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Masterthesis

# On Resolvent Estimates in $L^p$ for the Stokes Operator in Lipschitz Domains

Fabian Gabel

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Supervisor: Dr. Patrick Tolksdorf

Zweiter Gutachter: Name des Zweitgutachters

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# Introduction

Hier wird die Einleitung stehen. Dabei sollten Sie einen Kurzüberblick des Inhalts Ihrer Arbeit geben. Es ist sinnvoll, eingangs die bearbeitete Fragestellung zu erläutern, welches Ziel Sie und Ihr Betreuer hatten und welche Ergebnisse Sie schließlich erzielt haben.

Es ist hilfreich, auf die Struktur Ihrer Arbeit einzugehen, zum Beispiel indem Sie die einzelnen Kapitel kurz zusammenfassen. Stellen Sie auch klar heraus, welche Resultate schon aus der Literatur bekannt sind und welche Ergebnisse eigene Beiträge darstellen.

## Danksagung

Sie sind dazu verpflichtet (vgl. auch die Erklärung auf Seite 27), alle verwendeten Quellen und Hilfsmittel zu nennen. Viele dieser Quellen werden üblicherweise im Literaturverzeichnis aufgelistet, vgl. Seite 23. Zu den Quellen Ihrer Arbeit gehört zumindest auch der Betreuer, weil er nicht nur das Thema vergibt (in der Regel basierend auf seiner Idee), sondern Sie auch inhaltlich bei der Bearbeitung unterstützt. Die Danksagung stellt den natürlichen Rahmen dafür dar, den Betreuer namentlich zu erwähnen.

Außerdem kann es auch sein, dass ein wissenschaftlicher Mitarbeiter Sie (mit)betreut. In diesem Sinne ist dies auch eine Quelle oder ein Hilfsmittel für Ihre Arbeit. Daher sollten alle an der Betreuung beteiligten Personen erwähnt werden.

Es steht Ihnen frei, noch weitere Personen zu nennen:

- Kommilitonen, mit denen Sie über das Thema diskutieren konnten;
- Freunde, welche die Arbeit Korrektur gelesen haben.

# Chapter 1

## Fundamentals

### 1.1 Lipschitz-Domains

In this section we establish the fundamental notions regarding Lipschitz domains.

**Definition 1.1.** Let  $\Omega \subset \mathbb{R}^d$  be a bounded open connected set. We call  $\Omega$  a *bounded Lipschitz domain* if there exist  $r_0, M > 0$  such that for all  $x \in \partial\Omega$  there exists a function  $\eta_x: \mathbb{R}^{d-1} \rightarrow \mathbb{R}$  which is Lipschitz continuous and fulfills  $\eta_x(0) = 0$  and  $\|\nabla \eta_x\|_{L^\infty(\mathbb{R}^{d-1})} \leq M$ , and a Rotation  $R_x: \mathbb{R}^d \rightarrow \mathbb{R}^d$  such that for all  $0 < r \leq r_0$

$$\begin{aligned} R_x[\Omega - \{x\}] \cap D(r) &= D_{\eta_x}(r) \\ R_x[\partial\Omega - \{x\}] \cap D(r) &= I_{\eta_x}(r), \end{aligned}$$

where

$$\begin{aligned} D(r) &:= \{(x', x_d): |x'| < r, |x_d| < 10d(M+1)r\} \\ D_{\eta_x}(r) &:= \{(x', x_d): |x'| < r, \eta_x(x') < x_d < 10d(M+1)r\} \\ I_{\eta_x}(r) &:= \{(x', x_d): |x'| < r, \eta_x(x') = x_d\}. \end{aligned}$$

#### 1.1.1 Basic Definitions and Properties

#### 1.1.2 Tangential and Nontangential Operators

### 1.2 The Stokes Operator

# Chapter 2

## Estimating Fundamental Solutions

The purpose of this section is to study fundamental solutions of the Stokes resolvent problem and to deduce related estimates which will be crucial for the next chapters.

Let  $\lambda = re^{i\tau}$  with  $0 < r < \infty$  and  $-\pi + \theta < \tau < \pi - \theta$  and set  $k = \sqrt{r}e^{i(\pi+\tau)/2}$ . Then

$$k^2 = -\lambda \quad \text{and} \quad \frac{\theta}{2} < \arg(k) < \pi - \frac{\theta}{2}$$

as

$$\arg(k) = \frac{\pi + \tau}{2} > \frac{\pi}{2} + \frac{-\pi + \theta}{2} = \frac{\theta}{2}$$

on the one hand and

$$< \frac{\pi}{2} + \frac{\pi - \theta}{2} = \pi - \frac{\theta}{2}$$

on the other hand. This gives rise to the following estimate

$$\operatorname{Im}(k) > \sin(\theta/2)\sqrt{|\lambda|}. \quad \text{eq:imaginaryPartEstimate} \quad (2.1)$$

Indeed, we have

$$\operatorname{Im}(k) = \sqrt{r} \sin\left(\frac{\pi + \tau}{2}\right) = \sqrt{|\lambda|} \sin\left(\frac{\pi + \tau}{2}\right) \quad \text{and} \quad \frac{\theta}{2} < \frac{\pi + \tau}{2} < \pi - \frac{\theta}{2}$$

which gives for  $\tau$  with  $\frac{\pi + \tau}{2} \leq \frac{\pi}{2}$  that  $\sin(\frac{\pi + \tau}{2}) \geq \sin(\frac{\theta}{2})$  and for  $\tau$  with  $\frac{\pi + \tau}{2} > \frac{\pi}{2}$  that  $\sin(\frac{\pi + \tau}{2}) > \sin(\pi - \frac{\theta}{2}) = \sin(\frac{\theta}{2})$ .

Before diving into fundamental solutions of the Stokes resolvent problem, we will first consider a fundamental solution for the (scalar) Helmholtz equation in  $\mathbb{R}^d$

$$-\Delta u + \lambda u = 0.$$

One fundamental solution with pole at the origin is given by

$$G(x; \lambda) = \frac{i}{4(2\pi)^{\frac{d}{2}-1}} \cdot \frac{1}{|x|^{d-2}} \cdot \frac{1}{(k|x|)^{\frac{d}{2}-1}} H_{\frac{d}{2}-1}^{(1)}(k|x|), \quad \text{eq:definitionFundamentalHelmholtz} \quad (2.2)$$

where  $H_\nu^{(1)}(z)$  is the Hankel function of the first kind which can be written as

$$H_\nu^{(1)}(z) = \frac{2^{\nu+1} e^{i(z-\nu\pi)} z^\nu}{i\sqrt{\pi}\Gamma(\nu+\frac{1}{2})} \int_0^\infty e^{2zis} s^{\nu-\frac{1}{2}} (1+s)^{\nu-\frac{1}{2}} ds. \quad (2.3)$$

This formula holds for  $\nu > -\frac{1}{2}$  and  $0 < \arg(z) < \pi$ . We will usually set

$$\nu = \frac{d}{2} - 1 \quad \text{and} \quad z = k|x|.$$

Therefore, the formula (2.3) will hold for all dimensions  $d \geq 2$  and all  $x \in \mathbb{R}^d$ . In the case  $d = 2$  formula (2.2) simplifies to

$$G(x; \lambda) = \frac{i}{4} H_0^{(1)}(k|x|), \quad (2.4)$$

in the case  $d = 3$  one has an even easier formula, namely

$$G(x; \lambda) = \frac{e^{ik|x|}}{4\pi|x|}. \quad (2.5)$$

Our first estimate is concerned with derivatives of the fundamental solution for the (scalar) Helmholtz equation.

lem:estimateHelmholtzDerivatives

**Lemma 2.1.** *Let  $\lambda \in \Sigma_\theta$ . Then*

$$|\nabla_x^l G(x; \lambda)| \leq \frac{C_l e^{-c\sqrt{|\lambda||x|}}}{|x|^{d-2+l}} \quad (2.6)$$

for any integer  $l \geq 0$  if  $d \geq 3$  and for  $l \geq 1$  if  $d = 2$ . Here,  $c > 0$  depends only on  $\theta$  and  $C_l$  depends only on  $d, l$  and  $\theta$ .

*Proof.* We start with the case  $l = 0$  and  $d \geq 3$ . Let  $\text{Im}(z) > 0$  and  $\nu - \frac{1}{2} \geq 0$ . Then (2.3) gives

$$|H_\nu^{(1)}(z)| \leq C e^{-\text{Im}(z)} |z|^\nu \int_0^\infty e^{-2s\text{Im}(z)} s^{\nu-\frac{1}{2}} (1+s)^{\nu-\frac{1}{2}} ds.$$

Since by the substitution rule

$$\begin{aligned} e^{\frac{-\text{Im}(z)}{2}} \int_0^\infty e^{-s\text{Im}(z)} s^{\nu-\frac{1}{2}} (1+s)^{\nu-\frac{1}{2}} ds &= \int_0^\infty e^{-\text{Im}(z)(s+\frac{1}{2})} s^{\nu-\frac{1}{2}} (1+s)^{\nu-\frac{1}{2}} ds \\ &= \int_{\frac{1}{2}}^\infty e^{-\text{Im}(z)t} (t^2 - \frac{1}{4})^{\nu-\frac{1}{2}} dt \\ &\leq \int_0^\infty e^{-\text{Im}(z)t} t^{2\nu-1} dt \\ &= \int_0^\infty e^{-u} \left(\frac{u}{\text{Im}(z)}\right)^{2\nu-1} (\text{Im}(z))^{-1} du \\ &= (\text{Im}(z))^{-2\nu} \int_0^\infty e^{-u} u^{2\nu-1} du, \end{aligned}$$

we can estimate

$$|z|^\nu |H_\nu^{(1)}(z)| \leq C |z|^{2\nu} |\operatorname{Im}(z)|^{-2\nu} e^{-\frac{\operatorname{Im}(z)}{2}},$$

which for  $z = k|x|$  gives

$$|kx|^\nu |H_\nu^{(1)}(k|x|)| \leq \sin(\theta/2)^{-2\nu} e^{-\frac{1}{2} \sin(\theta/2) \sqrt{|\lambda|} |x|}, \quad \text{eq:zHEstimate} \quad (2.7)$$

where we used (2.1) to estimate

$$(|kx|)^{2\nu} \cdot |\operatorname{Im}(k|x|)|^{-2\nu} = |\lambda|^\nu \cdot |\operatorname{Im}(k)|^{-2\nu} \leq \sin(\theta/2)^{-2\nu}.$$

Using (2.2), we estimate for  $d \geq 3$  setting  $\nu = \frac{d}{2} - 1$

$$|G(x; \lambda)| \leq C |x|^{2-d} e^{-c \sqrt{|\lambda|} |x|}.$$

This gives the estimate for  $l = 0$  and  $d \geq 3$ .

Using the relation

$$\frac{d}{dz} \{z^{-\nu} H_\nu^{(1)}(z)\} = -z^{-\nu} H_{\nu+1}^{(1)}(z),$$

we can inductively establish the estimate (??) for  $l \geq 1$  and  $d \geq 2$ : For  $1 \leq j \leq d$ , we calculate

$$\begin{aligned} |\nabla_x G(x; \lambda)| &\leq C \cdot \{ |x|^{1-d} \cdot (k|x|)^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(k|x|) - |x|^{d-2} (k|x|)^{\frac{d}{2}-1} H_{\frac{d}{2}}^{(1)}(k|x|) k \} \\ &\leq C \cdot |x|^{1-d} \{ (k|x|)^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(k|x|) - (k|x|)^{\frac{d}{2}} H_{\frac{d}{2}}^{(1)}(k|x|) \}, \end{aligned}$$

where the first summand does not arise in the case  $d = 2$  due to (2.4). The terms in the bracket can now be estimated individually by (2.7). The extension of this proof to orders of differentiation  $l \geq 2$  is straightforward using the Leibniz product rule for higher derivatives.  $\square$

In the derivation of the next estimates we will use the following useful interior estimate which we write down for further use.

lem:interiorEstimatePoisson

**Lemma 2.2.** *Let  $w$  be a solution to  $\Delta w = f$  in  $B(x, r)$ . Then*

$$|\nabla^l w(x)| \leq C r^{-l} \sup_{B(x, r)} |w| + C \max_{0 \leq j \leq l-1} \sup_{B(x, r)} |\nabla^j f|. \quad \text{eq:interiorEstimatePoisson} \quad (2.8)$$

*Proof.* Todo  $\square$

We will need the following asymptotic expansions for the function  $z^\nu H_\nu^{(1)}(z)$  in  $\mathbb{C} \setminus (-\infty, 0]$ .

$$z^\nu H_\nu^{(1)}(z) = \frac{2^\nu \Gamma(\nu)}{i\pi} + \frac{i}{\pi} z^2 \log(z) + \omega z^2 + O(|z|^4 |\log(z)|) \text{ if } d=4, \quad \text{eq:asympoticd4} \quad (2.9)$$

$$z^\nu H_\nu^{(1)}(z) = \frac{2^\nu \Gamma(\nu)}{i\pi} + \frac{2^\nu \Gamma(\nu-1)}{4\pi i} z^2 + \omega z^3 + O(|z|^4) \text{ if } d=5, \quad \text{eq:asympoticd5} \quad (2.10)$$

$$z^\nu H_\nu^{(1)}(z) = \frac{2^\nu \Gamma(\nu)}{i\pi} + \frac{2^\nu \Gamma(\nu-1)}{4\pi i} z^2 + O(|z|^4 |\log z|) \text{ if } d=6, \quad \text{eq:asympoticd6} \quad (2.11)$$

$$z^\nu H_\nu^{(1)}(z) = \frac{2^\nu \Gamma(\nu)}{i\pi} + \frac{2^\nu \Gamma(\nu-1)}{4\pi i} z^2 + O(|z|^4) \text{ if } d \geq 7. \quad \text{eq:asympoticd7} \quad (2.12)$$

The derivation of these asymptotic expansions is based on asymptotic expansions of the Bessel functions of the first and the second kind and can be found in Tolksdorf [?].

We will denote the fundamental solution for  $-\Delta$  in  $\mathbb{R}^d$  with pole at the origin by

$$G(x; 0) := \begin{cases} -\frac{1}{2\pi} \log(|x|), & \text{for } d = 2, \\ c_d \frac{1}{|x|^{d-2}}, & \text{for } d > 2, \end{cases}$$

where

$$c_d = \frac{1}{(d-2)\omega_d}, \quad \text{with} \quad \omega_d = \frac{2\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2})} = |\mathbb{S}^{d-1}|.$$

Since

$$(d-2)\omega_d = 2\left(\frac{d}{2}-1\right) \frac{2\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2})} = 2\left(\frac{d}{2}-1\right) \frac{2\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2}-1)\Gamma(\frac{d}{2}-1)} = \frac{4\pi^{\frac{d}{2}}}{\Gamma(\frac{d}{2}-1)},$$

we will also sometimes use

$$c_d := \frac{\Gamma(\frac{d}{2}-1)}{4\pi^{\frac{d}{2}}}.$$

The leading coefficient of the asymptotic expansions for  $d \geq 3$  will be denoted as

$$a_d := \frac{2^{\frac{d}{2}-1} \Gamma(\frac{d}{2}-1)}{i\pi}. \quad \text{eq:Defnad} \quad (2.13)$$

The coefficients  $a_d$  and  $c_d$  are related in the following way

$$c_d = \frac{i}{4(2\pi)^{\frac{d}{2}-1}} a_d$$

This allows us to write for  $d \geq 3$

$$G(x; \lambda) - G(x; 0) = \frac{i}{4(2\pi)^{\frac{d}{2}-1}} \cdot \frac{1}{|x|^{d-2}} \left\{ (k|x|)^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(k|x|) - a_d \right\}. \quad \text{eq:HelmholtzLaplaceDifference} \quad (2.14)$$

The following lemma is concerned with estimating derivatives of (2.14)



**Lemma 2.3.** *Let  $\lambda \in \Sigma_\theta$ . Then*

$$|\nabla_x^l \{G(x; \lambda) - G(x; 0)\}| \leq C |\lambda| |x|^{4-d-l}, \quad (2.15)$$

if  $d \geq 5$  and  $l \geq 0$ , where  $C$  depends only on  $d$ ,  $l$  and  $\theta$ . If  $d = 3$  or  $4$ , estimate (2.15) holds for  $l \geq 1$ . If  $d = 2$ , then

$$|\nabla_x^l \{G(x; \lambda) - G(x; 0)\}| \leq \begin{cases} C |\lambda| |x|^{2-l}, & \text{if } |\lambda| |x|^2 \geq \frac{1}{2}, \\ C |\lambda| |x|^{2-l} \{|\log(|\lambda| |x|^2)| + 1\}, & \text{if } |\lambda| |x|^2 < \frac{1}{2}, \end{cases} \quad (2.16)$$

where  $C$  depends only on  $l$  and  $\theta$ .

*Proof.* (a) In this part we will show that the desired estimates (2.15) and (2.15) hold if we assume that  $|\lambda| |x|^2 \geq \frac{1}{2}$ . In this case, Lemma 2.1 gives

$$|\nabla_x^l \{G(x; \lambda) - G(x; 0)\}| \leq C \left\{ \frac{e^{-c\sqrt{|\lambda|}|x|}}{|x|^{d-2+l}} + \frac{1}{|x|^{d-2+l}} \right\} \leq C \frac{|\lambda|}{|x|^{d-4+l}},$$

where  $C$  depends only on  $d$ ,  $l$  and  $\theta$ . Therefore, for the remaining proof we will suppose  $|\lambda| |x|^2 < \frac{1}{2}$ .

(b) In this step, we show that we can restrict ourselves to proving (2.15) and, respectively, (2.16) in three cases: (1)  $d \geq 5$  and  $l = 0$ ; (2)  $d = 3$  or  $4$  and  $l = 1$ ; (3)  $d = 2$  and  $l = 1$ .

Suppose (2.15) holds in case (1) and let  $l > 1$ . If we set  $w(x) = G(x; \lambda) - G(x; 0)$ , we have  $\Delta_x w = \lambda G(x; \lambda)$  in  $\mathbb{R}^d \setminus \{0\}$ . For  $f = \lambda G(x; \lambda)$  estimate (2.8) now gives

$$\begin{aligned} |\nabla^l w(x)| &\leq C r^{-l} \sup_{B(x,r)} |w| + C \max_{0 \leq j \leq l-1} \sup_{B(x,r)} r^{j-l+2} |\nabla^j f| \\ &\leq C r^{-l} \sup_{y \in B(x,r)} |\lambda| |y|^{4-d} + C \sum_{j=0}^{l-1} \sup_{y \in B(x,r)} r^{j-l+2} |\lambda| |y|^{2-d-j} \\ &= C r^{-l} |\lambda| |x - r \frac{x}{|x|}|^{4-d} + C \sum_{j=0}^{l-1} r^{j-l+2} |\lambda| |x - r \frac{x}{|x|}|^{2-d-j}, \end{aligned}$$

for all  $0 < r < |x|$ , where we used (2.15) with  $l = 1$  for the first summand and (2.6) to estimate the second summand. Setting  $r = \frac{|x|}{2}$  now gives

$$\begin{aligned} |\nabla^l w(x)| &\leq C |\lambda| |x|^{-l} |x|^{4-d} + C \sum_{j=0}^{l-1} |x|^{j-l+2} |\lambda| |x|^{2-d-j} \\ &\leq C |\lambda| |x|^{4-d-l}. \end{aligned}$$

The proof for case (2) is completely analogous if one sets  $w(x) = \nabla_x(G(x; \lambda) - G(x; 0))$  and  $f(x) = \lambda \nabla_x G(x; \lambda)$ . Also case (3) is proven in a similar fashion. We will give the proof for the sake of completeness.

