IML Exercise 1 Answers

- 2. Theoretical part
- 2.1. Mathematical Background
- 2.1.1. Linear Algebra
 - 1. For any orthogonal matrix $A \in M_{n \times n}$ the linear transformation by A is isometric. i.e.: $\forall x \in V_n : ||Ax||_2 = ||x||_2$

Proof: Orthogonal Matrix is made of columns that are orthonormal vectors, i.e. they are $\{v_1, v_2, \dots, v_n\}: \forall i \in [n] \ \|v_i\| = 1$

and $\forall i \in [n]: \langle v_i, v_i \rangle = 1$, $\forall i, j \in [n] \ i \neq j: \langle v_i, v_j \rangle = 0$ vectors are mutually perpendicular.

and the $span(\{v_1, v_2, ..., v_n\}) = \mathbb{R}^n$

And for the reciprocal matrix $A^{\mathsf{T}}A = AA^{\mathsf{T}} = I = A^{-1}A = AA^{-1}$

So as a result, $\forall x \in \mathbb{R}^n$ can be represented by this base: $x = \sum a_i v_i$

For simplicity we'll prove the square of each norm $||Ax||_2^2 = ||x||_2^2$ Since the norms are in \mathbb{R}^+ even after taking the root we know it is not negative.

$$||x||^2 = \langle x, x \rangle = x^\top x \qquad - (\sum a_i v_i)^\top (\sum a_i v_i) = \sum_i \sum_i a_i a_i v_i^\top v_i =$$

$$||Ax||^2 = \langle Ax, Ax \rangle = (Ax)^{\mathsf{T}} (Ax) = x^{\mathsf{T}} A^{\mathsf{T}} Ax = x^{\mathsf{T}} x$$

So $||Ax||^2 = ||x||^2$ and hence: ||Ax|| = ||x||

2. We'll calculate SVD for $A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & -1 & 2 \end{bmatrix} = U\Sigma V^{\top}$

We can start the decomposition by wither calculating $A^{T}A$ or AA^{T}

Smaller and easier: $AA^{T} = U\Sigma V^{T}V\Sigma^{T}U^{T} = U\Sigma\Sigma^{T}U^{T}$

$$AA^{\top} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & -1 & 2 \end{bmatrix} \times \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 6 \end{bmatrix}$$
$$= I_{2\times 2} \times \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & \sqrt{6} & 0 \end{bmatrix} \times \begin{bmatrix} \sqrt{2} & 0 \\ 0 & \sqrt{6} \\ 0 & 0 \end{bmatrix} \times I_{2\times 2} = U\Sigma\Sigma^{\top}U^{\top}$$

So:
$$U = I_{2\times 2} = U^{\top} \quad \Sigma = \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & \sqrt{6} & 0 \end{bmatrix}$$

Now for computing V we will make EVD that we already know it's e.vals and we need only to compute the e.vecs:

$$A^{\mathsf{T}} A = V \Sigma^{\mathsf{T}} U^{\mathsf{T}} U \Sigma V^{\mathsf{T}} = V \Sigma^{\mathsf{T}} \Sigma V^{\mathsf{T}} = V \times \begin{bmatrix} 2 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times V^{\mathsf{T}}$$

$$A^{\mathsf{T}}A = \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 0 & 2 \end{bmatrix} \times \begin{bmatrix} 1 & 1 & 0 \\ 1 & -1 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 2 \\ 0 & 2 & -2 \\ 2 & -2 & 4 \end{bmatrix} = V \times \begin{bmatrix} 2 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 0 \end{bmatrix} \times V^{\mathsf{T}} = A'$$

For
$$\lambda_1 = 2$$
 : $\operatorname{null}(A' - \lambda I)$ is by $\begin{bmatrix} 2 & 0 & 2 \\ 0 & 2 & -2 \\ 2 & -2 & 4 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 2 \\ 0 & 0 & -2 \\ 2 & -2 & 2 \end{bmatrix}$

$$\begin{bmatrix} 0 & 0 & 2 \\ 0 & 0 & -2 \\ 2 & -2 & 2 \end{bmatrix} \times \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{array}{l} z = 0 \\ z = 0 \\ x + \overline{z} = y \end{array}$$
 So the e.vec:
$$\begin{bmatrix} \alpha \\ \alpha \\ 0 \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}$$

