```
> restart:
  with (linalg):
  p := (x) -> x^3 - 3 \times x + 1;
Warning, new definition for norm
Warning, new definition for trace
          p := x \to x^3 - 3 x + 1
> x0:=1.:x1:=2.:x2:=-1.:
> p0:=p(x0);p1:=p(x1);p2:=p(x2);
               p\theta := -1.
                p1 := 3.
                p2 := 3.
> x02:=x0^2:x12:=x1^2:x22:=x2^2:
> A := matrix(
  [[x02,x0,1],[x12,x1,1],[x22,x2,
  111):
  b := vector( [p0,p1,p2]):
  s:=linsolve(A, b);
S :=
 [2.000000000, -2.000000000, -1.000000000]
>
> k:=s[1]:1:=s[2]:m:=s[3]:
> sols:=
```

```
[solve (k*x^2+1*x+m=0,x)];
    sols := [-.3660254038, 1.366025404]
> q1:=sols[1];q2:=sols[2];
           q1 := -.3660254038
            q2 := 1.366025404
> x0:=x0;x1:=x1;x2:=x2;q1:=q1;q2:
  =q2;
                x\theta := 1.
                x1 := 2.
                x2 := -1.
           q1 := -.3660254038
            q2 := 1.366025404
> sort([x0,x1,x2,q1,q2]);
  [-1., -.3660254038, 1., 1.366025404, 2.]
> p(1.366025404);
              -.549038105
                  -- Next Iteration
> x0:=x0:x1:=x1:x2:=q2:
> p0:=p(x0);p1:=p(x1);p2:=p(x2);
                p0 := -1.
                  Page 2
```

```
p1 := 3.
           p2 := -.549038105
> x02:=x0^2:x12:=x1^2:x22:=x2^2:
> A := matrix(
  [[x02,x0,1],[x12,x1,1],[x22,x2,
  1]]):
  b := vector( [p0,p1,p2]):
  s:=linsolve(A, b);
s :=
 [4.366025403, -9.098076204, 3.732050801]
>
> k:=s[1]:1:=s[2]:m:=s[3]:
> sols:=
  [solve (k*x^2+1*x+m=0,x)];
    sols := [.5615026996, 1.522332222]
> q1:=sols[1];q2:=sols[2];
           q1 := .5615026996
           q2 := 1.522332222
> x0:=x0;x1:=x1;x2:=x2;q1:=q1;q2:
  =q2;
               x0 := 1.
               x1:-2.
```

```
x2 := 1.366025404
           q1 := .5615026996
           q2 := 1.522332222
> sort([x0,x1,x2,q1,q2]);
[.5615026996, 1., 1.366025404, 1.522332222,
 2.]
> p(1.522332223);
             -.038998749
               ----Next Iteration
> #
> x0:=x2:x2:=x1:x1:=q2:
> p0:=p(x0);p1:=p(x1);p2:=p(x2);
           p0 := -.549038105
           p1 := -.038998753
               p2 := 3.
> x02:=x0^2:x12:=x1^2:x22:=x2^2:
> A := matrix(
  [[x02,x0,1],[x12,x1,1],[x22,x2,
  1]]):
  b := vector( [p0,p1,p2]):
  s:=linsolve(A, b);
```

```
S :=
 [4.888357645, -10.85625981, 5.159089039]
>
> k:=s[1]:1:=s[2]:m:=s[3]:
> sols:=
   [solve (k*x^2+1*x+m=0,x)];
    sols := [.6889349725, 1.531904949]
> q1:=sols[1];q2:=sols[2];
            q1 := .6889349725
            q2 := 1.531904949
> x0:=x0; x1:=x1; x2:=x2; q1:=q1; q2:
  =q2;
            x\theta := 1.366025404
            x1 := 1.522332222
                x2 := 2.
            q1 := .6889349725
            q2 := 1.531904949
> sort([x0,x1,x2,q1,q2]);
[.6889349725, 1.366025404, 1.522332222,
 1.531904949, 2.]