For  $w$  and  $f$  as in case (2) by (2.15) we get

$$\begin{aligned} |\nabla^l w(x)| &\leq Cr^{-l} \sup_{B(x,r)} |w| + C \max_{0 \leq j \leq l-1} \sup_{B(x,r)} r^{j-l+2} |\nabla^j f| \\ &\leq Cr^{-l} \sup_{y \in B(x,r)} |\lambda| |y| (|\log |\lambda| |y|^2| + 1) + C \sum_{j=0}^{l-1} \sup_{y \in B(x,r)} r^{j-l+2} |\lambda| |y|^{-j-1} \\ &\leq S_1 + S_2, \end{aligned}$$

wheras

$$\begin{aligned} S_1 &\leq Cr^{-l} |\lambda| |x + r \frac{x}{|x|}| (|\log |\lambda| |x - r \frac{x}{|x|}|^2| + |\log (|\lambda| |x + r \frac{x}{|x|}|^2)| + 1) \\ &\leq C |\lambda| |x|^{1-l} (|\log (|\lambda| |x|^2)| + 1) \end{aligned}$$

if we choose  $r = \frac{|x|}{2}$ . For  $S_2$  we calculate as before, using estimate (2.6)

$$\begin{aligned} S_2 &\leq C \sum_{j=0}^{l-1} C |x|^{j-l+2} |\lambda| |x|^{-j-1} \\ &\leq C |\lambda| |x|^{1-l}. \end{aligned}$$

(c) In this step we prove (2.15) for  $d \geq 5$  and  $l = 0$ . First, note that for the functions

$$\begin{aligned} g(x) &:= (k|x|)^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(k|x|), \quad g(0) = a_d, \\ h(z) &:= z^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(z), \quad h(0) = a_d, \end{aligned}$$

the mean value theorem yields the estimate

$$|g(x) - g(0)| \leq |x| \sup_{B(0,|x|)} |\nabla f(y)| \leq |x| |k| \sup_{B(0,|x|)} \frac{d}{dz} |h(k|x|)|.$$

Due to (2.14) we estimate

$$\begin{aligned} |G(x; \lambda) - G(x; 0)| &\leq C |x|^{2-d} \cdot |k| |x| \max_{\substack{|z| \leq |k||x| \\ \text{Im}(z) > 0}} \left| \frac{d}{dz} \{ z^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(z) \} \right| \\ &= C |x|^{2-d} \cdot |k| |x| \max_{\substack{|z| \leq |k||x| \\ \text{Im}(z) > 0}} \left| \frac{d}{dz} \{ z^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(z) \} \right|, \end{aligned} \quad (2.17)$$

where for the last equality we used the relation

$$\frac{d}{dz} \{ z^{\nu} H_{\nu}^{(1)}(z) \} = z^{\nu} H_{\nu-1}^{(1)}(z). \quad (2.18)$$

Since the asymptotic expansions yield that  $|z^\nu H_\nu^{(1)}(z)| \leq C_\nu$  for  $\nu > 0$  and  $|z| \leq 1$  with  $\text{Im}(z) > 0$  it follows from (2.17) that

$$|G(x; \lambda) - G(x; 0)| \leq C|x|^{2-d} \cdot |k||x| \cdot |k||x| \max_{\substack{|z| \leq |k||x| \\ \text{Im}(z) > 0}} |z^{\frac{d}{2}-2} H_{\frac{d}{2}-2}^{(1)}(z)| \leq C|\lambda||x|^{4-d}$$

(d) Now we consider the case  $d = 4$  and  $l = 1$ . The asymptotic expansion (2.9) gives that

$$\left| \frac{d}{dz} \left\{ \frac{zH_1^{(1)}(z) - a_4}{z^2} \right\} \right| \leq C|z|^{-1} \quad \text{eq: mvt 4d (2.19)}$$

for all  $|z| \leq \frac{1}{2}$  with  $\text{Im}(z) > 0$ . Since

$$\frac{G(x; \lambda) - G(x; 0)}{\lambda} = -\frac{C(zH_1^{(1)}(z) - a_4)}{z^2},$$

where  $z = k|x|$ , it follows from (2.19) and the mean value theorem that

$$\left| \frac{\nabla_x \{G(x; \lambda) - G(x; 0)\}}{\lambda} \right| \leq C|k| \frac{d}{dz} \left( \frac{zH_1^{(1)}(z) - a_4}{z^2} \right) \Big|_{z=k|x|} \leq C|k||k|^{-1}|x|^{-1}.$$

Which after rearrangement of the involved terms gives the claim.

(e) For the case  $d = 3$  and  $l = 1$ , equation (2.14) reads

$$G(x; \lambda) - G(x; 0) = \frac{e^{ik|x|}}{4\pi|x|} - \frac{c_3}{|x|} = \frac{e^{ik|x|} - 1}{4\pi|x|}.$$

Now we calculate

$$\begin{aligned} \frac{\partial}{\partial x_j} \left\{ \frac{e^{ik|x|} - 1}{|x|} \right\} &= \frac{\partial}{\partial x_j} \left\{ \frac{e^{ik|x|} - 1 - ik|x|}{|x|} \right\} = \frac{\partial}{\partial x_j} \left\{ \sum_{n=2}^{\infty} \frac{(ik|x|)^n}{n!} \cdot \frac{1}{|x|} \right\} \\ &= \sum_{n=2}^{\infty} \frac{(ik)^n}{n!} (n-1) \cdot \frac{x_j}{|x|} |x|^{n-2} \end{aligned}$$

which in turn implies

$$\left| \frac{\partial}{\partial x_j} \left\{ \frac{e^{ik|x|} - 1}{|x|} \right\} \right| \leq |\lambda| \sum_{n=2}^{\infty} \frac{n-1}{n!} |k|^{n-2} |x|^{n-2} \leq C|\lambda|$$

since  $|\lambda||x| < \frac{1}{2}$ .

(f) For the last case  $d = 2$  and  $l = 1$ , we will directly calculate the estimate using the asymptotic expansion of  $H_0^{(1)}(z)$  with  $z = k|x|$ :

$$\begin{aligned} H_0^{(1)}(z) &= J_0(z) + iY_0(z) \\ &= \sum_{l=0}^{\infty} \frac{(-1)^l}{(l!)^2 4^l} z^{2l} \left( 1 - \frac{2i \log(2)}{\pi} \right) - \frac{2i}{\pi} \sum_{l=0}^{\infty} \frac{(-1)^l}{(l!)^2 4^l} \psi(l+1) \cdot z^{2l} \\ &\quad + \frac{2i}{\pi} \sum_{l=0}^{\infty} \frac{(-1)^l}{(l!)^2 4^l} z^{2l} \log(z) \end{aligned}$$

The first complex derivative of  $H_0^{(1)}(z)$  reads

$$\frac{d}{dz}H_0^{(1)}(z) =$$

□

The fundamental solution to the (scalar) Helmholtz equation and the Laplace equation form the main ingredient for the following matrix of fundamental solutions  $(\Gamma(x; \lambda) = (\Gamma_{\alpha\beta}(x; \lambda))_{d \times d}$  with pole at the origin to the Stokes resolvent problem with  $\lambda \in \Sigma_\theta$ :

$$\Gamma_{\alpha\beta}(x; \lambda) = G(x; \lambda)\delta_{\alpha\beta} - \frac{1}{\lambda} \frac{\partial^2}{\partial x_\alpha \partial x_\beta} \{G(x; \lambda) - G(x; 0)\}, \quad \alpha, \beta = 1, \dots, d. \quad (2.20)$$

Having the formula at sight, the following observations are obvious:

$$\Gamma_{\alpha\beta}(x; \lambda) = \Gamma_{\beta\alpha}(x; \lambda), \quad \overline{\Gamma_{\alpha\beta}(x; \lambda)} = \Gamma_{\alpha\beta}(x; \bar{\lambda}) \quad \text{and} \quad \Gamma_{\alpha\beta}(x; \lambda) = \Gamma_{\alpha\beta}(-x; \lambda).$$

For the pressure, we define the vector of fundamental solutions

$$\Phi_\beta(x) = -\frac{\partial}{\partial x_\beta} \{G(x; 0)\} = \frac{\text{eq:fundamentalVectorPressure}}{\omega_d |x|^d} \quad (2.21)$$

We note that  $\Phi_\beta(x) = \Phi_\beta(-x)$ .

Using the fact that  $\Delta_x G(x; \lambda) = \lambda G(x; \lambda)$  in  $\mathbb{R}^d \setminus \{0\}$ , one can see that on  $\mathbb{R}^d \setminus \{0\}$  and for all  $1 \leq \beta \leq d$

$$\begin{cases} (-\Delta_x + \lambda)\Gamma_{\alpha\beta}(x; \lambda) + \frac{\partial}{\partial x_\alpha} \{\Phi_\beta(x)\} &= 0 \quad \text{for } 1 \leq \alpha \leq d, \\ \frac{\partial}{\partial x_\alpha} \{\Gamma_{\alpha\beta}(x; \lambda)\} &= 0. \end{cases} \quad \text{eq:StokesSystem} \quad (2.22)$$

Note that in the last equation the summation convention was used.

We now keep up to the spirit of this exhausting section by proving further estimates, this time for the fundamental solutions to the Stokes resolvent problem.

thm:fundamentalMatrixEstimate

**Theorem 2.4.** *Let  $\lambda \in \Sigma_\theta$ . Then for any  $d \geq 3$  and  $l \geq 0$*

$$|\nabla_x^l \Gamma(x; \lambda)| \leq \frac{C}{(1 + |\lambda||x|^2)|x|^{d-2+l}} \quad \text{eq:fundamentalMatrixEstimate} \quad (2.23)$$

where  $C$  depends only on  $d$ ,  $l$  and  $\theta$ . For  $d = 2$  and  $l \geq 1$  the estimate reads

$$|\nabla_x^l \Gamma(x; \lambda)| \leq \begin{cases} \frac{C}{(1 + |\lambda||x|^2)|x|^l} & \text{if } |\lambda||x|^2 \geq \frac{1}{2}, \\ \frac{C}{(1 + |\lambda||x|^2)|x|^l} \{|\log(|\lambda||x|^2)| + 1\} & \text{if } |\lambda||x|^2 \leq \frac{1}{2}, \end{cases} \quad \text{eq:fundamentalMatrixEstimate2d} \quad (2.24)$$

where  $C$  depends only on  $l$  and  $\theta$ .

*Proof.* Let  $|\lambda||x|^2 > \frac{1}{2}$ . Then there exist constants  $C_a, C_b, C_c$  such that

$$\begin{aligned} e^{-c\sqrt{|\lambda||x|}}(1 + |\lambda||x|^2) &\leq C_a \\ 1 &\leq \frac{C_b|\lambda||x|^2}{1 + |\lambda||x|^2} \\ e^{-c\sqrt{|\lambda||x|}} &\leq \frac{C_c|\lambda||x|^2}{1 + |\lambda||x|^2}, \end{aligned}$$

where  $c$  is the constant from Lemma 2.1. Using these estimates and Lemma 2.1 gives

$$\begin{aligned} |\nabla_x^l \Gamma(x; \lambda)| &\leq |\nabla_x^l G(x; \lambda)| + \frac{1}{|\lambda|} |\nabla_x^{l+2} G(x; \lambda)| + \frac{1}{|\lambda|} |\nabla_x^{l+2} G(x; 0)| \\ &\leq \frac{C_l e^{-c\sqrt{|\lambda||x|}}}{|x|^{d-2+l}} + \frac{1}{|\lambda|} \frac{C_{l+2} e^{-c\sqrt{|\lambda||x|}}}{|x|^2 |x|^{d-2+l}} + \frac{1}{|\lambda|} \frac{C}{|x|^2 |x|^{d-2+l}} \\ &\leq \frac{C}{(1 + |\lambda||x|^2)} \frac{1}{|x|^{d-2+l}} \end{aligned}$$

Now let  $|\lambda||x|^2 \leq \frac{1}{2}$ . Then by 2.1 and 2.3 we get

$$\begin{aligned} |\nabla_x^l \Gamma(x; \lambda)| &\leq |\nabla_x^l G(x; \lambda)| + \frac{1}{|\lambda|} |\nabla_x^{l+2} (G(x; \lambda) - G(x; 0))| \\ &\leq \frac{C}{|x|^{d-2+l}} + \frac{1}{|\lambda|} \cdot C |\lambda||x|^{4-d-(l+2)} \\ &\leq \frac{C}{|x|^{d-2+l}} + \frac{1}{|\lambda|} \cdot C |\lambda||x|^{4-d-(l+2)} \\ &\leq \frac{C}{|x|^{d-2+l}} \frac{(1 + |\lambda||x|^2)}{(1 + |\lambda||x|^2)} \\ &\leq \frac{C}{(1 + |\lambda||x|^2) |x|^{d-2+l}} \end{aligned}$$

which gives the claim for  $d \geq 3$ . If  $d = 2$  the steps are analogous considering the different structure of the estimate (2.16).  $\square$

Regarding the structure of the above proof, the derived estimate for the case  $d = 2$  seems natural at first sight. One important difference compared to  $d \geq 3$  is that it is not possible to derive an estimate of the form  $|\nabla_x^l \Gamma(x; \lambda)| \leq C|x|^{-l}$ .

If  $\lambda = 0$ , the matrix of fundamental solutions to the Stokes problem in  $\mathbb{R}^d$  with pole at the origin is given by  $\Gamma(x; 0) = (\Gamma_{\alpha\beta}(x; 0))_{d \times d}$ , where

$$\Gamma_{\alpha\beta}(x; 0) = \frac{1}{2\omega_d} \left\{ \frac{\delta_{\alpha\beta}}{(d-2)|x|^{d-2}} + \frac{\delta_{\alpha\beta}}{|x|^d} \right\} \quad \text{eq: fundamentalSolutionStokes} \quad (2.25)$$

if  $d \geq 3$  and

$$\Gamma_{\alpha\beta}(x; 0) = \frac{1}{2\omega_2} \left\{ -\delta_{\alpha\beta} \log(|x|) + \frac{\delta_{\alpha\beta}}{|x|^2} \right\} \quad \text{eq: fundamentalSolutionStokes2d} \quad (2.26)$$

for  $d = 2$ . Note that the given fundamental solution for the case  $d = 2$  differs from the one given by Mitrea and Wright [?] by having summands with alternating signs. The alternatig sign is necessary for  $\Gamma_{\alpha\beta}$  to be divergence free.

One important technique in the following chapter will be to reduce problems formulated for  $\Gamma(x; \lambda)$  to problems formulated in  $\Gamma(x; 0)$  and the difference  $\Gamma(x; \lambda) - \Gamma(x; 0)$ . Under this aspect it seems reasonable to study estimates of the difference of fundamental solutions. To this end it is helpful to rewrite parts of the fundamental solution. Using the fact that for  $d \geq 5$  or  $d = 3$  we have

$$\frac{\partial^2}{\partial x_\alpha \partial x_\beta} \left( \frac{1}{|x|^{d-4}} \right) = -(d-4) \frac{\partial}{\partial x_\alpha} \frac{x_\beta}{|x|^{d-2}} = -(d-4) \frac{\delta_{\alpha\beta}}{|x|^{d-2}} + \frac{(d-4)(d-2)x_\alpha x_\beta}{|x|^d}$$

This allows us to express

$$\frac{x_\alpha x_\beta}{|x|^d} = \frac{\delta_{\alpha\beta}}{(d-2)|x|^{d-2}} + \frac{1}{(d-4)(d-2)} \frac{\partial^2}{\partial x_\alpha \partial x_\beta} \left( \frac{1}{|x|^{d-4}} \right)$$

which considering (2.25) gives

$$\Gamma_{\alpha\beta}(x; 0) = G(x; 0) \delta_{\alpha\beta} + \frac{1}{2\omega_d(d-4)(d-2)} \frac{\partial^2}{\partial x_\alpha \partial x_\beta} \left( \frac{1}{|x|^{d-4}} \right). \quad \text{eq:fundamentalSolutionStokes35} \quad (2.27)$$

A similar trick works for  $d = 4$ . Since  $\omega_4 = 2\pi^2$ , we have

$$\begin{aligned} \Gamma_{\alpha\beta}(x; 0) &= \frac{1}{2\omega_4} \frac{1}{|x|^2} \delta_{\alpha\beta} - \frac{1}{8\pi^2} \left( \frac{\delta_{\alpha\beta}}{|x|^2} - \frac{2x_\alpha x_\beta}{|x|^4} \right) \\ &= G(x; 0) \delta_{\alpha\beta} - \frac{1}{8\pi^2} \frac{\partial^2}{\partial x_\alpha \partial x_\beta} (\log(|x|)) \quad \text{eq:fundamentalSolutionStokes4} \end{aligned} \quad (2.28)$$

In the case  $d = 2$  this game shows that since

$$\frac{1}{8\pi} \frac{\partial^2}{\partial x_\alpha \partial x_\beta} (|x|^2 \log(|x|)) = \frac{\delta_{\alpha\beta}}{4\pi} \log(|x|) + \frac{1}{4\pi} \frac{x_\alpha x_\beta}{|x|^2} + \frac{\delta_{\alpha\beta}}{8\pi},$$

we can write

$$\Gamma_{\alpha\beta}(x; 0) = G(x; 0) \delta_{\alpha\beta} - \frac{\delta_{\alpha\beta}}{8\pi} - \frac{\partial^2}{\partial x_\alpha \partial x_\beta} (\log(|x|)) \quad \text{eq:fundamentalSolutionStokes2} \quad (2.29)$$

This ends the preparatory step and brings us to the next theorem.

thm: differenceFundamentalSolutionStokes

**Theorem 2.5.** Let  $\lambda \in \Sigma_\theta$ . Suppose that  $|\lambda||x|^2 \leq \frac{1}{2}$ . Then

$$|\nabla_x \{\Gamma(x; \lambda) - \Gamma(x; 0)\}| \leq \begin{cases} C|\lambda||x|^{3-d} & \text{if } d \geq 7 \text{ or } d = 5, \\ C|\lambda||x|^{3-d} |\log(|\lambda||x|^2)| & \text{if } d = 4 \text{ or } 6, \\ C\sqrt{|\lambda|}|x|^{-1} & \text{if } d = 3, \\ C|\lambda||x|(|\log(|\lambda||x|^2)| + 1) & \text{if } d = 2, \end{cases} \quad (2.30)$$

where  $C$  depends only on  $d$  and  $\theta$ .