Normalized by: $1 = ||e.vec||_2 = \sqrt{\alpha^2 + \alpha^2 + 0} = \sqrt{2} \cdot \alpha \Rightarrow \alpha = 1/\sqrt{2}$

For
$$\lambda_2 = 6$$
: null $(A' - \lambda I)$ is by $\begin{bmatrix} 2 & 0 & 2 \\ 0 & 2 & -2 \\ 2 & -2 & 4 \end{bmatrix} - \begin{bmatrix} 6 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 6 \end{bmatrix} = \begin{bmatrix} -4 & 0 & 2 \\ 0 & -4 & -2 \\ 2 & -2 & -2 \end{bmatrix}$

$$\operatorname{null} \begin{bmatrix} -4 & 0 & 2 \\ 0 & -4 & -2 \\ 2 & -2 & -2 \end{bmatrix} = \begin{bmatrix} r_1 \\ r_2 \\ r_3 + 0.5r_1 \end{bmatrix} \begin{bmatrix} -4 & 0 & 2 \\ 0 & -4 & -2 \\ 0 & -2 & -1 \end{bmatrix} = \begin{bmatrix} r_1 \\ r_2 \\ r_3 - 0.5r_2 \end{bmatrix} \begin{bmatrix} -4 & 0 & 2 \\ 0 & -4 & -2 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} -4 & 0 & 2 \\ 0 & -4 & -2 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} 2x = z \\ -2y = z \text{ So the e.vec: } \begin{bmatrix} \alpha \\ -\alpha \\ 2\alpha \end{bmatrix} = \begin{bmatrix} 1/\sqrt{6} \\ -1/\sqrt{6} \\ \sqrt{4/6} \end{bmatrix}$$

Normalized by: $1 = \|e.vec\|_2 = \sqrt{\alpha^2 + \alpha^2 + 4\alpha^2} = \sqrt{6} \cdot \alpha \implies \alpha = \frac{1}{\sqrt{6}}$

$$\operatorname{For} \lambda_3 = 0 : \operatorname{null}(A' - \underbrace{\lambda I}) \text{ is by } \begin{bmatrix} 2 & 0 & 2 \\ 0 & 2 & -2 \\ 2 & -2 & 4 \end{bmatrix} - \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 2 \\ 0 & 2 & -2 \\ 2 & -2 & 4 \end{bmatrix}$$

$$\operatorname{null}\begin{bmatrix}2 & 0 & 2 \\ 0 & 2 & -2 \\ 2 & -2 & 4\end{bmatrix} = \begin{matrix}r_1 \\ r_2 \\ r_3 - r_1\end{matrix} \operatorname{null}\begin{bmatrix}2 & 0 & 2 \\ 0 & 2 & -2 \\ 0 & -2 & 2\end{bmatrix} = \begin{matrix}r_1 \\ r_2 \\ r_3 + r_2\end{matrix} \operatorname{null}\begin{bmatrix}2 & 0 & 2 \\ 0 & 2 & -2 \\ 0 & 0 & 0\end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 & 2 \\ 0 & 2 & -2 \\ 0 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Rightarrow \begin{cases} -x = z \\ y = z \\ 0 = 0 \end{cases}$$
 So the e.vec:
$$\begin{bmatrix} -\alpha \\ \alpha \\ \alpha \end{bmatrix} = \begin{bmatrix} -1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}$$

Normalized by: $1 = \|e.vec\|_2 = \sqrt{\alpha^2 + \alpha^2 + \alpha^2} = \sqrt{3} \cdot \alpha \Rightarrow \alpha = 1/\sqrt{3}$

So collecting overall e.vecs:
$$V = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{6} & -1/\sqrt{3} \\ 1/\sqrt{2} & -1/\sqrt{6} & 1/\sqrt{3} \\ 0 & \sqrt{2/3} & 1/\sqrt{3} \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & -1 & 2 \end{bmatrix} = U\Sigma V^{\mathsf{T}} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \times \begin{bmatrix} \sqrt{2} & 0 & 0 \\ 0 & \sqrt{6} & 0 \end{bmatrix} \times \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 1/\sqrt{6} & -1/\sqrt{6} & \sqrt{2/3} \\ -1/\sqrt{3} & 1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix}$$

