

PyCon ID 2019

Introduction to Change Point Analysis

Elvyna Tunggawan
Data Scientist at Airy



Outline

1

Introduction

What is change point analysis?

2

Methodology

How do we find the “change”?

3

Conclusions

What have we learned?

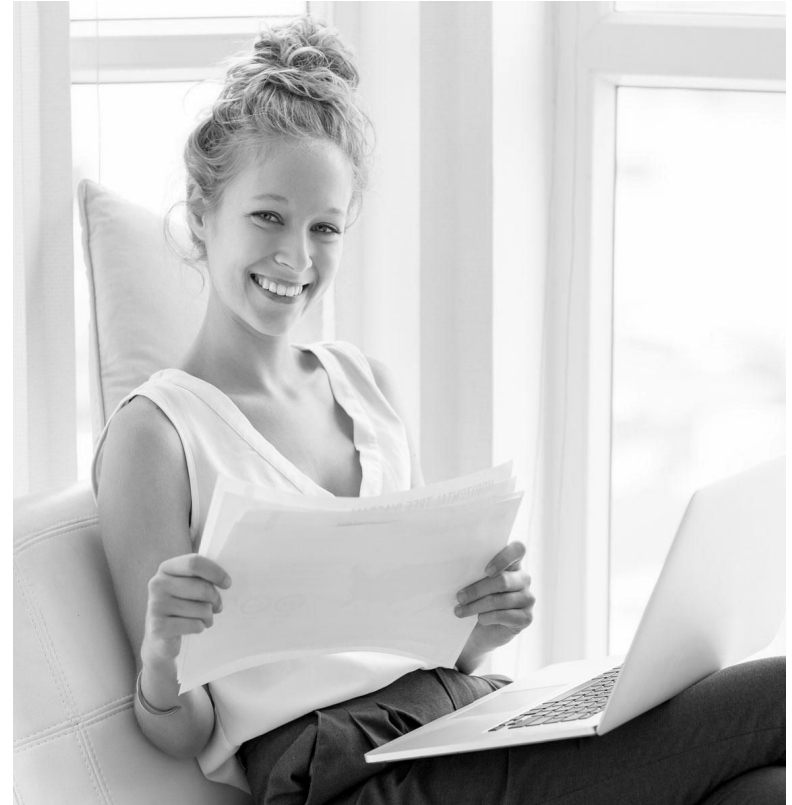


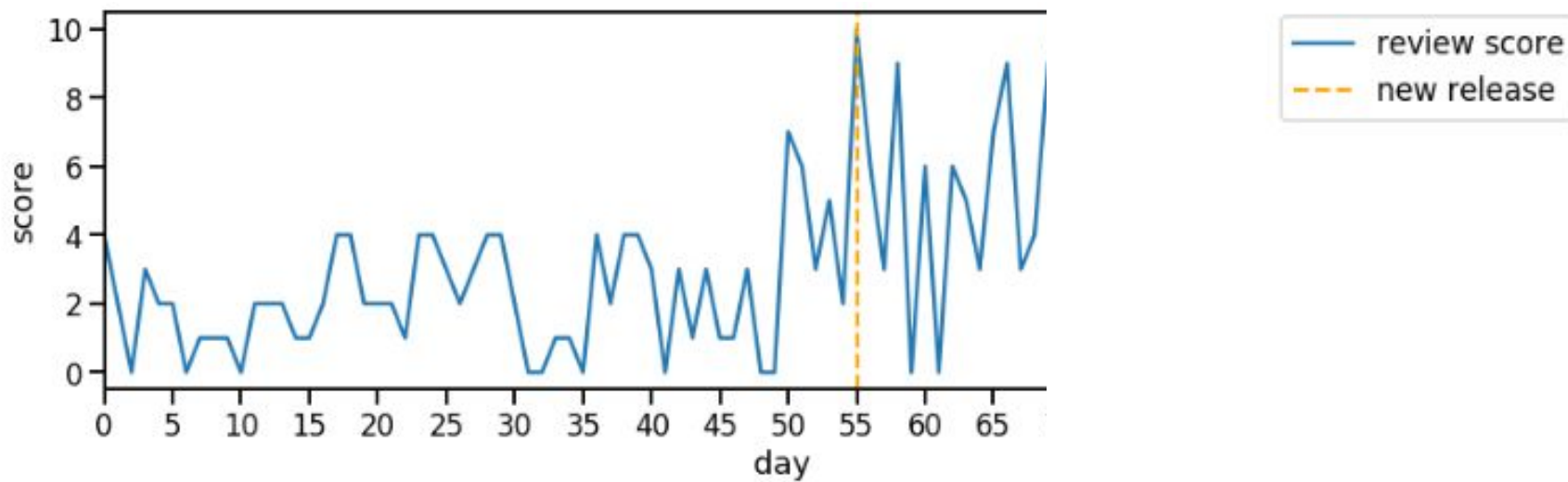
1. Introduction

What is change point analysis?

Whoa!

