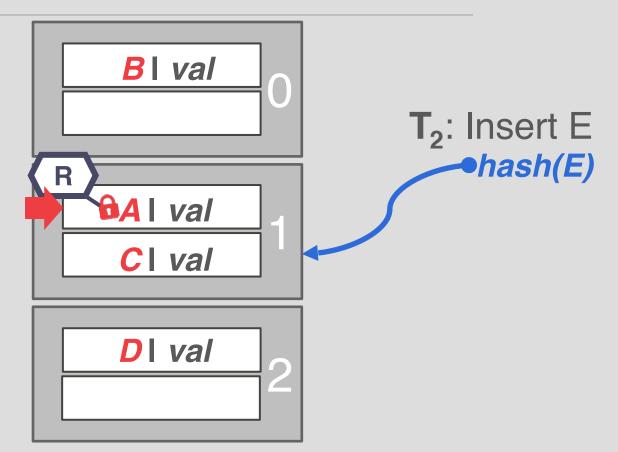




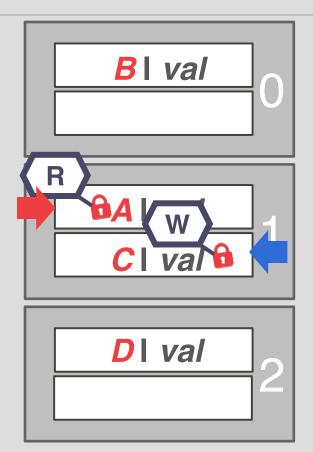
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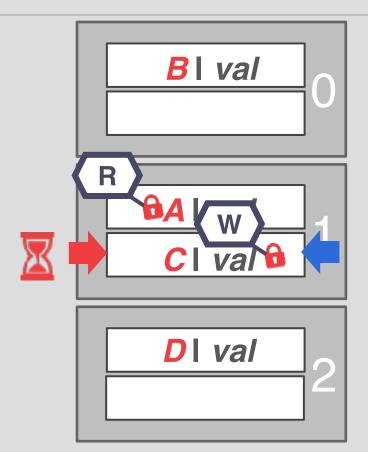
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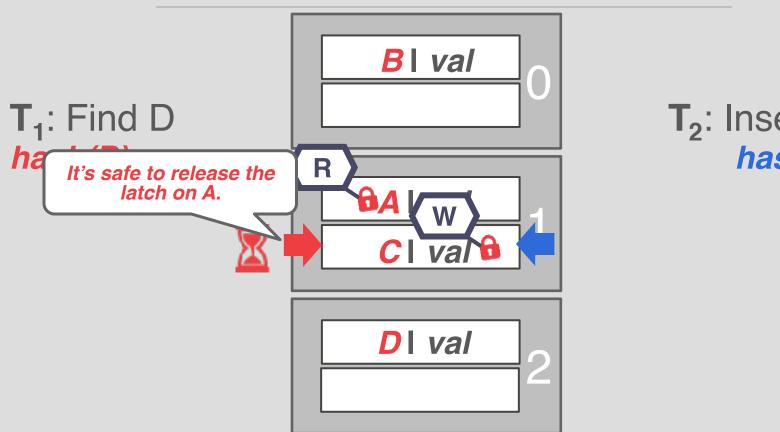


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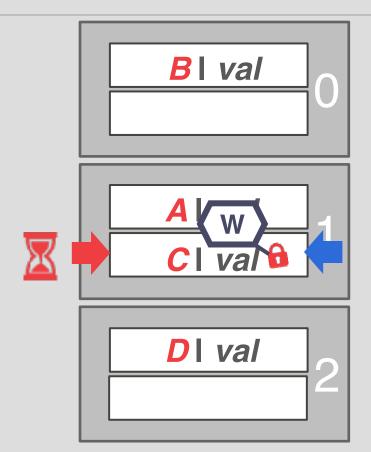


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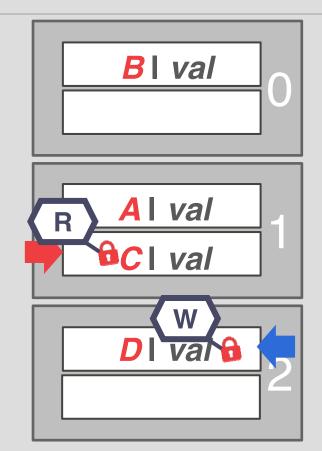


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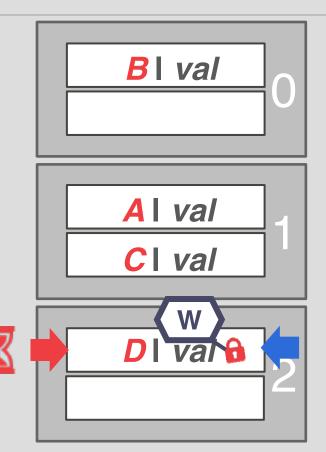


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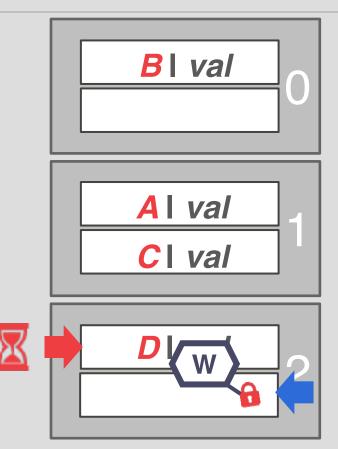
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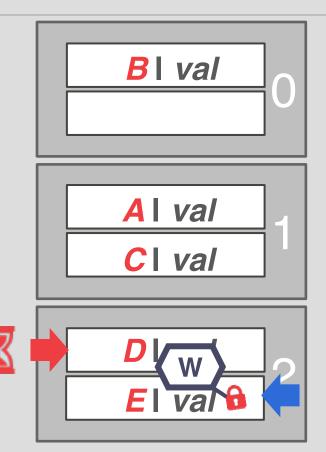
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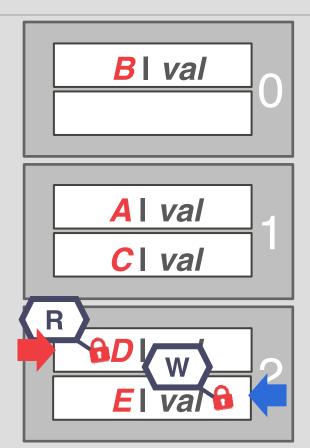
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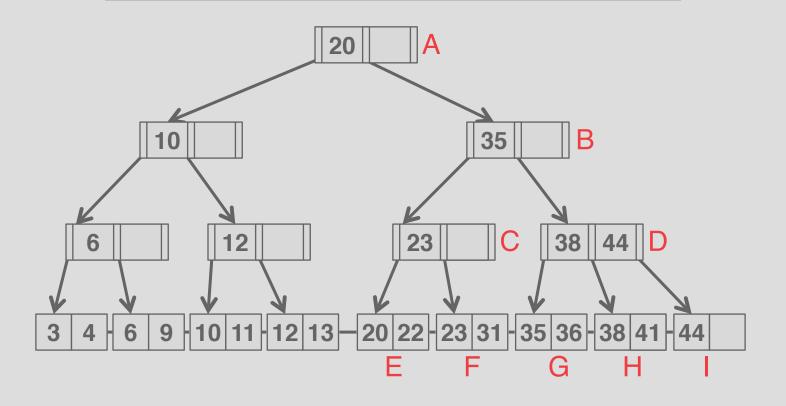
#### B+TREE CONCURRENCY CONTROL

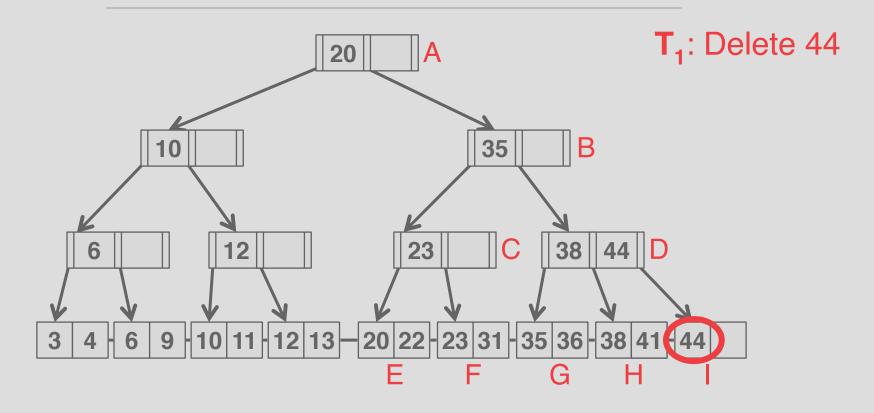
We want to allow multiple threads to read and update a B+Tree at the same time.

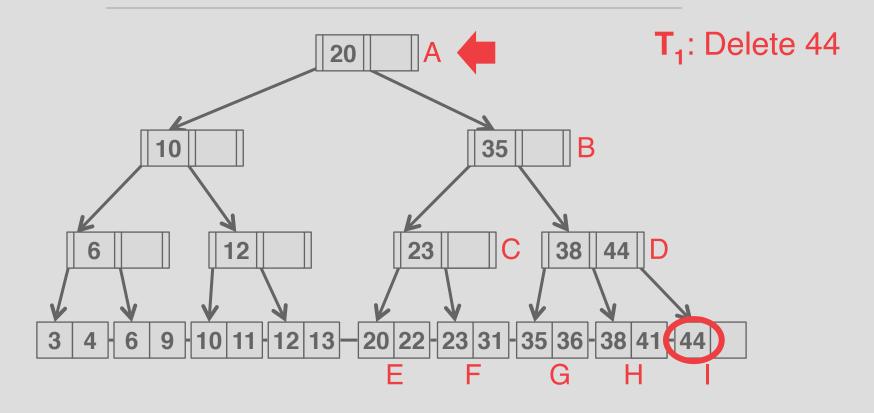
We need to protect against two types of problems:

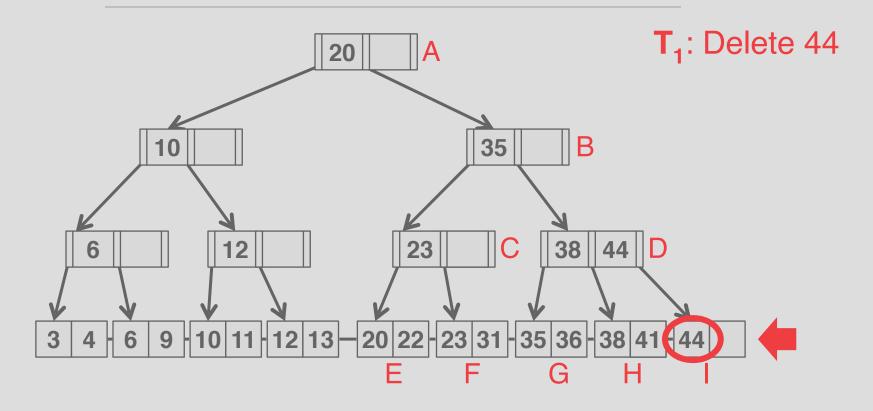
- → Threads trying to modify the contents of a node at the same time.
- → One thread traversing the tree while another thread splits/merges nodes.

