

Άσκηση 6

$$r_T \in (b, a), \varphi \in (-\pi/2, \pi) \rightarrow \vec{J} = (J_r, J_\varphi \frac{a^2}{r_T^2} \sin \varphi)$$

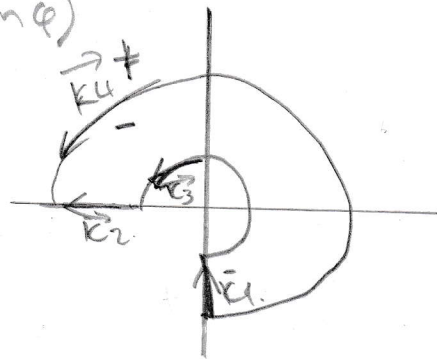
$$r_T \in (b, a), \varphi = -\pi/2 \rightarrow \vec{K}_1 (k_1, 0)$$

$$r_T \in (b, a), \varphi = \pi \rightarrow \vec{K}_2 (k_2, 0)$$

$$r_T = b, \varphi \in (-\pi/2, \pi) \rightarrow \vec{K}_3 (0, k_3)$$

$$r_T = a, \varphi \in (-\pi/2, \pi) \rightarrow \vec{K}_4 (0, k_4)$$

Εξωτερικός



Για το $J(r_T, \varphi)$ εφαρμόζω ΝΔΦ σε σφαίρα. $(r, \varphi) \in (b, a) \times (-\pi/2, \pi)$

$$N \Delta \Phi: \vec{\nabla} J + \frac{\partial \vec{p}^0}{\partial t} = 0 \rightarrow \text{σε φορά την κολοειδίου.}$$

$$\vec{\nabla} J \Leftrightarrow \frac{1}{r_T} \frac{d(r_T J_r)}{dr_T} + \frac{1}{r_T} \frac{dJ_\varphi}{d\varphi} = 0$$

$$\Rightarrow \frac{d(r_T J_r)}{dr_T} + J_0 \left(\frac{a}{r_T}\right)^2 \cos \varphi = 0 \rightarrow \frac{d(r_T J_r)}{dr_T} = -J_0 \left(\frac{a}{r_T}\right)^2 \cos \varphi$$

$$\text{Ολοκληρώνω: } \int_{r_T}^a d(r_T' J_{r_T}') = - \int_{r_T=r_T}^a J_0 \left(\frac{a}{r_T'}\right)^2 \cos \varphi dr_T' + C$$

$$\Rightarrow a J_r(a) - r_T J_r(r_T) = J_0 a^2 \cos \varphi \left[\frac{1}{2} - \frac{1}{r_T} \right] + C$$

$$\Rightarrow J_r(r_T, \varphi) = \frac{J_0 a^2}{r_T} \cos \varphi \left[\frac{1}{2} - \frac{1}{r_T} \right] + C$$

Εφαρμόζω συνοριακές συνθήκες: $\parallel r_T = a$ (παιχνάρο το k_4 που είναι ΝΔΦ σε σφαίρα):

$$\hat{n} \cdot (\vec{J}^+ - \vec{J}^-) = -\nabla \cdot \vec{K} - \frac{\partial \vec{p}^0}{\partial t} \Rightarrow k_T (-C \hat{e}_r) = -k_0 \cos \varphi \Rightarrow \boxed{C = k_0 \cos \varphi}$$

$$\Rightarrow J_r(r_T, \varphi) = \frac{J_0 a^2}{r_T} \cos \varphi \left[\frac{1}{2} - \frac{1}{r_T} \right] + k_0 \cos \varphi$$

$q = \pi$: Γue k_2 :