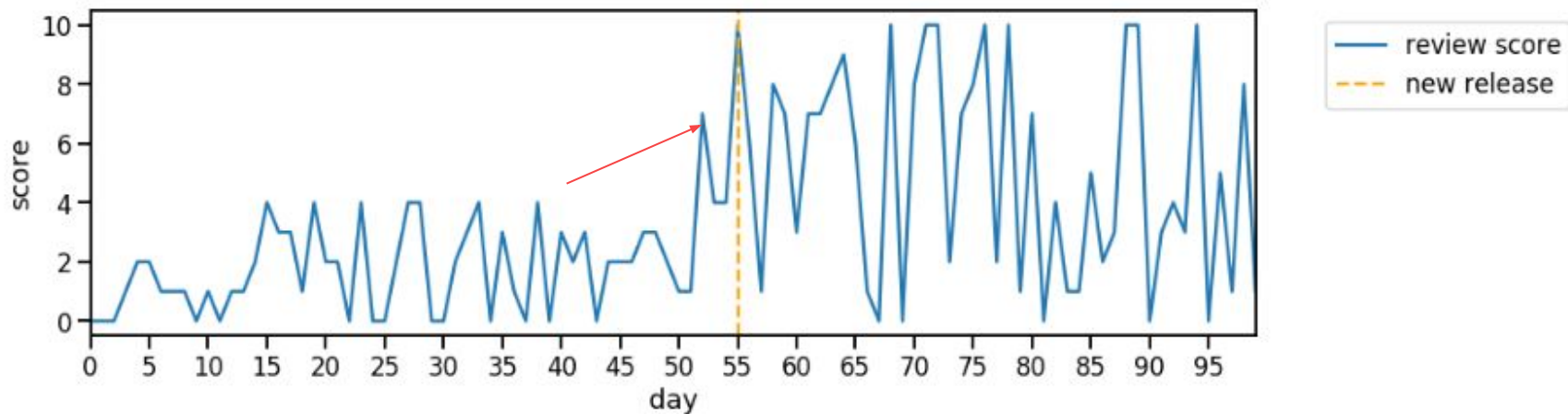
At the end of your peaceful Friday, a product manager came and asked a question...





Our reviews are getting **better**!
It's because of our **new feature** release, *isn't it?*

Is it *really* getting better?



What is change point analysis?

*Given a series of data, change point analysis involves **detecting the number and location of change points**, **locations in the data where some feature**, for example the mean, **changes**.*

There are two types of change point analysis ...

Offline

- all data are **processed in one go**
- main goal: **accurate** detection of changes

Online

- data must be **processed quickly** “on the fly” before new data arrives
- main goal: the **quickest** detection of a change after it has occurred

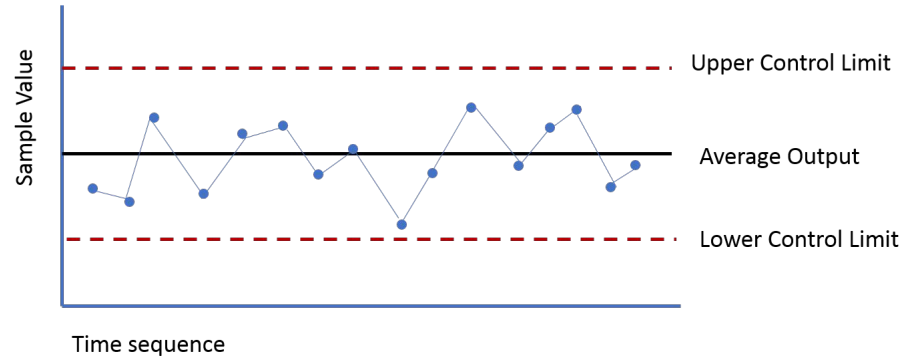


2. Methodology

How do we find the “change”?

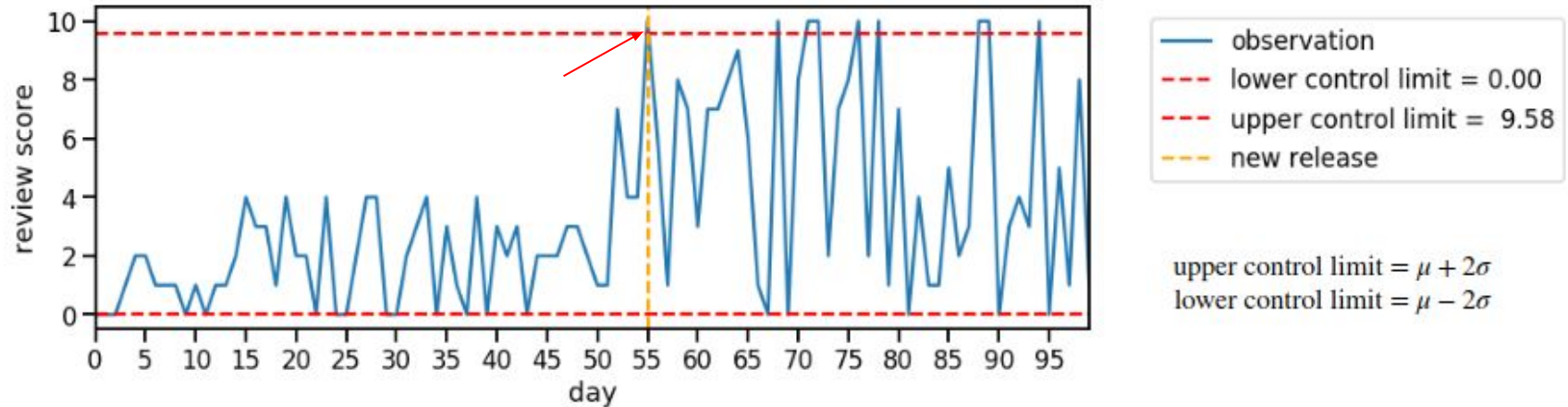
A. Control charts

- Common in **process control**
- Use average, lower & upper **control limit**
- Focus on **point-wise** error rate
- Lower & upper limit is determined based on **standard deviation**