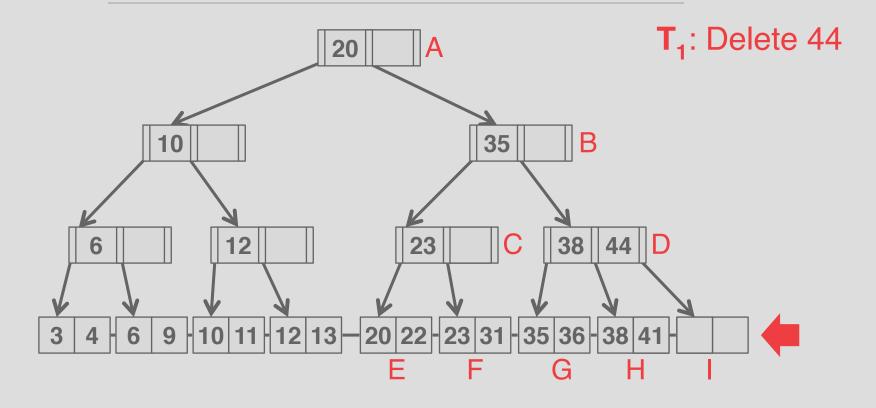
#### B+TREE MULTI-THREADED EXAMPLE

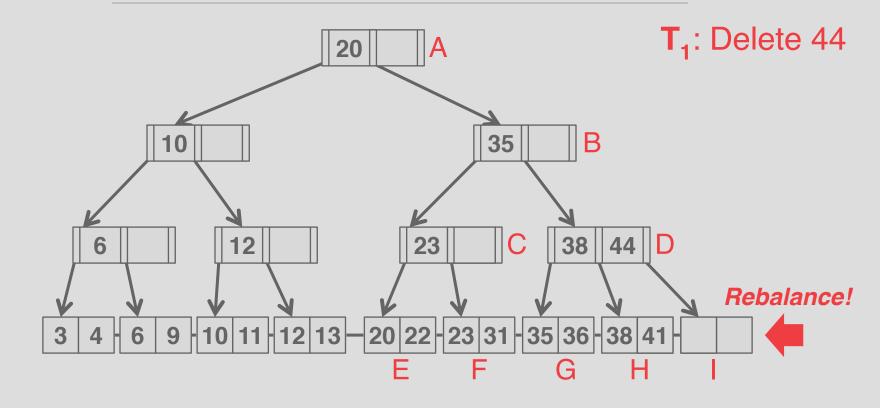


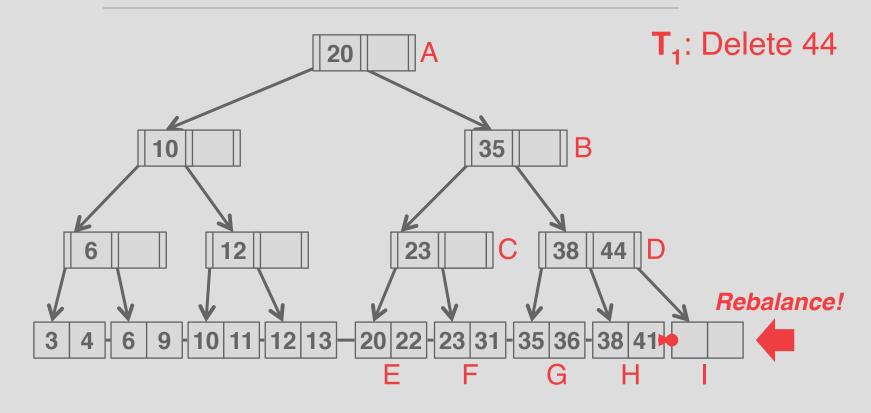


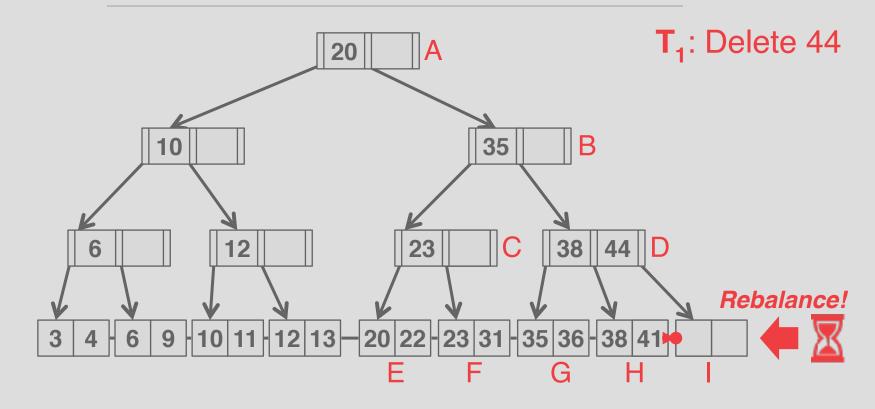


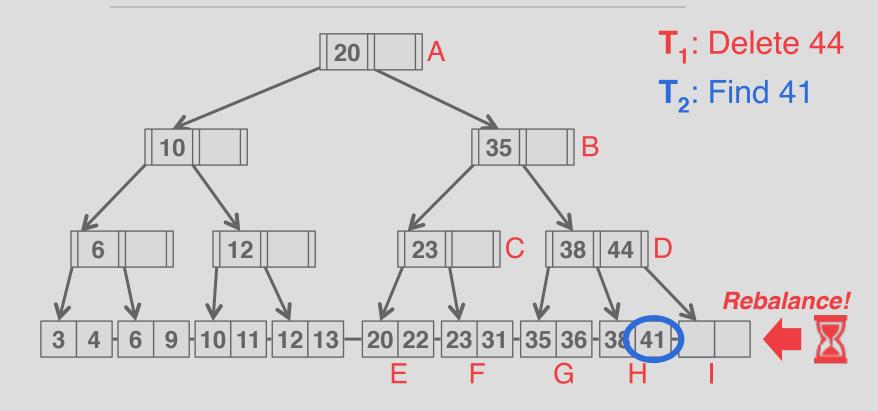


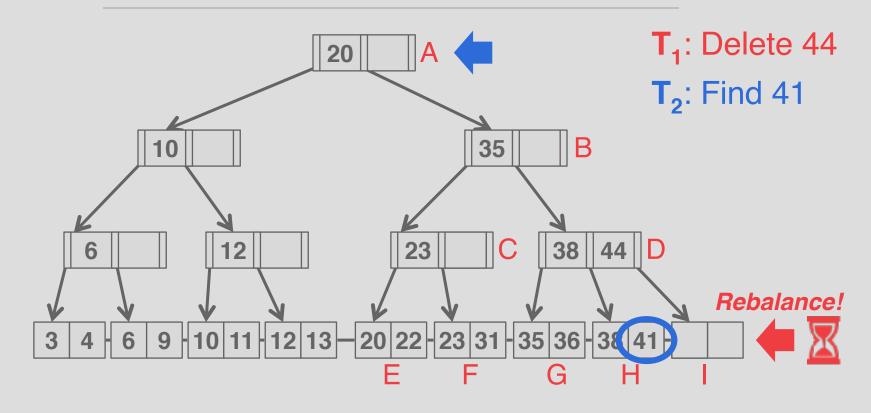


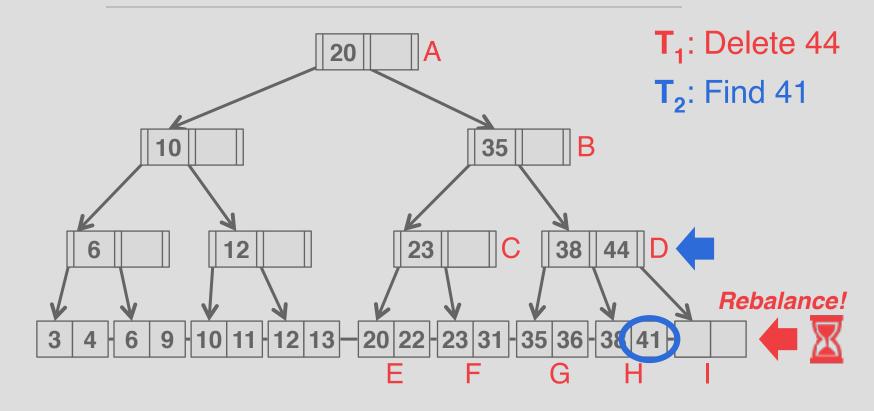


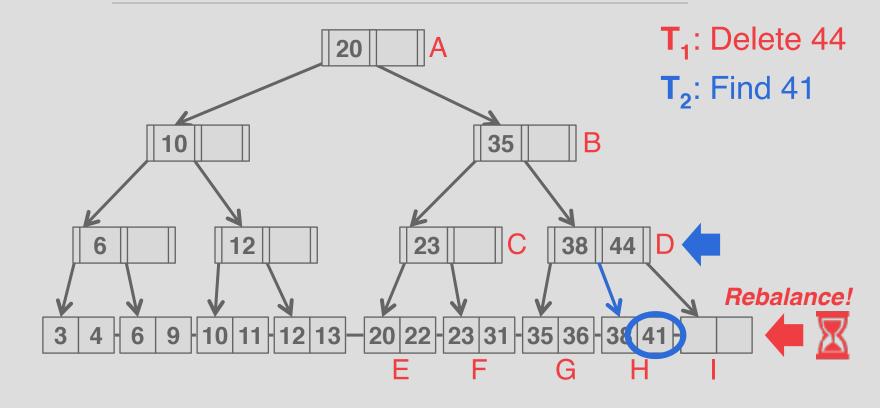


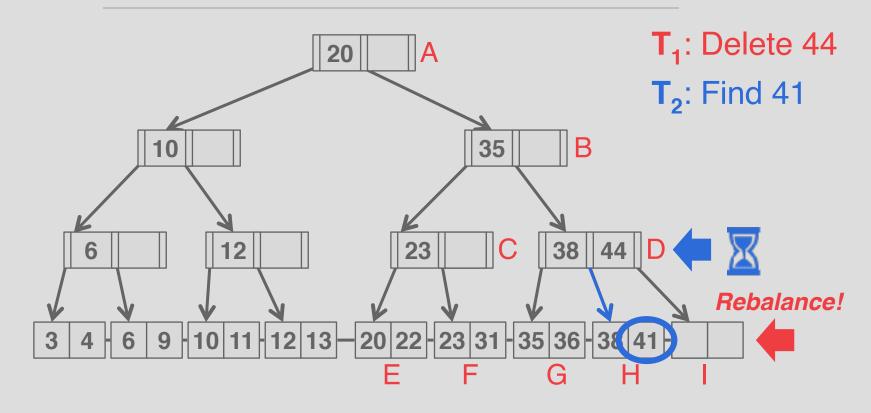


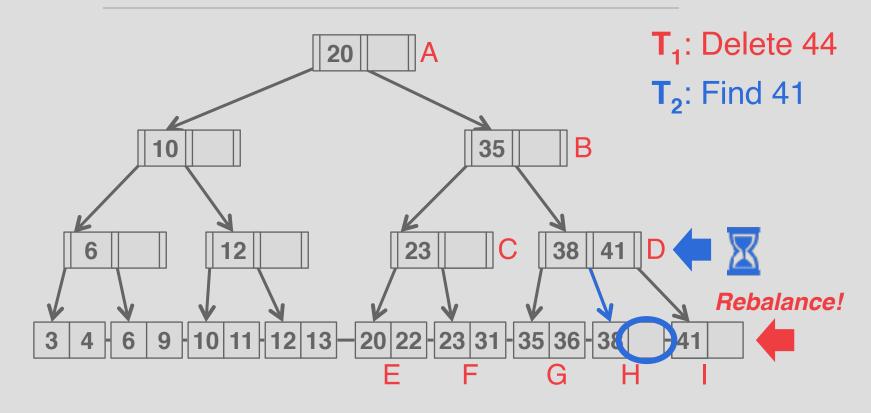


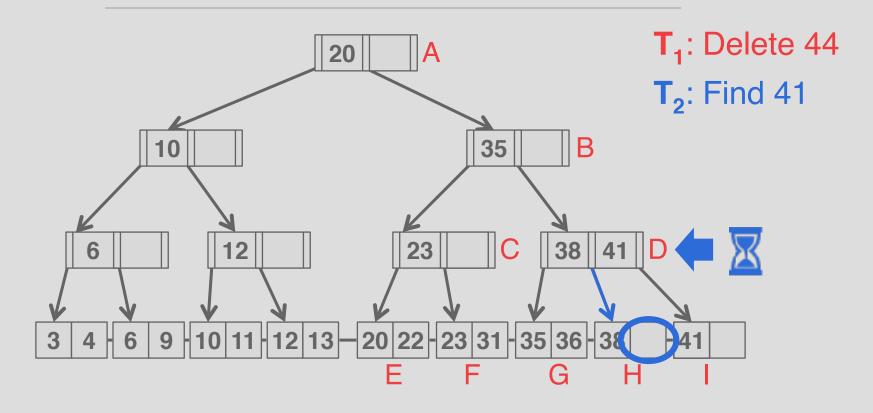


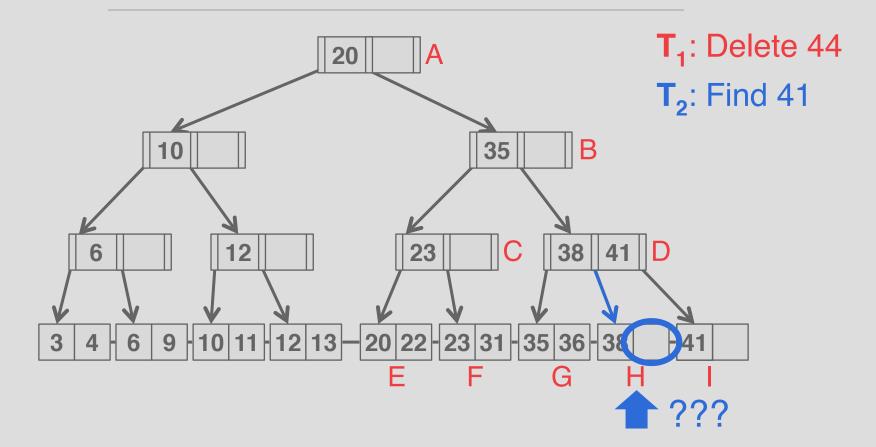












## LATCH CRABBING/COUPLING

Protocol to allow multiple threads to access/modify B+Tree at the same time.

- → Get latch for parent
- → Get latch for child
