Implementation and Performance Analyses of a Highly Efficient Algorithm for Pressure-Velocity Coupling

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Contents

1		oduction	1
		State of Research and Knowledge	
	1.2	Structure of the Thesis	2
2	Eum	domentals of Continuum Dhysics for Thorma Hydrodynamical Droblems	4
_		damentals of Continuum Physics for Thermo-Hydrodynamical Problems Conservation of Mass – Continuity Equation	-
	2.1		
	2.3	Closing the System of Equations – Newtonian Fluids	
		Conservation of Scalar Quantities	
	2.4	· · · · · · · · · · · · · · · · · · ·	
	2.5	Necessary Simplification of Equations	
		2.5.1 Incompressible Flows and Hydrostatic Pressure	
		2.5.2 Variation of Fluid Properties – The Boussinesq Approximation	
	2.6	Final Form of the Set of Equations	./
3	Finit	te-Volume Methods for Incompressible Flows – Theoretical Basics	8
_		Numerical Grid	
		Approximation of Integrals and Derivatives	
		Treatment of Non-Orthogonality of Grid Cells	
	3.3	3.3.1 Minimum Correction Approach	
		3.3.2 Orthogonal Correction Approach	
		3.3.3 Over-Relaxed Approach	
		3.3.4 Deferred Non-Orthogonal Correction	
	2 4	Numerical Solution of Non-Linear Systems – Picard Iteration	
	3.4	Numerical Solution of Non-Linear Systems – Picard Iteration	11
4	Imp	licit Finite-Volume Method for Incompressible Flows – Segregated Approach	12
		Discretization of the Mass Balance	12
	4.2	A Pressure-Weighted Interpolation Method for Velocities	12
		Implicit Pressure Correction and the SIMPLE-Algorithm	
		Discretization of the Mass Fluxes and the Pressure Correction Equation	
	4.5	Discretization of the Momentum Balance	
		4.5.1 Linearization and Discretization of the Convective Term	
		4.5.2 Discretization of the Diffusive Term	
		4.5.3 Discretization of the Source Terms	
	4.6	Discretization of the Temperature Equation	
		Boundary Conditions	
	,	4.7.1 Dirichlet Boundary Conditions	
		4.7.2 Treatment of Wall Boundaries	
		4.7.3 Treatment of Block Boundaries	
	4.8	Treatment of the Singularity of the Pressure Correction Equation with Neumann Boundaries	
	4.9	Structure of the Assembled Linear Systems	
	,		
5	Imp	licit Finite-Volume Method for Incompressible Flows – Fully Coupled Approach	28
	5.1	The Fully Coupled Algorithm – Pressure-Velocity Coupling Reconsidered	28
	5.2		
		5.2.1 Decoupled Approach – Explicit Velocity-to-Temperature Coupling	29
		5.2.2 Implicit Velocity-to-Temperature Coupling	
		5.2.3 Temperature-to-Velocity/Pressure Coupling – Newton-Raphson Linearization	30
	5.3	Boundary Conditions on Domain and Block Boundaries	31
	5.4	Assembly of Linear Systems – Final Form of Equations	32
_	C 4 =	FA Francescoule	20
6		FA Framework	36
		PETSc Framework	
	6.2	8	
	6.3	Implementation of CAFFA	
		6.3.1 The Message-Passing Model	
		6.3.2 Convergence Control	37

