

Bootload

- What is bootloader
- Bootloader is the first execute program on SOC (?)
- Boot : short bootstrap
 - Initialize basic of SOC (CPU, RAM, CLK)
- Down loader
 - Download Image or Application to ram from host (developer host PC)
- Loader
 - Load OS to ram form volatile memory

All kinds of embedded Linux bootloader

- U-boot
- UEFI
- Redboot
- Stubby (Linaro) ...
- Anyway, they are same target
 - Load and boot OS to RAM from storage

Concepts of the Boot Loader

- Boot Loader is varied from CPU to CPU, from board to board.
- All the system software and data are stored in some kind of nonvolatile memory.
- Operation Mode of Boot Loader
 - Boot: Initialize basic of SOC
 - Load: load OS to RAM

Introduce U-boot

U-boot

- Das U-Boot -- the Universal Boot Loader
- http://www.denx.de/wiki/U-Boot
- GitHub for u-boot
- Open Source follow GPL
- Supply many CPU
 - PPC, ARM, x86, MIPS, AVR32 ...
- Supply basic periphery devices
 - UART, Flash, SD/MMC



- Arch
 - Many types CPU: Arm, mips, i386 ...
- Board
 - Many types develop board : Samsung, ti, davinci ...
- Tools
 - Make Image (u-boot, linux) or S-Record image tool
- Drivers
 - Some HW control code

- Common
 - Major command and relation environment setting source code
- Api
- Implement unrelated hardware code
- nand_spl, onenand_ipl
 - Related nand/onenand flash control
- Example
 - Standalone application

- Post
 - Supply Power On Self Test function
- Fs
- Supply file system: fat, jffs2, ext2, cramfs
- Lib
- General public library: CRC32/16, bzlib, ldiv...
- Disk
 - Supply disk driver and partition handling

u-boot directory structure about tiny4412

arch arch	11 items folder	
▼ 📠 arm	4 items folder	
▼	15 items folder	
▶ 📠 arm11	4 items folder	
▶ \overline arm720t	8 items folder	
▶ 📠 arm920t	13 items folder	
▶ \overline arm925t	7 items folder	
▶ \overline arm926ejs	16 items folder	
▶ iii arm946es	5 items folder	
▶ \overline arm1136	7 items folder	
▶ \overline arm1176	7 items folder	
▶ iii arm_intcm	5 items folder	
▼ \overline armv7	15 items folder	
▼	18 items folder	
ace_sha1.c	4.1 kB C source code	
clock.c	1.6 kB C source code	
gpio.c	125.9 kB C source code	
i2c.c	26.7 kB C source code	
irom_copy.c	6.0 kB C source code	
Makefile	1.9 kB Makefile	
movi_partition.c	3.4 kB C source code	
nand.c	28.5 kB C source code	
nand_cp.c	3.5 kB C source code	
nand write bl.c	6.9 kB C source code	

u-boot directory structure about tiny4412

▼ ioard	282 items folder
▼ samsung	12 items folder
▶ i goni	6 items folder
▶	5 items folder
▶	5 items folder
▶	10 items folder
▶	8 items folder
▶ i smdk5250	11 items folder
▶ i smdk6400	5 items folder
▶ <u>i</u> smdk6450	6 items folder
▶ iii smdkc100	6 items folder
▶ iii smdkv210	6 items folder
▶ iii smdkv310	7 items folder
▼ iny4412	10 items folder
clock_init_tin	y4412.S 5.2 kB C source code
config.mk	361 bytes plain text document
lowlevel_init.	S 15.4 kB C source code
Makefile	1.6 kB Makefile
mem_init_tin	y4412.S 6.4 kB C source code
pmic.c	10.4 kB C source code
tiny4212_val.	h 11.2 kB Cheader
tiny4412.c	6.6 kB C source code
tiny4412_val.	h 10.2 kB Cheader

u-boot directory structure about tiny4412

- arch/arm/cpu/armv7/exynos/
 - Samsung exynos CPU related
 - Clock, i2c, irom, mmc, emmc ...
- board/samsung/tiny4412/
 - Tiny4412 EVB related
 - Low level init, memory init, link script ...
- Common
 - Tiny4412 u-boot command related
- include/configs/tiny4412.h
 - Tiny4412 EVB build configure related

How to build u-boot

- Clear
 - #make distclean
- Configure
 - #make board_config <tiny4412_config>
- Build
 - #make -j4
- Result of build
 - u-boot : ELF format file
 - u-boot.bin : raw data binary