Example of control chart ([source](#))

Sample control chart



The first observation which lies above upper control limit: **day 55**.

B. Change point analysis

- Can detect **subtle changes** frequently missed by control charts
- Can be conducted **once all observations are collected**, to identify **change-wise** error rate
- Based on **mean** or **variance**



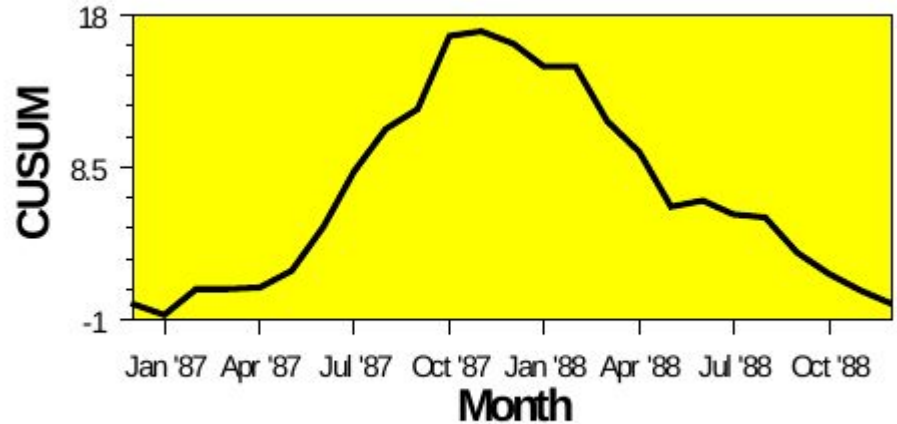
Single change point analysis

Method 1: Cumulative Sum (CUSUM)

Cumulative Sum (CUSUM)

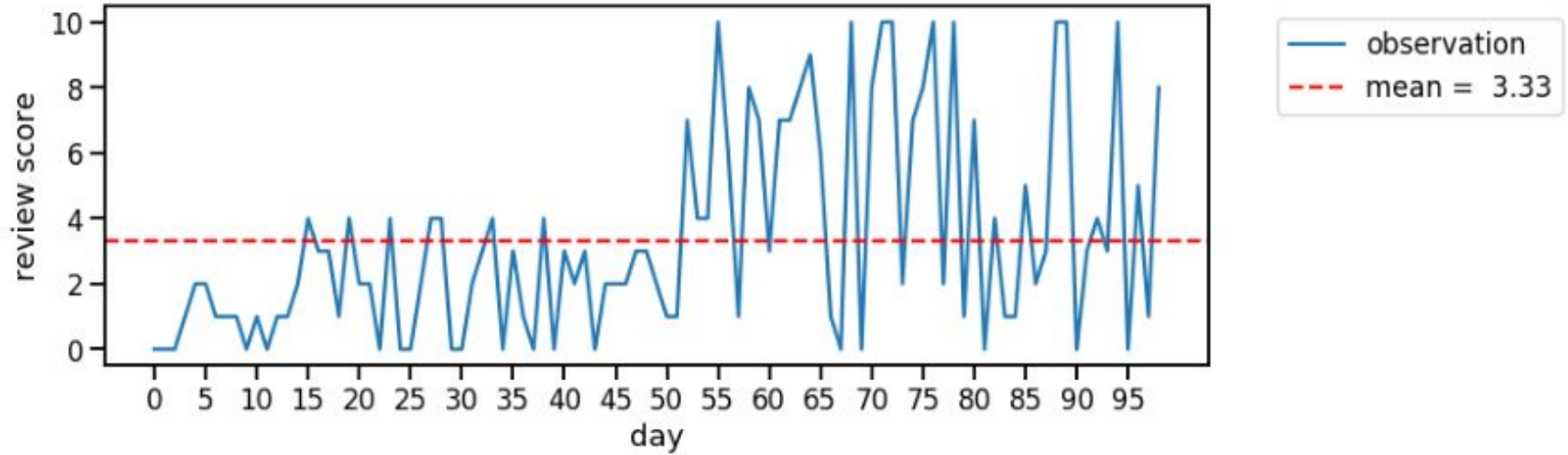
Steps:

1. Calculate **mean** value of **all observations** (\bar{y})
2. Calculate **residuals**: difference between y_i and \bar{y}
3. Set cumulative sum of residuals at 0: **$S_0 = 0$**
4. Calculate **cumulative sum of residuals**: $S_i = S_{i-1} + \varepsilon_i$

