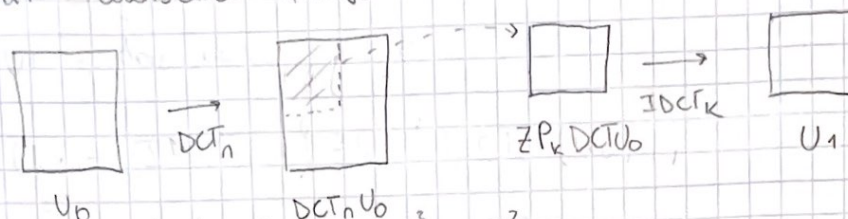


Elias Masquil

Image Denoising - Homework 2

Ex 5.1

n : initial image dimension
 k : image dimension at lower scale
 U_0 : initial image
 U_1 : downscaled image



$$U_1 = \underbrace{IDCT_k}_{k^2 \times k^2} \underbrace{ZP_k}_{k^2 \times n^2} \underbrace{DCT_n}_{n^2 \times n^2} \underbrace{U_0}_{n^2}$$

$$U_1 = \bar{U}_1 + \epsilon', \quad \epsilon' \sim N(0, \sigma'^2)$$

$$U_0 = \bar{U}_0 + \epsilon, \quad \epsilon \sim N(0, \sigma^2)$$

because DCT preserves noise distribution

$$\text{Var}(U_0) = \sigma^2 I_{n^2} \quad (\text{dimension } n^2 \times n^2)$$

ZP_k has the following form:

$$\begin{pmatrix} 1 & & & & & & & \\ & \ddots & & & & & & \\ & & 1 & & & & & \\ & & & \ddots & & & & \\ & & & & 1 & & & \\ & & & & & \ddots & & \\ & & & & & & 1 & \\ & & & & & & & \ddots \\ & & & & & & & & 1 \end{pmatrix}$$

We repeat the 1 k and 0 $n-k$ pattern until we fill the matrix

Note that $ZP_k ZP_k^T = I_{k^2}$ Ex: $(n=3, k=2)$

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{Var}(U_1) = DCT_k^T ZP_k DCT_n \sigma^2 I_{n^2} DCT_n^T ZP_k^T DCT_k$$

$$\text{Var}(U_1) = \sigma^2 DCT_k^T ZP_k I_{n^2} ZP_k^T DCT_k$$

$$\text{Var}(U_1) = \sigma^2 DCT_k^T I_{k^2} DCT_k$$

$$\text{Var}(U_1) = \sigma^2 I_{k^2} \rightarrow k^2 \times k^2 \text{ dimensions}$$

⊗ Since DCT is an isometry $DCT^T DCT = I_n$

Both covariance matrices have the same entries, but the original one is bigger. Although this change on the dimensions seen to play a role on the noise std, I don't see how it gets reduced by $\frac{k}{n}$

Elias Masquill

Image Denoising - Homework 2

Ex 6.1

$n(i)$ white noise $i \in \mathbb{Z}$

Discrete finite filter $a(i) \geq 0$ supported in $[-m, m]$

$$a * n(i) = \sum_{j=-m}^m n(i-j) a(j)$$

a) $\text{Var}(a * n(i))$?

white noise
(assuming 0 mean)

$$\text{Var}(X) = E(X^2) - E(X)^2$$

$$E[a * n(i)] = E\left[\sum_{j=-m}^m n(i-j) a(j)\right] = \sum \underbrace{E[n(i-j) a(j)]}_{0 \forall i} = 0$$

$$\begin{aligned} E[(a * n(i))^2] &= E\left[\sum_{j=-m}^m \sum_{k=-m}^m n(i-j) a(j) n(i-k) a(k)\right] \\ &= \sum_k \sum_j a(j) a(k) E[n(i-j) n(i-k)] \end{aligned}$$

Since n is white noise, all samples are independent from each other. Then, $E[n(i) n(j)] = E[n(i)] E[n(j)] = 0 \cdot 0 = 0$ if $i \neq j$

$$E[(a * n(i))^2] = \sum_{t=-m}^m a^2(t) E[n(t-m)^2] = \boxed{\sum_{-m}^m a^2(t) \sigma^2}$$

b) $\sum_i a(i) = 1$ and $a(i) \geq 0 \forall i$

Then $a(i)^2 \leq a(i) \forall i$

$$\sum a(i)^2 \leq \sum a(i) = 1$$

$$\Rightarrow \text{Var}[a * n(i)] = \sigma^2 \sum a(i)^2 \leq \sigma^2$$

c) $\min \sum a_i^2$

$$\text{s.t. } \sum a_i - 1 = 0$$

$$\mathcal{L}(a_i, \mu) = \sum a_i^2 + \mu(\sum a_i - 1)$$

$$\frac{\partial \mathcal{L}}{\partial a_i} = 2a_i + \mu = 0 \Rightarrow \mu = -2a_i$$

$$\sum a_i = 1 \Leftrightarrow -\frac{\sum \mu}{2} = 1 \Rightarrow \mu = \frac{-2}{2m+1}$$

$$\boxed{a_i = \frac{1}{2m+1}}$$

$a_i \geq 0 \checkmark$

(2)