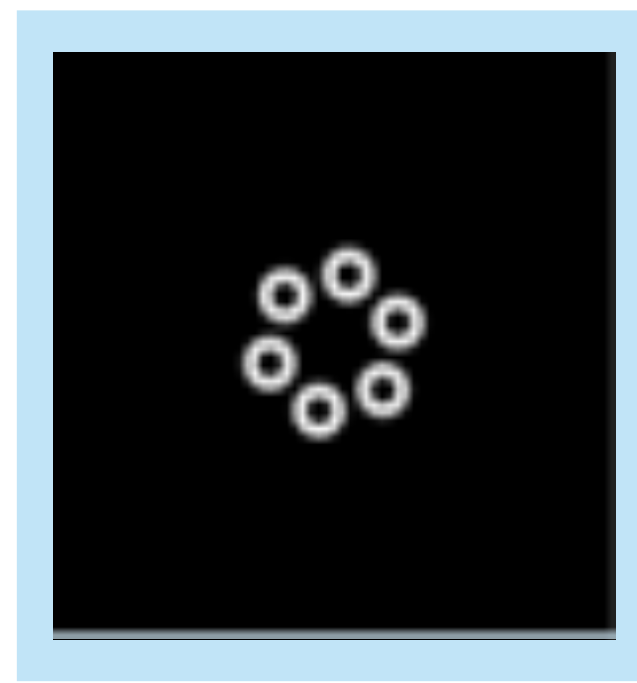
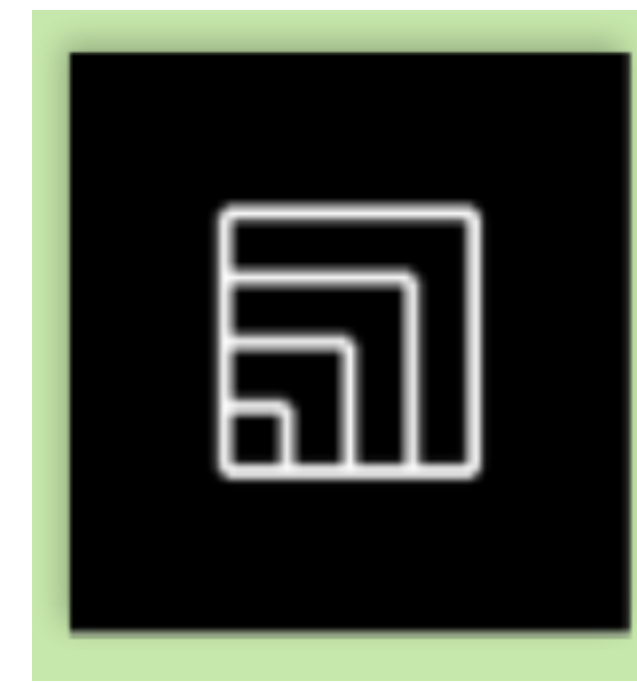


f19 7 (f11 f17)



(f19 6 (f13 ;f7))



(for i 4 (f6 i))

f11=(move 1 2pi)

f12=(/ 2pi)

f19=(λ(x) (f3 (f12 x) x))

rotational symmetry



f17=(f1 ε ε)

semicircle



f10=(λ(x y z) (for y (λ(u v) (move (* z u) x v))))

f3=(λ(x y z) (for y (λ(u v) (get/set z (move 0 x v)))))

f1=(f0 ∞)

f2=(f1 (/ ε 2) ε)

f18=(λ(x) (f1 ε (*εx)))

f4=(λ(x) (f1 (- 2pi ε) (*ε x)))

f16=(for 3 (λ(x y) (f2 (move 0 f5 y))))

f0=(λ(x y z) (for x (λ(u v) (move z y v))))

f6=(f0 4 f5)

square



f8=(λ(x) (for 7 (λ(y z) (f0 7 εx z))))

f9=(λ(x) (f8 (*ε x)))

f7=(λ(x) (for ∞ (λ (y z) (move x ε (move ε ε z)))))

circle



f15=(λ(x) (f13 (f7 εx)))

f5=(/ 2pi 4)

f13=(pen-up (λ(x) (move 1 0 x)))

f14=λ(x) (f13 (move 1 f5 x))