

Linear Algebra

Math 314 Fall 2025

Today's poll code:

MNE2CY

Lecture 5

Office hours

Mondays 5–6 pm

Wednesdays 2–3 pm

in Avery 339 (Dr. Grifo)

Tuesdays 11–noon

Thursdays 1–2 pm

in Avery 337 (Kara)

To do list:

- WebWork 2.2 due Friday
- Webwork 2.3 due Tuesday September 16
- WeBWork 2.4 due Friday September 19

Quiz 3 on Friday
on lectures 4—5

Office hours

Mondays 5–6 pm and Wednesdays 2–3 pm
in Avery 339 (Dr. Grifo)

Tuesdays 11–noon and Thursdays 1–2 pm
in Avery 337 (Kara)

Homogeneous linear systems

A linear system is **homogeneous** if we can write it as

$$Ax = 0.$$

A homogeneous system always has a solution:

the **trivial solution** $x = 0$.

A solution $x \neq 0$ is called **nontrivial**.

$$\begin{cases} 3x_1 + 5x_2 - 4x_3 = 0 \\ -3x_1 - 2x_2 + 4x_3 = 0 \\ 6x_1 + x_2 - 8x_3 = 0 \end{cases} \quad \text{homogeneous system}$$

$$\begin{cases} 3x_1 + 5x_2 - 4x_3 = 0 \\ -3x_1 - 2x_2 + 4x_3 = 0 \\ 6x_1 + x_2 - 8x_3 = 0 \end{cases} \quad \text{homogeneous system}$$

$$\underbrace{\begin{bmatrix} 3 & 5 & -4 \\ -3 & -2 & 4 \\ 6 & 1 & -8 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}}_x = \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_b \quad \text{matrix equation}$$

$$\begin{cases} 3x_1 + 5x_2 - 4x_3 = 0 \\ -3x_1 - 2x_2 + 4x_3 = 0 \\ 6x_1 + x_2 - 8x_3 = 0 \end{cases} \quad \text{homogeneous system}$$

$$\begin{array}{c}
\left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ -3 & -2 & 4 & 0 \\ 6 & 1 & -8 & 0 \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 + R_1} \left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ 0 & 3 & 0 & 0 \\ 6 & 1 & -8 & 0 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 2R_1} \left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & -9 & 0 & 0 \end{array} \right] \\
\xrightarrow{R_2 \rightarrow \frac{1}{3}R_2} \left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -9 & 0 & 0 \end{array} \right] \xrightarrow{R_1 \rightarrow R_1 - 5R_2} \left[\begin{array}{ccc|c} 3 & 0 & -4 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -9 & 0 & 0 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 + 9R_2} \left[\begin{array}{ccc|c} 3 & 0 & -4 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \\
\xrightarrow{R_1 \rightarrow \frac{1}{3}R_1} \left[\begin{array}{ccc|c} 1 & 0 & -\frac{4}{3} & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right].
\end{array}$$

Note that the last column doesn't really add any information!
When the system is homogeneous, can row reduce A instead.

$$\begin{cases} 3x_1 + 5x_2 - 4x_3 = 0 \\ -3x_1 - 2x_2 + 4x_3 = 0 \\ 6x_1 + x_2 - 8x_3 = 0 \end{cases} \quad \text{homogeneous system}$$

$$\left[\begin{array}{ccc} 3 & 5 & -4 \\ -3 & -2 & 4 \\ 6 & 1 & -8 \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 + R_1} \left[\begin{array}{ccc} 3 & 5 & -4 \\ 0 & 3 & 0 \\ 6 & 1 & -8 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 2R_1} \left[\begin{array}{ccc} 3 & 5 & -4 \\ 0 & 3 & 0 \\ 0 & -9 & 0 \end{array} \right]$$

$$\xrightarrow{R_2 \rightarrow \frac{1}{3}R_2} \left[\begin{array}{ccc} 3 & 5 & -4 \\ 0 & 1 & 0 \\ 0 & -9 & 0 \end{array} \right] \xrightarrow{R_1 \rightarrow R_1 - 5R_2} \left[\begin{array}{ccc} 3 & 0 & -4 \\ 0 & 1 & 0 \\ 0 & -9 & 0 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 + 9R_2} \left[\begin{array}{ccc} 3 & 0 & -4 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