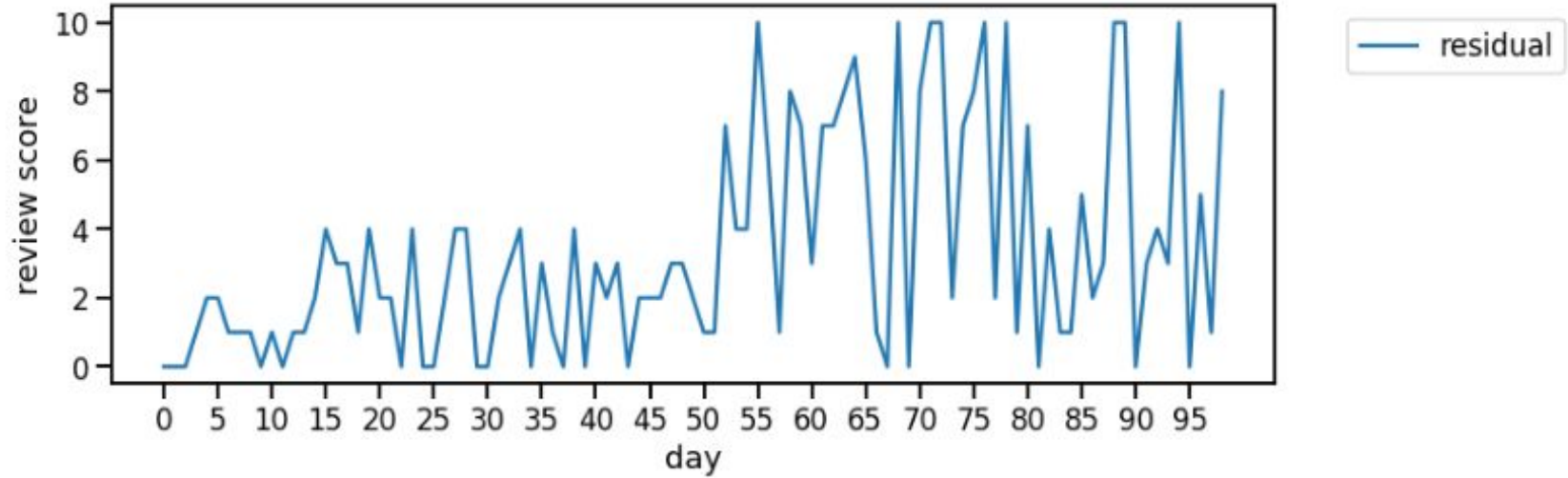


Example of CUSUM plot ([source](#))

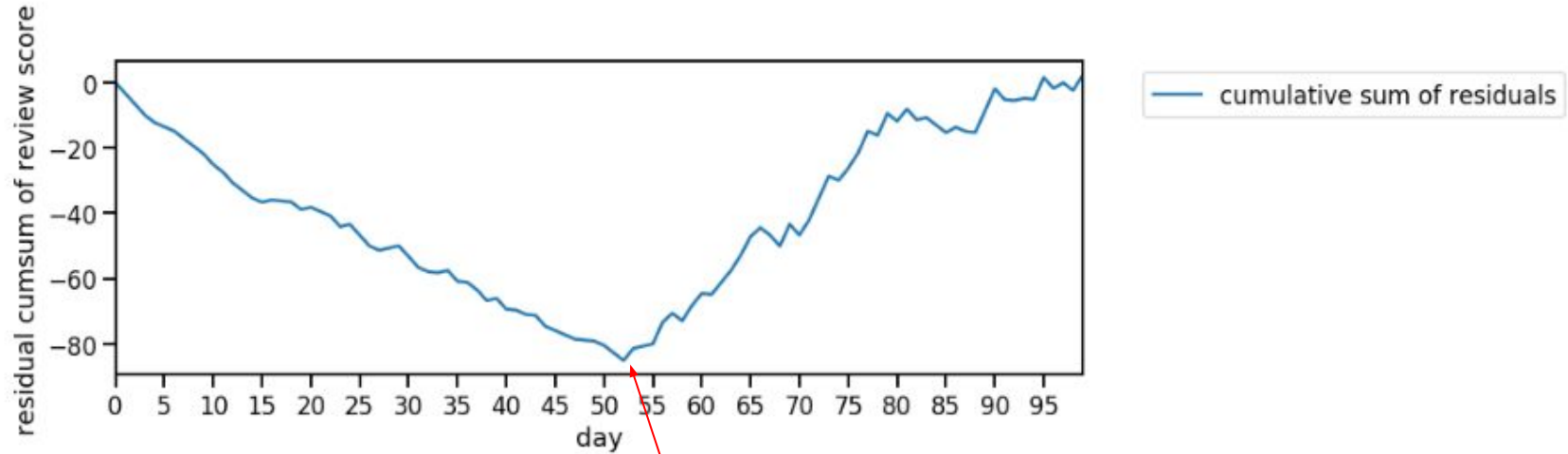
CUSUM: calculate mean



CUSUM: calculate residuals



CUSUM: calculate cumulative sum of residuals



Sudden change is observed at **day 52**.

CUSUM: how **confident** are we that the change exists?