- → Release latch for parent if "safe"

A <u>safe node</u> is one that will not split or merge when updated.

- → Not full (on insertion)
- → More than half-full (on deletion)

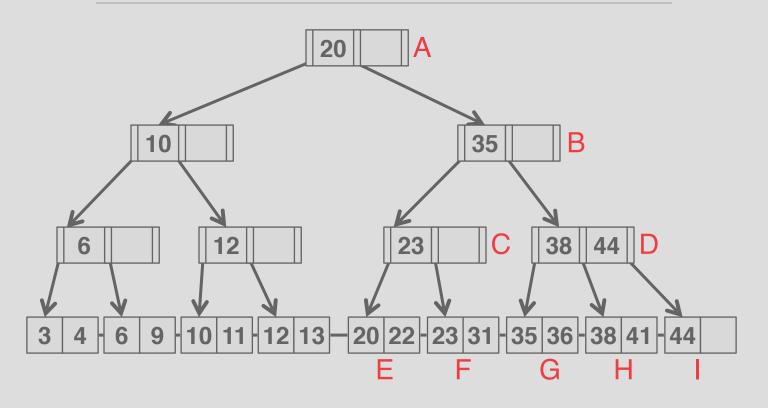
### LATCH CRABBING/COUPLING

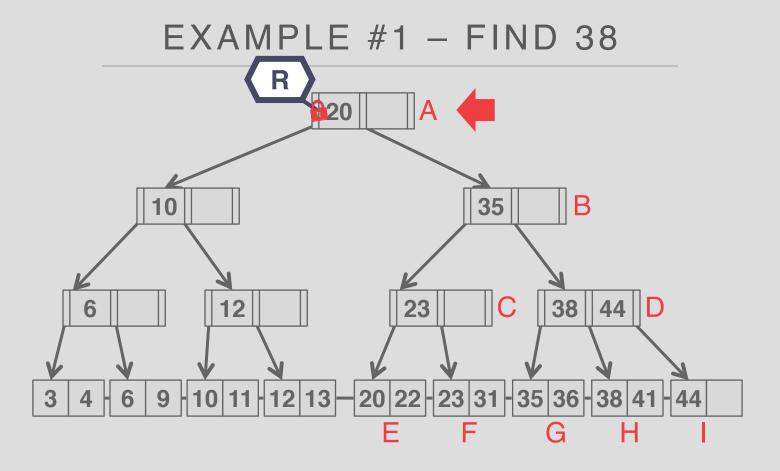
**Find**: Start at root and traverse down the tree:

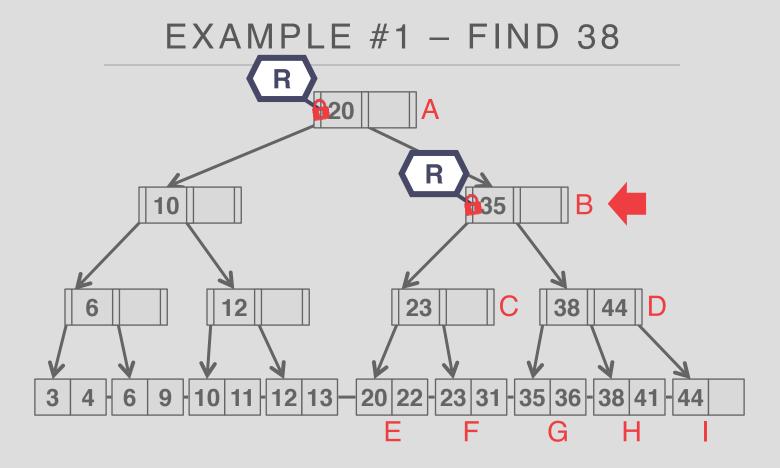
- → Acquire R latch on child,
- → Then unlatch parent.
- → Repeat until we reach the leaf node.

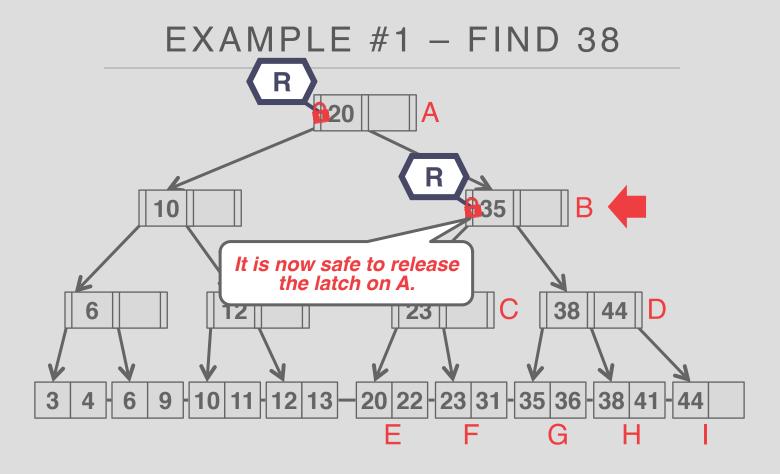
Insert/Delete: Start at root and go down, obtaining W latches as needed. Once child is latched, check if it is safe:

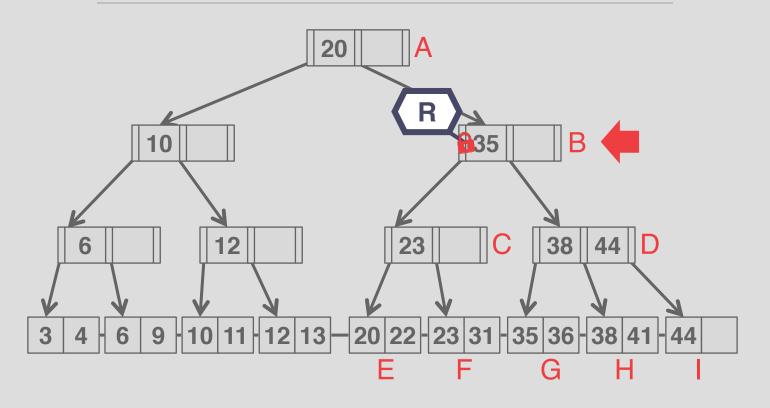
→ If child is safe, release all latches on ancestors

