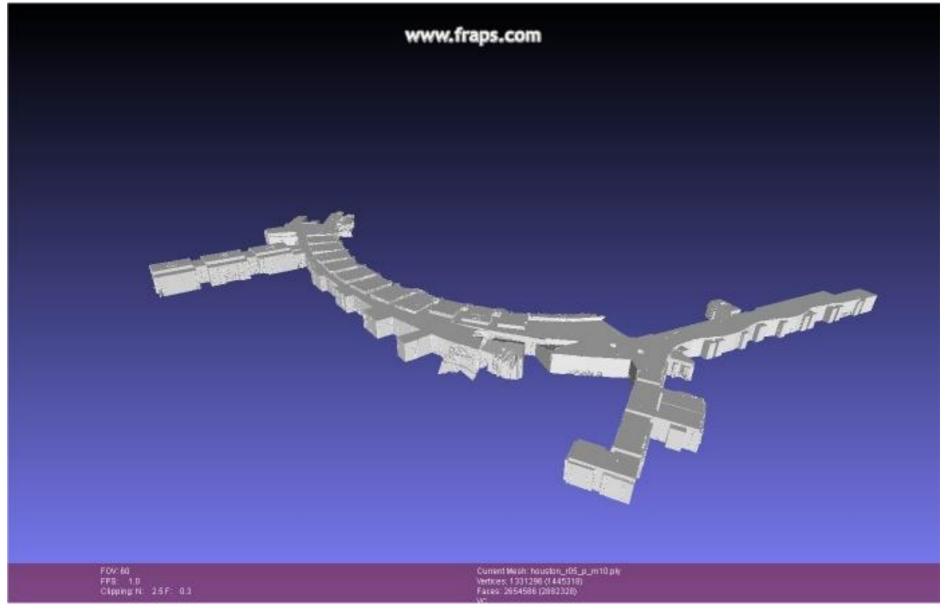
# Watertight Planar Surface Meshing of Indoor Point-Clouds with Voxel Carving

3DV - June 29, 2013

Eric Turner Avideh Zakhor

### **Surface Meshing of Buildings**



#### **Indoor Modeling**

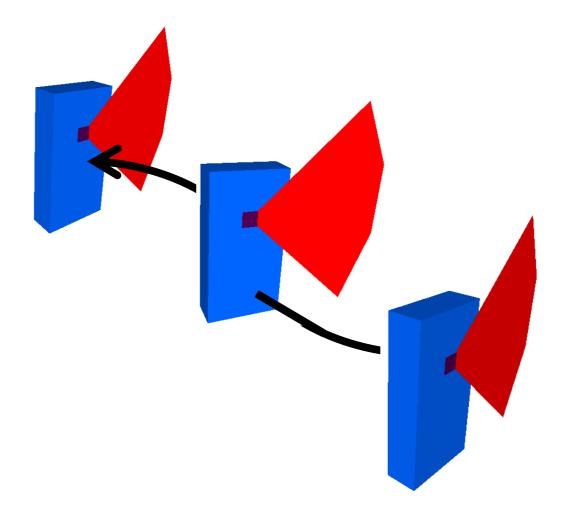
Acquisition System

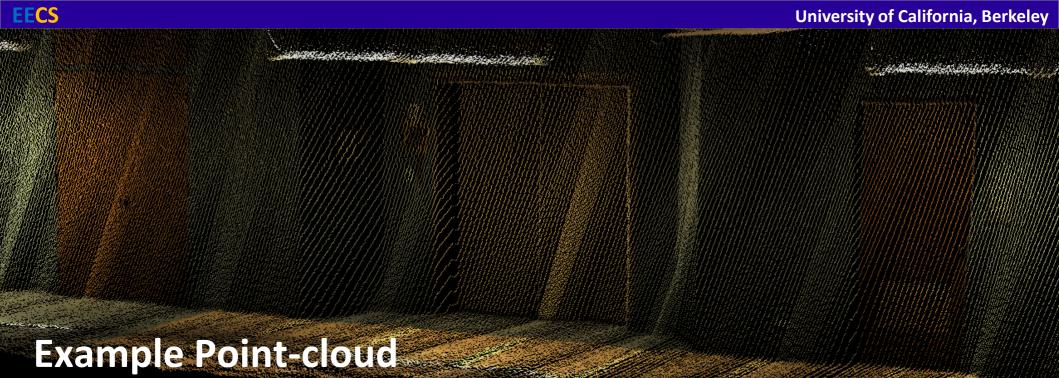




## **Indoor Modeling**

Point-cloud Generation







#### **Motivation**

- Why is meshing useful?
- Why do we want it to be planar?
- Why do we want it to be watertight?

#### **Motivation**

Why is meshing useful?



# **Example Point-cloud**

- 45 Million Pts
- 3.5 GB on disk

#### **Motivation**

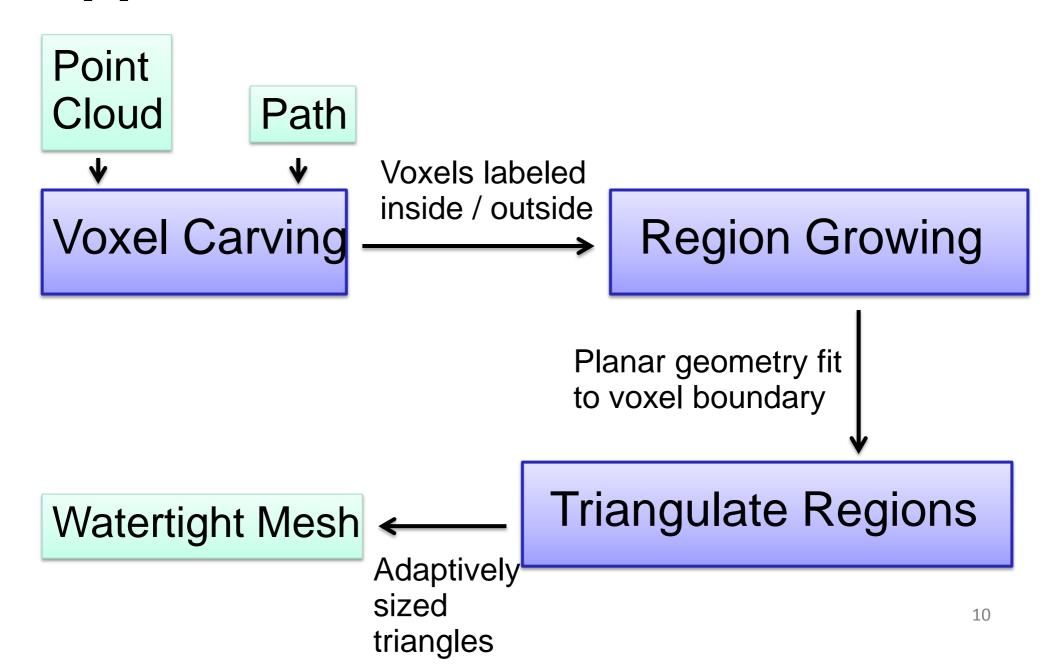
Why is meshing useful?