$$\xrightarrow{R_1 \rightarrow \frac{1}{3}R_1} \left[\begin{array}{ccc} 1 & 0 & -\frac{4}{3} \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right].$$

$$\begin{cases} 3x_1 + 5x_2 - 4x_3 = 0 \\ -3x_1 - 2x_2 + 4x_3 = 0 \\ 6x_1 + x_2 - 8x_3 = 0 \end{cases} \quad \text{homogeneous system}$$

$$\begin{array}{c}
\left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ -3 & -2 & 4 & 0 \\ 6 & 1 & -8 & 0 \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 + R_1} \left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ 0 & 3 & 0 & 0 \\ 6 & 1 & -8 & 0 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 2R_1} \left[\begin{array}{ccc|c} 3 & 5 & -4 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & -9 & 0 & 0 \end{array} \right] \\
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\xrightarrow{R_1 \rightarrow \frac{1}{3}R_1} \left[\begin{array}{ccc|c} 1 & 0 & -\frac{4}{3} & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right].
\end{array}$$

x_3 is free

$$x_1 = \frac{4}{3}x_3$$

$$x_2 = 0$$

$$\underbrace{\begin{bmatrix} 3 & 5 & -4 \\ -3 & -2 & 4 \\ 6 & 1 & -8 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}}_x = \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_b \quad \text{homogeneous system}$$

x_3 is free

$$x_1 = \frac{4}{3}x_3 \qquad x_2 = 0$$

General solution:

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} \frac{4}{3} \\ 0 \\ 1 \end{bmatrix} \quad \text{or} \quad t \begin{bmatrix} \frac{4}{3} \\ 0 \\ 1 \end{bmatrix}$$

$t = 0$ gives the trivial solution

Each choice of $t \neq 0$ gives a nontrivial particular solution

the general solution to a homogeneous system is
a linear combination of vectors with the free variables as coefficients

$$\underbrace{\begin{bmatrix} 3 & 5 & -4 \\ -3 & -2 & 4 \\ 6 & 1 & -8 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}}_x = \underbrace{\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}}_b$$

homogeneous system

General solution in parametric vector form

$$x = x_3 \begin{bmatrix} \frac{4}{3} \\ 0 \\ 1 \end{bmatrix} \quad \text{or} \quad x = t \begin{bmatrix} \frac{4}{3} \\ 0 \\ 1 \end{bmatrix}$$

Nonhomogeneous linear systems

A **nonhomogeneous linear system** is a linear system of the form

$$Ax = b \quad \text{with } b \neq 0$$

Theorem. The general solution to the nonhomogeneous system $Ax = b$ is

$$x = \text{one particular solution} + \text{general solution to the homogeneous system } Ax = 0$$

A homogeneous system always has a solution:
the **trivial solution** $x = 0$.

A nonhomogeneous system might not have a solution.

A nonhomogeneous system might not have a solution.

Example:

The nonhomogeneous system

$$0 = 1$$

has no solutions

$$\begin{bmatrix} 3 & 5 & -4 \\ -3 & -2 & 4 \\ 6 & 1 & 8 \end{bmatrix} x = \begin{bmatrix} 7 \\ 1 \\ -4 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 5 & -4 & 7 \\ -3 & -2 & 4 & 1 \\ 6 & 1 & 8 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -\frac{4}{3} & -1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$A \xrightarrow{\quad} \begin{bmatrix} 3 & 5 & -4 \\ -3 & -2 & 4 \\ 6 & 1 & 8 \end{bmatrix} x = \begin{bmatrix} 7 \\ 1 \\ -4 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 5 & -4 & 7 \\ -3 & -2 & 4 & 1 \\ 6 & 1 & 8 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -\frac{4}{3} & -1 \\ 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

General solution in
parametric vector form

$$x = \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} \frac{4}{3} \\ 0 \\ 1 \end{bmatrix}$$

particular
solution

solution
to $Ax = 0$

Important

To write the solution set of a consistent system:

- 1) Row-reduce the augmented matrix into reduced echelon form.
- 2) Write each non-free variable in terms of the free ones.
- 3) Write the general solution x as a vector whose entries depend on the free variables (if there are free variables).
- 4) Decompose this as a linear combination of vectors where each coefficient is a free variable (plus possibly one term with coefficient 1 for a particular solution).