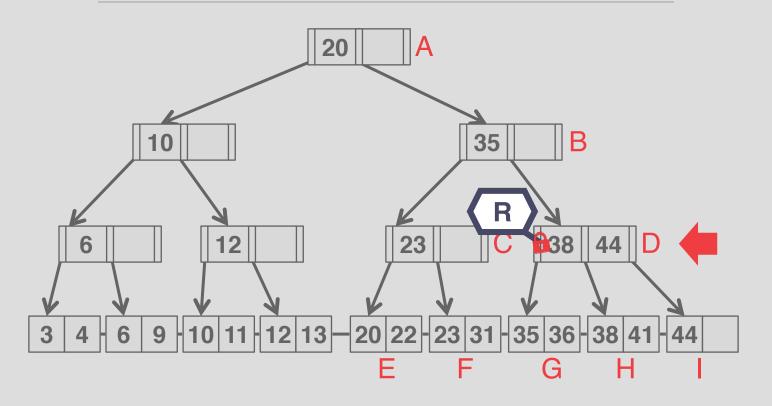


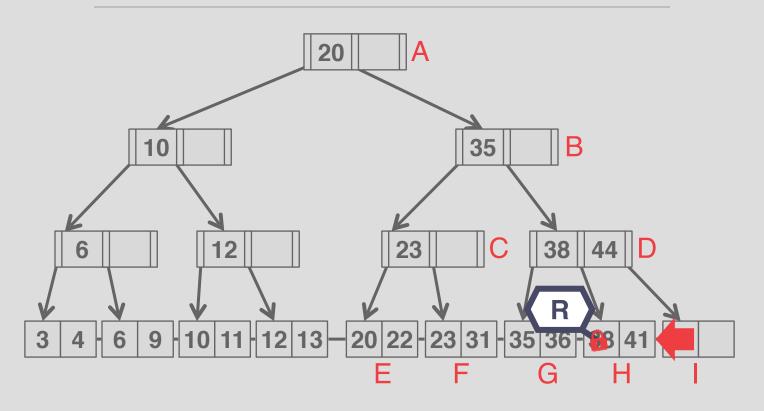


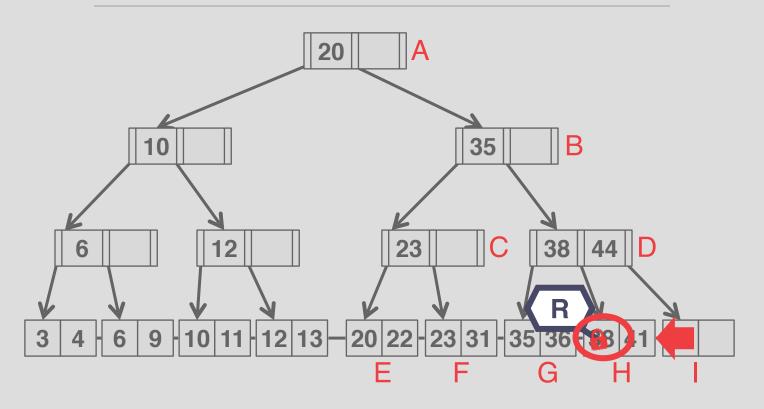


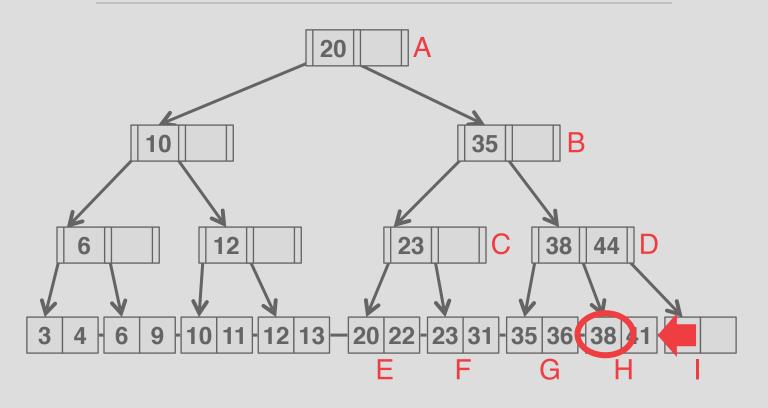


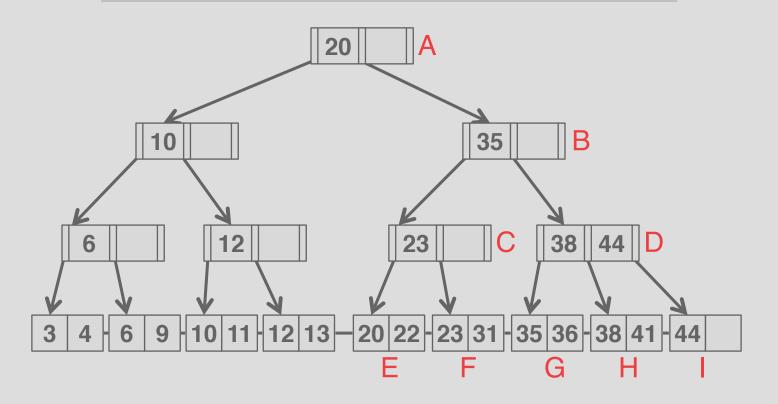


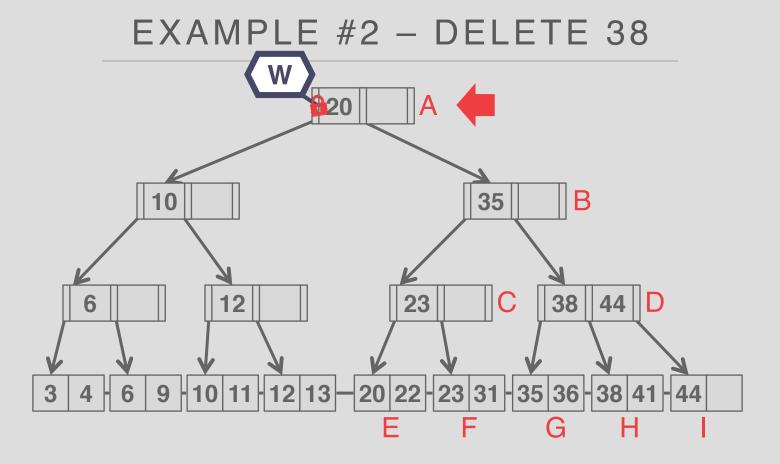


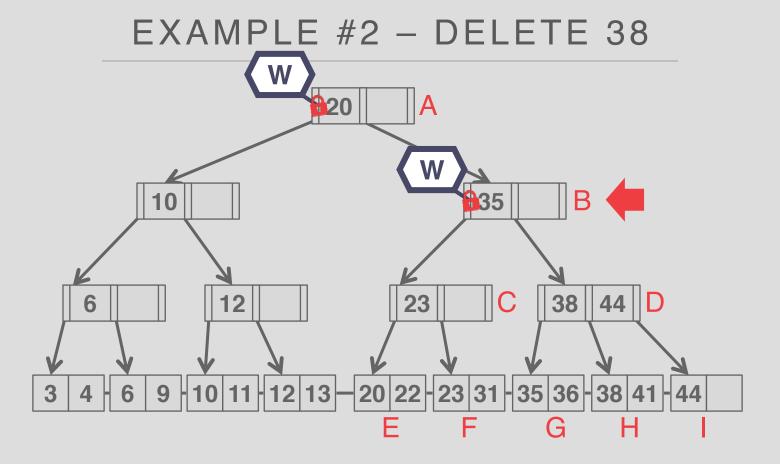


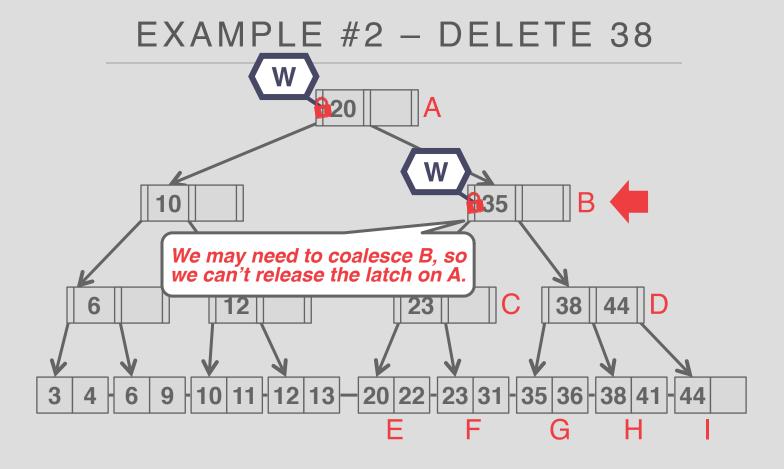


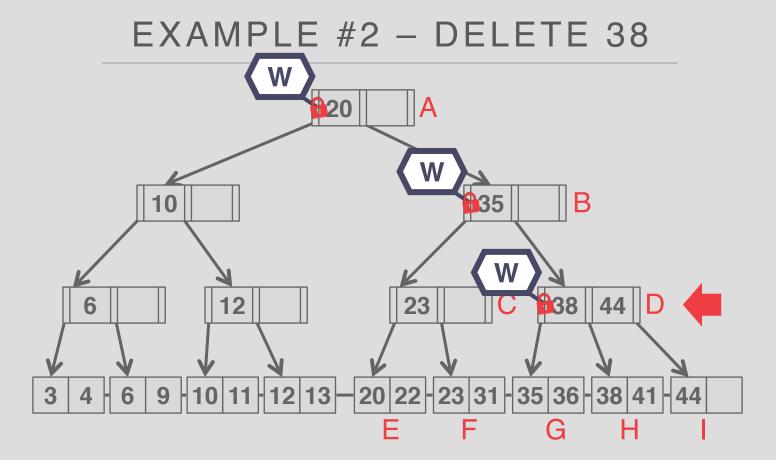


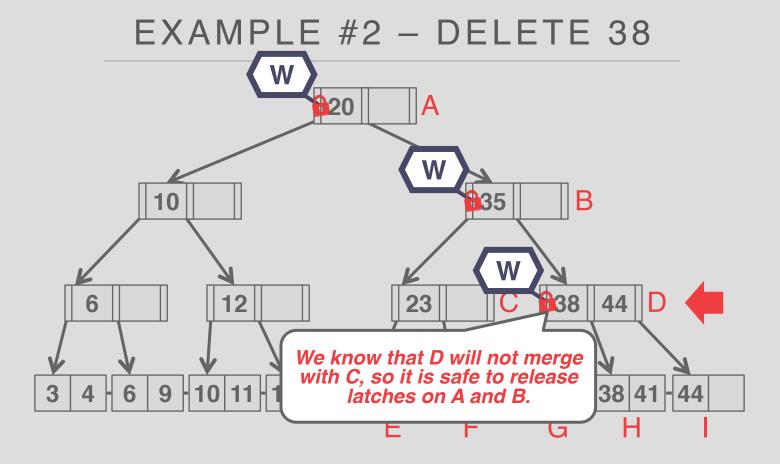


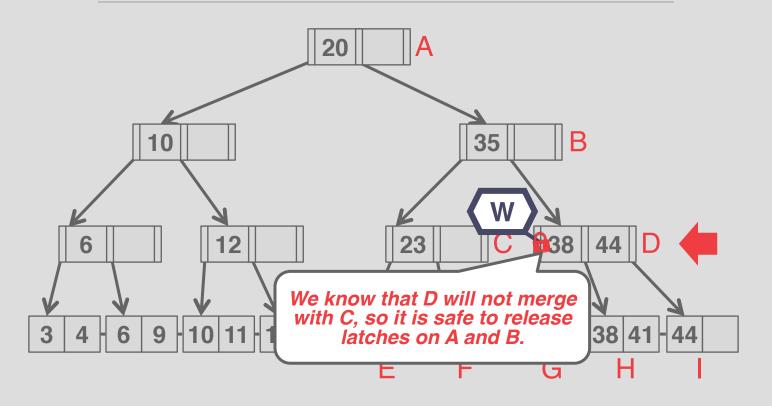


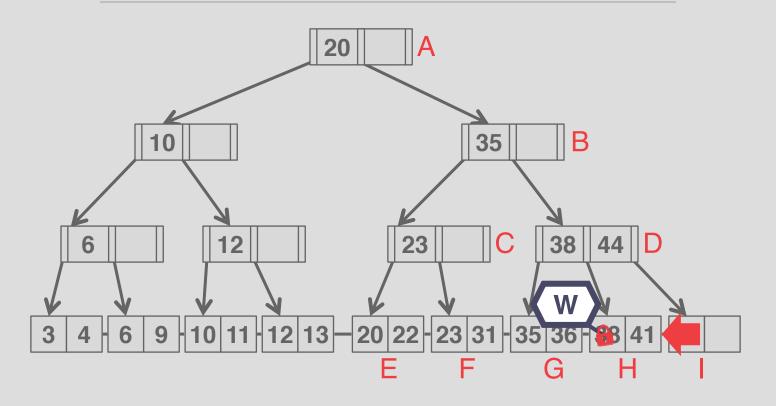


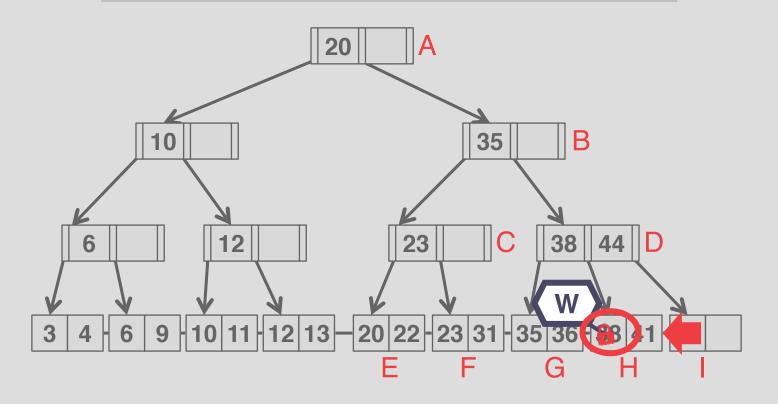


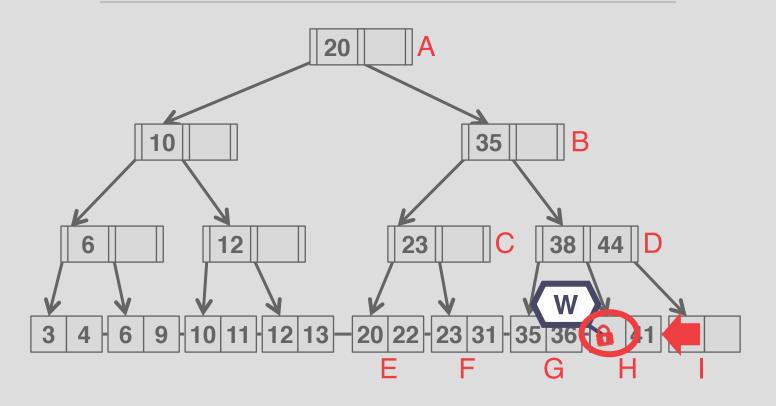


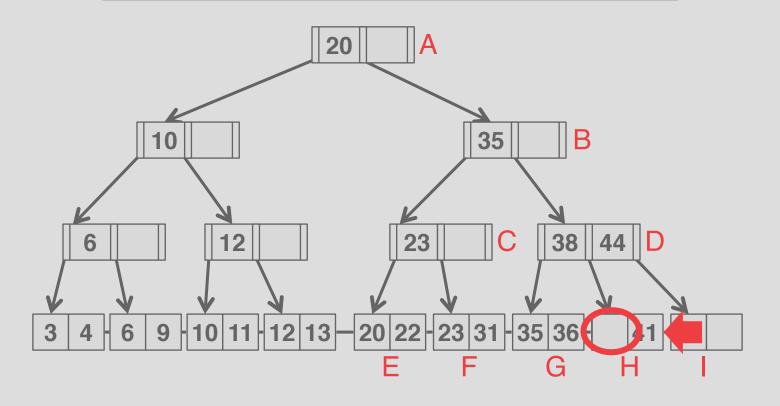


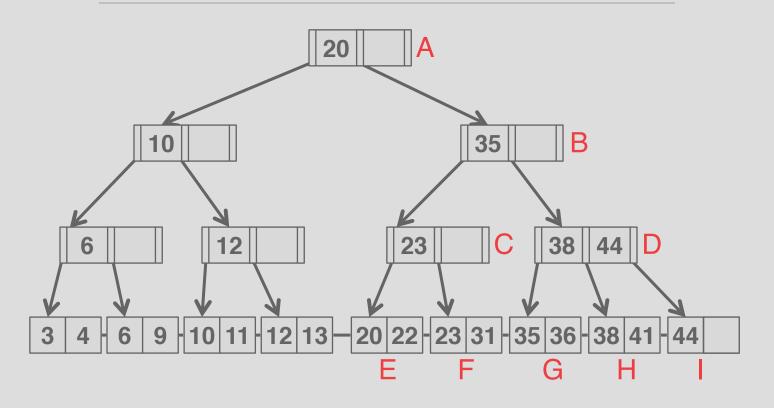


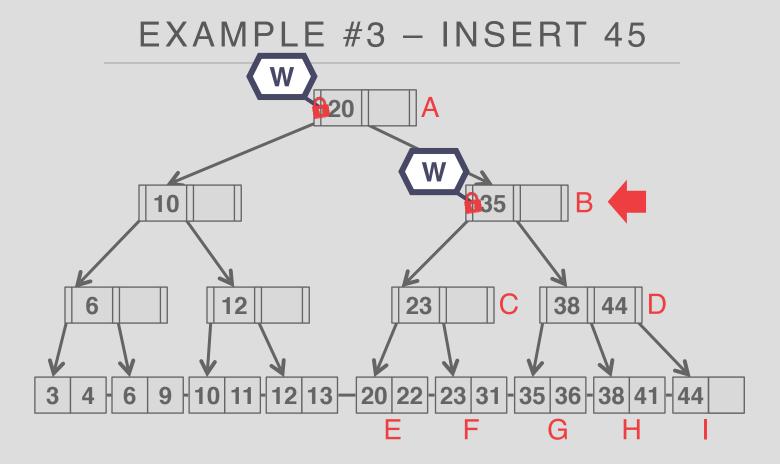


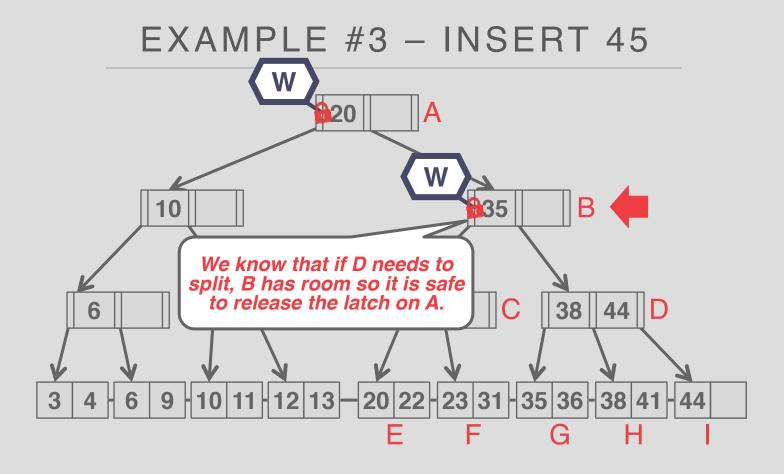


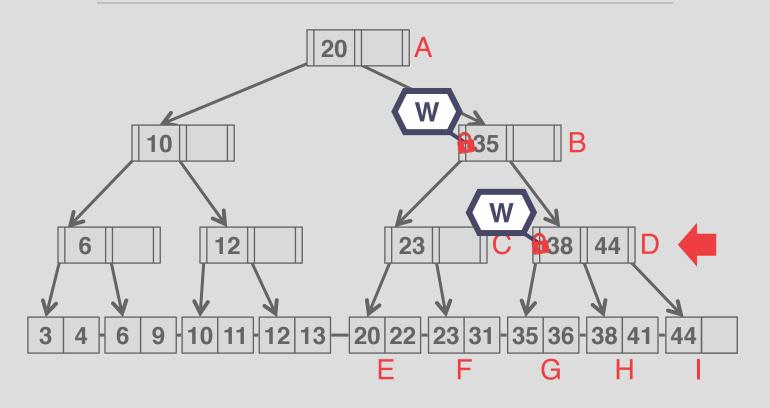


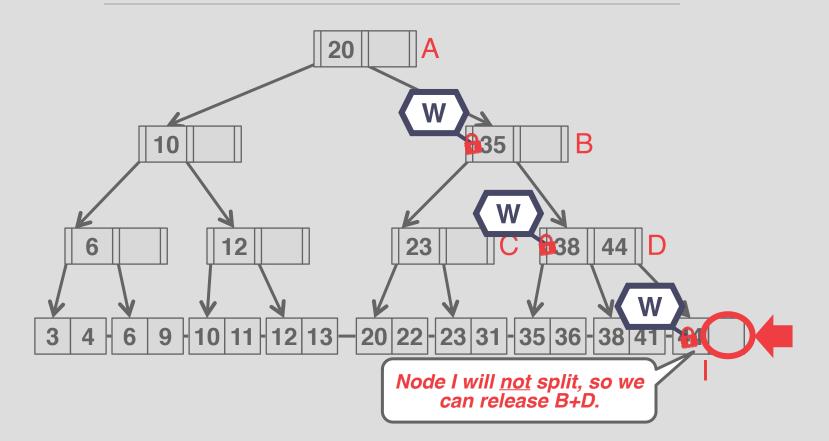


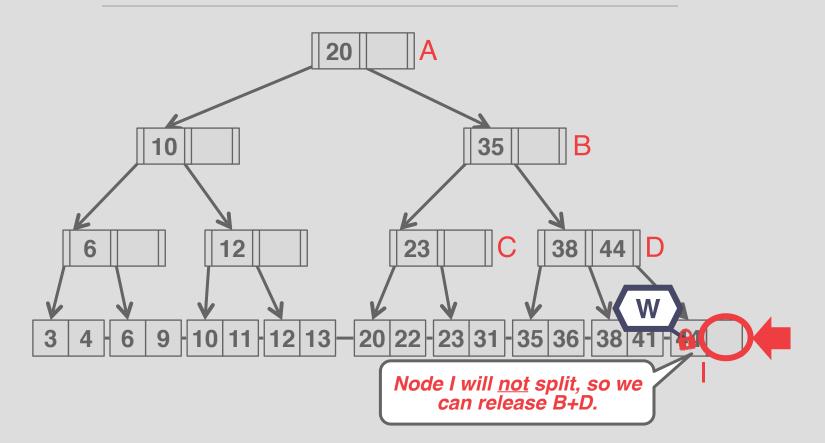


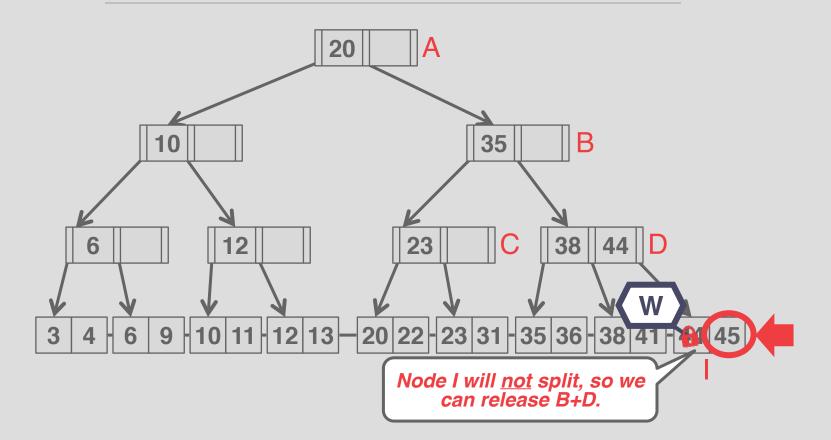


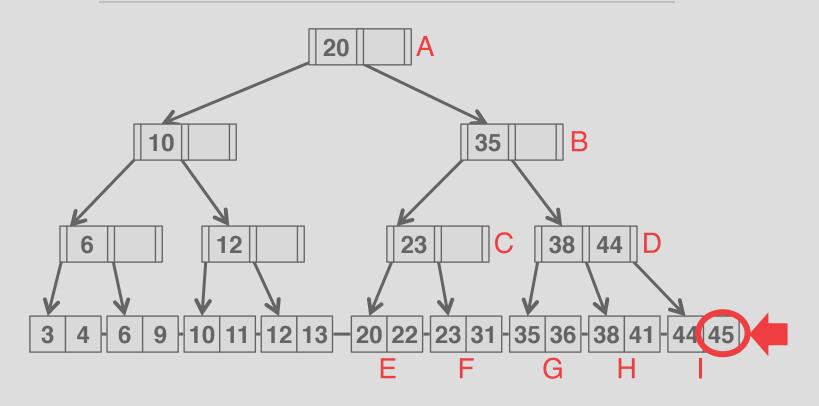


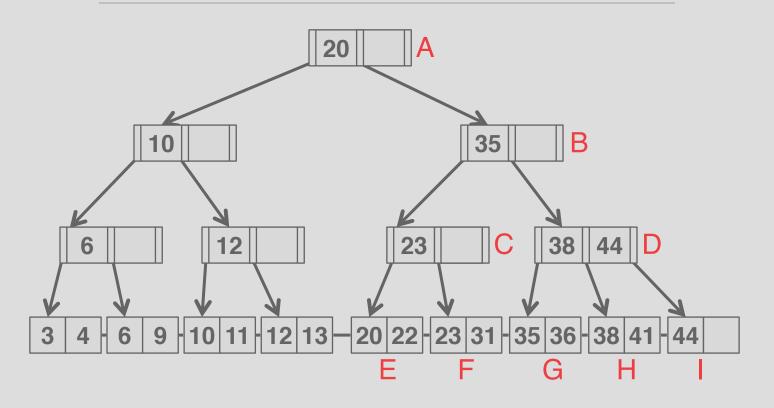


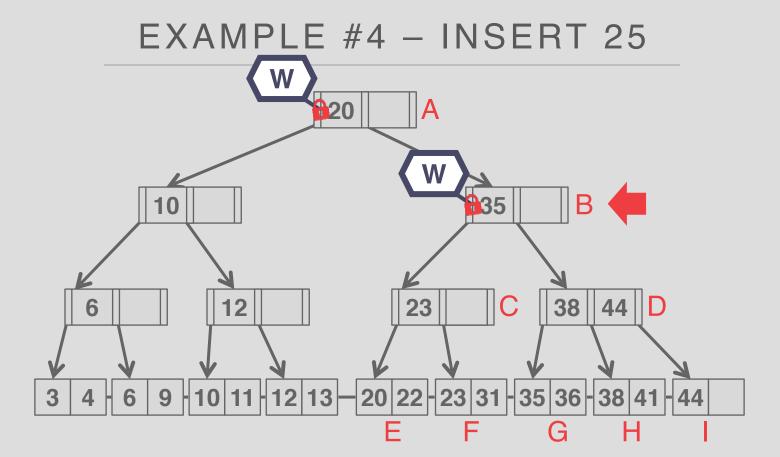


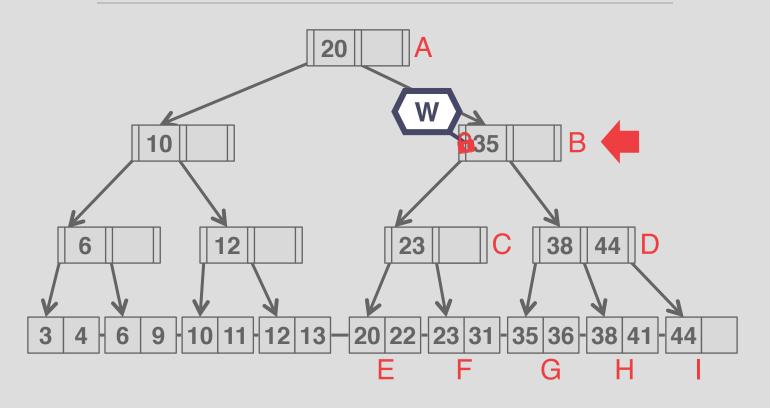