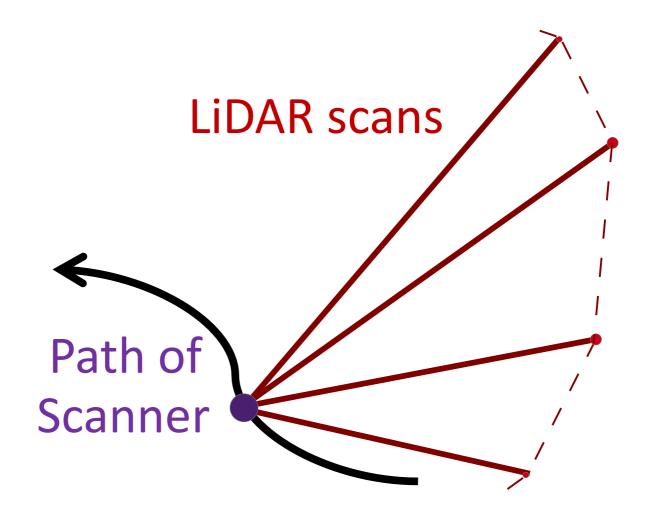


#### **Example Mesh**

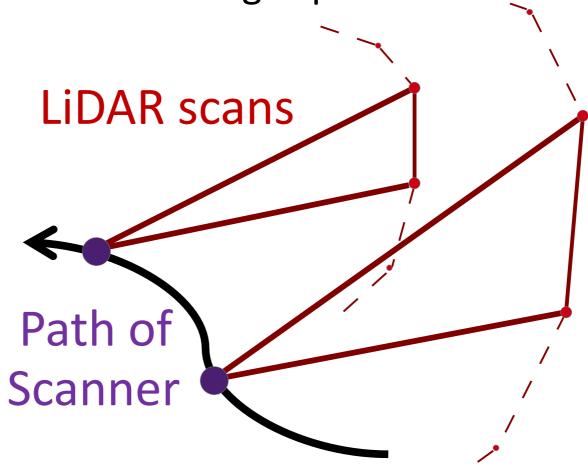
- 985,000 Tris
- 20 MB on disk

## **Approach**

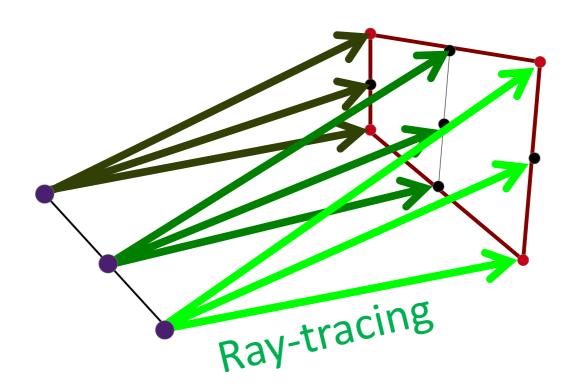




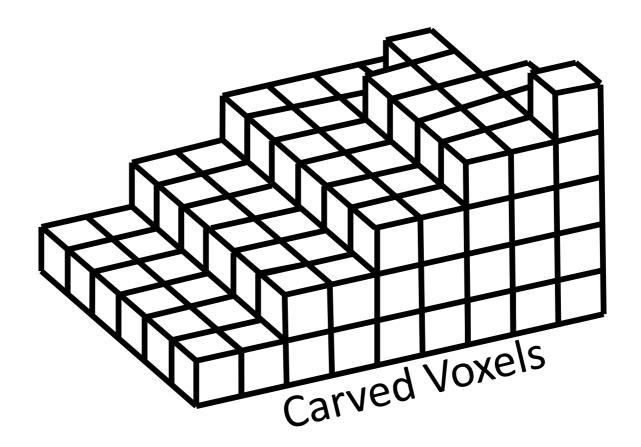
Trace path of laser through space



Interpolate neighboring scans to define volume

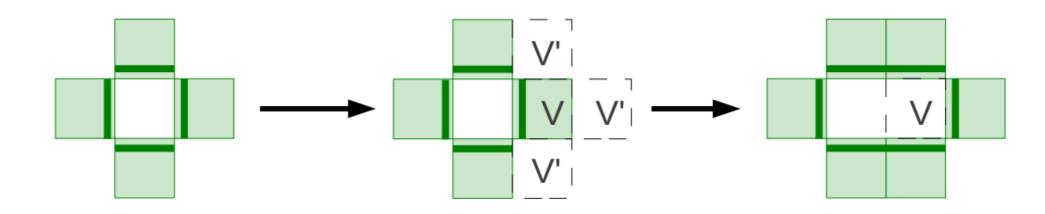


Define volume with voxels

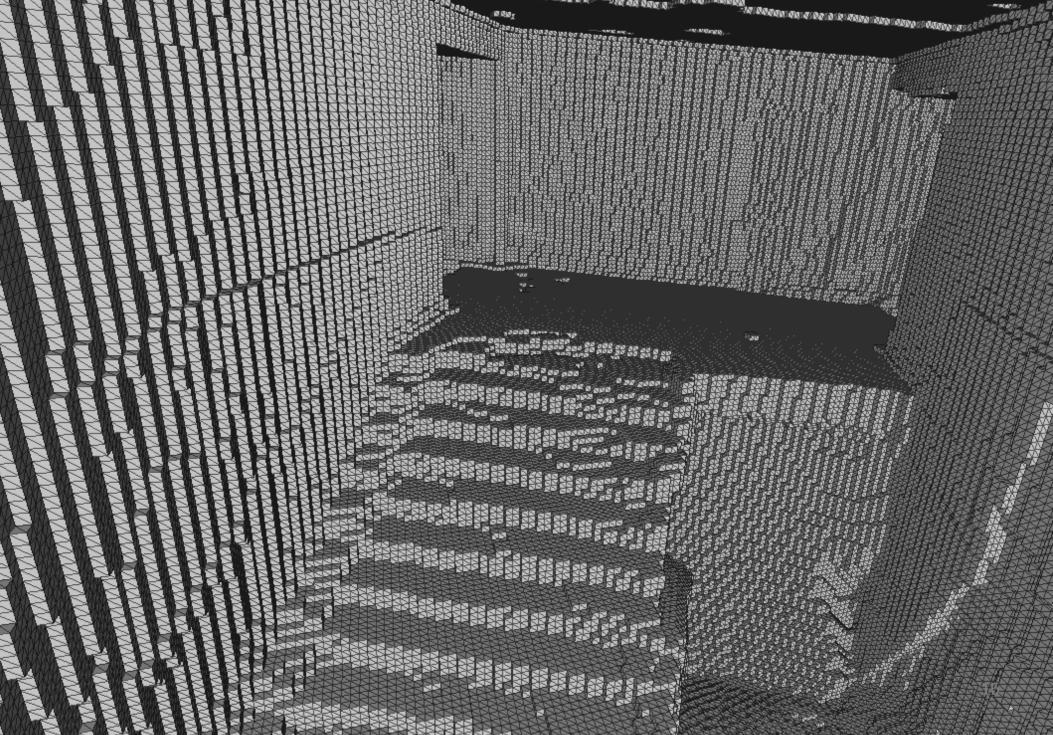


#### **Voxel Data Structure**

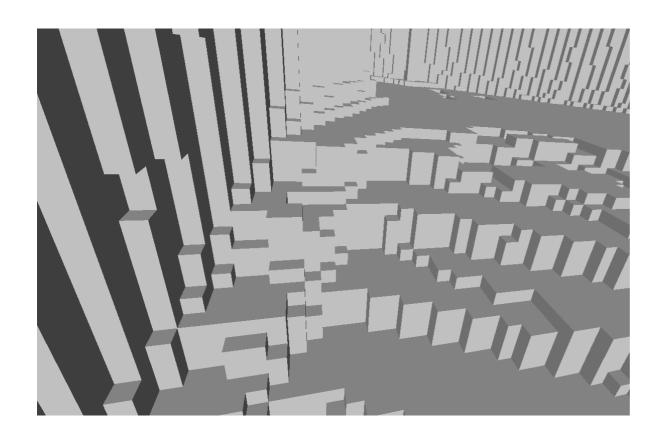
Only boundary voxels explicitly stored



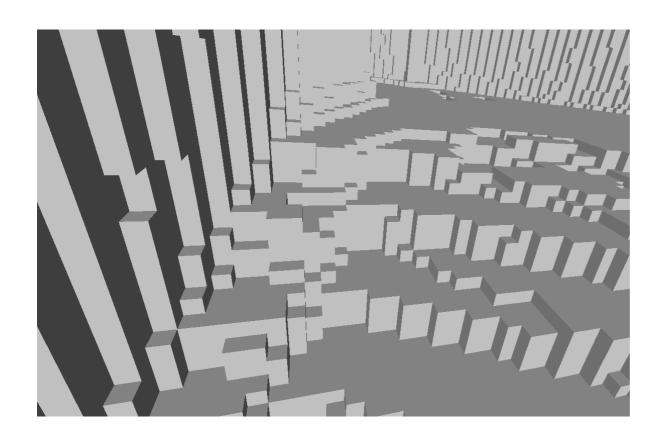
Carving preserves watertightness of volume



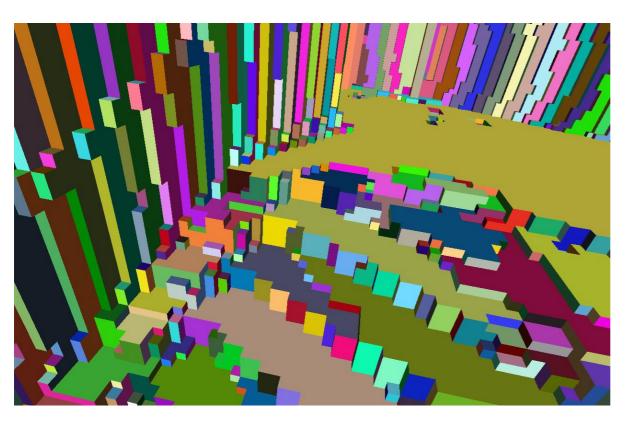
■ Goal: remove discretization artifacts on surface



- Goal: remove discretization artifacts on surface
- Combine voxel faces into planar regions

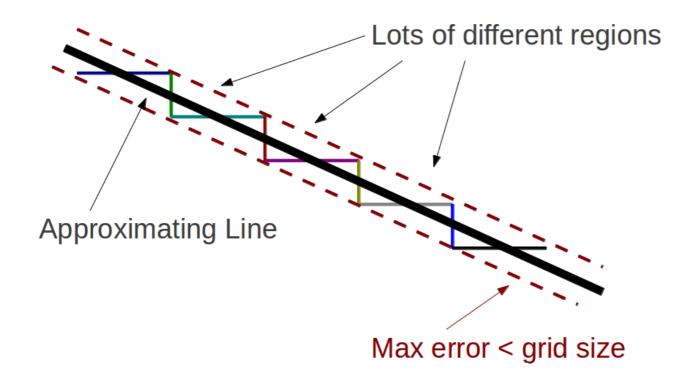


- Goal: remove discretization artifacts on surface
- Combine voxel faces into planar regions

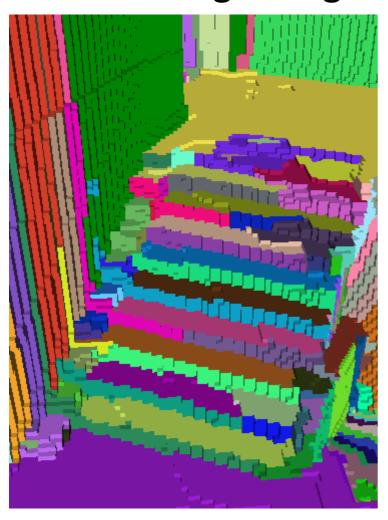


Initialize via flood-fill

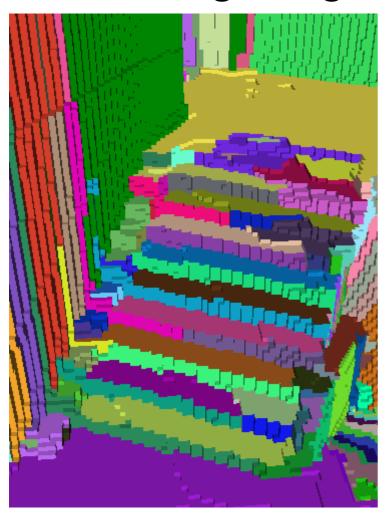
Merge regions by computing best-fit plane



Final merged regions

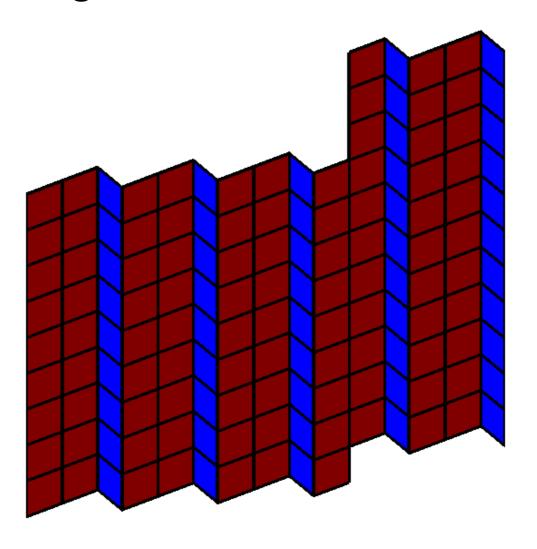


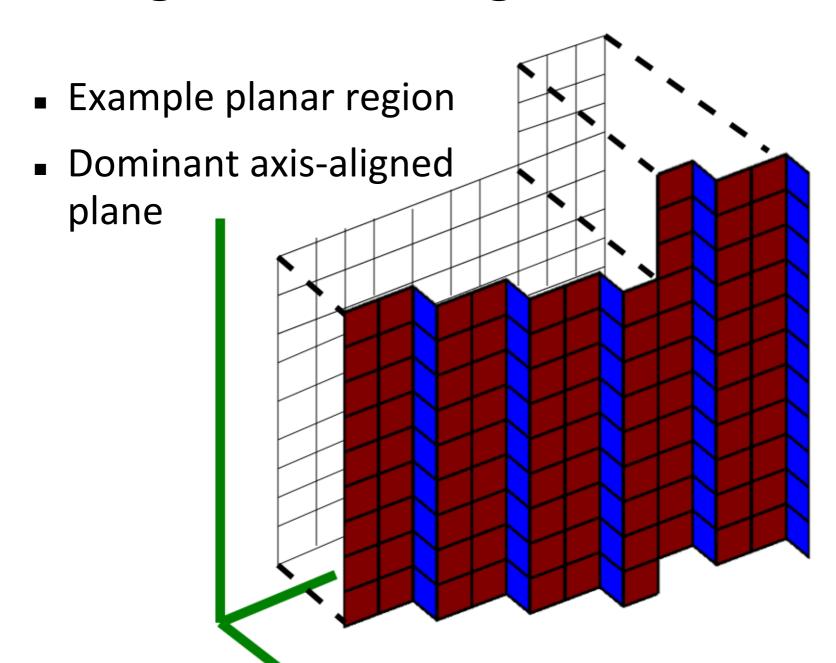
Final merged regions



- Identified locations of planar regions
- Now need to mesh

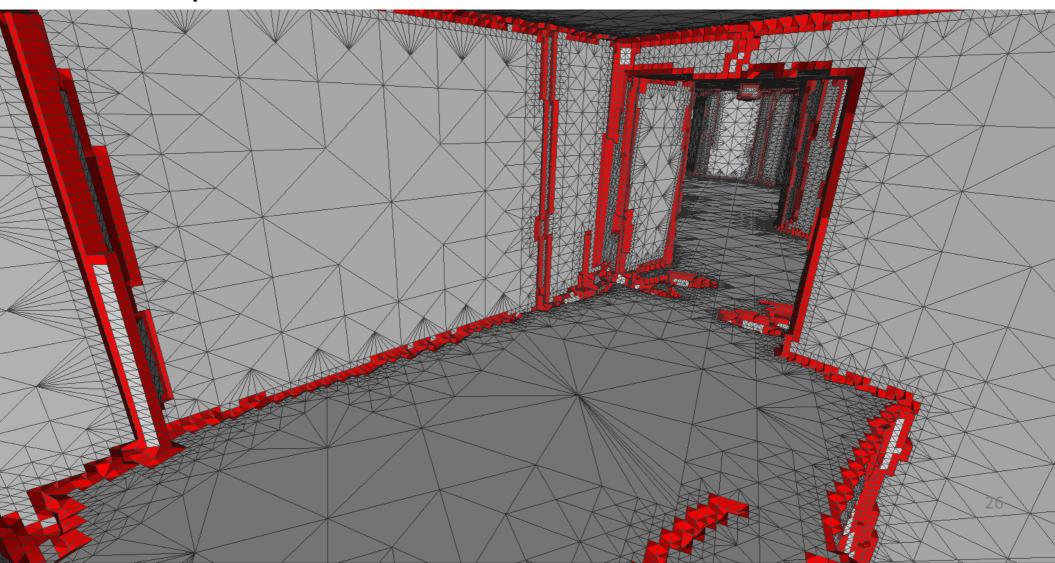
Example planar region



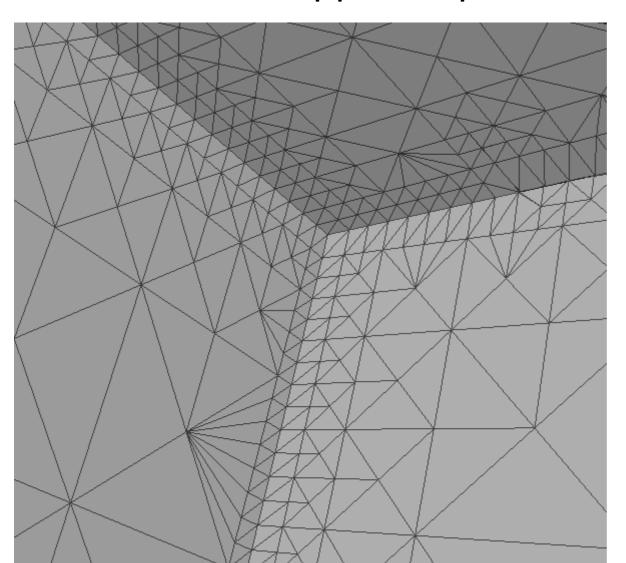


