

Aprendizagem Automática

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Redes Neurais

Redes Neurais

- ▶ Funcionamento inspirado no neurônio biológico.
- ▶ Tarefas de Aprendizado de Máquina
 - ▶ Classificação
 - ▶ Regressão



Neurônio Biológico x Neurônio Artificial

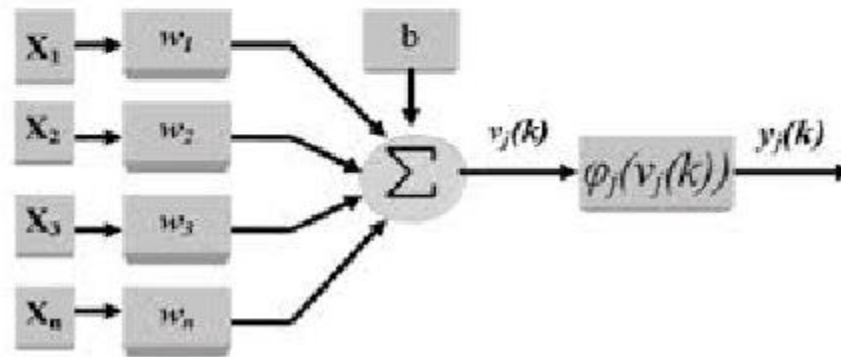


Figura 2: Representação do neurônio artificial.

Neurônio Biológico x Neurônio Artificial



McCulloch-Pitts

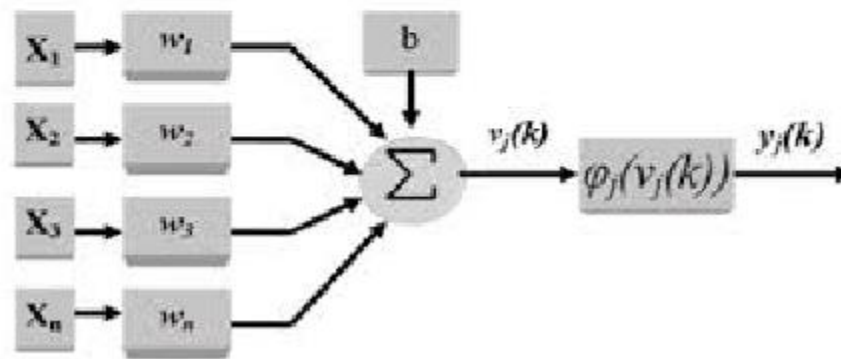


Figura 2: Representação do neurônio artificial.

Modelo de McCulloch-Pitts

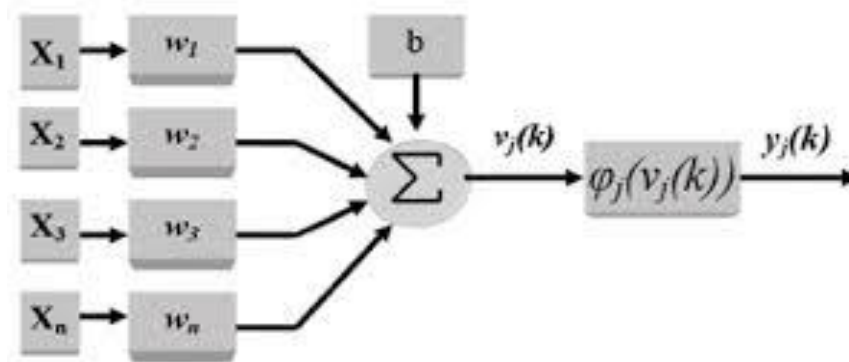


Figura 2: Representação do neurônio artificial.

$$v_j = w_1x_1 + w_2x_2 + \cdots - b$$

$$\phi(v_j) = 1 \text{ se } v_j > 0$$

$$\phi(v_j) = 0 \text{ se } v_j < 0$$

Modelo de McCulloch-Pitts

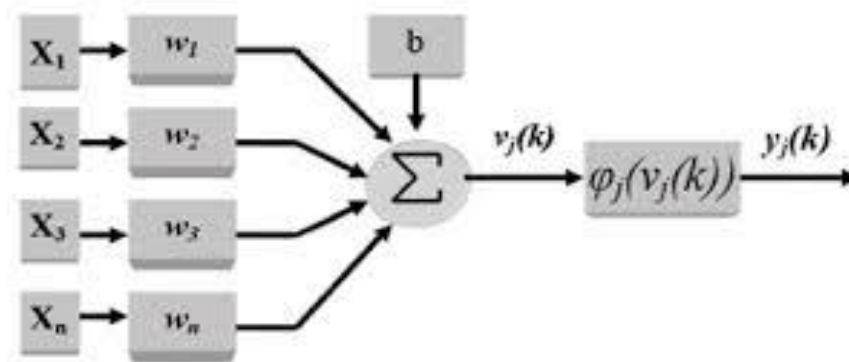


Figura 2: Representação do neurônio artificial.

$$v_j = w_1x_1 + w_2x_2 + \cdots - w_0x_0 = \mathbf{w}^T \mathbf{x} \quad \text{onde } w_0 = -1 \text{ e } x_0 = b$$

$$\varphi(v_j) = 1 \text{ se } v_j > 0$$

$$\varphi(v_j) = 0 \text{ se } v_j < 0$$

Perceptron

- ▶ Modelo

- ▶ $\bar{y}_i = \varphi(\mathbf{w}^T \mathbf{x}_i)$

- ▶ Regra de Aprendizagem

- ▶ $\mathbf{w} = \mathbf{w} - \alpha \frac{\partial J}{\partial \mathbf{w}}$

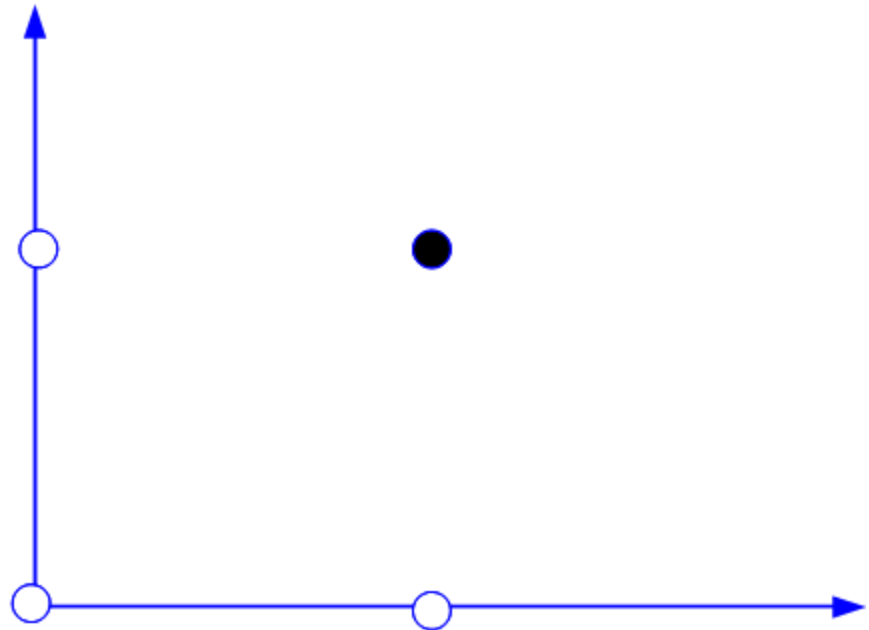
- ▶ $\mathbf{w} = \mathbf{w} + \alpha \frac{1}{n} \sum_{i=1}^n e_i \mathbf{x}_i$



Perceptron

► Problemas linearmente separáveis

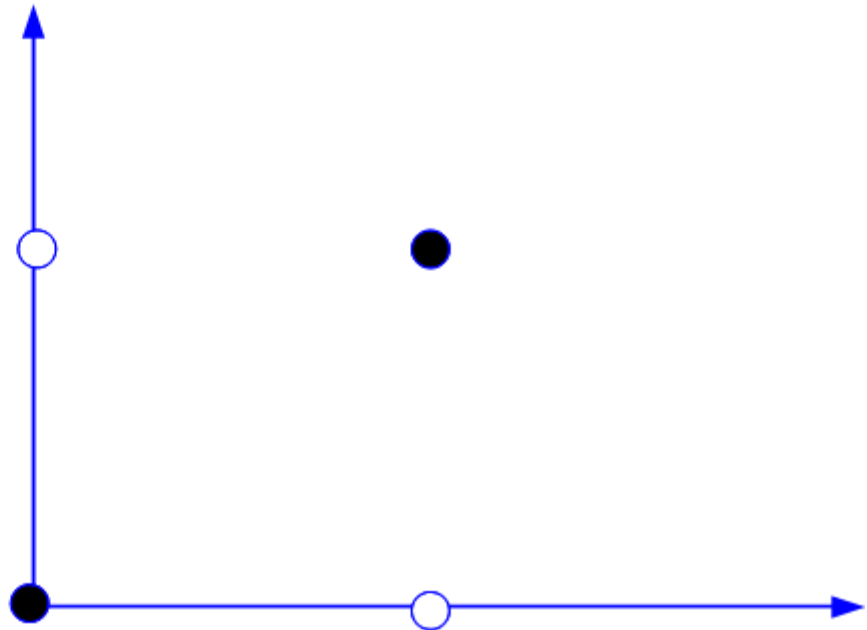
Entrada (x)	Saída (y)
0,0	0
0,1	0
1,0	0
1,1	1



Perceptron

- ▶ Minsky e Papert (1969)
 - ▶ Problema ou-exclusivo

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



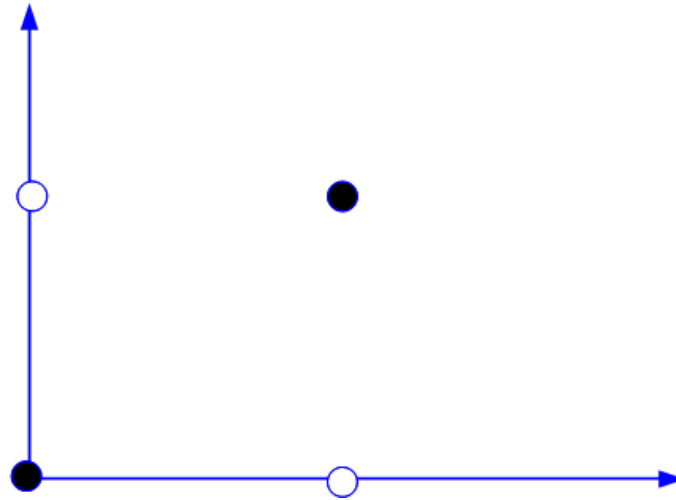
Perceptron

- ▶ Minsky e Papert (1969)
 - ▶ Problema ou-exclusivo
- ▶ Provaram que pode ser resolvido se for utilizada mais de uma camada de neurônios



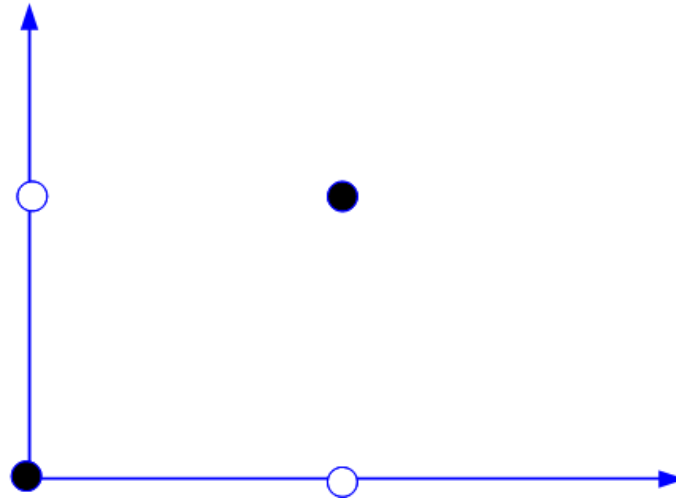
Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