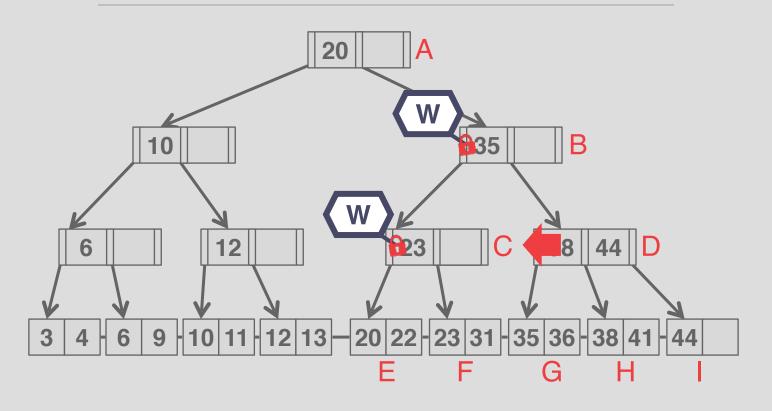


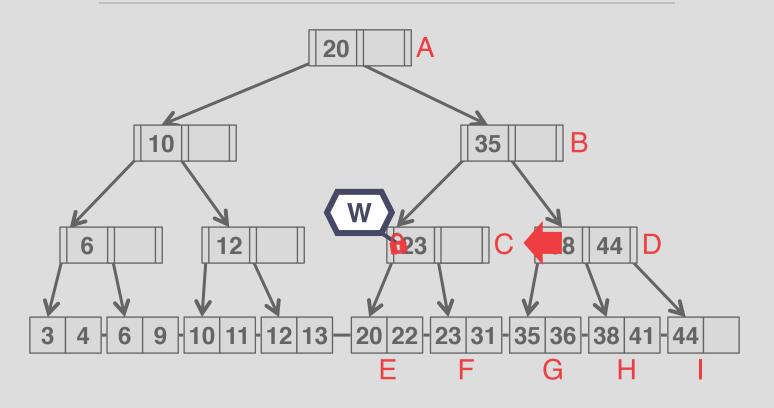


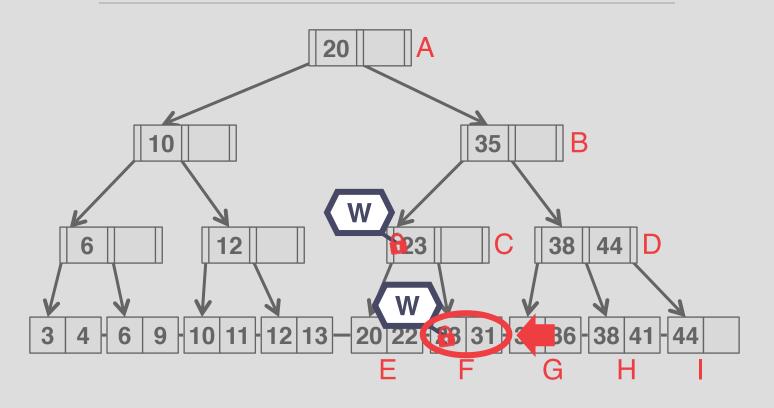


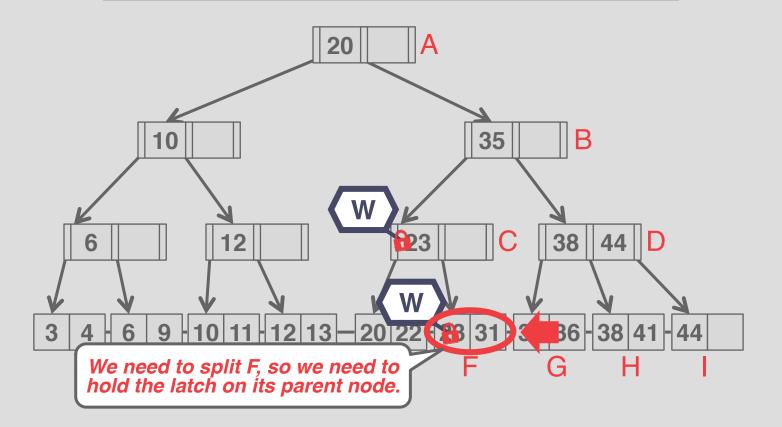


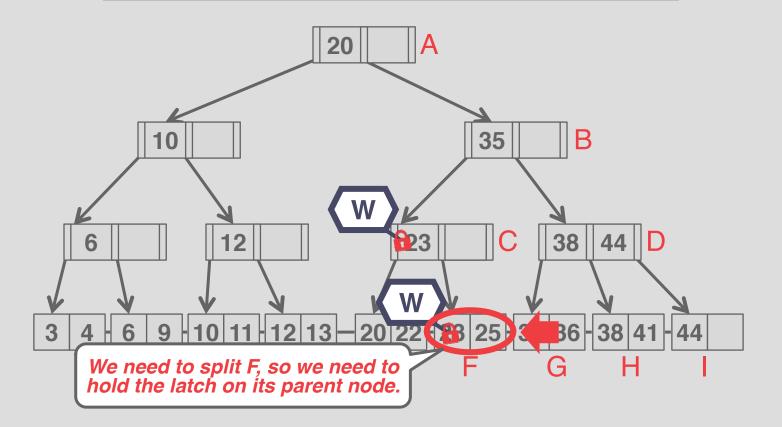


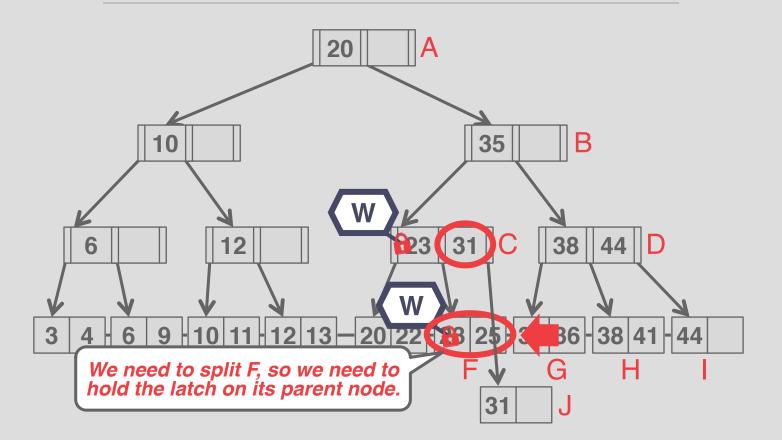










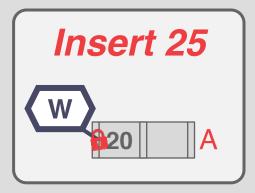


What was the first step that all the update examples did on the B+Tree?

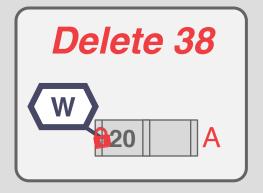
What was the first step that all the update examples did on the B+Tree?

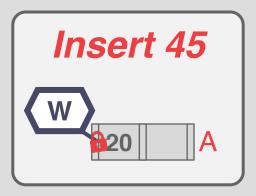


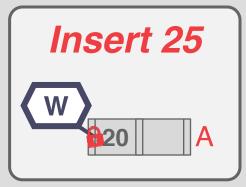




What was the first step that all the update examples did on the B+Tree?







Taking a write latch on the root every time becomes a bottleneck with higher concurrency.

#### BETTER LATCHING ALGORITHM

Most modifications to a B+Tree will not require a split or merge.

Instead of assuming that there will be a split/merge, optimistically traverse the tree using read latches.

If you guess wrong, repeat traversal with the pessimistic algorithm.

All Assessment S. D. CLARKS