Important

Caution! Given a linear system $Ax = b$, there is a big difference between the coefficient matrix A and the augmented matrix $[A \ b]$.

- Is the system $Ax = b$ consistent? \implies look at the augmented matrix.
- The system $Ax = 0$ is always consistent.

We can solve the system by focusing only on A and then finding a particular solution, but if we do so we must remember A is *not* the augmented matrix of the system.

Today's poll code:

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A homogeneous linear system
is always consistent.

A. True

B. False

Today's poll code:

MNE2CY

A nonhomogeneous linear system
is always consistent.

A. True

B. False

Linear independence

v_1, \dots, v_p vectors in \mathbb{R}^n

v_1, \dots, v_p are **linearly independent** if the equation

$$x_1v_1 + \cdots + x_pv_p = 0$$

has no nontrivial solutions.

v_1, \dots, v_p are **linearly dependent** if the equation

$$x_1v_1 + \cdots + x_pv_p = 0$$

has nontrivial solutions

v_1, \dots, v_p vectors in \mathbb{R}^n

v_1, \dots, v_p are **linearly independent** if

$$c_1v_1 + \dots + c_pv_p = 0 \implies c_1 = \dots = c_p = 0$$

v_1, \dots, v_p are **linearly dependent** if

$$c_1v_1 + \dots + c_pv_p = 0$$

for some c_1, \dots, c_p not all zero

v_1, \dots, v_p are **linearly dependent** if

$$c_1v_1 + \cdots + c_pv_p = 0$$

for some c_1, \dots, c_p not all zero



in this case
the equation

$$c_1v_1 + \cdots + c_pv_p = 0$$

is an **equation of linear dependence**

among v_1, \dots, v_p

v_1, \dots, v_p are **linearly independent** if

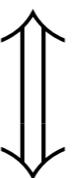
$$c_1v_1 + \cdots + c_pv_p = 0 \implies c_1 = \cdots = c_p = 0$$

$\{v\}$ is linearly independent

v_1, \dots, v_p are **linearly independent** if

$$c_1v_1 + \cdots + c_pv_p = 0 \implies c_1 = \cdots = c_p = 0$$

$\{v\}$ is linearly independent



$$v \neq 0$$

v_1, \dots, v_p are **linearly dependent** if

$$c_1v_1 + \cdots + c_pv_p = 0$$

for some c_1, \dots, c_p not all zero

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ are}$$

v_1, \dots, v_p are **linearly dependent** if

$$c_1v_1 + \cdots + c_pv_p = 0$$

for some c_1, \dots, c_p not all zero

$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ are linearly dependent

v_1, \dots, v_p are **linearly dependent** if

$$c_1v_1 + \cdots + c_pv_p = 0$$

for some c_1, \dots, c_p not all zero

$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ are linearly dependent

for example

$$0 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + 2 \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Theorem. Any set of vectors in \mathbb{R}^n that contains the zero vector is linearly dependent.

v_1, \dots, v_p are **linearly dependent** if

$$c_1v_1 + \cdots + c_pv_p = 0$$

for some c_1, \dots, c_p not all zero

$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$ are linearly dependent

for example

$$2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + (-1) \begin{bmatrix} 2 \\ 0 \end{bmatrix} = 0$$

v_1, \dots, v_p are **linearly dependent** if

$$c_1v_1 + \cdots + c_pv_p = 0$$

for some c_1, \dots, c_p not all zero

$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$ are linearly dependent

for example

$$2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + (-1) \begin{bmatrix} 2 \\ 0 \end{bmatrix} = 0$$

Any two nonzero vectors that are scalar multiples of each other
are linearly dependent.

Any two nonzero vectors that are scalar multiples of each other
are linearly dependent.

v is any nonzero vector and $t \neq 1$



v and tv are linearly dependent

$$t \cdot v + (-1) \cdot (tv) = 0$$

A set $\{v_1, \dots, v_p\}$ of two or more vectors is linearly dependent if and only if one of the vectors is a linear combination of the others.

Note: this does not say that every v_i is a linear combination of the rest.

