

x -Fast and y -Fast Tries

Outline for Today

- ***Data Structures on Integers***
 - How can we speed up operations that work on integer data?
- ***x-Fast Tries***
 - Bit manipulation meets tries and hashing.
- ***y-Fast Tries***
 - Combining RMQ, strings, balanced trees, amortization, and randomization!

Working with Integers

- Many practical problems involve working specifically with integer values.
 - **CPU Scheduling:** Each thread has some associated integer priority, and we need to maintain those priorities in sorted order.
 - **Network Routing:** Each computer has an associated IP address, and we need to figure out which connections are active.
 - **ID Management:** We need to store social security numbers, zip codes, phone numbers, credit card numbers, etc. and perform basic lookups and range searches on them.
- We've seen many general-purpose data structures for keeping things in order and looking things up.
- **Question:** Can we improve those data structures if we know in advance that we're working with integer data?

Working with Integers

- Integers are interesting objects to work with:
 - Their values can directly be used as indices in lookup tables.
 - They can be treated as strings of bits, so we can use techniques from string processing.
 - They fit into machine words, so we can process the bits in parallel with individual word operations.
- The data structures we'll explore over the next few lectures will give you a sense of what sorts of techniques are possible with integer data.

An Auxiliary Motive

- Integer data structures are also a great place to see just how much you've learned over the quarter!
- Today's data structures cover every single unit from the quarter (RMQ, strings, balanced trees, amortization, and randomization).
- I hope this gives you a chance to pause and reflect on just how far you've come!

The Setup

Our Machine Model

- We will assume we're working on a machine where memory is segmented into w -bit words.
 - Although on any one fixed machine w is a constant, in general, don't assume this is the case. 32-bit was the norm until fairly recently, and before that 16-bit was standard.
- We will assume that, if we build a data structure that holds n elements, then $w = \Omega(\log n)$.
 - This is called the ***transdichotomous machine model***. Essentially, your word size has to be big enough to hold the size of your input.
- We'll assume C integer operators work in constant time, and won't assume other integer operations (say, finding most significant bits, counting 1 bits set) are available.

+ - * / % << >> & | ^ = <=

Besting BSTs

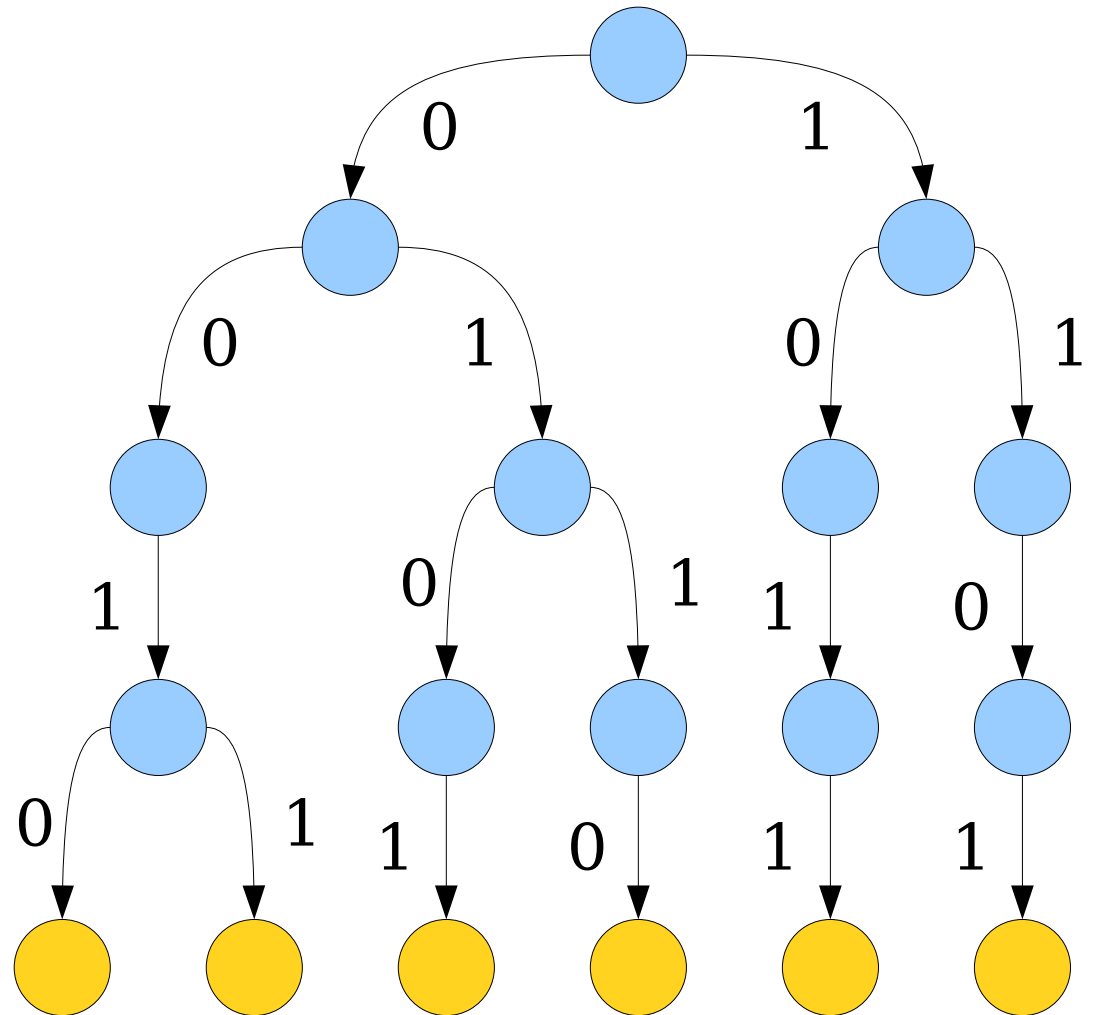
Besting BSTs

- BSTs store their elements in sorted order, which enables them to quickly answer each of the following queries:
 - **lookup**(x), which returns whether $x \in S$;
 - **insert**(x), which adds x to S ;
 - **delete**(x), which removes x from S ;
 - **max**() / **min**(), which return the max/min element of S ;
 - **successor**(x), which returns the smallest element of S greater than x ; and
 - **predecessor**(x), which returns the largest element of S smaller than x .
- **Question:** Can we build another data structure that answers these same queries, but does so faster than a BST?

A Start: ***Bitwise Tries***

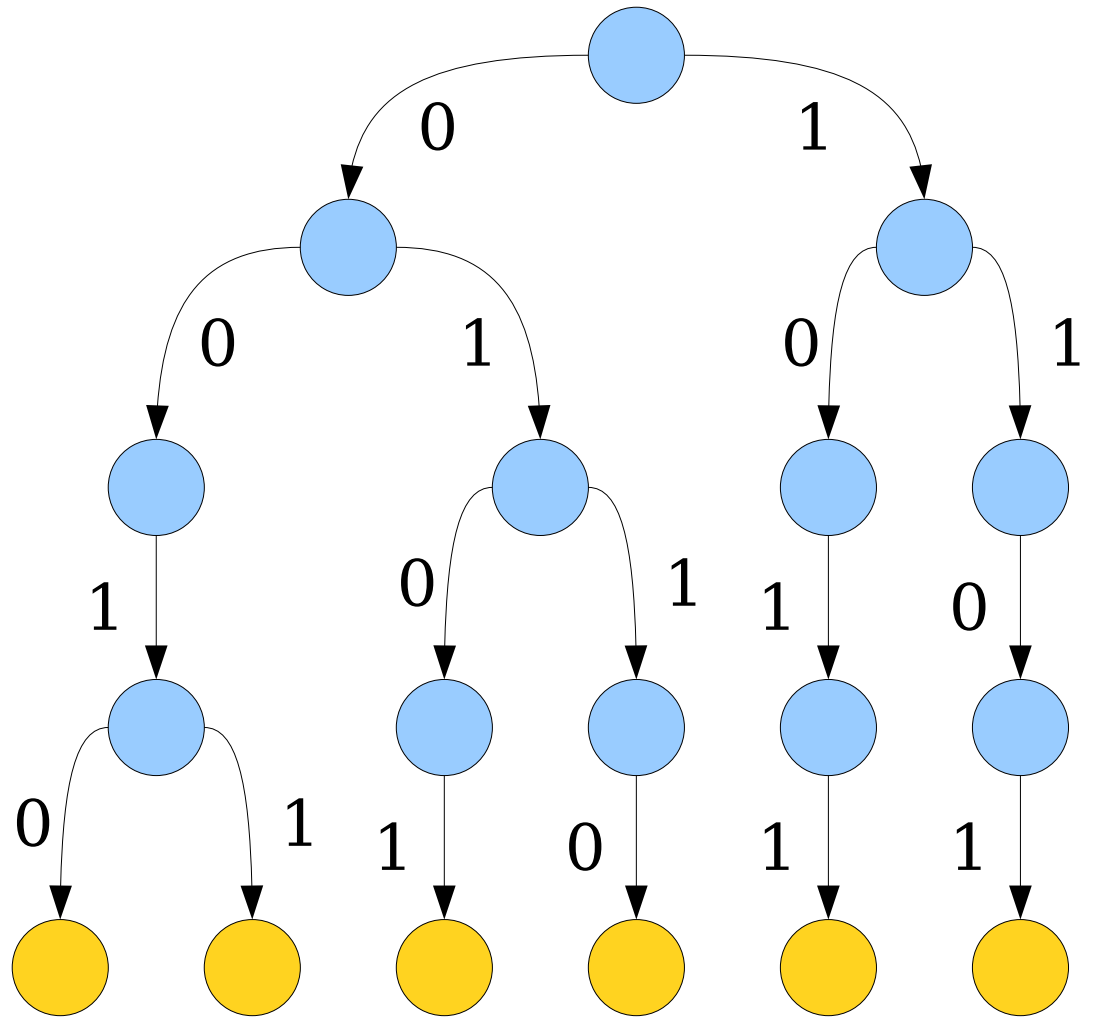
Tries Revisited

- **Recall:** A trie is a simple data structure for storing strings.
- Integers can be thought of as strings of bits.
- **Idea:** Store integers in a **bitwise trie**.



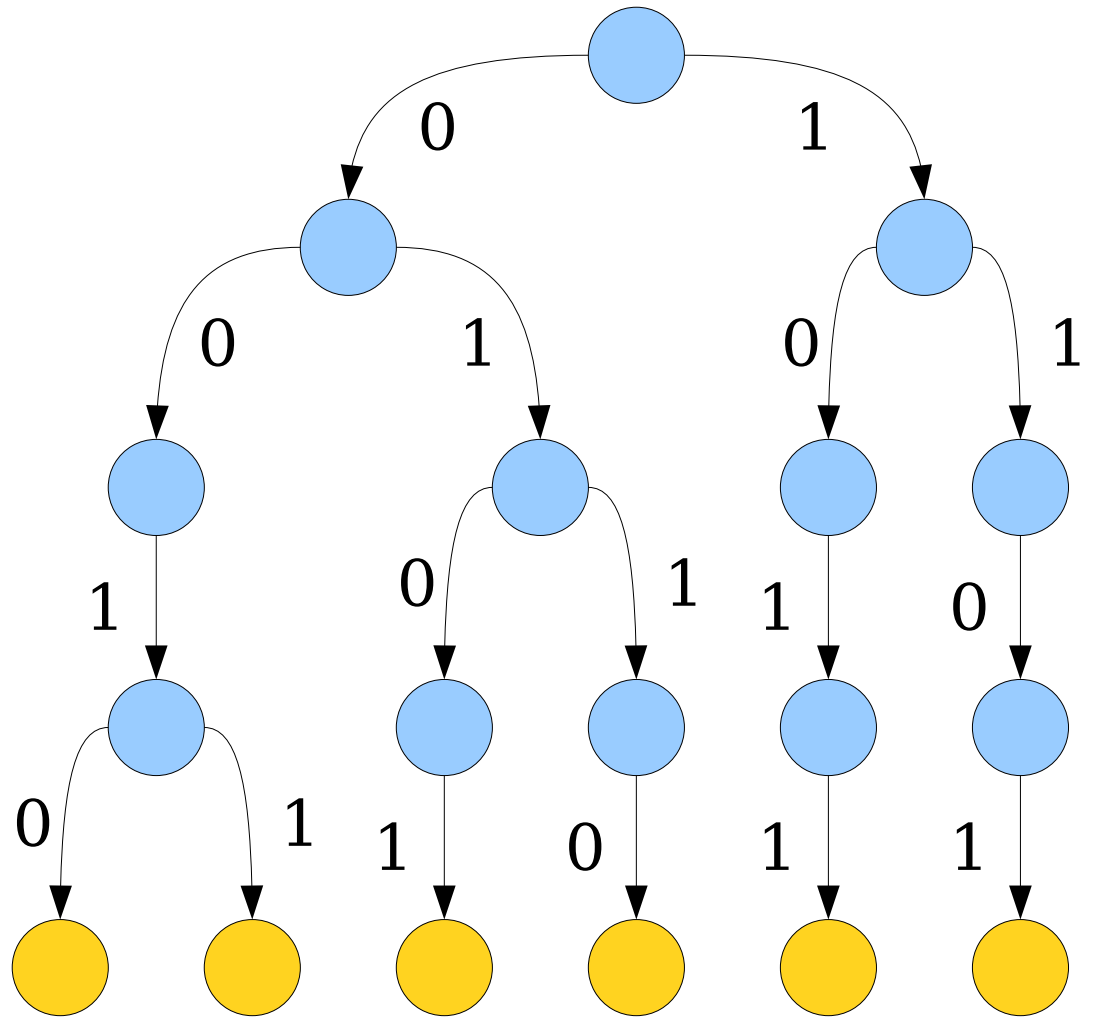
Finding Successors

- To compute **successor**(x), do the following:
 - Search for x .
 - If x is a leaf node, its successor is the next leaf.
 - If you don't find x , back up until you find a node with a 1 child not already followed, follow the 1, then take the cheapest path down.



Bitwise Trie Efficiency

- All operations on bitwise tries take time proportional to the number of bits in each number.
- Runtime for each operation: $O(w)$.
 - This is worse than a BST's $O(\log n)$.
- *Can we do better?*



Speeding up Successors

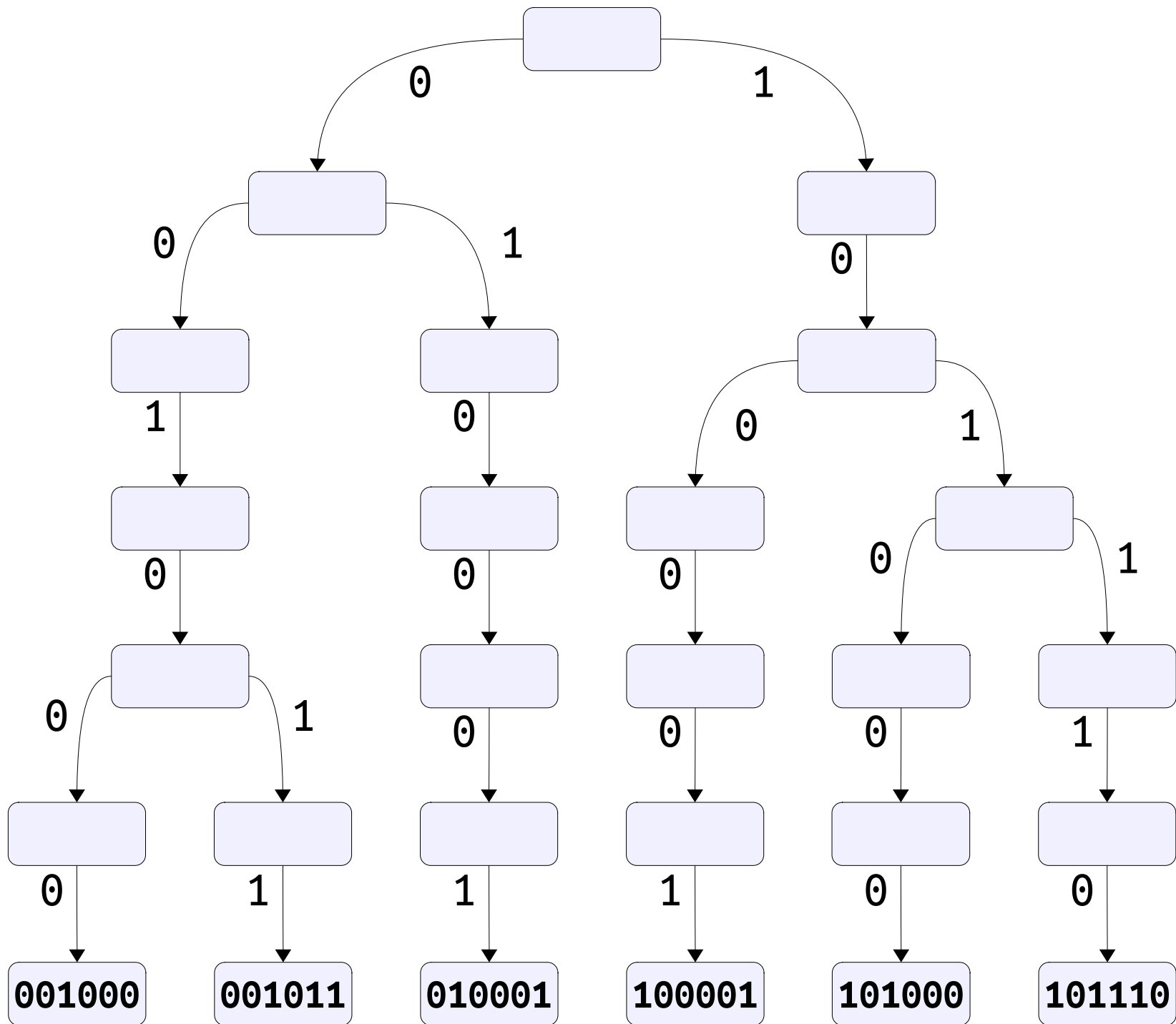
- There are two independent pieces that contribute to the $O(w)$ runtime:
 - Need to walk down the trie following the bits of x , and there are $\Theta(w)$ of those.
 - From there, need to back up to a branching node where we can find the successor.
- Can we speed up those operations? Or at least work around them?

A Quick Algorithms Problem

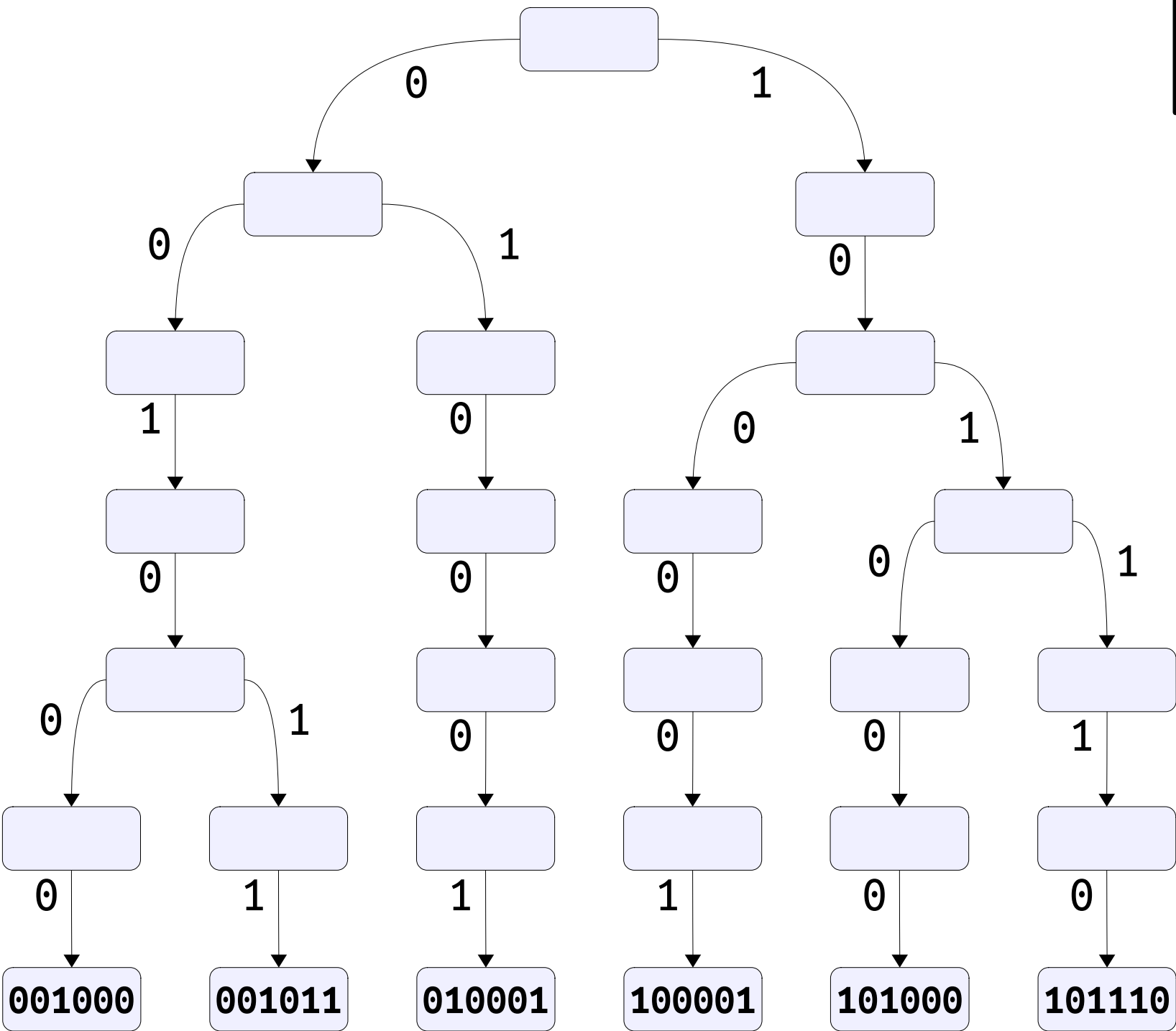
- You're given an array consisting of some number of **Y**'s followed by some number of **N**'s. There are k total letters.

YYYYYYY...YYNNNNN...NN

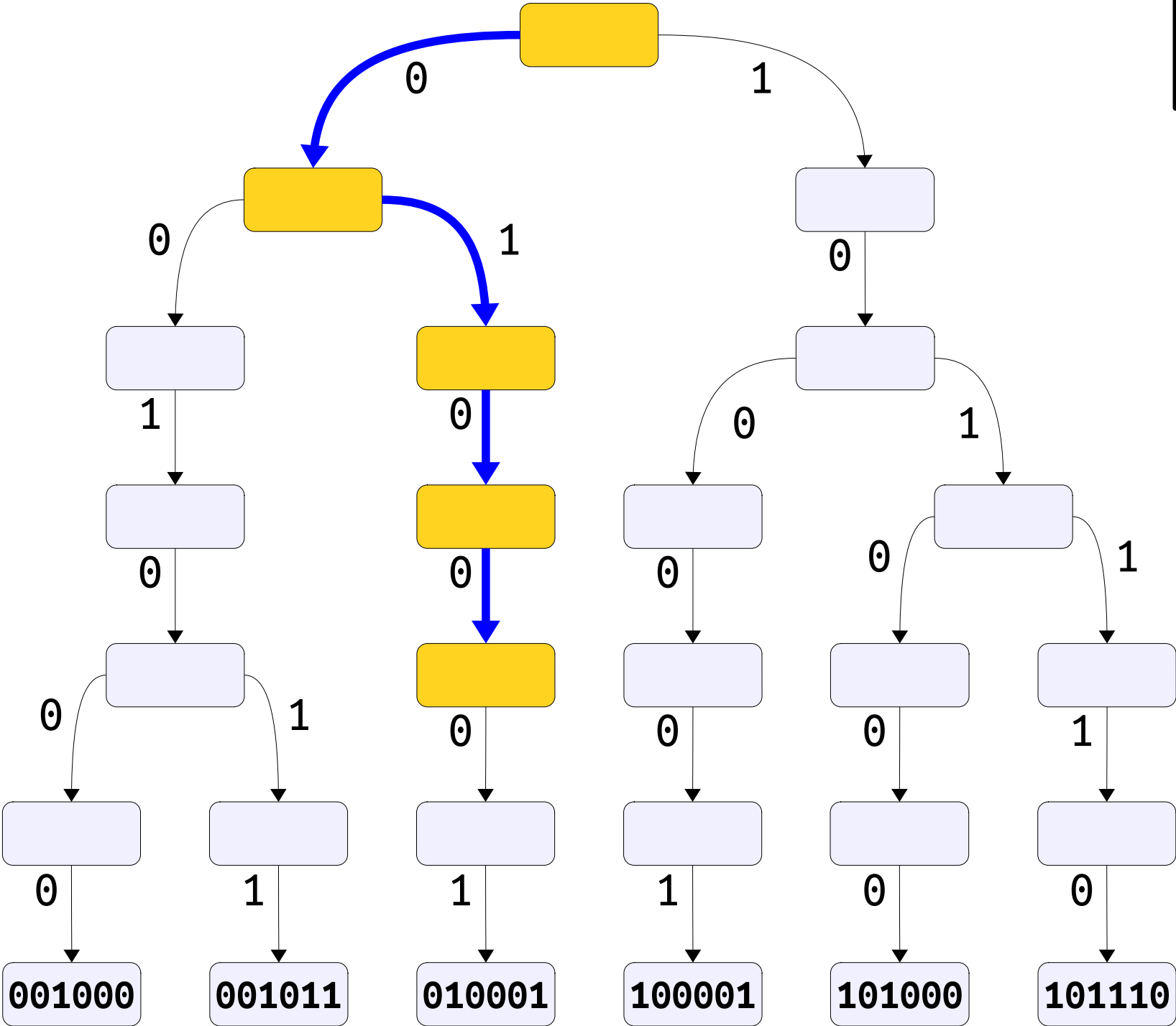
- How quickly can you find the last Y?
- **Answer:** Can be done in time $O(\log k)$ using a binary search.



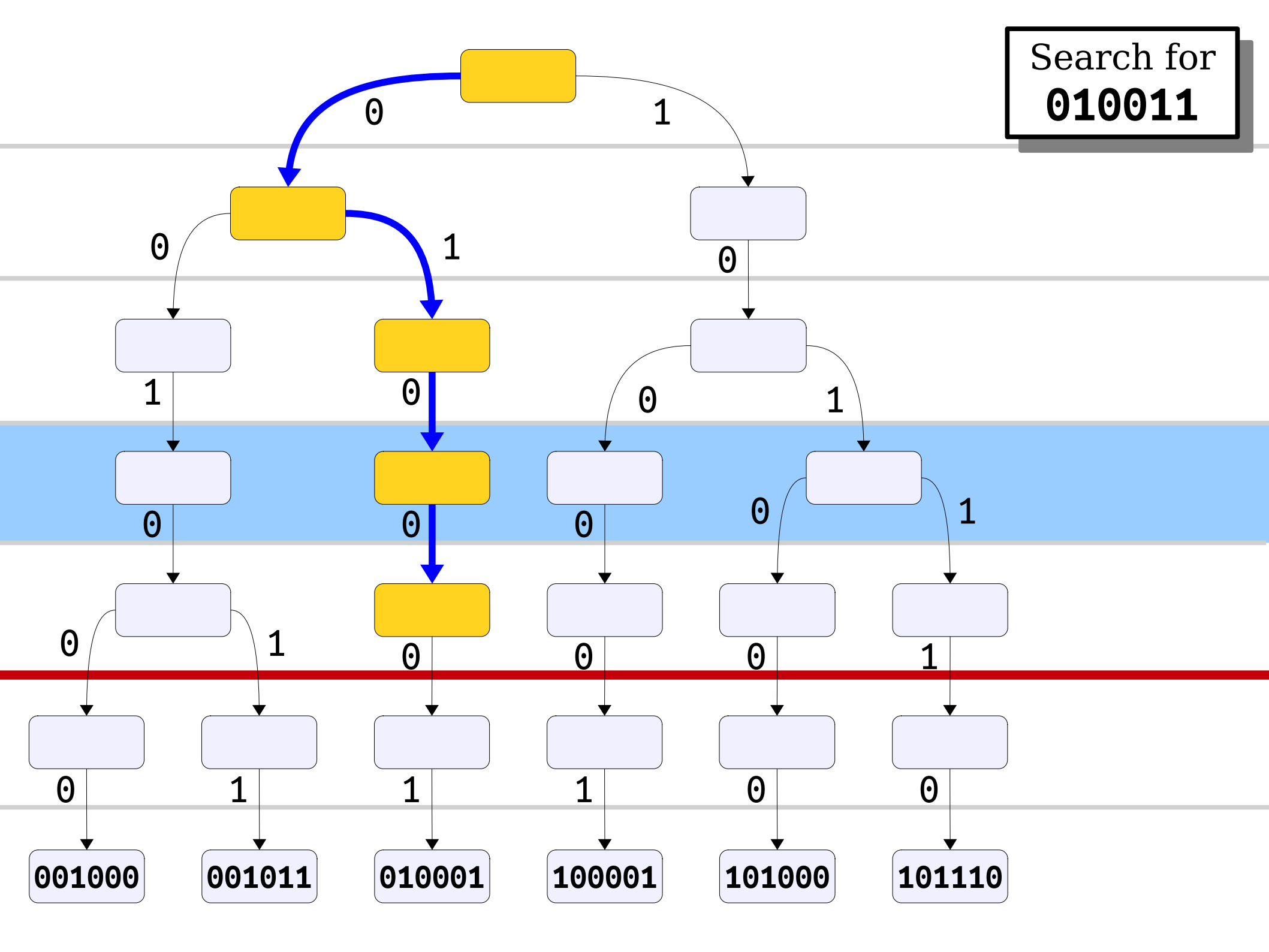
Search for
010011



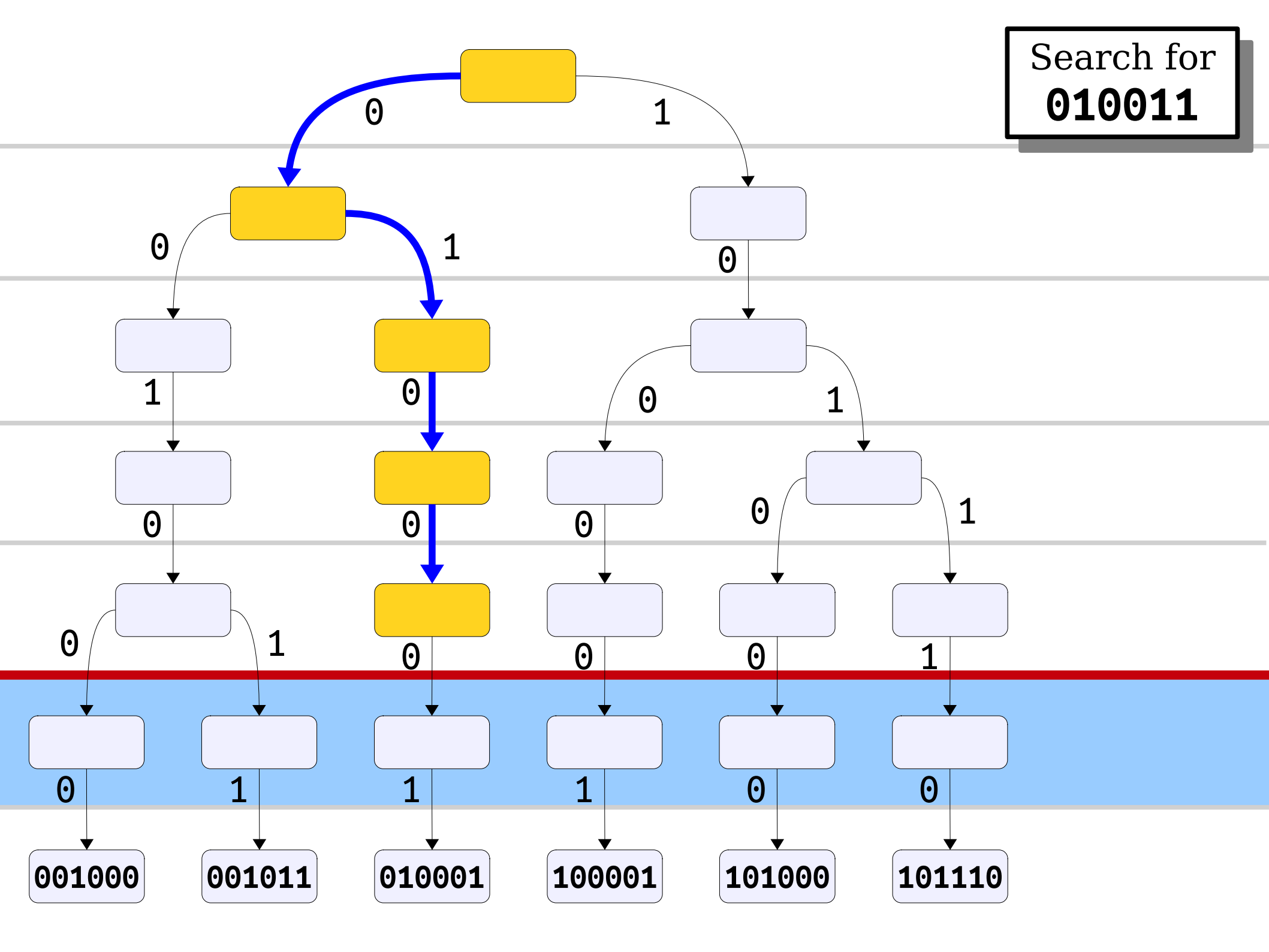
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010011



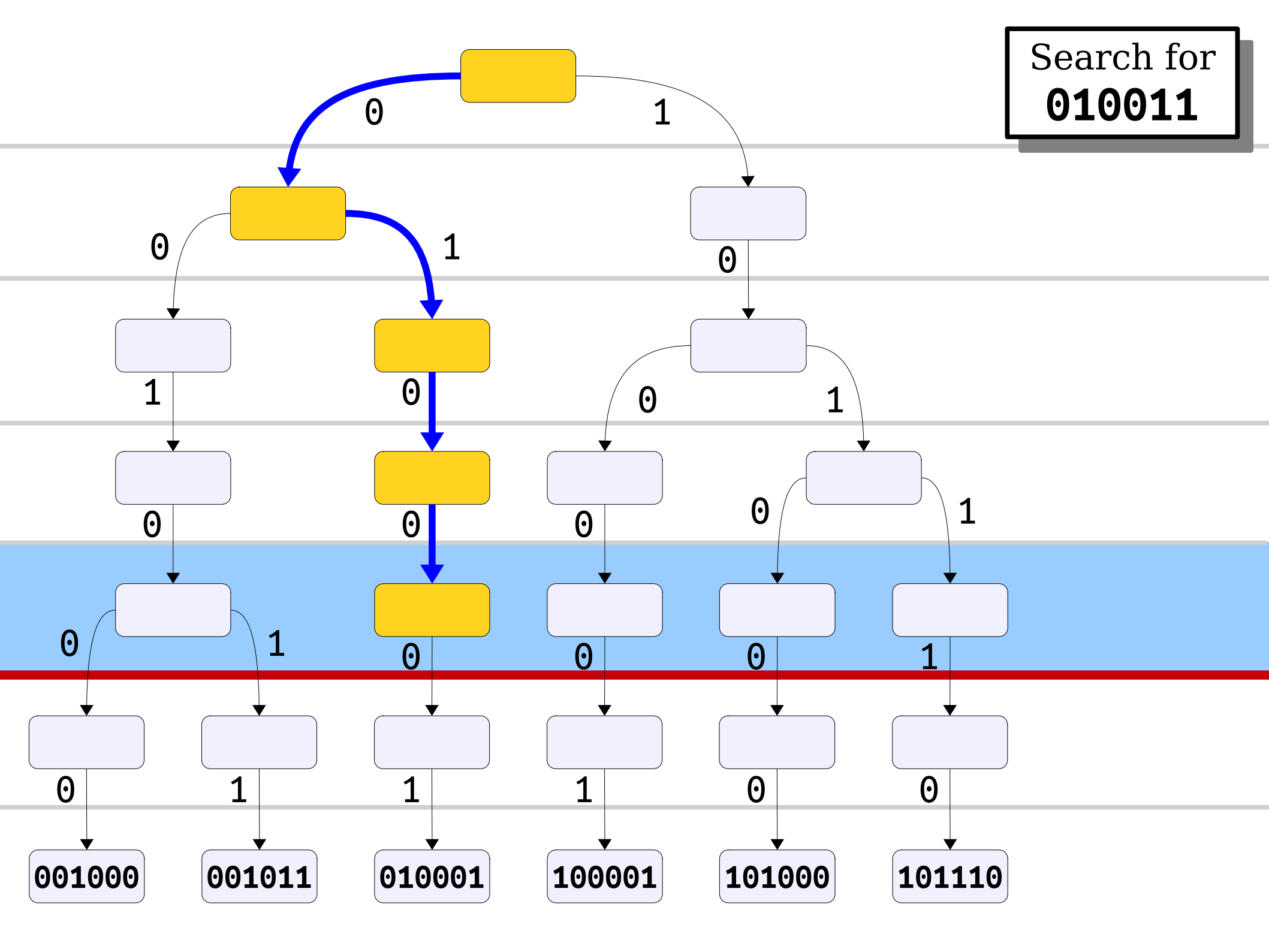
Search for
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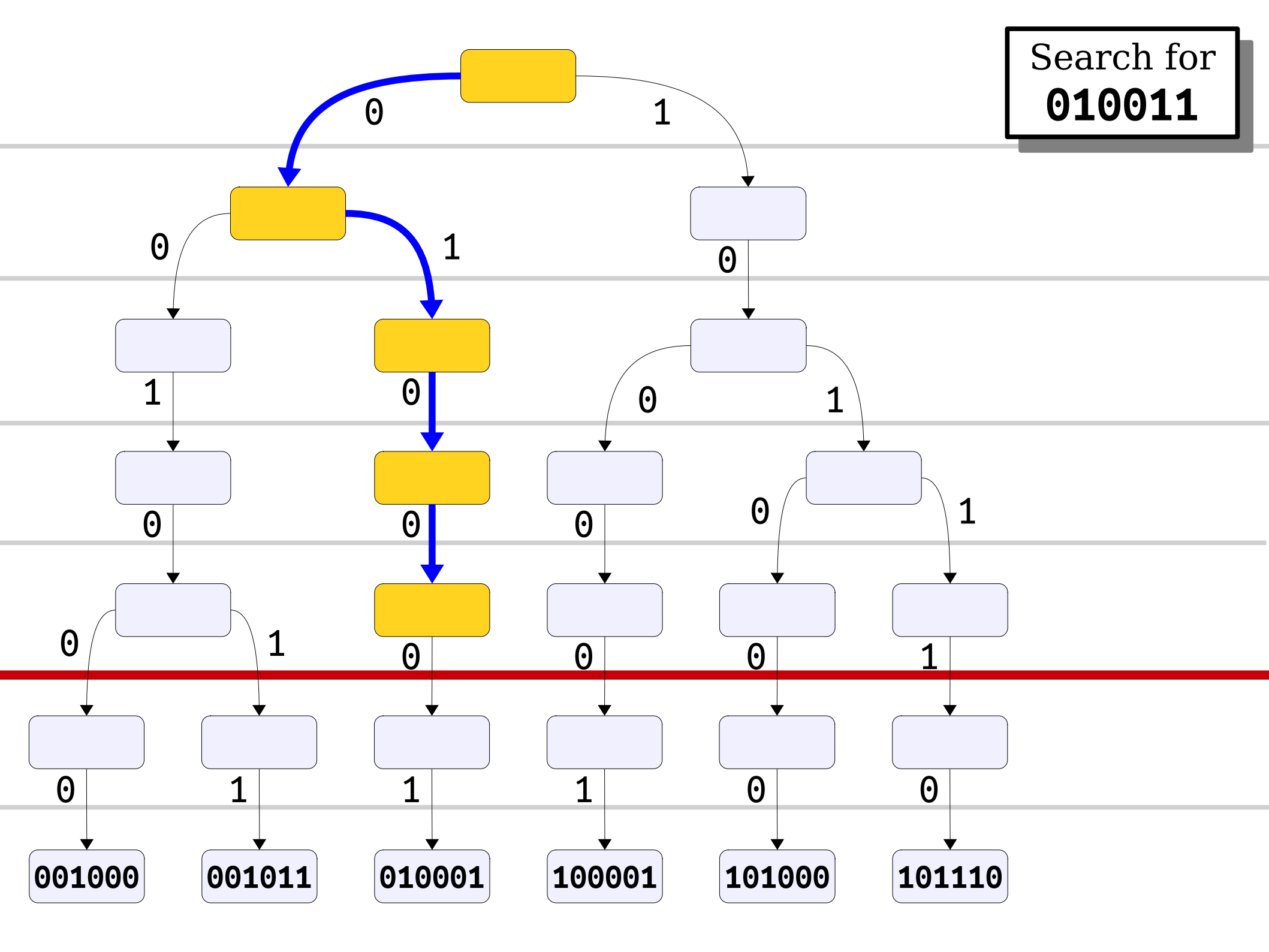
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010011



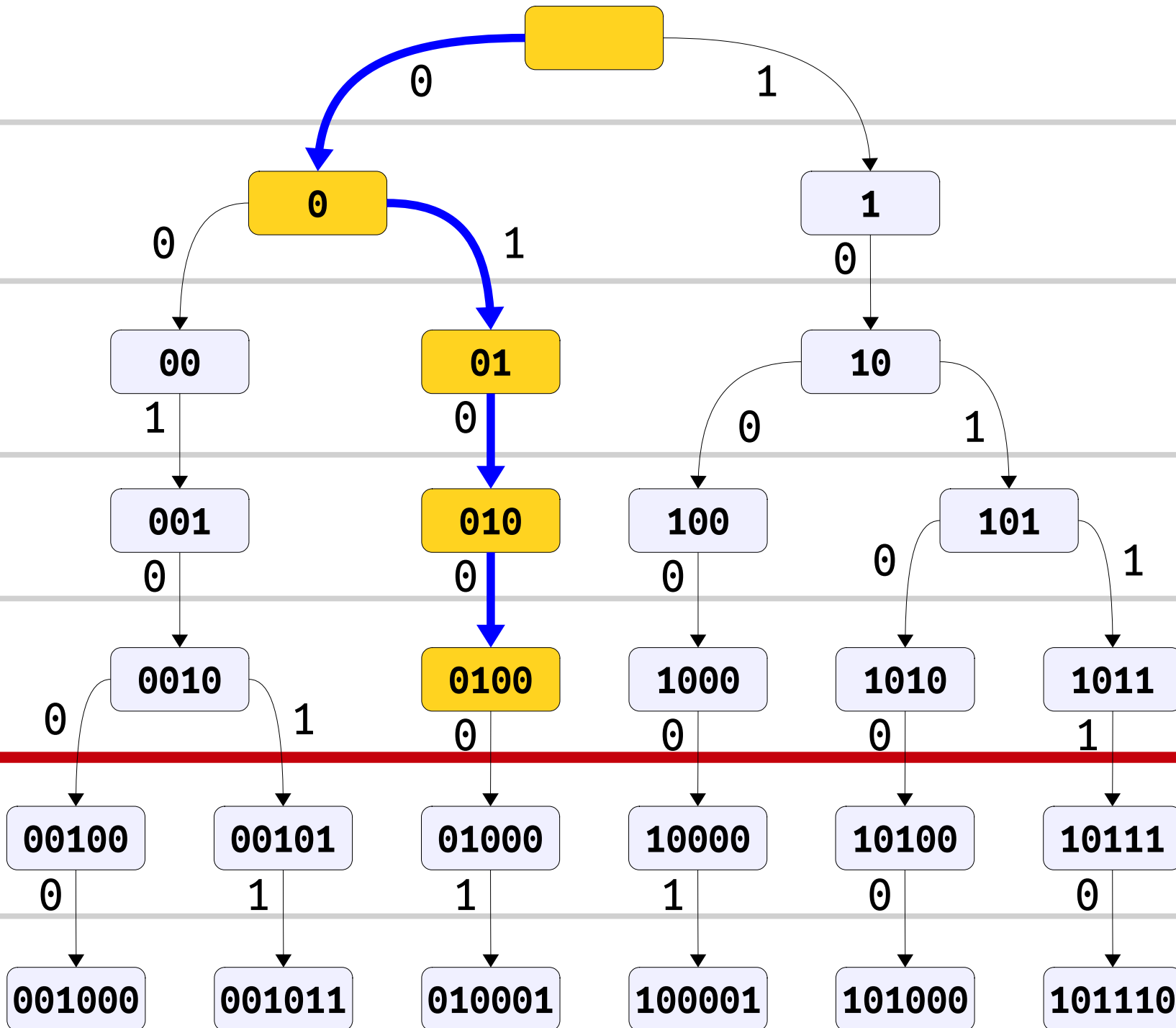
Search for
010011



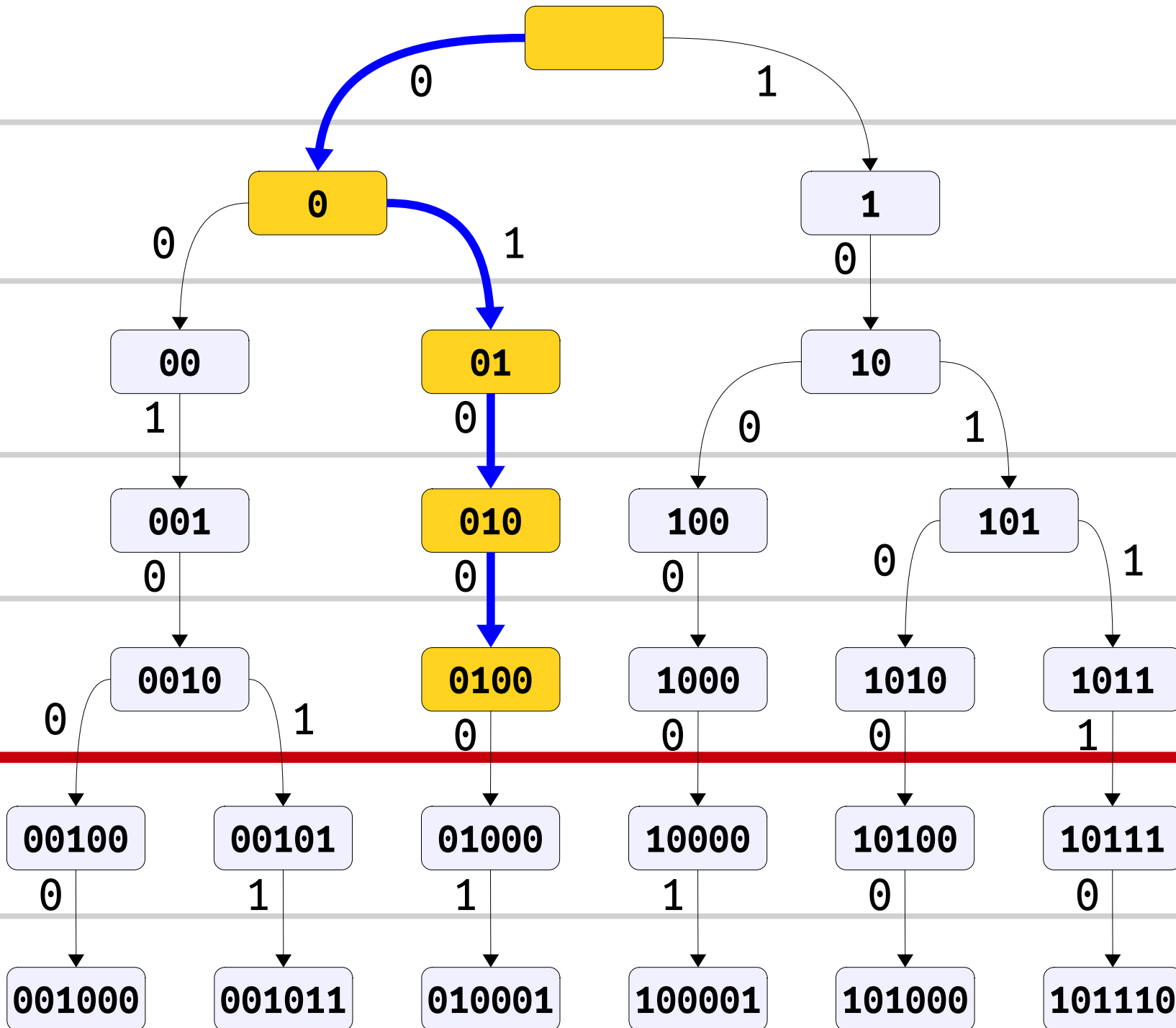
Search for
010011



Search for
010011



Search for
010011



0 1

00 01
10

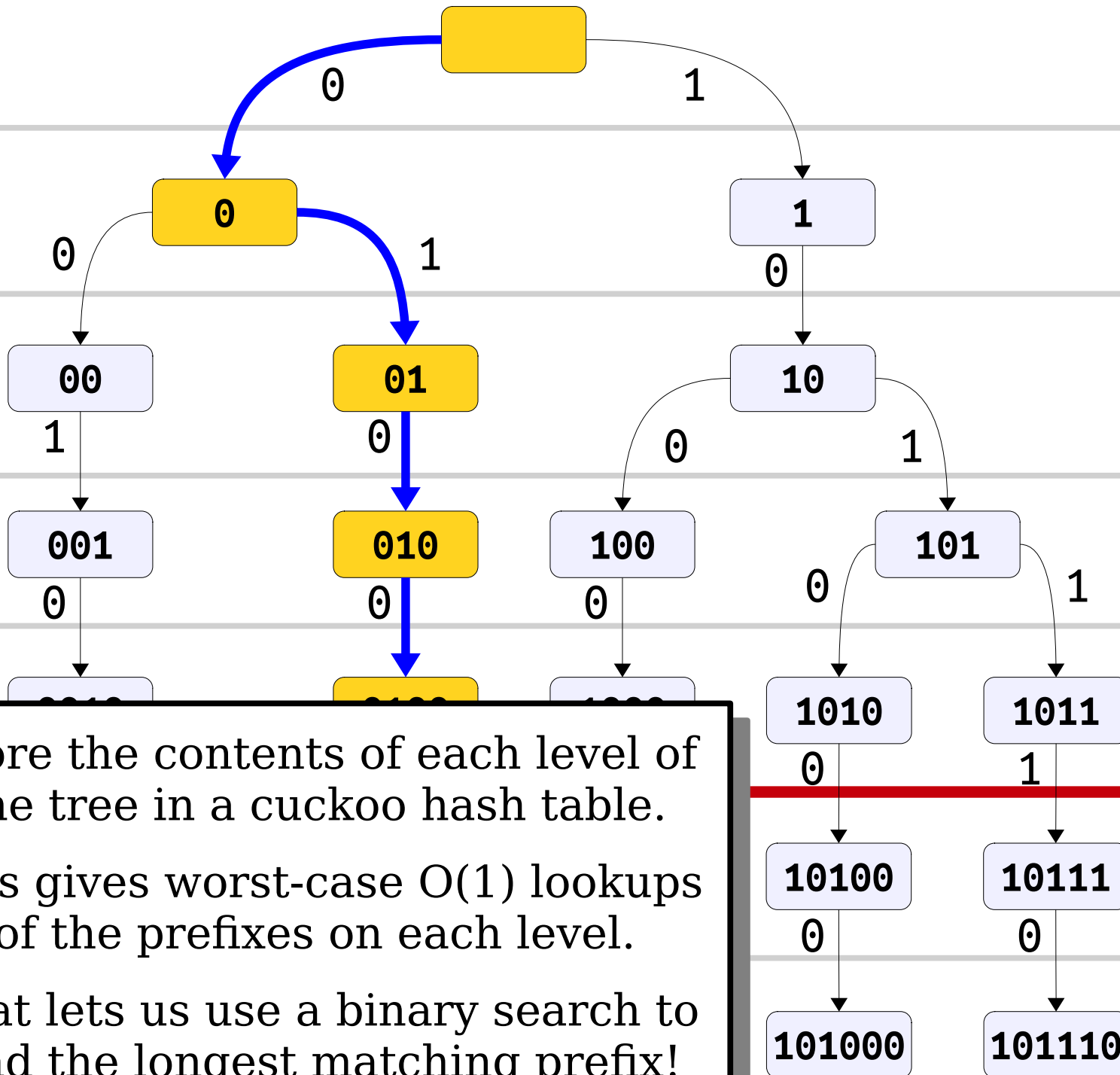
001 010
100 101

0010 0100
1000 1010
1011

00100 00101
01000 10000
10100 10111

001000 001011
010001 100001
101000 101110

Search for
010011



0 1

00 01
10

001 010
100 101

0010 0100
1000 1010
1011

00100 00101
01000 10000
10100 10111

001000 001011
010001 100001
101000 101110

One Speedup

- **Goal:** Encode the trie so that we can do a binary search over its layers.
- **One Solution:** Store an array of cuckoo hash tables, one per layer of the trie, that holds all the nodes in that layer.
- Can now query, in worst-case time $O(1)$, whether a node's prefix is present on a given layer.
- There are $O(w)$ layers in the trie.
- Binary search will take worst-case time **$O(\log w)$** . This is *much* better than $O(\log n)$ for any reasonable value of n .

Performing the Binary Search

- This binary search assumes that, given a number x and a length k , we can extract the first k bits of x in time $O(1)$.
- Fortunately, we can do this!

x

11011100 10111011 11000100 11010110 11110011 01111011 11110000 10001100

Performing the Binary Search

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x	11011100 10111011 11000100 11010110 11110011 01111011 11110000 10001100
$mask$	11111111 11111111 11111111 11110000 00000000 00000000 00000000 00000000
$prefix$	11011100 10111011 11000100 11010000 00000000 00000000 00000000 00000000

```
uint64_t x      = /* ... */;  
uint64_t mask   = something magical;  
uint64_t prefix = x & mask;
```

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$mask$	00000000 00000000 00000000 00010000 00000000 00000000 00000000 00000000
$prefix$	11011100 10111011 11000100 11010000 00000000 00000000 00000000 00000000

```
uint64_t x      = /* ... */;  
uint64_t mask   = (uint64_t(1) << (64 - k));  
uint64_t prefix = x & mask;
```


Performing the Binary Search

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- Fortunately, we can do this!

x	11011100 10111011 11000100 11010110 11110011 01111011 11110000 10001100
$mask$	11111111 11111111 11111111 11101111 11111111 11111111 11111111 11111111
$prefix$	11011100 10111011 11000100 11010000 00000000 00000000 00000000 00000000

```
uint64_t x      = /* ... */;  
uint64_t mask   = ~(uint64_t(1) << (64 - k));  
uint64_t prefix = x & mask;
```

Performing the Binary Search

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- Fortunately, we can do this!

x	11011100 10111011 11000100 11010110 11110011 01111011 11110000 10001100
$mask$	11111111 11111111 11111111 11110000 00000000 00000000 00000000 00000000
$prefix$	11011100 10111011 11000100 11010000 00000000 00000000 00000000 00000000

$$-x = \sim x + 1$$

Thanks, CS107!

```
uint64_t x = /* ... */;  
uint64_t mask = ~(uint64_t(1) << (64 - k)) + 1;  
uint64_t prefix = x & mask;
```

Performing the Binary Search

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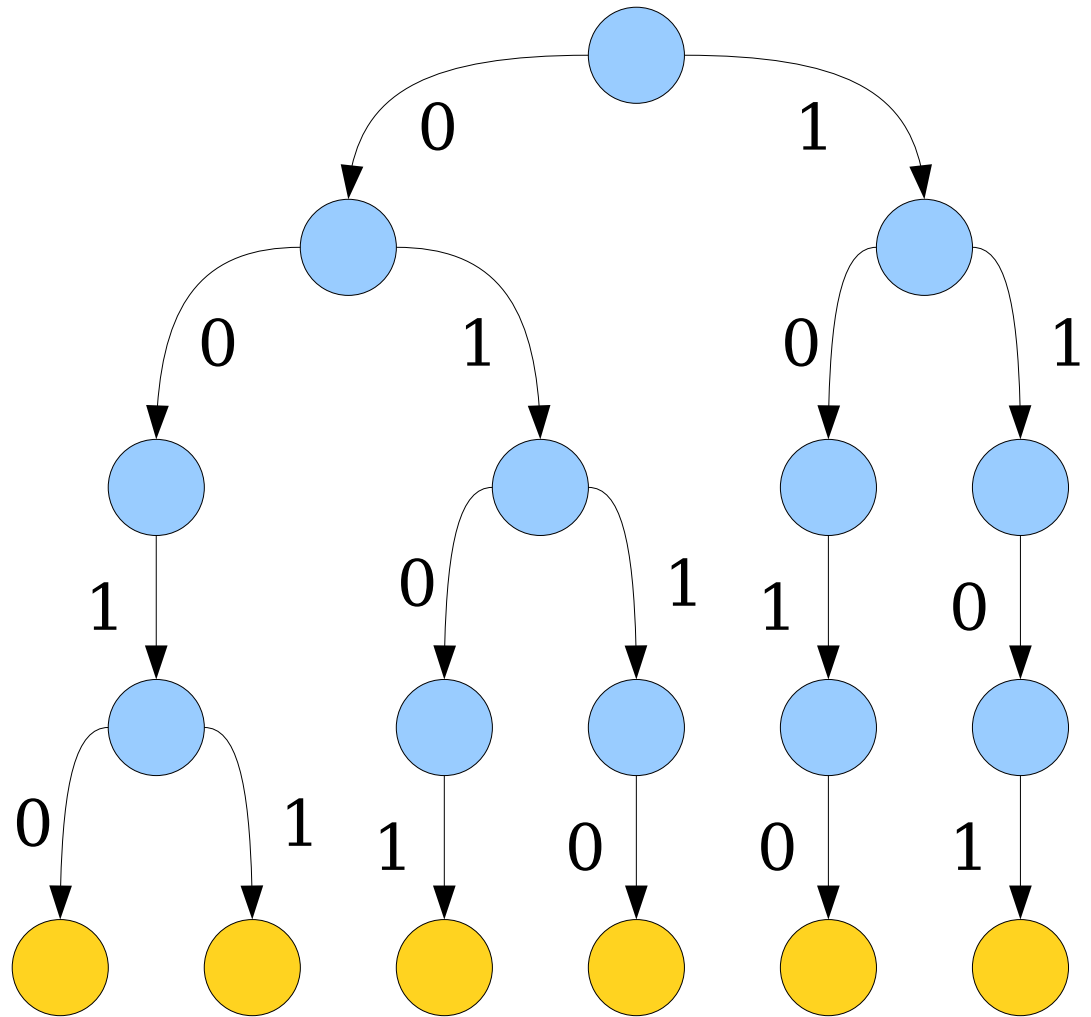
x	11011100 10111011 11000100 11010110 11110011 01111011 11110000 10001100
$mask$	11111111 11111111 11111111 11110000 00000000 00000000 00000000 00000000
$prefix$	11011100 10111011 11000100 11010110

There's an edge case to handle here for $k = 0$, but that's easily special-cased. Let me know if there's a way to avoid this!

```
uint64_t x = /* ... */;  
uint64_t mask = ~(uint64_t(1) << (64 - k));  
uint64_t prefix = x & mask;
```

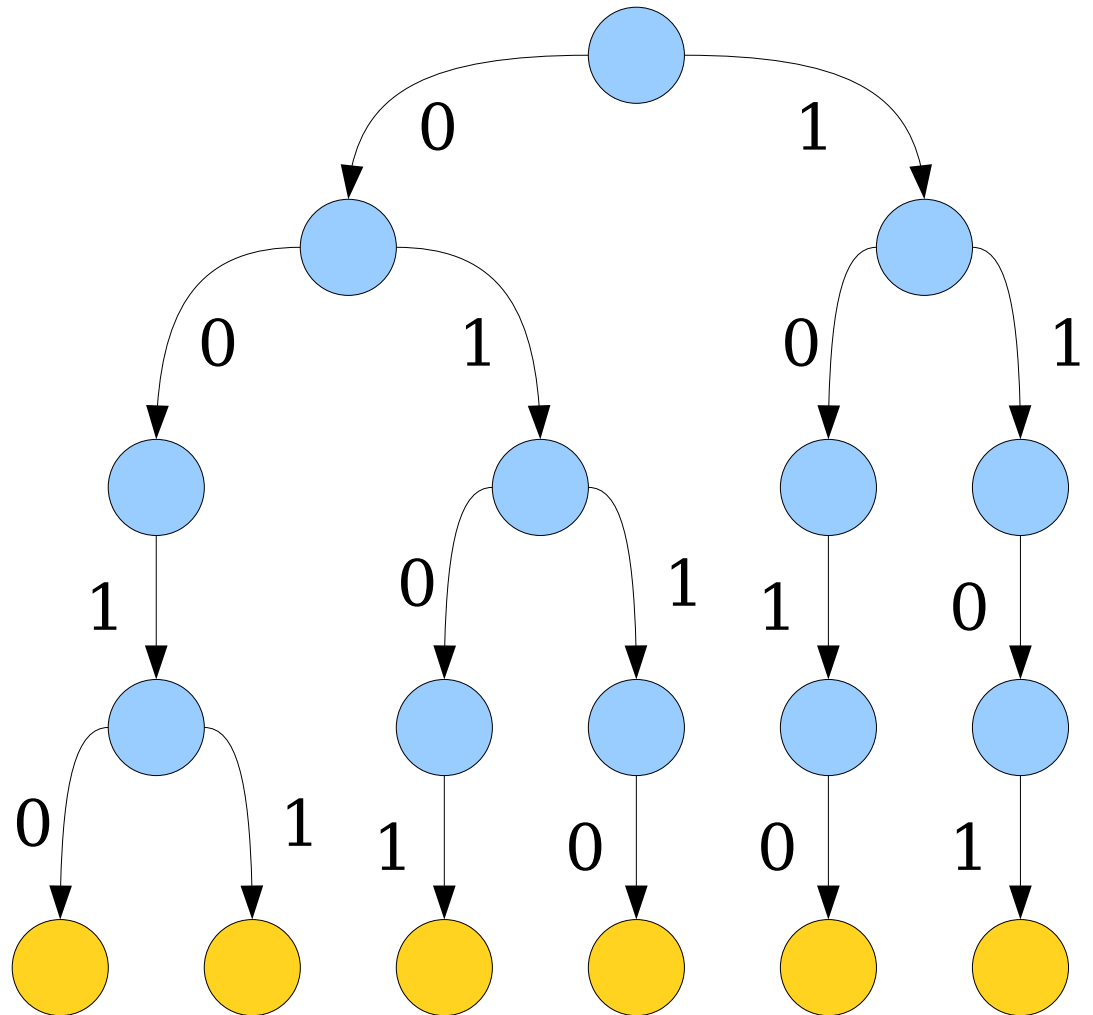
Finding Successors

- We can now find the node where the successor search would initially arrive in time $O(\log w)$.
- At this point, we'd normally back up until we find a branching node where we can follow a 1 child pointer, then descend from there to the leaves.
- This will take time $O(w)$.
- ***Can we do better?***



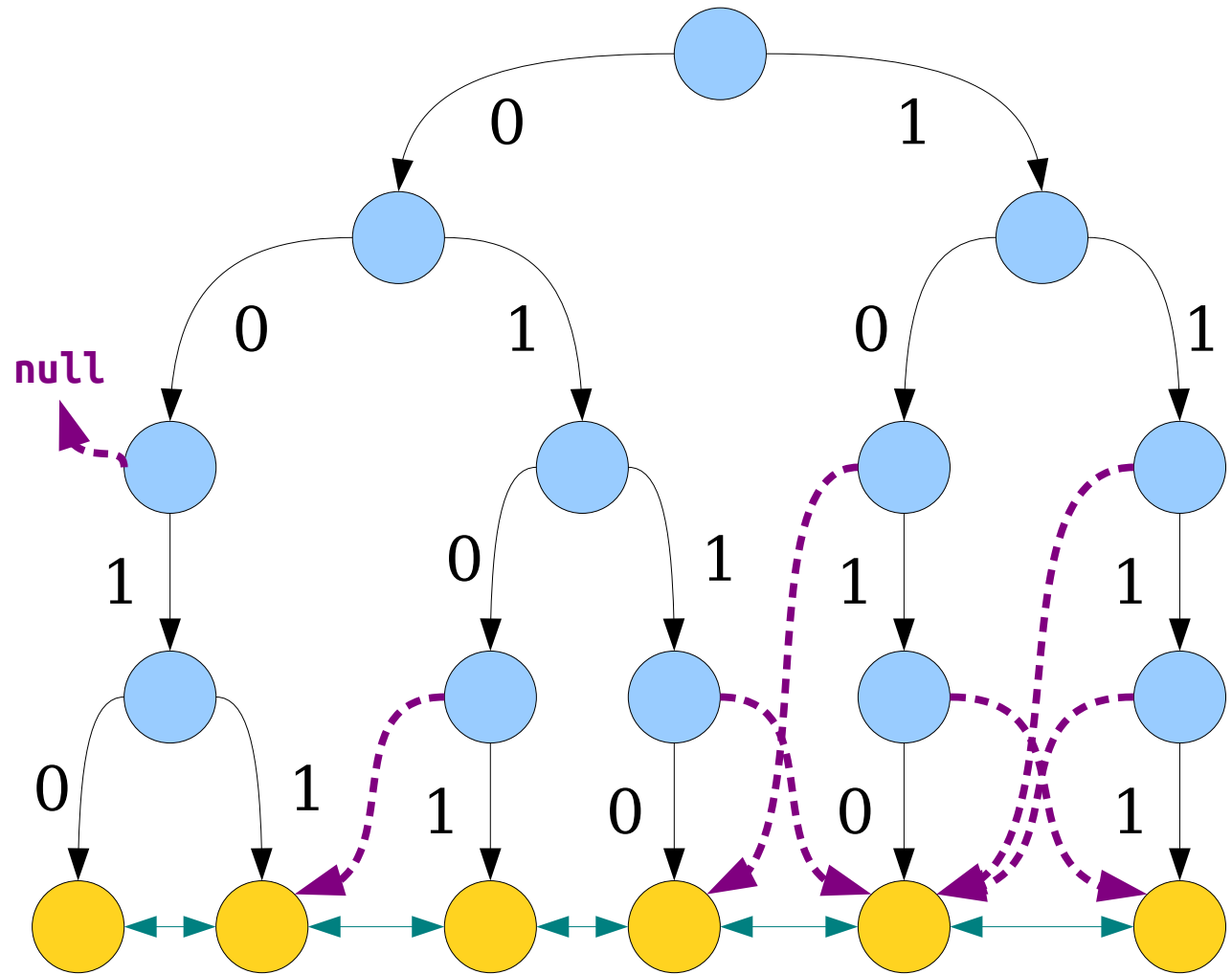
Finding Successors

- ***Claim:*** If the binary search terminates at a node v , that node must have at most one child.
- If it doesn't, it has both a 0 child and a 1 child, so there's a longer prefix that can be matched.
- ***Idea:*** Steal the missing pointers and use them to speed up successor and predecessor searches.



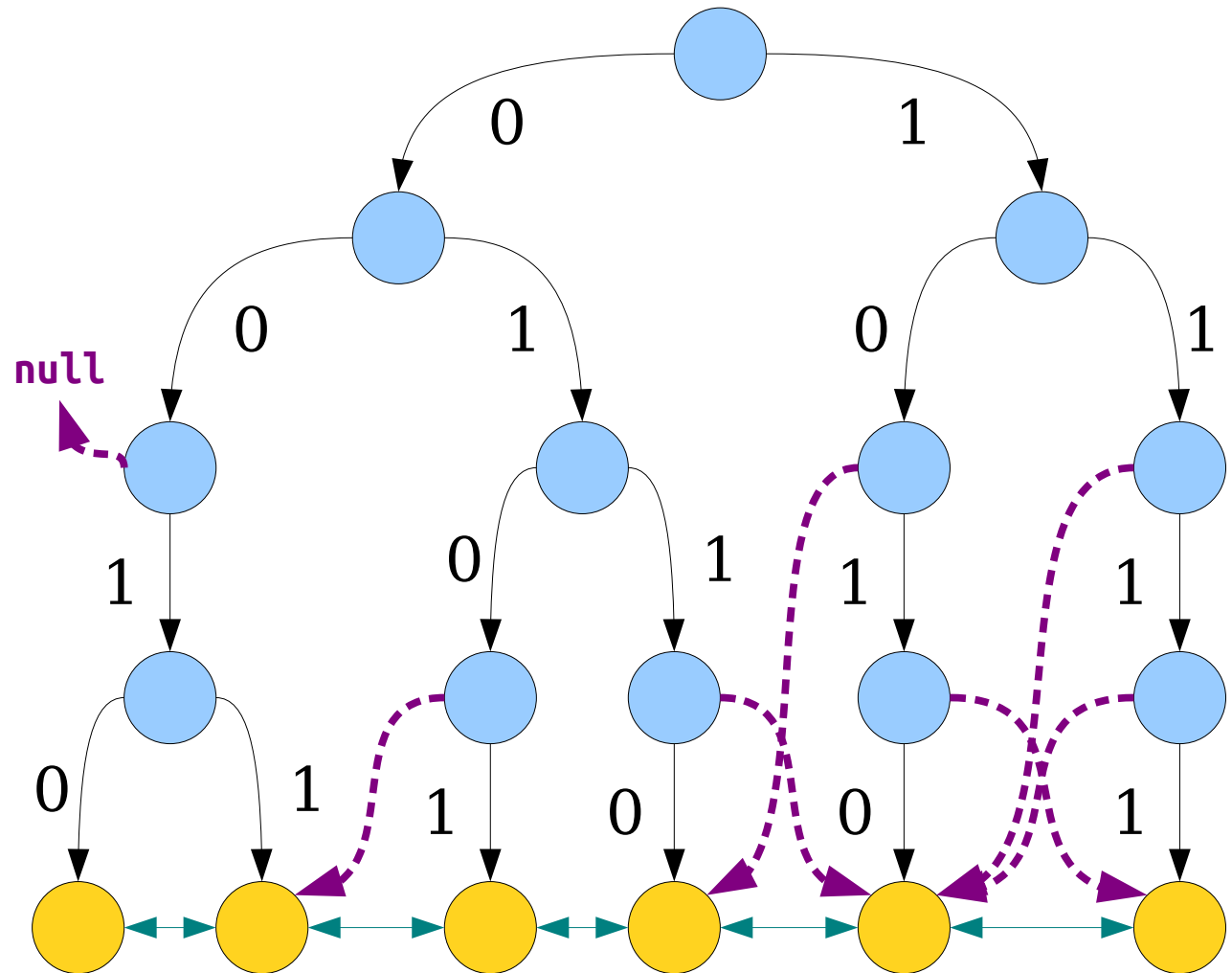
x-Fast Tries

- An **x-fast trie** is a modified binary trie.
- Each missing 1 pointer points to a node's successor.
- Each missing 0 pointer points to a node's predecessor.
- Each layer of the tree is stored in a cuckoo hash table for fast binary search.



x-Fast Tries

- **Claim:** Can determine **successor**(x) in time $O(\log w)$.
- Binary search for the longest prefix of x .
- If that node has a missing 1 pointer, it points to the successor.
- Otherwise, it has a missing 0 pointer. Follow it to a leaf, then follow the leaf's 1 pointer.

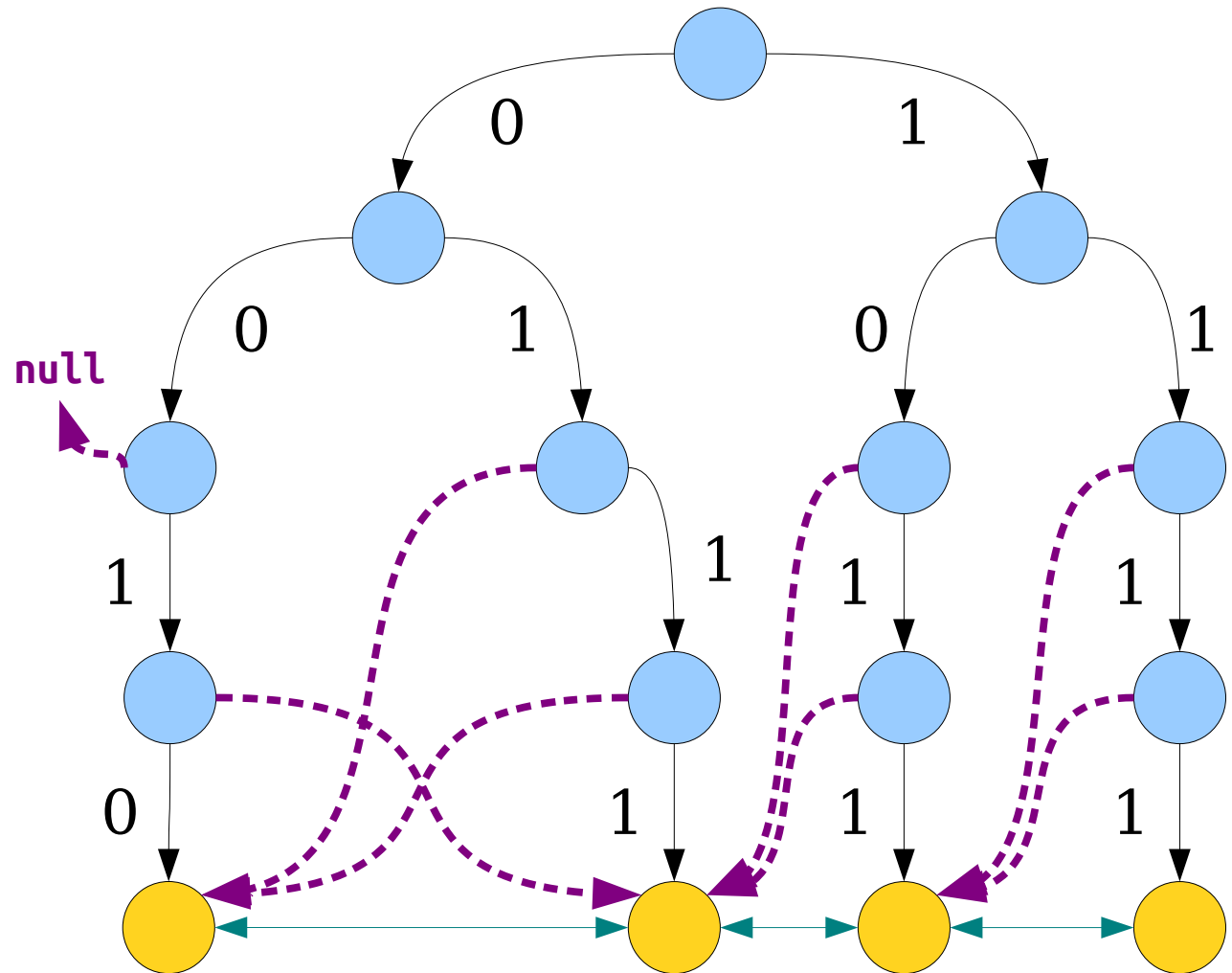


x-Fast Trie Maintenance

- Based on what we've seen:
 - *lookup* takes worst-case time $O(1)$.
 - *successor* and *predecessor* queries take worst-case time $O(\log w)$.
 - *min* and *max* can be done in time $O(1)$, assuming we cache those values.
- How efficiently can we support *insert* and *delete*?

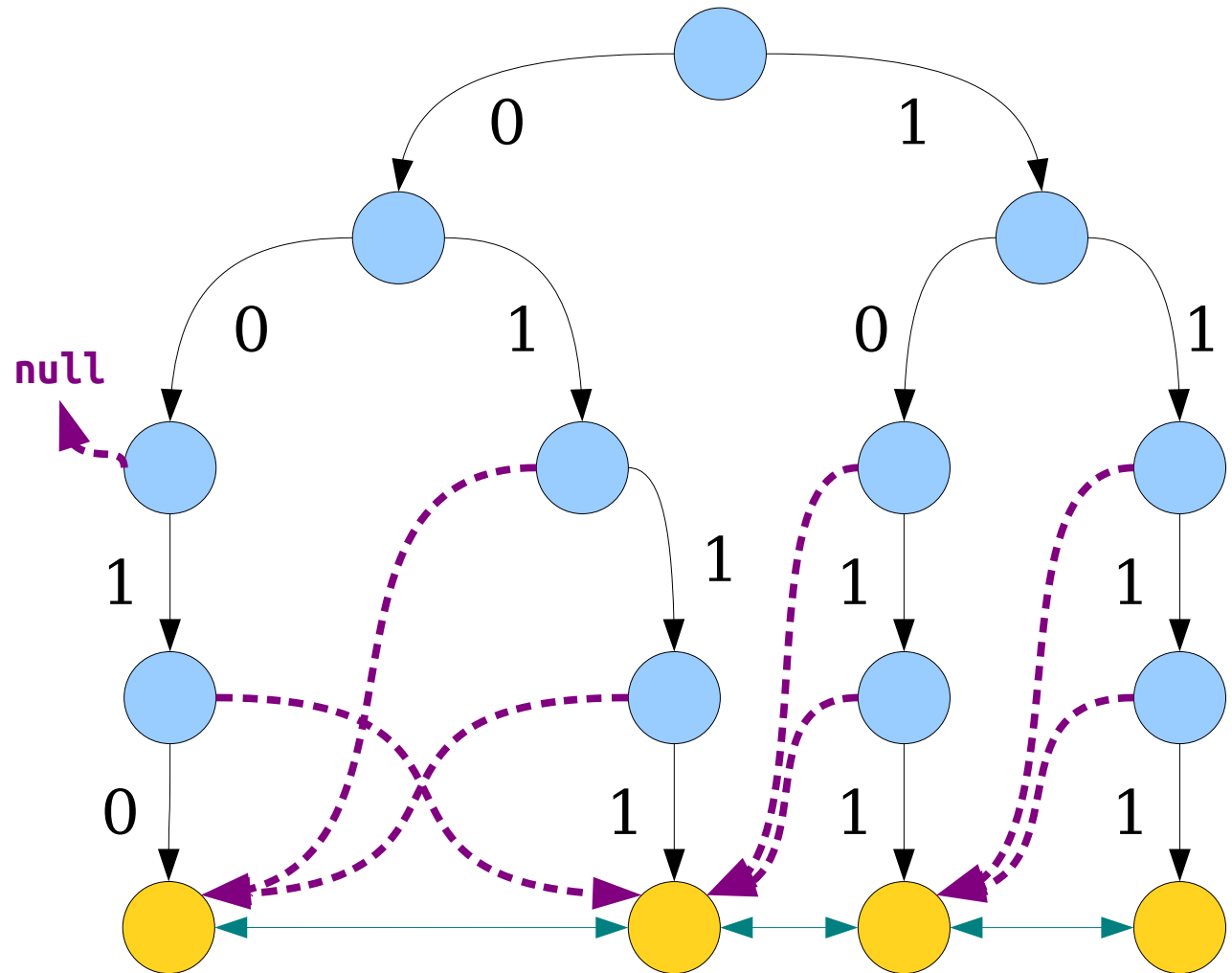
x-Fast Tries

- If we *insert*(x), we need to
 - add some new nodes to the trie;
 - wire x into the doubly-linked list of leaves; and
 - update the thread pointers to include x .
- Worst-case will be $\Omega(w)$ due to the first and third steps.



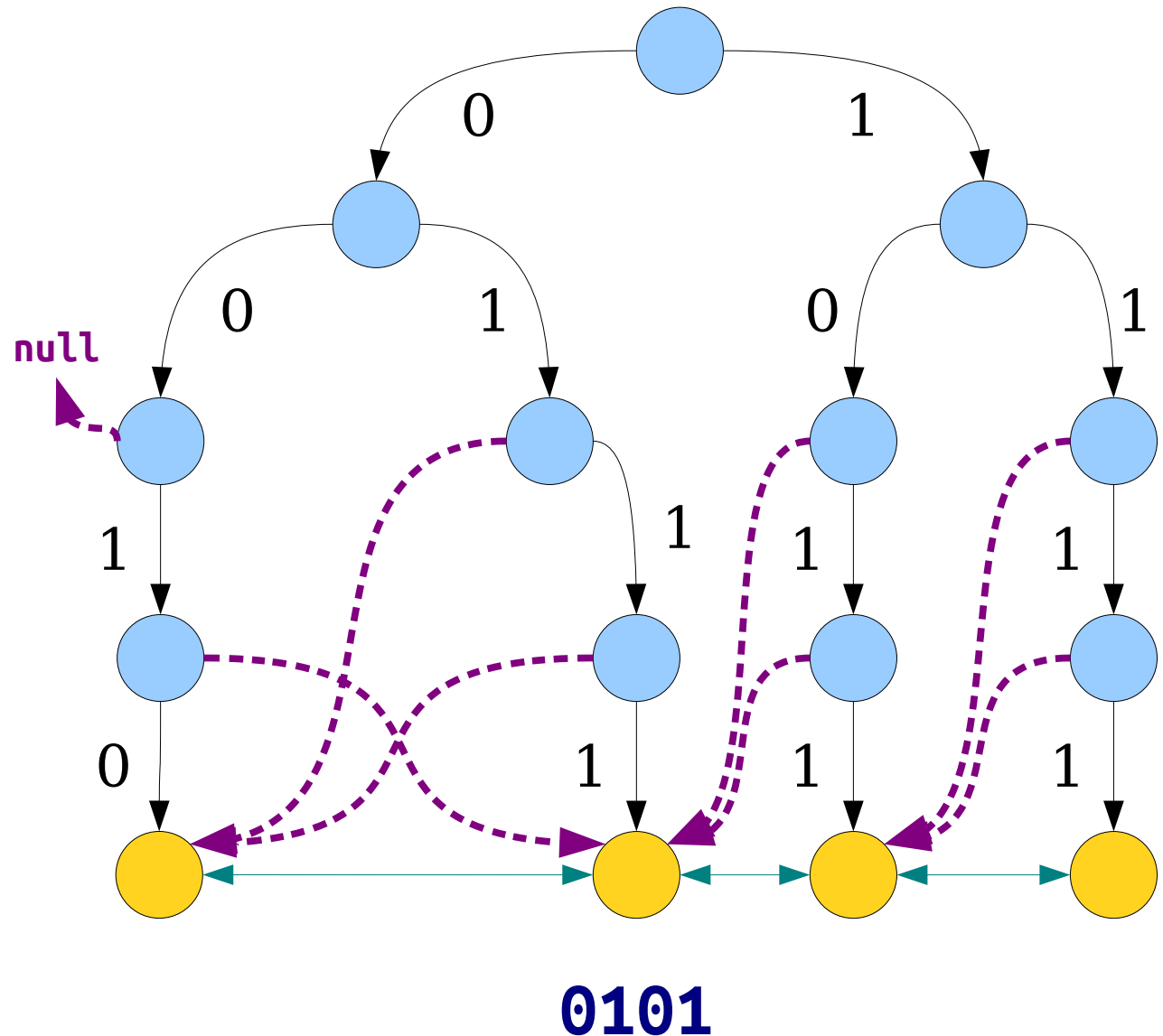
x-Fast Tries

- Here is an (amortized, expected) $O(w)$ -time algorithm for *insert*(x):
 - Find *successor*(x).
 - Add x to the trie.
 - Using the successor from before, wire x into the linked list.
 - Walk up from x , its successor, and its predecessor and update threads.



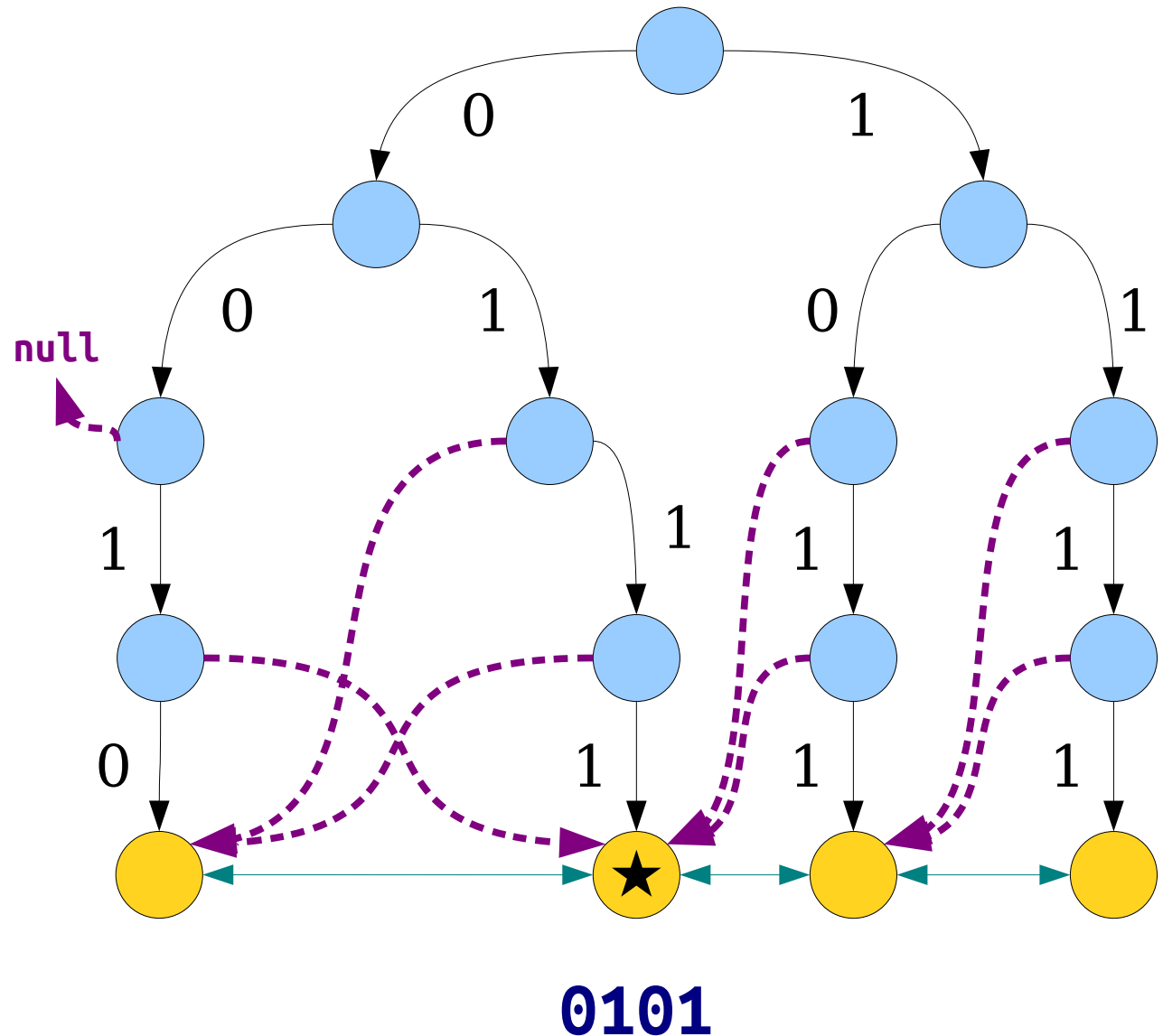
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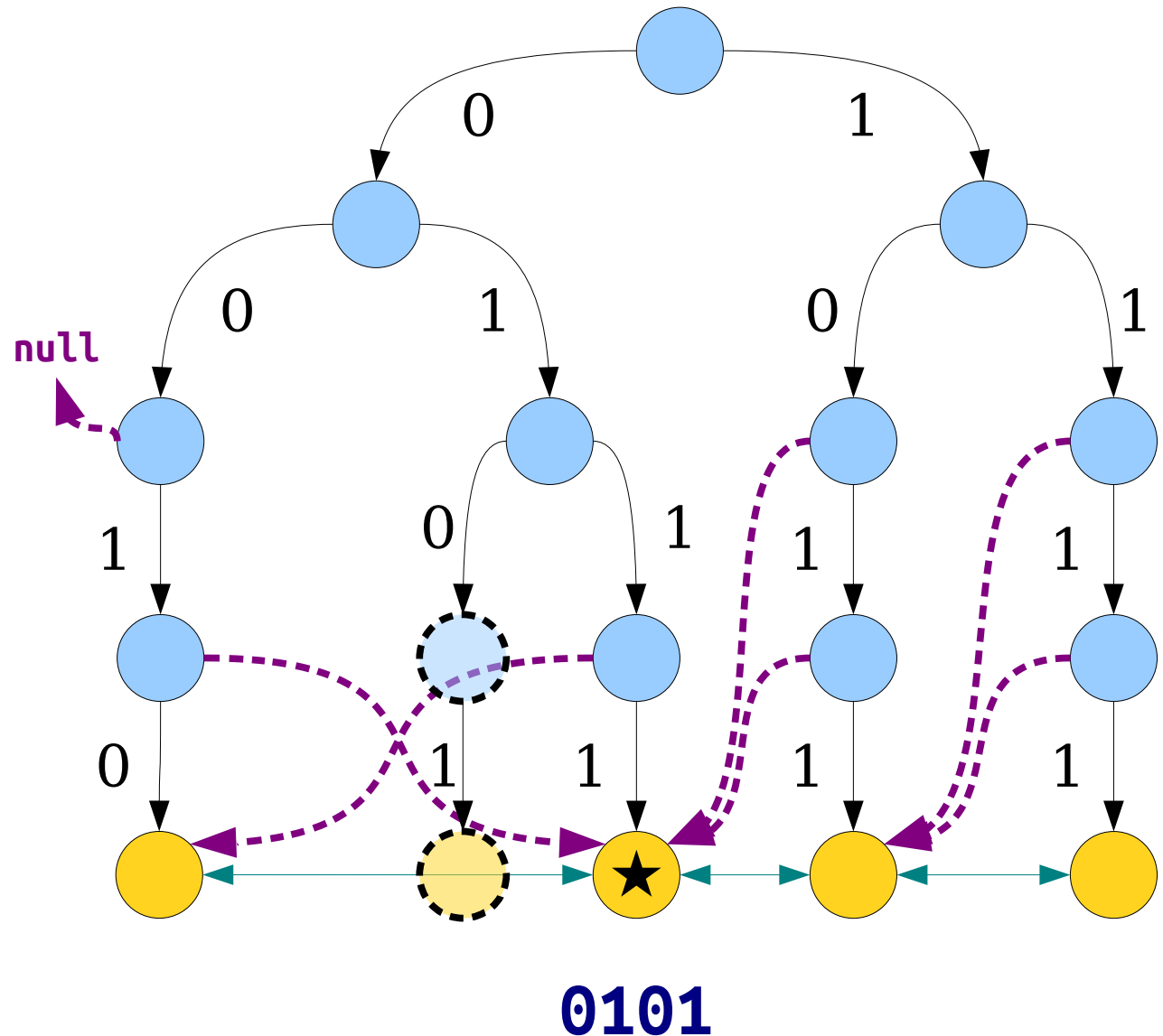
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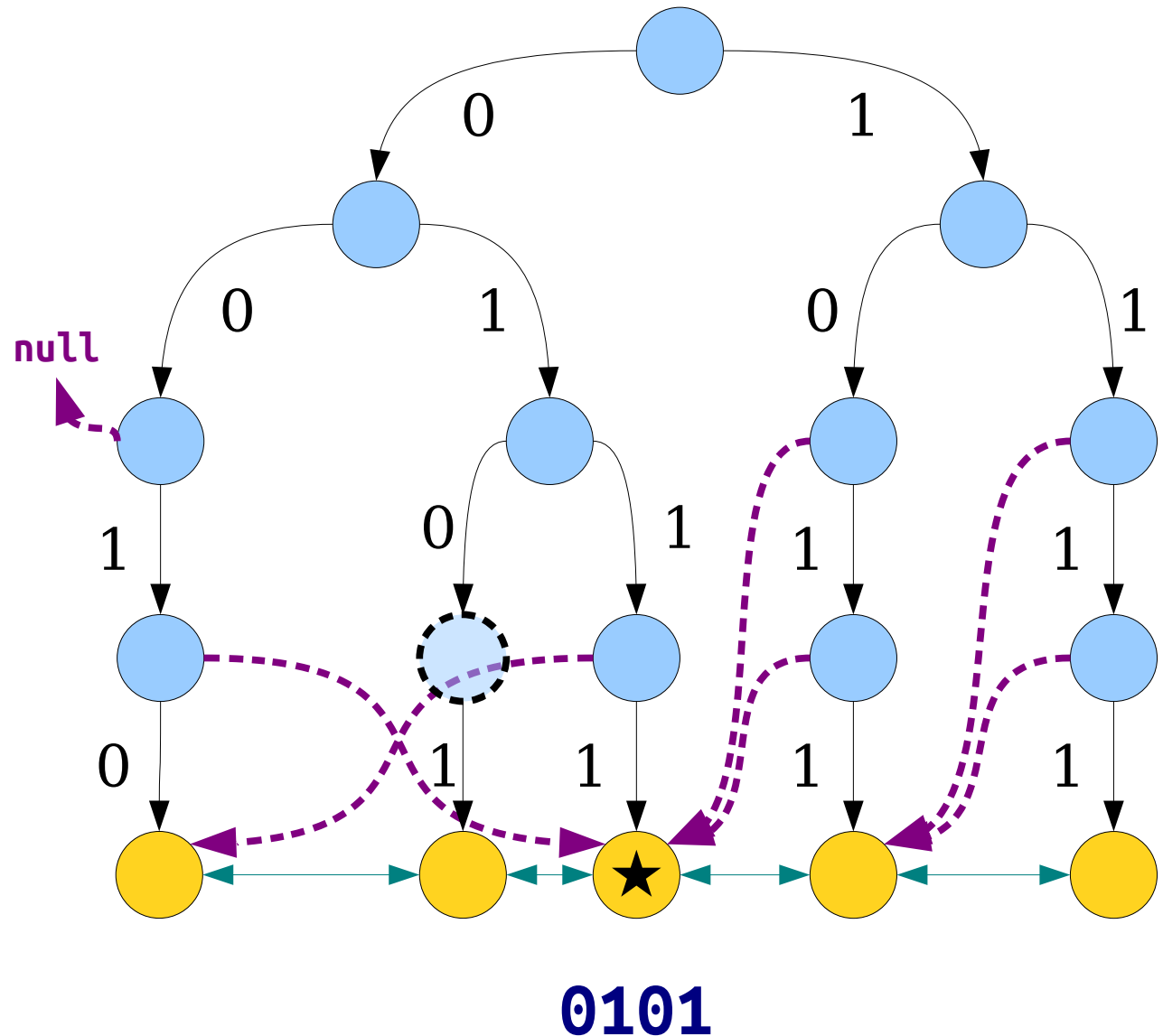
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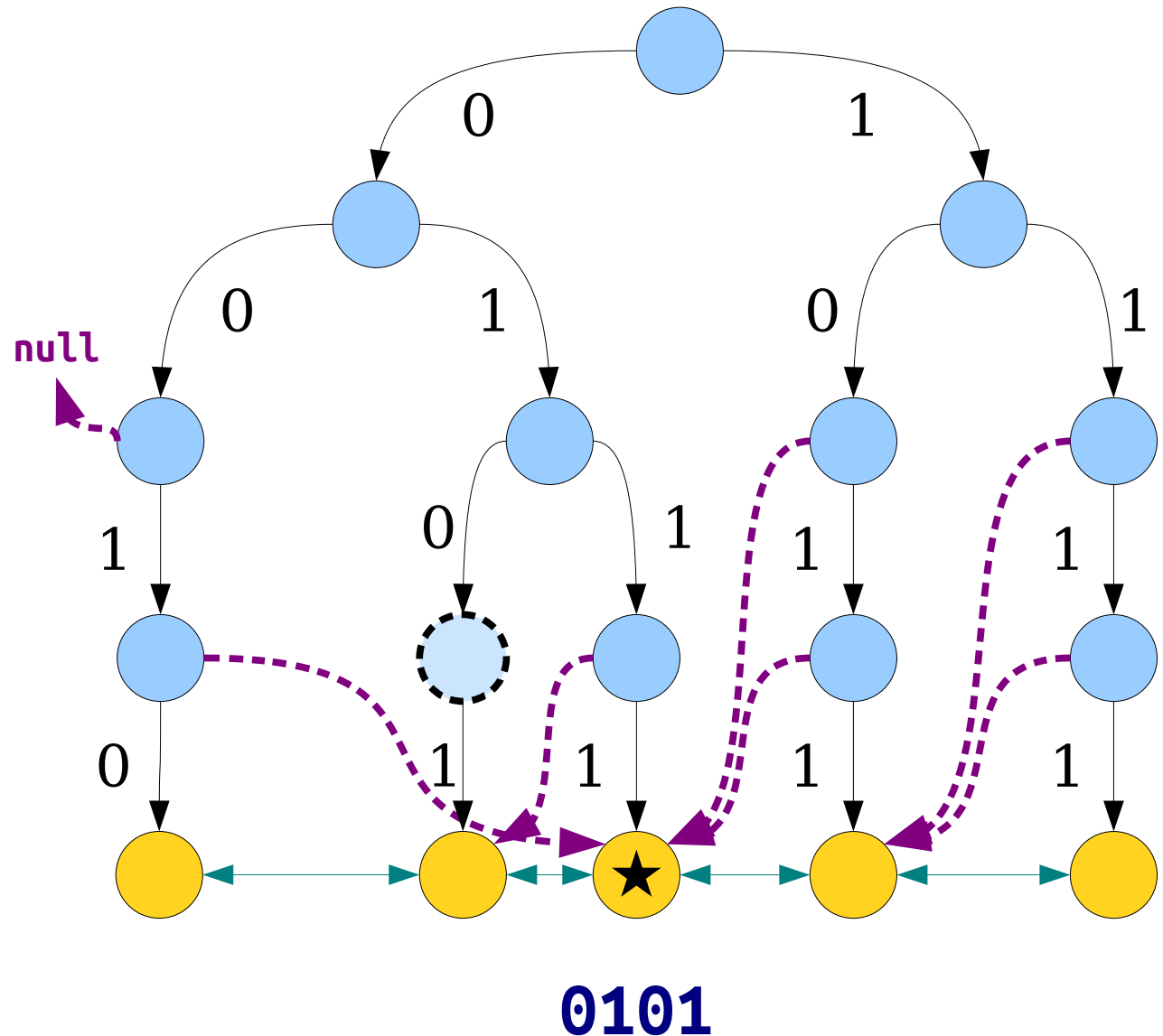
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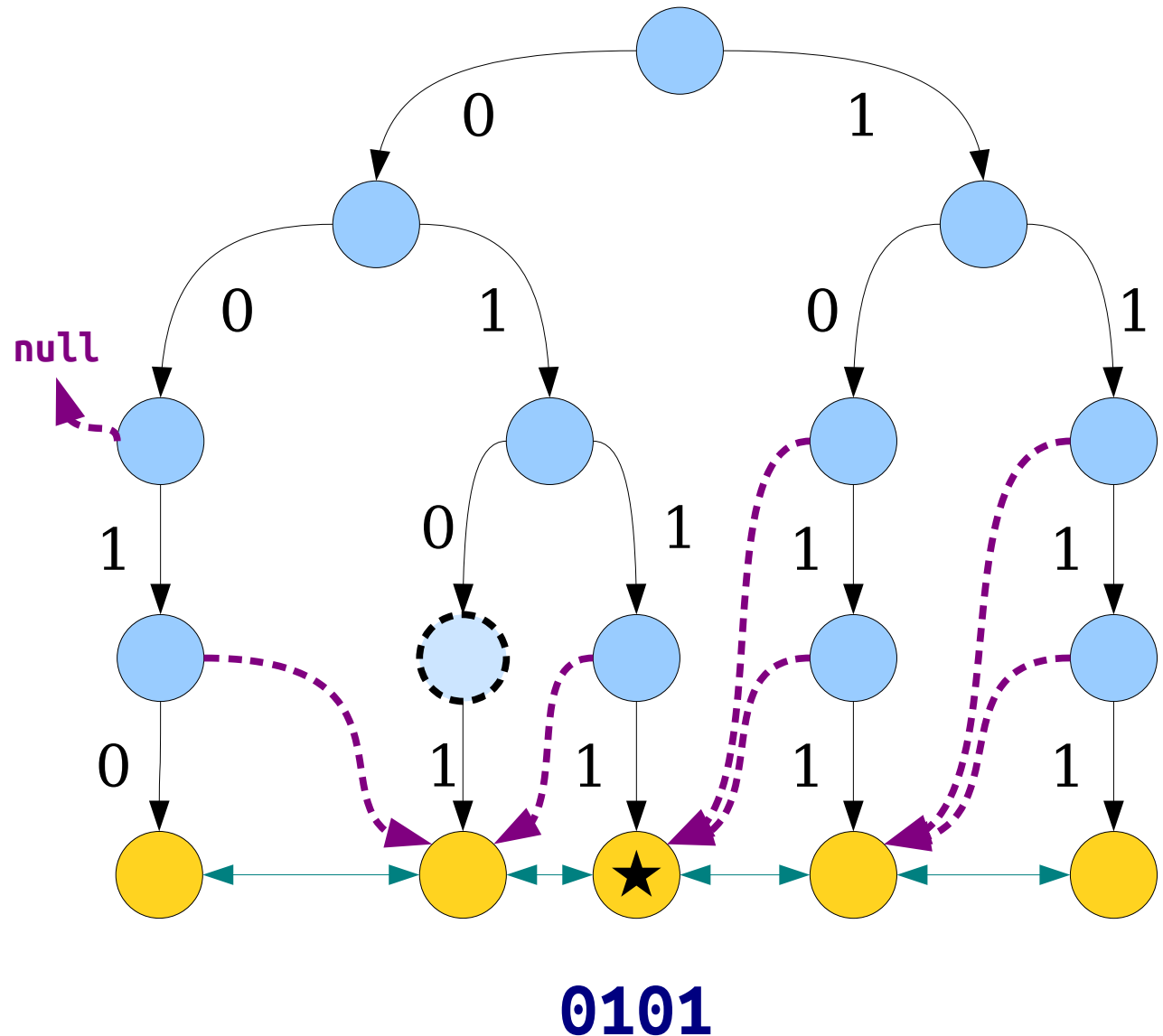
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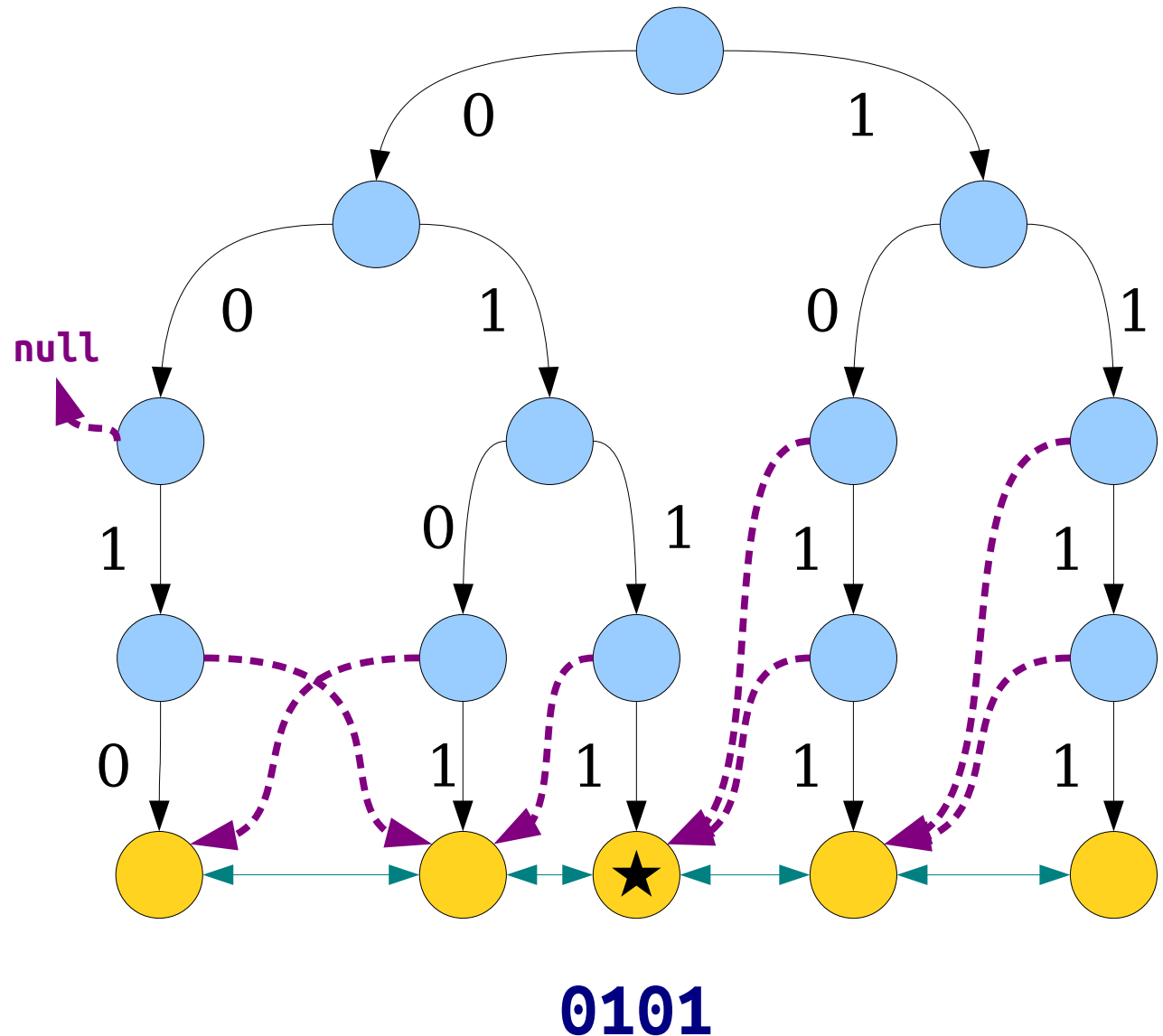
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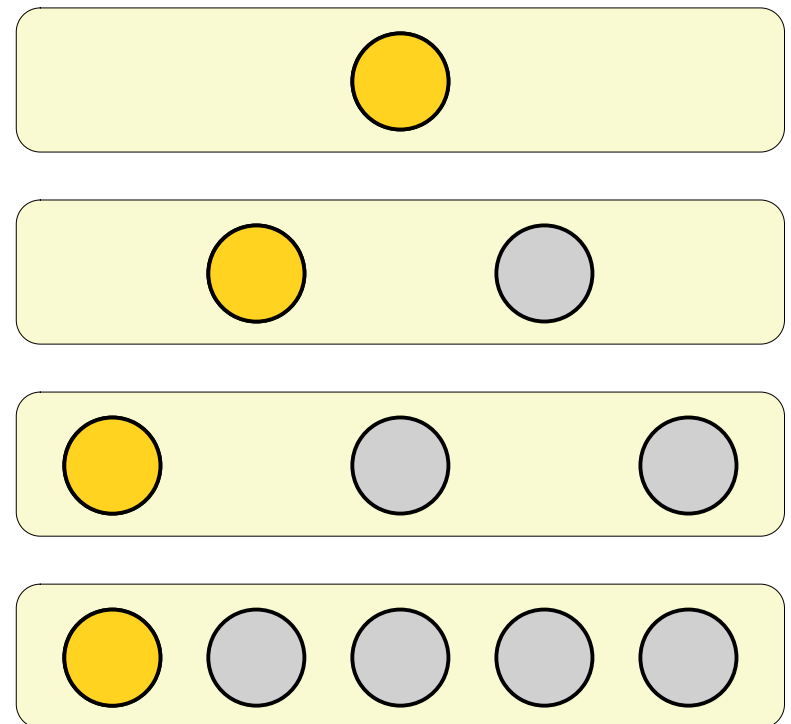
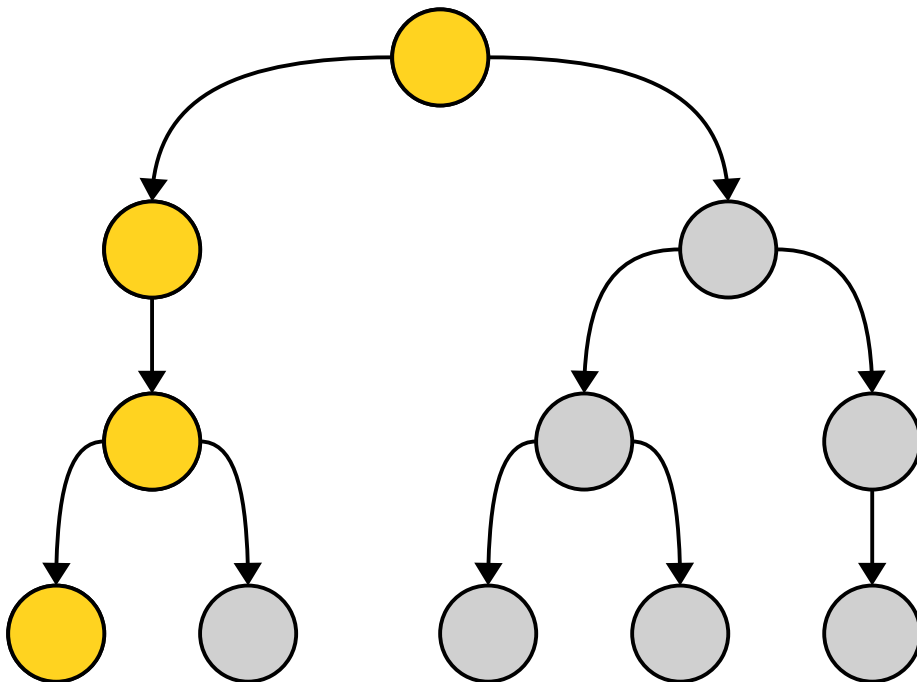


Deletion

- To *delete*(x), we need to
 - Remove x from the trie.
 - Splice x out of its linked list.
 - Update thread pointers from x 's former predecessor and successor.
- Runs in expected, amortized time $O(w)$.
- Full details are left as a proverbial Exercise to the Reader. ☺

Space Usage

- Each leaf node (item stored in the x-fast trie) contributes at most $O(w)$ nodes in the trie and at most $O(w)$ entries into the hash tables.
- Total space: **$O(nw)$** .



Where We Stand

- Right now, we have a reasonably fast data structure for storing a sorted set of integers.
- If we have a *static* set of integers that we want to make lots of queries on, this is pretty good as-is!
- As you'll see, though, we can make this even better with some kitchen sink techniques.

x-Fast Trie:

- **lookup**: $O(1)$
- **insert**: $O(w)^*$
- **delete**: $O(w)^*$
- **max**: $O(1)$
- **succ**: $O(\log w)$
- **is-empty**: $O(1)$
- Space: $O(nw)$

* Expected, amortized

Where We Stand

- Where is there room for improvement in this data structure?
- Ideally, we'd like to improve these highlighted costs, which are places where this structure currently is beaten by a standard BST.

x-Fast Trie:

- *lookup*: $O(1)$
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* Expected, amortized

Shaving Off Logs

- We're essentially at a spot where we need to shave off a factor of w from a couple of operations.
- Figure that w is kinda sorta ish like $\log n$, so this is like shaving off a log factor.
- **Question:** What techniques have we developed so far to do this?

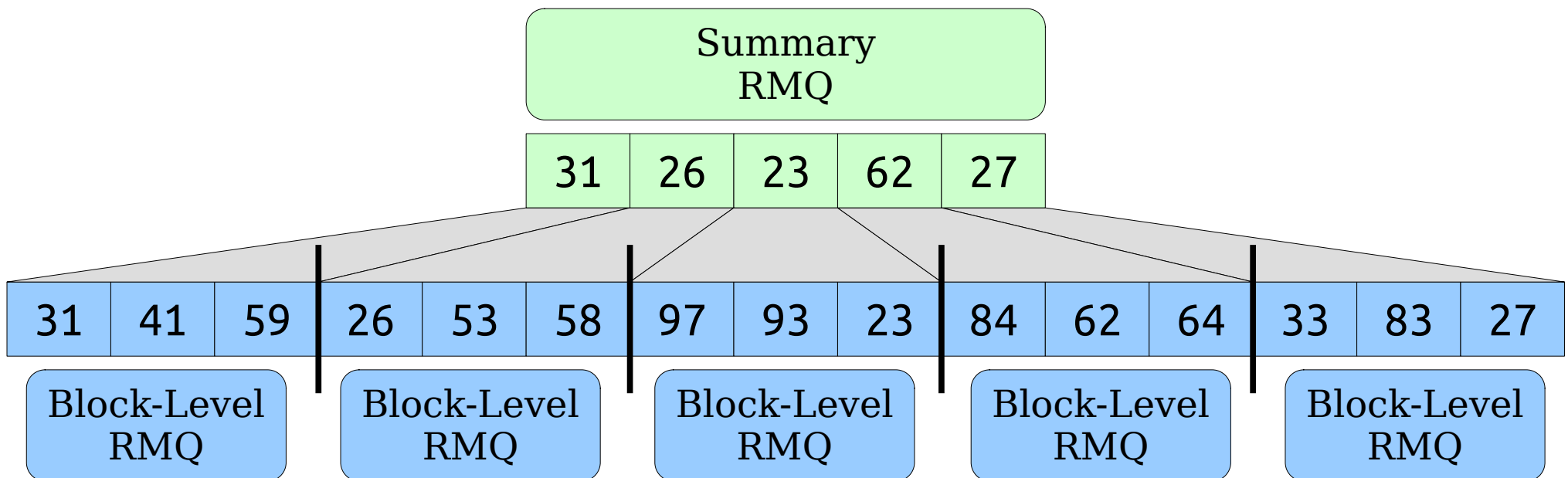
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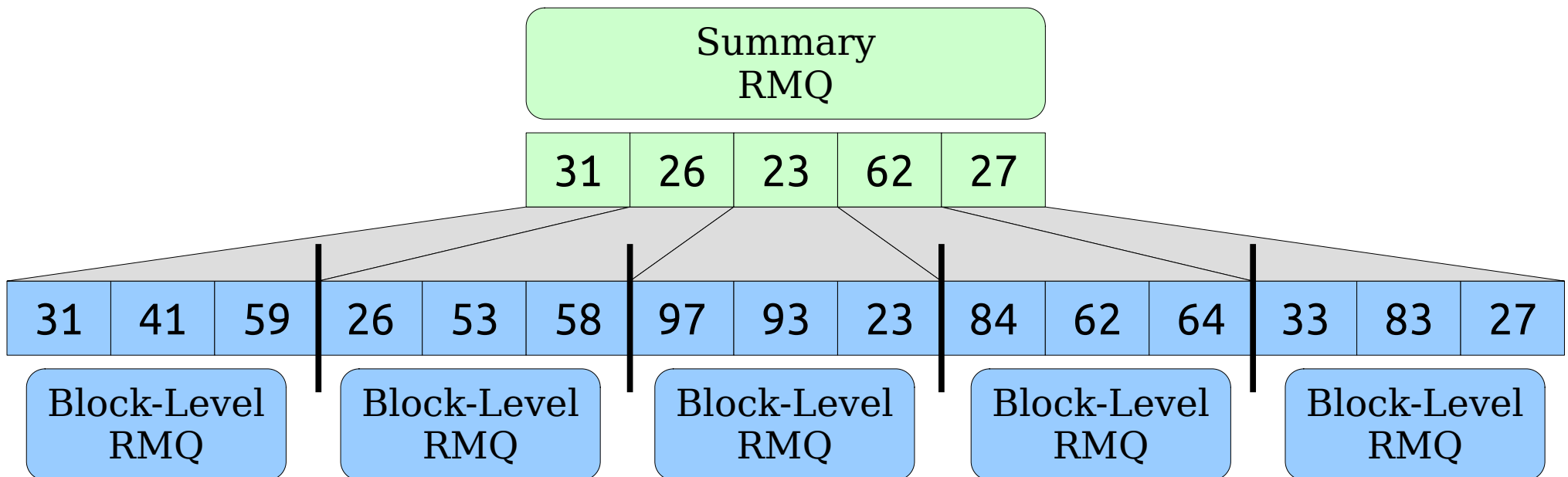
Two-Level Structures

- Think back to the hybrid approach we used for solving RMQ.
- It consisted of a two-tiered structure:
 - A bunch of small, lower-level structures that each solve the problem in small cases.
 - A single, larger, top-level structure that helps aggregate those solutions together.



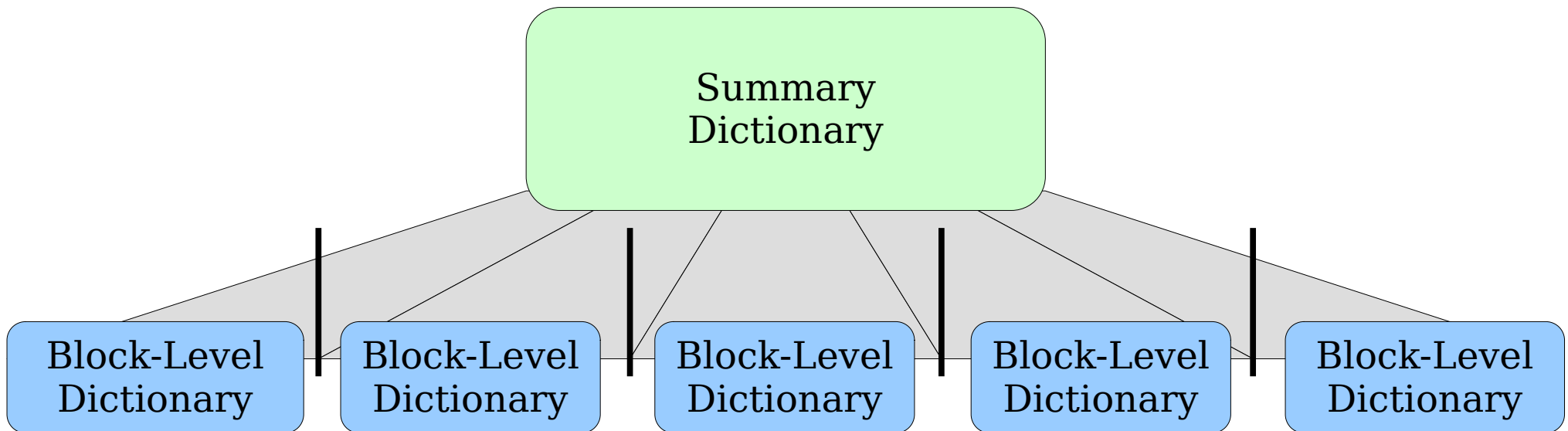
Two-Level Structures

- **Main Idea:** Partition the input into blocks that are really, really small.
- Small blocks make the block-level structures run quickly.
- Assuming they're not “too small,” small blocks reduce the size of the inputs to the summary as well.



The Idea

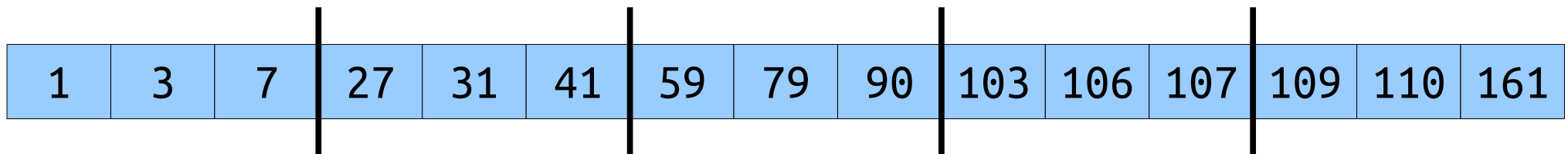
- Build a two-level ordered dictionary out of existing ordered dictionaries.
- Split the keys apart into logarithmic-sized blocks.
- Build ordered dictionaries for each of the block-level dictionaries.
- Build a summary dictionary to aggregate the blocks together.



The y -Fast Trie

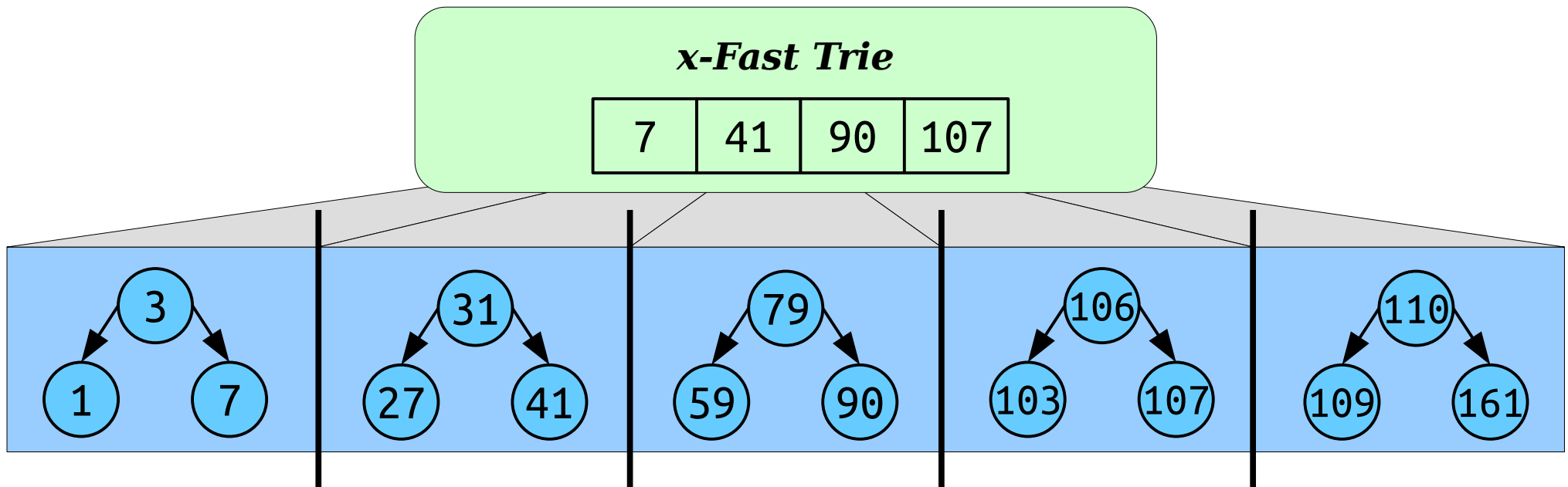
The Setup

- For now, assume all keys are given to us in advance, in sorted order.
- Split the keys apart into blocks of size $\Theta(w)$ and store them in balanced BSTs.



The Setup

- For now, assume all keys are given to us in advance, in sorted order.
- Split the keys apart into blocks of size $\Theta(w)$ and store them in balanced BSTs.
- Create a summary x-fast trie that stores the maximum key from each block but the last.

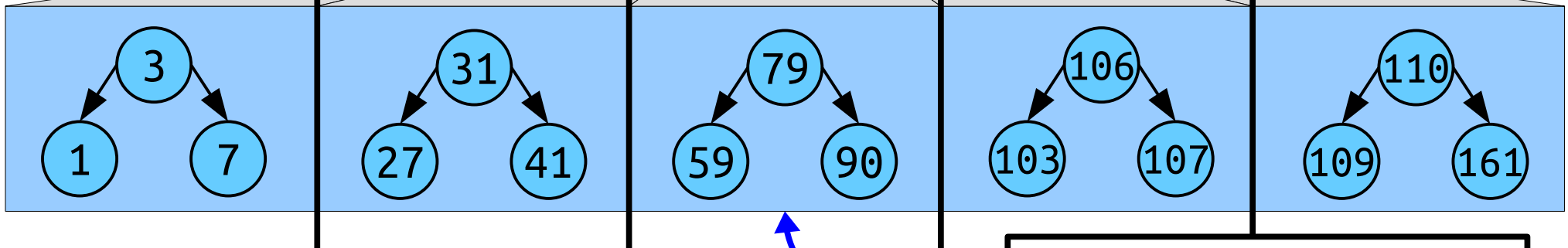


The Setup

This summary structure is used for **routing information** so we know which BSTs to look at.

x-Fast Trie

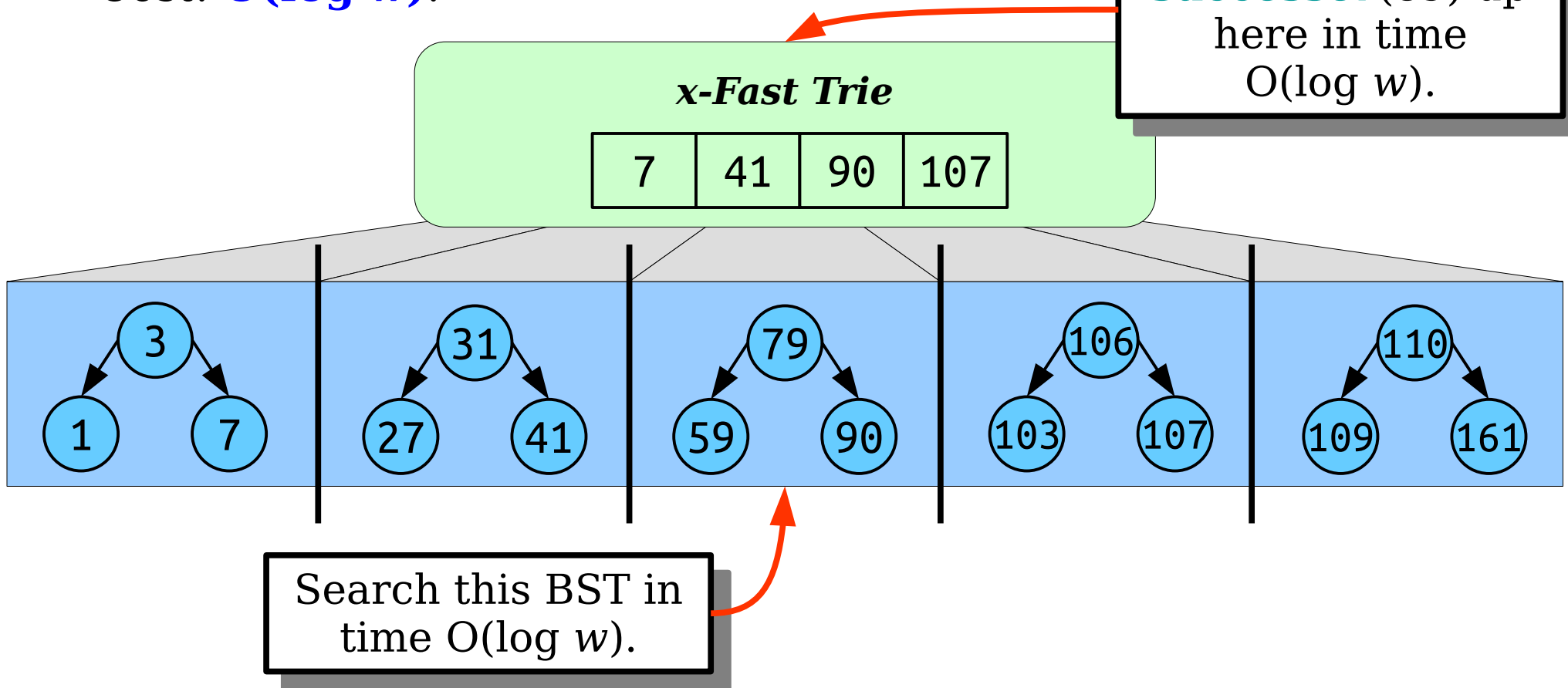
7	41	90	107
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These trees are used for **storage** of the actual items.

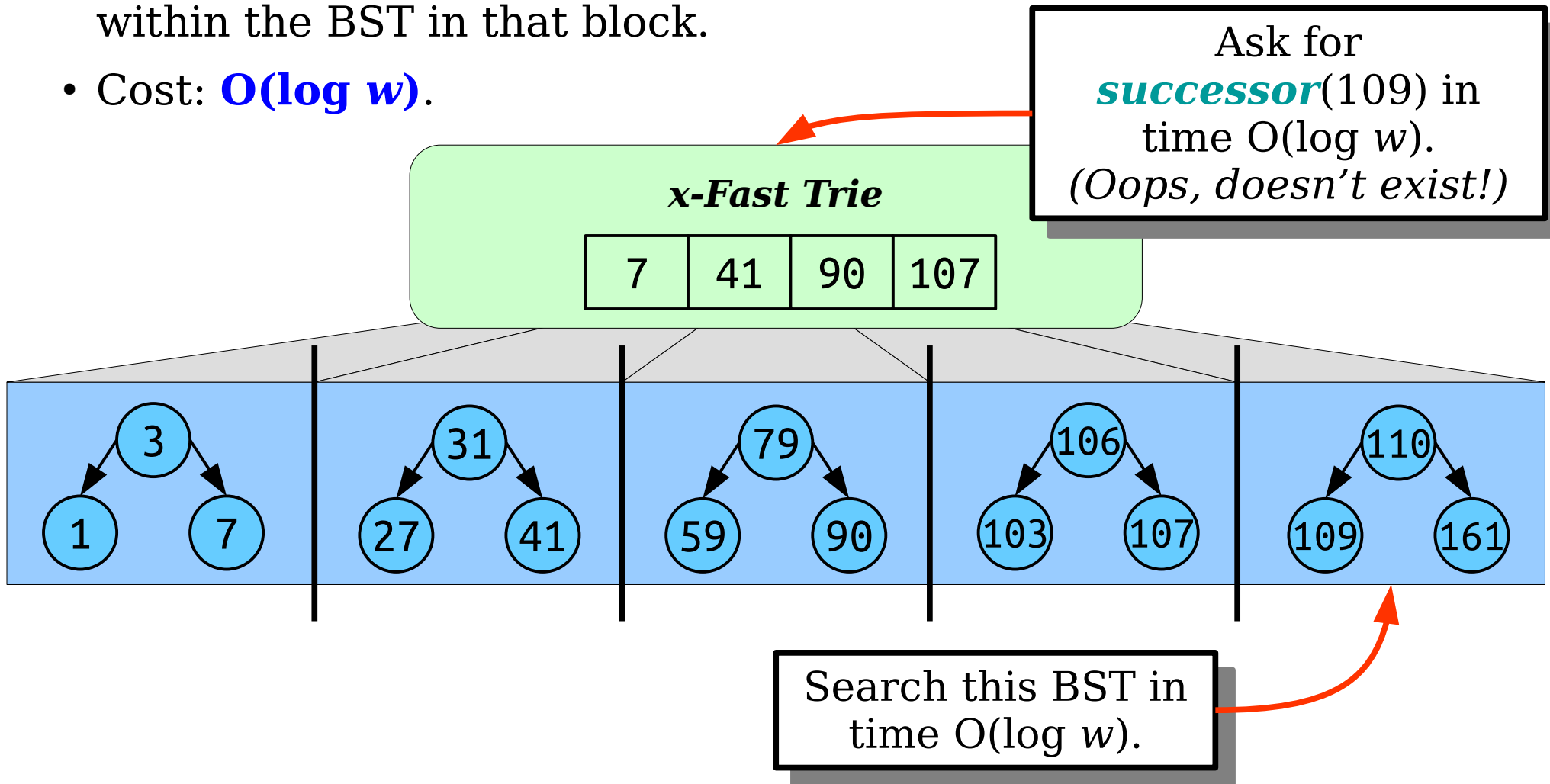
Performing a Lookup

- Suppose we want to perform *lookup*(90).
- **Idea:** figure out which block 90 would belong to, then search within the BST in that block.
- Cost: **$O(\log w)$** .



Performing a Lookup

- Suppose we want to perform **lookup**(110).
- **Idea**: figure out which block 109 would belong to, then search within the BST in that block.
- Cost: **$O(\log w)$** .



Successor Queries

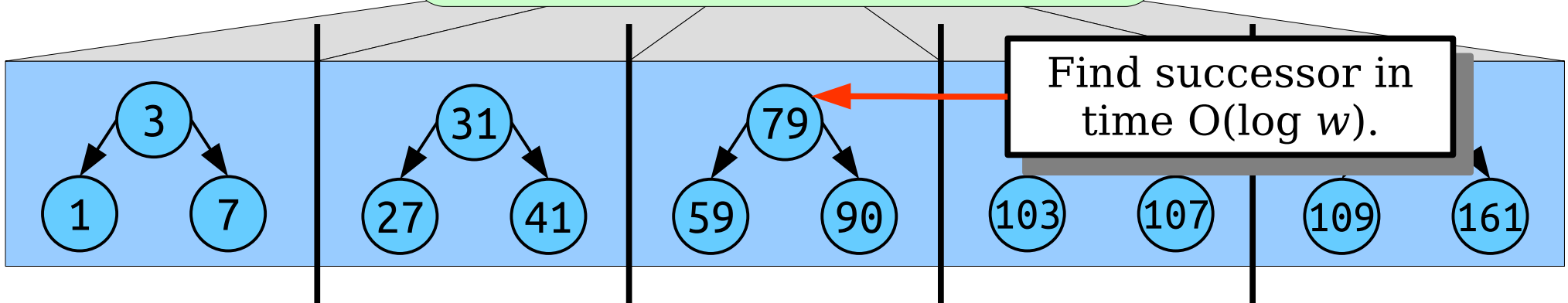
- How might we perform *successor* queries?
- Here's how we'd determine *successor*(59).

Ask for
successor(58) up
here in time
 $O(\log w)$.

x-Fast Trie

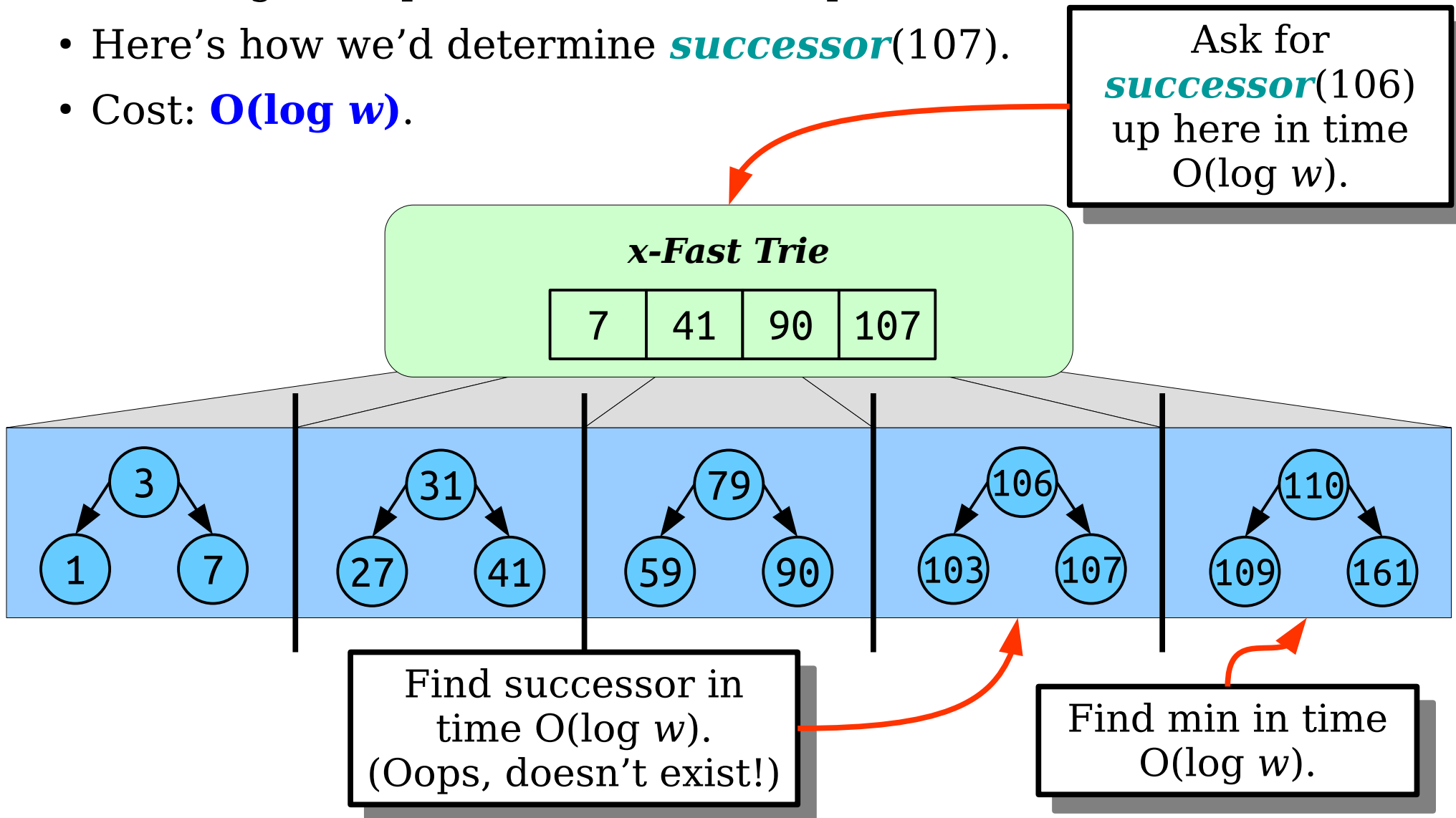
7	41	90	107
---	----	----	-----

Find successor in
time $O(\log w)$.



Successor Queries

- How might we perform *successor* queries?
- Here's how we'd determine *successor*(107).
- Cost: $O(\log w)$.

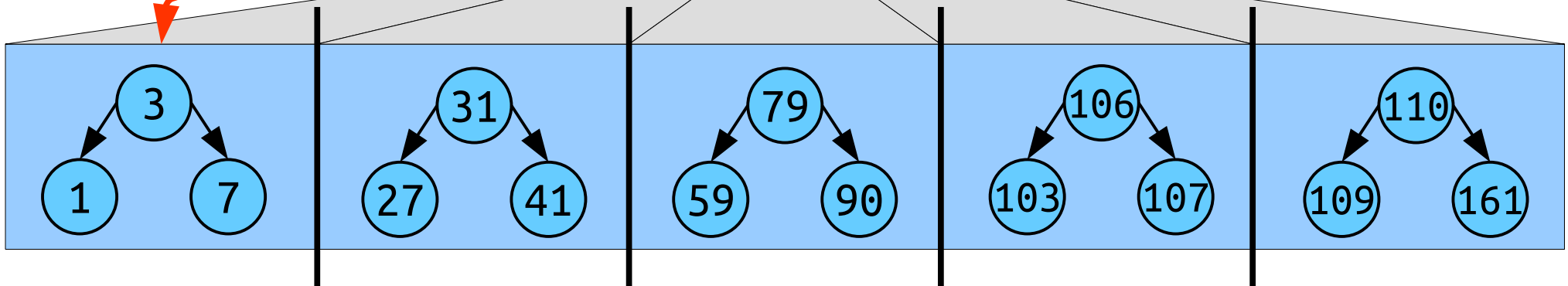
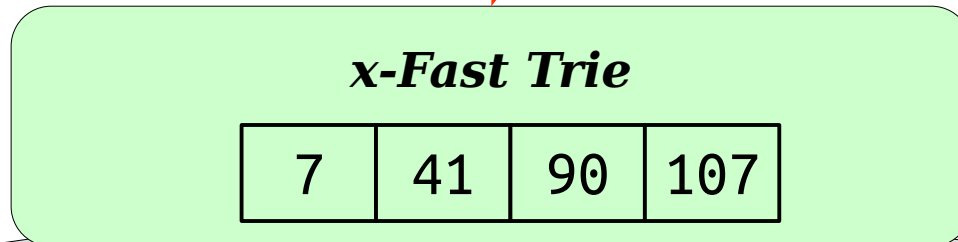


Making Edits

- With a major caveat, insertions follow the same procedure as before.
- Here's how we'd *insert*(6)

insert into this
BST in time
 $O(\log w)$

Ask for
successor(5) in
time $O(\log w)$.

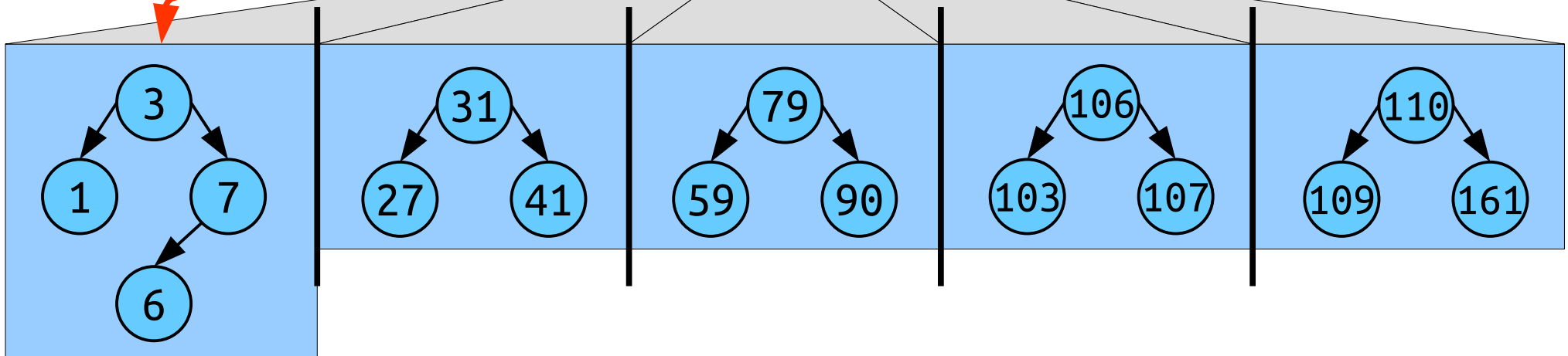
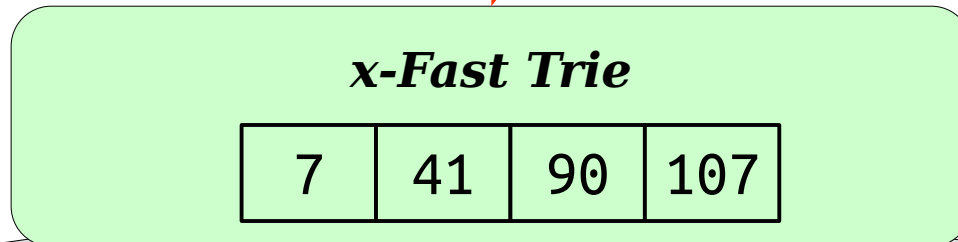


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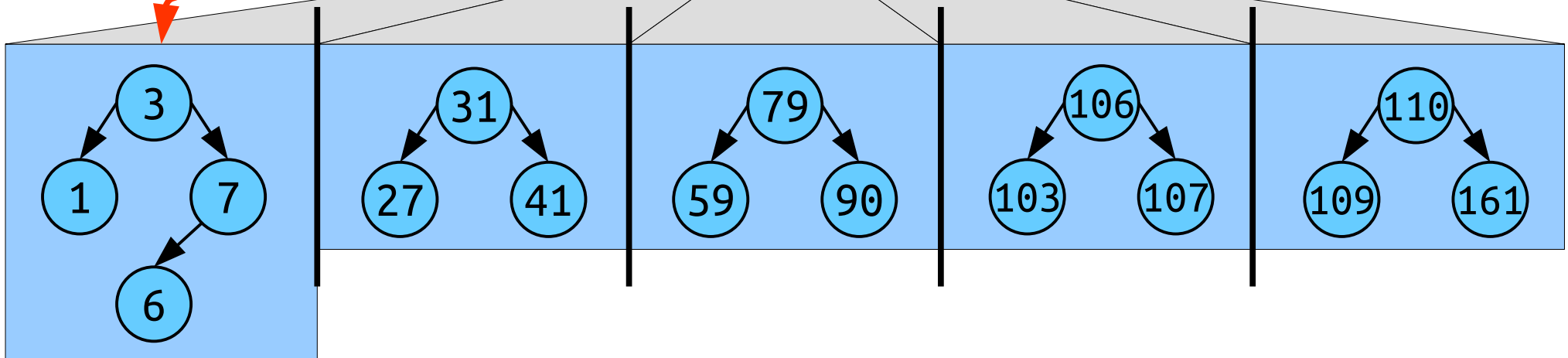
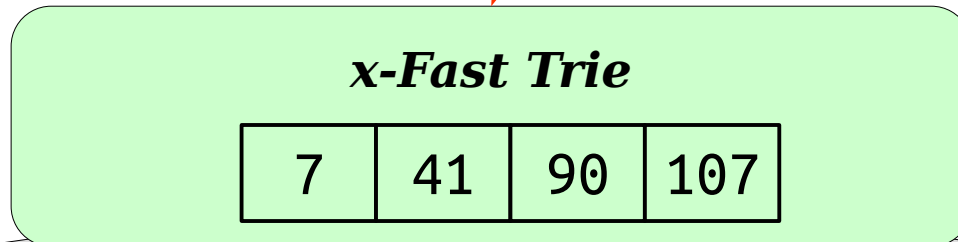


Making Edits

- With a major caveat, insertions follow the same procedure as before.
- Here's how we'd *insert*(4)

insert into this
BST in time
 $O(\log w)$

Ask for
successor(3) in
time $O(\log w)$.

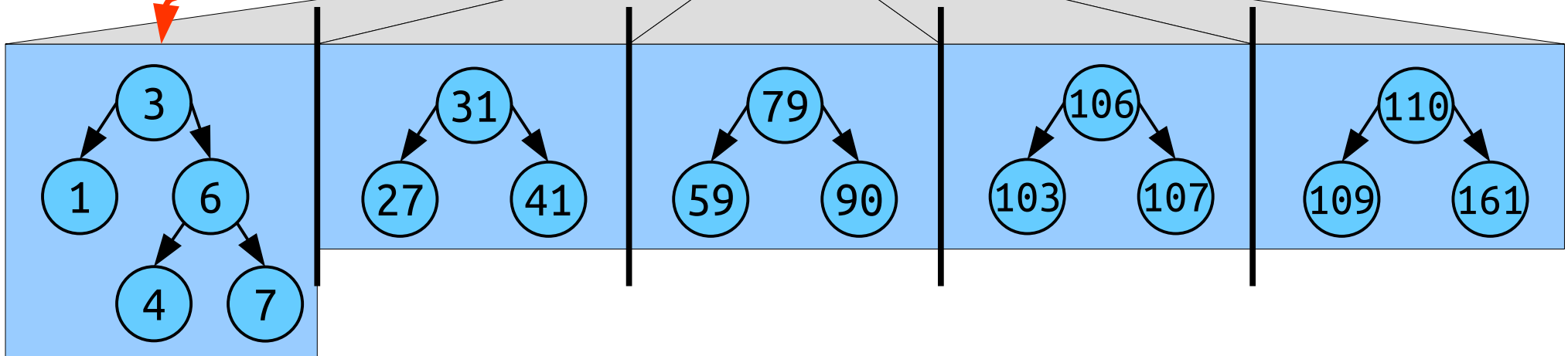
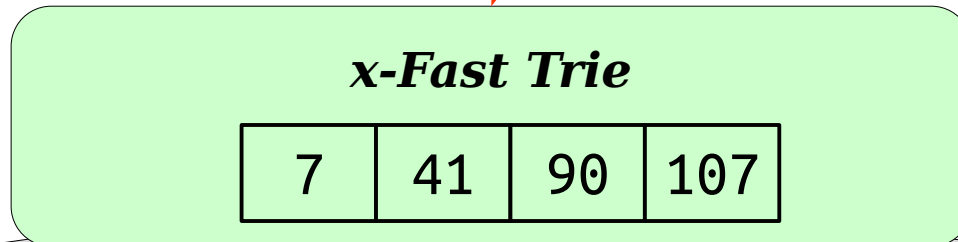


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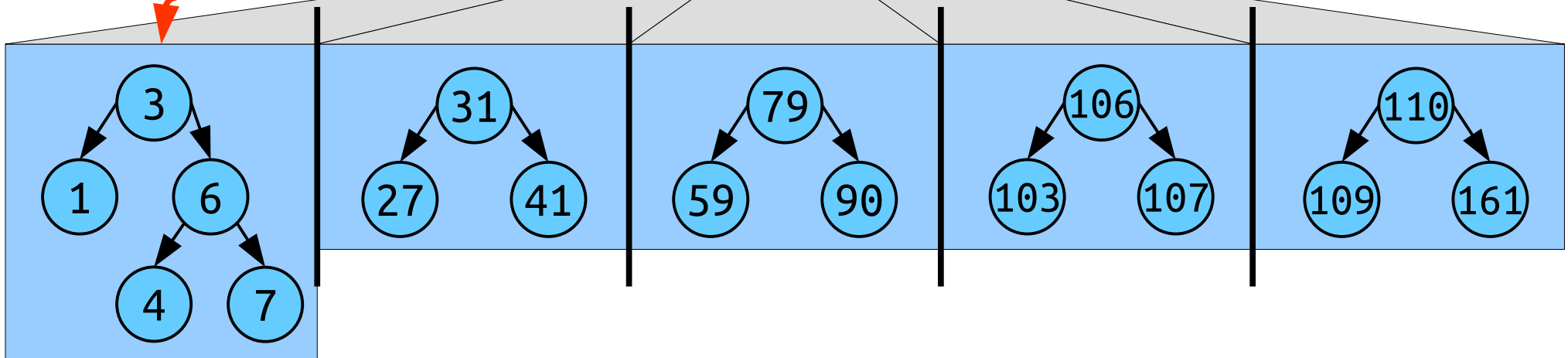
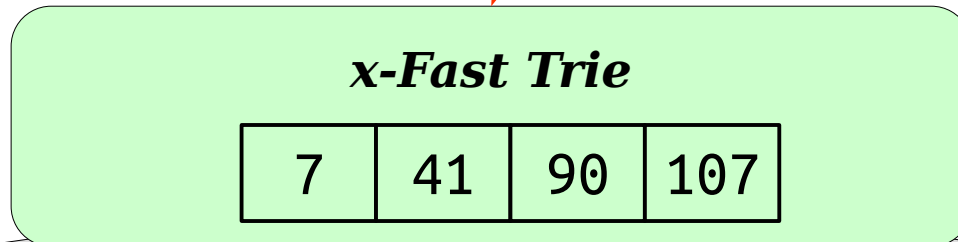


Making Edits

- With a major caveat, insertions follow the same procedure as before.
- Here's how we'd *insert*(2)

insert into this
BST in time
 $O(\log w)$

Ask for
successor(1) in
time $O(\log w)$.

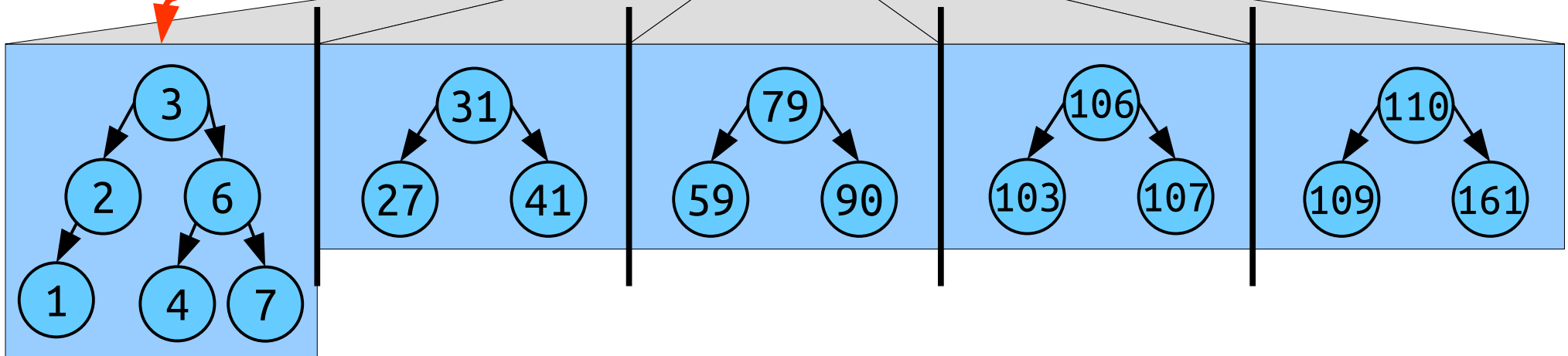
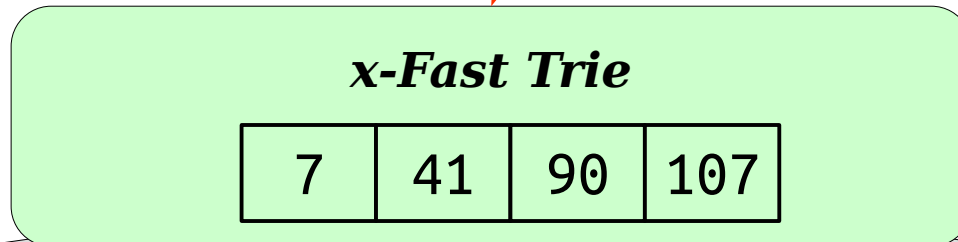


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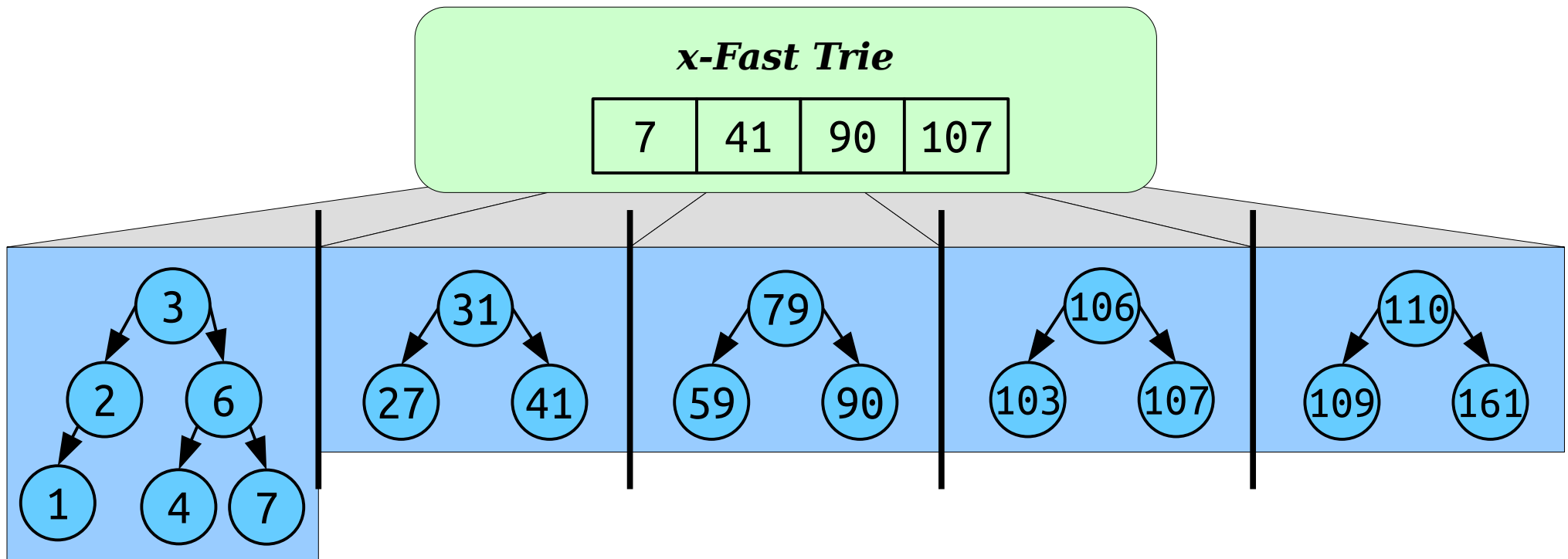
insert into this
BST in time
 $O(\log w)$

Ask for
successor(1) in
time $O(\log w)$.



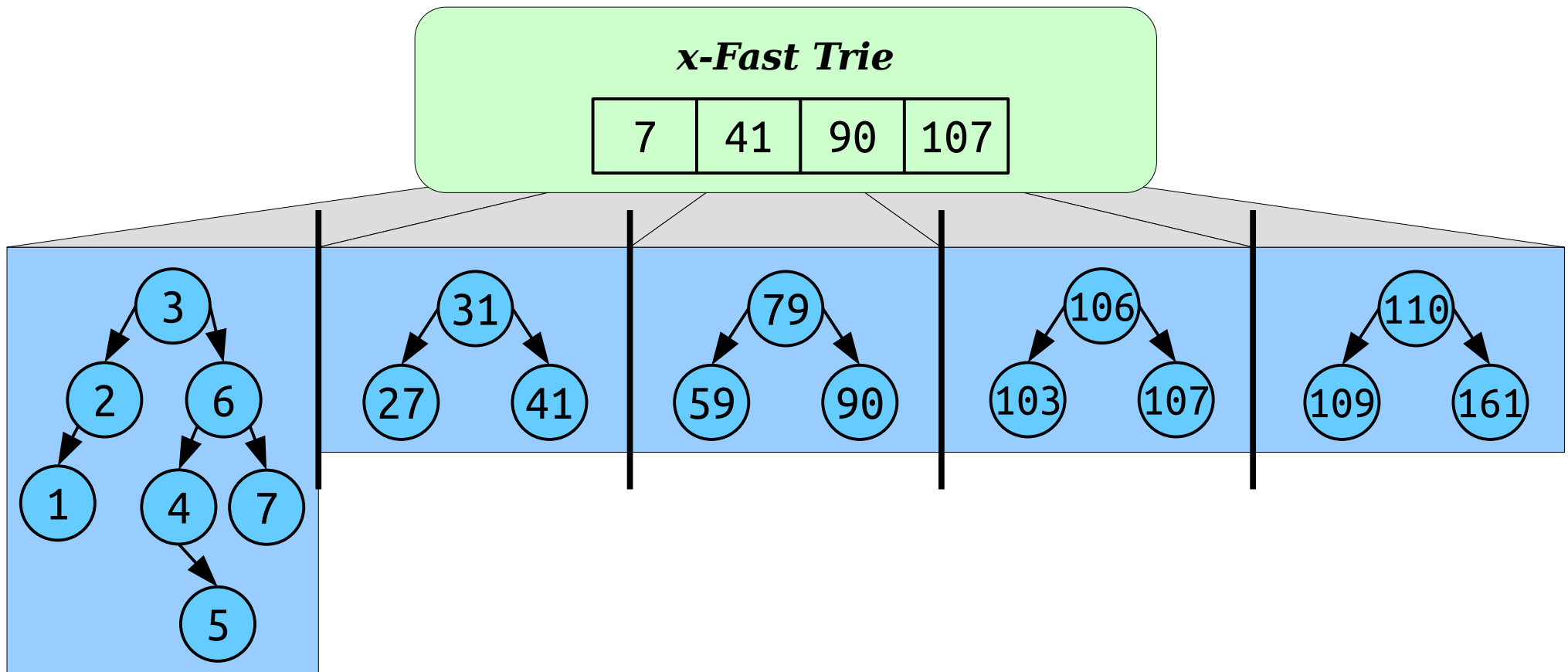
The Problem

- If our trees get too big, we may lose our $O(\log w)$ time bound. (*Why?*)
- **Idea:** Require each tree to have at most $2w$ elements. If it gets too big, split it and update the x-fast trie.



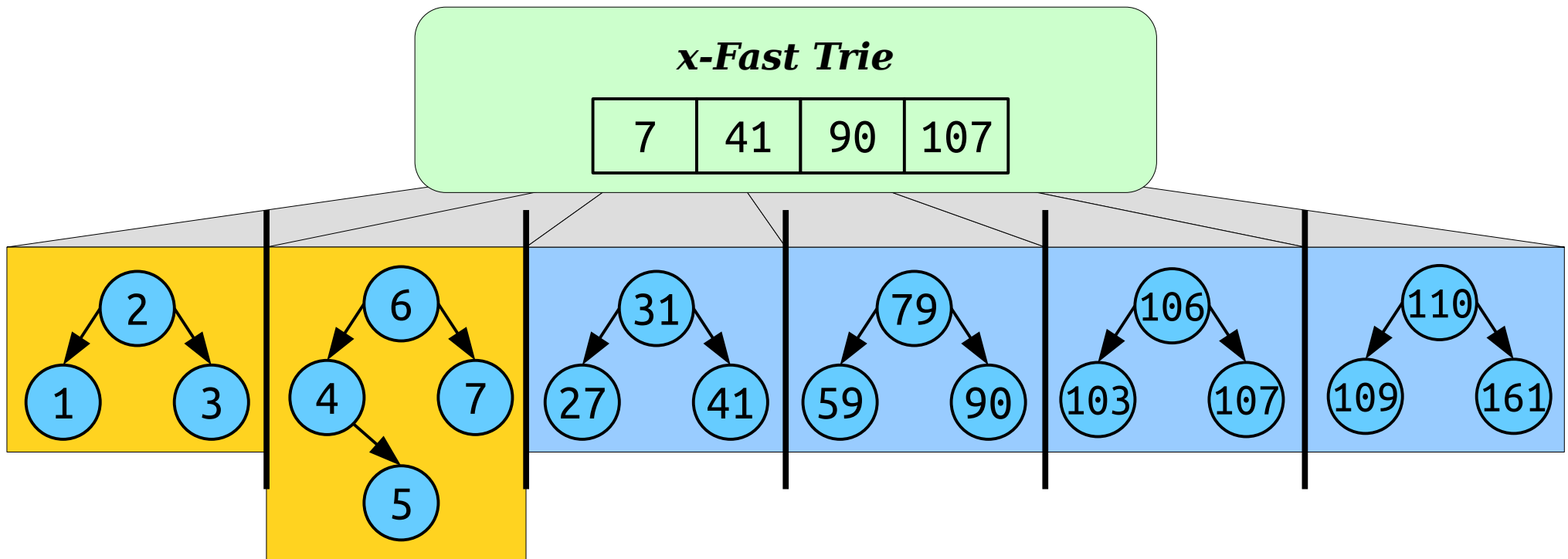
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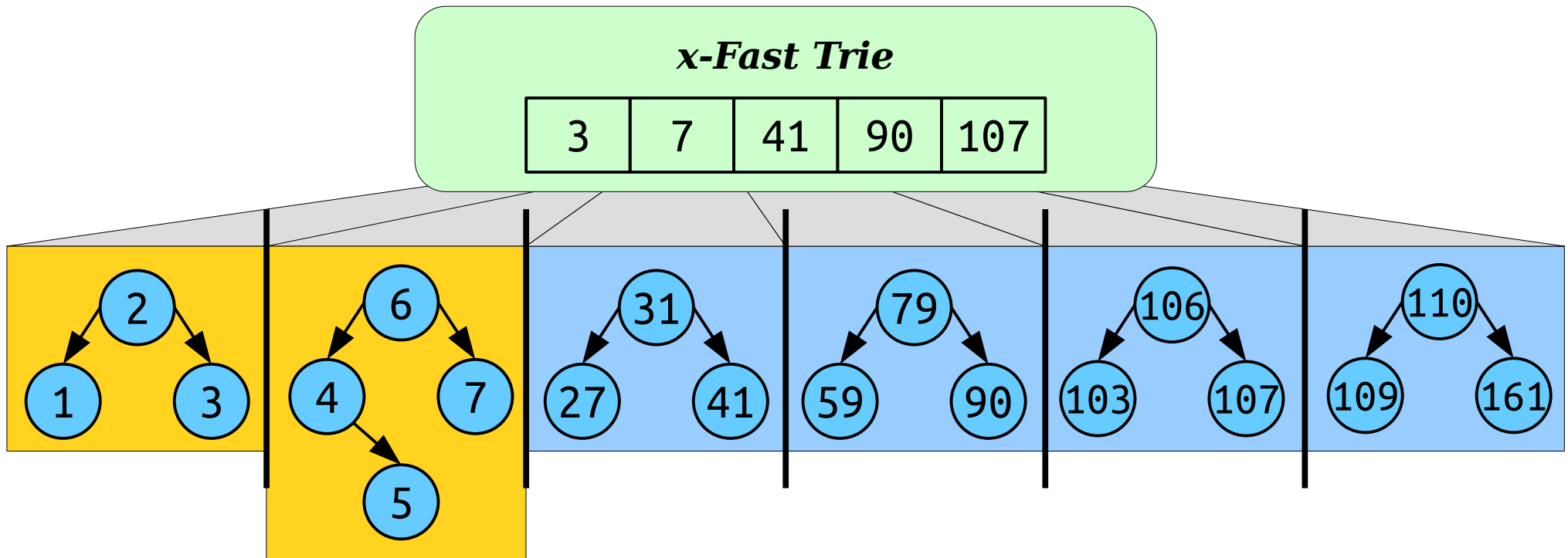
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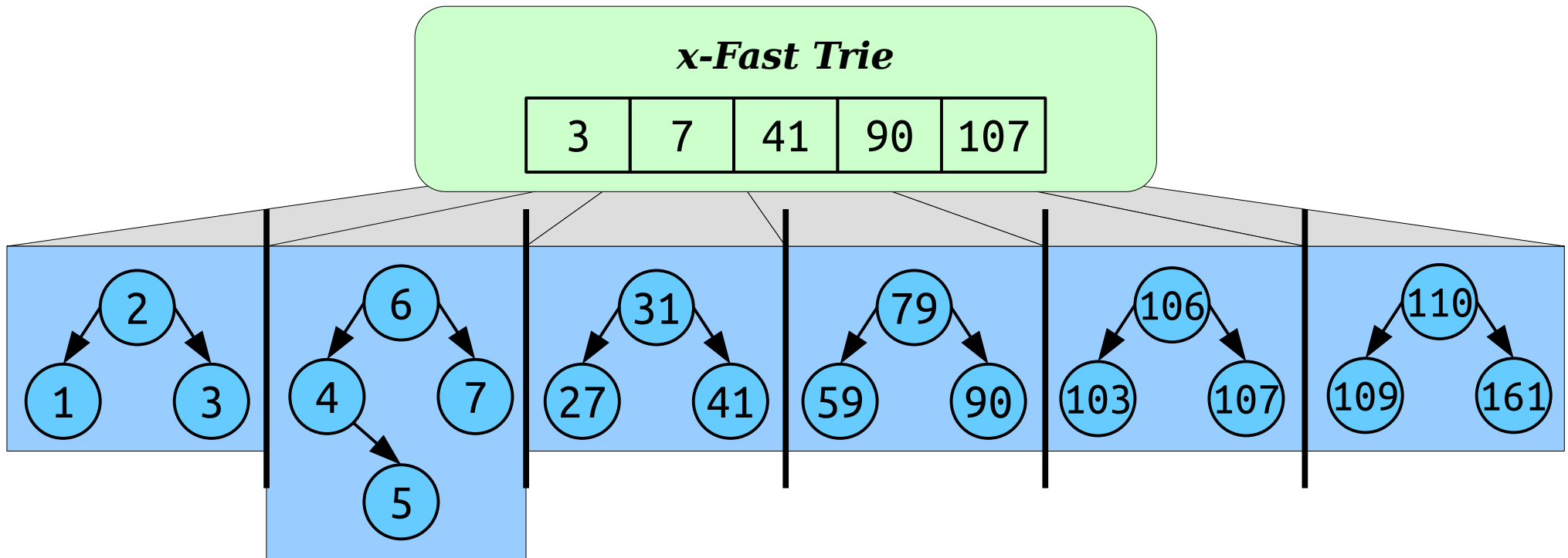
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Analyzing an Insertion

- If we perform an *insert* and don't end up doing a resize, the cost is $O(\log w)$.
- If we perform an *insert* and *do* have to do a resize, the work done is
 - $O(\log w)$ to *split* the binary search tree (say, using a splay tree), and
 - $O(w)$ to insert into the x-fast trie.
- Total work: **$O(w)$** .

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 - $O(w)$ to insert into the x-fast trie.
- Total work: **$O(w)$** .

But this is uncommon!
We only do this if a tree
got way too big.

An Amortized Analysis

- Whenever we do an insertion, place a credit on the newly-inserted element.
 - Cost of a “light” *insert* still $O(\log w)$.
- If we have to split a tree, the tree size was above $2w$, so there must be w credits on it (one for each element above w).
- The *amortized* cost of a “heavy” insert is then

$$O(\log w) + O(w) - \Theta(w) = O(\log w).$$

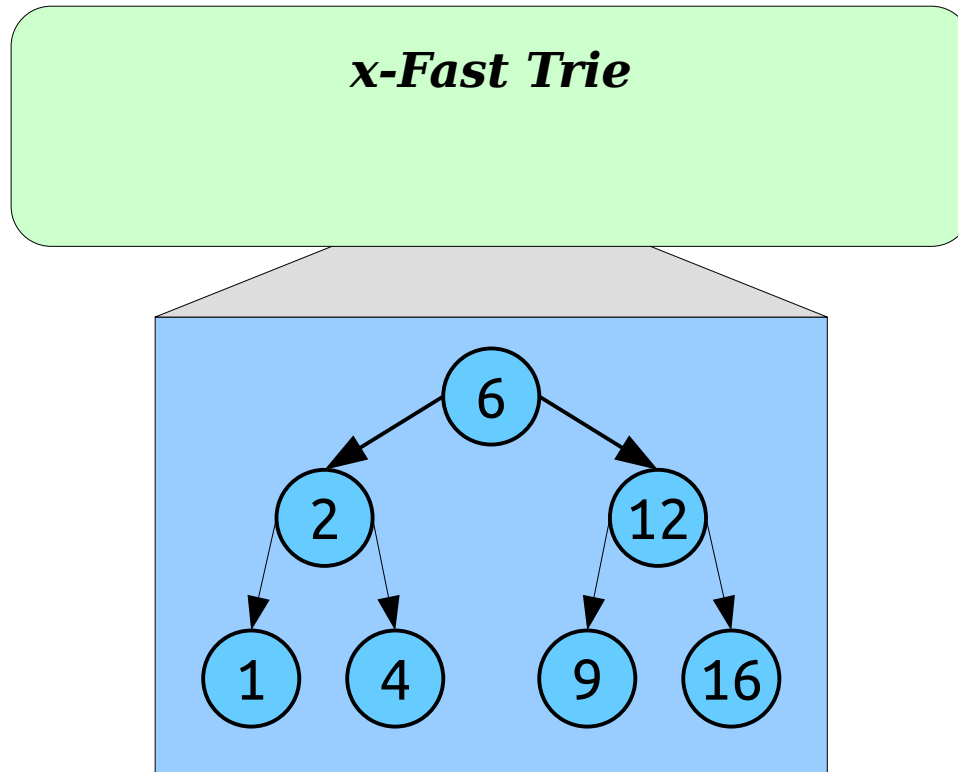
Cost of a regular insert, plus the tree split.

Cost of adding to the x-fast trie.

Credits spent.