- **Frequentist** method
- **Sampling without replacement**: randomly reorder the observations

1. determine number of iteration N

2. for each iteration:

- take random sample without replacement from the observations $X_1^0, X_2^0, \dots, X_n^0$, where n = number of observations
- calculate the sample's cumulative sum of residuals (S^0): $S_1^0, S_2^0, \dots, S_n^0$
- calculate the difference between maximum and minimum residuals in each bootstrap

$$S_{\text{diff}}^0 = S_{\text{max}}^0 - S_{\text{min}}^0$$

- If $S_{\text{diff}}^0 < S_{\text{diff}}$, it means the result from the sample is consistent with actual observations

$$\text{confidence level(\%)} = 100 * \frac{X}{N}$$

where X represents number of iteration which has $S_{\text{diff}}^0 < S_{\text{diff}}$

CUSUM: how **confident** are we that the change exists?

```
def calculate_residual_difference(df):  
    ## calculate difference between maximum and minimum cumsum residuals  
    resid_max = df['residual_cumsum'].max()  
    resid_min = df['residual_cumsum'].min()  
  
    resid_diff = resid_max - resid_min  
    return resid_diff
```

CUSUM: how **confident** are we that the change exists?

```
N = 1000 ## determine number of iteration
X = 0 ## occurrence when sample residual difference < observed residual difference

for i in np.arange(0,N):
    _sample = pd.DataFrame(
        np.random.choice(df[0], size = df.shape[0], replace = False)
    )
    _sample = calculate_cusum_residuals(_sample)
    _sample_resid_diff = calculate_residual_difference(_sample)

    if _sample_resid_diff < resid_diff:
        X += 1

confidence_level = 100 * X / N
print("Confidence level: {:.2f}%".format(confidence_level))
```

Single change point analysis

Method 2: Structure change model - MSE Estimator

Structure Change Model: MSE Estimator

Steps:

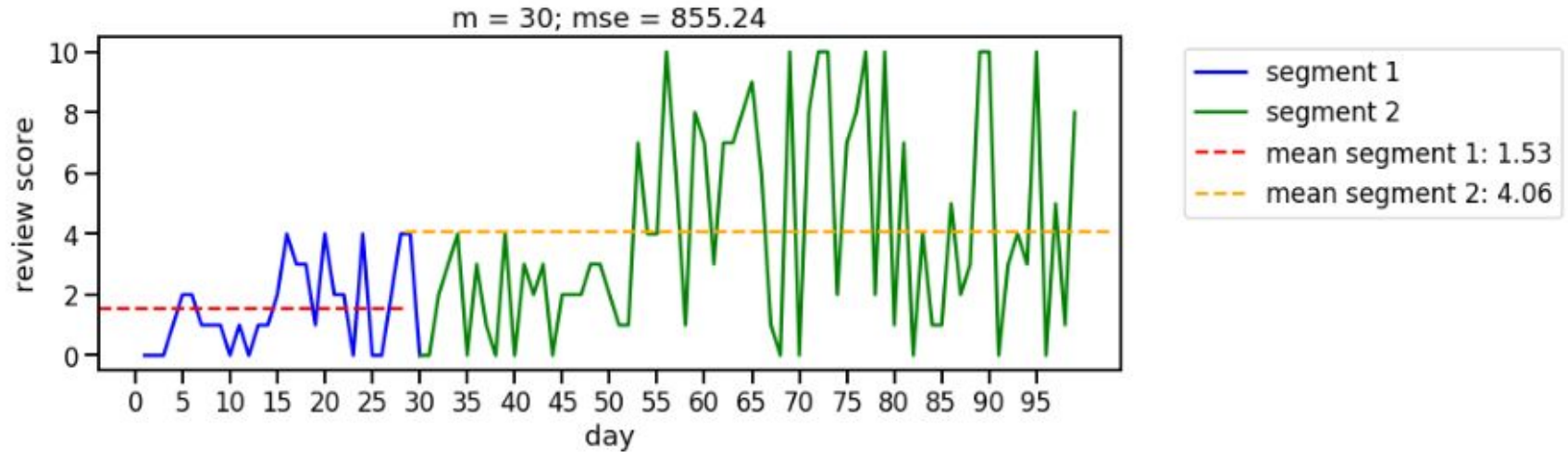
1. Split the data into **2 segments**
 - segment 1 = $\{1, \dots, m\}$
 - segment 2 = $\{m+1, \dots, n\}$
2. Calculate **average** value of each segment: \bar{X}_1 and \bar{X}_2
3. Calculate **mean squared error** of observation in **each segment**

$$MSE(m) = \sum_{i=1}^m (X_i - \bar{X}_1)^2 + \sum_{i=m+1}^n (X_i - \bar{X}_2)^2$$