*Proof.* We will split the proof in several parts. We start by considering the cases  $d = 3$  and  $d \geq 5$ . Taking into account (2.27) we have

$$\begin{aligned} \Gamma_{\alpha\beta}(x; \lambda) - \Gamma_{\alpha\beta}(x; 0) &= \{G(x; \lambda) - G(x; 0)\} \delta_{\alpha\beta} \\ &\quad - \frac{1}{\lambda} \frac{\partial^2}{\partial x_\alpha \partial x_\beta} \left\{ G(x; \lambda) - G(x; 0) + \frac{\lambda}{2\omega_d(d-4)(d-2)|x|^{d-4}} \right\} \end{aligned}$$

As the first term can already be estimated via Lemma 2.3, we will only be concerned about the second one. If  $d = 3$ , a direct calculation will yield the desired result: We start by noting that  $\omega_3 = 4\pi$  gives

$$\begin{aligned} \frac{e^{ik|x|}}{4\pi|x|} - \frac{1}{4\pi|x|} - \frac{(ik)^2}{2\omega_3|x|^{-1}} &= \frac{1}{4\pi|x|} \left( e^{ik|x|} - 1 - \frac{(ik)^2|x|^2}{2} \right) \\ &= \frac{1}{4\pi|x|} \left( ik|x| + \sum_{n=3}^{\infty} \frac{(ik|x|)^n}{n!} \right) \\ &= \frac{1}{4\pi} \left( ik + \sum_{n=3}^{\infty} \frac{(ik)^n|x|^{n-1}}{n!} \right). \end{aligned}$$

Taking the first derivative of this expression we get

$$\frac{\partial}{\partial x_\beta} \dots = \frac{x_\beta}{4\pi} \sum_{n=3}^{\infty} \frac{(ik)^n(n-1)}{n!} |x|^{n-3}$$

and differentiating with respect to  $x_\alpha$  yields

$$\frac{\partial}{\partial x_\alpha} \dots = \frac{\delta_{\alpha\beta}}{4\pi} \sum_{n=3}^{\infty} \frac{(ik)^n(n-1)}{n!} |x|^{n-3} + \frac{x_\beta x_\alpha}{4\pi} \sum_{n=4}^{\infty} \frac{(ik)^n(n-1)(n-3)}{n!} |x|^{n-5}.$$

As we are interested in estimating the gradient of the difference of  $\Gamma(x; \lambda)$  and  $\Gamma(x; 0)$  we have to consider one additional derivative. This leaves us with

$$\begin{aligned} \frac{\partial}{\partial x_\gamma} \dots &= \frac{\delta_{\alpha\beta} x_\gamma + \delta_{\beta\gamma} x_\alpha + \delta_{\alpha\gamma} x_\beta}{4\pi} \sum_{k=4}^{\infty} \frac{(ik)^k(k-1)(k-3)}{k!} |x|^{k-5} \\ &\quad + \frac{x_\beta x_\alpha x_\gamma}{4\pi} \sum_{n=4}^{\infty} \frac{(ik)^n(n-1)(n-3)(n-5)}{n!} |x|^{n-7}. \end{aligned}$$

We can now prove the stated estimate

$$\begin{aligned} \left| \frac{1}{\lambda} \frac{\partial^3}{\partial x_\gamma \partial x_\alpha \partial x_\beta} \dots \right| &\leq \frac{1}{|k|^2 \pi} \sum_{k=4}^{\infty} \frac{|k|^k(k-1)(k-3)(1+(k-5))}{k!} |x|^{k-4} \\ &\leq \frac{1}{|k|^2 |x| \pi} |k|^3 \sum_{k=4}^{\infty} \frac{(k-1)(k-3)(1+(k-5))}{k!} |k|^{k-3} |x|^{k-3} \\ &\leq C \frac{1}{|k||x|}. \end{aligned}$$

This gives the claim for  $d = 3$ . If  $d \geq 5$ , equation (2.14) gives

$$\begin{aligned} G(x; \lambda) - G(x; 0) &+ \frac{\lambda}{2\omega_2(d-4)(d-2)|x|^{d-4}} \\ &= \frac{i}{4(2\pi)^{\frac{d}{2}-1}} \frac{1}{|x|^{d-2}} \{z^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(z) - a_d - b_d z^2\}, \end{aligned}$$

where  $z = k|x|$ ,  $a_d$  was calculated in (2.13) and  $b_d$  is given by

$$\begin{aligned} b_d &= \frac{2i(2\pi)^{\frac{d}{2}-1}}{\omega_d(d-4)(d-2)} = -\frac{2i(2\pi)^{\frac{d}{2}-1}\Gamma(\frac{d}{2})}{2\pi^{\frac{d}{2}}(d-2)(d-4)} = \frac{2^{\frac{d}{2}-1}}{\pi i(d-4)} \frac{\Gamma(\frac{d}{2})}{(d-2)} \\ &= \frac{2^{\frac{d}{2}-1}}{2\pi i} \frac{\Gamma(\frac{d}{2}-1)}{(d-4)} = \frac{2^{\frac{d}{2}-1}}{4\pi i} \frac{\Gamma(\frac{d}{2}-1)}{(\frac{d}{2}-1-1)} = \frac{2^{\frac{d}{2}-1}\Gamma(\frac{d}{2}-2)}{4\pi i}. \end{aligned}$$

If  $d \geq 7$  this shows that  $b_d$  is the second coefficient of the asymptotic expansion (2.12) and thus we can estimate

$$\left| \frac{d^l}{dz^l} \{z^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(z) - a_d - b_d z^2\} \right| \leq C|z|^{4-l} \quad \text{eq:estimateDerivativesd7} \quad (2.31)$$

for  $0 \leq l \leq 3$  and  $z \in \mathbb{C} \setminus (-\infty, 0]$ . For better readability we set

$$g(z) = z^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(z) - a_d - b_d z^2$$

and consider the function  $f(x) = g(k|x|)$  on  $\mathbb{R}^d \setminus \{0\}$ . The derivatives of  $f$  read

$$\begin{aligned} \frac{\partial}{\partial x_\beta} f(x) &= \left( \frac{d}{dz} g \right)(k|x|) \frac{kx_\beta}{|x|} \\ \frac{\partial^2}{\partial x_\alpha \partial x_\beta} f(x) &= \left( \frac{d^2}{dz^2} g \right)(k|x|) \frac{k^2 x_\alpha x_\beta}{|x|^2} + \left( \frac{d}{dz} \right) g(k|x|) k \left\{ \frac{\delta_{\alpha\beta}}{|x|} - \frac{x_\beta x_\alpha}{|x|^3} \right\} \\ \frac{\partial^3}{\partial x_\gamma \partial x_\alpha \partial x_\beta} f(x) &= \left( \frac{d^3}{dz^3} g \right)(k|x|) \frac{k^3 x_\alpha x_\beta x_\gamma}{|x|^3} \\ &\quad + \left( \frac{d^2}{dz^2} g \right)(k|x|) k^2 \left\{ \frac{x_\alpha \delta_{\beta\gamma} + x_\beta \delta_{\alpha\gamma} + x_\gamma \delta_{\alpha\beta}}{|x|^2} - \frac{3x_\alpha x_\beta x_\gamma}{|x|^4} \right\} \\ &\quad + \left( \frac{d}{dz} g \right)(k|x|) k \left\{ -\frac{\delta_{\alpha\beta} x_\gamma}{|x|^3} - \frac{x_\alpha \delta_{\beta\gamma} + x_\beta \delta_{\alpha\gamma}}{|x|^3} + \frac{3x_\alpha x_\beta x_\gamma}{|x|^5} \right\}. \end{aligned}$$

If we now look for estimates on the absolute value of the derivatives, we see that by (2.31)

$$|\nabla_x^l f(x)| \leq C|k|^4|x|^{4-l}, \quad 1 \leq l \leq 3,$$

where  $C$  only depends on  $l$ . We can now finally uncover the desired estimate via

$$\begin{aligned} &\left| \frac{1}{\lambda} \nabla_x^3 \left\{ \frac{i}{4(2\pi)^{\frac{d}{2}-1}} \frac{1}{|x|^{d-2}} \{z^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(z) - a_d - b_d z^2\} \right\} \right| \\ &\leq C \frac{1}{|k|^2} \sum_{l=0}^3 |\nabla_x^{3-l} \left( \frac{1}{|x|^{d-2}} \right)| |\nabla_x^l f(x)| \leq C \sum_{l=0}^3 |x|^{-d+2-3+l} |k|^2 |x|^{4-l} = C|\lambda| |x|^{3-d}, \end{aligned}$$



where  $C$  is a constant only depending on  $d$ . If  $d = 6$ , this shows that the asymptotic expansion (2.11) gives us similar to (2.31)

$$\left| \frac{d^l}{dz^l} \left\{ z^{\frac{d}{2}-1} H_{\frac{d}{2}-1}^{(1)}(z) - a_d - b_d z^2 \right\} \right| \leq C |z|^{4-l} |\log(z)|, \quad (2.32)$$

for  $0 \leq l \leq 3$  and  $z \in \mathbb{C} \setminus (-\infty, 0]$ . Using as before the expressions for derivatives of  $f$ , we can estimate

$$|\nabla_x^l f(x)| \leq C |k|^4 |x|^{4-l} |\log(|\lambda| |x|^2)|,$$

which by a calculation analogous to the case  $d \geq 7$  yields

$$|\nabla_x \{\Gamma(x; \lambda) - \Gamma(x; 0)\}| \leq C |\lambda| |x|^{3-d} |\log(|\lambda| |x|^2)|.$$

For  $d = 5$  write

$$\begin{aligned} & \frac{\partial^2}{\partial x_\alpha \partial x_\beta} \left\{ G(x; \lambda) - G(x; 0) + \frac{\lambda}{2\omega_d(d-4)(d-2)|x|d-4} \right\} \\ &= \frac{\partial^2}{\partial x_\alpha \partial x_\beta} \left\{ \frac{i}{4(2\pi)^{\frac{3}{2}}} \cdot \frac{1}{|x|^3} [z^{\frac{3}{2}} H_{\frac{3}{2}}^{(1)}(z) - a_5 - b_5 z^2 - w z^3] \right\}, \end{aligned}$$

where  $w \in \mathbb{C}$  can be an any constant if we set  $z = k|x|$ . Now, for the appropriate choice of  $w \in \mathbb{C}$  the asymptotic expansion (2.10) gives the same estimate as (2.31) which proves the claim for  $d = 5$ .

In the case  $d = 4$  we use (2.28) to reformulate

$$\begin{aligned} & \Gamma_{\alpha\beta}(x; \lambda) - \Gamma_{\alpha\beta}(x; 0) \\ &= \{G(x; \lambda) - G(x; 0)\} \delta_{\alpha\beta} - \frac{1}{\lambda} \frac{\partial^2}{\partial x_\alpha \partial x_\beta} \left\{ G(x; \lambda) - G(x; 0) - \frac{\lambda \log(|x|)}{8\pi^2} \right\} \\ &= \{G(x; \lambda) - G(x; 0)\} \delta_{\alpha\beta} \\ & \quad - \frac{i}{\lambda} \frac{\partial^2}{\partial x_\alpha \partial x_\beta} \left\{ \frac{1}{8\pi|x|^2} [z H_1^{(1)}(z) - a_4 - w z^2 - b_4 z^2 \log(z)] \right\}, \end{aligned}$$

where  $z = k|x|$ ,  $b_4 = \frac{i}{\pi}$  and  $w \in \mathbb{C}$  is an arbitrary constant. Using the asymptotic expansion (2.9) and the appropriate constant  $w \in \mathbb{C}$  we get the estimate

$$\left| \frac{d^l}{dz^l} \left\{ z H_1^{(1)}(z) - a_4 - w z^2 - b_4 z^2 \log(z) \right\} \right| \leq C |z|^{4-l} |\log(z)|.$$

For  $d = 2$  the estimate follows from a direct calculation. □

We can now use the assumption  $|\lambda| |x|^2 \leq \frac{1}{2}$  to unify the structure of the estimates for  $d \geq 2$ .

cor: differenceFundamentalSolutionStokes

**Corollary 2.6.** *Let  $\lambda \in \Sigma_\theta$ . Suppose that  $|\lambda||x|^2 \leq \frac{1}{2}$ . Then for all  $d \geq 2$*

$$|\nabla_x \{\Gamma(x; \lambda) - \Gamma(x; 0)\}| \leq C \sqrt{|\lambda|} |x|^{2-d},$$

where  $C$  depends only on  $d$  and  $\theta$ .

*Proof.* We just extend the estimates given in Theorem 2.5. Let  $d \geq 7$  or  $d = 5$ . Since  $|\lambda|^{\frac{1}{2}} \leq C|x|$  we have

$$C|\lambda||x|^{3-d} \leq C|\lambda|^{\frac{1}{2}}|x|^{2-d}.$$

For  $d = 4, 6$  we have

$$C|\lambda||x|^{3-d} |\log(|\lambda||x|^2)| = C|\lambda|^{\frac{1}{2}}|x|^{2-d} \cdot |\lambda|^{\frac{1}{2}}|x| |\log(|\lambda||x|^2)| \leq C|\lambda|^{\frac{1}{2}}|x|^{2-d},$$

since  $|\lambda|^{\frac{1}{2}}|x| |\log(|\lambda||x|^2)|$  is bounded for  $|\lambda||x|^2 \leq \frac{1}{2}$ . For  $d = 2$  the same argument applies to the expression  $|\lambda|^{\frac{1}{2}}|x|(|\log(|\lambda||x|^2)| + 1)$ .  $\square$

# Chapter 3

## Single and Double Layer Potentials

In this chapter, we will deal with *single* and *double layer potentials*. Both will serve as “representation formulas” for solutions to the Stokes resolvent problem. We will study their properties as they will serve as the crucial ingredient to solving the Neumann and Dirichlet boundary problems associated to the Stokes resolvent problem. In this chapter we will always assume that  $\Omega$  is a bounded Lipschitz domain in  $\mathbb{R}^d$  with  $d \geq 2$  and  $1 < p < \infty$ . We will also tacitly use the summation convention.

Let  $\lambda \in \Sigma_\theta$ . For  $f \in L^2(\partial\Omega; \mathbb{C}^d)$ , the single layer potential  $u = \mathcal{S}_\lambda(f)$  is defined by

$$u_j(x) = \int_{\partial\Omega} \Gamma_{jk}(x-y; \lambda) f_k(y) d\sigma(y), \quad \text{eq: defSingleLayer} \quad (3.1)$$

where  $\Gamma_{jk}$  is the fundamental solution to the Stokes resolvent problem given by (2.20). For the pressure, respectively, we define the single layer potential  $\phi = \mathcal{S}_\Phi(f)$  by

$$\phi(x) = \int_{\partial\Omega} \Phi_k(x-y) f_k(y) d\sigma(y), \quad \text{eq: defSingleLayerPressure} \quad (3.2)$$

where  $\Phi_k$  is given by (2.21). As we have already shown,  $(u, \phi)$  defines a solution to the Stokes resolvent problem (??).

We define two further integral operators

$$T_\lambda^*(f)(P) = \sup_{t>0} \left| \int_{\substack{y \in \partial\Omega \\ |y-P|>t}} \nabla_x \Gamma(P-y; \lambda) f(y) d\sigma(y) \right| \quad \text{eq: supTOperator} \quad (3.3)$$

$$T_\lambda(f)(P) = \text{p.v.} \int_{\partial\Omega} \nabla_x \Gamma(P-y; \lambda) f(y) d\sigma(y) \quad \text{eq: pvTOperator} \quad (3.4)$$

for  $P \in \partial\Omega$  which will be used to prove boundedness of maximal operators related to  $u$ . lem: lpBoundednessT

**Lemma 3.1.** *Let  $1 < p < \infty$  and  $T_\lambda(f), T_\lambda^*(f)$  be defined by (3.3) and (3.4). Then  $T_\lambda(f)(P)$  exists for almost everywhere  $P \in \partial\Omega$  and*

$$\|T_\lambda(f)\|_{L^p(\partial\Omega)} \leq \|T_\lambda^*(f)\|_{L^p(\partial\Omega)} \leq C_p \|f\|_{L^p(\partial\Omega)}, \quad \text{eq: lpBoundednessT} \quad (3.5)$$

where  $C_p$  depends only on  $d, \theta, p$ , and the Lipschitz character of  $\Omega$ .

*Proof.* If  $\lambda = 0$ , the Lemma is known [?] as a consequence of the seminal result of Coifman et al. [?]. One idea of the proof in the case  $\lambda \in \Sigma_\theta$  will thus be to nourish from this result and to consider the difference  $\Gamma(x-y; \lambda) - \Gamma(x-y; 0)$  as a well-disposed integral kernel.

We start with the second inequality of 3.5. To this end, let  $t > 0$  and additionally assume that  $t^2|\lambda| \geq \frac{1}{2}$ . Theorem 2.4 gives

$$\left| \int_{|y-P|>t} \nabla \Gamma(P-y; \lambda) f(y) d\sigma(y) \right| \leq C \int_{|P-y|>t} \frac{|f(y)|}{|\lambda| |P-y|^{d+1}} d\sigma(y)$$

Choose now  $N \in \mathbb{N}$  such that  $2^N t \leq \text{diam}(\Omega) < 2^{N+1} t$ . We now exhaust the domain of integration by suitable annuli and calculate

$$\begin{aligned} & \sum_{k=0}^N \int_{B(P, 2^{k+1}t) \cap \partial\Omega} \frac{1}{|\lambda| 2^{k(d+1)} t^{d+1}} |f(y)| d\sigma(y) \\ & \leq \frac{1}{|\lambda| t^2} \frac{1}{2^{1-d}} \sum_{k=0}^N \frac{1}{2^{2k}} \frac{1}{(2^{k+1}t)^{d-1}} \int_{B(P, 2^{k+1}t) \cap \partial\Omega} |f(y)| d\sigma(y) \\ & \leq C \sum_{k=0}^N \frac{1}{2^{2k}} M_{\partial\Omega}(f)(P) \\ & \leq CM_{\partial\Omega}(f)(P) \end{aligned}$$

where for the second inequality we used Lemma ?? to estimate

$$\frac{1}{(2^{k+1}t)^{d-1}} \leq C(\sigma(B(P, 2^{k+1}t) \cap \partial\Omega))^{-1}.$$

which gives the claimed estimate with a constant  $C$  that depends on  $d$ ,  $\theta$  and the Lipschitz character of  $\Omega$ . Now let  $t^2|\lambda| < \frac{1}{2}$ . We then split the integral as follows

$$\begin{aligned} & \left| \int_{|y-P|>t} \nabla \Gamma(P-y; \lambda) f(y) d\sigma(y) \right| \\ & \leq \left| \int_{|y-P| \geq (2|\lambda|)^{-1/2}} \nabla \Gamma(P-y; \lambda) f(y) d\sigma \right| + \left| \int_{t < |y-P| < (2|\lambda|)^{-1/2}} \nabla \Gamma(P-y; \lambda) f(y) d\sigma \right|. \end{aligned}$$

The first summand can be estimated like in the step before, if we substitute  $t$  by  $(2|\lambda|)^{-1/2}$ . For the second term we use the principle of the nutrient zero and estimate

$$\begin{aligned} & \left| \int_{t < |y-P| < (2|\lambda|)^{-1/2}} \nabla \Gamma(P-y; \lambda) f(y) d\sigma \right| \\ & \leq \int_{t < |y-P| < (2|\lambda|)^{-1/2}} |\nabla \Gamma(P-y; \lambda) - \nabla \Gamma(P-y; 0)| |f(y)| d\sigma \\ & \quad + \left| \int_{t < |y-P| < (2|\lambda|)^{-1/2}} \nabla \Gamma(P-y; 0) f(y) d\sigma \right|. \end{aligned}$$

We don't need to worry about the second summand here since the corresponding estimate is already covered by the case of  $\lambda = 0$  and therefore

$$\begin{aligned} & \left| \int_{t < |y-P| < (2|\lambda|)^{-1/2}} \nabla \Gamma(P-y; 0) f(y) \, d\sigma \right| \\ & \leq \left| \int_{|y-P| > t} \nabla \Gamma(P-y; 0) f(y) \, d\sigma \right| + \left| \int_{|y-P| > (2|\lambda|)^{-1/2}} \nabla \Gamma(P-y; 0) f(y) \, d\sigma \right| \\ & \leq 2T_0^*(f)(P). \end{aligned}$$

For the first summand we make use of Theorem 2.5 and more precisely of Corollary 2.6 which unifies all estimates. We then calculate

$$\begin{aligned} & \int_{t < |y-P| < (2|\lambda|)^{-1/2}} |\nabla \Gamma(P-y; \lambda) - \nabla \Gamma(P-y; 0)| f(y) \, d\sigma \\ & \leq \int_{t < |y-P| < (2|\lambda|)^{-1/2}} |\lambda|^{\frac{1}{2}} |y-P|^{2-d} |f(y)| \, d\sigma, \end{aligned}$$

and as before we choose adequate  $N$  such that  $2^{N+1}t > (2|\lambda|)^{-1/2} \geq 2^N t$  which leads to

$$\begin{aligned} & \leq |\lambda|^{\frac{1}{2}} \sum_{k=0}^N \int_{2^k t < |y-P| < 2^{k+1} t} |y-P|^{2-d} |f(y)| \, d\sigma \\ & \leq |\lambda|^{\frac{1}{2}} t^{2-d} \sum_{k=0}^N 2^{k(2-d)} \int_{B(P, 2^{k+1} t)} |f(y)| \, d\sigma \\ & \leq 2^d |\lambda|^{\frac{1}{2}} t \sum_{k=0}^N 2^{k-1} 2^{(k+1)(1-d)} t^{1-d} \int_{B(P, 2^{k+1} t)} |f(y)| \, d\sigma \\ & \leq C |\lambda|^{\frac{1}{2}} t \frac{2^N - 1}{1} M_{\partial\Omega}(f)(P) \\ & \leq C |\lambda|^{\frac{1}{2}} (2|\lambda|)^{-\frac{1}{2}} M_{\partial\Omega}(f)(P). \end{aligned}$$