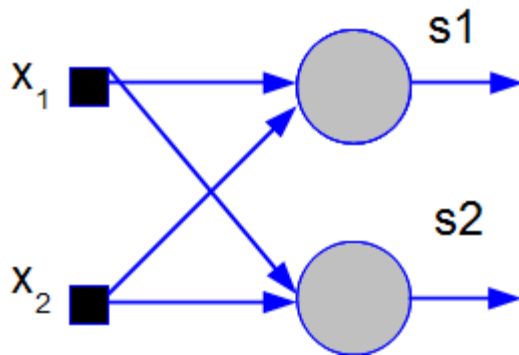
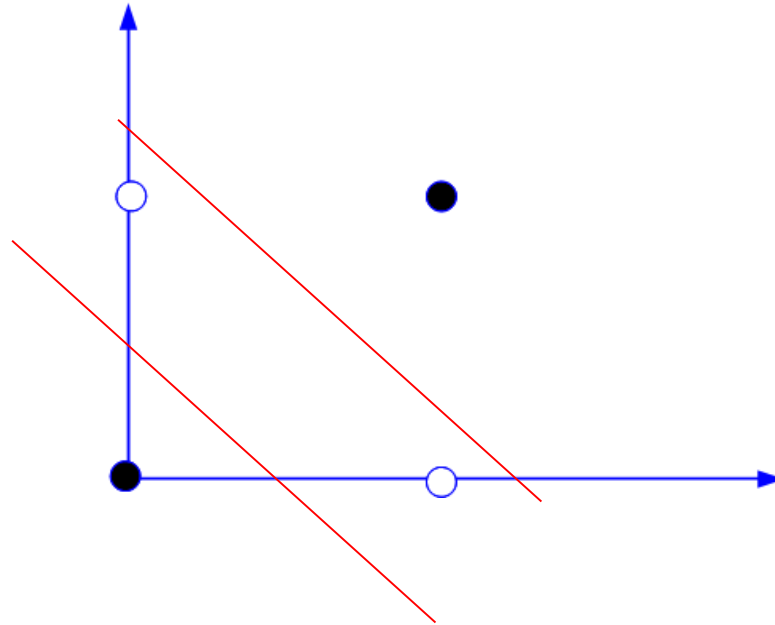
x_1 ■

x_2 ■



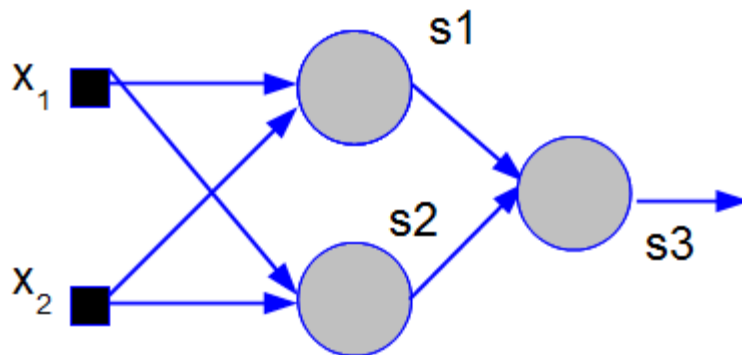
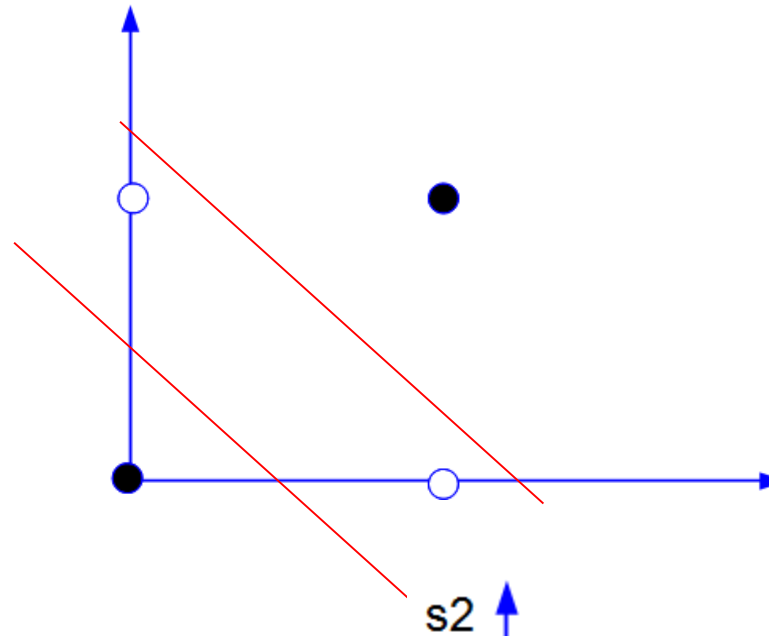
Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



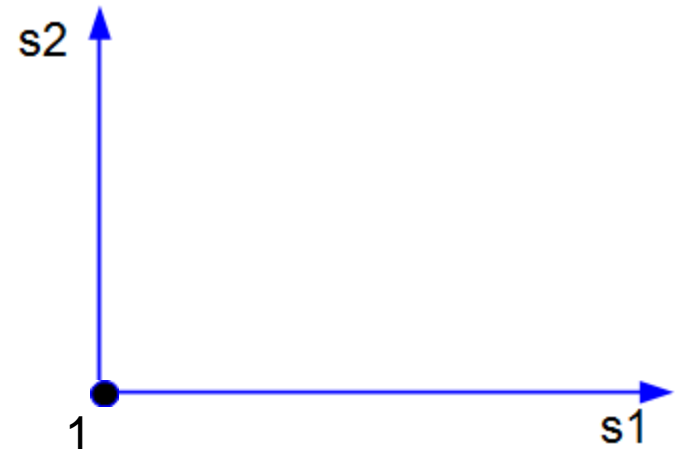
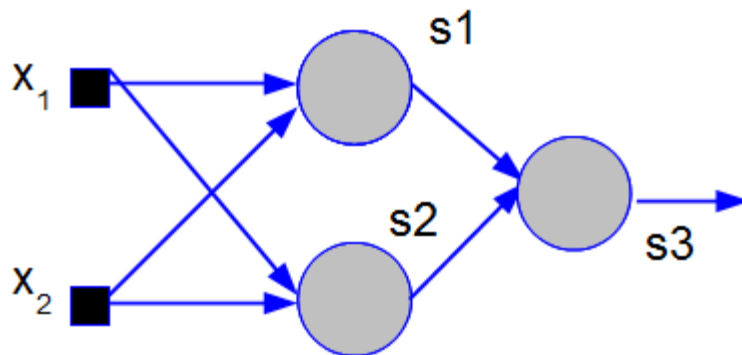
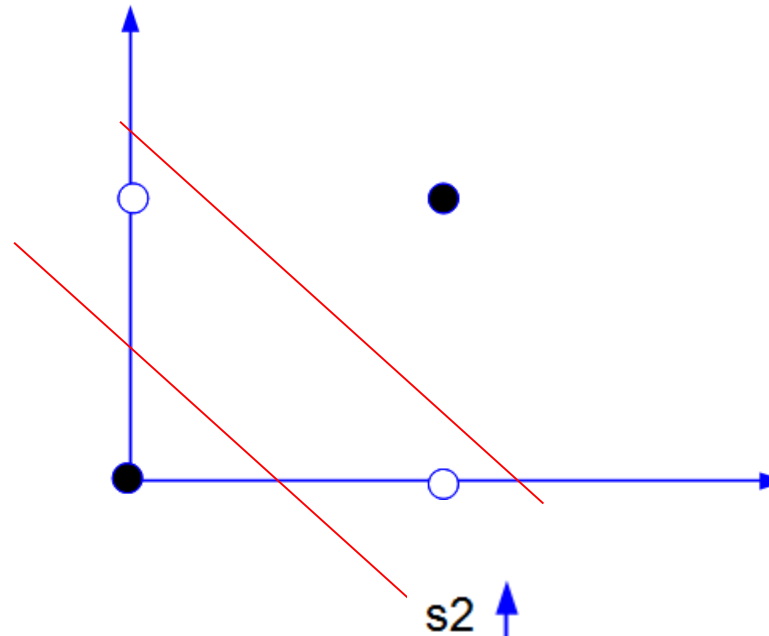
Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



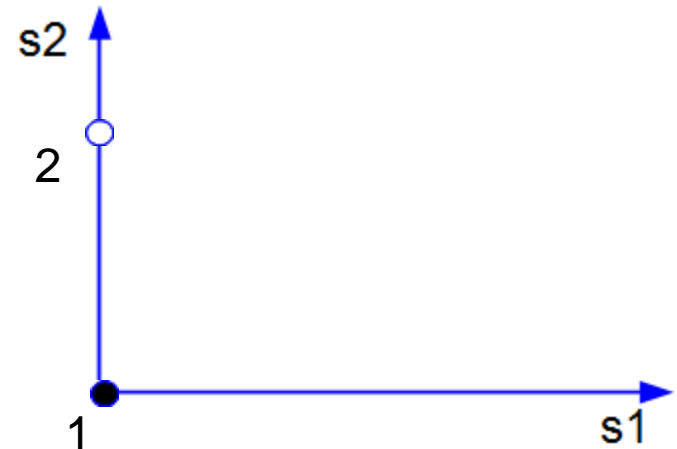
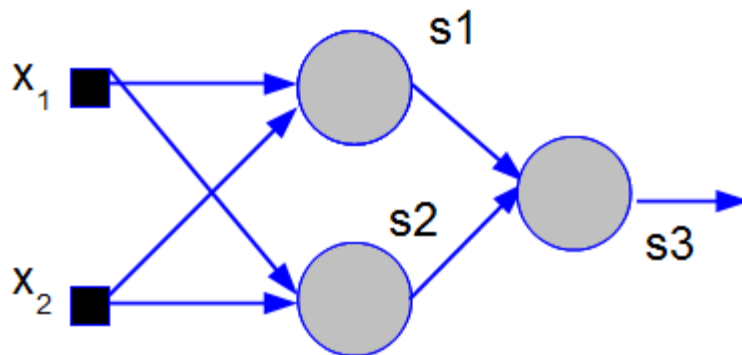
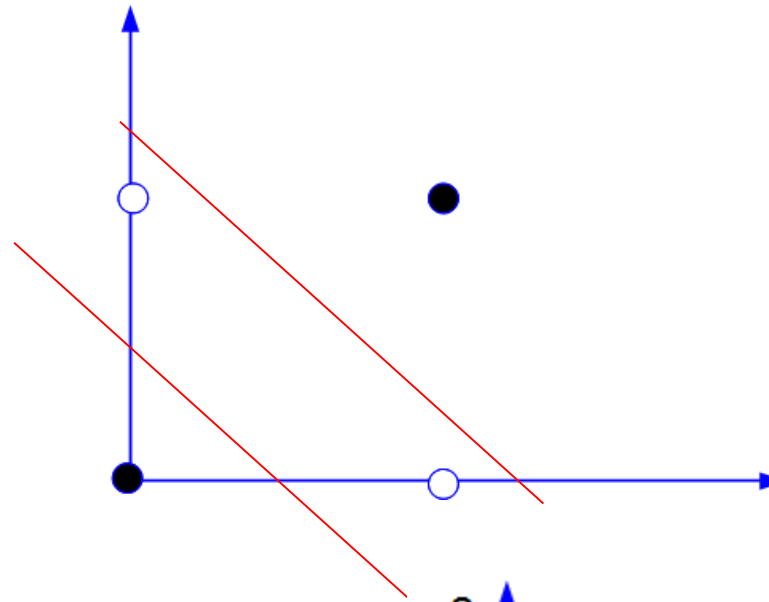
Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



