# DreamCoder: Bootstrapping Domain-Specific Languages for Neurally-Guided Bayesian Program Learning

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# Wake/Sleep DSL Induction

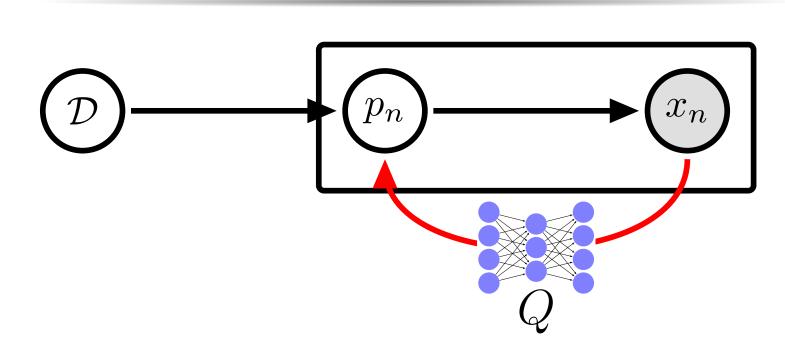
Domain Specific Language (DSL): A finely-tuned program representation, specialized to a domain of programming tasks. Prior work in program learning largely uses hand-engineered DSLs.

Approach: DreamCoder algorithm, which bootstraps a learned DSL while jointly training a neural net to search for programs in the learned DSL. Given a few hundred programming tasks, alternatingly:

- Wake: synthesize programs
- Sleep-R: train neural net (Recognition model)
- Sleep-G: improve DSL (Generative model)

representation: Program conditionals,  $\approx$ Lisp; variables,  $\lambda$  abstraction

## Bayesian framing



Observe N tasks, written  $\{x_n\}_{n=1}^N$ , each a program synthesis problem. Solve task  $x_n$  with latent program  $p_n$ **Likelihood model**  $\mathbb{P}[x_n|p_n]$  scores program  $p_n$  on task  $x_n$ 

Latent  $\mathbf{DSL}$   $\mathcal{D}$  acts as generative model over programs:  $\mathbb{P}[x|\mathcal{D}]$ 

$$\underbrace{p_n^* = \underset{p_n}{\operatorname{arg\,max}} \mathbb{P}[x_n|p_n]\mathbb{P}[p_n|\mathcal{D}^*]}_{\mathbf{Wake}}$$

$$\mathcal{D}^* = \underset{\mathcal{D}}{\operatorname{arg\,max}} \mathbb{P}[\mathcal{D}] \prod_{n} \sum_{p_n} \mathbb{P}[x_n|p_n]\mathbb{P}[p_n|\mathcal{D}]$$
Sleep-G

# Neural recognition model

Neural network Q(p|x) predicts distribution over programs conditioned on tasks. Simple Q: just predicts probabilities of DSL productions. Goal: learn to invert generative model

$$\underbrace{\min_{Q} \operatorname{KL}\left(\mathbb{P}[p|x,\mathcal{D}]||Q(p|x)\right)}_{\mathbf{Sleep-R}}$$

Train on two sources of data:

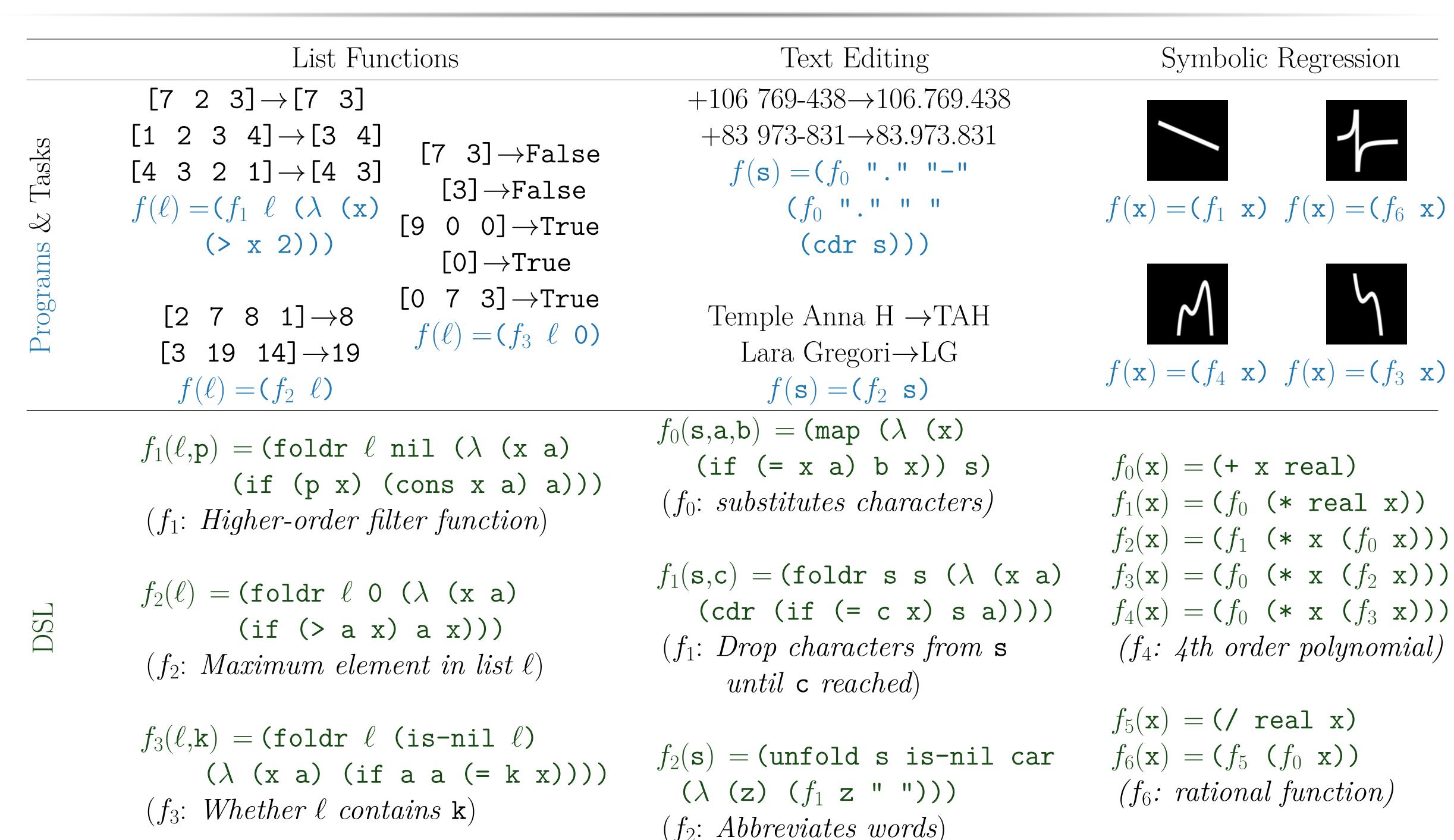
 Samples ("Dreams") from **DSL**: Unlimited data, but only high-quality if generative model  $\mathcal{D}$  is good. Like Helmholtz Machine's recognition model training. Loss:

 $\mathbb{E}_{(p,x)\sim\mathcal{D}}\left[\log Q(p|x)\right]$ 

• Self-Supervised:  $(x_n, p_n)$  pairs discovered during waking. Loss:

$$\frac{\mathbb{P}\left[x_n, p_n | \mathcal{D}\right]}{\sum_{(x_n, p'_n)} \mathbb{P}\left[x_n, p_n | \mathcal{D}\right]} \log Q(p_n | x_n)$$

## Model outputs for three different task domains



Top: Tasks from three domains we apply our algorithm to, each followed by the programs DreamCoder discovers for them. Bottom: Several examples from learned DSL. Notice that learned DSL primitives can call each other, and that DreamCoder rediscovers higher-order functions like filter ( $f_1$  under List Functions)

# Fragment Grammars: Inducing a DSL

Fragment grammars: introduced in computational linguistics (O'Donnell 2015)