 Triangulate 2D projection × × × × × 25 ×

Example

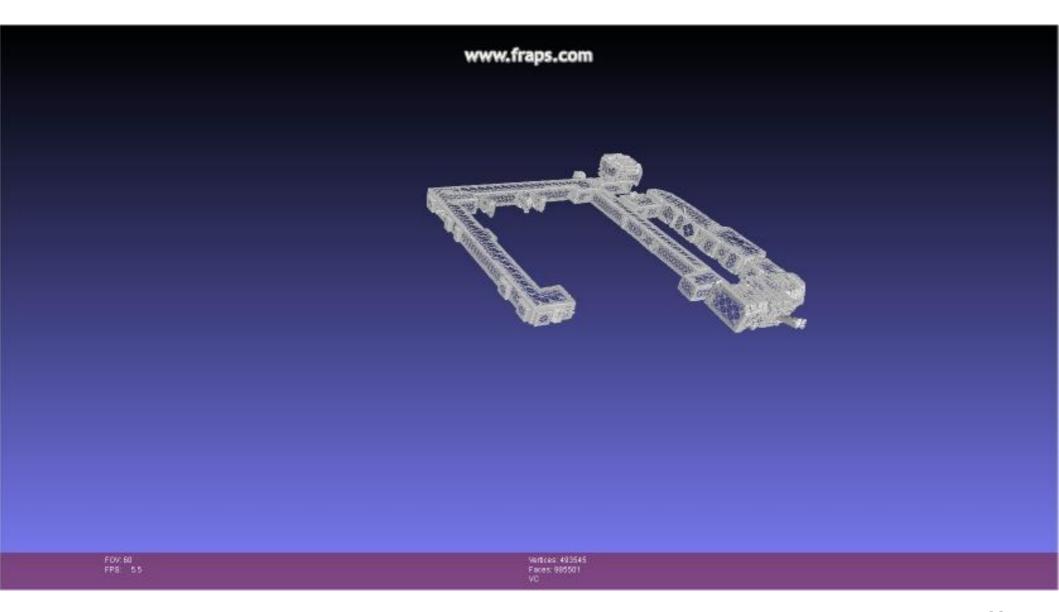


Boundaries snapped to plane intersections

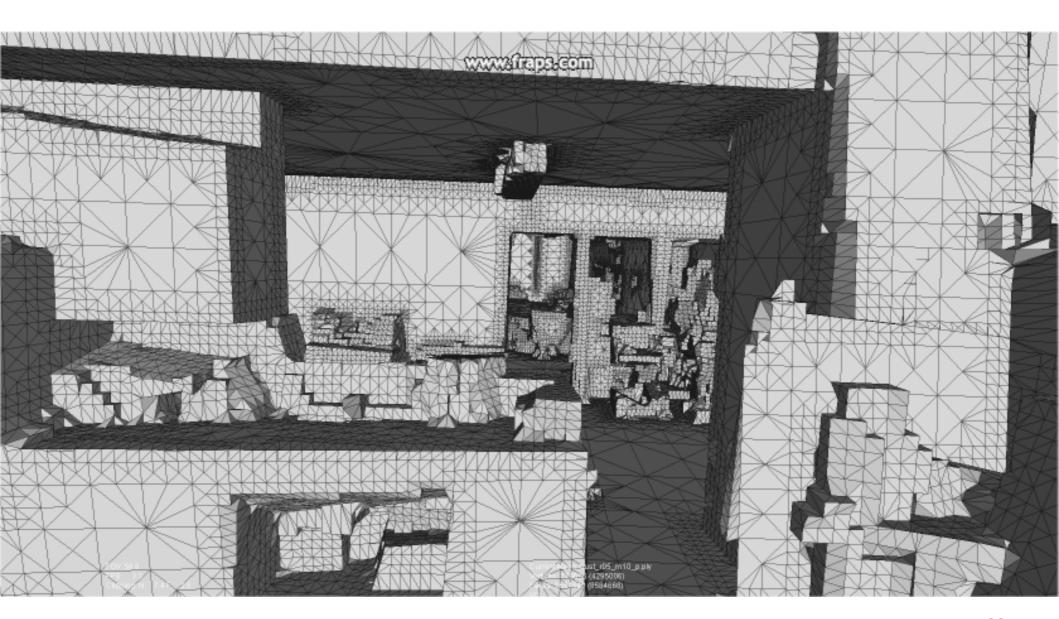


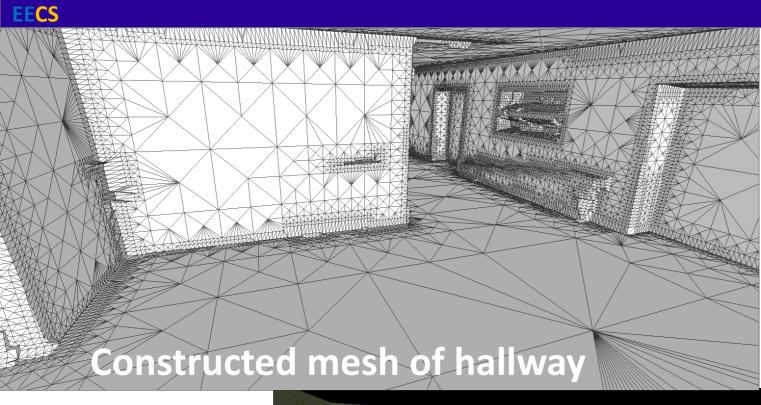


#### **Results**



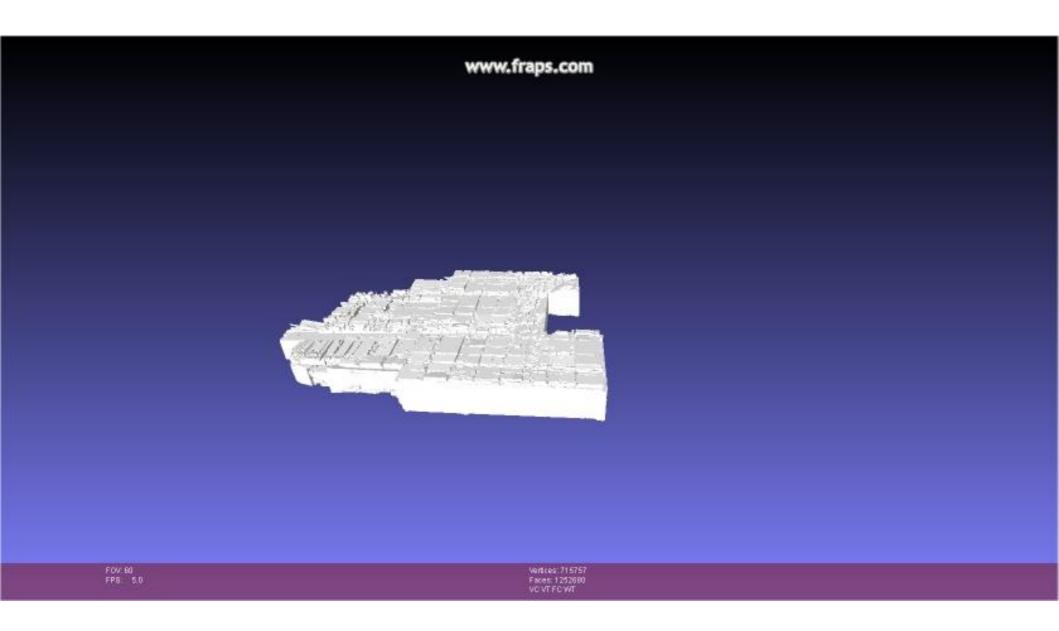
#### Results

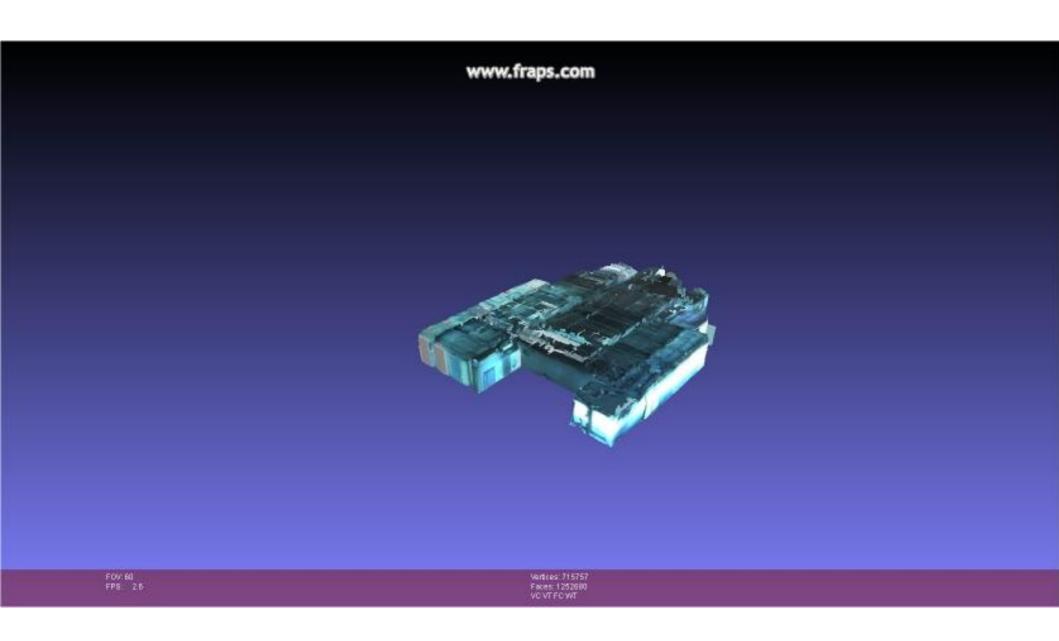








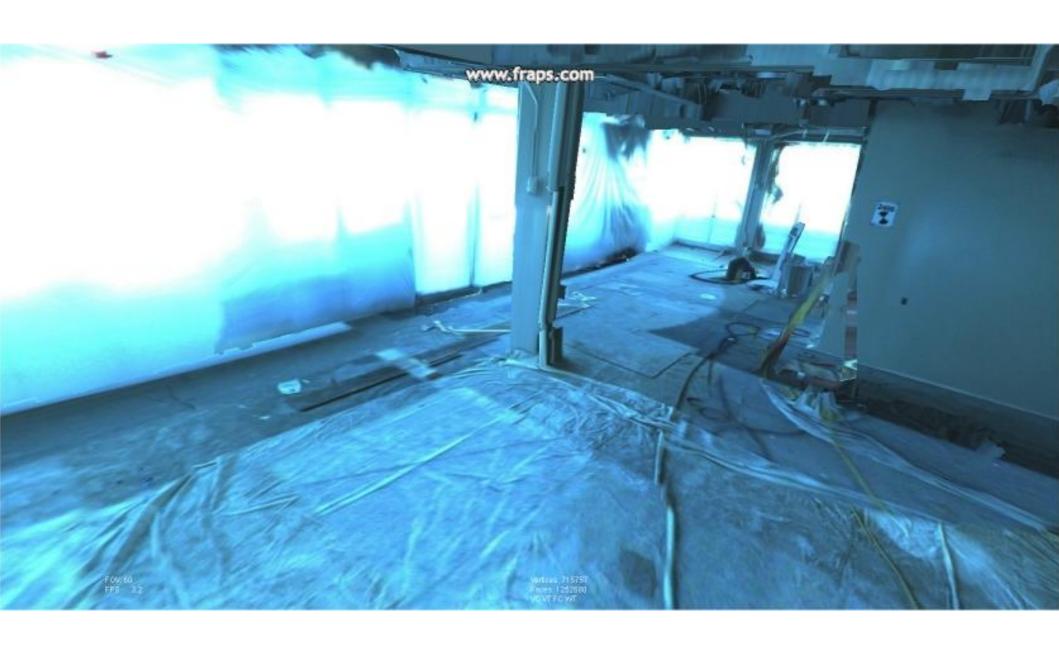


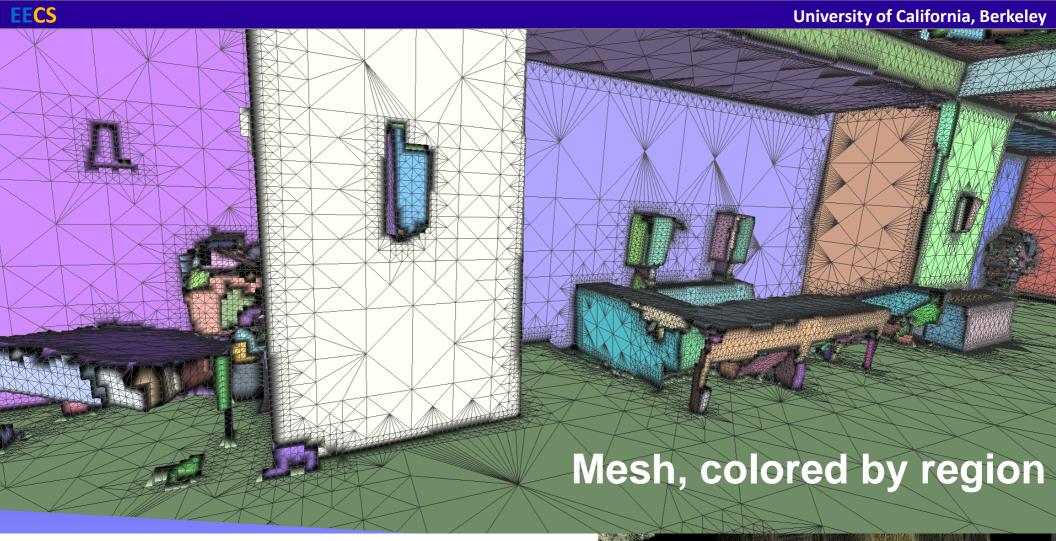












# Close up of hotel hallway

Viewing triangulation and planar regions



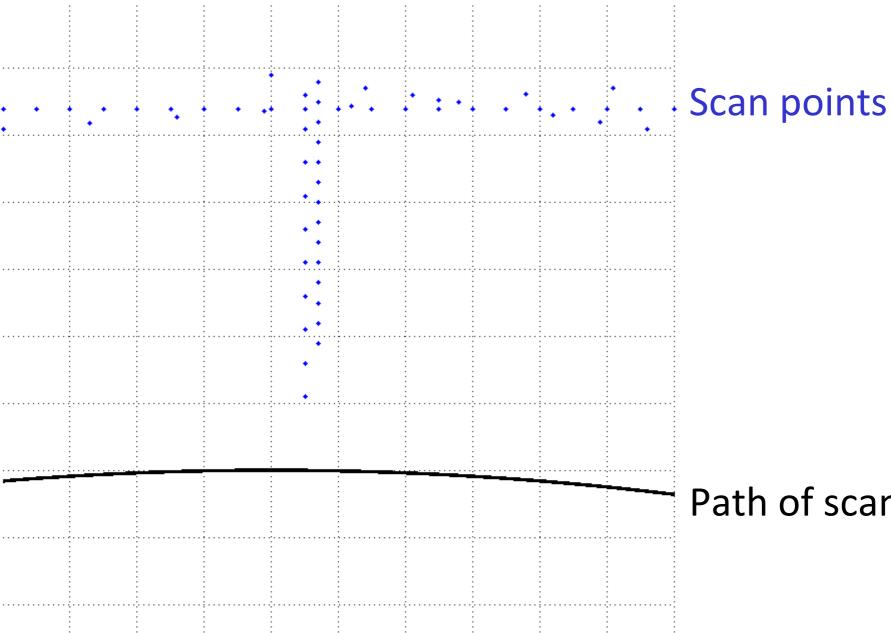
#### **Large Retail Shopping Center**



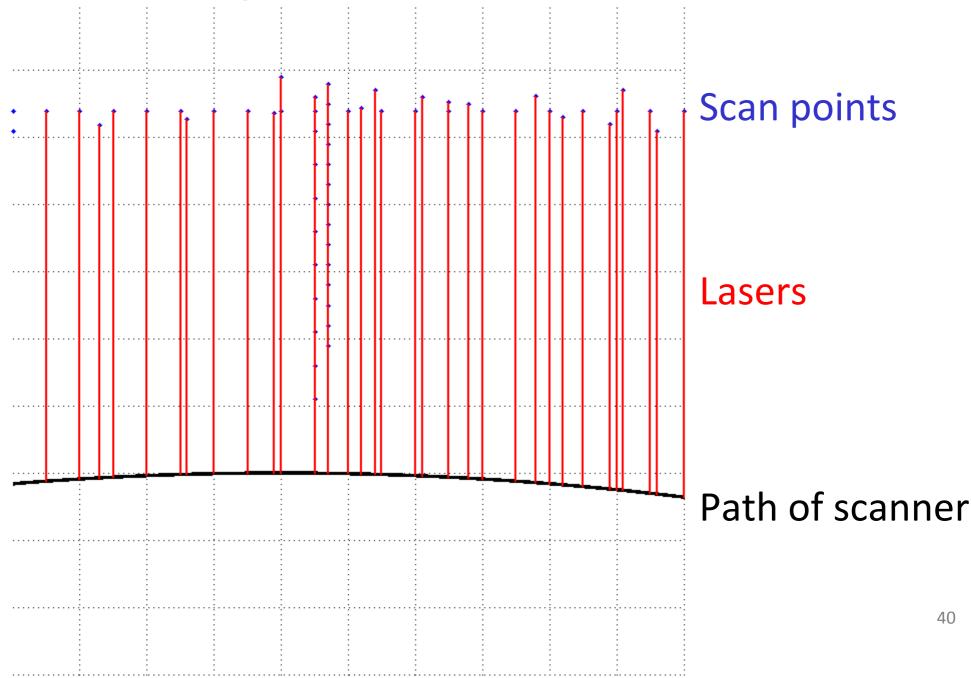
112 m x 78 m