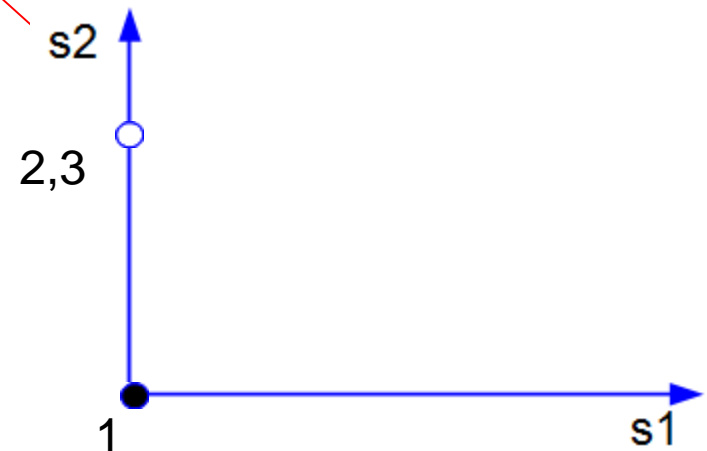
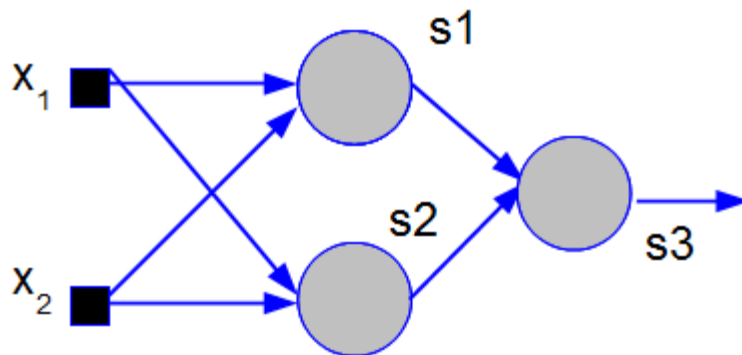
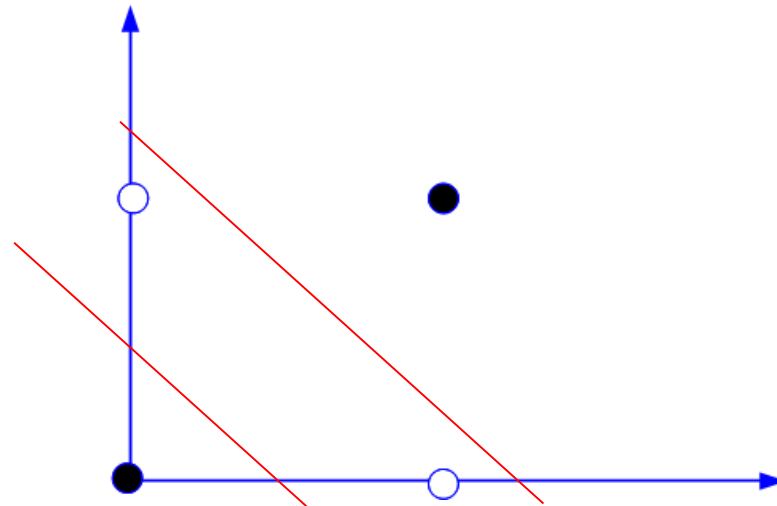
Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



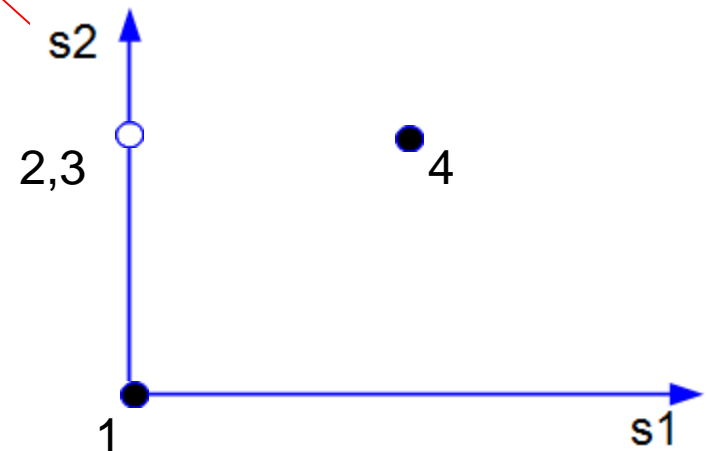
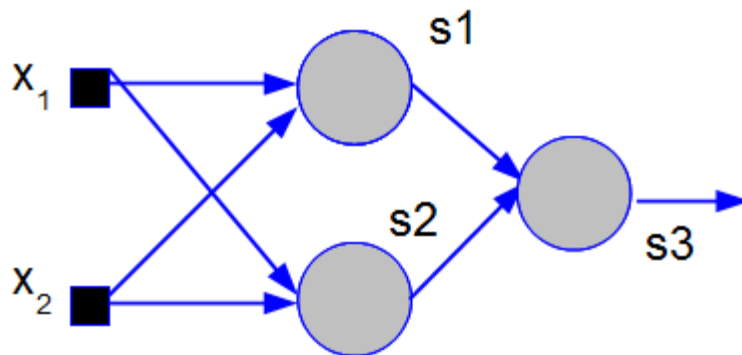
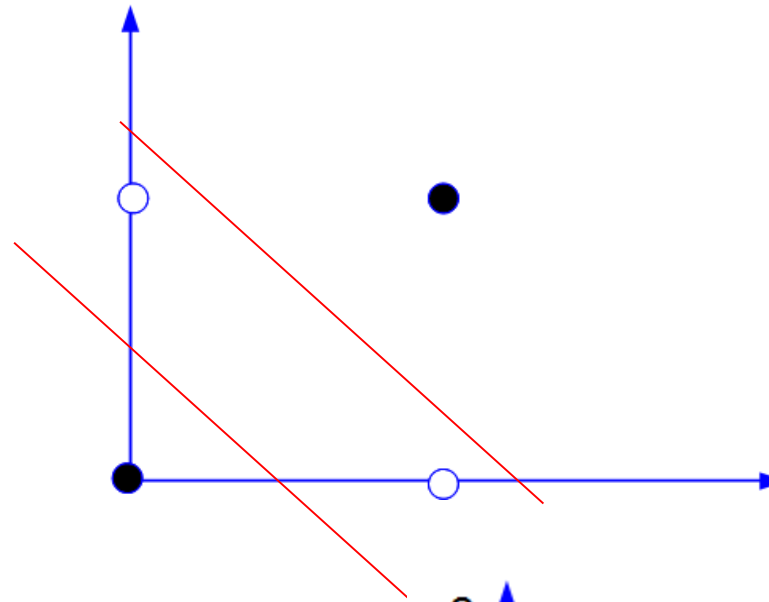
Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



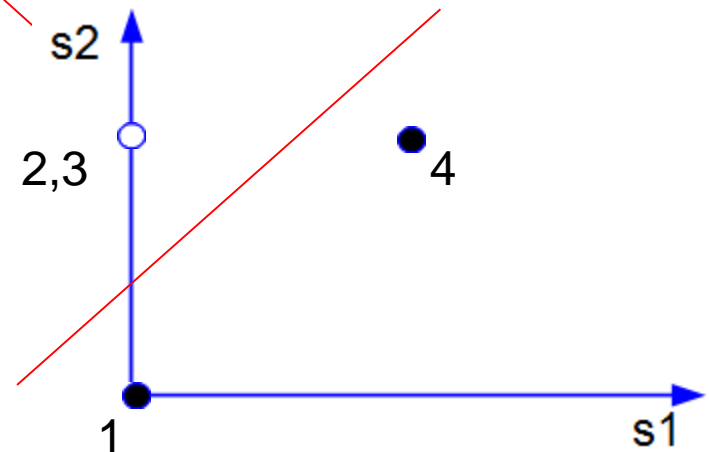
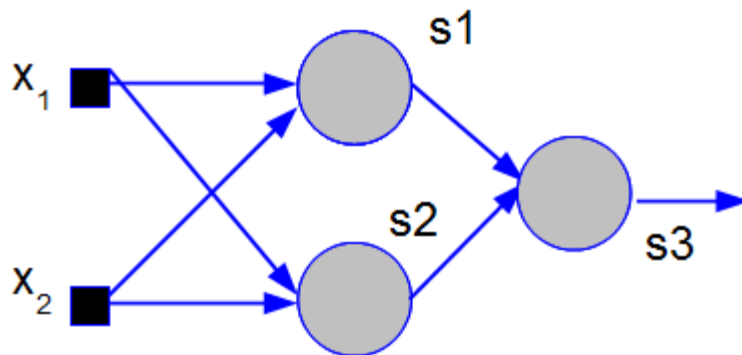
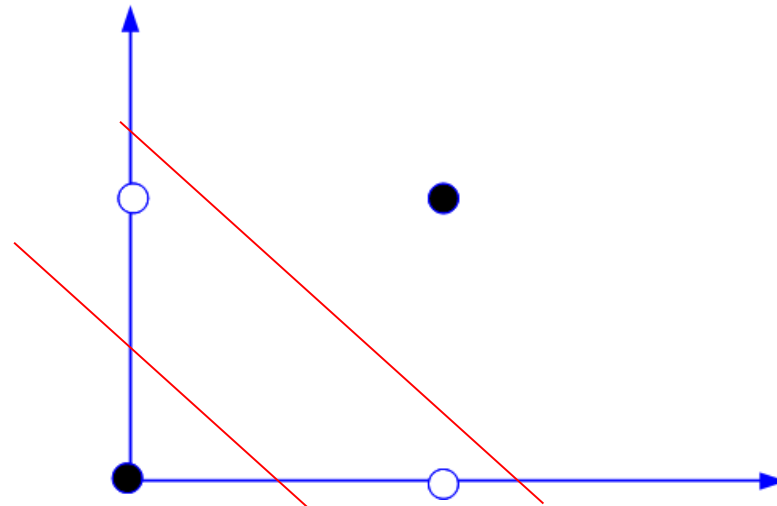
Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