Taking now the supremum over all  $t > 0$  we see that

$$T_\lambda^*(f)(P) \leq C(M_{\partial\Omega}(f)(P) + T_0^*(f)(P)),$$

for all  $P \in \partial\Omega$ . Once again using the result for  $\lambda = 0$  and the  $L^p$  boundedness of the Hardy-Littlewood maximal operator we see that

$$\|T_\lambda^*(f)\|_{L^p(\partial\Omega)} \leq C \|f\|_{L^p(\partial\Omega)}$$

To conclude the first inequality in (3.5), we want to use a standard result from harmonic analysis [?, 2.1.14]. First we will show that the integral operator

$$T_\lambda(f)(P) = \lim_{t \rightarrow 0} \int_{\substack{y \in \partial\Omega \\ |y-P| > t}} \nabla_x \Gamma(P-y; \lambda) f(y) \, d\sigma(y)$$

exists for almost every  $P \in \partial\Omega$  and all  $f \in C(\partial\Omega; \mathbb{C}^d)$ . In a first step, we can split this operator formally in

$$T_\lambda(f)(P) = T_0(f)(P) + \lim_{t \rightarrow 0} \int_{\substack{y \in \partial\Omega \\ |y-P| > t}} \nabla_x \{\Gamma(P-y; \lambda) - \Gamma(P-y; 0)\} f(y) d\sigma(y)$$

The right expression is well defined for  $f \in \mathbb{C}_0^\infty$ , once we prove integrability of

$$|\nabla \{\Gamma(P-y; \lambda) - \Gamma(P-y; 0)\}|$$

on  $\partial\Omega$ . To this end we first note that it suffices to consider the integral

$$\int_{|P-y| \leq \varepsilon} |\nabla \{\Gamma(P-y; \lambda) - \Gamma(P-y; 0)\}| d\sigma(y),$$

for  $\varepsilon \leq \min(2|\lambda|^{-1/2}, r_0/4)$  as the integrand is smooth away from 0 and the domain of integration is bounded. Now Corollary 2.6 and Tolksdorf 4.3.2 give that this can be estimated by

$$\int_{|P-y| \leq \varepsilon} |\lambda|^{1/2} |P-y|^{2-d} d\sigma(y) \leq C|\lambda|^{1/2} \varepsilon \leq C.$$

Based on the preceding calculation we conclude that for all  $f \in C(\partial\Omega, \mathbb{C}^d)$  the operator  $T_\lambda(f)(P)$  exists whenever  $T_0(f)(P)$  exists.  $T_0(f)(P)$  exists for almost everywhere  $P \in \partial\Omega$  because of Fabes, Kenig and Verchota [?]. As furthermore  $T_\lambda^*(f)(P)$  is bounded on  $L^p(\partial\Omega)$  we may now apply Theorem 2.1.14 from Grafakos [?] to conclude that  $T_\lambda(f)(P)$  exists now for all  $f \in L^p(\partial\Omega; \mathbb{C}^d)$  and almost everywhere  $P \in \partial\Omega$ . The desired  $L^p$  estimate on  $T_\lambda(f)$  now follows from the observation that

$$|T_\lambda(f)(P)| \leq T_\lambda^*(f)(P)$$

for almost everywhere  $P \in \partial\Omega$ . □

For a function  $u$  in  $\Omega$ , we define the nontangential maximal function  $(u)^*$  by

$$(u)^*(P) = \sup\{|u(x)| : x \in \Omega \text{ and } |x-P| < \frac{1}{C} \text{dist}(x, \partial\Omega)\} \quad \text{eq: defnNontangMaxFunction} \quad (3.6)$$

for  $P \in \partial\Omega$ , where  $C > 2$  is a fixed and sufficiently large constant depending on  $d$  and the Lipschitz character of  $\Omega$ . Note that in Shen cones we have that for  $P, y \in \partial\Omega$  and  $x \in \Gamma(P)$

$$\begin{aligned} |P-y| &\leq |P-x| + |x-y| \leq C \text{dist}(x, \partial\Omega) + |x-y| \\ &\leq (C+1)|x-y| \end{aligned} \quad \text{eq: shenConeEstimate} \quad (3.7)$$

where  $C$  is the constant from (3.6)

We can now prove the boundedness of certain nontangential maximal operators.

**Lemma 3.2.** *Let  $1 < p < \infty$  and  $(u, \phi)$  be given by (3.1) and (3.2). Let furthermore  $d \geq 3$ . Then*

$$\|(\nabla u)^*\|_{L^p(\partial\Omega)} + \|(\phi)^*\|_{L^p(\partial\Omega)} + |\lambda|^{\frac{1}{2}}\|(u)^*\|_{L^p(\partial\Omega)} \leq C_p \|f\|_{L^p(\partial\Omega)}, \quad (3.8)$$

where  $C_p$  depends only on  $d$ ,  $\theta$ ,  $p$  and the Lipschitz character of  $\Omega$ .

*Proof.* A proof of the estimate  $\|(\phi)^*\|_{L^p(\partial\Omega)} \leq C_p \|f\|_{L^p(\partial\Omega)}$  can be found in Verchota [?]. The proof for  $\|(\nabla u)^*\|_{L^p(\partial\Omega)}$  works in the same way. We will provide a proof for the sake of completeness. To immitate the proof of Verchota, we will work with the corresponding type of cones. Therefore the results for  $\nabla u$  and  $\phi$  will at first only be established for the type of maximal operators defined by Verchota. The transferability to Shen's maximal operators is given by Tolksdorf [?] as the solution  $(u, \phi)$  has a representation as a single layer potential.

Let  $x \in \Gamma_V(P)$  and set  $t = |x - P|$ . Then,

$$\begin{aligned} |(\nabla u)(x)| &= \left| \int_{\partial\Omega} \nabla \Gamma_{jk}(x-y; \lambda) f_k d\sigma(y) \right| \\ &\leq \left| \int_{|y-P|>t} \nabla \Gamma_{jk}(x-y; \lambda) f_k d\sigma(y) \right| + \left| \int_{|y-P|\leq t} \nabla \Gamma_{jk}(x-y; \lambda) f_k d\sigma(y) \right| \\ &= I_1 + I_2. \end{aligned}$$

We will now estimate  $I_1$  and  $I_2$  separately. Note that in Verchota cones we have that for all  $Q \in \partial\Omega$  we have  $|x - Q| > C|x - P|$ , where  $C$  is a constant only depending on  $d$  and the Lipschitz character of  $\Omega$ . By Theorem 2.4 we know that

$$\begin{aligned} I_2 &\leq C \int_{|y-P|\leq t} \frac{1}{|x-y|^{d-1}} |f(y)| d\sigma(y) \\ &\leq \frac{C}{t^{n-1}} \int_{|y-P|\leq t} |f(y)| d\sigma(y) \leq CM_{\partial\Omega}(f)(P). \end{aligned}$$

For  $I_1$ , we calculate

$$\begin{aligned} &\left| \int_{|y-P|>t} \nabla \Gamma_{jk}(x-y; \lambda) f_k(y) - \nabla \Gamma_{jk}(P-y; \lambda) f_k(y) + \nabla \Gamma_{jk}(P-y; \lambda) f_k(y) d\sigma(y) \right| \\ &\leq \left| \int_{|y-P|>t} \nabla \Gamma_{jk}(x-y; \lambda) f_k(y) - \nabla \Gamma_{jk}(P-y; \lambda) f_k(y) d\sigma(y) \right| \\ &\quad + \left| \int_{|y-P|>t} \nabla \Gamma_{jk}(P-y; \lambda) f_k(y) d\sigma(y) \right|. \end{aligned}$$

The second summand can directly be estimated by  $T_\lambda^*(f)(P)$ . For the second one we

apply the mean value theorem and derive using once again Theorem 2.4

$$\begin{aligned}
& \int_{|y-P|>t} |\nabla \Gamma_{jk}(x-y; \lambda) - \nabla \Gamma_{jk}(P-y; \lambda)| |f(y)| d\sigma(y) \\
& \leq \int_{|y-P|>t} |\nabla^2 \Gamma_{jk}(s-y; \lambda)| |x-P| |f(y)| d\sigma(y) \\
& \leq Ct \int_{|y-P|>t} \frac{1}{|s-y|^d} |f(y)| d\sigma(y) \\
& \leq Ct \int_{|y-P|>t} \frac{1}{|y-P|^d} |f(y)| d\sigma(y),
\end{aligned}$$

where  $s$  is an element on the line connecting  $x$  and  $P$  and we used the property of Verchota-cones that  $|s-y| \geq C|y-P|$ . Note that Verchota cones are convex. By exhausting the domain of integration using annuli, we can estimate this integral by  $M_{\partial\Omega}f(P)$ : Choose  $N$  such that  $2^N t \leq \text{diam}(\Omega) < 2^{N+1}t$ . Then

$$\begin{aligned}
& \int_{|y-P|>t} \frac{1}{|y-P|^{d-1}} |f(y)| d\sigma(y) \\
& = \sum_{k=0}^N \int_{2^{k+1}t > |y-P| \geq 2^k t} \frac{1}{|y-P|^{d-1}} |f(y)| d\sigma(y) \\
& \leq \sum_{k=0}^N \frac{1}{2^{k(d-1)} t^{d-1}} \int_{|y-P| < 2^{k+1}t} |f(y)| d\sigma(y) \\
& \leq C \sum_{k=0}^N 2^{k-d+1} M_{\partial\Omega}(f)(P) \leq
\end{aligned}$$

Taking the supremum over all  $x \in \Omega$  the claim follows.

We will now work on the proof of the estimate for  $(u)^*$ . In order to derive  $L^p$  estimates on this maximal operator we will work directly with the Definition of the single layer potential (3.1). For  $P \in \partial\Omega$ , estimate (2.23) together with the estimate for Shen cones (3.7) gives that for all  $x \in \Gamma(P)$

$$|u^*(x)| \leq C \int_{\partial\Omega} \frac{1}{|x-y|^{d-2}} |f(y)| d\sigma(y) \leq C \int_{\partial\Omega} \frac{1}{|P-y|^{d-2}} |f(y)| d\sigma(y),$$

where  $C$  only depends on  $d$ ,  $\theta$  and the Lipschitz character of  $\Omega$ . Passing to the maximal operator yields the inequality

$$u^*(P) \leq C \int_{\partial\Omega} \frac{1}{|P-y|^{d-2}} |f(y)| d\sigma(y),$$

We are now left with the task to estimate the integral

$$\int_{\partial\Omega} \frac{1}{|P-y|^{d-2}} d\sigma(y)$$



uniformly for all  $P \in \partial\Omega$ . Then the work that is left can then be given over to the Young inequality. Let  $r_0$  be the Radius from the definition of Lipschitz cylinders. Then

$$\begin{aligned} \int_{\partial\Omega} \frac{1}{|P-y|^{d-2}} d\sigma(y) &\leq \int_{\partial\Omega \cap B(P; r_0/4)} \frac{1}{|P-y|^{d-2}} d\sigma(y) + \int_{\partial\Omega \setminus B(P; r_0/4)} \frac{1}{|P-y|^{d-2}} d\sigma(y). \\ &\leq Cr_0/4 + \sigma(\partial\Omega) r_0^{2-d} 4^{d-2}. \end{aligned}$$

where  $C$  only depends on  $d$  and the Lipschitz character of  $\Omega$ .  $\square$

The next Lemma deals with *trace formulas* for  $\nabla u$  and  $\phi$ . We can now finally talk about boundary values as the existence of nontangential limits guarantees that there exists something on  $\partial\Omega$  that is related to the function inside  $\Omega$ .

lem:traceFormulas

**Lemma 3.3.** *Let  $(u, \phi)$  be given by (3.1) and (3.2) with  $f \in L^p(\partial\Omega; \mathbb{C}^d)$  and  $1 < p < \infty$ . Then*

$$\begin{aligned} \left(\frac{\partial u_i}{\partial x_j}\right)_\pm(x) &= \pm \frac{1}{2} \{n_j(x) f_i(x) - n_i(x) n_j(x) n_k(x) f_k(x)\} \\ &\quad + \text{p.v.} \int_{\partial\Omega} \frac{\partial}{\partial x_j} \{\Gamma_{ik}(x-y; \lambda)\} f_k(y) d\sigma(y), \quad \text{eq:traceFormula (3.9)} \\ \phi_\pm(x) &= \mp \frac{1}{2} n_k(x) f_k(x) + \text{p.v.} \int_{\partial\Omega} \Phi_k(x-y) f_k(y) d\sigma(y) \end{aligned}$$

for almost everywhere  $x \in \partial\Omega$ . The subscripts  $+$  and  $-$  indicate nontangential limits taken inside  $\Omega$  and outside  $\bar{\Omega}$ , respectively.

*Proof.* The correctness of the trace formulas (3.9) is known for the case  $\lambda = 0$  since Fabes, Kenig and Verchota [?]. This fact will now be reused for  $\lambda \in \Sigma_\theta$ . We insert a 0 to the nontangential limit as

$$(\nabla u_j)_\pm(x) = (\nabla v_j)_\pm(x) + (\nabla u_j - \nabla v_j)_\pm(x),$$

where  $v_j(x) = \int_{\partial\Omega} \Gamma_{jk}(x-y; 0) f_k(y) d\sigma(y)$ . Because of [?] we know that the first nontangential limit exists and is given by (3.9) with  $\lambda = 0$ . It therefore remains to show that

$$(\nabla u_j - \nabla v_j)_\pm(x) = \int_{\partial\Omega} \nabla \{\Gamma_{jk}(x-y; \lambda) - \Gamma_{jk}(x-y; 0)\} f_k(y) d\sigma(y)$$

for all  $x \in \partial\Omega$ . To this end let  $(x_l)_{l \in \mathbb{N}}$  a sequence in  $\Gamma(x)$  with  $\lim_{l \rightarrow \infty} x_l = x$ . Furthermore let us note that for almost everywhere  $x \in \partial\Omega$  we have that

$$\int_{\partial\Omega} \frac{1}{|x-y|^{d-2}} |f(y)| d\sigma(y) < \infty.$$

This is a consequence of the fact that

$$\sup_{x \in \partial\Omega} \left| \int_{\partial\Omega} \frac{1}{|x-y|^{d-2}} d\sigma(y) \right| < \infty$$

and an application of Young's inequality which can be found in Tolksdorf [?]: Let  $x \in \partial\Omega$ . Then

$$\begin{aligned} & \int_{\partial\Omega} \frac{1}{|x-y|^{d-2}} d\sigma(y) \\ & \leq \int_{\partial\Omega \cap B(x, r_0/4)} \frac{1}{|x-y|^{d-2}} d\sigma(y) + \int_{\partial\Omega \setminus B(x, r_0/4)} \frac{1}{|x-y|^{d-2}} d\sigma(y) \\ & \leq Cr_0 + r^{2-d} 4^{d-2} \sigma(\partial\Omega) \end{aligned}$$

by Lemma ???. Now Young's inequality gives us the desired result. In the next step we will show that

$$\frac{1}{|x-y|^{d-2}} |f(y)|$$

gives a suitable function for dominated convergence. Set  $\varepsilon = (4|\lambda|^2)^{-1}$  and without loss of generality assume that  $\text{supp } f \subseteq B(x, \varepsilon)$ . Furthermore assume that  $|x_l - x| < \varepsilon$  for all  $l \in \mathbb{N}$ . Then  $|x_l - y| \leq (2|\lambda|^2)^{-1}$  and Corollary 2.6 give

$$\begin{aligned} & (\nabla u_j - \nabla v_j)(x_l) \int_{\partial\Omega} \nabla \{ \Gamma_{jk}(x_l - y; \lambda) - \Gamma_{jk}(x_l - y; 0) \} f_k(y) d\sigma(y) \\ & \leq \int_{\partial\Omega} \frac{1}{\sqrt{|\lambda|} |x_l - y|^{d-2}} |f(y)| d\sigma(y) \\ & \leq \frac{C}{\sqrt{|\lambda|}} \int_{\partial\Omega} \frac{1}{|x-y|^{d-2}} |f(y)| d\sigma(y) < \infty. \end{aligned}$$

Now dominated convergence gives the claim for  $x_l \rightarrow x$ . Note that it does not affect the proof if the sequence  $x_l$  lays inside  $\Omega$  or outside  $\bar{\Omega}$ .  $\square$

The previous Lemma enables us to talk about boundary values of partial derivatives. The next theorem will now give a similar result but for conormal derivatives which are defined by

$$\frac{\partial u}{\partial \nu} = \frac{\partial u}{\partial n} - \phi n.$$

We will also be working with tangential derivatives which are defined via

*DEFINE*

thm:jumpConditions

**Theorem 3.4.** Let  $\lambda \in \Sigma_\theta$  and  $\Omega$  be a bounded Lipschitz domain in  $\mathbb{R}^d$ ,  $d \geq 3$ . Let  $(u, \phi)$  be given by (3.1) and (3.2) with  $f \in L^p(\partial\Omega; \mathbb{C}^d)$  and  $1 < p < \infty$ . Then  $\nabla_{\tan} u_+ = \nabla_{\tan} u_-$  and

$$\left(\frac{\partial u}{\partial \nu}\right)_\pm = \left(\pm \frac{1}{2}I \mp \mathcal{K}_\lambda\right)f \quad (3.10)$$

on  $\partial\Omega$ , with  $\mathcal{K}_\lambda$  a bounded operator on  $L^p(\partial\Omega; \mathbb{C}^d)$  with

$$\|\mathcal{K}_\lambda f\|_{L^p(\partial\Omega)} \leq C_p \|f\|_{L^p(\partial\Omega)},$$

where  $C_p$  depends only on  $d$ ,  $\theta$ ,  $p$  and the Lipschitz character of  $\Omega$ .

