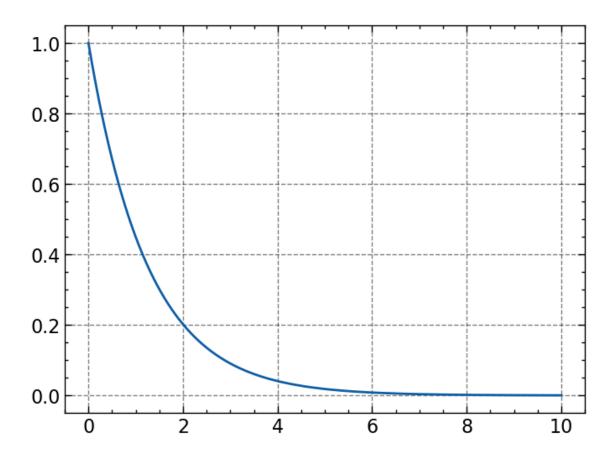
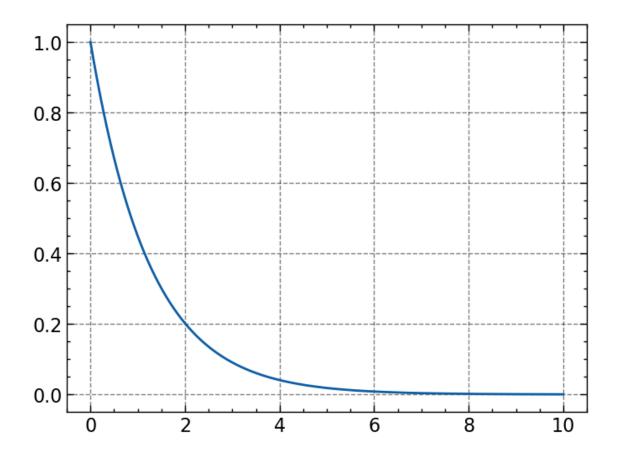
plot entanglement bell states

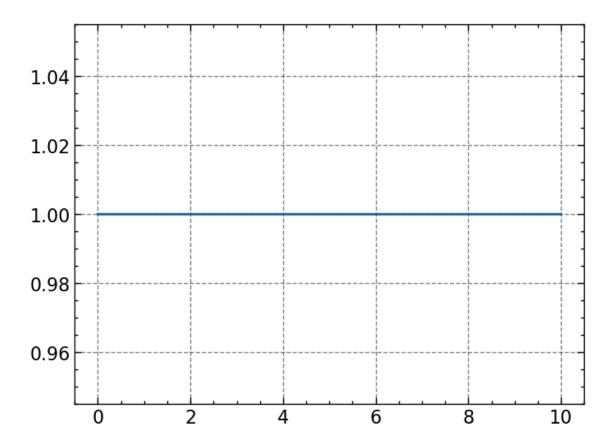
November 12, 2024

```
[1]: # import qutip as qt
     import numpy as np
     import matplotlib.pyplot as plt
     import qutip as qt
     import scienceplots
     plt.style.use(['science', 'grid', 'nature', 'notebook'])
[2]: def load_data(path2data):
         with open(path2data, 'r') as f:
             data = f.read()
             # cargo time step
             index_time_step = data.find('time step:')
             index_time_step_end = data.find('\n', index_time_step)
             h = float(data[index_time_step+len('time_step:'):index_time_step_end])
             # cargo time limits:
             index_time_limits = data.find('time limits:')
             index_time_limits_end = data.find('\n', index_time_limits)
             time_limits = data[index_time_limits+len('time limits:'):
      →index_time_limits_end].split(',')
             time_limits = [float(i) for i in time_limits]
             # Cargo estados
             index_start_shape = data.find('shape:')
             index_end_shape = data.find('\n', index_start_shape)
             shape = data[index_start_shape+len('shape:'):index_end_shape].split(',')
             shape = [int(i) for i in shape]
             index_start_n_states = data.find('n_states:')
             index_end_n_states = data.find('\n', index_start_n_states)
             n_states = int(data[index_start_n_states+len('n_states:'):
      →index_end_n_states])
```

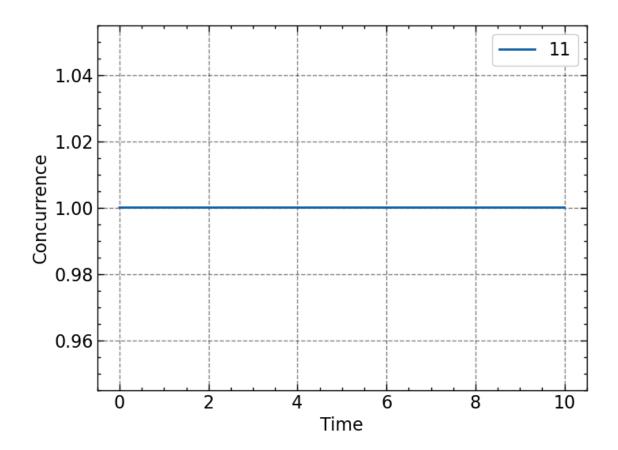
```
states = data[index_end_n_states+2:].strip().split('),(') # separo_
      →los estados
             states[-1] = states[-1][:-1] # saco el ultimo parentesis
             # los paso a numeros complejos de numpy
            res = np.empty(n states*shape[0]*shape[1], dtype=complex)
             for i, state in enumerate(states):
                 state_splited = state.split(',')
                 res[i] = complex(float(state_splited[0]), float(state_splited[1]))
            res = res.reshape(n_states, shape[0], shape[1])
            return res, h, time_limits
[3]: path2data_00 = '../results/results_bell_state_00.csv'
     path2data_01 = '../results/results_bell_state_01.csv'
     path2data_10 = '../results/results bell state 10.csv'
     path2data_11 = '../results/results_bell_state_11.csv'
     states_00, h_00, time_limits_00 = load_data(path2data_00)
     states_01, h_01, time_limits_01 = load_data(path2data_01)
     states_10, h_10, time_limits_10 = load_data(path2data_10)
     states_11, h_11, time_limits_11 = load_data(path2data_11)
[4]: def concurrence(states):
         return np.array([qt.concurrence(qt.Qobj(s, dims=[[2, 2], [2, 2]])) for s in_
      ⇒states])
[5]: concurrence_00 = concurrence(states_00)
     concurrence_01 = concurrence(states_01)
     concurrence_10 = concurrence(states_10)
     concurrence_11 = concurrence(states_11)
[9]: time_axis = np.arange(time_limits_00[0], time_limits_00[1]+h_00, h_00)
     plt.plot(time_axis, concurrence_00, label='00')
     plt.show()
     plt.plot(time_axis, concurrence_01, label='01')
     plt.show()
     plt.plot(time_axis, concurrence_10, label='10')
     plt.show()
     plt.plot(time_axis, concurrence_11, label='11')
     # plt.show()
     plt.legend()
     plt.xlabel('Time')
     plt.ylabel('Concurrence')
```







[9]: Text(0, 0.5, 'Concurrence')



[]: