Mathematical Methods in Physics

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Review

- PDEs
- Some examples
- Linear operator and decomposition of linear operator
- General solutions and particular solutions

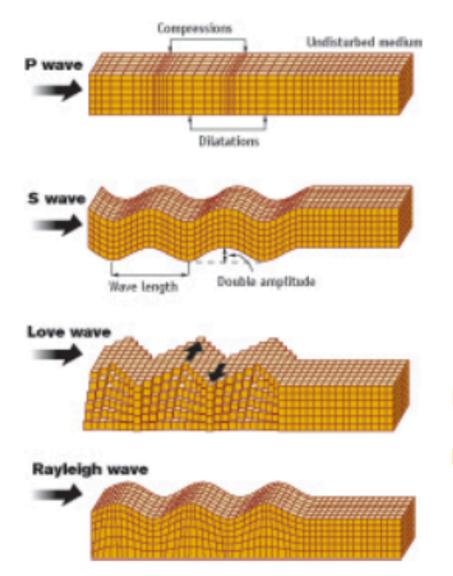
Chapter – 03: Partial Differential Equations (PDEs)

We will continue to discuss PDEs.

 We will be focusing on some specific types of PDEs: the wave equation and the heat equation (or the diffusion equation).

You will learn how to formulate a problem.

The wave equation



Different types of wave during an earthquake

https://www.iris.edu/gallery3/general/posters/exploring_earth/WaveIllustration

Let's try to work out the problem associated with string vibration.

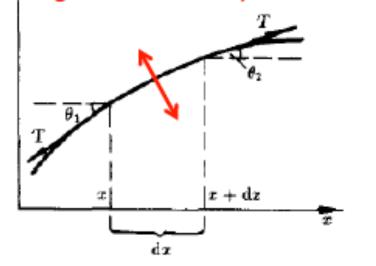
Assume the two ends of a soft string are x=0, and x=lEvery point along the string can be associated with a unique coordinate x.

u(x, t) represents the **transverse displacement** of point x at time t. We further assume that u(x, t) is very small.

$$\tan \theta(x,t) = \frac{\partial u}{\partial x}|_x$$

String is soft, so there is no stress along the normal direction.

We can also ignore gravity (elastic force is much larger than gravitational force).



$$(T\cos\theta)_{x+\Delta x}-(T\cos\theta)_x=0$$
 Horizontal
$$(T\sin\theta)_{x+\Delta x}-(T\sin\theta)_x=\rho\Delta x\frac{\overline{\partial^2 u}}{\partial t^2}$$
 Vertical 5

u(x,t)

u(x,t)

Force balance

Under the assumption of small displacement $\left|\frac{\partial u}{\partial x}\right| \ll 1$

$$\cos \theta \approx 1$$

$$\sin \theta \approx \tan \theta = \frac{\partial u}{\partial x}$$

$$T|_{x+\Delta x} = T|_{x}$$

$$\cos \theta \approx 1$$

$$\sin \theta \approx \tan \theta = \frac{\partial u}{\partial x}$$

$$\int T|_{x+\Delta x} = T|_{x}$$

$$T\left(\frac{\partial u}{\partial x}|_{x+\Delta x} - \frac{\partial u}{\partial x}|_{x}\right) = \rho \sum_{x=0}^{x} \frac{\overline{\partial^{2} u}}{\partial t^{2}}$$

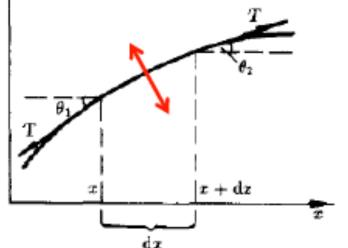
$$\frac{\partial^2 u}{\partial x^2}|_x \cdot \mathbf{X} x$$

$$\Delta x \to 0$$



String is soft, so there is no stress along the normal direction.

We can also ignore gravity (elastic force is much larger than gravitational force).



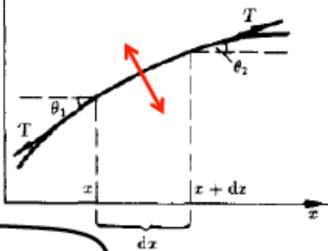
$$T\frac{\partial^2 u}{\partial x^2} = \rho \frac{\partial^2 u}{\partial t^2}$$

String is soft, so there is no stress along the normal direction.

Force balance

$$\begin{split} (T\cos\theta)_{x+\Delta x} - (T\cos\theta)_x &= 0 \qquad \text{Horizontal} \\ (T\sin\theta)_{x+\Delta x} - (T\sin\theta)_x &= \rho\Delta x \frac{\overline{\partial^2 u}}{\overline{\partial t^2}} \quad \text{Vertical} \end{split}$$

We can also ignore gravity (elastic force is much larger than gravitational force).



Under the assumption of small displacement $\ |\frac{\partial u}{\partial x}| \ll 1$

$$\frac{\partial^2 u}{\partial u^2} - a^2 \frac{\partial^2 u}{\partial u^2} = 0$$

The wave equation (homogeneous PDE)
Free vibration, no external force

u(x,t)

$$a = \sqrt{T/\rho}$$

u(x,t) is along the transverse (vertical)direction, while propagation is along the xdirection.Transverse wave

Wave propagation velocity

If there is an external force, say f (for a unit length of the string) $\Delta s - \Delta x = \sqrt{\Delta u^2 + \Delta x^2} - \Delta x$

$$\approx \left[\sqrt{1 + \left(\frac{\partial u}{\partial x} \right)^2} - 1 \right] \Delta x = O\left(\left(\frac{\partial u}{\partial x} \right)^2 \right)$$

$$\Delta s \approx \Delta x$$

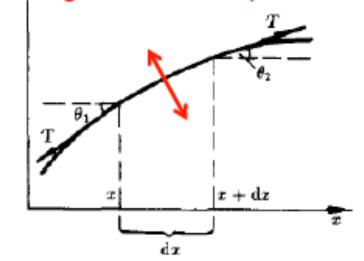
$$\rho \Delta x \frac{\overline{\partial^2 u}}{\partial t^2} = T \left[\frac{\partial u}{\partial x} |_{x + \Delta x} - \frac{\partial u}{\partial x} |_x \right] + f \Delta x$$

$$\frac{\partial^2 u}{\partial t^2} - a^2 \frac{\partial^2 u}{\partial x^2} = \frac{f}{\rho}$$

The wave equation (inhomogeneous PDE) with external force

String is soft, so there is no stress along the normal direction.

We can also ignore gravity (elastic force is much larger than gravitational force).



u(x,t)

The wave equation (longitudinal wave)

Let's consider the vibration inside a 1D bar.

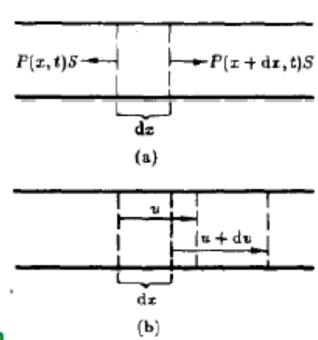
Similar to the case analyzed before, we assume every

point inside the bar is associated with a unique

coordinate x.

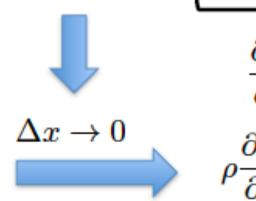
Displacement u(x,t) is along the x direction.

Wave propagates along the x direction



$$\rho S \Delta x \frac{\overline{\partial^2 u}}{\partial t^2} = [P(x + \Delta x, t) - P(x, t)] S$$

Force balance along x direction



$$\frac{\partial P}{\partial x} \Delta x$$

$$\rho \frac{\partial^2 u}{\partial t^2} = \frac{\partial P}{\partial x}$$

$$P|_{x} = E \frac{\partial u}{\partial x}$$

Hooke's law, E=Young's modulus

$$\frac{\partial^2 u}{\partial t^2} - a^2 \frac{\partial^2 u}{\partial x^2} = 0$$

$$a = \sqrt{E/\rho}$$

Wave propagation velocity

The wave equation (in 3D)

$$\frac{\partial^2 u}{\partial t^2} - a^2 \nabla^2 u = 0$$

$$abla^2 u =
abla \cdot (
abla u)$$
Inner product

$$\Delta = \nabla^2 = \nabla \cdot \nabla = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

Laplace operator

Let's consider another type of problem: heat transfer

Fourier's law

$$q_x = -k \frac{\partial u}{\partial x}$$

Heat flux along x direction

Heat per unit area of $\Delta y \Delta z$ per unit time

 $\frac{u(x)}{\partial x} < 0$ $\frac{\partial u}{\partial x} < 0$ $\frac{\partial u}{\partial x} > 0$ $\frac{\partial u}{\partial x} > 0$

u(x): low temperature

k: thermal conductivity; u: temperature

The negative sign implies the heat flux is from high temperature to low temperature

$$q_x=-krac{\partial u}{\partial x}, \ q_y=-krac{\partial u}{\partial y}, \ q_z=-krac{\partial u}{\partial z}$$
 in 3D

K: 3 x 3 matrix

For isotropic

$$\mathbf{q} = -k\nabla u$$

vector

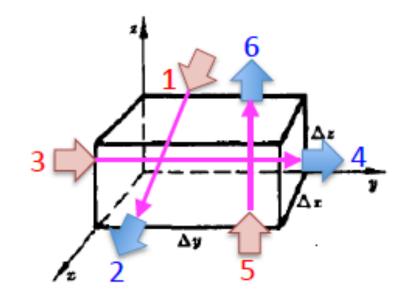
For anisotropic

$$\mathbf{q} = -\mathbf{K} \cdot \nabla u$$

The total heat flux transferred *into* the cuboid over time Δt

1-2:
$$(q_x|_x - q_x|_{x+\Delta x})\Delta y \Delta z \Delta t = -\frac{\partial q_x}{\partial x}\Delta x \Delta y \Delta z \Delta t$$

3-4: $(q_y|_y - q_y|_{y+\Delta y})\Delta x \Delta z \Delta t = -\frac{\partial q_y}{\partial y}\Delta y \Delta x \Delta z \Delta t$
5-6: $(q_z|_z - q_z|_{z+\Delta z})\Delta x \Delta y \Delta t = -\frac{\partial q_z}{\partial z}\Delta z \Delta x \Delta y \Delta t$



Consider the conservation of total energy

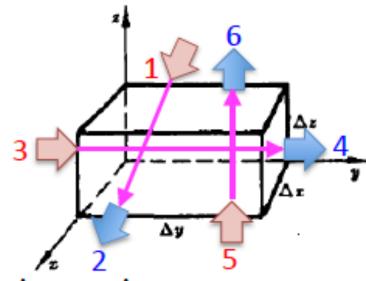
$$-\nabla \cdot \mathbf{q} \Delta x \Delta y \Delta z \Delta t + \underline{F(x, y, z, t)} \Delta x \Delta y \Delta z \Delta t = \rho \Delta x \Delta y \Delta z \cdot c \cdot \Delta u$$

Heat production (source term)
per unit volume per unit time

 $y\Delta z\cdot c\cdot \Delta u$ Heat capacity

Temperature change

Mass density



Consider the conservation of total energy

$$-\nabla \cdot \mathbf{q} \Delta x \Delta y \Delta z \Delta t + F(x, y, z, t) \Delta x \Delta y \Delta z \Delta t = \rho \Delta x \Delta y \Delta z \cdot c \cdot \Delta u$$

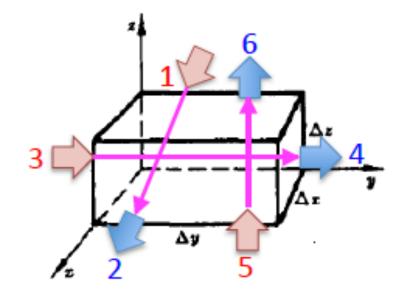
$$\frac{\partial(\rho c u)}{\partial t} + \nabla \cdot \mathbf{q} = F(x, y, z, t)$$

For isotropic medium:
$$\frac{\partial u}{\partial t} - \kappa \nabla^2 u = \frac{F}{\rho c} = f$$

$$\kappa = k/(\rho c)$$

For anisotropic medium:
$$\frac{\partial(\rho cu)}{\partial t} - \nabla \cdot (\mathbf{K} \cdot \nabla u) = F(x,y,z,t)$$

$$\frac{\partial u}{\partial t} - \kappa \nabla^2 u = \frac{F}{\rho c} = f \qquad \begin{array}{l} \text{Inhomogeneous} \\ \text{heat equation} \end{array}$$



If there is **no source/sink term** inside the cuboid, F'=0

$$rac{\partial u}{\partial t} - \kappa
abla^2 u = 0$$
 Homogeneous heat equation

Like the heat problem, the flux of fluid (or molecules) follows a similar law: Fick's law

$$\frac{\partial u}{\partial t} - D\nabla^2 u = f(x, y, z, t)$$

u: density/concentration (浓度) of molecules

D: diffusivity

The diffusion equation

Problem in steady state

Note: both the wave equation and the heat equation depend on time.

If the problem does not depend on time, it is said to be in steady state: $\frac{\partial u}{\partial t} = 0$

For example, after a long enough time, equilibrium in temperature can be reached.

Poisson equation

$$\nabla^2 u = -\frac{f}{\kappa}$$

Laplace equation

$$\nabla^2 u = 0$$

Classification

- The wave equation (*hyperbolic equation*): $\frac{\partial^2 u}{\partial t^2} a^2 \frac{\partial^2 u}{\partial x^2} = 0$ 2nd order in time and space
- The heat equation (*parabolic equation*): $\frac{\partial u}{\partial t} \kappa \nabla^2 u = 0$ 1st order in time, 2nd order in space
- Poisson equation (*elliptical equation*): $\nabla^2 u = -\frac{f}{\kappa}$ Oth order in time, 2nd order in space

 Differential equation alone is not enough for fully determining the solution, other conditions are also needed, such as the initial condition and/or the boundary condition.

$$\frac{d^2u}{dt^2}=a,\ u|_{t=0}=u_0,\ \frac{du}{dt}|_{t=0}=v_0 \qquad \text{Newton's second law}$$

$$u=u_0+v_0t+\frac{1}{2}at^2$$

 Also note that differential equation only applies to the interior of the considered region. The behavior along the boundary has to be determined separately.

 Differential equation alone is not enough for fully determining the solution, other conditions are also needed, such as the initial condition and/or the boundary condition.

The wave equation is 2nd order in time

$$u|_{t=0} = \phi(x, y, z), \ \frac{\partial u}{\partial t}|_{t=0} = \psi(x, y, z), \ (x, y, z) \in \overline{V}$$

The heat equation is 1st order in time

$$u|_{t=0} = \phi(x, y, z), \ (x, y, z) \in \overline{V}$$

 Differential equation alone is not enough for fully determining the solution, other conditions are also needed, such as the initial condition and/or the boundary condition.

The wave equation (transverse wave)

$$u|_{x=0} = 0, \ u|_{x=l} = 0, \ t \ge 0$$



Fixed at the two ends

Differential equation alone is not enough for fully determining the solution, other conditions are also needed, such as **the initial condition** and/or **the boundary** condition.

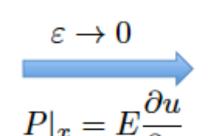
The wave equation (longitudinal wave)

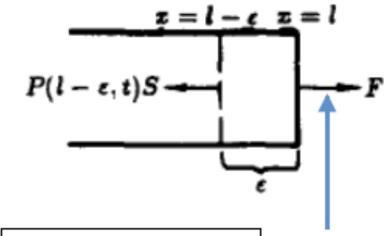
Fixed at one end

$$u|_{x=0}=0$$

Force balance at the other end

$$\rho \varepsilon S \frac{\overline{\partial^2 u}}{\partial t^2} = F(t)S - P(l - \varepsilon, t)S \qquad \begin{array}{c} \varepsilon \to 0 \\ \\ P|_x = E \frac{\partial u}{\partial x} \end{array}$$





$$\frac{\partial u}{\partial x}|_{x=l} = \frac{1}{E}F(t)$$

Traction at

Differential equation alone is not enough for fully determining the solution, other conditions are also needed, such as **the initial condition** and/or **the boundary** condition.

The wave equation (longitudinal wave)

If the traction is zero

$$\frac{\partial u}{\partial x}|_{x=l} = 0$$

If the traction is given by a spring

$$F(t)S = -k\left[u(l,t) - u_0\right] \quad \Longrightarrow \quad$$

 $F(t)S = -k \left[u(l,t) - u_0 \right] \qquad \qquad \left| \left(ku + ES \frac{\partial u}{\partial x} \right) \right|_{x=l} = ku_0$ Traction at the boundary

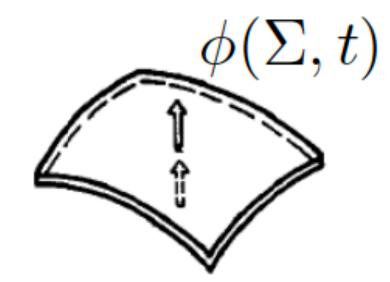
 u_0 : the equilibrium position of the spring

 Differential equation alone is not enough for fully determining the solution, other conditions are also needed, such as the initial condition and/or the boundary condition.

The heat equation

If the temperature is known at the boundary

$$u|_{\Sigma} = \phi(\Sigma,t)$$



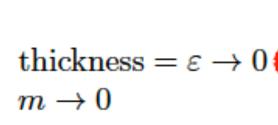
 Differential equation alone is not enough for fully determining the solution, other conditions are also needed, such as the initial condition and/or the boundary condition.

The heat equation

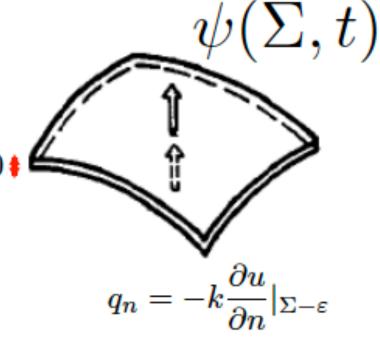
 If the heat flux is known at the boundary

$$-k\frac{\partial u}{\partial n}|_{\Sigma} = \psi(\Sigma, t)$$

$$\frac{\partial}{\partial n} = \mathbf{n} \cdot \nabla$$



No heat production or loss inside the thin layer, no flux along other boundaries



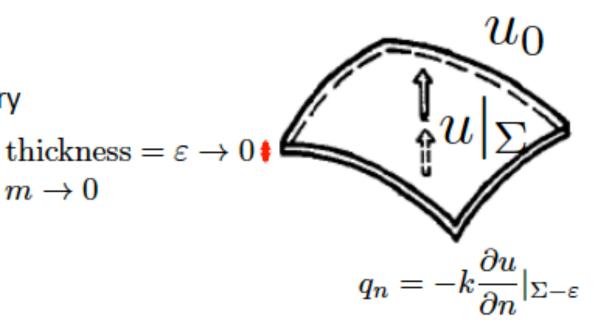
 $m \to 0$

Differential equation alone is not enough for fully determining the solution, other conditions are also needed, such as **the initial condition** and/or **the boundary** condition.

The heat equation

If the heat flux across the boundary follows the cooling law

$$-k\frac{\partial u}{\partial n}|_{\Sigma} = H(u|_{\Sigma} - u_0)$$



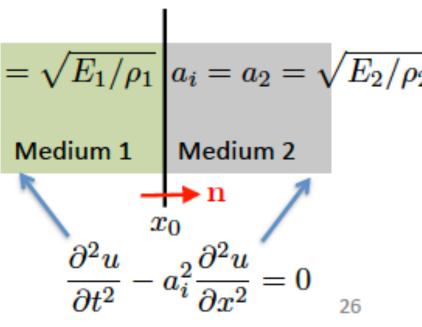
 Differential equation alone is not enough for fully determining the solution, other conditions are also needed, such as the initial condition and/or the boundary condition.

Classification of boundary conditions

- First kind (Dirichlet): $u|_{\Sigma} = \phi(\Sigma, t)$
- Second kind (Neumann): $\frac{\partial u}{\partial n}|_{\Sigma} = \psi(\Sigma,t)$
- Third kind (mixed): $\left(A\cdot u+B\cdot \frac{\partial u}{\partial n}\right)|_{\Sigma}=F(\Sigma,t)$

- So far discussion is made for a bounded region.
- Sometimes we need to discuss the behavior at the infinity.
- Sometimes there could be a discontinuity (or jump) across an interface inside the
 region. It is difficult to apply PDE directly to such discontinuity; instead, we often
 require the following conditions across the interface:
 - Continuity in displacement (along n direction) $u_1(x,t)|_{x=x_0-0}=u_2(x,t)|_{x=x_0+0}$
 - Continuity in stress (along n direction)

$$\left[E_1 \frac{\partial u_1(x,t)}{\partial x}\right]|_{x=x_0-0} = \left[E_2 \frac{\partial u_2(x,t)}{\partial x}\right]|_{x=x_0+0}$$



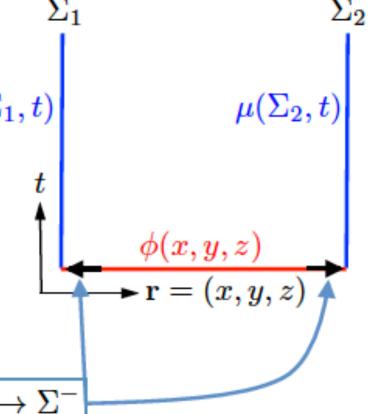
Well posedness (适定性)

Let's consider the following problem, where PDE, initial and boundary conditions are

given:
$$\begin{split} \frac{\partial u}{\partial t} - \kappa \nabla^2 u &= f(x,y,z,t), \ (x,y,z,t) \in V, \ t > 0 \\ u|_{\Sigma} &= \mu(\Sigma,t), \quad t \geq 0 \\ u|_{t=0} &= \phi(x,y,z), \quad (x,y,z) \in \overline{V} \\ \overline{V} &= V + \Sigma \end{split}$$

We assume that $f(x,y,z,t), \ \mu(\Sigma,t), \ \phi(x,y,z)$ are continuous, then the solution should satisfy:

- (1) u is continuous over $(x, y, z) \in V, t > 0$
- (2) $\partial u/\partial t$, $\partial^2 u/\partial x_i^2$ are continuous over $(x,y,z) \in V$, t>0
- (3) u satisfies the PDE over $(x,y,z) \in V, \ t>0$
- (4) u satisfies the boundary condition for t>0, and $t\to 0^+$
- (5) u satisfies the initial condition for $(x,y,z) \in V$, and $(x,y,z) \to \Sigma^-$



Well posedness (适定性)

Let's consider the following problem, where PDE, initial and boundary conditions are

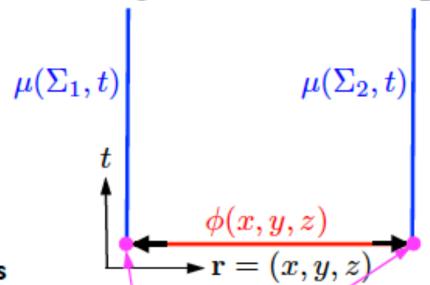
given:
$$\begin{split} \frac{\partial u}{\partial t} - \kappa \nabla^2 u &= f(x,y,z,t), \ (x,y,z,t) \in V, \ t > 0 \\ u|_{\Sigma} &= \mu(\Sigma,t), \quad t \geq 0 \\ u|_{t=0} &= \phi(x,y,z), \quad (x,y,z) \in \overline{V} \\ \overline{V} &= V + \Sigma \end{split}$$

We want to know:

- Whether the solution exists
- Whether there exists a unique solution
- Whether the solution is stable

The dependence of solution on parameters related to PDE and initial/boundary conditions

$$\kappa$$
, f , μ , ϕ



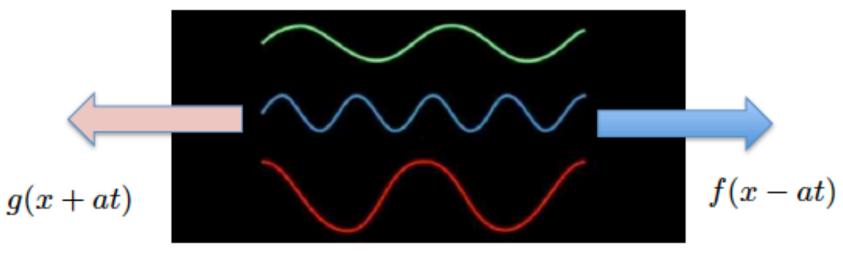
Well posedness

well-posed or ill-posed?

$$\mu(\Sigma, t)|_{t=0} = \phi(x, y, z)|_{\Sigma}$$

• Traveling wave (行波)

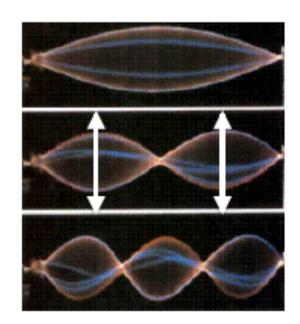
The wave propagates



• Standing wave (驻波)

The wave does not "propagate"

(superposition of two propagating waves in opposite directions)



Traveling wave (行波)

The wave propagates

$$u(x,t) = f(x-at) + g(x+at)$$

Apply the initial condition

$$\begin{cases} f(x) + g(x) = \phi(x) \\ a[f'(x) - g'(x)] = -\psi(x) \implies f(x) - g(x) = -(1/a) \int_0^x \psi(\xi) d\xi + C \end{cases}$$

$$f(x) = \frac{1}{2}\phi(x) - \frac{1}{2a} \int_0^x \psi(\xi) d\xi + \frac{C}{2}, \ g(x) = \frac{1}{2}\phi(x) + \frac{1}{2a} \int_0^x \psi(\xi) d\xi - \frac{C}{2}$$

Traveling wave (行波)

The wave propagates

$$f(x) = \frac{1}{2}\phi(x) - \frac{1}{2a} \int_0^x \psi(\xi)d\xi + \frac{C}{2}$$

$$g(x) = \frac{1}{2}\phi(x) + \frac{1}{2a} \int_0^x \psi(\xi)d\xi - \frac{C}{2}$$

$$\frac{\partial u}{\partial t}|_{t=0} = \psi(x), \quad -\infty < x < \infty$$

$$u(x,t)|_{x \to \pm \infty} \to 0 \quad \text{or is bounded}$$

$$\frac{\partial^2 u}{\partial t^2} - a^2 \frac{\partial^2 u}{\partial x^2} = 0, \quad -\infty < x < \infty, \quad t > 0$$

$$u(x,t)|_{t=0} = \phi(x), \quad -\infty < x < \infty$$

$$\frac{\partial u}{\partial t}|_{t=0} = \psi(x), \quad -\infty < x < \infty$$

$$u(x,t)|_{x\to\pm\infty} \to 0 \quad \text{or is bounded}$$

Traveling wave solution or d'Alembert solution

$$u(x,t) = f(x-at) + g(x+at) = \frac{1}{2} [\phi(x-at) + \phi(x+at)] + \frac{1}{2a} \int_{x-at}^{x+at} \psi(\xi) d\xi$$

Traveling wave (行波)

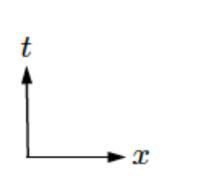
The wave propagates

Perturbation due to initial displacement

$$u(x,t)|_{t=0} = \phi(x), -\infty < x < \infty$$

$$\frac{\partial u}{\partial t}|_{t=0} = \psi(x), -\infty < x < \infty$$

$$u(x,t) = f(x-at) + g(x+at) = \frac{1}{2} [\phi(x-at) + \phi(x+at)] + \frac{1}{2a} \int_{x-at}^{x+at} \psi(\xi) d\xi$$



wave propagation

has reached

Perturbation due to initial velocity

Disturbance due to wave propagation has not yet reached

$$t = 0$$

Slope = 1/a

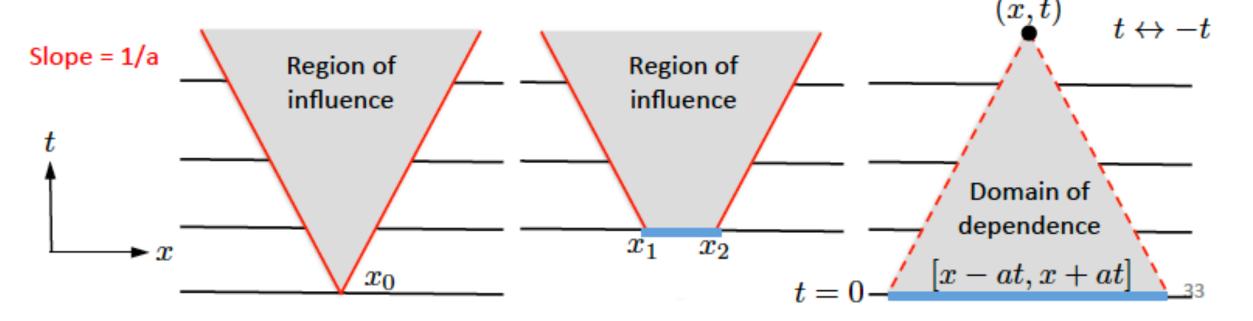
Traveling wave (行波)

The wave propagates

$$u(x,t)|_{t=0} = \phi(x), -\infty < x < \infty$$

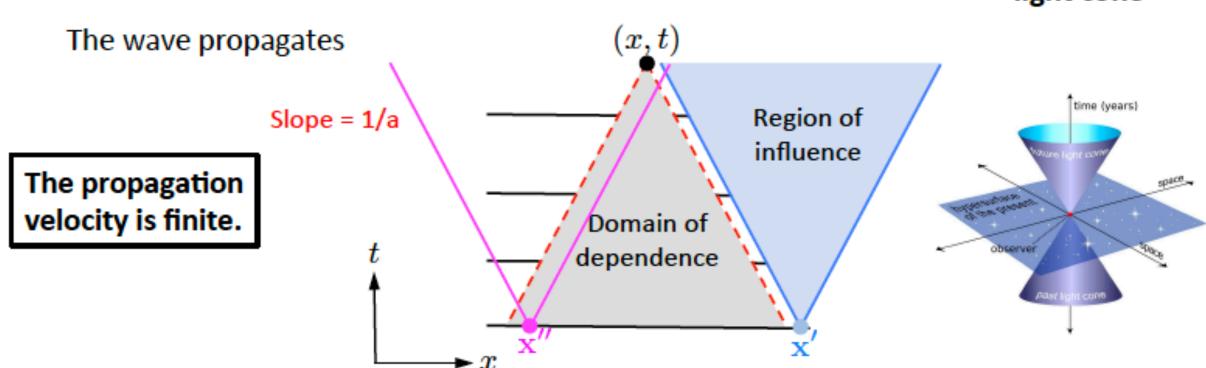
$$\frac{\partial u}{\partial t}|_{t=0} = \psi(x), -\infty < x < \infty$$

$$u(x,t) = f(x-at) + g(x+at) = \frac{1}{2} [\phi(x-at) + \phi(x+at)] + \frac{1}{2a} \int_{x-at}^{x+at} \psi(\xi) d\xi$$



• Traveling wave (行波)

Relativity: event horizon light cone



x" can influence (x,t), while x' cannot. All the points (or regions) that can influence (x,t) constitute the domain of dependence of (x,t).

Now let's consider the heat equation in 1D.
$$\begin{cases} \frac{\partial u}{\partial t} - \kappa \frac{\partial^2 u}{\partial x^2} = 0 \\ u|_{t=0} = \phi(x) \end{cases}$$
 er transformation
$$u|_{x\to\pm\infty} \text{ is bounded}$$

Fourier transformation

$$u(x,t) = \int_{-\infty}^{\infty} A(k)e^{-\kappa k^2t}e^{\mathrm{i}kx}dk$$
 Exchange the order of integration
$$u(x,t=0) = \phi(x) = \int_{-\infty}^{\infty} A(k)e^{\mathrm{i}kx}dk$$

$$u(x,t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-\kappa k^2t}dk \int_{-\infty}^{\infty} e^{\mathrm{i}kx}\phi(x')e^{-\mathrm{i}kx'}dx'$$

$$A(k) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \phi(x)e^{-\mathrm{i}kx}dx$$

$$u(x,t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-\kappa k^2 t} dk \int_{-\infty}^{\infty} e^{ikx} \phi(x') e^{-ikx'} dx'$$

$$\int_0^\infty e^{-t^2} dt = \frac{1}{2} \sqrt{\pi}$$

Now let's consider the heat equation in 1D.
$$\begin{cases} \frac{\partial u}{\partial t} - \kappa \frac{\partial^2 u}{\partial x^2} = 0 \\ u|_{t=0} = \phi(x) \\ u|_{x\to\pm\infty} \text{ is bounded} \end{cases}$$

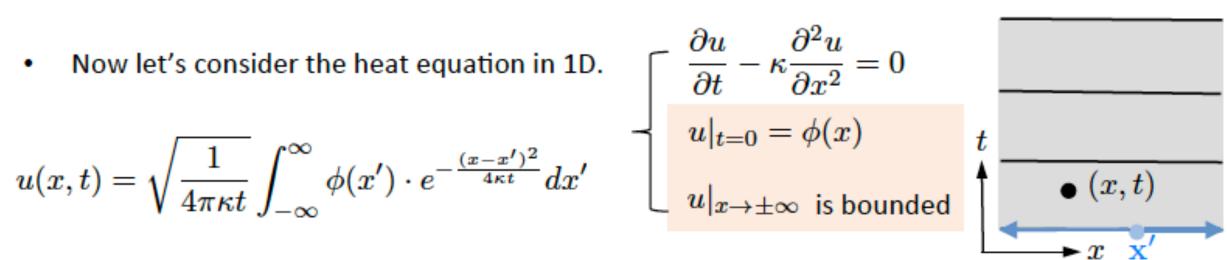
$$u(x,t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-\kappa k^2 t} dk \int_{-\infty}^{\infty} e^{\mathrm{i}kx} \phi(x') e^{-\mathrm{i}kx'} dx'$$

$$=\frac{1}{2\pi}\int_{-\infty}^{\infty}e^{-\left[\sqrt{\kappa t}k-\frac{\mathrm{i}(x-x')}{2\sqrt{\kappa t}}\right]^{2}}\cdot e^{-\frac{(x-x')^{2}}{4\kappa t}}dk\int_{-\infty}^{\infty}\phi(x')dx'$$

$$= \frac{1}{2\pi} \cdot \frac{\sqrt{\pi}}{\sqrt{\kappa t}} \int_{-\infty}^{\infty} \phi(x') \cdot e^{-\frac{(x-x')^2}{4\kappa t}} dx'$$

$$= \sqrt{\frac{1}{4\pi\kappa t}} \int_{-\infty}^{\infty} \phi(x') \cdot e^{-\frac{(x-x')^2}{4\kappa t}} dx'$$

$$u(x,t) = \sqrt{\frac{1}{4\pi\kappa t}} \int_{-\infty}^{\infty} \phi(x') \cdot e^{-\frac{(x-x')^2}{4\kappa t}} dx'$$

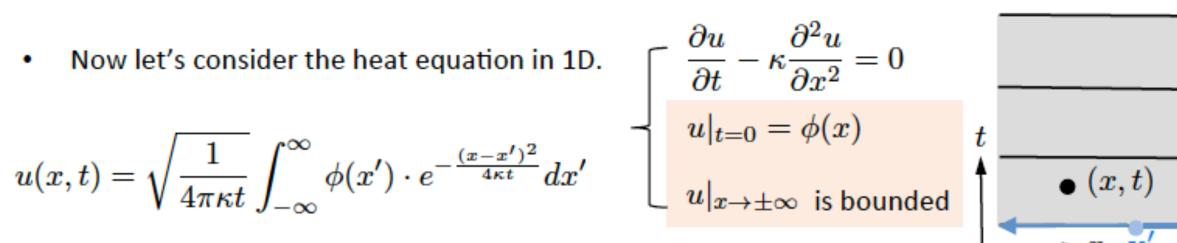


The initial state at point x' $\phi(x')$ can influence the state at (x,t) with a weighting factor of $e^{-\frac{(x-x')^2}{4\kappa t}}$

The integration is from $-\infty$ to ∞ , implying that the domain of dependence is the entire x axis. Conversely, every point of the initial state can influence the entire domain

(the "propagation velocity" of heat transfer is infinite).

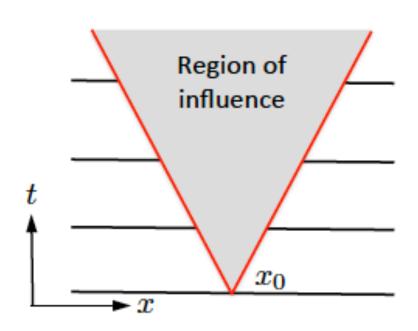
$$u(x,t) = \sqrt{\frac{1}{4\pi\kappa t}} \int_{-\infty}^{\infty} \phi(x') \cdot e^{-\frac{(x-x')^2}{4\kappa t}} dx'$$



The "propagation velocity" of heat transfer is infinite.

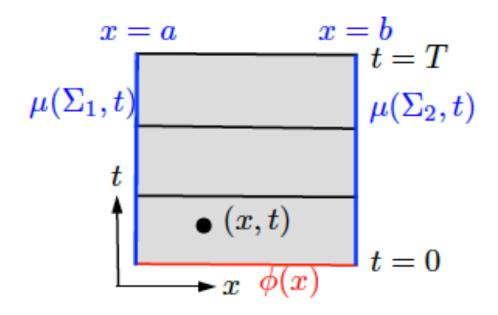
The above statement is mathematically correct, but physically incorrect. We have made some simplified assumptions when formulating the mathematical problem.

The wave equation vs. the heat equation



u(x,t) can reach its maximum/minimum inside the region.

Finite propagation velocity.



If u(x,t) is continuous in the rectangular region $a \le x \le b, \ 0 \le t \le T$, then it must reach the maximum/minimum at the initial state or at its boundary.

Infinite propagation velocity.