If we want e.vals sorted in the Σ matrix it will look like

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & -1 & 2 \end{bmatrix} = U\Sigma V^{\mathsf{T}} = \underbrace{\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}}_{row\ swap} \times \begin{bmatrix} \sqrt{6} & 0 & 0 \\ 0 & \sqrt{2} & 0 \end{bmatrix} \times \begin{bmatrix} 1/\sqrt{6} & -1/\sqrt{6} & \sqrt{2/3} \\ 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ -1/\sqrt{3} & 1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix}$$

3. We'll prove the power-iteration algorithm convergence to $\pm v_1$ (e.vec of λ_1) when $\forall i \in \{2...n\}: \lambda_1 > \lambda_i$ and initial selected $b_0 = \sum_{i=1}^n a_i v_i$ has $a_1 \neq 0$

First we'll prove that
$$b_{k+1}=rac{c_0^{k+1}b_0}{\|c_0^{k+1}b_0\|} \ \ \forall k\in\mathbb{R}^+$$
 by recursion

For
$$b_1=rac{C_0^1b_0}{\|C_0^1b_0\|}$$
 by definition, Assuming $b_k=rac{C_0^kb_0}{\|C_0^kb_0\|}$:

$$b_{k+1} = \frac{C_0^1 b_k}{\|C_0^1 b_k\|} = \frac{C_0^1 \frac{C_0^k b_0}{\|C_0^k b_0\|}}{\left\|C_0^1 \frac{C_0^k b_0}{\|C_0^k b_0\|}\right\|} = \frac{C_0^1 C_0^k b_0}{\left\|C_0^k b_0\right\|} \cdot \frac{1}{\left(\frac{1}{\|C_0^k b_0\|}\right) \|C_0^1 C_0^k b_0\|} = \frac{C_0^{k+1} b_0}{\left\|C_0^{k+1} b_0\right\|}$$

Now
$$C_0^m = (A^{\mathsf{T}}A)^m = (V\Sigma^{\mathsf{T}}\Sigma V^{\mathsf{T}})^m = \underbrace{(V\Sigma^{\mathsf{T}}\Sigma V^{\underline{\mathsf{T}}})(V\Sigma^{\mathsf{T}}\Sigma V^{\underline{\mathsf{T}}})\dots(V\Sigma^{\mathsf{T}}\Sigma V^{\mathsf{T}})}_{m \ times} = VD^mV^{\mathsf{T}}$$

when $D \stackrel{\text{def}}{=} \Sigma^{\mathsf{T}} \Sigma$ and is a diagonal matrix with $\lambda_1 \dots \lambda_n$ on its diagonal.

Now let's examine:
$$C_0^{k+1}b_0 = VD^{k+1}V^{\mathsf{T}}\sum a_iv_i = VD^{k+1}\sum\sum a_iv_i^{\mathsf{T}}v_i\widehat{e}_i = VD^{k+1}\sum\sum a_iv_i^{\mathsf{T}}v_i\widehat{e}_i$$

$$\begin{split} VD^{k+1} \sum \sum a_i \delta_{ij} \widehat{e_j} &= VD^{k+1} \sum a_i \widehat{e_i} = V \sum \lambda_i^{k+1} a_i \widehat{e_i} = V \sum \lambda_i^{k+1} a_i \widehat{e_i} = \sum \lambda_i^{k+1} a_i V \widehat{e_i} = \\ & \sum \lambda_i^{k+1} a_i v_i \end{split}$$

$$\begin{aligned} \left\| C_0^{k+1} b_0 \right\|^2 &= \left\langle \sum \lambda_i^{k+1} a_i v_i , \sum \lambda_j^{k+1} a_j v_j \right\rangle = \sum \sum a_i a_j \lambda_i^{k+1} \lambda_j^{k+1} \left\langle v_i, v_j \right\rangle = \\ &= \sum \sum a_i a_j \lambda_i^{k+1} \lambda_j^{k+1} \delta_{ij} = \sum a_i^2 \lambda_i^{2k+2} \end{aligned}$$

So:

$$b_{k+1} = \frac{C_0^{k+1}b_0}{\|C_0^{k+1}b_0\|} = \frac{\sum \lambda_i^{k+1}a_iv_i}{\left(\sum a_i^2\lambda_i^{2k+2}\right)^{1/2}} \underbrace{\rightarrow_{k\to\infty}}_{*} \frac{\lambda_1^{k+1}a_1}{|\lambda_1^{k+1}a_1|} v_1 = \begin{cases} +v_1 & \text{if } a_1 > 0 \\ -v_1 & \text{if } a_1 < 0 \end{cases}$$

* - Since $\lambda_1 >$ other λ s it dominants when k goes to infinity.