#### Consumers of Operations on 2 Trees

P. Danta \* and Ad Schakeliniak and Asserting and the John College College

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the solution greatest how too sargie bridge granters. "Inc., we assume that B transact he and advantageously in a realistic and assumences.

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in any extent wy counting the process of concentral accounts to distinguishing a material and follows. This speed of cognitionals was interfaced up begin and work counting and concentration with account is facility to all electronic [112]. Nechromose material of an event continued to the single some environment. Proceeding, their conformation of an event content to the single some environment. Some partial standards have been some exhaust the facility of the respective, but they entitled to the same exhaust the facility of the respective, but tige entitlement [11, 20] and [21].

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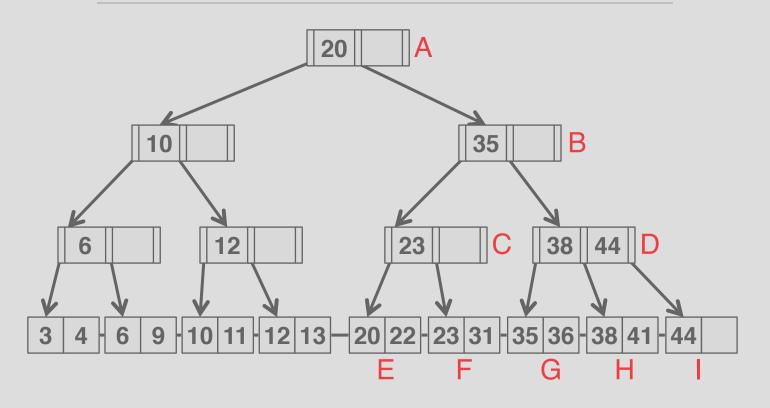
#### BETTER LATCHING ALGORITHM

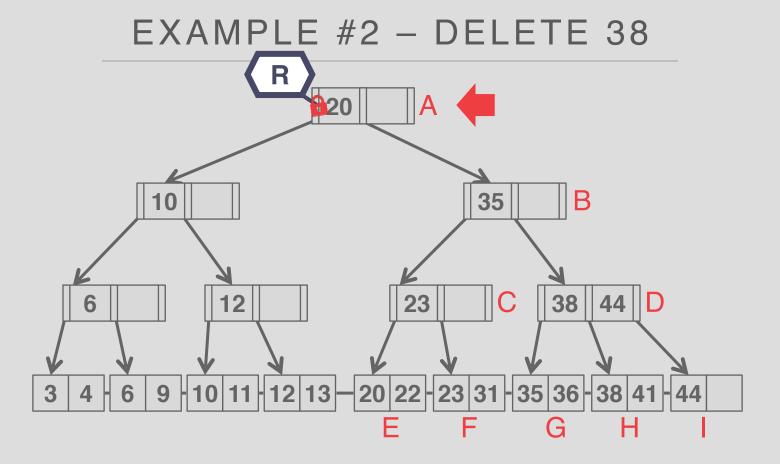
Search: Same as before.

