# Lisul Elvitigala

U.S. Citizen | (516) 532-4675 | elvitigalalis@gmail.com | linkedin.com/in/lisul | github.com/elvitigalalis

# **EDUCATION**

# **Stony Brook University**

Bachelor of Science, Computer Science

Expected Graduation: May 2027

GPA: 3.95/4.00

 Relevant Coursework: Data Structures & Algorithms, Discrete Mathematics, Graph Theory, Linear Algebra, Computational Geometry, Functional Programming, Object Oriented Programming, Probability & Statistics

### EXPERIENCE

**Clever Devices** 

June 2025 - Aug 2025

Software Engineer Intern

- Enabled real-time depot detection for 200+ OTA buses by developing a zero-downtime C# geofencing system.
- Reduced data retrieval latency 85% by integrating lower-load vehicle and attribute SQL script to WCF service.
- Built Python fuzzing tool that generated 250+ synthetic POST payloads across 10 threads, uncovering 3 unhandled exceptions in a fault-tolerant vehicle REST API; containerized with Docker and visualized in Splunk.

Princeton Al Lab Dec 2024 – May 2025

Undergraduate Researcher

- Authored paper on automated prompt-to-video pipeline, producing 30s video outputs for CUbits using Python.
- Designed Q&A platform for 30+ students with permissions using React, Tailwind, Node, MongoDB, MySQL.
- Constructed user validation for discussion forum using React, Firestore database integration via Firebase API.

Cloud Data Pro June 2024 – Aug 2024

Software Engineer Intern

- Built version manager for internal tools by creating web application using CRUD framework in ASP.NET Core.
- Sped up ResX file translation from English to Portuguese by 300% by developing automation script in Python.
- Restored zero-downtime by developing SQL hotfix to patch broken stored procedure, deploying to live system.
- Integrated pipeline for pulling and deploying Docker images from cloud artifactory using JWT auth, Powershell.

## PROJECTS

## **Maze Solver Robot** $\mid C++, C, CMake, Python, Raspberry Pi$

- Engineered a Raspberry Pi to autonomously navigate a 16x16 unexplored maze using motors and sensor I/O.
- Integrated BFS and Dijkstra algorithm maze logic by leveraging C++ and C, simulating 250% speed increase.
- Developed projector-built maze tests in Python, allowing 500+ runs over 20+ mazes; synced with simulator.

#### **Neural Detector Robot** | Java, Python, Pandas, PyTorch

- Used Python (PyTorch, Pandas) to build a <u>CNN</u> on 3,500+ Gaussian-smoothed images for classifier/detector.
- Decreased autonomous robot overshoot by over 70% by integrating Coral TPU detector to Java framework.

### **Autonomous ML Robotic Arm** | C++, CUDA, OpenCV, Jetson, Python, PyTorch

- Developed 6-DoF arm control using Python, recording 1,000+ imitation learning demos training ML policies.
- Integrated PyTorch inference with CUDA on Jetson Orin Nano, reducing latency from  $\sim$ 120ms to <50 ms.
- Achieved OpenCV preprocessing and hybrid C++ modules, decreasing actuation delay 20% across 50+ tests.

## SKILLS

**Programming Languages:** Python, C++, C#, C, Java, JavaScript, HTML, CSS **Frameworks and Libraries:** Node, MongoDB, Express, React, Tailwind, Pandas, Flask, ASP.NET Core **Tools:** Git, Jenkins, Jira, AWS, Linux, Docker, Firebase, SQL, NoSQL, Excel, Splunk, REST API **Concepts:** Backend Development, Frontend Development, Fullstack Development, Software Engineering, Robotics Engineering, Machine Learning, Networking, CI/CD, Microservices, DevOps, Automation, Agile