# 1. Description

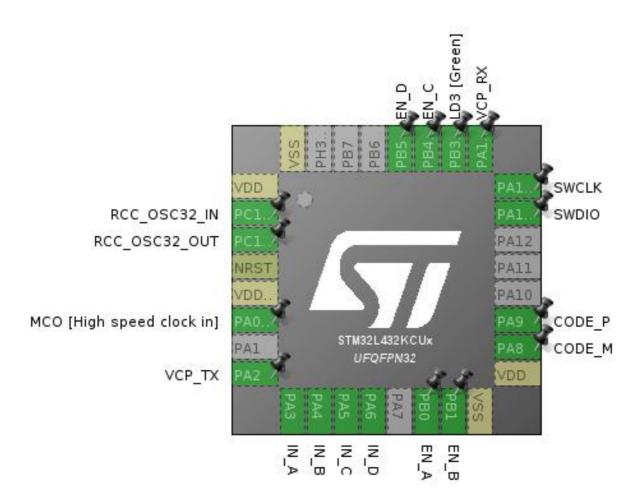
## 1.1. Project

Project Name	l4-windsensor
Board Name	NUCLEO-L432KC
Generated with:	STM32CubeMX 4.20.1
Date	05/03/2017

### 1.2. MCU

MCU Series	STM32L4
MCU Line	STM32L4x2
MCU name	STM32L432KCUx
MCU Package	UFQFPN32
MCU Pin number	32

# 2. Pinout Configuration

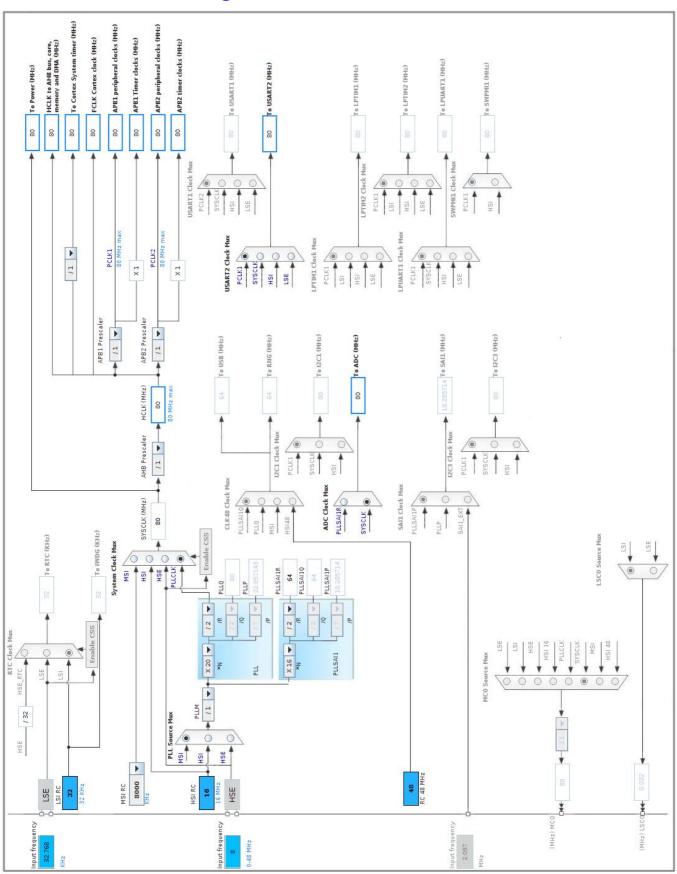


# 3. Pins Configuration

Pin Number UFQFPN32	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
1	VDD	Power		
2	PC14-OSC32_IN (PC14)	I/O	RCC_OSC32_IN	
3	PC15-OSC32_OUT (PC15)	I/O	RCC_OSC32_OUT	
4	NRST	Reset		
5	VDDA/VREF+	Power		
6	PA0-CK_IN	I/O	RCC_CK_IN	MCO [High speed clock in]
8	PA2	I/O	USART2_TX	VCP_TX
9	PA3	I/O	ADC1_IN8	IN_A
10	PA4	I/O	ADC1_IN9	IN_B
11	PA5	I/O	ADC1_IN10	IN_C
12	PA6	I/O	ADC1_IN11	IN_D
14	PB0 *	I/O	GPIO_Output	EN_A
15	PB1 *	I/O	GPIO_Output	EN_B
16	VSS	Power		
17	VDD	Power		
18	PA8 *	I/O	GPIO_Output	CODE_M
19	PA9 *	I/O	GPIO_Output	CODE_P
23	PA13 (JTMS-SWDIO)	I/O	SYS_JTMS-SWDIO	SWDIO
24	PA14 (JTCK-SWCLK)	I/O	SYS_JTCK-SWCLK	SWCLK
25	PA15 (JTDI)	I/O	USART2_RX	VCP_RX
26	PB3 (JTDO-TRACESWO) *	I/O	GPIO_Output	LD3 [Green]
27	PB4 (NJTRST) *	I/O	GPIO_Output	EN_C
28	PB5 *	I/O	GPIO_Output	EN_D
32	VSS	Power		