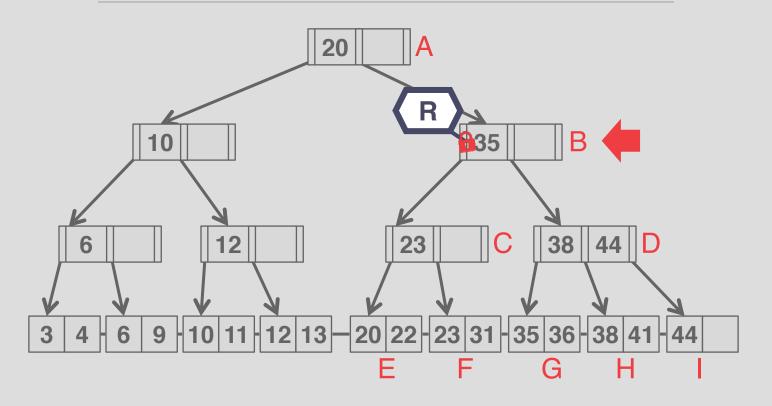
#### Insert/Delete:

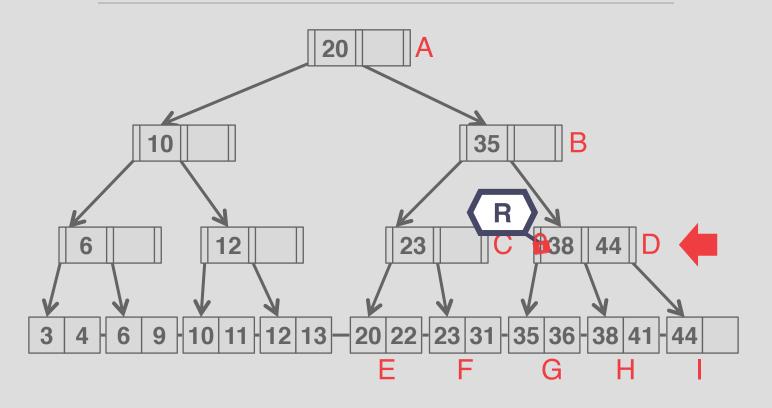
- → Set latches as if for search, get to leaf, and set W latch on leaf.
- → If leaf is not safe, release all latches, and restart thread using previous insert/delete protocol with write latches.

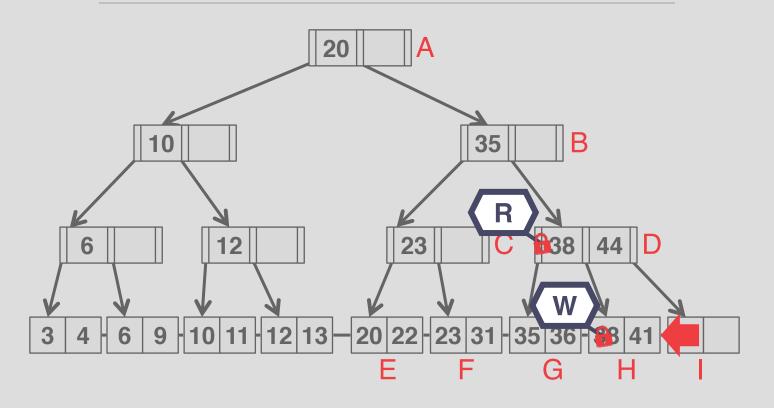
This approach optimistically assumes that only leaf node will be modified; if not, R latches set on the first pass to leaf are wasteful.

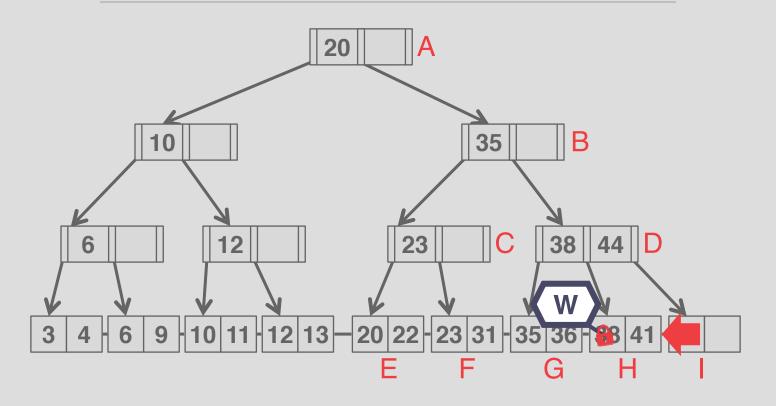


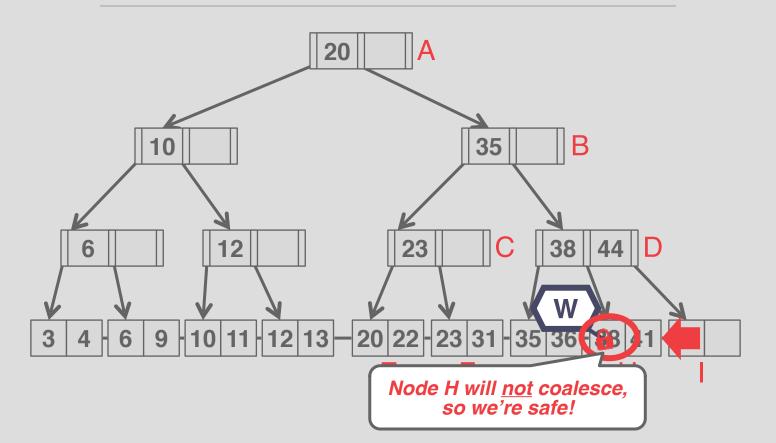


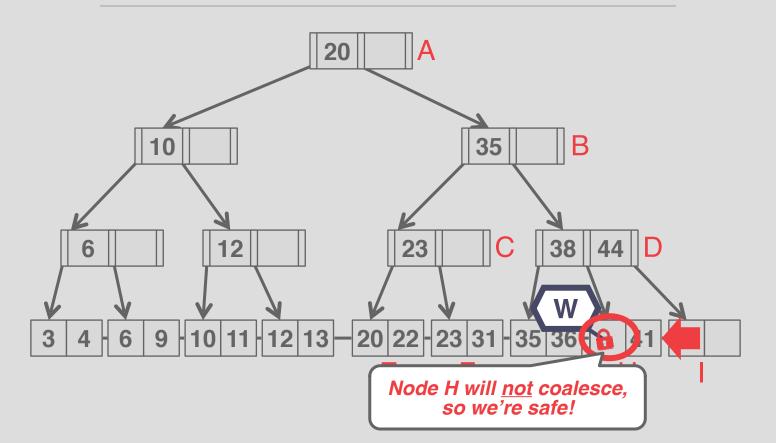


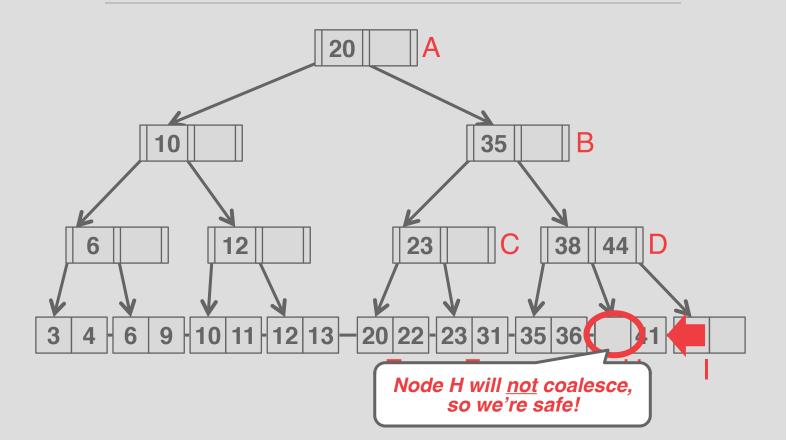


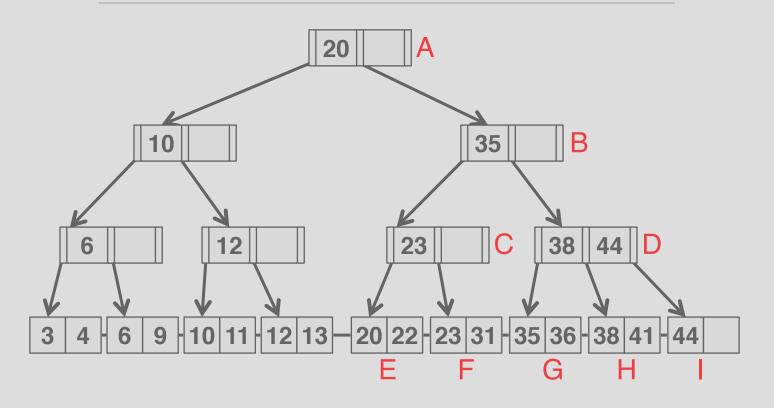


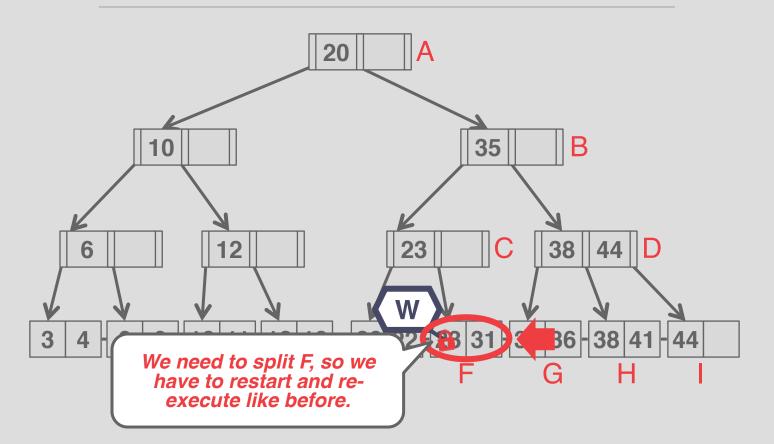








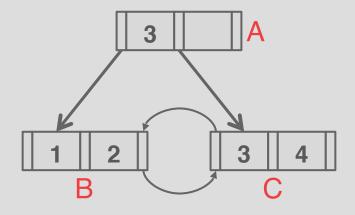


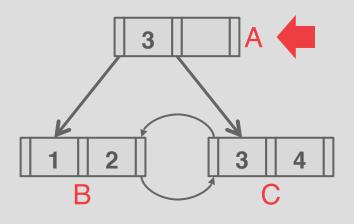


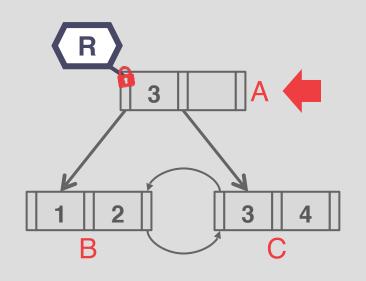
The threads in all the examples so far have acquired latches in a "top-down" manner.