4. For $x \in \mathbb{R}^n$ fixed, $U \in \mathbb{R}^{n \times n}$ fixed orthogonal matrix, $f: \mathbb{R}^n \to \mathbb{R}^n$ $f(\sigma) = U \operatorname{diag}(\sigma) U^{\top} x$

Since U is orthogonal matrix it's columns are vectors that spans \mathbb{R}^n so we can express x:

$$x = \sum a_i u_i \text{ or } U \times \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = x \text{ and to get this } \overline{a} \text{ use } \overline{a} = U^{\mathsf{T}} x$$

$$f(\sigma) = U \operatorname{diag}(\sigma) \ U^{\mathsf{T}} \sum a_i u_i = U \operatorname{diag}(\sigma) \sum \sum a_i u_j^{\mathsf{T}} u_i \widehat{e}_j =$$

$$= U \operatorname{diag}(\sigma) \sum a_i \widehat{e}_i = U \sum \sigma_i a_i \widehat{e}_i = \sum \sigma_i a_i u_i$$

So the Jacobian:

$$J_{\sigma}\big(f(\sigma)\big) = \begin{bmatrix} f_1(\sigma) \\ \vdots \\ f_n(\sigma) \end{bmatrix} \times \begin{bmatrix} \frac{\partial}{\partial \sigma_1} & \dots & \frac{\partial}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_1} & \dots & \frac{\partial f_1(\sigma)}{\partial \sigma_n} \\ \vdots & & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_1} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_n(\sigma)}{\partial \sigma_n} & \dots & \frac{\partial f_n(\sigma)}{\partial \sigma_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial f_1(\sigma)}{\partial \sigma_n} & \dots &$$

We'll examine on specific index k, l:

$$J_{\sigma}(f(\sigma))_{kl} = \left(J_{\sigma}(\sum \sigma_{l} a_{l} u_{l})\right)_{kl} = \frac{\partial (\sum \sigma_{l} a_{l} u_{l})_{k}}{\partial \sigma_{l}} = (a_{l} \overline{u_{l}})_{k} = a_{l} U_{kl}$$

$$J_{\sigma}\big(f(\sigma)\big) = \begin{bmatrix} a_1U_{11} & \dots & a_nU_{1n} \\ \vdots & & \vdots \\ a_1U_{n1} & \dots & a_nU_{nn} \end{bmatrix} = U \times \begin{bmatrix} a_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & a_n \end{bmatrix} = U \operatorname{diag}(\bar{a})$$

$$J_{\sigma}(f(\sigma)) = U \operatorname{diag}(U^{\mathsf{T}}x)$$

5. For $h: \mathbb{R}^n \to \mathbb{R}$ $h(\sigma) = \frac{1}{2} \|f(\sigma) - y\|^2$ we want to find $\nabla_x(h(x))$

We got:
$$f: \mathbb{R}^n \to \mathbb{R}^n$$
 $f(\sigma) = U \operatorname{diag}(\sigma) U^{\mathsf{T}} x$

Define:
$$g: \mathbb{R}^n \to \mathbb{R}$$
 $g(x) \stackrel{\text{def}}{=} \frac{1}{2} ||x||^2$ $\nabla_x(g): \mathbb{R} \to \mathbb{R}^n$

We'll leaned in the recitation that for $g(x) \stackrel{\text{def}}{=} \frac{1}{2} ||x||^2$: $\nabla_x (g(x)) = \nabla_x (\frac{1}{2} ||x||^2) = x$