*Proof.* For the the  $j$ th component of the tangential derivative of  $u_i$ ,  $1 \leq i, j \leq d$ , we calculate using the results from Lemma 3.3

$$\begin{aligned} ((\nabla_{\tan} u_i)_+)_j &= \left(\frac{\partial u_i}{\partial x_j}\right)_+ - \langle (\nabla u_i)_+, n \rangle n_j \\ &= \left(\frac{\partial u_i}{\partial x_j}\right)_+ - \left(\frac{\partial u_i}{\partial x_k}\right)_+ n_k n_j \\ &= \frac{1}{2} \{n_j f_i - n_i n_j n_k f_k\} - \frac{1}{2} \{n_k f_i - n_i n_k n_l f_l\} n_k n_j \\ &\quad + \text{p.v.} \int_{\partial\Omega} \frac{\partial}{\partial x_j} \{\Gamma_{ik}(x-y; \lambda)\} f_k(y) d\sigma(y) \\ &\quad + \text{p.v.} \int_{\partial\Omega} \frac{\partial}{\partial x_k} \{\Gamma_{il}(x-y; \lambda)\} f_l(y) d\sigma(y) n_k n_j. \end{aligned}$$

As the first two summands add up to zero the entire expression does not depend on the direction of the nontangential limit. This gives

$$(\nabla_{\tan} u)_+ = (\nabla_{\tan} u)_-$$

We calculate for the  $j$ th component of the nontangential limit of the conormal derivative of  $u$  at  $x \in \partial\Omega$  using the results from Lemma 3.3

$$\begin{aligned} \left(\frac{\partial u_j}{\partial x_i}\right)_+(x) n_i - \phi_+(x) n_j &= \frac{1}{2} \{n_i f_j(x) - n_j n_i n_k f_k(x)\} n_i + \text{p.v.} \int_{\partial\Omega} \frac{\partial}{\partial x_i} \{\Gamma_{jk}(x-y; \lambda)\} f_k(y) d\sigma(y) n_i \\ &\quad + \frac{1}{2} n_k f_k(x) n_j - \text{p.v.} \int_{\partial\Omega} \Phi_k(x-y) f_k(y) d\sigma(y) n_j \\ &= \frac{1}{2} f_j(x) + (\mathcal{K}_\lambda f)_j(x), \end{aligned}$$

where  $n$  denotes the normal vector at  $x$  and

$$(\mathcal{K}_\lambda f)(x) = \text{p.v.} \int_{\partial\Omega} \nabla_x \Gamma(x-y; \lambda) f(y) d\sigma(y) n - \text{p.v.} \int_{\partial\Omega} \Phi_k(x-y) f_k(y) d\sigma(y) n. \quad \text{eq: defnKlambda} \quad (3.11)$$

We note that  $\mathcal{K}_\lambda$  essentially consists of two boundary layer potentials. The  $L^p$ -boundedness of the first one was proven in Lemma 3.1. The  $L^p$ -boundedness of the second boundary layer potential follows in an analogous way using the fact that the operators

$$A^*(f)(P) = \sup_{t>0} \left| \int_{\substack{y \in \partial\Omega \\ |y-P|>t}} \frac{P-y}{|P-y|^n} f(y) d\sigma(y) \right|, \quad P \in \partial\Omega$$

are bounded by Lemma 1.2 of Verchota [?]. □

Similar to  $\mathcal{K}_\lambda$  for  $\lambda = 0$  we have

$$= \text{p.v.} \int_{\partial\Omega} \nabla_x \Gamma(x-y; 0) f(y) d\sigma(y) n - \text{p.v.} \int_{\partial\Omega} \Phi_k(x-y) f_k(y) d\sigma(y) n, \quad \text{eq: defnK0} \quad (3.12)$$

as was show by Fabes, Kenig and Verchota [?, (0.12)]. We note a fact that will be crucial for solving the  $L^2$  Dirichlet problem in Chapter 5 and will fortify the hopes of translating results for  $\lambda = 0$  to  $\lambda \in \Sigma_\theta$ .

lem: compactness

**Lemma 3.5.** *Let  $\lambda \in \Sigma_\theta$  and  $d \geq 3$ . Then the operator  $\mathcal{K}_\lambda - \mathcal{K}_0$  on  $L^2(\partial\Omega; \mathbb{C}^d)$  is compact.*

*Proof.* The idea of this proof is similar to the one in Tolksdorf [?, Lemma 4.3.5]. Let  $f \in L^2(\partial\Omega; \mathbb{C}^d)$ . Let's denote  $\mathcal{K} := \mathcal{K}_\lambda - \mathcal{K}_0$ . We will now try to approximate  $\mathcal{K}$  by compact operators in the operator norm. To this end we define for all  $\varepsilon > 0$

$$(\mathcal{K}^{(\varepsilon)} f)(x) := \int_{\partial\Omega \setminus B(x, \varepsilon)} \nabla \{\Gamma(x-y; \lambda) - \Gamma(x-y; 0)\} f(y) d\sigma(y), \quad x \in \partial\Omega.$$

We can now estimate by Young's inequality ??

$$\|(\mathcal{K}^{(\varepsilon)} f)(x)\|_{L^2(\partial\Omega)} \leq \sup_{p \in \partial\Omega} \|\nabla \{\Gamma(p-\cdot; \lambda) - \Gamma(p-\cdot; 0)\} 1_{B(p, \varepsilon)}\|_{L^1(\partial\Omega)} \|f\|_{L^2(\partial\Omega)}.$$

Our goal is to show that

$$\sup_{p \in \partial\Omega} \|\nabla \{\Gamma(p-\cdot; \lambda) - \Gamma(p-\cdot; 0)\} 1_{B(p, \varepsilon)}\|_{L^1(\partial\Omega)} \rightarrow 0 \quad \text{as } \varepsilon \rightarrow 0.$$

To this end, let  $\varepsilon$  be small enough such that we can apply the estimates from Corollary 2.6 to calculate for some  $p \in \partial\Omega$

$$\begin{aligned} & \|\nabla \{\Gamma(p-\cdot; \lambda) - \Gamma(p-\cdot; 0)\} 1_{B(p, \varepsilon)}\|_{L^1(\partial\Omega)} \\ & \leq C \int_{\partial\Omega \cap B(p, \varepsilon)} \sqrt{|\lambda|} |p-y|^{2-d} d\sigma(y) \leq C \sqrt{|\lambda|} \varepsilon \end{aligned}$$

where for the last step we applied Lemma ???. For  $\varepsilon \rightarrow 0$  this gives us  $\mathcal{K}^{(\varepsilon)} \rightarrow \mathcal{K}$  in the operator norm. The last step is to verify the compactness of  $\mathcal{K}^{(\varepsilon)}$ . We note that the integral kernel of  $\mathcal{K}^{(\varepsilon)}$  is bounded which gives us that in particular the kernel is an element of  $L^2(\partial\Omega \times \partial\Omega; \mathbb{C}^{d \times d})$ . The compactness of  $\mathcal{K}^{(\varepsilon)}$  now follows from Weidmann [?, Thm. 6.11].  $\square$

Our next step is to introduce the *double layer potential*  $u(x) = \mathcal{D}_\lambda(f)(x)$  for the Stokes resolvent problem, where

$$u_j(x) = \int_{\partial\Omega} \left\{ \frac{\partial}{\partial y_i} \{ \Gamma_{jk}(y-x; \lambda) \} n_i(y) - \Phi_j(y-x) n_k(y) \right\} f_k(y) d\sigma(y). \quad \text{eq: defDoubleLayer} \quad (3.13)$$

The corresponding pressure is defined via

$$\phi(x) = \frac{\partial^2}{\partial x_i \partial x_k} \int_{\partial\Omega} G(y-x; 0) n_i(y) f_k(y) d\sigma(y) + \lambda \int_{\partial\Omega} G(y-x; 0) n_k(y) f_k(y) d\sigma(y). \quad \text{eq: defDoubleLayerPressure} \quad (3.14)$$

Using 2.21 and 2.22 one can show that  $(u, \phi)$  defines again a solution to the Stokes resolvent problem in  $\mathbb{R}^d \setminus \partial\Omega$ .

The next theorem will give us a suitable operator which maps a given function  $f \in L^p(\partial\Omega; \mathbb{C}^d)$  to boundary values of  $u = \mathcal{D}_\lambda(f)$ .

**Theorem 3.6.** *Let  $\lambda \in \Sigma_\theta$  and  $\Omega$  be a bounded Lipschitz domain in  $\mathbb{R}^d$ ,  $d \geq 3$ . Let  $u$  be given by (3.13) for  $f \in L^p(\partial\Omega; \mathbb{C}^d)$ ,  $1 < p < \infty$ . Then*

$$\|(u)^*\|_{L^p(\partial\Omega)} \leq C_p \|f\|_{L^p(\partial\Omega)}$$

where  $C_p$  depends only on  $d$ ,  $p$ ,  $\theta$  and the Lipschitz character of  $\Omega$ . Furthermore

$$u_\pm = \left( \mp \frac{1}{2} I + \mathcal{K}_\lambda^* \right) f, \quad \text{eq: nontangentialLimitDoubleLayer} \quad (3.15)$$

where  $K_\lambda^*$  is the adjoint of the operator  $K_\lambda$  in (3.10)

*Proof.* The estimate for  $(u)^*$  is a direct consequence of Lemma 3.2, in particular of the estimates on  $(\nabla u)^*$  and  $(\phi)^*$ .

For the proof of (3.15), we begin by determining the adjoint of the operator  $\mathcal{K}_\lambda$ . To this end we first work with truncated operators  $\mathcal{K}_\lambda^{(\varepsilon)}$  which are defined as

$$(\mathcal{K}_\lambda^{(\varepsilon)} f)(x) = \int_{\partial\Omega} 1_{E(x, \varepsilon)} \nabla_x \Gamma(x-y; \lambda) f(y) d\sigma(y) n - \int_{\partial\Omega} 1_{E(x, \varepsilon)} \Phi_k(x-y) f_k(y) d\sigma(y) n,$$

for  $x \in \partial\Omega$  and  $E(x, \varepsilon) := \mathbb{R}^d \setminus B(x, \varepsilon)$ . Now for  $f \in L^p(\partial\Omega; \mathbb{C}^d)$  and  $g \in L^q(\partial\Omega; \mathbb{C}^d)$  with  $1/p + 1/q = 1$  we calculate

$$\begin{aligned} \langle \mathcal{K}_{\bar{\lambda}}^{(\varepsilon)} f, g \rangle &= \int_{\partial\Omega} (\mathcal{K}_{\bar{\lambda}}^{(\varepsilon)} f_j)(x) \overline{g_j(x)} d\sigma(x) \\ &= \int_{\partial\Omega} \int_{\partial\Omega} \frac{\partial}{\partial x_i} \{ \Gamma_{jk}(x-y; \bar{\lambda}) \} f_k(y) 1_{E(x, \varepsilon)}(y) d\sigma(y) n_i(x) \overline{g_j(x)} d\sigma(x) \\ &\quad + \int_{\partial\Omega} \int_{\partial\Omega} \Phi_k(x-y) f_k(y) 1_{E(x, \varepsilon)}(y) d\sigma(y) n_j(x) \overline{g_j(x)} d\sigma(x). \end{aligned}$$

Note that  $1_{E(x, \varepsilon)}(y) = 1_{E(y, \varepsilon)}(x)$ . Now an application of Fubini and factoring out  $f_k(y)$  gives that the lengthy expression is equal to

$$\int_{\partial\Omega} f_k(y) \int_{\partial\Omega} \left\{ \frac{\partial}{\partial x_i} \{ \Gamma_{jk}(x-y; \bar{\lambda}) \} n_i(x) - \Phi_k(x-y) n_j(x) \right\} 1_{E(y, \varepsilon)}(x) \overline{g_j(x)} d\sigma(x) d\sigma(y).$$

Therefore we see that the adjoint of the truncated operator  $\mathcal{K}_{\bar{\lambda}}^{(\varepsilon)}$  is given by

$$((K_{\bar{\lambda}}^{(\varepsilon)})^* g)_k(y) = \int_{\partial\Omega} \left\{ \frac{\partial}{\partial x_i} \{ \Gamma_{jk}(x-y; \lambda) \} n_i(x) - \Phi_k(x-y) n_j(x) \right\} 1_{E(y, \varepsilon)}(x) g_j(x) d\sigma(x),$$

for  $y \in \partial\Omega$  since  $\overline{\Gamma_{jk}(x-y; \bar{\lambda})} = \Gamma_{jk}(x-y; \lambda)$ .

In the next step we will go from truncated operators to principal value operators. For this to work we will look for suitable majorants. If  $x \in \partial\Omega$  we estimate

$$\begin{aligned} |(\mathcal{K}_{\bar{\lambda}}^{(\varepsilon)} f)_j(x)| &= \left| \int_{|x-y|>\varepsilon} \frac{\partial}{\partial x_i} \{ \Gamma_{jk}(x-y; \lambda) \} f_k(y) d\sigma(y) n_i(x) \right. \\ &\quad \left. - \int_{|x-y|>\varepsilon} \Phi_k(x-y) f_k(y) n_j(x) d\sigma(y) \right| \\ &\leq T_{\lambda}^*(f)(x) + A^*(f)(x) \end{aligned}$$

Now dominated convergence gives

$$\lim_{\varepsilon \rightarrow 0} \langle K_{\bar{\lambda}}^{(\varepsilon)} f, g \rangle = \langle K_{\bar{\lambda}} f, g \rangle.$$

A similar argument gives

$$\lim_{\varepsilon \rightarrow 0} \langle f, K_{\bar{\lambda}}^{(\varepsilon)*} g \rangle = \langle f, K_{\bar{\lambda}}^* g \rangle,$$

where

$$((K_{\bar{\lambda}}^* g)_k)(y) = \text{p.v.} \int_{\partial\Omega} \left\{ \frac{\partial}{\partial x_i} \{ \Gamma_{kj}(x-y; \lambda) \} n_i(x) - \Phi_k(x-y) n_j(x) \right\} g_j(x) d\sigma(x).$$

Note that we have used the symmetry of  $(\Gamma_{\alpha\beta})$ .

The last part now consists of proving that the equality (3.15) holds. To simplify the calculations and make Lemma 3.3 more accessible note that on the one hand

$$\begin{aligned} \int_{\partial\Omega} \frac{\partial}{\partial y_i} \{\Gamma_{jk}(y-x; \lambda)\} n_i(y) f_k(y) d\sigma(y) &= - \int_{\partial\Omega} \frac{\partial}{\partial x_i} \{\Gamma_{jk}(x-y; \lambda)\} n_i(y) f_k(y) d\sigma(y) \\ &= - \frac{\partial}{\partial x_i} \mathcal{S}(n_i f)_j(x) \end{aligned}$$

and on the other hand

$$- \int_{\partial\Omega} \Phi_j(y-x) n_k(y) f_k(y) d\sigma(y) = \int_{\partial\Omega} \Phi_l(x-y) \delta_{lj} n_k(y) f_k(y) d\sigma(y) = \mathcal{S}_\Phi(\tilde{f}^j)(x),$$

where  $\tilde{f}_l^j = \delta_{lj} n_k f_k$ . For  $x \in \partial\Omega$  we can now calculate

$$\begin{aligned} &\left( \int_{\partial\Omega} \frac{\partial}{\partial y_i} \{\Gamma_{jk}(y-\cdot; \lambda)\} n_i(y) f_k(y) d\sigma(y) \right)_\pm(x) \\ &= - \left( \frac{\partial}{\partial x_i} \mathcal{S}_\lambda(n_i f)_j \right)_\pm(x) \\ &= \mp \frac{1}{2} \{n_i(x) n_i(x) f_j(x) - n_j(x) n_i(x) n_k(x) n_i(x) f_k(x)\} \\ &\quad - \text{p.v.} \int_{\partial\Omega} \frac{\partial}{\partial x_i} \{\Gamma_{jk}(x-y; \lambda)\} n_i(y) f_k(y) d\sigma(y) \\ &= \mp \frac{1}{2} \{f_j(x) - n_j(x) n_k(x) f_k(x)\} \\ &\quad + \text{p.v.} \int_{\partial\Omega} \frac{\partial}{\partial y_i} \{\Gamma_{jk}(x-y; \lambda)\} n_i(y) f_k(y) d\sigma(y), \end{aligned}$$

where we used trace formula (3.9). A similar procedure for the second integral part of the double layer potential gives

$$\begin{aligned} &- \left( \int_{\partial\Omega} \Phi_j(y-\cdot) n_k(y) f_k(y) d\sigma(y) \right)_\pm(x) \\ &= (\mathcal{S}_\Phi(\tilde{f}^j))_\pm(x) \\ &= \mp \frac{1}{2} n_k(x) \tilde{f}_k^j(x) - \text{p.v.} \int_{\partial\Omega} \Phi_k(x-y) \tilde{f}_k^j(x) d\sigma(y) \\ &= \mp \frac{1}{2} n_j(x) n_k(x) f_k(x) - \text{p.v.} \int_{\partial\Omega} \Phi_j(x-y) n_k(x) f_k(x) d\sigma(y) \end{aligned}$$

Putting everything together we get

$$(u_j)_\pm(x) = \mp \frac{1}{2} f_j(x) + (K_\lambda^* f)_j(x)$$

which proves the claim.  $\square$

# Chapter 4

## Rellich Estimates

In this section we will establish Rellich type estimates for the Stokes resolvent problem. We will for this entire section always assume that  $\Omega$  is a bounded Lipschitz domain in  $\mathbb{R}^d$ ,  $d \geq 2$  with connected boundary and  $|\partial\Omega| = 1$ . Furthermore we will use the shorthand notation

$$\|\cdot\|_{\partial} := \|\cdot\|_{L^2(\partial\Omega)}.$$

The goal of this section is to derive an Rellich type inequality which will be used to prove the invertibility of the operators  $\pm(1/2)I + \mathcal{K}_{\lambda}$ . This inequality is part of the following theorem.

thm:rellich

**Theorem 4.1.** *Let  $\lambda \in \Sigma_{\theta}$  and  $|\lambda| \geq \tau$ , where  $\tau \in (0, 1)$ . Let  $(u, \phi)$  be a solution to the Stokes resolvent problem in  $\Omega$  and suppose that  $(\nabla u)^* \in L^2(\partial\Omega)$  and  $(\phi)^* \in L^2(\partial\Omega)$ . Furthermore, assume that  $\nabla u, \phi$  have nontangential limits almost everywhere on  $\partial\Omega$ . Then*

$$\|\nabla u\|_{\partial} + \|\phi - \oint_{\partial\Omega} \phi\|_{\partial} \leq C \{ \|\nabla_{\tan} u\|_{\partial} + |\lambda|^{1/2} \|u\|_{\partial} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} \} \quad \text{eq:rellich1} \quad (4.1)$$

and

$$\|\nabla u\|_{\partial} + |\lambda|^{1/2} \|u\|_{\partial} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} + \|\phi\|_{\partial} \leq C \left\| \frac{\partial u}{\partial \nu} \right\|_{\partial}, \quad \text{eq:rellich2} \quad (4.2)$$

where  $\frac{\partial}{\partial \nu}$  denotes the conormal derivative, and  $C$  depends only on  $d, \tau, \theta$  and the Lipschitz character of  $\Omega$ .

We will now prepare the proof of this theorem by proving several helpful lemmata.

lem:rellichIdentity



**Lemma 4.2.** *Under the same conditions on  $(u, \phi)$  as in Theorem 4.1, we have*

$$\begin{aligned} \int_{\partial\Omega} h_k n_k |\nabla u|^2 d\sigma &= 2 \operatorname{Re} \int_{\partial\Omega} h_k \frac{\partial \bar{u}_i}{\partial x_k} \left( \frac{\partial u}{\partial \mathbf{v}} \right)_i d\sigma + \int_{\Omega} \operatorname{div}(h) |\nabla u|^2 dx \\ &\quad - 2 \operatorname{Re} \int_{\Omega} \frac{\partial h_k}{\partial x_j} \cdot \frac{\partial u_i}{\partial x_k} \cdot \frac{\partial \bar{u}_i}{\partial x_j} dx + 2 \operatorname{Re} \int_{\Omega} \frac{\partial h_k}{\partial x_i} \cdot \frac{\partial u_i}{\partial x_k} \bar{\phi} dx \\ &\quad - 2 \operatorname{Re} \int_{\Omega} h_k \frac{\partial u_i}{\partial x_k} \cdot \bar{\lambda} \bar{u}_i dx \end{aligned} \quad \text{eq:rellichIdentity} \quad (4.3)$$

and

$$\begin{aligned} \int_{\partial\Omega} h_k n_k |\nabla u|^2 d\sigma &= 2 \operatorname{Re} \int_{\partial\Omega} h_k \frac{\partial \bar{u}_i}{\partial x_j} \left\{ n_k \frac{\partial u_i}{\partial x_j} - n_j \frac{\partial u_i}{\partial x_k} \right\} d\sigma \\ &\quad + 2 \operatorname{Re} \int_{\partial\Omega} h_k \bar{\phi} \left\{ n_i \frac{\partial u_i}{\partial x_k} - n_k \frac{\partial u_i}{\partial x_i} \right\} d\sigma - \int_{\Omega} \operatorname{div}(h) |\nabla u|^2 dx \\ &\quad + 2 \operatorname{Re} \int_{\Omega} \frac{\partial h_k}{\partial x_j} \cdot \frac{\partial u_i}{\partial x_k} \cdot \frac{\partial \bar{u}_i}{\partial x_j} dx - 2 \operatorname{Re} \int_{\Omega} \frac{\partial h_k}{\partial x_i} \cdot \frac{\partial u_i}{\partial x_k} \bar{\phi} dx \\ &\quad + 2 \operatorname{Re} \int_{\Omega} h_k \frac{\partial u_i}{\partial x_k} \cdot \bar{\lambda} \bar{u}_i dx, \end{aligned} \quad \text{eq:rellichIdentity2} \quad (4.4)$$

where  $h = (h_1, \dots, h_d) \in C_0^1(\mathbb{R}^d, \mathbb{R}^d)$ .