$\nabla \Delta \Phi$ για ερευνα

$$\hat{\nabla} \ln (\vec{J}^+ - \vec{J}^-) = -\nabla^2 \chi - \frac{d\vec{J}^0}{dt}$$

$$\Rightarrow \hat{\nabla} \ln (\vec{J}^+ - \vec{J}^-) = -\nabla^2 \chi - \frac{d\vec{J}^0}{dt} \Rightarrow \frac{1}{r_T} \frac{d(r_T k_2(r_T))}{dr_T}$$

$$\Rightarrow \int_0^a \frac{a^2}{r_T^2} \sin^2 u = \frac{1}{r_T} \cdot \frac{d(r_T k_2(r_T))}{dr_T}$$

$$\Rightarrow k_2(r_T) = \frac{C}{r_T}$$

$$k_2(a) + k_4(a^-) = 0$$

$$\Rightarrow k_2(r) = 0$$

$r_T = b$: Γue $k_3(u)$:

$$\hat{\nabla} \ln (\vec{J}^+ - \vec{J}^-) = -\nabla^2 k_3 - \frac{d\vec{J}^0}{dt} \Rightarrow \cos u \left[\int_0^a \left(\frac{a^2}{b^2} + k_0 - \int_0^a a \right) = \frac{1}{b} \frac{d(k_3(u))}{du} \right]$$

$$\Rightarrow d k_3(u) = - \left[\int_0^a \left(\frac{a^2}{b} \right) + k_0 - \int_0^a a \right] \cos u du \Leftrightarrow \int_{u=q}^u d(k_3(u)) = - \int_{u=q}^u \cos u' du'$$

$$\Rightarrow k_3(u^-) - k_3(u) = - \int_0^a a \left(\frac{a}{b} - 1 \right) + k_0 \sin u$$

$$k_3(u^-) = k_2(b^+) = 0$$

$k_1(y)$: Ευνοη-ορι στο $q = -\pi/2$:

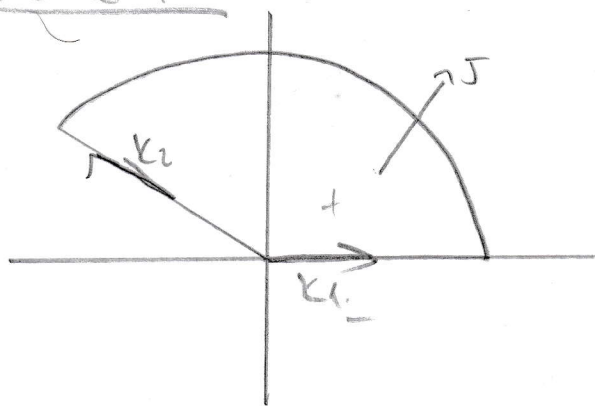
$$\hat{\nabla} \ln (\vec{J}^+ - \vec{J}^-) = -\nabla^2 k_1 - \frac{d\vec{J}^0}{dt} \Rightarrow \int_0^a \left(\frac{a}{y} \right)^2 = \frac{d k_1}{dy} \Rightarrow \int_0^a a^2 \int_y^a d \left(\frac{1}{y} \right) = \int_y^a d k_1(y')$$

$$\Rightarrow \int_0^a a^2 \left(\frac{1}{a} - \frac{1}{y} \right) = k_1(a) - k_1(y) \Rightarrow k_1(y) = \int_0^a \frac{a^2}{y} - \int_0^a a + k_1(a)$$

$$\text{Αρα } k(a) = k_4(-\pi/2^+) \Rightarrow k_1(a) = +k_0 \sin(-\pi/2) - k_0$$

$$\Rightarrow k_1(y) = \int_0^a \frac{a^2}{y} + k_0 - \int_0^a a$$

Άσκηση 7



$$r < a, \varphi \in (0, 2\pi/3) \rightarrow \vec{J}(J_r, J_\varphi \cos \varphi)$$

$$r < a, \varphi = 0 \rightarrow \vec{k}_1(k_1, 0)$$

$$r < a, \varphi = 2\pi/3 \rightarrow \vec{k}_2(k_2, 0)$$

Για το $J(r, \varphi)$ εφαρμόζω ΝΔΦ με συντεταγμένες $(r, \varphi) \in (0, a) \times (0, 2\pi/3)$

$$\vec{\nabla} J + \frac{\partial J}{\partial t} = 0 \Rightarrow \frac{1}{r} \frac{\partial (r J_r)}{\partial r} + \frac{1}{r} \frac{\partial (J_\varphi \cos \varphi)}{\partial \varphi} = 0$$