Perceptron

Entrada (x)	Saída (y)
0,0	0
0,1	1
1,0	1
1,1	0



Perceptron de Múltiplas Camadas

- ▶ Rede MLP (MultiLayer Perceptron)
 - ▶ Problemas não linearmente separáveis



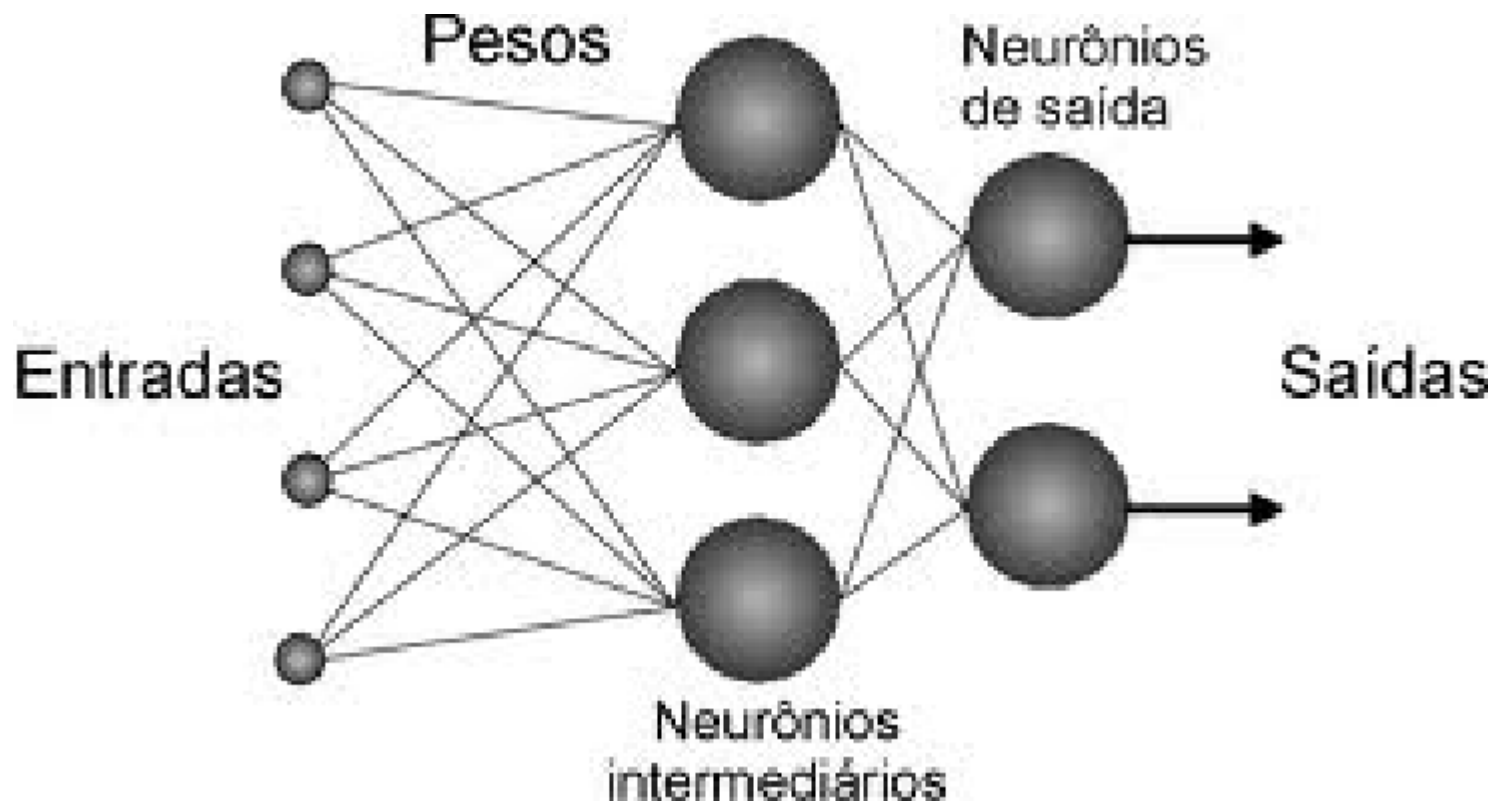


Redes MLP

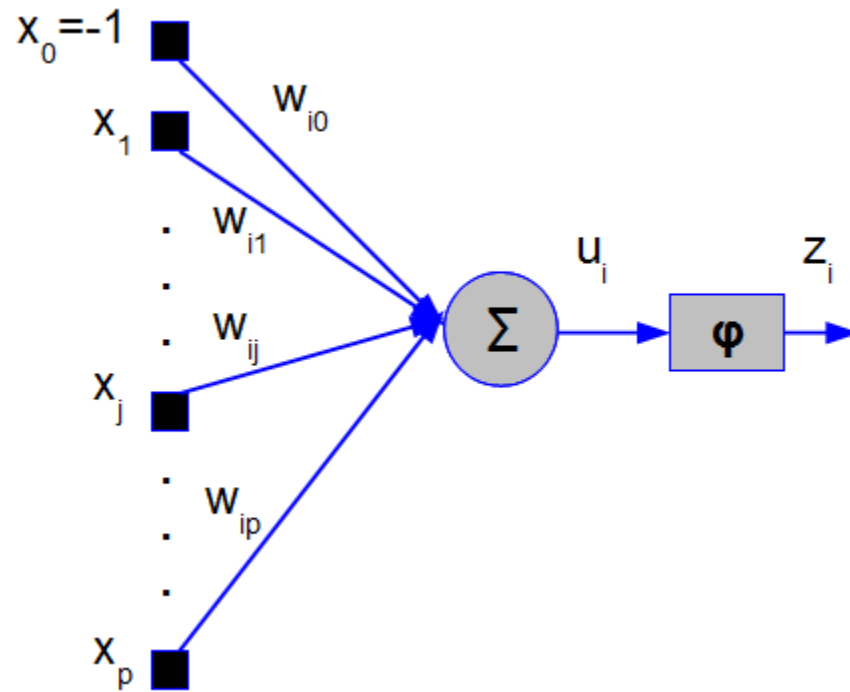
Redes Neurais

Redes MLP

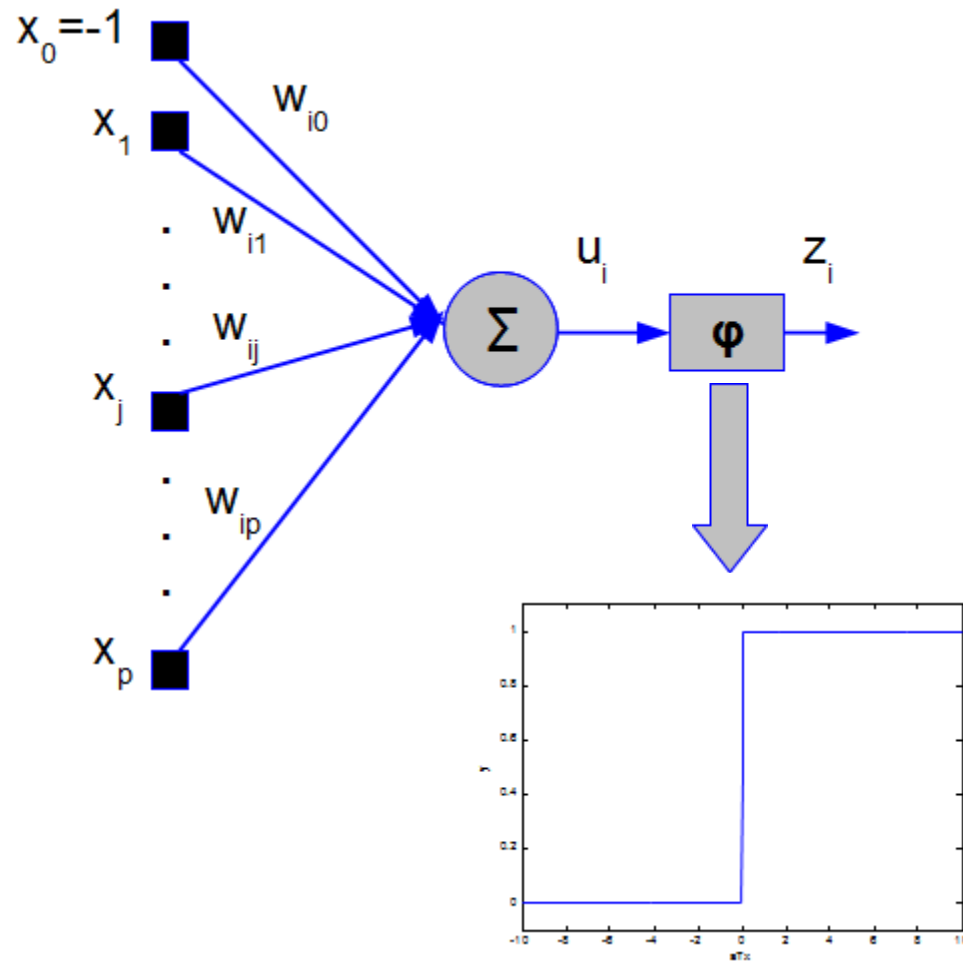
- ▶ Redes com múltiplas camadas de neurônios artificiais