		6.3.3 Indexing of Variables and Treatment of Boundary Values	
7	Veri	ification of the developed CAFFA Framework	40
	7.1	The Method of Manufactured Solutions for Navier-Stokes Equations	40
	7.2	Manufactured Solution for the Navier-Stokes Equations and the Temperature Equation	
	7.3	Measurement of Error and Calculation of Order	
	7.4	Influence of the Under-Relaxation Factor for the Velocities	42
8	Com	nparison of Solver Concepts	45
	8.1		45
		8.1.1 Employed Hardware and Software – The Lichtenberg-High Performance Computer	45
		8.1.2 Measures of Performance	45
		8.1.3 Preliminary Upper Bounds on Performance – The STREAM Benchmark	46
		8.1.4 Speed-Up Measurement and Impact of Coupling Algorithm for Analytic Test Case	
	8.2		
	8.3		
	8.4		
	8.5	Classical Benchmarking Case – Temperature-Driven Cavity Flow	54
9	Con	clusion and Outlook	57
10	TFS.	TING ONLY	58
			58
Da	eferer		60
Ne	Herei	ices	bu
Lis	st of F	Figures	
	1	Vertex centered, cell centered and staggered variable arrangement. For the staggered arrangement, the arrows denote the velocity component and their location on the grid. The centered dot denotes the location	
		of the pressure and further scalar quantities	8
	2	Block-structured grid consisting of two blocks	
	3	Minimum correction, orthogonal correction and over-relaxed approach	11
	4	Possible interpretation of a virtual control volume (grey) located between nodes P and Q	13
	5	Non-matching grid cells with hanging nodes at a two-dimensional block boundary. Indexing is based on	
		the face segments S_l	24
	6	Non-zero structure of the linear systems used in the SIMPLE-algorithm for a block-structured grid consist-	
		O	27
	7	Non-zero structure of block submatrices of the linear systems used in the coupled solution algorithm for a	
		block-structured grid consisting of one $2 \times 2 \times 2$ cell block and one $3 \times 3 \times 3$ cell block. The blue coefficients	
		represent the pressure-velocity coupling, the red coefficients correspond to the velocity-to-temperature coupling and the green coefficients result from the Newton-Raphson linearization technique	22
	8	Non-zero structure of the linear system used in the coupled solution algorithm for a block-structured grid	33
	0	consisting of one $2 \times 2 \times 2$ cell block and one $3 \times 3 \times 3$ cell block. The variables have been interlaced and	
			34
	9	Non-zero structure the linear system used in the coupled solution algorithm for a block-structured grid	דע
		consisting of one $2 \times 2 \times 2$ cell block and one $3 \times 3 \times 3$ cell block. The variables have been ordered such	
			35
	10	Storage and update of ghost values in vectors related to variables on multi block domains. The blocks have	
		been assigned to two different processes, <i>Proc</i> 1 and <i>Proc</i> 2. The control volumes of the two-dimensional	
			39
	11	Comparison of calculated error for different under-relaxation factors $\alpha_{\mathbf{u}}$ on a grid with different grid	
		resolutions unknowns	44
	12	Sustainable memory bandwidth as determined by the STREAM benchmark (Triad) for different process	
		0 1	47
	13	Sustainable memory bandwidth as determined by the STREAM benchmark (Triad) for different process	_
		binding options on one node of the MPI2 section	48

14	Wall-clock time comparison for the SIMPLE-algorithm solving for an analytical solution on a grid with 64 ³ cells using different under-relaxation factors
15	Wall-clock time and Speed-Up comparison for segregated and fully coupled solution algorithm solving for
13	an analytical solution on a grid with 128 ³ cells
16	Comparison of the number of outer iterations and the corresponding wall-clock time, needed to achieve a
	reduction of 1E-8 of the initial residual, for different methods to resolve pressure-velocity coupling 51
17	Average number of inner iterations for different process counts solving for an analytical solution with the
	fully coupled solution algorithm
18	Sketch of the channel flow problem domain
19	West and east boundary of the numerical grid for the channel flow problem
20	Blocking for the two different obstacles within the problem domain of the channel flow
21	Temperature field and velocity field in the coordinate direction of the gravitational force of the
	temperature-driven cavity flow problem for a cross section in the middle of the problem domain 54
22	Skewing of an initially equidistant structured orthogonal grid via random movement of inner grid points
	within a small neighborhood of their original location. The neighborhood with maximal diameter is indi-
	cated by a circle around an inner grid point
23	Number of needed outer iterations for different relative diameters of the neighborhood in which the move-
	ment of grid points takes place parametrized by the orthogonal corrector
List of	Tables
1	Comparison of the errors of the velocity calculated by the segregated and the coupled solver for different grid resolutions and the resulting order of accuracy
2	Comparison of the errors of the pressure calculated by the segregated and the coupled solver for different
2	grid resolutions and the resulting order of accuracy
3	Comparison of the errors of the temperature calculated by the segregated and the coupled solver for
Ü	different grid resolutions and the resulting order of accuracy
4	Characteristic problem properties used in the performance measurements solving for an analytic solution . 50
5	Characteristic problem properties used in the channel flow test case
6	Performance analysis results of the channel flow problem for different numbers of unknowns comparing
	the segregated (SEG) to the fully coupled (CPLD) solution algorithm using one process on the MPI2 section
	of the HHLR supercomputer
7	Characteristic problem properties used in the heated cavity flow test case
8	Performance analysis results of the temperature-driven cavity flow problem comparing the SIMPLE-
	algorithm with segregated temperature solve (SEG), the fully coupled solution algorithm with segregated
	temperature solve (CPLD), the fully coupled solution algorithm with an implicit Boussinesq approxima-
	tion (TCPLD) and the fully coupled solution algorithm using an implicit Boussinesq approximation and a
	semi-implicit Newton-Raphson linearization of the convective part of the temperature equation (NRCPLD). 55
List of	Algorithms
1	SIMPLE-Algorithm
2	Fully Coupled Solution Algorithm