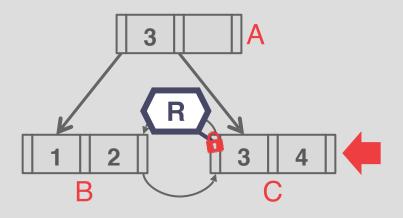
- → A thread can only acquire a latch from a node that is below its current node.
- → If the desired latch is unavailable, the thread must wait until it becomes available.

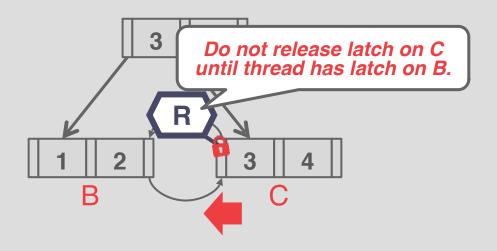
But what if threads want to move from one leaf node to another leaf node?

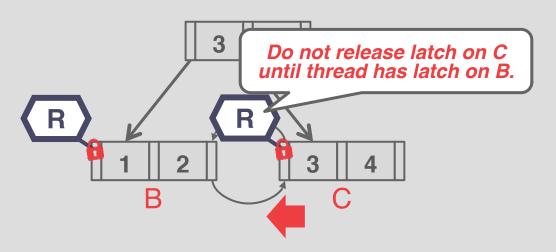


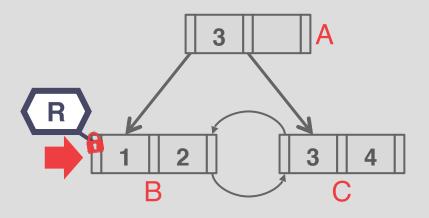


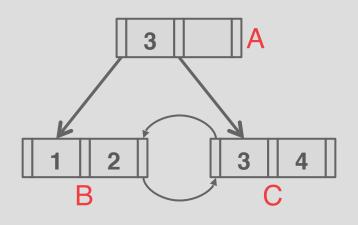






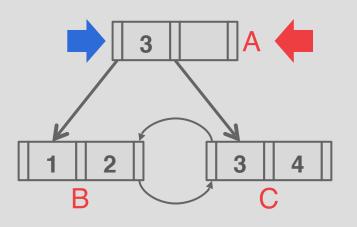






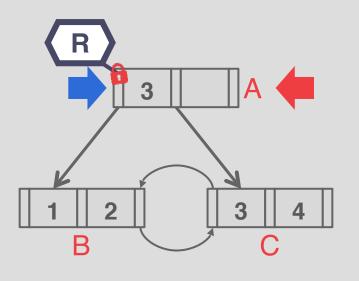
 $T_1$ : Find Keys < 4

 $T_2$ : Find Keys > 1



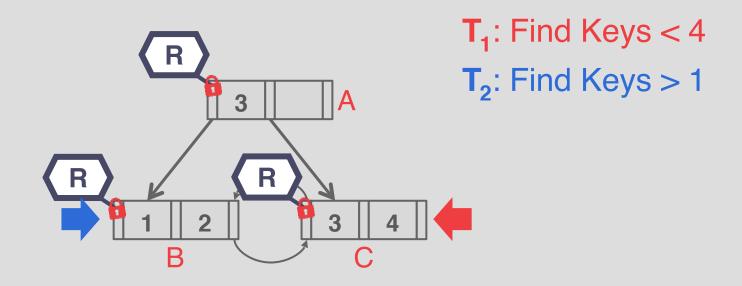
 $T_1$ : Find Keys < 4

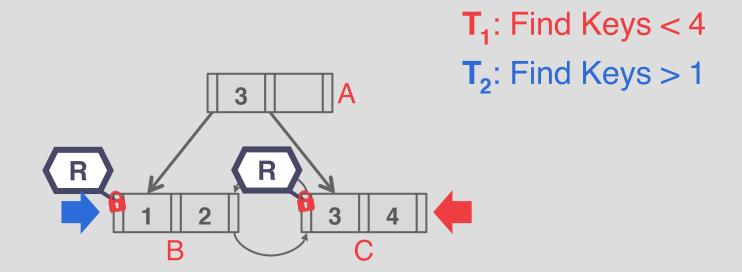
T<sub>2</sub>: Find Keys > 1

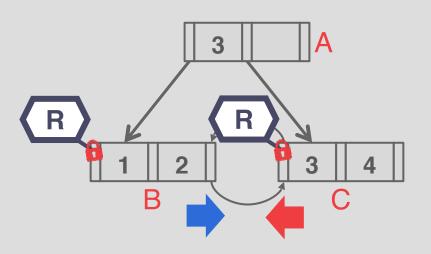


 $T_1$ : Find Keys < 4

T<sub>2</sub>: Find Keys > 1







 $T_1$ : Find Keys < 4

 $T_2$ : Find Keys > 1

 $T_1$ : Find Keys < 4 **、:** Find Keys > 1 Both  $T_1$  and  $T_2$  now hold Both  $T_1$  and  $T_2$  now hold this read latch. this read latch. B

 $T_1$ : Find Keys < 4

Both  $T_1$  and  $T_2$  now hold this read latch.

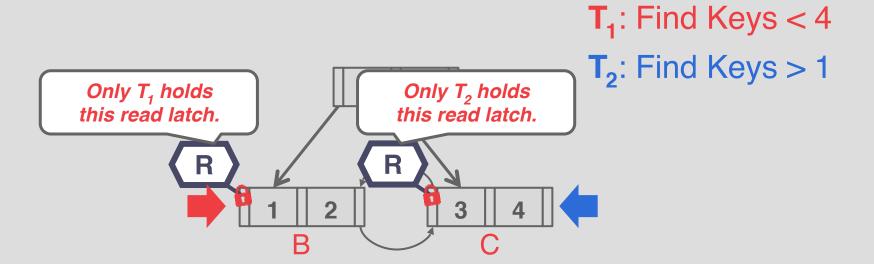
Both  $T_1$  and  $T_2$  now hold this read latch.

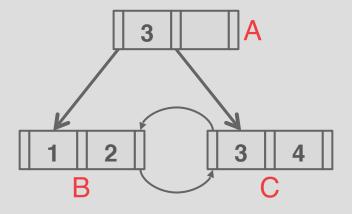
R

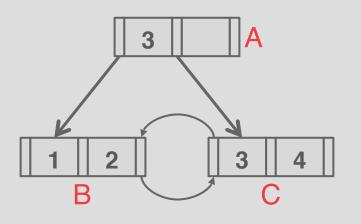
R

R

C

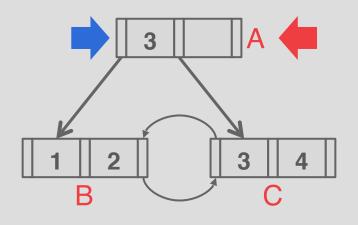






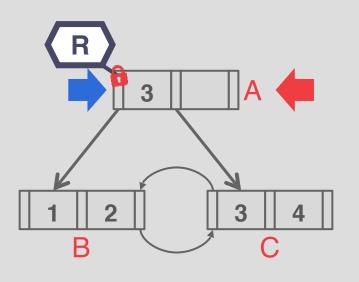
T<sub>1</sub>: Delete 4

 $T_2$ : Find Keys > 1



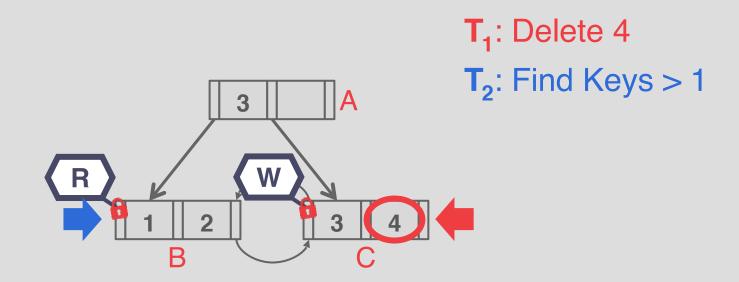
T<sub>1</sub>: Delete 4

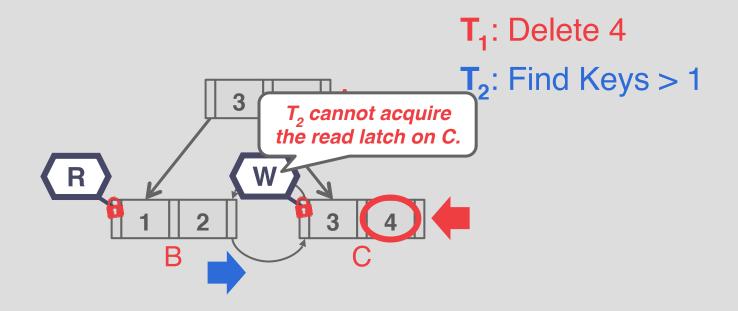
 $T_2$ : Find Keys > 1

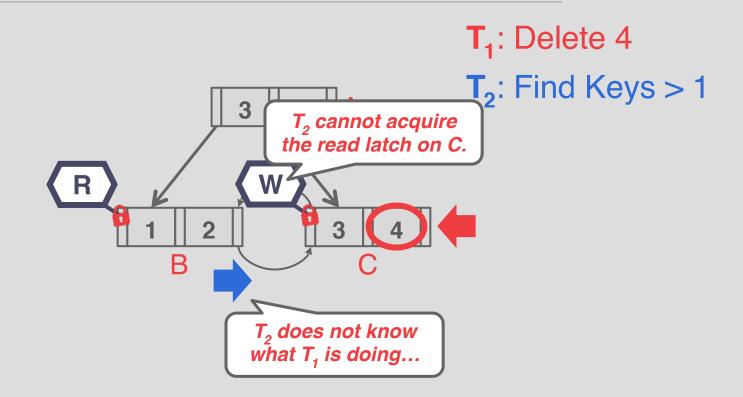


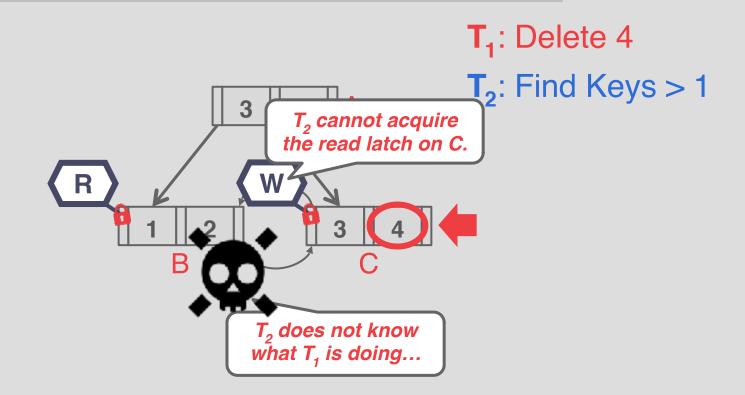
T<sub>1</sub>: Delete 4

T<sub>2</sub>: Find Keys > 1









#### LEAF NODE SCANS

Latches do <u>not</u> support deadlock detection or avoidance. The only way we can deal with this problem is through coding discipline.

The leaf node sibling latch acquisition protocol must support a "no-wait" mode.

The DBMS's data structures must cope with failed latch acquisitions.

#### CONCLUSION

Making a data structure thread-safe is notoriously difficult in practice.

We focused on B+Trees, but the same highlevel techniques are applicable to other data structures.

## **NEXT CLASS**

We will finally discuss how to execute queries...