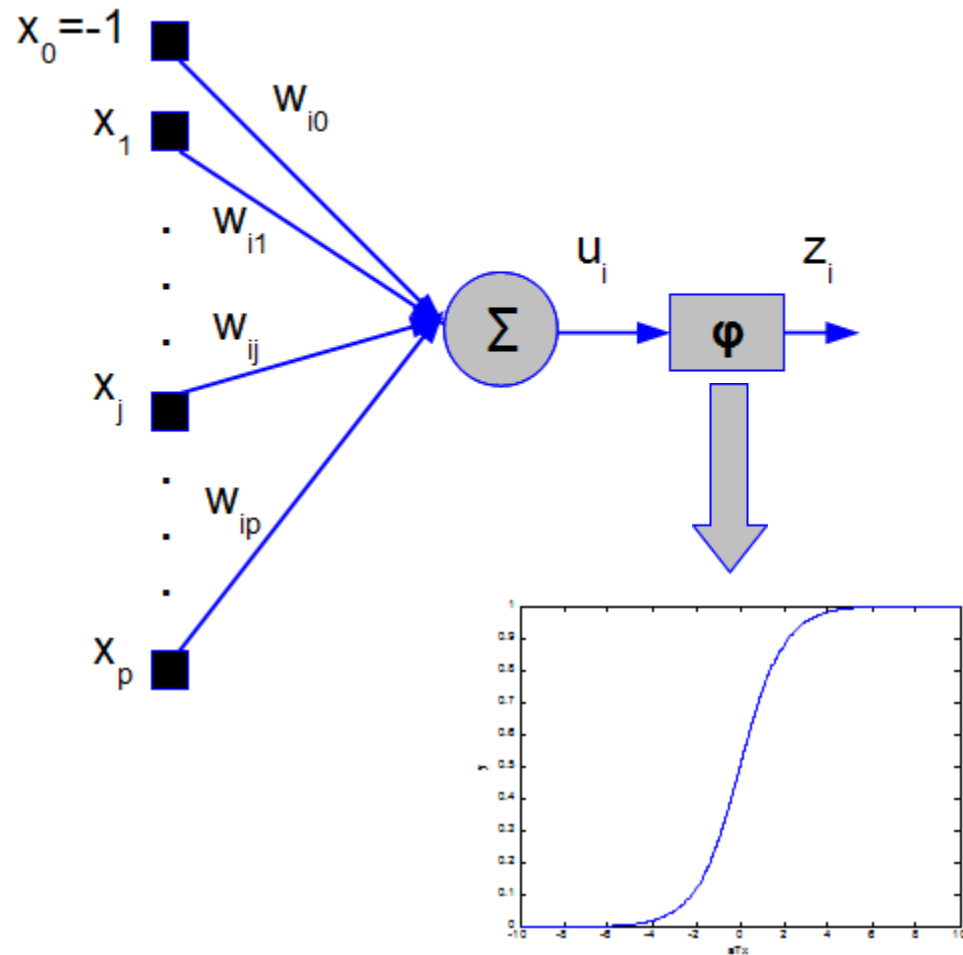
Neurônio Artificial



Neurônio Artificial



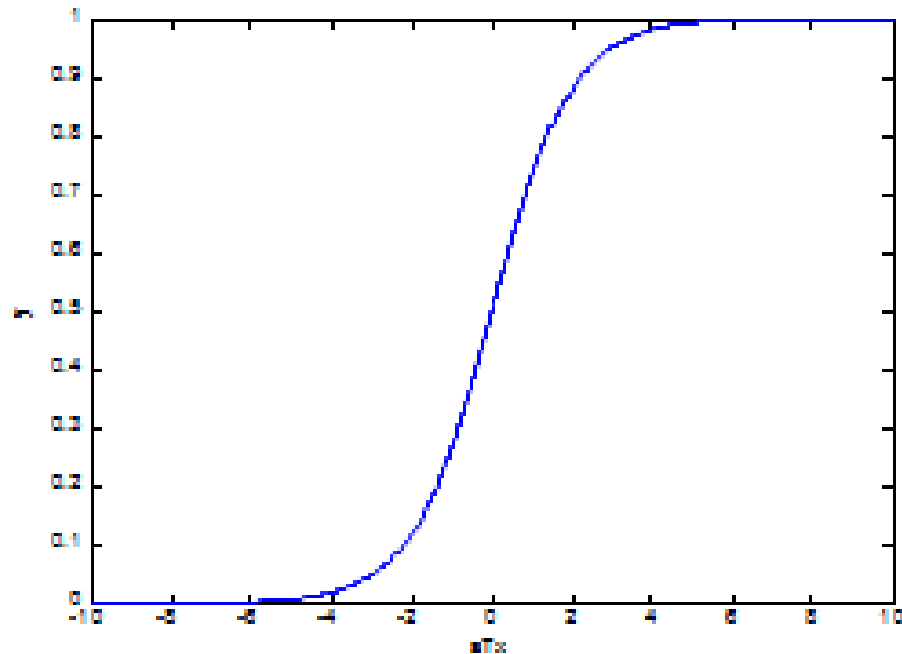
Neurônio Artificial



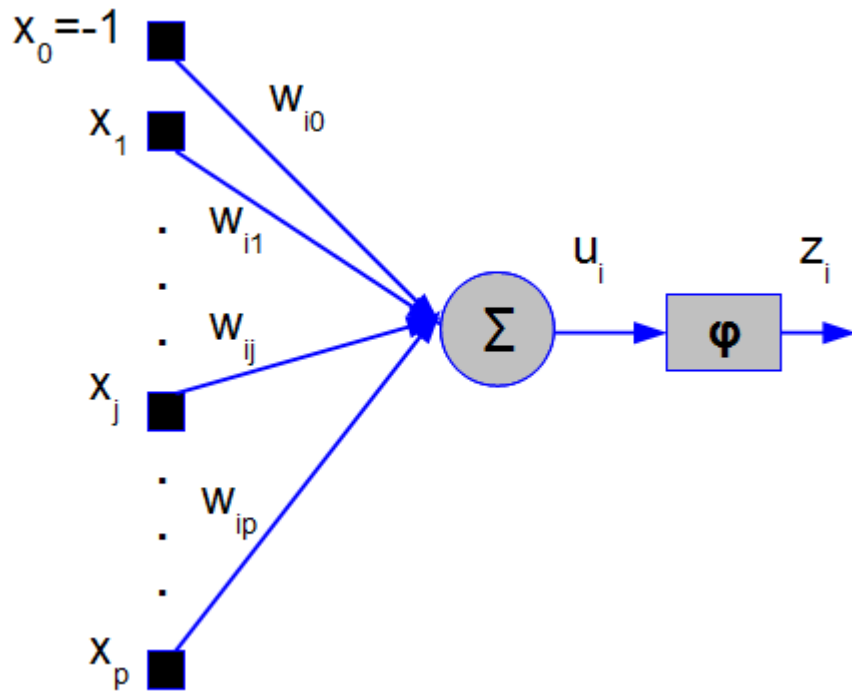
Neurônio Artificial

► Função Logística

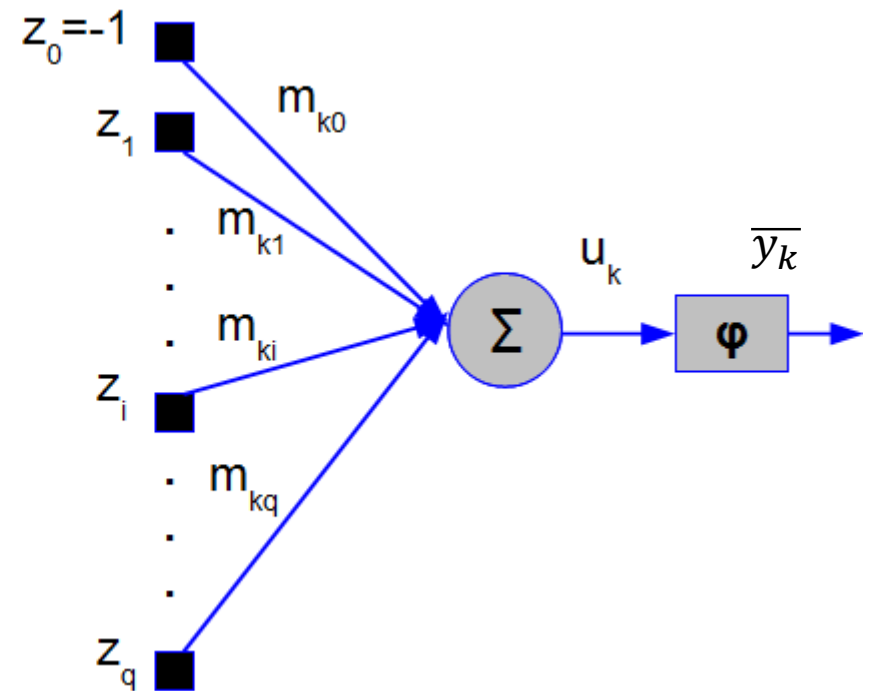
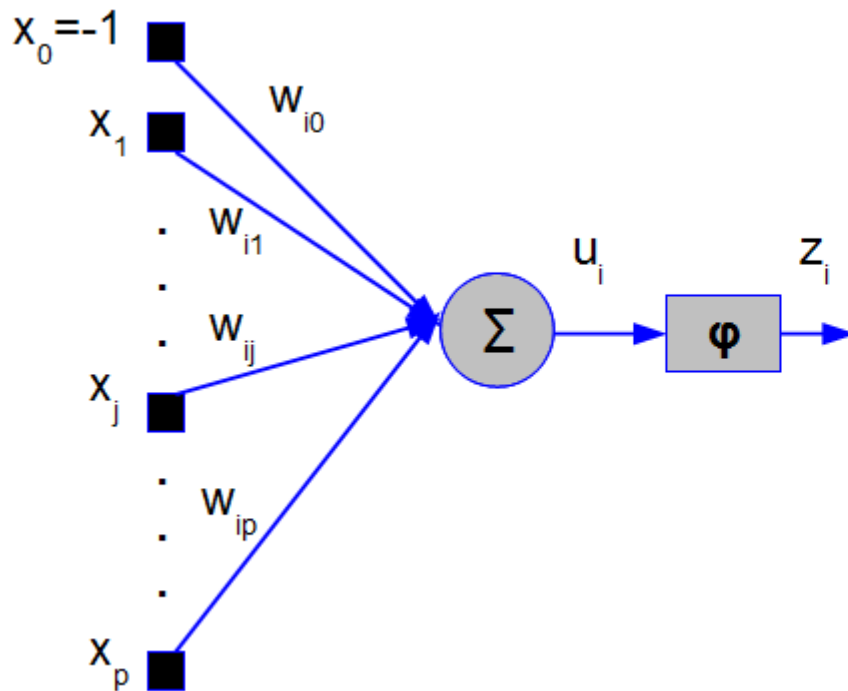
- $f(x) = \frac{1}{1+e^{-x}}$
- $f'(x) = f(x)[1 - f(x)]$