<sup>\*</sup> The pin is affected with an I/O function

# 4. Clock Tree Configuration



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## 5. IPs and Middleware Configuration

#### 5.1. ADC1

IN8: IN8 Single-ended IN9: IN9 Single-ended IN10: IN10 Single-ended IN11: IN11 Single-ended

#### 5.1.1. Parameter Settings:

#### ADC\_Settings:

Clock Prescaler Asynchronous clock mode divided by 1

Resolution ADC 12-bit resolution

Data Alignment Right alignment

Scan Conversion Mode Disabled

Continuous Conversion Mode Disabled

Discontinuous Conversion Mode Disabled

DMA Continuous Requests Enabled \*

End Of Conversion Selection End of single conversion

Overrun behaviour Overrun data preserved

Low Power Auto Wait Disabled

ADC\_Regular\_ConversionMode:

Enable Regular ConversionsEnableEnable Regular OversamplingDisableNumber Of Conversion1

External Trigger Conversion Source Timer 1 Trigger Out event \*

External Trigger Conversion Edge Trigger detection on the rising edge

Rank 1

Channel 10 \*

Sampling Time 2.5 Cycles
Offset Number No offset

ADC\_Injected\_ConversionMode:

Enable Injected Conversions Disable

**Analog Watchdog 1:** 

Enable Analog WatchDog1 Mode false

**Analog Watchdog 2:** 

Enable Analog WatchDog2 Mode false

**Analog Watchdog 3:** 

Enable Analog WatchDog3 Mode

false

#### 5.2. RCC

mode: High Speed Clock (HSE)

Low Speed Clock (LSE): Crystal/Ceramic Resonator

#### 5.2.1. Parameter Settings:

#### **System Parameters:**

VDD voltage (V) 3.3
Instruction Cache Enabled
Prefetch Buffer Disabled
Data Cache Enabled

Flash Latency(WS) 4 WS (5 CPU cycle)

**RCC Parameters:** 

HSI Calibration Value 16

MSI Calibration Value 0

MSI Auto Calibration Enabled

HSE Startup Timout Value (ms) 100

LSE Startup Timout Value (ms) 5000

LSE Drive Capability

LSE oscillator low drive capability

**Power Parameters:** 

Power Regulator Voltage Scale Power Regulator Voltage Scale 1

#### 5.3. SYS

**Debug: Serial Wire** 

Timebase Source: SysTick

#### 5.4. TIM1

**Clock Source: Internal Clock** 

#### 5.4.1. Parameter Settings:

#### **Counter Settings:**

Prescaler (PSC - 16 bits value) 0

Counter Mode Up

Counter Period (AutoReload Register - 16 bits value ) 49

Internal Clock Division (CKD)

No Division

Repetition Counter (RCR - 8 bits value) 0

**Trigger Output (TRGO) Parameters:** 

Master/Slave Mode Enable (sync between this TIM (Master) and its Slaves

(through TRGO)) \*

Trigger Event Selection TRGO Update Event \*

Trigger Event Selection TRGO2 Reset (UG bit from TIMx\_EGR)

#### 5.5. TIM2

Slave Mode: External Clock Mode 1

**Trigger Source: ITR0** 

#### 5.5.1. Parameter Settings:

#### **Counter Settings:**

Prescaler (PSC - 16 bits value) 0
Counter Mode Up
Counter Period (AutoReload Register - 32 bits value) 19 \*

Internal Clock Division (CKD)

No Division

Slave Mode Controller

ETR mode 1

**Trigger Output (TRGO) Parameters:** 

Master/Slave Mode Disable (no sync between this TIM (Master) and its Slaves

#### 5.6. USART2

**Mode: Asynchronous** 

#### 5.6.1. Parameter Settings:

#### **Basic Parameters:**

Baud Rate 115200

Word Length 8 Bits (including Parity) \*

Parity None Stop Bits 1

#### **Advanced Parameters:**

Data Direction Receive and Transmit

Over Sampling 16 Samples
Single Sample Disable

#### **Advanced Features:**

Auto Baudrate Disable TX Pin Active Level Inversion Disable RX Pin Active Level Inversion Disable Disable Data Inversion TX and RX Pins Swapping Disable Enable Overrun DMA on RX Error Enable MSB First Disable