*Proof.* The proof of the stated identities reduces to several integrations by part once we establish its applicability. Approximating  $\partial\Omega$  by a sequence of  $C^\infty$  domains with uniform Lipschitz characters as described in Verchota [?] and the facts that on the one hand  $(\nabla u)^*, (\phi)^* \in L^2(\partial\Omega)$  and on the other hand  $\nabla u$  and  $\phi$  have nontantential limits almost everywhere, the integration by parts is justified. Details on how the approximation argument works can be found in Brown [?]. For the sake of completeness we show the approximation argument once for a solid integral and once for a boundary integral.

Let  $(\Omega_l)_{l \in \mathbb{N}}$  denote the approximating sequence of  $C^\infty$  domains with outer normal  $n^{(l)}$ . Then

$$\int_{\partial\Omega_l} h_k n_k^{(l)} |\nabla u|^2 d\sigma_l = \int_{\partial\Omega} w_l(x) h_k(\Lambda_l(x)) n_k^{(l)}(\Lambda_l(x)) |\nabla u|^2(\Lambda_l(x)) d\sigma$$

Now we know that  $\lim_{l \rightarrow \infty} w_l(x) = 1$  and  $\lim_{l \rightarrow \infty} \Lambda_l(x) = x$  almost everywhere and  $\Lambda_l(x) \in \Gamma(x)$  for all  $l \in \mathbb{N}$ . Furthermore we know that  $\lim_{l \rightarrow \infty} n_k^{(l)} = n_k$  almost everywhere and that  $\nabla u$  has a nontangential limit almost everywhere. This gives us that the integrand converges almost everywhere to  $h_k(x) n_k(x) |\nabla u|^2(x)$ . Now furthermore we have that the integrand is dominated by  $\delta \|h\|_\infty ((\nabla u)^*)^2$ , where  $\delta$  is a uniform bound to  $w_l$ . Since by assumption  $(\nabla u)^* \in L^2(\partial\Omega)$ , the dominated convergence theorem gives us

$$\lim_{l \rightarrow \infty} \int_{\partial\Omega} w_l(x) h_k(\Lambda_l(x)) n_k^{(l)}(\Lambda_l(x)) |\nabla u|^2(\Lambda_l(x)) d\sigma = \int_{\partial\Omega} h_k n_k |\nabla u|^2 d\sigma.$$

It is easy to check, that the only differences in the approximation argument when applied to the other boundary integrals lie in the choice of the majorant. Now consider for instance the solid integral

We now start a formal calculation on  $\Omega$  and  $\partial\Omega$  keeping in mind that the stated equalities sometimes hold only after the application of the former approximation argument.

Let's expand the first summand in (4.3) using the definition of conormal derivatives

$$\begin{aligned} 2\operatorname{Re} \int_{\partial\Omega} h_k \frac{\partial \bar{u}_i}{\partial x_k} \left( \frac{\partial u}{\partial \mathbf{v}} \right)_i d\sigma &= 2\operatorname{Re} \int_{\partial\Omega} h_k \frac{\partial \bar{u}_i}{\partial x_k} \left( \frac{\partial u_i}{\partial x_j} \right) n_j d\sigma - 2\operatorname{Re} \int_{\Omega} h_k \frac{\partial \bar{u}_i}{\partial x_k} \phi n_i dx \\ &=: I_1 - I_2. \end{aligned}$$

For  $I_1$  we find using the divergence theorem

$$\begin{aligned} I_1 &= 2\operatorname{Re} \int_{\Omega} \frac{\partial}{\partial x_j} \left( h_k \frac{\partial}{\partial x_j} \frac{\partial \bar{u}_i}{\partial x_k} \frac{\partial u_i}{\partial x_j} \right) dx \\ &= 2\operatorname{Re} \int_{\Omega} \frac{\partial h_k}{\partial x_j} \frac{\partial \bar{u}_i}{\partial x_k} \frac{\partial u_i}{\partial x_j} + h_k \frac{\partial^2 \bar{u}_i}{\partial x_j \partial x_k} \frac{\partial u_i}{\partial x_j} + h_k \frac{\partial \bar{u}_i}{\partial x_k} \frac{\partial^2 u_i}{\partial x_j^2} dx \\ &=: I_3 + I_4 + I_5. \end{aligned}$$

For  $I_5$  we use the fact that  $u$  solves the Stokes resolvent problem which gives

$$\begin{aligned} I_5 &= 2\operatorname{Re} \int_{\Omega} h_k \frac{\partial \bar{u}_i}{\partial x_k} \frac{\partial \phi}{\partial x_i} dx + 2\operatorname{Re} \int_{\Omega} h_k \frac{\partial \bar{u}_i}{\partial x_k} \lambda u_i dx \\ &=: I_6 + I_7. \end{aligned}$$

Another application of the divergence theorem gives

$$\begin{aligned} I_2 &= 2\operatorname{Re} \int_{\Omega} \frac{\partial}{\partial x_i} \left( h_k \frac{\partial \bar{u}_i}{\partial x_k} \phi \right) dx \\ &= 2\operatorname{Re} \int_{\Omega} \frac{\partial h_k}{\partial x_i} \frac{\partial \bar{u}_i}{\partial x_k} \phi + h_k \frac{\partial^2 \bar{u}_i}{\partial x_j \partial x_k} \phi + h_k \frac{\partial \bar{u}_i}{\partial x_k} \frac{\partial \phi}{\partial x_i} dx \\ &=: I_8 + I_9 + I_{10}. \end{aligned}$$

One term that hasn't come up so far, the second summand of the right side in (4.3), will now be expanded

$$\begin{aligned} \operatorname{div}(h)|\nabla u|^2 dx &= \int_{\Omega} \operatorname{div}(h|\nabla u|^2) dx - \int_{\Omega} h_k \frac{\partial}{\partial x_i} |\nabla u|^2 dx \\ &=: I_{10} - I_{11}. \end{aligned}$$

Expanding this further gives us

$$I_{11} = \int_{\Omega} h_i \frac{\partial}{\partial x_i} \left( \frac{\partial u_k}{\partial x_j} \frac{\partial \bar{u}_k}{\partial x_j} \right) dx = \int_{\Omega} h_i \frac{\partial^2 u_k}{\partial x_i \partial x_j} \frac{\partial \bar{u}_k}{\partial x_j} + \frac{\partial u_k}{\partial x_j} \frac{\partial^2 \bar{u}_k}{\partial x_i \partial x_j} = I_4.$$

If we now put everything together, the right side of (4.3) reads

$$\begin{aligned} & (I_1 - I_2) + (I_{10} - I_{11}) - I_3 + I_8 - I_7 \\ &= (I_3 + I_4 + I_6 + I_7) - (I_8 + I_9 + I_6) + I_{10} - I_{11} - I_3 + I_8 - I_7 = I_{10}. \end{aligned}$$

Noting that by the divergence theorem we have

$$I_{10} = \int_{\partial\Omega} h_k n_k |\nabla u|^2 d\sigma,$$

the first identity is proven.

In order to prove identity (4.4), we show that the expression we get from considering ((4.3) + (4.4)) holds, i.e. we show the identity

$$\begin{aligned} 2 \int_{\partial\Omega} h_k n_k |\nabla u|^2 d\sigma &= 2 \operatorname{Re} \int_{\partial\Omega} h_k \frac{\partial \bar{u}_i}{\partial x_k} \left( \frac{\partial u}{\partial \mathbf{v}} \right)_i \\ &\quad + 2 \operatorname{Re} \int_{\partial\Omega} h_k \frac{\partial \bar{u}_i}{\partial x_j} \left\{ n_k \frac{\partial u_i}{\partial x_j} - n_j \frac{\partial u_i}{\partial x_k} \right\} d\sigma \\ &\quad + 2 \operatorname{Re} \int_{\partial\Omega} h_k \bar{\phi} \left\{ n_i \frac{\partial u_i}{\partial x_i} - n_k \frac{\partial u_i}{\partial x_i} \right\} d\sigma. \end{aligned}$$

To this end, note that the left side of the identity equals  $2I_{10}$ , whereas the right side can be written as

$$I_1 - I_2 + 2I_{10} - I_1 + I_2 - 0,$$

where we used the fact that  $\operatorname{div} u = 0$ . □

We note that the operators

$$\left\{ n_k \frac{\partial u_i}{\partial x_j} - n_j \frac{\partial u_i}{\partial x_k} \right\} \quad \text{and} \quad \left\{ n_i \frac{\partial u_i}{\partial x_k} - n_k \frac{\partial u_i}{\partial x_i} \right\}$$

are the *first-order tangential derivative operators* which can be found in Mitrea and Wriath [?].

We make a quick detour that gives us the following lemma.

lem:lambdaIneq

**Lemma 4.3.** *Let  $\theta \in (0, \pi/2)$ . Then there exists  $\alpha$  depending only on  $\theta$  such that*

$$\operatorname{Re}(\lambda) + \alpha |\operatorname{Im}(\lambda)| \geq |\lambda|$$

for all  $\lambda \in \Sigma_\theta$ .

*Proof.* For  $|\lambda| = 1$  we have  $\operatorname{Re}(\lambda) = \cos(\varphi)$  and  $\operatorname{Im}(\lambda) = \sin(\varphi)$  for some  $\varphi \in (0, \pi - \theta)$ . Set

$$\alpha = \frac{1 - \cos(\pi - \theta)}{\sin(\pi - \theta)} \geq \frac{1 - \cos(\varphi)}{\sin(\varphi)}.$$

Then we have

$$\operatorname{Re}(\lambda) + \alpha |\operatorname{Im}(\lambda)| = \cos(\varphi) + \alpha \sin(\varphi) \geq 1.$$

For arbitrary  $\lambda$  the claim follows by considering the normalized value  $\lambda/|\lambda|$ .  $\square$

The next lemma enables us to handle the solid integrals in (4.3) and (4.4).

lem:laxMilgramIneq

**Lemma 4.4.** *Under the same assumptions on  $(u, \phi)$  and  $\lambda$  as in Theorem 4.1, we have*

$$\int_{\Omega} |\nabla u|^2 dx + |\lambda| \int_{\Omega} |u|^2 \leq C \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial} \|u\|_{\partial}, \quad \text{eq:laxMilgramIneq (4.5)}$$

where  $C$  depends only on  $\theta$ .

*Proof.* Testing the Stokes resolvent problem against the solution  $u$  gives us

$$\int_{\Omega} -\Delta u \cdot \bar{u} dx + \lambda \int_{\Omega} u \cdot \bar{u} dx = \int_{\Omega} -\nabla \phi \cdot \bar{u} dx$$

Using integration by parts which may, as in the proof of the previous lemma, be justified by an approximation argument, we get

$$\int_{\Omega} |\nabla u|^2 dx - \int_{\partial\Omega} \frac{\partial u}{\partial n} \cdot \bar{u} d\sigma + \lambda \int_{\Omega} |u|^2 dx = \int_{\partial\Omega} \Phi n \cdot \bar{u} d\sigma$$

or with the definition of conormal derivatives

$$\int_{\Omega} |\nabla u|^2 dx + \lambda \int_{\Omega} |u|^2 dx = \int_{\partial\Omega} \frac{\partial u}{\partial \mathbf{v}} \cdot \bar{u} d\sigma. \quad \text{eq:testedStokes (4.6)}$$

If we now take the real and imaginary part of (4.6) and sum them up with a prefactor  $\alpha > 0$ , we get

$$\int_{\Omega} |\nabla u|^2 dx + \{\operatorname{Re}(\lambda) + \alpha |\operatorname{Im}(\lambda)|\} \int_{\Omega} |u|^2 dx \leq (1 + \alpha) \left| \int_{\partial\Omega} \frac{\partial u}{\partial \mathbf{v}} \cdot \bar{u} d\sigma \right|.$$

Lemma 4.3 now gives

$$\int_{\Omega} |\nabla u|^2 dx + |\lambda| \int_{\Omega} |u|^2 dx \leq C \left| \int_{\partial\Omega} \frac{\partial u}{\partial \mathbf{v}} \cdot \bar{u} d\sigma \right|,$$

from which we get estimate (4.5) after applying the Cauchy-Schwartz inequality.  $\square$

The next lemma combines Rellich identities (4.3) and (4.4) with estimate (4.5).

**Lemma 4.5.** *Under the same assumptions on  $(u, \phi)$  and  $\lambda$  as in Theorem 4.1, we have*

$$\|\nabla u\|_{\partial} \leq C_{\varepsilon} \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial} + \varepsilon \left\{ \|\nabla u\|_{\partial} + \|\phi\|_{\partial} + \|\lambda\|^{1/2} \|u\|_{\partial} \right\} \quad \text{eq:gradEstimateRellich (4.7)}$$

and

$$\|\nabla u\|_{\partial} \leq C_{\varepsilon} \left\{ \|\nabla_{\tan} u\|_{\partial} + \|\lambda\|^{1/2} \|u\|_{\partial} \right\} + \varepsilon \left\{ \|\nabla u\|_{\partial} + \|\phi\|_{\partial} \right\} \quad \text{eq:gradEstimateRellich2 (4.8)}$$

for all  $\varepsilon \in (0, 1)$ , where  $C_{\varepsilon}$  depends only on  $d$ ,  $\theta$ ,  $\tau$ ,  $\varepsilon$  and the Lipschitz character of  $\Omega$ .

*Proof.* Let  $h = (h_1, \dots, h_d) \in C_0^1(\mathbb{R}^d, \mathbb{R}^d)$  with  $h_k n_k \geq c > 0$  on  $\partial\Omega$ . The existence of this vector field follows from Verchota. Now in view of identity (??), we have

$$\|\nabla u\|_{\partial}^2 \leq C \left\{ \|\nabla u\|_{\partial} \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial} + \int_{\Omega} |\nabla u|^2 dx + \int_{\Omega} |\nabla u| |\phi| dx + |\lambda| \int_{\Omega} |\nabla u| |u| dx \right\}, \quad (4.9) \quad \text{eq:normRellich}$$

where the first term follows from the Cauchy-Schwartz inequality. Since  $\Delta\phi = 0$  and the nontangential maximal function  $(\phi)^* \in L^2(\partial\Omega)$  a result from Dahlberg [?] gives

$$\int_{\Omega} |\phi|^2 dx \leq C \|(\phi)^*\|_{\partial}^2 \leq C \|\phi\|_{\partial}^2. \quad \text{eq:dahlbergEstimate} \quad (4.10)$$

The last summand of (4.9) can be estimated as follows

$$\begin{aligned} |\lambda| \int_{\Omega} |\nabla u| |u| dx &\leq |\lambda| \left\{ \frac{|\lambda|^{1/2}}{2} \int_{\Omega} |u|^2 dx + \frac{1}{2|\lambda|^{1/2}} \int_{\Omega} |\nabla u|^2 dx \right. \\ &\quad \left. \leq C \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial} \|\lambda|^{1/2} u\|_{\partial}, \right. \end{aligned} \quad \text{eq:lambdaNablaU} \quad (4.11)$$

where in the first step we used the weighed Young inequality and in the second step we applied estimate (4.5). Similarly we calculate

$$\int_{\Omega} |\nabla u| |\phi| dx \leq \left( \int_{\Omega} |\nabla u|^2 dx \right)^{1/2} \left( \int_{\Omega} |\phi|^2 dx \right)^{1/2} \leq C \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial}^{1/2} \|u\|_{\partial}^{1/2} \|\phi\|_{\partial}, \quad \text{eq:nablaPhi} \quad (4.12)$$

where the first step is just the Cauchy-Schwartz inequality and the second step combines estimate (??) with estimate (4.10). Putting everything together, we calculate

$$\begin{aligned} \|\nabla u\|_{\partial}^2 &\leq C \|\nabla u\|_{\partial} \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial} + C \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial} \|u\|_{\partial} + C \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial}^{1/2} \|u\|_{\partial}^{1/2} \|\phi\|_{\partial} \\ &\quad + C \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial} \|\lambda|^{1/2} u\|_{\partial}. \end{aligned}$$

Note that we used the fact that  $|\lambda| \geq \tau$  to bound  $\|u\|_{\partial}$  as

$$\|u\|_{\partial} \leq \frac{|\lambda|^{1/2}}{\tau^{1/2}} \|u\|_{\partial} = C |\lambda|^{1/2} \|u\|_{\partial}.$$

The desired estimate (4.7) now follows applying Young's weighted inequality and the norm equivalence on finite dimensional vector spaces.

For inequality (4.8) we use the identity (4.4) and obtain

$$\begin{aligned} \|\nabla u\|_{\partial}^2 &\leq C \|\nabla_{\tan} u\|_{\partial} \{ \|\nabla u\|_{\partial} + \|\phi\|_{\partial} \} + C \int_{\Omega} |\nabla u|^2 dx \\ &\quad + C \int_{\Omega} |\nabla u| |\phi| dx + C |\lambda| \int_{\Omega} |\nabla u| |u| dx. \end{aligned}$$

Using estimates (4.5), (4.10), (4.11) and (4.12) together with the weighted Young inequality gives us

$$\|\nabla u\|_{\partial}^2 \leq C_{\varepsilon} \{ \|\nabla_{\tan} u\|_{\partial}^2 + \|\lambda|^{1/2} u\|_{\partial}^2 \} + \varepsilon \{ \|\nabla u\|_{\partial}^2 + \|\phi\|_{\partial}^2 + \frac{1}{4} \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial}^2 \}.$$

The claim now follows if we use the definition of the conormal derivative and the norm equivalence on finite dimensional vector spaces.  $\square$

We prove one last lemma before we tackle the central theorem of this chapter.

**Lemma 4.6.** *Assume that  $(u, \phi)$  satisfies the same conditions as in Theorem 4.1. Then*

$$\|\phi - \oint_{\partial\Omega} \phi\|_{\partial} \leq C\{\|\nabla u\|_{\partial} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)}\} \quad \text{eq:phiDashintPhi} \quad (4.13)$$

and

$$|\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} \leq C\{\|\phi\|_{\partial} + \|\nabla u\|_{\partial}\}, \quad \text{eq:lambdaun} \quad (4.14)$$

where  $C$  depends only on  $d$  and the Lipschitz character of  $\Omega$ .

*Proof.* By Verchota's approximation argument [?] we may assume that  $\Delta u = \nabla \phi + \lambda u$  on  $\partial\Omega$ . Multiplying the Stokes resolvent equation on  $\partial\Omega$  with  $n$  and using the triangle inequality gives

$$\begin{aligned} \|\nabla \phi \cdot n\|_{H^{-1}(\partial\Omega)} &\leq \|\Delta u \cdot n\|_{H^{-1}(\partial\Omega)} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)}, \\ |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} &\leq \|\Delta u \cdot n\|_{H^{-1}(\partial\Omega)} + \|\nabla \phi \cdot n\|_{H^{-1}(\partial\Omega)}. \end{aligned} \quad \text{eq:stokesEquationH1} \quad (4.15)$$

We will now show that

$$\|\Delta u \cdot n\|_{H^{-1}(\partial\Omega)} \leq C\|\nabla u\|_{\partial} \quad \text{eq:deltaun} \quad (4.16)$$

and

$$c\|\phi - \oint_{\partial\Omega} \phi \, d\sigma\|_{\partial} \leq \|\nabla \phi \cdot n\|_{H^{-1}(\partial\Omega)} \leq C\|\phi\|_{\partial} \quad \text{eq:nablaPhiin} \quad (4.17)$$

Using these two estimates applied to (4.15), we can directly derive (4.13) and (4.14).