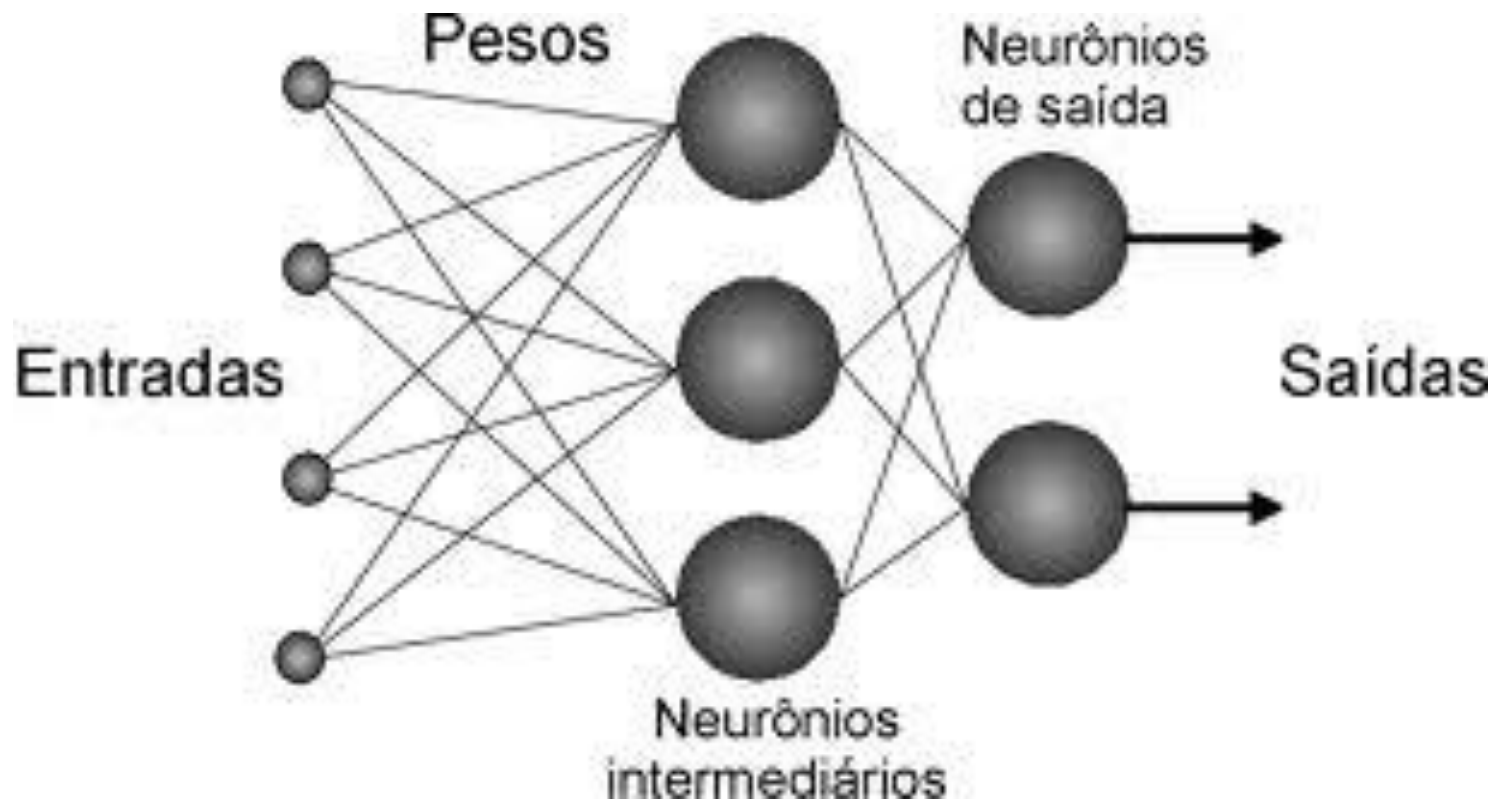
Rede MLP



Rede MLP



Rede MLP

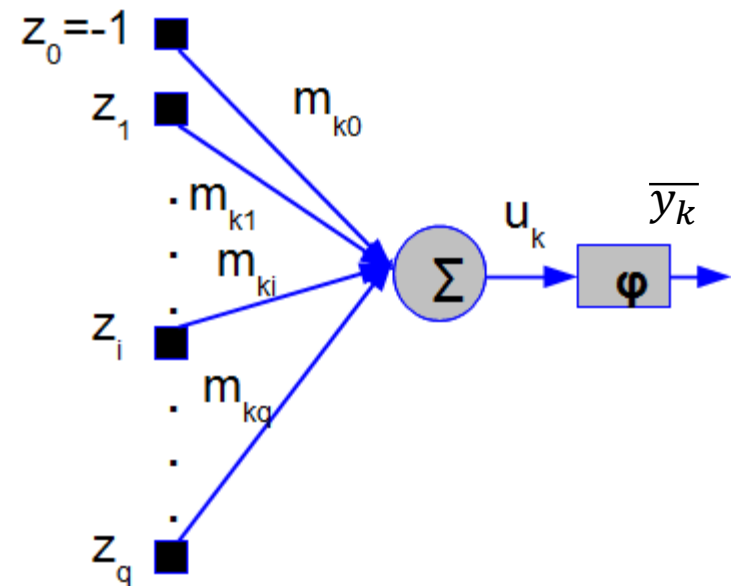


Rede MLP

- ▶ Atualização dos pesos da camada de saída

- ▶ $m = m - \alpha \frac{\partial J}{\partial m}$

- ▶ $J(m_{ki}) = \frac{1}{2} \{ [y_k - \overline{y_k}]^2 \}$

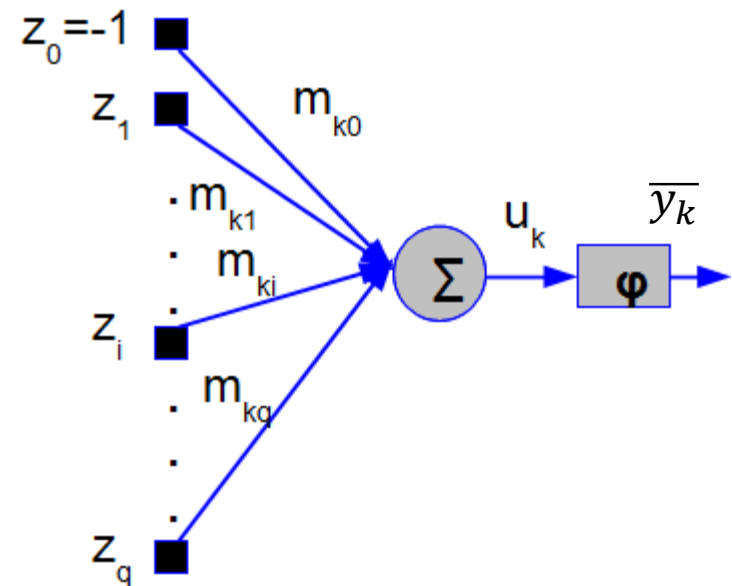


Rede MLP

► Atualização dos pesos da camada de saída

► $m = m - \alpha \frac{\partial J}{\partial m}$

► $J(m_{ki}) = \frac{1}{2} \{ [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)]^2 \}$



Rede MLP

- ▶ Atualização dos pesos da camada de saída

- ▶ $m = m - \alpha \frac{\partial J}{\partial m}$

- ▶ $J(m_{ki}) = \frac{1}{2} \{ [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)]^2 \}$

- ▶ $\frac{\partial J}{\partial m_{ki}} = \frac{1}{2} 2 [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)] [(-1) \varphi'(\sum_{i=0}^q m_{ki} z_i) z_i]$



Rede MLP

► Atualização dos pesos da camada de saída

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- $\frac{\partial J}{\partial m_{ki}} = -e_k \varphi'(u_k) z_i$



Rede MLP

► Atualização dos pesos da camada de saída

► $m = m - \alpha \frac{\partial J}{\partial m}$

► $J(m_{ki}) = \frac{1}{2} \{ [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)]^2 \}$

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► $\frac{\partial J}{\partial m_{ki}} = -e_k \varphi'(u_k) z_i$

► $m_{ki} = m_{ki} + \alpha e_k \varphi'(u_k) z_i$

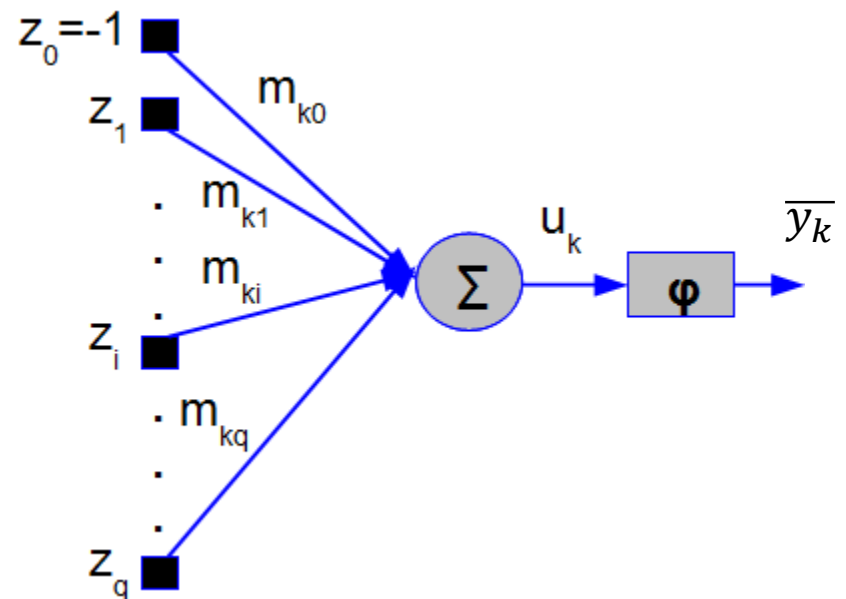
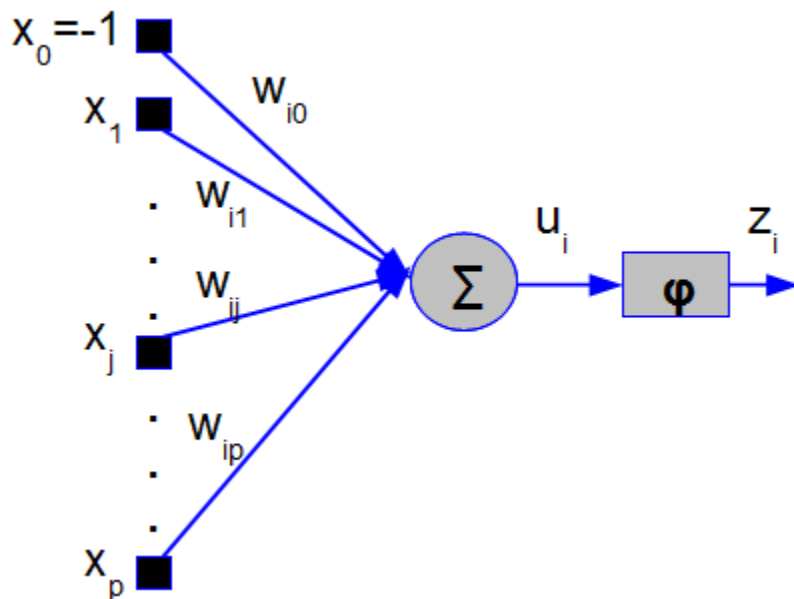