> p(1.531904949);
                   Page 5
```

```
-.000743298
                 ----Next Iteration
> #
> x0:=x1:x1:=q2:x2:=x2:
> p0:=p(x0);p1:=p(x1);p2:=p(x2);
           p\theta := -.038998753
           p1 := -.000743298
               p2 := 3.
> x02:=x0^2:x12:=x1^2:x22:=x2^2:
> A := matrix(
  [[x02,x0,1],[x12,x1,1],[x22,x2,
  1]]):
  b := vector( [p0,p1,p2]):
  s:=linsolve(A, b);
S :=
 [5.054238537, -11.44054742, 5.664140691]
>
> k:=s[1]:1:=s[2]:m:=s[3]:
> sols:=
  [solve (k*x^2+1*x+m=0,x)];
    sols := [.7314664203, 1.532088680]
> q1:=sols[1];q2:=sols[2];
```

```
q1 := .7314664203
            q2 := 1.532088680
> x0:=x0;x1:=x1;x2:=x2;q1:=q1;q2:
  =q2;
            x0 := 1.522332222
            x1 := 1.531904949
                x2 := 2.
            q1 := .7314664203
            q2 := 1.532088680
> sort([x0,x1,x2,q1,q2]);
[.7314664203, 1.522332222, 1.531904949,
  1.532088680, 2.]
> p(1.532088679);
                -.838\ 10^{-6}
                      ---Next
   Iteration
> p0:=p(x0);p1:=p(x1);p2:=p(x2);
            p0 := -.038998753
            p1 := -.000743298
                p2 := 3.
> x02:=x0^2:x12:=x1^2:=x2^2:=x2^2:
```

```
> A := matrix(
  [[x02,x0,1],[x12,x1,1],[x22,x2,
  1]]):
  b := vector( [p0,p1,p2]):
  s:=linsolve(A, b);
S :=
 [5.054238537, -11.44054742, 5.664140691]
> k:=s[1]:1:=s[2]:m:=s[3]:
> sols:=
  [solve (k*x^2+1*x+m=0,x)];
    sols := [.7314664203, 1.532088680]
> q1:=sols[1];q2:=sols[2];
           q1 := .7314664203
           q2 := 1.532088680
> x0:=x0;x1:=x1;x2:=x2;q1:=q1;q2:
  =q2;
           x\theta := 1.522332222
           x1 := 1.531904949
               x2 := 2.
           q1 := .7314664203
```

```
q2 := 1.532088680
> sort([x0,x1,x2,q1,q2]);
[.7314664203, 1.522332222, 1.531904949,
 1.532088680, 2.]
> p(1.532088679);
               -.838 \cdot 10^{-6}
                     ----Next
  Iteration
> x0:=x1:x1:=q2:x2:=x2:
> p0:=p(x0);p1:=p(x1);p2:=p(x2);
           p\theta := -.000743298
             p1 := -.834 \cdot 10^{-6}
                p2 := 3.
> x02:=x0^2:x12:=x1^2:x22:=x2^2:
> A := matrix(
  [[x02,x0,1],[x12,x1,1],[x22,x2,
  1]]):
  b := vector( [p0,p1,p2]):
  s:=linsolve(A, b);
S :=
 [5.064023375, -11.47510655, 5.694119603]
```

```
>
> k:=s[1]:1:=s[2]:m:=s[3]:
> sols:=
   [solve (k*x^2+1*x+m=0,x)];
    sols := [.7339169556, 1.532088886]
> q1:=sols[1];q2:=sols[2];
            q1 := .7339169556
            q2 := 1.532088886
> x0:=x0;x1:=x1;x2:=x2;q1:=q1;q2:
  =q2;
            x0 := 1.531904949
            x1 := 1.532088680
                x2 := 2.
            q1 := .7339169556
            q2 := 1.532088886
> sort([x0,x1,x2,q1,q2]);
[.7339169556, 1.531904949, 1.532088680,
 1.532088886, 2.]
> p(1.532088886);
                 -.1 \cdot 10^{-8}
```