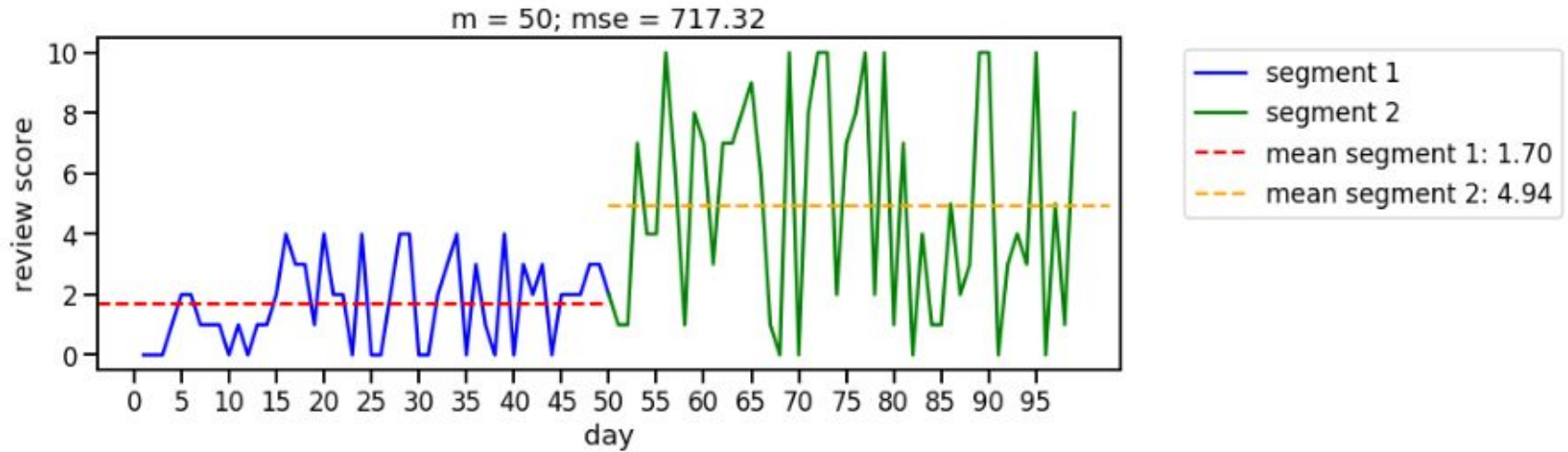
$$\text{where } \bar{X}_1 = \frac{\sum_{i=1}^m X_i}{m} \text{ and } \bar{X}_2 = \frac{\sum_{i=m+1}^n X_i}{n - m}$$