Rede MLP

► Atualização dos pesos da camada oculta

► $w = w - \alpha \frac{\partial J}{\partial w}$

► $J(w_{ij}) = \frac{1}{2} [\sum_{k=1}^r (y_k - \overline{y_k})^2]$

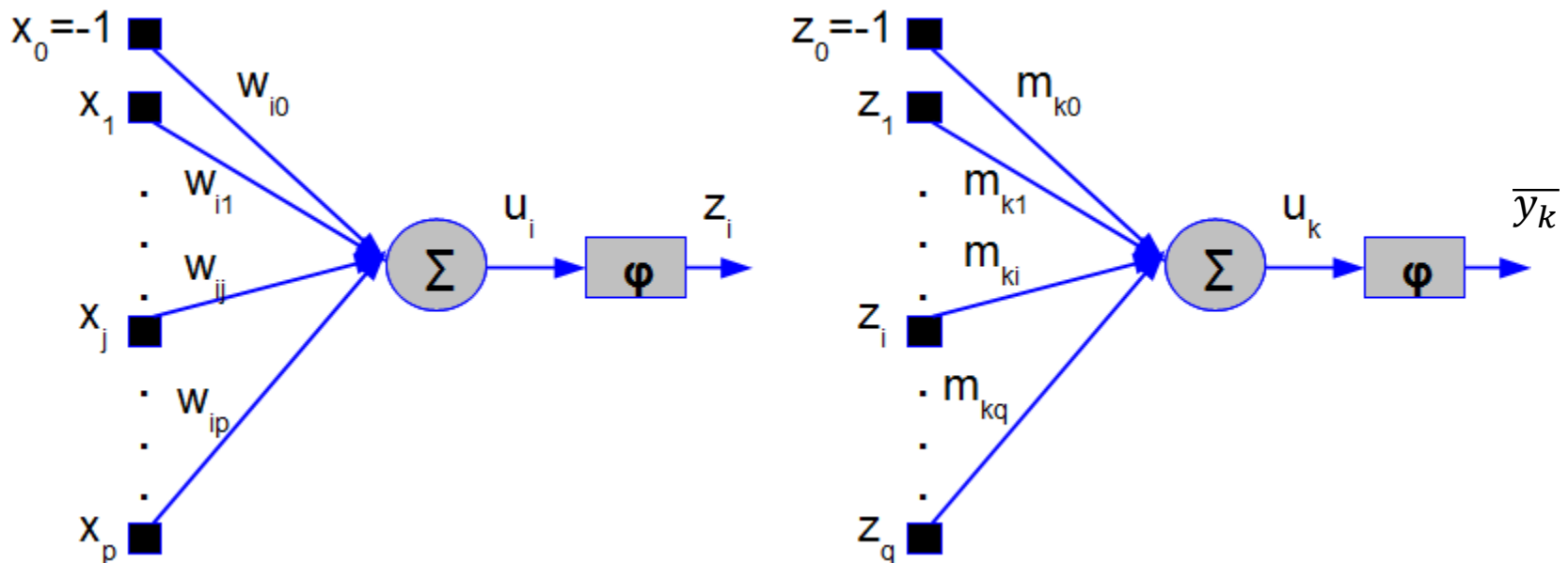


Rede MLP

► Atualização dos pesos da camada oculta

► $w = w - \alpha \frac{\partial J}{\partial w}$

► $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} z_i)]^2 \}$

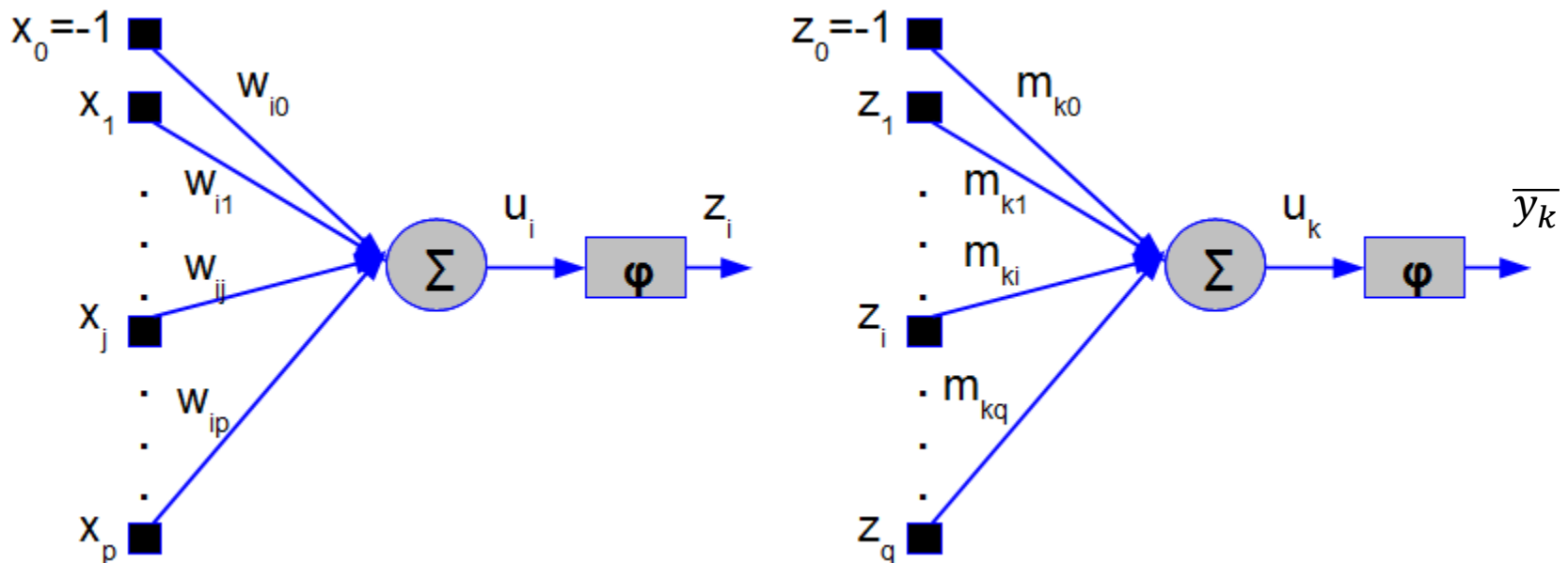


Rede MLP

► Atualização dos pesos da camada oculta

► $w = w - \alpha \frac{\partial J}{\partial w}$

► $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} \varphi(u_i))]^2 \}$

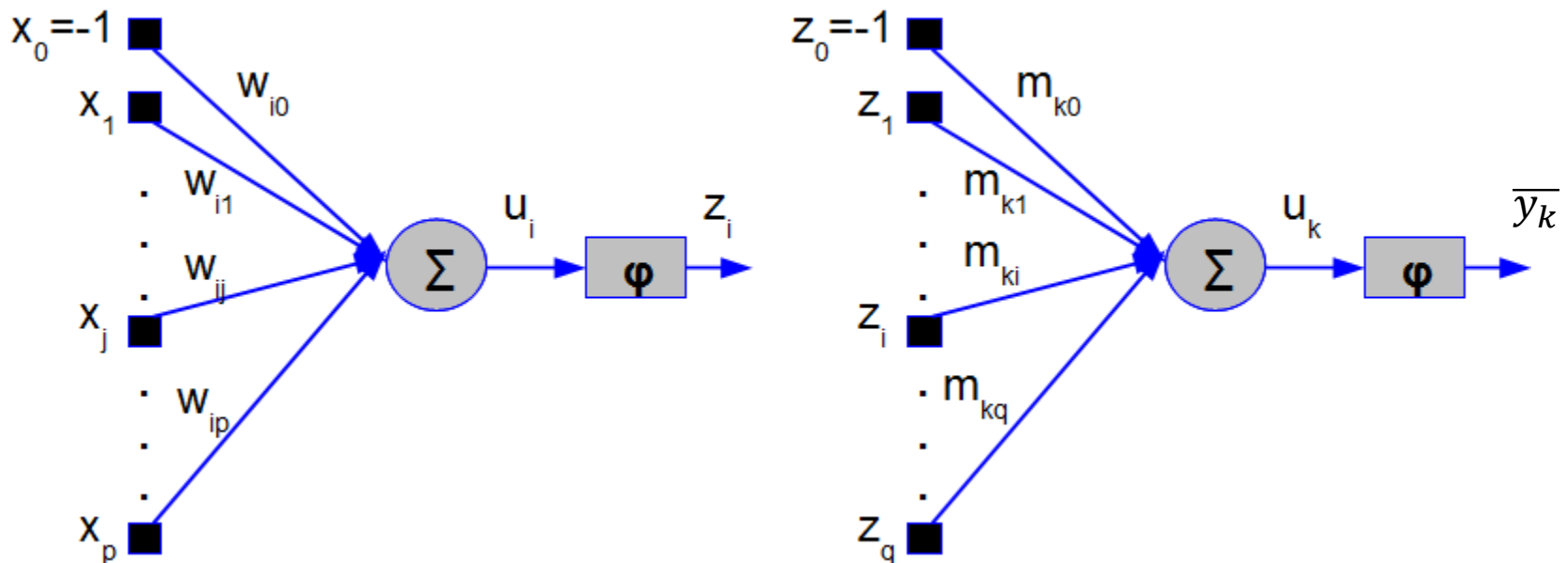


Rede MLP

► Atualização dos pesos da camada oculta

► $w = w - \alpha \frac{\partial J}{\partial w}$

► $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} \varphi(\sum_{j=0}^p w_{ij} x_j))]^2 \}$



Rede MLP

- ▶ Atualização dos pesos da camada oculta

- ▶ $w = w - \alpha \frac{\partial J}{\partial w}$

- ▶ $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} \varphi(\sum_{j=0}^p w_{ij} x_j))]^2 \}$

- ▶ $\frac{\partial J}{\partial w_{ij}} = -\varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$



Rede MLP

- ▶ Atualização dos pesos da camada oculta

- ▶ $w = w - \alpha \frac{\partial J}{\partial w}$

- ▶ $J(w_{ij}) = \frac{1}{2} \{ \sum_{k=1}^r [y_k - \varphi(\sum_{i=0}^q m_{ki} \varphi(\sum_{j=0}^p w_{ij} x_j))]^2 \}$

- ▶ $\frac{\partial J}{\partial w_{ij}} = -\varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$

- ▶ $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$



Backpropagation

- ▶ $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$
- ▶ $m_{ki} = m_{ki} + \alpha e_k \varphi'(u_k) z_i$



Backpropagation

- ▶ $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r e_k \varphi'(u_k) m_{ki}$
- ▶ $m_{ki} = m_{ki} + \alpha e_k \varphi'(u_k) z_i$
- ▶ Gradiante local
 - ▶ $\delta_k = e_k \varphi'(u_k)$



Backpropagation

- ▶ $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r \delta_k m_{ki}$
- ▶ $m_{ki} = m_{ki} + \alpha \delta_k z_i$
- ▶ Gradiante local
 - ▶ $\delta_k = e_k \varphi'(u_k)$



Backpropagation

- ▶ $w_{ij} = w_{ij} + \alpha \varphi'(u_i) x_j \sum_{k=1}^r \delta_k m_{ki}$
- ▶ $m_{ki} = m_{ki} + \alpha \delta_k z_i$
- ▶ **Gradiente local**
 - ▶ $\delta_k = e_k \varphi'(u_k)$
 - ▶ $\delta_i = \varphi'(u_i) \sum_{k=1}^r \delta_k m_{ki}$



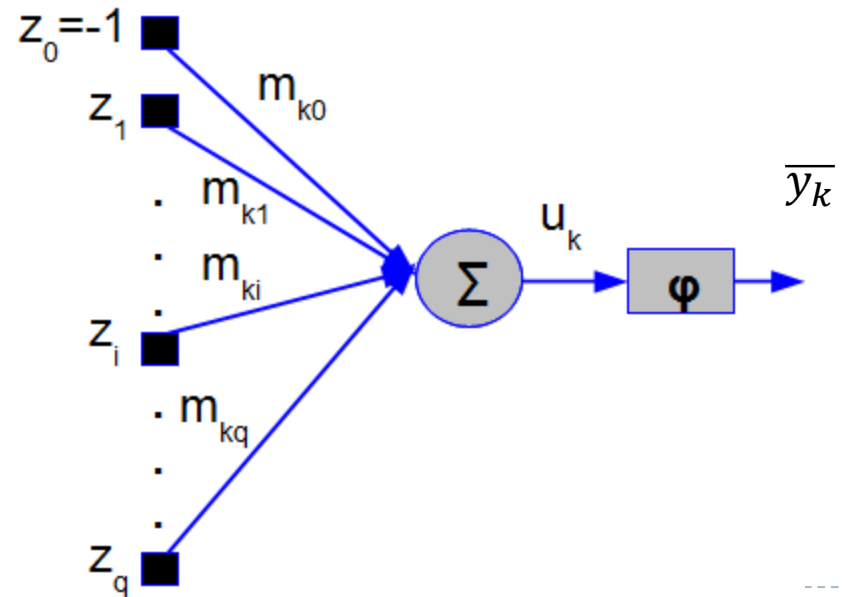
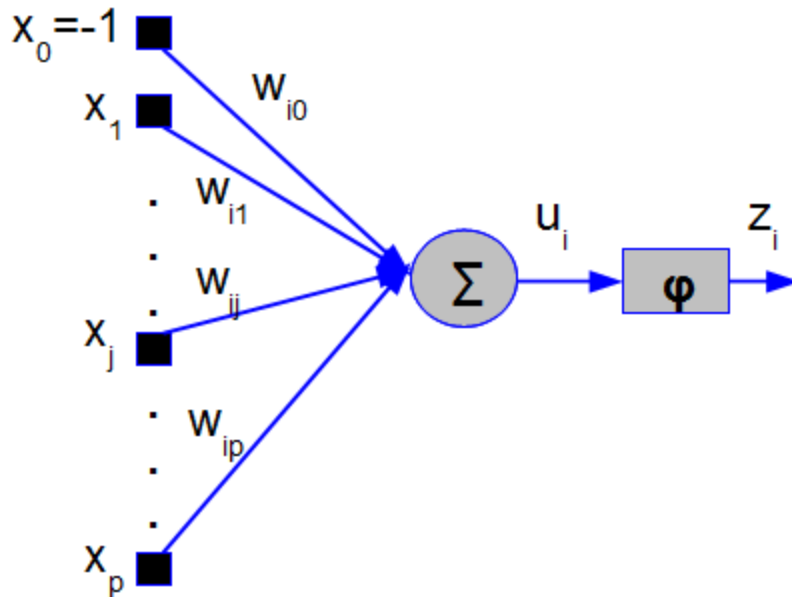
Backpropagation