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \end{bmatrix} \right\}$$

is linearly dependent

since

$$\begin{bmatrix} 2 \\ 2 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

But $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is not a linear combination of the other two vectors

An equation of linear dependence among the vectors v_1, \dots, v_n is a nontrivial solution to the homogeneous system

$$x_1v_1 + \cdots + x_nv_n = 0$$

To decide if the vectors v_1, \dots, v_n are linearly independent, we consider the matrix

$$A = [v_1 \quad \cdots \quad v_n]$$

and ask whether the system

$$Ax = 0$$

has a nontrivial solution

Theorem. The columns of a matrix A are linearly independent if and only if the homogeneous system $Ax = 0$ has only the trivial solution.

$$v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \quad v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

Are v_1 , v_2 , and v_3 linearly independent?

$$v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \quad v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

Are v_1 , v_2 , and v_3 linearly independent?

$$A = [v_1 \quad v_2 \quad v_3] = \begin{bmatrix} 1 & 4 & 2 \\ 2 & 5 & 1 \\ 3 & 6 & 0 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \quad v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

Are v_1 , v_2 , and v_3 linearly independent?

$$A = [v_1 \quad v_2 \quad v_3] = \begin{bmatrix} 1 & 4 & 2 \\ 2 & 5 & 1 \\ 3 & 6 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 4 & 2 \\ 2 & 5 & 1 \\ 3 & 6 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \quad v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

Are v_1 , v_2 , and v_3 linearly independent?

$$A = [v_1 \quad v_2 \quad v_3] = \left[\begin{array}{ccc|c} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \quad v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

Are v_1 , v_2 , and v_3 linearly independent?

$$A = [v_1 \quad v_2 \quad v_3] = \left[\begin{array}{ccc|c} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

free variable

$$v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \quad v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

Are v_1 , v_2 , and v_3 linearly independent?

$$A = [v_1 \quad v_2 \quad v_3] = \left[\begin{array}{ccc|c} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

free variable

$Ax = 0$ has nontrivial solutions \implies

v_1, v_2, v_3 are
linearly dependent

$$A = [v_1 \quad \cdots \quad v_n]$$

v_1, \dots, v_n are

linearly independent



$Ax = 0$ has

only one solution



A has

pivots in every column

Theorem. Consider the matrix

$$A = [v_1 \quad \cdots \quad v_n].$$

The column vectors v_1, \dots, v_n are linearly independent

if and only if

A has a pivot in every column.

$$v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$$

$$v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

free variable

$Ax = 0$ has nontrivial solutions $\implies v_1, v_2, v_3$ are linearly dependent

Relation of linear dependence:

$$v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix}$$

$$v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 1 & 4 & 2 & 0 \\ 2 & 5 & 1 & 0 \\ 3 & 6 & 0 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & -2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

free variable

$Ax = 0$ has nontrivial solutions $\implies v_1, v_2, v_3$ are linearly dependent
 relation of linear dependence: any nontrivial solution to $Ax = 0$

$$\begin{cases} x_3 \text{ free} \\ x_1 = 2x_3 \\ x_2 = -x_3 \end{cases} \implies x = t \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \implies x = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

general solution

particular solution

$$v_1 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \quad v_2 = \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \quad v_3 = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

$Ax = 0$ has nontrivial solutions $\implies v_1, v_2, v_3$ are linearly dependent

$$x = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

particular solution

Relation of linear dependence:

$$2 \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - 1 \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Theorem. Any set of more than n vectors in \mathbb{R}^n is linearly dependent.

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$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

are

- A. Linearly dependent
- B. Linearly independent

Today's poll code:

MNE2CY

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

are

- A. Linearly dependent
- B. Linearly independent

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$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \text{ and } \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

are

- A. Linearly dependent
- B. Linearly independent

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$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} 3 \\ 4 \\ 0 \end{bmatrix}$$

are

- A. Linearly dependent
- B. Linearly independent

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$$\begin{bmatrix} 71 \\ 135 \\ -7 \end{bmatrix} \text{ and } \begin{bmatrix} 8 \\ 42 \\ 0 \end{bmatrix} \text{ and } \begin{bmatrix} -3 \\ 4 \\ 23 \end{bmatrix} \text{ and } \begin{bmatrix} 9 \\ 0 \\ -500 \end{bmatrix}$$

are

- A. Linearly dependent
- B. Linearly independent

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- WebWork 2.2 due Friday
- WeBWorK 2.3 due Tuesday Sep 16
- WeBWorK 2.4 due Friday Sep 19

On Friday:

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at the beginning

of the recitation

on Lectures 4—5

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