Short proof:
$$\nabla_x \left(\frac{1}{2} \|x\|^2\right)_i = \frac{\partial_{\frac{1}{2}}^1 \|x\|^2}{\partial x_i} = \frac{1}{2} \frac{\partial x^T x}{\partial x_i} = \frac{1}{2} \frac{\partial \sum x_k^2}{\partial x_i} = \frac{1}{2} (2x_i + 0) = x_i$$

$$\nabla_{\sigma}(h(\sigma)) = \nabla_{\sigma}(g(f(\sigma) - y)) = \nabla_{f(\sigma)}(g(f(\sigma) - y)) \times J_{\sigma}(f(\sigma)) =$$

$$= \underbrace{f(\sigma)}_{\nabla_{f(\sigma)}\left(\frac{1}{2}\|f(\sigma)\|^{2}\right) = f(\sigma)} \times \underbrace{U \operatorname{diag}(U^{\mathsf{T}}x)}_{\operatorname{const in } w} = \underbrace{(U \operatorname{diag}(\sigma) U^{\mathsf{T}}x)^{\mathsf{T}}}_{f(\sigma) \in \mathbb{R}^{1 \times n}} \times \underbrace{U \operatorname{diag}(U^{\mathsf{T}}x)}_{\in \mathbb{R}^{n \times n} \operatorname{const in } w}$$
$$= x^{\mathsf{T}} U \operatorname{diag}(\sigma) U^{\mathsf{T}}U \operatorname{diag}(U^{\mathsf{T}}x)$$

$$= x^{\mathsf{T}} U \operatorname{diag}(\sigma) \operatorname{diag}(U^{\mathsf{T}} x) \quad \text{of } \mathbb{R}^{1 \times n}$$

6. The soft-max function is $S: \mathbb{R}^d \to [0,1]^k \quad \forall j \in [d]: \quad S(x)_j = \frac{e^{x_j}}{\sum_{l=1}^k e^{x_l}}$ We'll assume k=d as was answered in the exercise forum. The Q's is $J_x \big(S(x) \big) = ?$

$$\begin{split} \operatorname{By}\left(\frac{g(x)}{f(x)}\right)' &= \frac{g'(x)f(x) - f'(x)g(x)}{f^2(x)} \\ \operatorname{We have} \frac{\partial S(x)_j}{\partial x_i} &= \frac{1}{\left(\sum_{l=1}^k e^{x_l}\right)^2} \cdot \left(\frac{\partial e^{x_j}}{\partial x_i} \sum_{l=1}^k e^{x_l} - \frac{\partial \sum_{l=1}^k e^{x_l}}{\partial x_i} e^{x_j}\right) = \\ &= \frac{1}{\left(\sum_{l=1}^k e^{x_l}\right)^2} \cdot \left(\delta_{ij} e^{x_j} \sum_{l=1}^k e^{x_l} - e^{x_i} e^{x_j}\right) = \\ &= \frac{\delta_{ij} e^{x_j}}{\sum_{l=1}^k e^{x_l}} - \frac{e^{x_i} e^{x_j}}{\left(\sum_{l=1}^k e^{x_l}\right)^2} = \\ &= \frac{e^{x_j}}{\sum_{l=1}^k e^{x_l}} \left(\delta_{ij} - \frac{e^{x_i}}{\sum_{l=1}^k e^{x_l}}\right) = \\ &S(x)_j \left(\delta_{ij} - S(x)_i\right) \end{split}$$

So the Jacobian is
$$J_x (S(x)) = \begin{bmatrix} S(x)_1 - S(x)_1^2 & -S(x)_1 S(x)_2 & \dots & -S(x)_1 S(x)_d \\ -S(x)_1 S(x)_2 & S(x)_2 - S(x)_2^2 & \dots & -S(x)_2 S(x)_d \\ \vdots & \vdots & \ddots & \vdots \\ -S(x)_1 S(x)_d & -S(x)_2 S(x)_d & \dots & S(x)_d - S(x)_d^2 \end{bmatrix}$$

Note it is a symmetric matrix.

It is positive on the diagonal and negative on the rest of the entries.