#### \* User modified value

# 6. System Configuration

## 6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
ADC1	PA3	ADC1_IN8	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	IN_A
	PA4	ADC1_IN9	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	IN_B
	PA5	ADC1_IN10	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	IN_C
	PA6	ADC1_IN11	Analog mode for ADC conversion	No pull-up and no pull-down	n/a	IN_D
RCC	PC14- OSC32_IN (PC14)	RCC_OSC32_IN	n/a	n/a	n/a	
	PC15- OSC32_OU T (PC15)	RCC_OSC32_O UT	n/a	n/a	n/a	
	PA0-CK_IN	RCC_CK_IN	n/a	n/a	n/a	MCO [High speed clock in]
SYS	PA13 (JTMS- SWDIO)	SYS_JTMS- SWDIO	n/a	n/a	n/a	SWDIO
	PA14 (JTCK- SWCLK)	SYS_JTCK- SWCLK	n/a	n/a	n/a	SWCLK
USART2	PA2	USART2_TX	Alternate Function Push Pull	Pull-up	Very High *	VCP_TX
	PA15 (JTDI)	USART2_RX	Alternate Function Push Pull	Pull-up	Very High *	VCP_RX
GPIO	PB0	GPIO_Output	Output Push Pull	Pull-down *	Low	EN_A
	PB1	GPIO_Output	Output Push Pull	Pull-down *	Low	EN_B
	PA8	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Very High	CODE_M
	PA9	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Very High	CODE_P
	PB3 (JTDO- TRACESWO	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD3 [Green]
	PB4 (NJTRST)	GPIO_Output	Output Push Pull	Pull-down *	Low	EN_C
	PB5	GPIO_Output	Output Push Pull		Low	EN_D

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
				Pull-down *		

### 6.2. DMA configuration

DMA request	Stream	Direction	Priority
USART2_TX	DMA1_Channel7	Memory To Peripheral	Low
ADC1	DMA2_Channel3	Peripheral To Memory	Low
TIM2_UP	DMA1_Channel2	Peripheral To Memory	Low

#### USART2\_TX: DMA1\_Channel7 DMA request Settings:

Mode: Normal
Peripheral Increment: Disable
Memory Increment: Enable \*
Peripheral Data Width: Byte

Memory Data Width:

### ADC1: DMA2\_Channel3 DMA request Settings:

Byte

Mode: Normal

Peripheral Increment: Disable

Memory Increment: Enable \*

Peripheral Data Width: Half Word

Memory Data Width: Half Word

### TIM2\_UP: DMA1\_Channel2 DMA request Settings:

Mode: Normal
Peripheral Increment: Disable
Memory Increment: Enable \*
Peripheral Data Width: Byte \*

## 6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Prefetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	0	0
System tick timer	true	0	0
DMA1 channel2 global interrupt	true 0 0		0
DMA1 channel7 global interrupt	true	0	0
DMA2 channel3 global interrupt	true	0	0
PVD/PVM1/PVM2/PVM3/PVM4 interrupts through EXTI lines 16/35/36/37/38		unused	
Flash global interrupt		unused	
RCC global interrupt	unused		
ADC1 global interrupt		unused	
TIM1 break interrupt and TIM15 global interrupt		unused	
TIM1 update interrupt and TIM16 global interrupt	unused		
TIM1 trigger and commutation interrupts	unused		
TIM1 capture compare interrupt	unused		
TIM2 global interrupt	unused		
USART2 global interrupt	unused		
FPU global interrupt		unused	

<sup>\*</sup> User modified value

# 7. Power Consumption Calculator report

#### 7.1. Microcontroller Selection

Series	STM32L4
Line	STM32L4x2
MCU	STM32L432KCUx
Datasheet	028798_Rev1

#### 7.2. Parameter Selection

Temperature	25
Vdd	null

# 8. Software Project

## 8.1. Project Settings

Name	Value
Project Name	l4-windsensor
Project Folder	/home/elmot/projects/l4-windsensor
Toolchain / IDE SW4STM32	
Firmware Package Name and Version	STM32Cube FW_L4 V1.7.0

## 8.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	No
consumption)	