10 TESTING ONLY

10.1 Effect of Different Non-Orthogonal Correctors

Section 3.3 introduced different ways to address the degradation of the grid quality due to non-orthogonality of the grid. This section compares the three different correctors, the orthogonal correction, the minimum correction and the overrelaxed approach, which are used in the discretization process of the gradients at cell boundary faces. For this purpose the grid generator program of section ?? was extended to generate skewed grids. For this purpose a random number generator was used to randomly move each inner grid point within a specified neighborhood of the original location. Figure 22 illustrates the concept for a two-dimensional 8 grid. To maintain the grid's integrity after the movement of the grid points the neighborhoods were limited by half the distance Δx of two neighboring grid points.

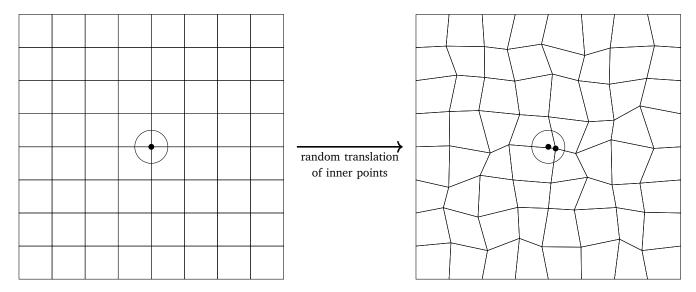


Figure 22: Skewing of an initially equidistant structured orthogonal grid via random movement of inner grid points within a small neighborhood of their original location. The neighborhood with maximal diameter is indicated by a circle around an inner grid point

To measure the effect of different non-orthogonal corrections on the solution process, tests for different skewed grids were performed, measuring the number of needed outer iterations. The grid skewness was parametrized with the relative diameter α of the maximal neighborhood, which constrains the movement of grid points. $\alpha \in [0,1)$, where $\alpha=0$ corresponds to no movement of grid points at all and $\alpha=1$ would move grid points up to $\frac{\Delta x}{2}$ away from their original location. The choice of $\alpha=1$ is not permitted to maintain the grid's integrity. Such a choice would permit the grid generator to place two grid points at the same location.

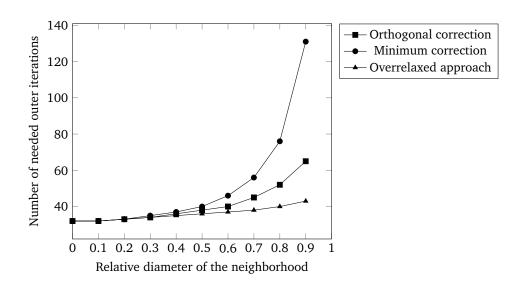


Figure 23: Number of needed outer iterations for different relative diameters of the neighborhood in which the movement of grid points takes place parametrized by the orthogonal corrector

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