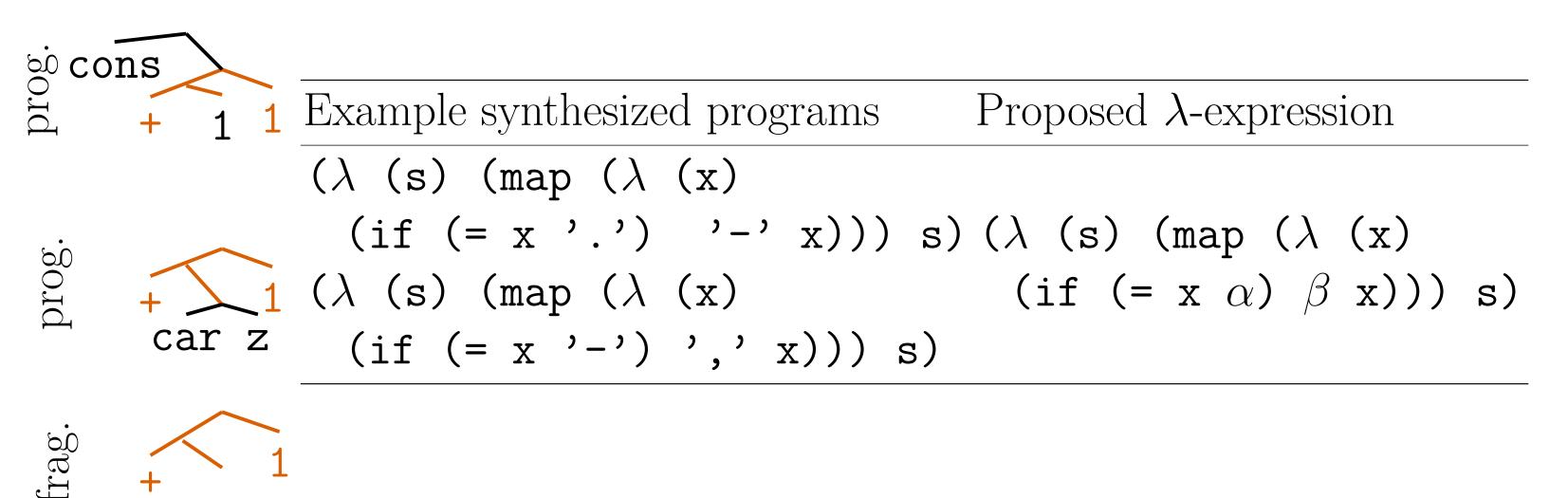
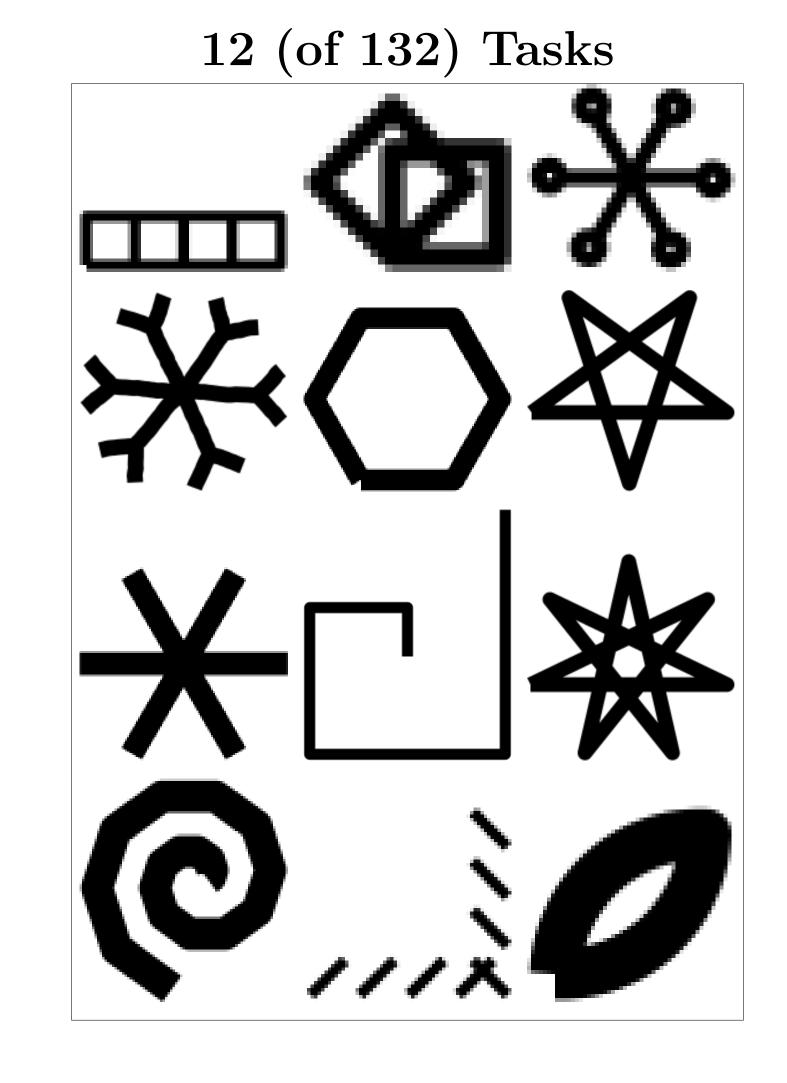
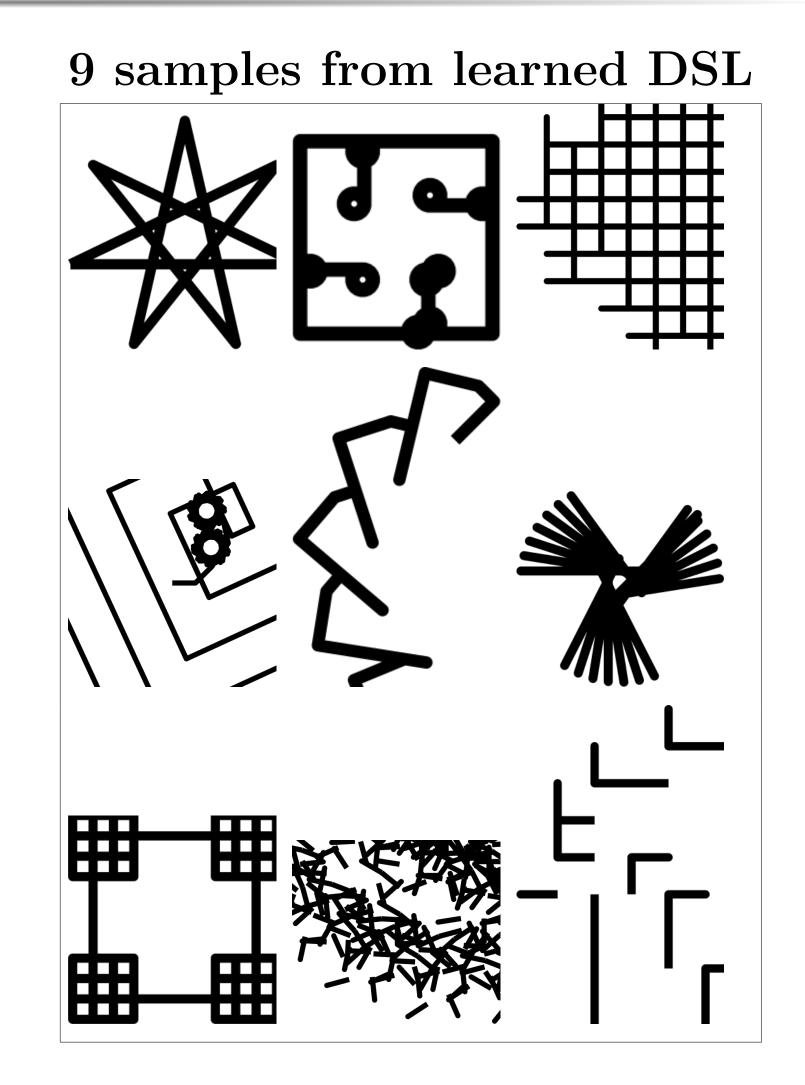


