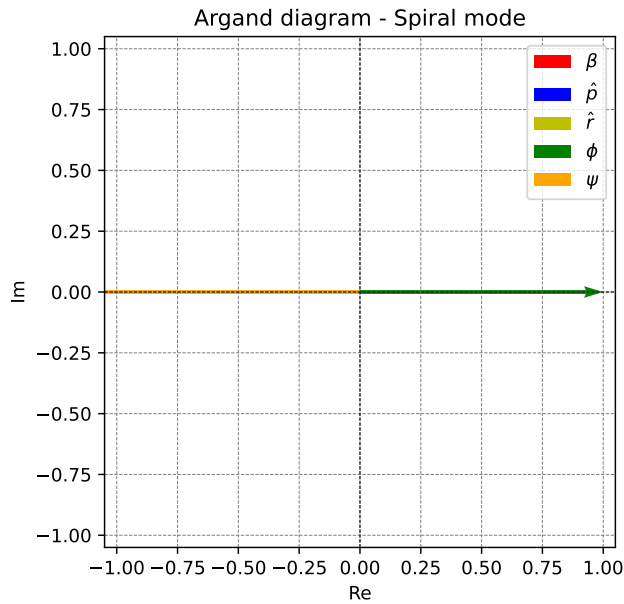
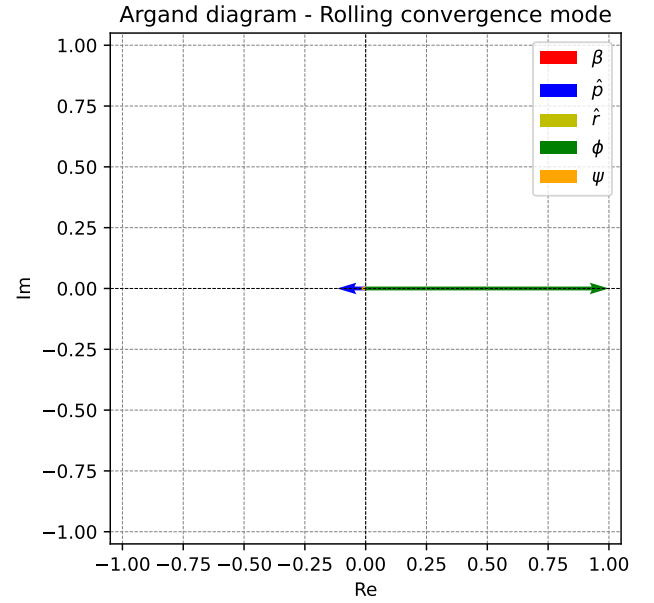
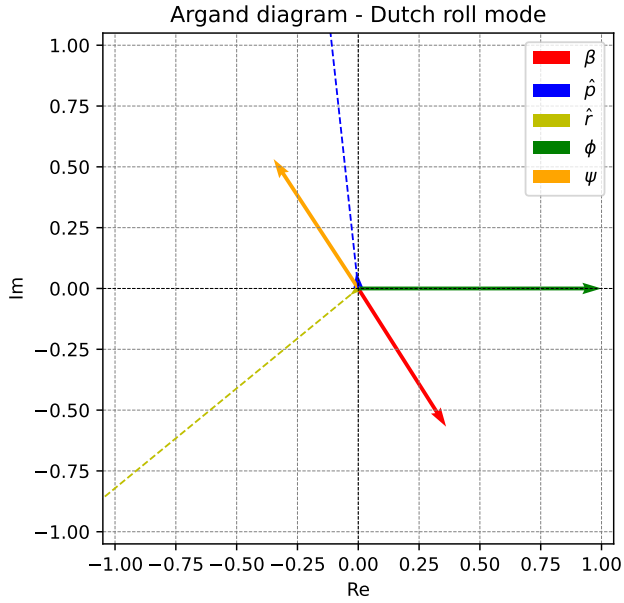


## Argand diagrams of aircraft lateral-directional modes

Equilibrium conditions:  $V_e = 500$  mph,  $\gamma_e = 0^\circ$ ,  $\rho_e = 0.458$  kg/m<sup>3</sup>,  $SM = 0.15$



In the Dutch roll mode, the state variables that change most are the sideslip angle  $\beta$ , the bank angle  $\Phi$ , and the azimuth angle  $\Psi$ , with  $\Psi$  leading  $\Phi$  by approximately  $130^\circ$  in phase.  $\beta$  and  $\Psi$  are almost equal and opposite. This mode is characterized by a lateral oscillation combined with a yawing motion, as the aircraft swings like a pendulum while rotating around the  $z$ -axis.

In the rolling convergence mode, the motion can be approximated as a single-degree-of-freedom rotation around the  $x$ -axis. The bank angle  $\Phi$  and the roll angular velocity  $p$  are the primary variables showing significant changes.

In the spiral mode, the bank angle  $\Phi$  and the azimuth angle  $\Psi$  change most, with opposite signs, and  $\Psi$  dominates, being more than six times greater than  $\Phi$ . The mode consists mainly of a yaw with almost zero sideslip and some roll. It is a banked turn with a variable radius of curvature, which increases if the mode is stable. Once the transient has ended, the aircraft returns to its initial direction with the wings level.