7. The function $f: \mathbb{R}^2 \to \mathbb{R}$ $f(x,y) = x^3 - 5xy - y^5$, we'll find the Hessian of f

$$\nabla f(x,y) = \left[\frac{\partial f(x,y)}{\partial x}, \frac{\partial f(x,y)}{\partial y} \right] = [3x^2 - 5y, -5y^4 - 5x]$$

$$H[f(x,y)] = \begin{bmatrix} \frac{\partial^2 f(x,y)}{\partial x^2} & \frac{\partial^2 f(x,y)}{\partial x \partial y} \\ \frac{\partial^2 f(x,y)}{\partial y \partial x} & \frac{\partial^2 f(x,y)}{\partial y} \end{bmatrix} = \begin{bmatrix} 6x & -5 \\ -5 & -20y^3 \end{bmatrix}$$

2.2. Estimation Theory

8. $x_1, x_2, ... \sim^{\text{i.i.d}} \mathcal{P}$ with $\mathbb{E}(\mathcal{P}) = \mu$, $Var(\mathcal{P}) = \sigma^2$ finite. We look on first $n \in \mathbb{N}$ and the mean estimator $\hat{\mu}_n = \frac{1}{n} \sum x_i$ This estimator is unbiased as we saw in the lecture and $\mathbb{E}(\hat{\mu}_n) = \mu$ We'll show it is also consistent meaning the probability is concentrated around the expected value with $\mathbb{P}(|\mu - \hat{\mu}_n| > \varepsilon) \xrightarrow{n \to \infty} 0$

By Chebyshev:

$$\mathbb{P}(|\mu - \hat{\mu}_n| > \varepsilon) < \frac{Var(\hat{\mu}_n)}{\varepsilon^2}$$

As we saw in the lecture

$$Var(\hat{\mu}_n) = Var\left(\frac{1}{n}\sum x_i\right) = \frac{1}{n^2}Var(\sum x_i) = \frac{1}{n^2}\sum_{i=j}^{|\cdot|=n}Var(x_i) + \underbrace{\sum_{i\neq j}^{|\cdot|=n^2-n}Cov(x_i,x_j)}_{0 \text{ bacuse it's i.i.d}}$$
$$Var(\hat{\mu}_n) = \frac{n}{n^2}\sigma^2$$

So for every finite given μ , σ , ε the bounding is: $\mathbb{P}(|\mu - \hat{\mu}_n| > \varepsilon) < \frac{\sigma^2}{n \cdot \varepsilon^2} \underset{n \to \infty}{\longrightarrow} 0$

9. The sample set: $x_1, x_2, ... x_m \sim^{\text{i.i.d}} \mathcal{N}(\mu, \Sigma)$ when $\mu \in \mathbb{R}^d$, $\Sigma \in \mathbb{R}^{d \times d}$ are finite. We saw in the lecture the PDF of a sample is:

$$f(X) = \frac{1}{\sqrt{(2\pi)^d |\Sigma|}} \exp\left(-\frac{1}{2}(X - \mu)^{\mathsf{T}} \Sigma^{-1} (X - \mu)\right)$$

The likelihood of the m i.i.d. samples set will be:

$$\mathcal{L}(\mu, \Sigma | \boldsymbol{x}_1, \boldsymbol{x}_2, \dots, \boldsymbol{x}_m) = \prod_{i=1}^m \mathcal{L}(\mu, \Sigma | \boldsymbol{x}_i)$$

$$\mathcal{L}(\mu, \Sigma | \boldsymbol{x}_1, \boldsymbol{x}_2, \dots, \boldsymbol{x}_m) = \prod_{i=1}^m \left((2\pi)^d |\Sigma| \right)^{-\frac{1}{2}} \exp\left(-\frac{1}{2} (\boldsymbol{x}_i - \mu)^\top \Sigma^{-1} (\boldsymbol{x}_i - \mu) \right)$$

So the log-likelihood will be:

$$\ell(\mu, \Sigma | \mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_m) = \sum_{i=1}^m -\frac{d}{2} \log(2\pi) - \frac{1}{2} \log(|\Sigma|) - \frac{1}{2} (\mathbf{x}_i - \mu)^{\mathsf{T}} \Sigma^{-1} (\mathbf{x}_i - \mu)$$

While for a single sample:

$$\ell(\mu, \Sigma | \boldsymbol{x}_i) = -\frac{\mathrm{d}}{2} \log(2\pi) - \frac{1}{2} \log(|\Sigma|) - \frac{1}{2} (\boldsymbol{x}_i - \mu)^{\mathsf{T}} \Sigma^{-1} (\boldsymbol{x}_i - \mu)$$

3. Practical part

3.1. Univariate Gaussian Estimation

1. From a 1000 samples of normal distribution of $\mathcal{N}(10,1)$ with np.random.seed(0), we got estimated mean , variance (unbiased estimator) of:

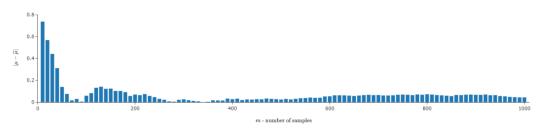
(9.954743292509804, 0.9752096659781323)

Calculated by:
$$\hat{\mu}_m = \frac{1}{m} \sum_{i=1}^m x_i$$
 $\hat{\sigma}_m^2 = \frac{1}{m-1} \sum_{i=1}^m (x_i - \hat{\mu}_m)^2$

$$\hat{\sigma}_m^2 = \frac{1}{m-1} \sum_{i=1}^m (x_i - \hat{\mu}_m)^2$$

2. When sample set size is increasing from 10 to 1000 only on the samples set we already took on Q1, the consistency is demonstrated.

Question 2 - Empirically showing sample mean is consistent

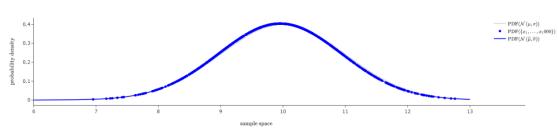


3. The Probability-Density-Function of the values in the data set of 1000 samples of $\mathcal{N}(10,1)$ with np.random.seed(0), is compared here versus the ideal PDF.

We can see we under-estimated the variance (0.975) and the ideal was slightly higher (1.0)

The PDF of the sample points are on the estimated normal distribution model.

Question 3 - Plotting Empirical PDF of fitted model



3.2. Multivariate Gaussian Estimation

4. From a 1000 samples of normal distribution of $\mathcal{N}(\mu, \Sigma)$ when

$$\mu = [0,0,4,0] \quad \Sigma = \begin{bmatrix} 1 & 0.2 & 0 & 0.5 \\ 0.2 & 2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0.5 & 0 & 0 & 1 \end{bmatrix}$$

```
with np.random.seed(0),
```

We estimate expected value by: $\, \hat{\mu}_{m_i} = \frac{1}{m} \sum_{k=1}^m x_{i_k} \,$

We estimate variance value by: $\hat{\sigma}_{m_{ij}}^2 = \frac{1}{m-1} \sum_{k=1}^m \left(x_{j_k} - \hat{\mu}_{m_j} \right) \left(x_{i_k} - \hat{\mu}_{m_i} \right)$

we got estimated mean , variance (unbiased estimator) of:

```
Estimated mu vector is

[-0.02282878 -0.04313959 3.9932571 -0.02038981]

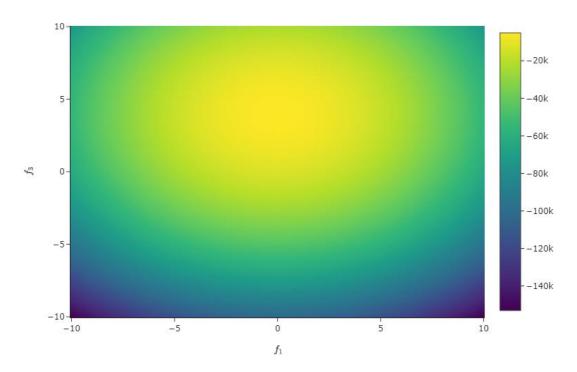
Estimated Covariance (Sigma) matrix is

[[ 0.91667608 0.16634444 -0.03027563 0.46288271]
  [ 0.16634444 1.9741828 -0.00587789 0.04557631]
  [-0.03027563 -0.00587789 0.97960271 -0.02036686]
  [ 0.46288271 0.04557631 -0.02036686 0.9725373 ]]
```

5. With the same covariance Matrix and same samples as in Q4, we scan the most probable $\mu = [f_1, 0, f_3, 0]$ vector.

We expect to get the result of $\widehat{f}_1\cong 0$, $\widehat{f}_3\cong 4$ and this is indeed the point with the highest log-likelihood.

Question 5 - Likelihood evaluation $\mu = [f_1, 0, f_3, 0]$



6. The highest probable f_1 , f_3 are

```
(f1,f3) = (-0.05, 3.97)
```

(Note it comes from an estimation with resolution of $\frac{10-(-10)}{200-1}\cong\frac{1}{10}$ and at the center of the range we have ~ ... -0.15, -0.05, 0.05, 0.15 ...)