- ▶ $w_{ij} = w_{ij} + \alpha \delta_i x_j$
- ▶ $m_{ki} = m_{ki} + \alpha \delta_k z_i$
- ▶ **Gradiente local**
 - ▶ $\delta_k = e_k \varphi'(u_k)$
 - ▶ $\delta_i = \varphi'(u_i) \sum_{k=1}^r \delta_k m_{ki}$



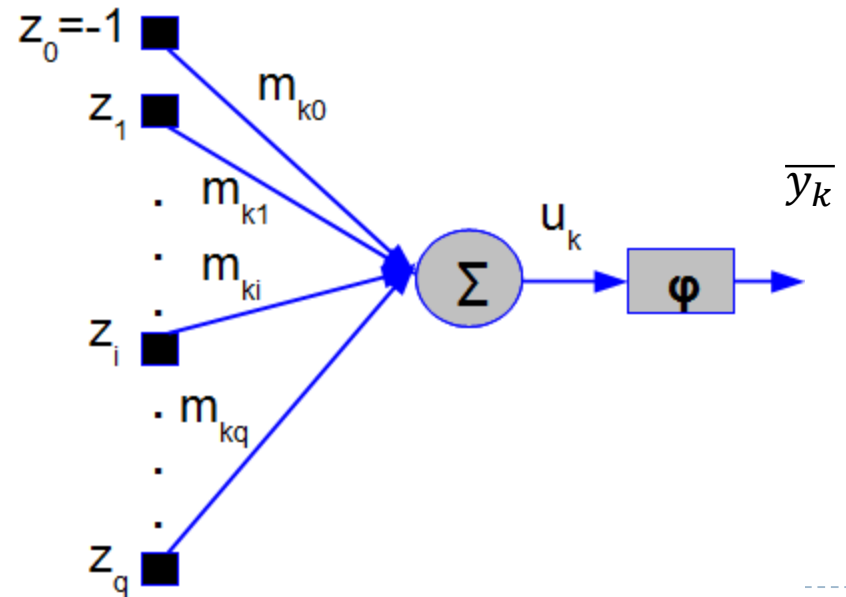
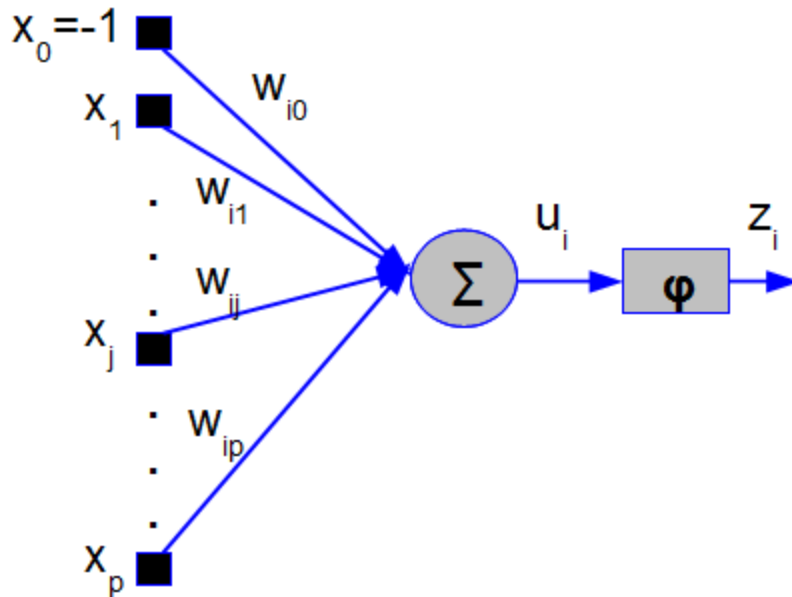
MLP - Treinamento

- ▶ Inicializa os pesos com valores entre 0 e 1
- ▶ Duas fases
 - ▶ Sentido direto
 - ▶ Sentido inverso



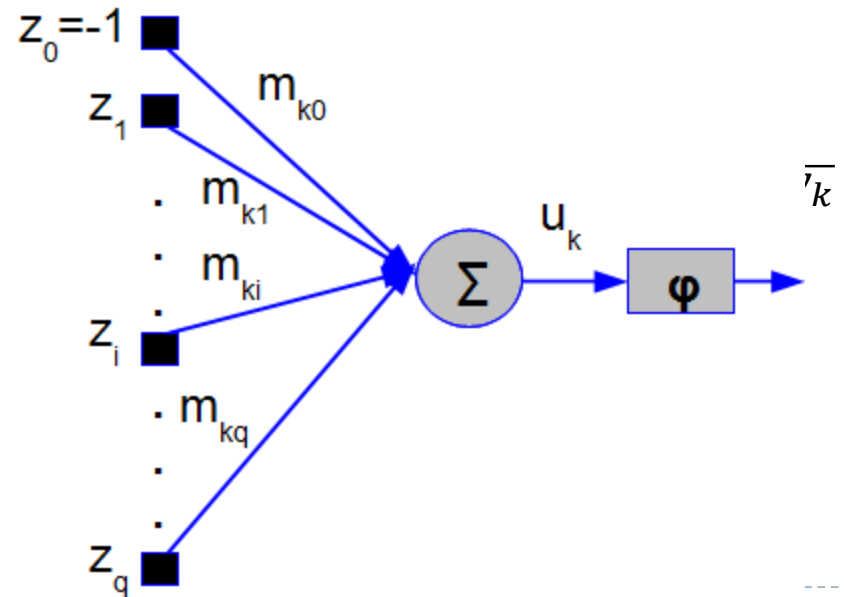
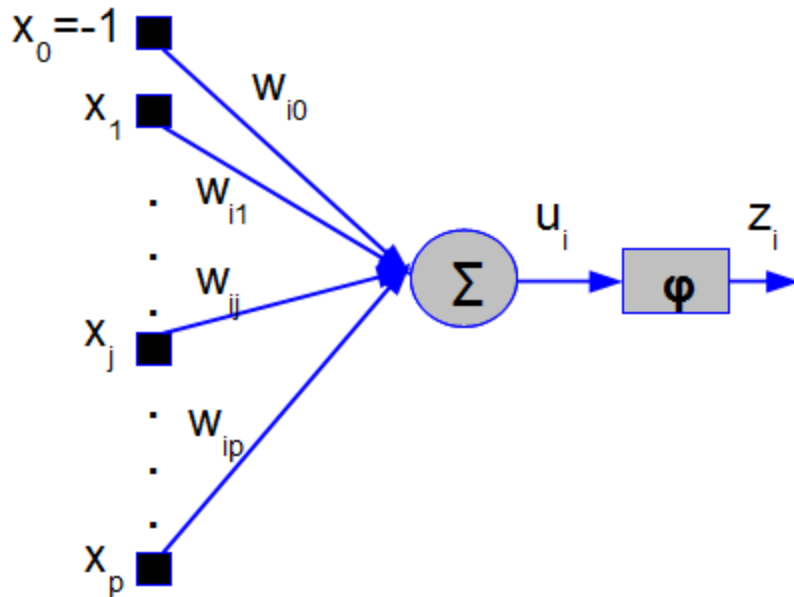
MLP - Treinamento

- ▶ Para cada amostra de treinamento
 - ▶ Sentido direto
 - ▶ Calcula $\overline{y_k}$
 - ▶ Calcula $e_k = y_k - \overline{y_k}$



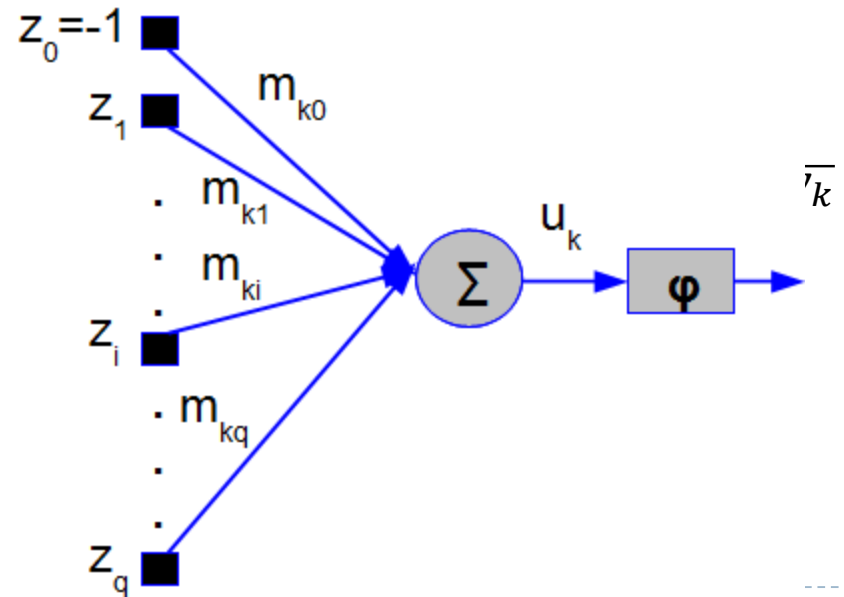
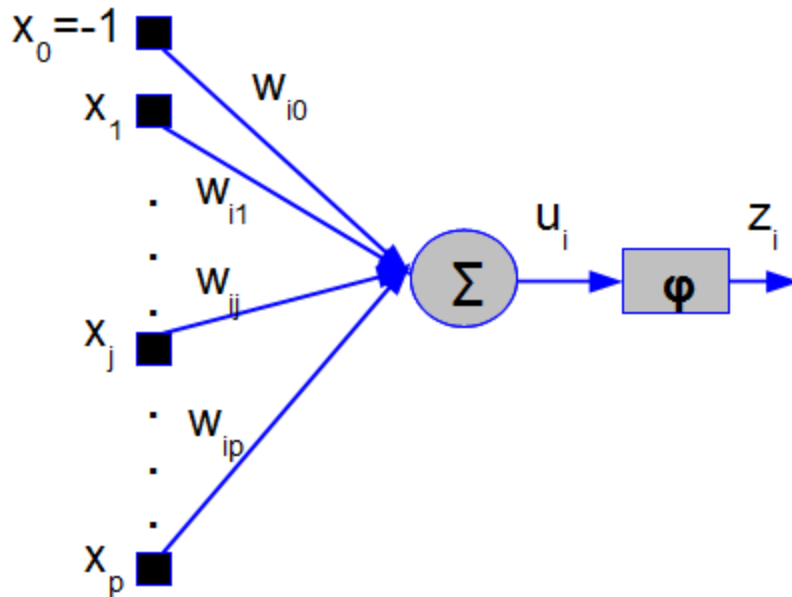
MLP - Treinamento

- ▶ Para cada amostra de treinamento
 - ▶ Sentido inverso
 - ▶ Calcula os gradientes locais
 - ▶ $\delta_k = e_k \varphi'(u_k)$
 - ▶ $\delta_i = \varphi'(u_i) \sum_{k=1}^r \delta_k m_{ki}$



MLP - Treinamento

- ▶ Para cada amostra de treinamento
 - ▶ Sentido inverso
 - ▶ Atualiza os pesos
 - ▶ $w_{ij} = w_{ij} + \alpha \delta_i x_j$
 - ▶ $m_{ki} = m_{ki} + \alpha \delta_k z_i$





Dúvidas ?