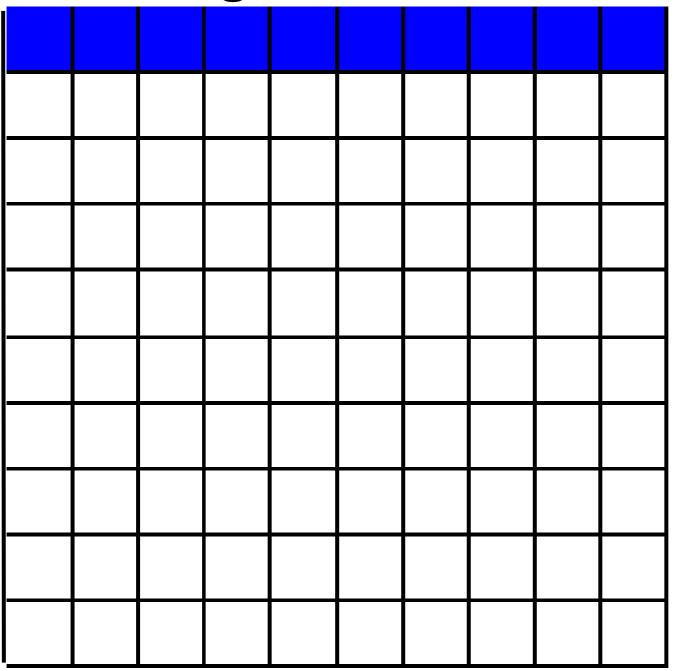
2.7 million triangles from 220 million points

# Supplemental



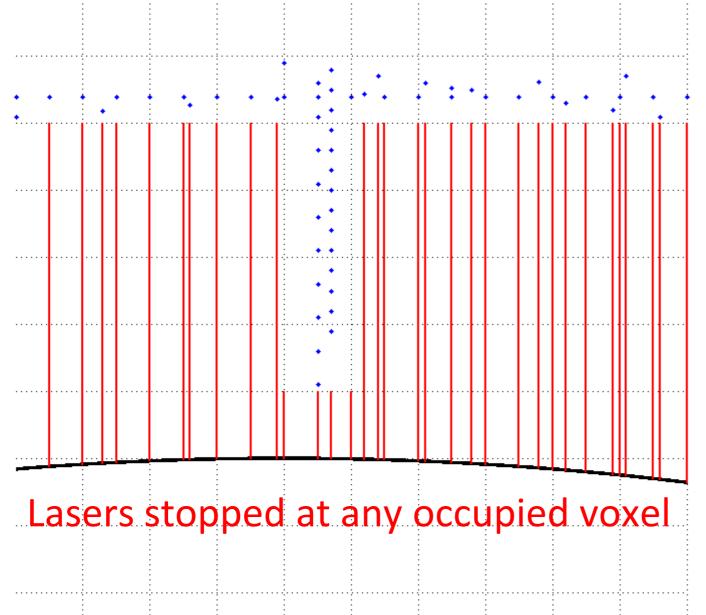
Path of scanner





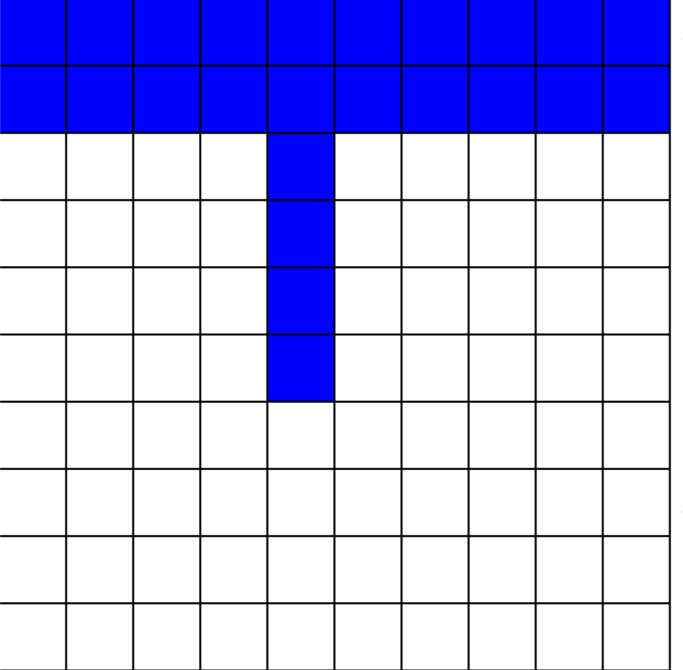
**Exterior Space** 

Interior Space



Scan points

Path of scanner



**Exterior Space** 

Interior Space