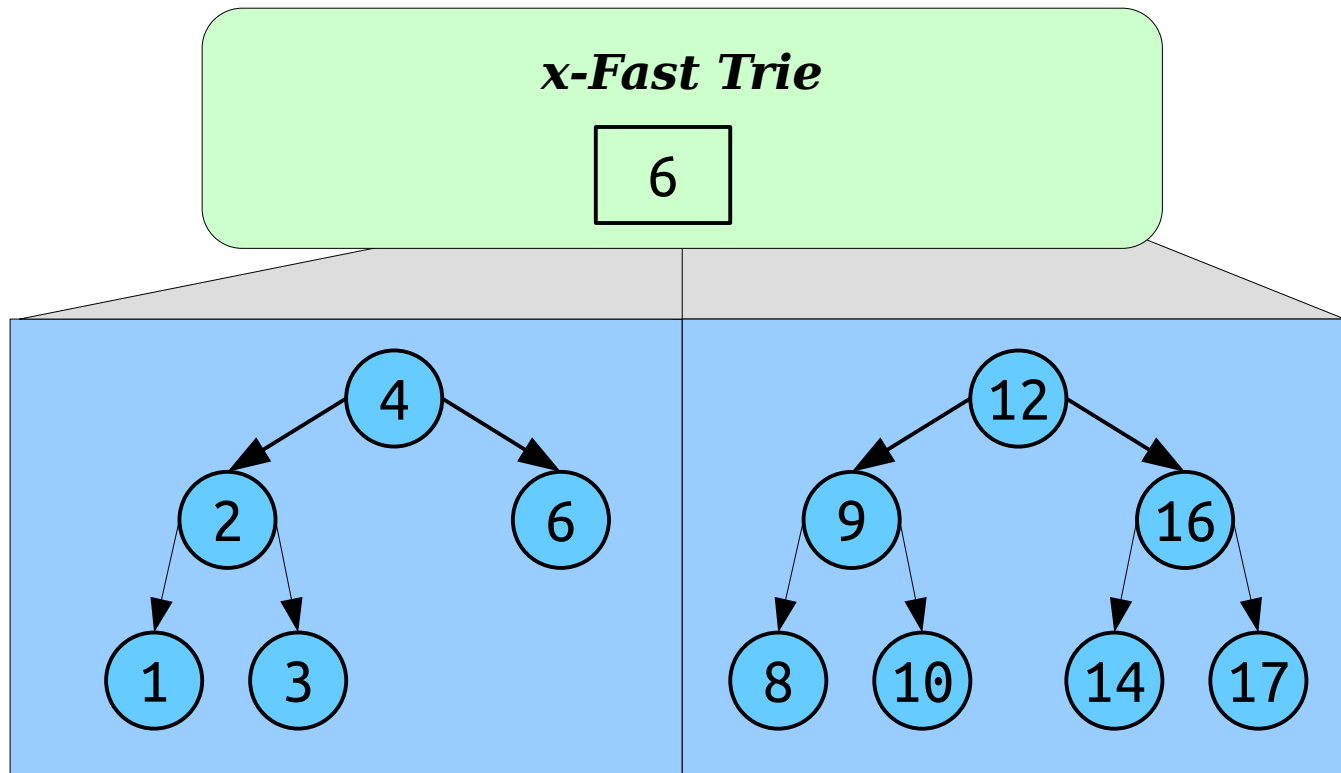
A Nice Side-Effect

- We can now abandon our assumption that we're given all the keys in sorted order in advance.
- Each insertion takes amortized time $O(\log w)$, so we can build the structure up from scratch!



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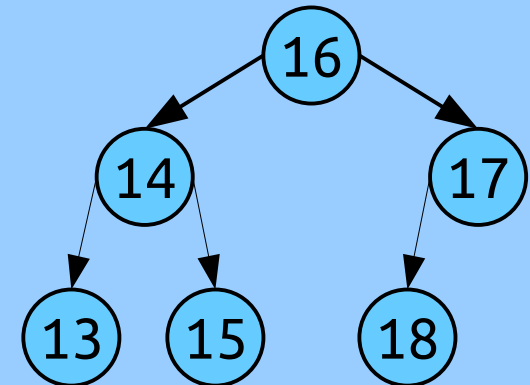
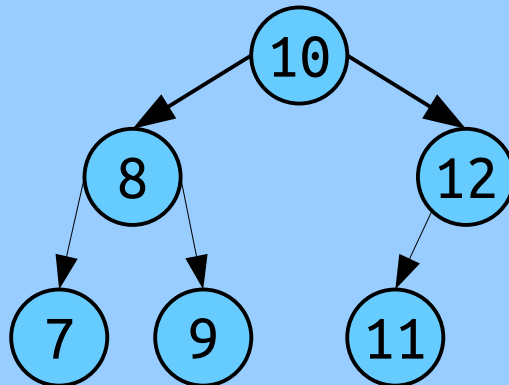
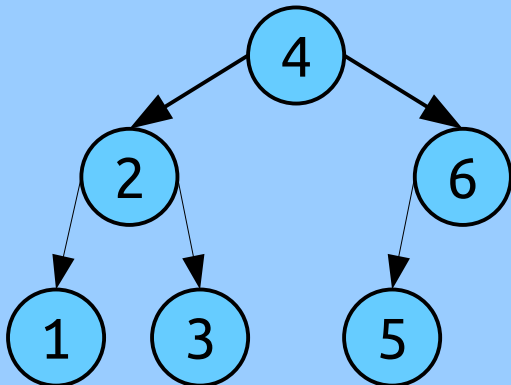
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x-Fast Trie

6

12

This is an (expected)
 $O(n \log w)$ -time
sorting algorithm!

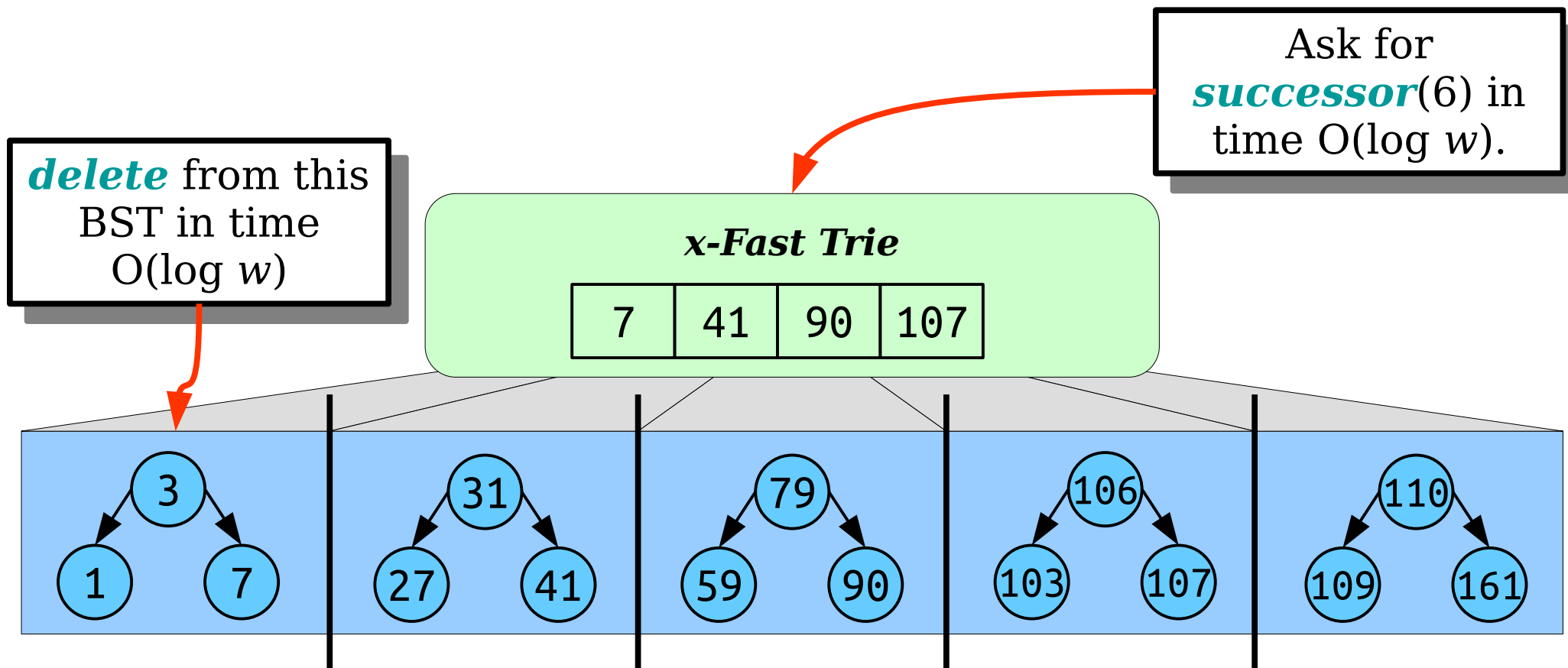


Making Edits

- With a major caveat, deletions follow the same procedure as insertions.
- Here's how we'd *delete*(7).

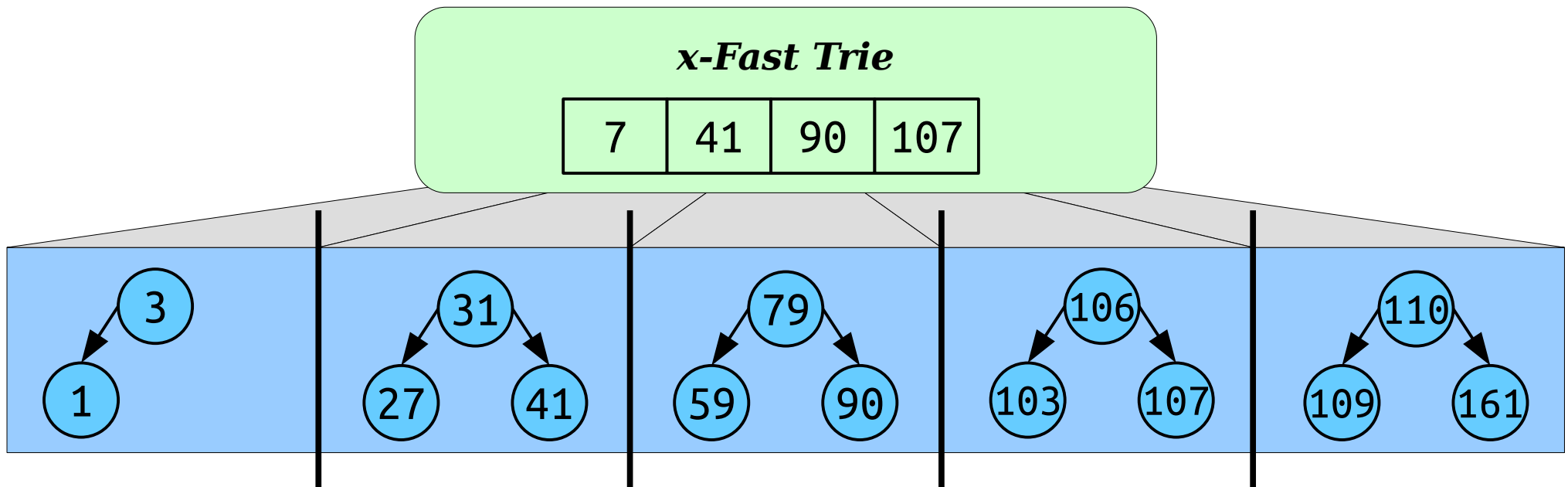
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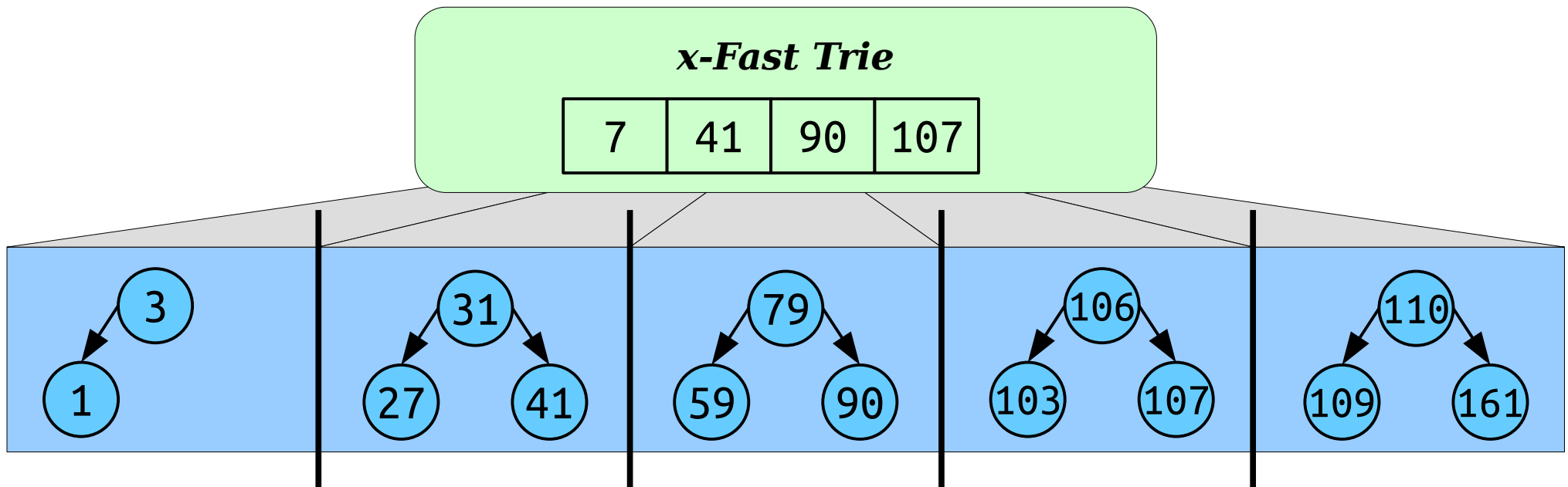
Making Edits

- Our x-fast trie still holds 7, even though 7 is no longer present.
- That's not a problem – those keys just serve as “routing information” to tell us which BSTs to look at.
- **Intuition:** The x-fast trie keys act as partitions between BSTs. They don't need to actually be present in our data structure.



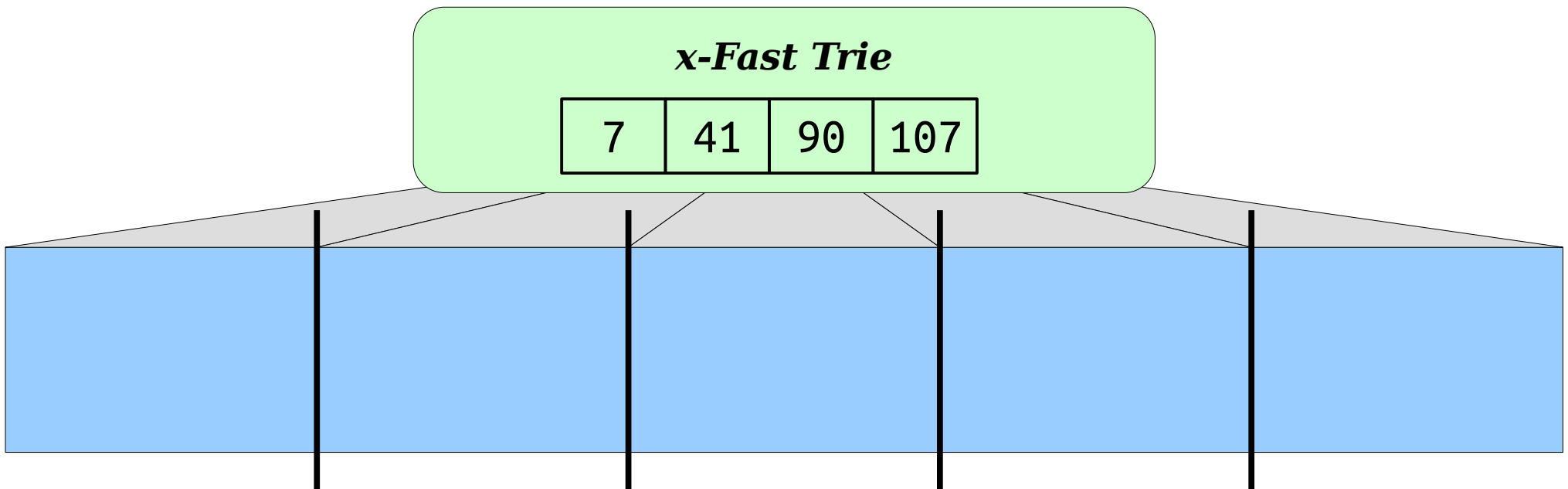
Shrinking our Structure

- What happens if we remove all the elements from our structure without touching the x-fast trie?



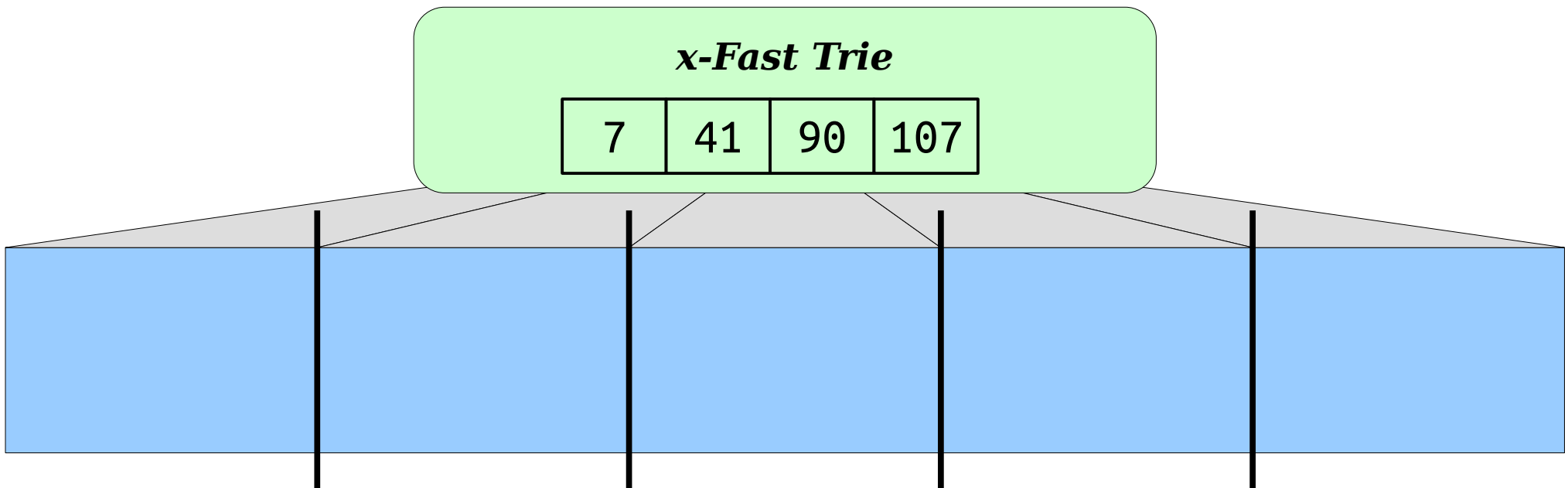
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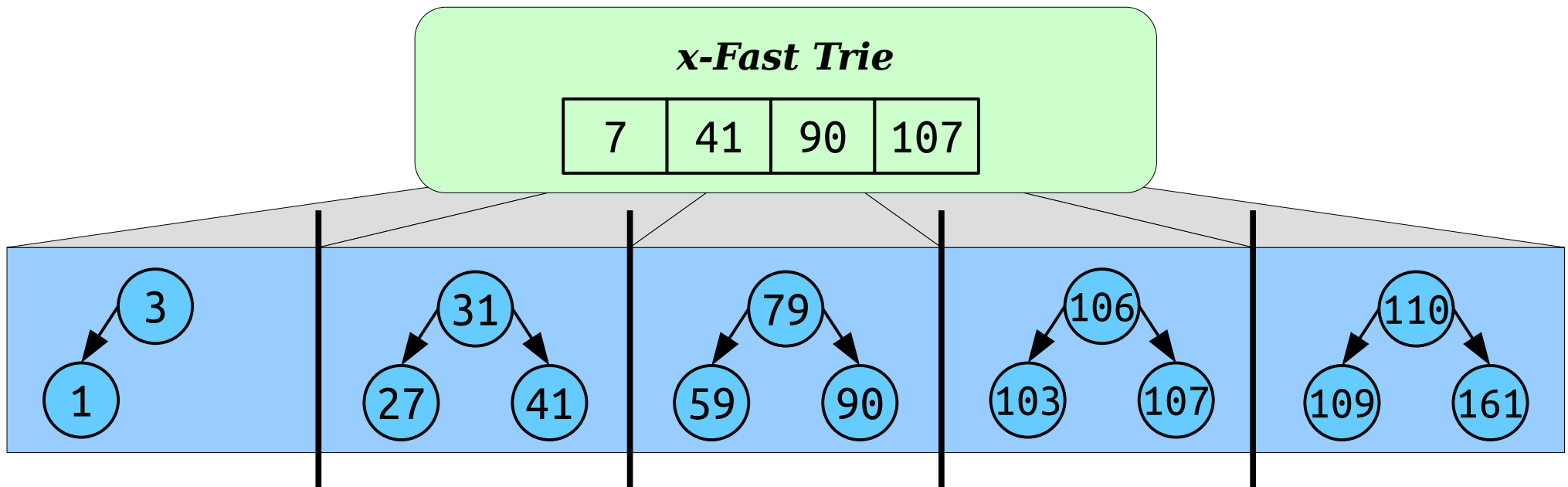
Shrinking our Structure

- What happens if we remove all the elements from our structure without touching the x -fast trie?
- Each operation still takes time **$O(\log w)$** .
- But now our space usage depends on the maximum size we reached, not the current size!



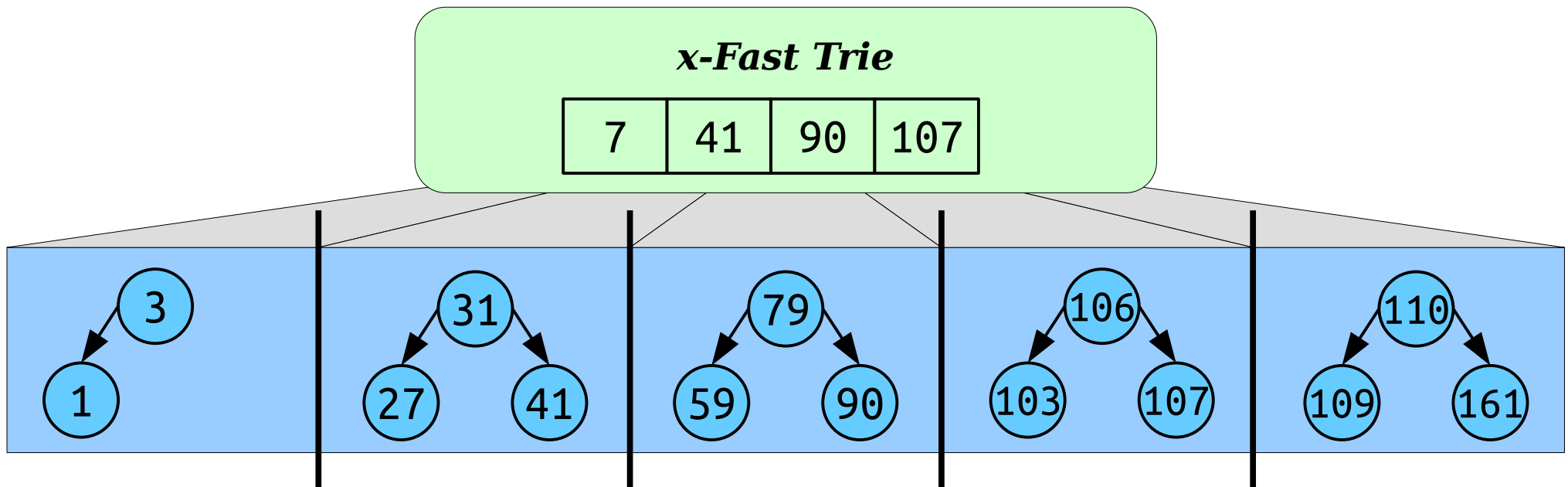
Achieving a Balance

- **Invariant:** Require each tree to have between $\frac{1}{2}w$ and $2w$ elements.
- If a tree gets too small:
 - Merge with the tree next to you, editing the x-fast trie as appropriate.
 - If the resulting tree is too big, split it in half, editing the x-fast trie.
- This does $O(w)$ on the x-fast trie only once every $\Theta(w)$ operations, so this amortizes out to $O(\log w)$ work per operation.



Achieving a Balance

- If each tree has $\Theta(w)$ elements in it, then our space usage is
 - $\Theta(n)$ for all the trees, plus
 - $\Theta((n / w) w) = \Theta(n)$ for the x-fast trie,
- This uses **$\Theta(n)$** total memory.



What We've Seen

- Here's the final scorecard for the y-fast trie.
- Assuming $n = \omega(w)$, which it probably is, this is faster than a binary search tree!
- And it gives rise to an $O(n \log w)$ -expected-time sorting algorithm!

The y-Fast Trie:

- **lookup**: $O(\log w)$
 - **insert**: $O(\log w)^*$
 - **delete**: $O(\log w)^*$
 - **max**: $O(\log w)$
 - **succ**: $O(\log w)$
 - Space: $\Theta(n)$
- * Expected, amortized.

What We Needed

- An x-fast trie requires *tries* and *cuckoo hashing*.
- The y-fast trie requires *amortized analysis* and *split/join* on *balanced BSTs*.
- y-fast tries also use the “blocking” technique from *RMQ* we used to shave off log factors.

What's Missing

- There's still a little gap between where BSTs dominate and where y-fast tries take over.
 - Specifically, what if $n = \Theta(w)$?
- Our solution still involves randomness.
 - We need that in the cuckoo hash tables at each level.
- **Question:** Can we build a solution with neither of these weaknesses?

Next Time

- ***Word-Level Parallelism***
 - Treating arithmetic as parallel computation.
- ***Sardine Trees***
 - A fast ordered dictionary for truly tiny integers.
- ***Finding the Most Significant Bit***
 - An astonishing algorithm for a deceptively tricky problem.