



## **Control Components Applications**

**Sheet 1 solu.**

## **Introduction to Embedded Systems**

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**Q1: Write embedded program that produces continuous pulses with duration of 2 seconds and duty cycle of 25%.**

```
#include <avr/io.h>

#include <util/delay.h>

int main(void){

    DDRA = 0x00;

    while(1){

        PORTA = 0X01;

        _delay_ms(500);

        PORTA = 0X00;

        _delay_ms(1500);

    }

    return 0;

}
```

**Q2: Write embedded program that show a bouncing light between 4 LEDs connected to pins 4, 5, 6 and 7. The bouncing delay is 1 second.**

```
#include <avr/io.h>

#include <util/delay.h>

int main(void){

    DDRA = 0x00;

    while(1){

        PORTA = 0X04;

        _delay_ms(1000);

        PORTA = 0X05;

        _delay_ms(1000);

        PORTA = 0X06;

        _delay_ms(1000);

        PORTA = 0X07;

        _delay_ms(1000);

        PORTA = 0X06;

        _delay_ms(1000);

        PORTA = 0X05;

        _delay_ms(1000) }

    return 0;

}
```