			Original	Improved	Original	Improved
		Desired	Controller	Controller	Controller	Tuned
			Simulated	Simulated	Quanser	Quanser
Objectives	Tr(s)	4	1.65	1.5	2.57	1.35
	Ts (4%) (s)	5	1.65	1.5	2.57	1.35
	OS(%)	10	1.868	0.29	2.284	1.16
Ö	Ess (%)	0	0	0	0	0