Figure 1: Left: syntax trees of two programs sharing common structure, highlighted in orange, from which we extract a fragment and add it to the DSL (bottom). Right: actual programs, from which we extract fragments that perform character substitutions.

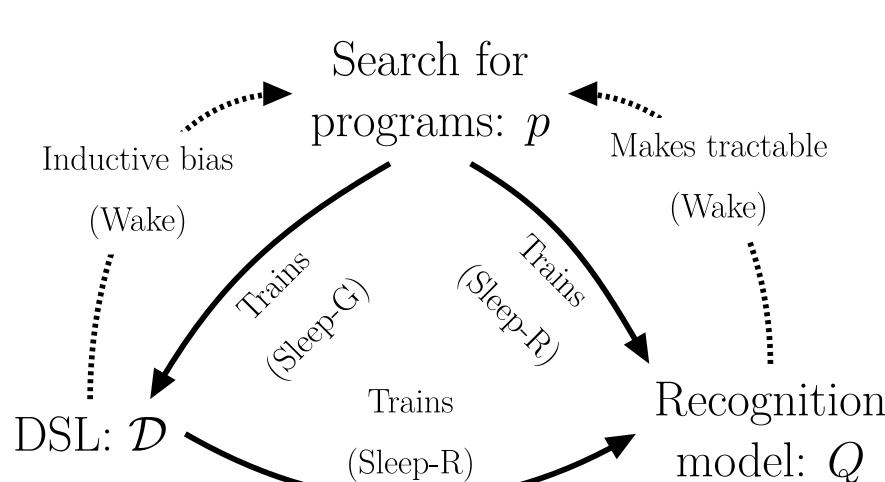
## Generative models of images: Turtle/LOGO Graphics





Left: Agent controls a 'pen' – tasked with drawing pictures. Right: During Sleep-R, agent 'dreams' by sampling programs from learned DSL and rendering them.

# Why this works: Bootstrapping



#### Learning from Scratch

Start w/ McCarthy 1959 Lisp: recursion, conditionals, lists. Train on 22 programming exercises. After 93 hours on 64 CPUs, rediscovers 9 functional programming staples: map, fold, zip, unfold, index, length, range, incr, decr.

#### Generative models of text

Learn probabilistic program: stochastic regex

Tasks:		
cut	F	Moss Side
control	$\operatorname{CL}$	Burnage
control	F	City Centre
cut	PCFL	Brooklands
Learned generative models:		
\1*\1	((\u\u)*) F	(  \u\w*)*
Samples from synthesized generative mode		
ya	DQDF	Vr DR
glrwfden	c F	BeF lKQ
mgs	F	W
piljnl	KI	kqBfZ 0
kj	F	ON
zci	$\operatorname{GL}$	Bttc

sxpm