4. Value of **m** which **minimizes the MSE** is the best estimator of the **last point before the change occurred**

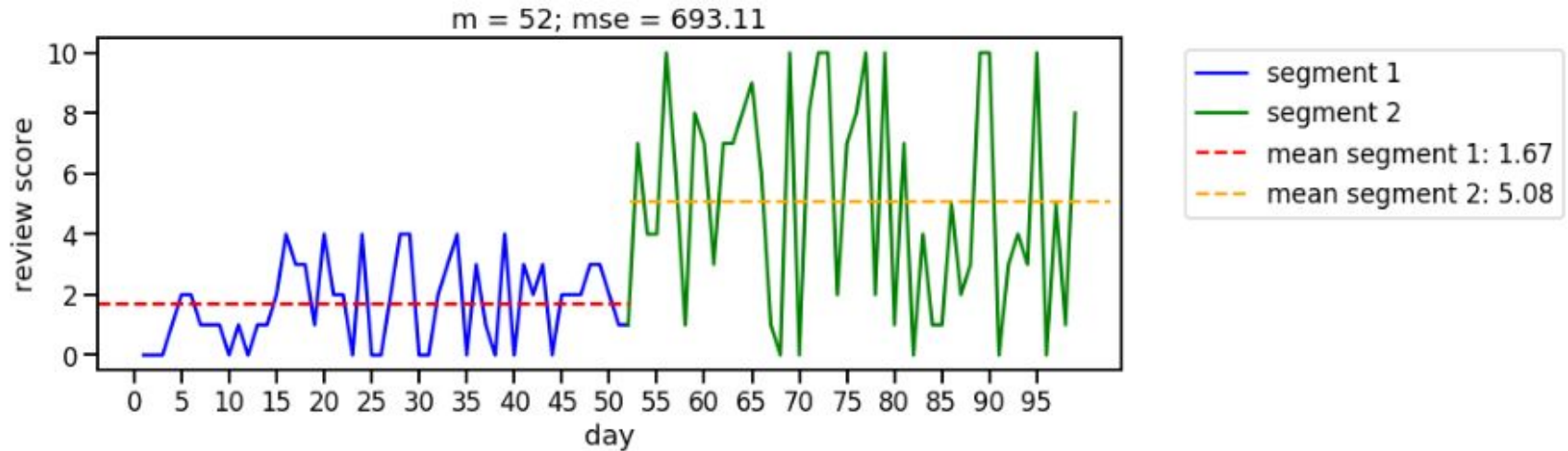
MSE estimator: intuition




MSE estimator: intuition



MSE estimator: intuition

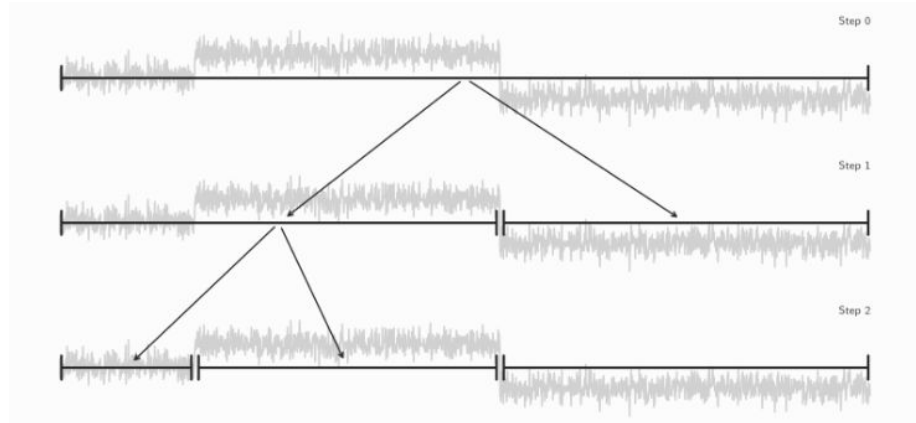


Value of **m** which **minimizes the MSE** is the best estimator of the **last point before the change occurred** → **day 52**

A man in a black suit is seen from behind, looking at a large, complex line graph. The graph is plotted on a blue grid background with white grid lines. The graph features several lines in yellow, green, and brown, showing various trends and fluctuations. The man's head is positioned in the lower center of the frame, looking towards the graph. The text "What if we're looking for more than one change point?" is overlaid on the bottom left of the image.

What if we're looking for
more than one change point?

Multiple Change Point: Binary Segmentation



Schematic view of the binary segmentation algorithm ([source](#))

Libraries



python™

ruptures
bayesloop
fbProphet



changepoint
bcp
strucchange
cpm

Confused?
You can apply *Bayesian*
approach too!

—Anonymous

Bayesian Approach

1. Set **prior** distribution of μ_1 , μ_2 , and overall σ
2. The **changepoint** could occur in $\tau \in \{1, \dots, n\}$
3. Assign:

$$\mu = \begin{cases} \mu_1 & \text{if } \tau \geq t \\ \mu_2 & \text{if } \tau < t \end{cases}$$

4. Produce the **sample**!

Bayesian Approach: PyMC3 - Example

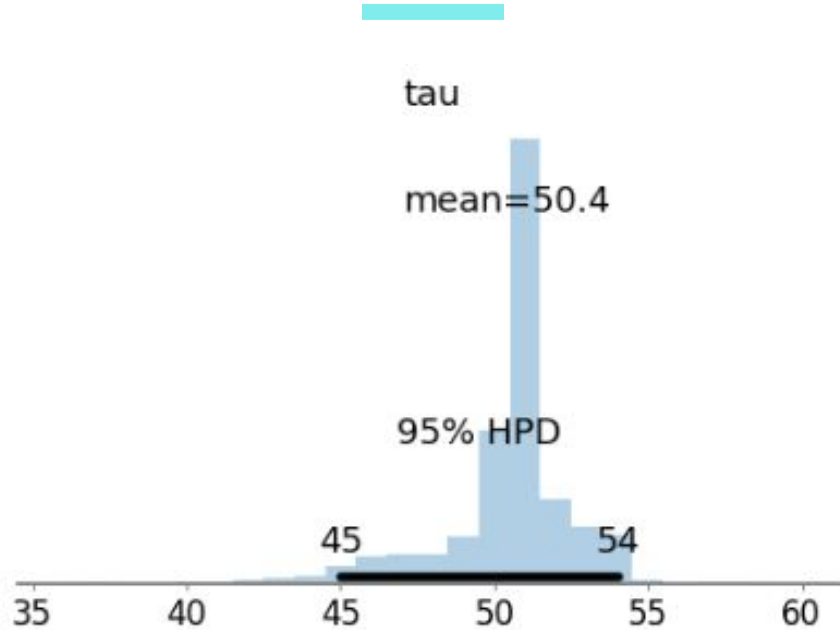
```
import pymc3 as pm

## set number of sample
## set t = time, from 0 to length of observations
samples = 5000 ## number of iteration
t = np.arange(0, len(z)) ## array of observation positions (time)

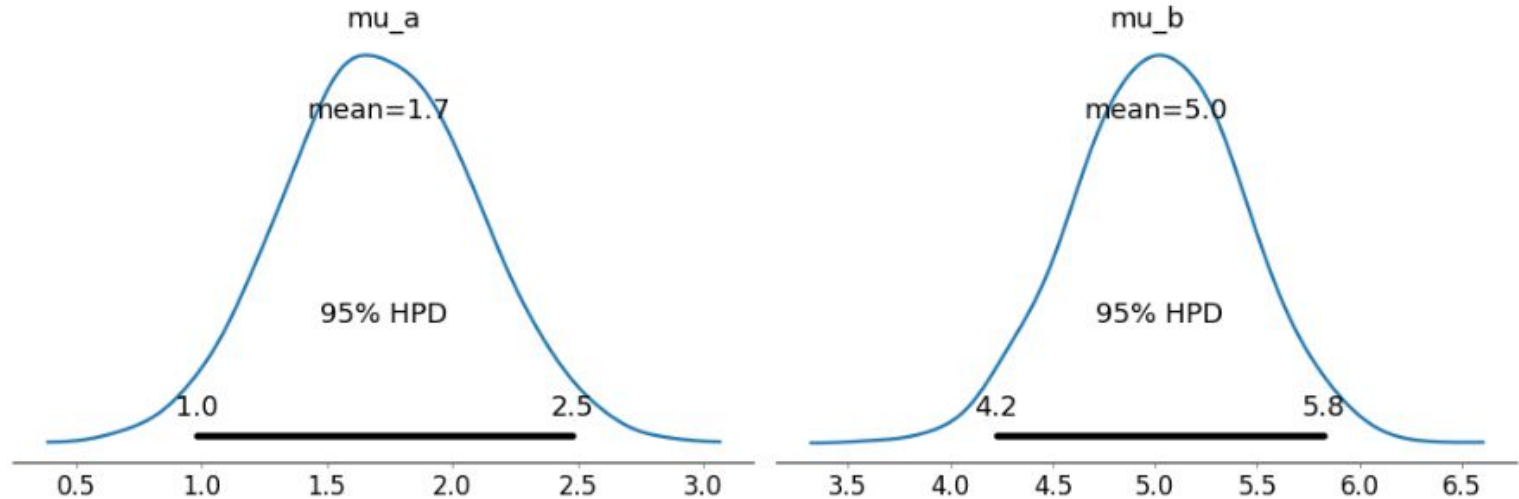
with pm.Model() as model:
    ## define uniform priors for the mean values
    mu_a = pm.Uniform('mu_a', 0, 10)
    mu_b = pm.Uniform('mu_b', 0, 10)
    sigma = pm.HalfCauchy('sigma', np.std(z))
    tau = pm.DiscreteUniform('tau', t.min(), t.max())
    ## define stochastic variable mu
    mu = pm.math.switch(tau >= t, mu_a, mu_b)
    observation = pm.Normal('observation', mu, sigma, observed = z)

    trace = pm.sample(samples, step = pm.NUTS())
    burned_trace = trace[1000:]
```