In order to prove (4.16), note that

$$\Delta u \cdot n = n_i \frac{\partial^2 u_i}{\partial x_j^2} = \left( n_i \frac{\partial}{\partial x_j} - n_j \frac{\partial}{\partial x_i} \right) \frac{\partial u_i}{\partial x_j}$$

since  $\operatorname{div} u = 0$  in  $\overline{\Omega}$ . As the expression in between the brackets is a tangential derivative we derive estimate (4.16) from

$$|\langle \Delta u \cdot n, u \rangle| = |\langle \nabla u, \nabla_{\tan} u \rangle| \leq \|\nabla u\|_{\partial}^2$$

since this implies

$$\|\nabla u \cdot n\|_{H^{-1}(\partial\Omega)} \leq \|\nabla u\|_{\partial}.$$

Now for the proof of estimate (4.17) we will use  $L^2$ -estimates for the Neumann and regularity problems for the Laplace equation in Lipschitz domains. For  $g \in L^2(\partial\Omega)$  with

mean value zero, by Jerison and Kenig [?] the Neumann problem for Laplace's equation on the Lipschitz domain  $\Omega$  has a solution  $\psi$  with  $(\nabla \psi)^* \in L^2(\partial\Omega)$  and  $\frac{\partial \psi}{\partial n} = g$  on  $\partial\Omega$ . Green's identity we have that since  $\phi$  and  $\psi$  are harmonic

$$\begin{aligned} \left| \int_{\partial\Omega} \phi g \, d\sigma \right| &= \left| \int_{\partial\Omega} \phi \frac{\partial \psi}{\partial n} \, d\sigma \right| = \left| \int_{\partial\Omega} \frac{\partial \phi}{\partial n} \psi \, d\sigma \right| \\ &\leq \left\| \frac{\partial \phi}{\partial n} \right\|_{H^{-1}(\partial\Omega)} \|\psi\|_{H^1(\partial\Omega)} \leq C \left\| \frac{\partial \phi}{\partial n} \right\|_{H^{-1}(\partial\Omega)} \|g\|_{\partial}, \end{aligned} \quad (4.18)$$

where in the last step we used the estimate  $\|\psi\|_{H^1(\partial\Omega)} \leq C\|g\|_{\partial}$  for the  $L^2$  Neumann problem which can be found in Jerison and Kenig [?]. Now if we set  $\bar{g} = \phi - \tilde{\phi}$ , with  $\tilde{\phi} = \int_{\partial\Omega} \phi \, d\sigma$  and use that  $\int_{\partial\Omega} (\phi - \tilde{\phi})(\phi - \tilde{\phi}) \, d\sigma = \int_{\partial\Omega} \phi(\phi - \tilde{\phi}) \, d\sigma$ , we get from (4.18)

$$\|\phi - \tilde{\phi}\|_{\partial}^2 \leq C \left\| \frac{\partial \phi}{\partial n} \right\|_{H^{-1}(\partial\Omega)} \|\phi - \tilde{\phi}\|_{\partial}$$

or, after rearranging and expanding

$$\left\| \phi - \int_{\partial\Omega} \phi \, d\sigma \right\|_{\partial} \leq C \left\| \frac{\partial \phi}{\partial n} \right\|_{H^{-1}(\partial\Omega)}$$

We work in a similar way with results from the regularity problem of Laplace's equation by Jerison and Kenig [?]. Given  $f \in H^1(\partial\Omega)$ , there exists a harmonic function  $\psi$  in  $\Omega$  such that  $(\nabla \psi)^* \in L^2(\partial\Omega)$  and  $\psi = f$  on  $\partial\Omega$ . As for (4.18), we calculate

$$\begin{aligned} \left| \int_{\partial\Omega} \frac{\partial \phi}{\partial n} f \, d\sigma \right| &= \left| \int_{\partial\Omega} \frac{\partial \phi}{\partial n} \psi \, d\sigma \right| = \left| \int_{\partial\Omega} \phi \frac{\partial \psi}{\partial n} \, d\sigma \right| \\ &\leq \|\phi\|_{\partial} \|\nabla \psi\|_{\partial} \leq C \|\phi\|_{\partial} \|f\|_{H^1(\partial\Omega)}, \end{aligned}$$

where in the last step we used the estimate  $\|\nabla \psi\|_{\partial} \leq C\|f\|_{H^1(\partial\Omega)}$  for the  $L^2$  regularity problem. By duality this gives that

$$\left\| \frac{\partial \phi}{\partial n} \right\|_{H^{-1}(\partial\Omega)} \leq C \|\phi\|_{\partial}.$$

□  
rem:harmonicEstimate

*Remark 4.7.* A careful look at the proof of inequality (4.17) reveals that the estimate

$$c\|\phi\|_{\partial} \leq \|\nabla \phi \cdot n\|_{H^{-1}(\partial\Omega)},$$

holds for all harmonic functions  $\phi$  with vanishing mean on  $\partial\Omega$ .

After all this preparation we are now able to prove Theorem 4.1.

*Proof of Theorem 4.1.* For the proof of estimate (4.1), without loss of generality we can assume that  $\int_{\partial\Omega} \phi \, d\sigma = 0$ .

Using (4.13) for the second summand in (4.1) and then (4.8) for the terms involving  $\nabla u$  we get

$$\begin{aligned} \|\nabla u\|_{\partial} + \|\phi\|_{\partial} &\leq C\{\|\nabla u\|_{\partial} + |\lambda| \|u \cdot n\|_{H^1(\partial\Omega)}\} \\ &\leq C_{\varepsilon} \left\{ \|\nabla_{\tan} u\|_{\partial} + |\lambda|^{1/2} \|u\|_{\partial} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} \right\} \\ &\quad + C\varepsilon \{\|\nabla u\|_{\partial} + \|\phi\|_{\partial}\} \end{aligned}$$

for all  $\varepsilon \in (0, 1)$ . Choosing  $\varepsilon$  such that  $C\varepsilon < (1/2)$  we can rearrange the above inequality and obtain estimate (4.1).

Estimate (4.2) will need more effort to be proven. We start with inequality (4.14) and derive

$$\|\nabla u\|_{\partial} + \|\phi\|_{\partial} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} \leq C\{\|\nabla u\|_{\partial} + \|\phi\|_{\partial}\} \leq C\left\{\left\|\frac{\partial u}{\partial \mathbf{v}}\right\|_{\partial} + \|\nabla u\|_{\partial}\right\},$$

where in the last step we used the definition of conormal derivatives. If we now apply (4.7) we get

$$\|\nabla u\|_{\partial} + \|\phi\|_{\partial} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} \leq C_{\varepsilon} \left\|\frac{\partial u}{\partial \mathbf{v}}\right\|_{\partial} + \varepsilon \{\|\nabla u\|_{\partial} + \|\phi\|_{\partial} + \|\lambda|^{1/2} u\|_{\partial}\}$$

for all  $\varepsilon \in (0, 1)$ . Choosing  $\varepsilon$  appropriately yields

$$\|\nabla u\|_{\partial} + \|\phi\|_{\partial} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} \leq C \left\|\frac{\partial u}{\partial \mathbf{v}}\right\|_{\partial} + C|\lambda|^{1/2} \|u\|_{\partial}. \quad \text{eq: partOfRellich2} \quad (4.19)$$

Now we need to estimate  $|\lambda|^{1/2} \|u\|_{\partial}$ . Green's identity yields

$$\begin{aligned} \int_{\partial\Omega} h_k n_k |u|^2 d\sigma &= \int_{\Omega} \frac{\partial}{\partial x_k} (h_k |u|^2) dx = \int_{\Omega} \frac{\partial h_k}{\partial x_k} |u|^2 dx + \int_{\Omega} h_k \frac{\partial |u|^2}{\partial x_k} dx \\ &= \int_{\Omega} \operatorname{div}(h) |u|^2 dx + 2 \operatorname{Re} \int_{\Omega} h_k \frac{\partial \bar{u}}{\partial x_k} u dx. \quad \text{eq: hknkgreen} \quad (4.20) \end{aligned}$$

We choose  $h \in C_0^1(\mathbb{R}^d, \mathbb{R}^d)$  with  $h_k n_k \geq c > 0$  on  $\partial\Omega$ . The existence of such a function  $h$  was proven by Verchota [?]. Using this, we can continue the estimate (4.20) as

$$\|u\|_{\partial}^2 \leq C \int_{\Omega} |u|^2 dx + C \int_{\Omega} |u| |\nabla u| dx. \quad \text{eq: estupartial} \quad (4.21)$$

The next estimate uses (4.21) and (4.5) which gives

$$\begin{aligned} |\lambda| \|u\|_{\partial}^2 &\leq |\lambda| C \int_{\Omega} |u|^2 dx + |\lambda| C \int_{\Omega} |u| |\nabla u| dx \\ &\leq C \left\|\frac{\partial u}{\partial \mathbf{v}}\right\|_{\partial} \|u\|_{\partial} + |\lambda|^{1/2} C \int_{\Omega} (|\lambda|^{1/2} |u|) |\nabla u| dx \\ &\leq C \left\|\frac{\partial u}{\partial \mathbf{v}}\right\|_{\partial} \|u\|_{\partial} + |\lambda|^{1/2} C \left( \int_{\Omega} |\lambda| |u|^2 \right)^{1/2} \left( \int_{\Omega} |\nabla u|^2 dx \right)^{1/2} \\ &\leq C \left\|\frac{\partial u}{\partial \mathbf{v}}\right\|_{\partial} \|\lambda|^{1/2} u\|_{\partial}. \end{aligned}$$



Note that for the last estimate we also used the fact that  $|\lambda| \geq \tau$  helps us to bound  $\|u\|_{\partial}$  by  $C|\lambda|^{1/2}\|u\|_{\partial}$ . Rearranging terms in the last estimate, we now derive

$$\| |\lambda|^{1/2} u \|_{\partial} \leq C \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial}. \quad \text{eq:lambda12u} \quad (4.22)$$

Estimate (4.2) follows directly from (4.19) in combination with (4.22) and this concludes our proof.  $\square$

Shen proved that under reasonable assumptions a theorem similar to 4.1 also holds for exterior domains

thm:rellichExterior

**Theorem 4.8.** *Let  $\lambda \in \Sigma_{\theta}$  and  $|\lambda| \geq \tau$ , where  $\tau \in (0, 1)$ . Let  $(u, \phi)$  be a solution of the Stokes resolvent Problem in  $\Omega_- = \mathbb{R}^d \setminus \overline{\Omega}$ . Suppose additionally that  $(\nabla u)^*, (\phi)^* \in L^2(\partial\Omega)$  and that  $\nabla u, \phi$  have nontangential limits almost everywhere on  $\partial\Omega$ . Furthermore let for  $|x| \rightarrow \infty$*

$$|\phi(x)| + |\nabla u(x)| = O(|x|^{1-d}) \quad \text{and} \quad u(x) = \begin{cases} O(|x|^{2-d}) & \text{if } d \geq 3 \\ o(1) & \text{if } d = 2. \end{cases}$$

Then

$$\|\nabla u\|_{\partial} + \|\phi\|_{\partial} \leq C \left\{ \|\nabla_{\tan} u\|_{\partial} + |\lambda|^{1/2} \|u\|_{\partial} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} \right\} \quad \text{eq:rellich1ext} \quad (4.23)$$

and

$$\|\nabla u\|_{\partial} + |\lambda|^{1/2} \|u\|_{\partial} + |\lambda| \|u \cdot n\|_{H^{-1}(\partial\Omega)} + \|\phi\|_{\partial} \leq C \left\| \frac{\partial u}{\partial \mathbf{v}} \right\|_{\partial}, \quad \text{eq:rellich2ext} \quad (4.24)$$

where  $C$  depends only on  $d, \tau, \theta$  and the Lipschitz character of  $\Omega$ .

# Chapter 5

## Solving the $L^2$ -Dirichlet Problem

This section is all about the application of the method of layer potentials to solve the  $L^2$  Dirichlet problem for the Stokes resolvent system. Furthermore we will establish a uniform  $L^p$  estimate for the nontangential-maximal-function which will be important for the proof of our central theorem.

For the remainder of this chapter let  $\Omega$  always denote a bounded Lipschitz domain in  $\mathbb{R}^d$ ,  $d \geq 3$  with connected boundary. We will use  $L_n^2(\partial\Omega)$  to denote the function space

$$L_n^2(\partial\Omega) := \left\{ f \in L^2(\partial\Omega; \mathbb{C}^d) : \int_{\partial\Omega} f \cdot n \, d\sigma = 0 \right\},$$

and  $L_0^2(\partial\Omega; \mathbb{C}^d)$  to denote the function space of  $L^2$  functions with mean value zero. As before  $\|\cdot\|_{\partial}$  stands for the norm of  $L^2(\partial\Omega)$ .

We will first derive bounds on the inverse operator of  $(1/2)I + \mathcal{K}_\lambda$  from Chapter 3.

**Lemma 5.1.** *Let  $\lambda \in \Sigma_\theta$  and  $|\lambda| \geq \tau$ , where  $\tau \in (0, 1)$ . Suppose that  $|\partial\Omega| = 1$ . Then  $(1/2)I + \mathcal{K}_\lambda$  is an isomorphism on  $L^2(\partial\Omega; \mathbb{C}^d)$  and*

$$\|f\|_{\partial} \leq C \|((1/2)I + \mathcal{K}_\lambda)f\|_{\partial} \quad \text{for any } f \in L^2(\partial\Omega; \mathbb{C}^d), \quad \text{eq:inverseEstimate} \quad (5.1)$$

where  $C$  depends only on  $d$ ,  $\theta$ ,  $\tau$  and the Lipschitz character of  $\Omega$ .

*Proof.* We start with  $f \in L^2(\partial\Omega; \mathbb{C}^d)$  and the corresponding single layer potentials  $u = \mathcal{S}_\lambda(f)$  and  $\phi = \mathcal{S}_\Phi(f)$  given by (3.1) and (3.2). We saw in Chapter 3 that  $(u, \phi)$  solves the Stokes resolvent problem in  $\mathbb{R}^d \setminus \partial\Omega$  and got from Lemma 3.2 with  $p = 2$  for the nontangential maximal functions that  $(\nabla u)^*, (\phi)^* \in L^2(\partial\Omega)$ . We furthermore saw in Lemma 3.3 that  $\nabla u$  and  $\phi$  have nontangential limits almost everywhere on  $\partial\Omega$ . Finally in Theorem 3.4 we saw that  $\nabla_{\tan} u_+ = \nabla_{\tan} u_-$  and derived the jump condition  $(\frac{\partial u}{\partial \nu})_{\pm} = (\pm(1/2)I + \mathcal{K}_\lambda)f$ .

Our next step will be to show the estimate

$$\|\nabla u_-\|_{\partial} + \|\phi_-\|_{\partial} \leq C \left\| \left( \frac{\partial u}{\partial \mathbf{v}} \right)_+ \right\|_{\partial}. \quad \text{eq:negNablaPhi} \quad (5.2)$$

Assuming that (5.2) holds we can prove (5.1): Set  $f = \left( \frac{\partial u}{\partial \mathbf{v}} \right)_+ - \left( \frac{\partial u}{\partial \mathbf{v}} \right)_-$ . Then this gives with the definition of the conormal derivative and estimate (5.2) that

$$\begin{aligned} \|f\|_{\partial} &\leq \left\| \left( \frac{\partial u}{\partial \mathbf{v}} \right)_+ \right\|_{\partial} + \left\| \left( \frac{\partial u}{\partial \mathbf{v}} \right)_- \right\|_{\partial} \\ &\leq \left\| \left( \frac{\partial u}{\partial \mathbf{v}} \right)_+ \right\|_{\partial} + \left\| \left( \frac{\partial u}{\partial n} \right)_- \right\|_{\partial} + \|\phi_- n\|_{\partial} \\ &\leq C \left\| \left( \frac{\partial u}{\partial \mathbf{v}} \right)_+ \right\|_{\partial} = C \|(1/2)I + K_{\lambda}\| f\|_{\partial}. \end{aligned}$$

In order to prove (5.2), note that since  $|u(x)| + |\nabla u(x)| = O(|x|^{-N})$  for all  $N > 0$  and  $\phi(x) = O(|x|^{1-d})$  as  $|x| \rightarrow \infty$  we can use Theorem 4.8 to derive

$$\begin{aligned} \|\nabla u_-\|_{\partial} + \|\phi_-\|_{\partial} &\leq C \left\{ \|\nabla_{\tan} u_-\|_{\partial} + |\lambda|^{1/2} \|u_-\|_{\partial} + |\lambda| \|n \cdot u_-\|_{H^{-1}(\partial\Omega)} \right\} \\ &= C \left\{ \|\nabla_{\tan} u_+\|_{\partial} + |\lambda|^{1/2} \|u_+\|_{\partial} + |\lambda| \|n \cdot u_+\|_{H^{-1}(\partial\Omega)} \right\}, \quad \text{eq:nablauMinus} \quad (5.3) \end{aligned}$$

where we used the fact that  $u_+ = u_-$  and  $\nabla_{\tan} u_+ = \nabla_{\tan} u_-$  on  $\partial\Omega$ . Inequality (4.2) of Theorem 4.1 now allows us to estimate the right hand side of (5.3) by  $C \left\| \left( \frac{\partial u}{\partial \mathbf{v}} \right)_+ \right\|_{\partial}$  and thus the desired estimate (5.2) follows.

Let's now work on the invertibility of  $(1/2)I + \mathcal{K}_{\lambda}$ . In the case  $\lambda = 0$ , Fabes, Kenig and Verchota showed in [?] that  $(1/2)I + \mathcal{K}_0$  as an operator on  $L^2(\partial\Omega; \mathbb{R}^d)$  has a one dimensional null space and as range the space  $L_0^2(\partial\Omega; \mathbb{R}^d)$ . Thus  $(1/2)I + \mathcal{K}_0$  has Fredholm index 0. This remains true if we replace  $L^2(\partial\Omega; \mathbb{R}^d)$  by  $L^2(\partial\Omega; \mathbb{C}^d)$  as this just corresponds to a complexification of the vector space and the operator. Since the operator  $\mathcal{K}_{\lambda} - \mathcal{K}_0$  is compact on  $L^2(\partial\Omega; \mathbb{C}^d)$  (see Toks Dorf [?]) we deduce that the operator

$$(1/2)I + \mathcal{K}_{\lambda} = (1/2)I + \mathcal{K}_0 + (\mathcal{K}_{\lambda} - \mathcal{K}_0)$$

has the Fredholm index zero as well for all  $\lambda \in \Sigma_{\theta}$ . Now inequality (5.1) gives that  $(1/2)I + \mathcal{K}_{\lambda}$  is injective and thus the Fredholm index of zero implies that it is also surjective and hence an isomorphism.  $\square$

The next lemma works with the counterpart of  $(1/2)I + \mathcal{K}_{\lambda}$ .

**Lemma 5.2.** *Let  $\lambda \in \Sigma_{\theta}$ . Then  $-(1/2)I + \mathcal{K}_{\lambda}$  is a Fredholm operator on  $L^2(\partial\Omega; \mathbb{C}^d)$  with index zero and*

$$\|f\|_{\partial} \leq C \|(-(1/2)I + \mathcal{K}_{\lambda})f\|_{\partial} \quad \text{for all } f \in L_n^2(\partial\Omega). \quad \text{eq:inverseEstimate2} \quad (5.4)$$

*Proof.* In the case  $\lambda = 0$ , Fabes Kenig and Verchota proved in [?] that the Fredholm index of the operator  $-(1/2)I + \mathcal{K}_0$  on  $L^2(\partial\Omega; \mathbb{R}^d)$  is zero and estimate (5.4) holds. As in the previous proof, this still remains true if we complexify the operator making it a Fredholm operator with index zero on  $L^2(\partial\Omega; \mathbb{C}^d)$ . Since  $\mathcal{K}_\lambda - \mathcal{K}_0$  is compact on  $L^2(\partial\Omega; \mathbb{C}^d)$  and the Fredholm index remains unchanged under compact perturbations, we know that the Fredholm index of  $-(1/2)I + \mathcal{K}_\lambda$  on  $L^2(\partial\Omega; \mathbb{C}^d)$  is zero for all  $\lambda \in \Sigma_\theta$ . This proves the first claim of the lemma.