$$\Rightarrow \frac{\partial (r J_r)}{\partial r} + \frac{\partial (J_\varphi \cos \varphi)}{\partial \varphi} = 0$$

$$\Rightarrow \frac{\partial (r J_r)}{\partial r} - J_\varphi \sin \varphi = 0$$

$$\Rightarrow \int_{r=r_0}^a \frac{\partial (r J_r)}{\partial r} dr = \int_{r=r_0}^a J_\varphi \sin \varphi dr + C$$

$$\Rightarrow a J_r(a) - r J_r = J_\varphi \sin \varphi [r - a] + C(\varphi)$$

$$\Rightarrow r J_r = J_\varphi \sin \varphi \left[\frac{r-a}{r} \right]$$

Θέτω $\varphi = 0$ και ορίζω $J_\varphi = 0$

$$\hat{n} \cdot (\vec{J}(y=0^+) - \vec{J}(y=0^-)) + \vec{\nabla} k_1 = 0 \Rightarrow \hat{r} \cdot (\vec{J}(\varphi=0, r)) + \vec{\nabla} k_1 = 0$$

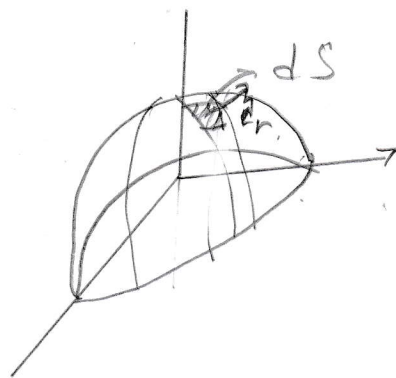
$$\Rightarrow J_0 + \frac{\partial k_1}{\partial r} = 0 \Rightarrow \frac{\partial k_1}{\partial r} = -J_0$$

$$\text{Για } r \Rightarrow k_1(a) = 0 \Rightarrow 0 = J_0 a \Rightarrow k_1(r) = J_0(a-r) \Rightarrow k_1(r_2) = 0 - J_0 r$$

Ορίζω $\varphi = 2\pi/3$

$$\hat{n} \cdot (\vec{J}(r, \varphi=2\pi/3^+) - \vec{J}(r, \varphi=2\pi/3^-)) + \vec{\nabla} k_2 = 0 \Rightarrow -J_\varphi(r, \varphi=2\pi/3) = -\frac{\partial k_2}{\partial r}$$

$$\Rightarrow k_2(r) = a - J_0 r$$

$$J = \frac{1}{r} \frac{\partial}{\partial r} (r k_r) + \frac{1}{r^2} \frac{\partial}{\partial \theta} (r^2 k_\theta)$$


$$\vec{\chi}_1(\chi_1, 0, 0) \rightarrow \theta = \pi/2.$$

$$N\Delta Q \Rightarrow \oint_S \vec{J} \cdot d\vec{S} + \int_V \frac{d\rho}{dt} dV = 0$$

$$\text{Ques } i(r) = \int_{r'=r}^{a} \int_0^{2\pi} \frac{k_0}{r' \sin \theta} \cancel{r' \sin \theta} \, d\phi \, dr' =$$

Θα υπολογιστεί με επιλογή και αντιστοίχως k

$$\ln(5 \pm \cancel{8^9}) + \vec{v} \cdot \vec{k} + \cancel{\frac{d}{dt}} = 0$$

$$\Rightarrow -\hat{l}_z \hat{l}_z \frac{k_0}{r} + \frac{1}{r} \frac{\partial}{\partial r} (rk) = 0 \Rightarrow rk = k_0 r + C \quad (C \in \mathbb{R})$$

$$\rightarrow K_0 = -\frac{C}{a}$$

$$\vec{K}(r) = \left(k_0 - \frac{k_0 a}{r} \right) \hat{r} \Rightarrow \vec{K}(r) = k_0 \left(1 - \frac{a}{r} \right) \hat{r}$$