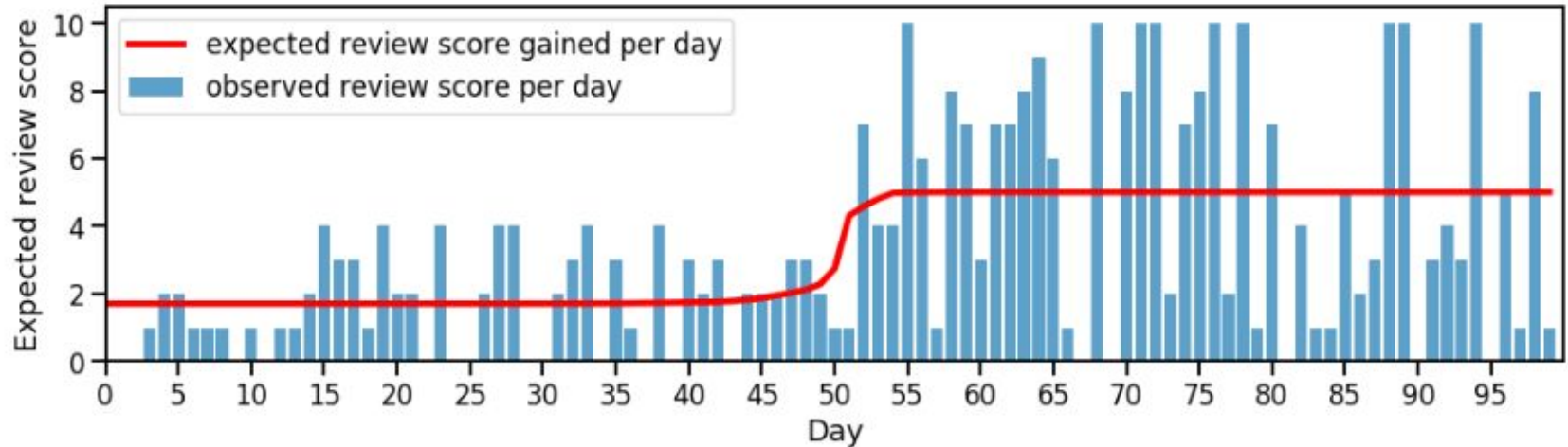
Bayesian Approach: PyMC3 - Changepoint distribution



Bayesian Approach: PyMC3 - Mean distribution



Bayesian Approach: Estimate the change point





3. Conclusions

What have we learned?

Thanks!



Materials: <https://github.com/elvyna/pycon-id-2019>

Find me on Twitter: @vexenta

Want to learn more?

[Killick, R. \(2017\). Introduction to optimal changepoint detection algorithms. useR! Tutorial 2017](#)

[Kass-Hout, T. \(2010\). Change point analysis. Slideshare.](#)

[Bellei, C. \(2016\). Changepoint Detection. Part I - A Frequentist Approach. \[Blog\]](#)

[Bellei, C. \(2017\). Changepoint Detection. Part II - A Bayesian Approach. \[Blog\]](#)

[Davidson-Pilon, C. \(2015\). Chapter 1 - Introduction - PyMC3. Probabilistic Programming and Bayesian Methods for Hackers.](#)

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