Now let  $\tau < \frac{1}{2\text{diam}(\Omega)^2+1}$  and  $|\lambda| < \tau$ . Then

$$\|(\mathcal{K}_\lambda - \mathcal{K}_0)f\|_\partial \leq C|\lambda|^{1/2}\|f\|_\partial.$$

In order to prove this inequality we once again apply Young's inequality, i.e. we start by estimating

$$\|(\mathcal{K}_\lambda - \mathcal{K}_0)f\|_\partial \leq \sup_{p \in \partial\Omega} \|\nabla_x \{\Gamma(p - \cdot; \lambda) - \Gamma(p - \cdot; 0)\}\|_{L^1(\partial\Omega)} \|f\|_{L^2(\partial\Omega)}.$$

In the next step we prove that for  $p \in \partial\Omega$  the integral over the gradients of  $\Gamma$  can be estimated independent of  $p$ . This is straightforward using Lemma ?? as Corollary 2.6 gives us

$$\begin{aligned} & \int_{\partial\Omega} |\nabla_x \{\Gamma(p - y; \lambda) - \Gamma(p - y; 0)\}| d\sigma(y) \\ & \leq C|\lambda|^{1/2} \int_{\partial\Omega} \frac{1}{|p - y|^{d-2}} d\sigma(y) \\ & = |\lambda|^{1/2} C \int_{\partial\Omega \cap B(p, r_0/4)} \frac{1}{|p - y|^{d-2}} d\sigma(y) + |\lambda|^{1/2} C \int_{\partial\Omega \setminus B(p, r_0/4)} \frac{1}{|p - y|^{d-2}} d\sigma(y) \\ & \leq C|\lambda|^{1/2} (r_0/4 + 4^{2-d} r_0^{d-2} |\partial\Omega|), \end{aligned}$$

where  $r_0$  is the radius from the definition of Lipschitz domains. Note that by the choice of  $\tau$  the estimate from Corollary 2.6 applies on the whole domain of integration.

For  $f \in L_n^2(\partial\Omega)$  we can now estimate

$$\begin{aligned} \|f\|_\partial & \leq C\|(-(1/2)I + \mathcal{K}_0)f\|_\partial \\ & \leq C\|(-(1/2)I + \mathcal{K}_\lambda)f\|_\partial + \|(\mathcal{K}_\lambda - \mathcal{K}_0)f\|_\partial \\ & \leq C\|(-(1/2)I + \mathcal{K}_\lambda)f\|_\partial + C|\lambda|^{1/2}\|f\|_\partial, \end{aligned}$$

with a constant  $C$  depending only on  $d$ ,  $\theta$  and the Lipschitz character of  $\partial\Omega$ . Choosing  $\tau$  even smaller allows us to rearrange the terms in the above estimate such that estimate (5.4) holds for  $\lambda \in \Sigma_\theta$  and  $|\lambda| < \tau$ , with  $\tau$  depending on  $d$ ,  $\theta$  and the Lipschitz character of  $\Omega$ .

Now leave  $\tau$  fixed and consider the case  $|\lambda| \geq \tau$ . This case will be handled using the Rellich estimates from Section 4. We use the facts that for  $\nabla_{\tan} u$  and  $u$  the inner and outer nontangential limits coincide and apply Theorems 4.1 and 4.8 to conclude that

$$\begin{aligned} & \|\nabla u_+\|_{\partial} + \|\phi_+ - \int_{\partial\Omega} \phi_+ \| \\ & \leq C\{\|(\nabla_{\tan} u)_+\|_{\partial} + |\lambda|^{1/2}\|u_+\|_{\partial} + |\lambda|\|u_+ \cdot n\|_{H^{-1}(\partial\Omega)}\} \\ & = C\{\|(\nabla_{\tan} u)_-\|_{\partial} + |\lambda|^{1/2}\|u_-\|_{\partial} + |\lambda|\|u_- \cdot n\|_{H^{-1}(\partial\Omega)}\} \\ & \leq C\|(\frac{\partial u}{\partial \mathbf{v}})_-\|_{\partial}. \end{aligned}$$

We can now use this inequality to estimate  $\|(\frac{\partial u}{\partial \mathbf{v}})_+\|_{\partial}$  since

$$\begin{aligned} \|(\frac{\partial u}{\partial \mathbf{v}})_+\|_{\partial} & \leq \|(\frac{\partial u}{\partial \mathbf{n}})_+\|_{\partial} + C\|\phi_+\|_{\partial} \\ & \leq C\|(\nabla u)_+\|_{\partial} + C\|\phi_+ - \int_{\partial\Omega} \phi_+ d\sigma\|_{\partial} + C|\int_{\partial\Omega} \phi_+ d\sigma| \\ & \leq C\|(\frac{\partial u}{\partial \mathbf{v}})_-\|_{\partial} + C|\int_{\partial\Omega} \phi_+ d\sigma| \end{aligned}$$

Considering the jump relation (3.10) and the previous estimate we get that

$$\begin{aligned} \|f\|_{\partial} & \leq \|(\frac{\partial u}{\partial \mathbf{v}})_+\|_{\partial} + \|(\frac{\partial u}{\partial \mathbf{v}})_-\|_{\partial} \\ & \leq C\|(\frac{\partial u}{\partial \mathbf{v}})_-\|_{\partial} + C|\int_{\partial\Omega} \phi_+ d\sigma| \\ & \leq C\|(-(1/2)I + \mathcal{K}_{\lambda})f\|_{\partial} + C|\int_{\partial\Omega} \phi_+ d\sigma|. \end{aligned} \quad \text{eq:estimatef} \quad (5.5)$$

We now are left with the term  $\int_{\partial\Omega} \phi_+ d\sigma$  that needs to be estimated. To this end, note that multiplying the conormal derivatives of  $u$  by  $n$  gives

$$(\frac{\partial u}{\partial \mathbf{v}})_+ \cdot n = (\frac{\partial u_i}{\partial x_j})_+ n_i n_j - \phi_+ = n_j(n_i \frac{\partial}{\partial x_j} - n_j(\frac{\partial}{\partial x_i})u_i)_+ - \phi_+,$$

where for the second equality we used that  $\operatorname{div}(u) = 0$  in  $\Omega$  and thus this also holds for the nontangential limit. This identity now implies

$$\begin{aligned} |\int_{\partial\Omega} \phi_+ d\sigma| & \leq |\int_{\partial\Omega} (\frac{\partial u}{\partial \mathbf{v}})_+ \cdot n d\sigma| + C\|\nabla_{\tan} u\|_{\partial} \\ & \leq |\int_{\partial\Omega} (\frac{\partial u}{\partial \mathbf{v}})_- \cdot n d\sigma| + C\|\nabla_{\tan} u\|_{\partial} \\ & \leq C\|(\frac{\partial u}{\partial \mathbf{v}})_-\|_{\partial}, \end{aligned} \quad \text{eq:estimatephiplus} \quad (5.6)$$

where in the second step, we used the jump relation to exchange  $(\frac{\partial u}{\partial \mathbf{v}})_+ \cdot n$  by  $(\frac{\partial u}{\partial \mathbf{v}})_- + f \cdot n$  and then used the fact  $f \in L_n^2(\partial\Omega)$ . The third step follows from Theorem 4.8 considering

that  $\|\nabla_{\tan} u\|_{\partial} \leq C\|\nabla u\|_{\partial}$ . Now extending estimate (5.5) by (5.6) gives

$$\|f\|_{\partial} \leq C\|(-(1/2)I + \mathcal{K}_{\lambda})f\|_{\partial} + C\|(\frac{\partial u}{\partial \nu})_{-}\|_{\partial} \leq C\|(-(1/2)I + \mathcal{K}_{\lambda})f\|_{\partial},$$

where we used the jump relation (3.10) again. This proves estimate (5.4) in the case  $|\lambda| \geq \tau$  and thus concludes the proof.  $\square$

In the following lemma we will show the uniqueness of solutions to the  $L^2$  Dirichlet problem to the Stokes resolvent system.

**Lemma 5.3.** *Let  $\lambda \in \Sigma_{\theta}$  and  $(u, \phi)$  be a solution to the Stokes resolvent problem in  $\Omega$ . Furthermore suppose that the nontantential limit of  $u$  exists almost everywhere on  $\partial\Omega$  and that  $(u)^* \in L^2(\partial\Omega)$ . Then*

$$\int_{\Omega} |u|^2 dx \leq C \int_{\partial\Omega} |u|^2 d\sigma, \quad \text{eq:OmegaBoundaryEstimate} \quad (5.7)$$

where  $C$  depends only on  $d$ ,  $\theta$  and the Lipschitz character of  $\Omega$ .

*Proof.* We use Verchota's approximation theorem [?] and approximate  $\Omega$  by a sequence of smooth domains with uniform Lipschitz characters from inside. As a consequence we may assume that  $\Omega$  is smooth and  $u, \phi$  are smooth in  $\bar{\Omega}$ . Let  $(w, \psi) \in H_0^1(\Omega; \mathbb{C}^d) \times H^1(\Omega)$  be a solution to the inhomogenous system

$$\begin{cases} -\Delta w + \lambda w + \nabla \psi = \bar{u} & \text{in } \Omega, \\ \operatorname{div}(w) = 0 & \text{in } \Omega. \end{cases} \quad \text{eq:inhomogenousStokes} \quad (5.8)$$

In fact the regularity theory for the Stokes equation gives us that  $w$  and  $\psi$  are smooth. It follows from testing (5.8) against  $u$  that

$$\int_{\Omega} |u|^2 dx = \int_{\Omega} u \cdot \{-\Delta w + \lambda w + \nabla \psi\} dx. \quad \text{eq:testingInhomogenousStokes} \quad (5.9)$$

Using one of Green's identities on the first summand and the fact that  $u$  is the solution to the Stokes resolvent problem gives that

$$\begin{aligned} \int_{\Omega} -u \cdot \Delta w dx &= \int_{\Omega} -w \cdot \Delta u dx - \int_{\partial\Omega} u \cdot \frac{\partial w}{\partial n} d\sigma, \\ &= \int_{\Omega} w \cdot (-\lambda u - \nabla \phi) dx - \int_{\partial\Omega} u \cdot \frac{\partial w}{\partial n} d\sigma \\ &= \int_{\Omega} -\lambda w \cdot u dx - \int_{\partial\Omega} u \cdot \frac{\partial w}{\partial n} d\sigma, \end{aligned}$$

where in the last step we used partial integration and the fact that  $w$  vanishes on  $\partial\Omega$  and is divergence free:

$$\int_{\Omega} w \cdot \nabla \phi dx = - \int_{\Omega} \operatorname{div}(w) \phi dx + \int_{\partial\Omega} \phi w \cdot n d\sigma = 0.$$

For the third summand in (5.9) we do the same with the only difference that the second integral does not vanish. Putting everything together gives

$$\begin{aligned} \int_{\Omega} |u|^2 dx &= - \int_{\partial\Omega} u \cdot \left\{ \frac{\partial w}{\partial n} - \psi n \right\} d\sigma \\ &\leq \|u\|_{\partial} \{ \|\nabla w\|_{\partial} + \|\psi\|_{\partial} \} \end{aligned} \quad \text{eq:u2estimate} \quad (5.10)$$

by the Cauchy-Schwartz inequality. As the pressure  $\psi$  is only specified modulo additive constants, we may as well assume that  $\int_{\partial\Omega} \psi d\sigma = 0$ . Furthermore by the Schwartz theorem we see from (5.8) that  $\Delta\psi = \text{div}(\bar{u}) = 0$  in  $\Omega$ . As stated in Remark 4.7, this allows us to use the results from the proof of (4.17) by setting  $\phi = \psi$  to conclude that

$$\|\psi\|_{\partial} \leq C \|\nabla \psi \cdot n\|_{H^{-1}(\partial\Omega)}$$

and since  $w$  has vanishing trace on  $\partial\Omega$  we can use that fact that  $(w, \psi)$  solves (5.8) to further estimate

$$\begin{aligned} &\leq C \{ \|\Delta w \cdot n\|_{H^{-1}(\partial\Omega)} + \|u \cdot n\|_{H^{-1}(\partial\Omega)} \} \\ &\leq C \{ \|\nabla w\|_{\partial} + \|u\|_{\partial} \}, \end{aligned} \quad \text{eq:psiEstimate} \quad (5.11)$$

where for the last estimate we used (4.16) which is applicable since  $\text{div} w = 0$  on  $\Omega$ . If we combine inequalities (5.10) and (5.11), we get

$$\int_{\Omega} |u|^2 dx \leq C \|u\|_{\partial} \|\nabla w\|_{\partial} + C \|u\|_{\partial}^2. \quad \text{eq:u2estimate2} \quad (5.12)$$

We are left with estimating the first term in (5.12). In fact it will suffice to show the following inequality

$$\int_{\partial\Omega} |\nabla w|^2 d\sigma \leq C \int_{\Omega} |u|^2 dx + C \int_{\partial\Omega} |u|^2 d\sigma \quad \text{eq:w2estimate} \quad (5.13)$$

since by the weighted Young inequality this would make the estimate

$$C \|u\|_{\partial} \|\nabla w\|_{\partial} \leq \frac{1}{2} \int_{\Omega} |u|^2 dx + C \int_{\partial\Omega} |u|^2 d\sigma$$

available which after rearranging terms yields (5.7).

To this end, we will first prove the Rellich type identity

$$\begin{aligned} \int_{\partial\Omega} h_k n_k |\nabla w|^2 d\sigma &= \int_{\Omega} \text{div}(h) |\nabla w|^2 dx + 2 \text{Re} \int_{\Omega} h_j \frac{\partial \psi}{\partial x_j} \frac{\bar{w}_j}{\partial x_k} dx \\ &\quad + 2 \text{Re} \int_{\Omega} h_k \lambda w_j \frac{\partial \bar{w}_j}{\partial x_k} + 2 \text{Re} \int_{\Omega} h_k \bar{u}_j \frac{\partial \psi}{\partial x_k} dx. \end{aligned} \quad \text{eq:rellichIdentity3} \quad (5.14)$$

Note that since all involved quantities are smooth up to the boundary, integration by parts is allowed and the proof the stated Rellich identity boils down to a formal calculation. Let

$h \in C_0^1(\mathbb{R}^d, \mathbb{R}^d)$  with  $h_k n_k \geq c > 0$  on  $\partial\Omega$ , see Verchota [?]. Then the divergence theorem gives

$$\int_{\partial\Omega} h_k n_k |\nabla w|^2 d\sigma = \int_{\Omega} \operatorname{div}(h |\nabla w|^2) dx = \int_{\Omega} \operatorname{div}(h) |\nabla w|^2 dx + \int_{\Omega} h_k \frac{\partial}{\partial x_k} (|\nabla w|^2) dx$$

and we can rewrite the second summand as

$$\begin{aligned} \int_{\Omega} h_k \frac{\partial}{\partial x_k} (|\nabla w|^2) dx &= \int_{\Omega} h_k \frac{\partial}{\partial x_k} \left( \frac{\partial w_j}{\partial x_i} \frac{\partial \bar{w}_j}{\partial x_i} \right) dx \\ &= 2 \operatorname{Re} \int_{\Omega} h_k \frac{\partial^2 w_j}{\partial x_k \partial x_i} \frac{\partial \bar{w}_j}{\partial x_i} dx \\ &= -2 \operatorname{Re} \int_{\Omega} h_k \frac{\partial}{\partial x_k} \left( \frac{\partial^2}{\partial x_i^2} w_j \right) \bar{w}_j dx + \int_{\partial\Omega} h_k \left( \frac{\partial^2}{\partial x_k \partial x_i} w_j \right) \bar{w}_j dx \\ &= 2 \operatorname{Re} \int_{\Omega} h_k (\Delta w_j) \frac{\partial \bar{w}_j}{\partial x_k} dx + 0 \\ &= 2 \operatorname{Re} \int_{\Omega} h_k \left( \frac{\partial \psi}{\partial x_j} + \lambda w_j - \bar{u}_j \right) \frac{\partial \bar{w}_j}{\partial x_k} dx, \end{aligned}$$

where in addition to partial integration we used (5.8) and the fact that  $w = 0$  on  $\partial\Omega$ . Now we can apply the triangle inequality to the Rellich type identity (5.14) to obtain

$$\begin{aligned} \int_{\partial\Omega} |\nabla w|^2 d\sigma &\leq C \left\{ \int_{\Omega} |\nabla w|^2 dx + \int_{\Omega} |\nabla w| |\psi| dx \right. \\ &\quad \left. + |\lambda| \int_{\Omega} |\nabla w| |w| dx + \int_{\Omega} |\nabla w| |u| dx \right\}. \end{aligned} \quad \text{eq:rellichInequality3} \quad (5.15)$$

The next step consists in deriving estimates which are compatible with the right hand side of (5.8). Testing (5.8) with  $\bar{w}$ , integration by parts gives us as in the proof of Lemma 4.4

$$\int_{\Omega} |\nabla w|^2 dx + |\lambda| \int_{\Omega} |w|^2 dx \leq C \int_{\Omega} |w| |u| dx$$

The next step consists in using the previous inequality and the Poincaré inequality to estimate

$$\begin{aligned} \int_{\Omega} |\nabla w|^2 dx + (1 + |\lambda|) \int_{\Omega} |w|^2 dx &\leq (1 + C) \int_{\Omega} |\nabla w|^2 dx + |\lambda| \int_{\Omega} |w|^2 dx \\ &\leq C \int_{\Omega} |w| |u| dx \\ &\leq C \|w\|_{\partial} \|u\|_{\partial}, \end{aligned}$$

where for the last step we used the Cauchy-Schwartz inequality. The weighted Young inequality allows us to further estimate

$$\begin{aligned} &\leq \frac{C}{4\varepsilon} \int_{\Omega} |u|^2 dx + C\varepsilon \int_{\Omega} |w|^2 dx \\ &= \frac{\tilde{C}}{1 + |\lambda|} \int_{\Omega} |u|^2 dx + \frac{1}{2} (1 + |\lambda|) \int_{\Omega} |w|^2 dx \end{aligned}$$



if we set  $\varepsilon = \frac{(1+|\lambda|)}{2C}$ . Rearranging terms, we can produce our next estimate

$$\int_{\Omega} |\nabla w|^2 dx + (1 + |\lambda|) \int_{\Omega} |w|^2 dx \leq \frac{C}{1 + |\lambda|} \int_{\Omega} |u|^2 dx. \quad \text{eq:w2lambdaEstimate (5.16)}$$

Now it's time to harvest: Using estimate (5) together with (5.16) gives

$$\begin{aligned} & \int_{\partial\Omega} |\nabla w|^2 d\sigma \\ & \leq C \left\{ \int_{\Omega} |\nabla w|^2 dx + \int_{\Omega} |\nabla w| |\psi| dx + |\lambda| \int_{\Omega} |\nabla w| |w| dx + \int_{\Omega} |\nabla w| |u| dx \right\}. \end{aligned}$$

Using the weighted Young inequality, we see that we can simplify the right hand to

$$C_{\varepsilon}(1 + |\lambda|) \int_{\Omega} |\nabla w|^2 dx + C|\lambda| \int_{\Omega} |w|^2 dx + C \int_{\Omega} |u|^2 dx + \varepsilon \int_{\Omega} |\psi|^2 dx,$$

which with (5.16) can be bounded in this way

$$\leq C_{\varepsilon} \int_{\Omega} |u|^2 dx + \varepsilon \int_{\Omega} |\psi|^2 dx.$$

Using the estimate  $\|\psi\|_{L^2(\partial\Omega)} \leq C\|\psi\|_{\partial}$  and inequality (5.11) gives

$$\varepsilon \int_{\Omega} |\psi|^2 dx \leq \varepsilon C \int_{\partial\Omega} |\nabla w|^2 d\sigma + C_{\varepsilon} \int_{\partial\Omega} |u|^2 d\sigma.$$

Choosing  $\varepsilon = \frac{1}{2C}$  and rearranging gives the desired estimate (5.13). This concludes our proof.  $\square$



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