Link Script

- u-boot.lds
 - board/samsung/tiny4412/u-boot.lds
 - The link script will pack all into binary.
 - The binary file will put in storage.
 - The start address (.TEXT) can be modified.
- CONFIG_SYS_TEXT_BASE
 - board/samsung/tiny4412/config.mk
 - Check u-boot.map

u-boot.map

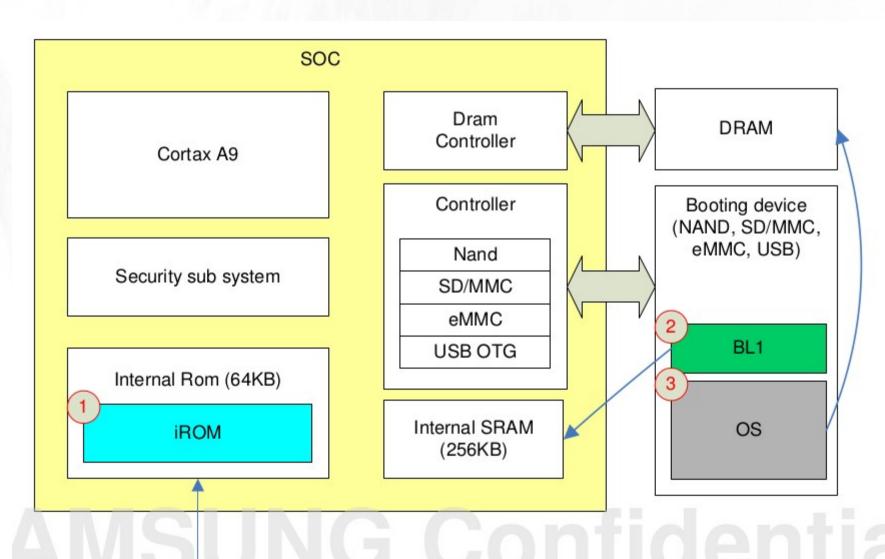
```
0x00000000
                                           = 0x0
               0x00000000
                                          \cdot = ALIGN (0x4)
               0xc3e00000
                              0x2d6e8
.text
arch/arm/cpu/armv7/start.o(.text)
                                0x460 arch/arm/cpu/armv7/start.o
.text
               0xc3e00000
                                          start
               0xc3e00040
                                          _end_vect
                                          _TEXT_BASE
               0xc3e00040
               0xc3e00044
                                          _bss_start_ofs
               0xc3e00048
                                          bss end ofs
                                          IRQ STACK START IN
               0xc3e0004c
               0xc3e00074
                                          relocate code
board/samsung/tiny4412/libtiny4412.o(.text)
               0xc3e00460
                               0x154c board/samsung/tiny4412/libtiny4412.o
.text
               0xc3e00464
                                          cache init
                                          lowlevel init
               0xc3e00468
               0xc3e0064c
                                          uart_asm_init
               0xc3e0085c
                                          nand_asm_init
                                          theLastJump
               0xc3e00930
                                          mem_ctrl_asm_init
               0xc3e00a30
                                          system_clock_init
               0xc3e00d80
                                          board_init
               0xc3e00fec
               0xc3e010f4
                                          dram_init
               0xc3e010fc
                                          dram_init_banksize
                                          board_eth_init
               0xc3e01174
                                          checkboard
               0xc3e0117c
                                          board_late_init
               0xc3e0119c
```

Link Script

arch/arm/cpu/armv7

```
OUTPUT FORMAT("elf32-littlearm", "elf32-littlearm", "elf32-littlearm")
OUTPUT ARCH(arm)
ENTRY( start)
SECTIONS
      = 0x000000000;
    \cdot = \cdot ALIGN(4);
    .text →:
        arch/arm/cpu/armv7/start.o → (.text)
        *(.text)
   → . ·= ·ALIGN(4);
   → .rodata : { *(SORT BY ALIGNMENT(SORT BY NAME(.rodata*))) }
    . = ALIGN(4);
    .data : {
        *(.data)
    . = ALIGN(4);
      u boot cmd start = .;
    .u boot cmd : { *(.u boot cmd) }
    u boot cmd end = .;
    . = ALIGN(4);
    .rel.dyn::{
          rel dyn start = .;
        *(.rel*)
         rel_dyn_end = .;
    .dynsym : {
          dynsym_start = .;
        *(.dynsym)
```

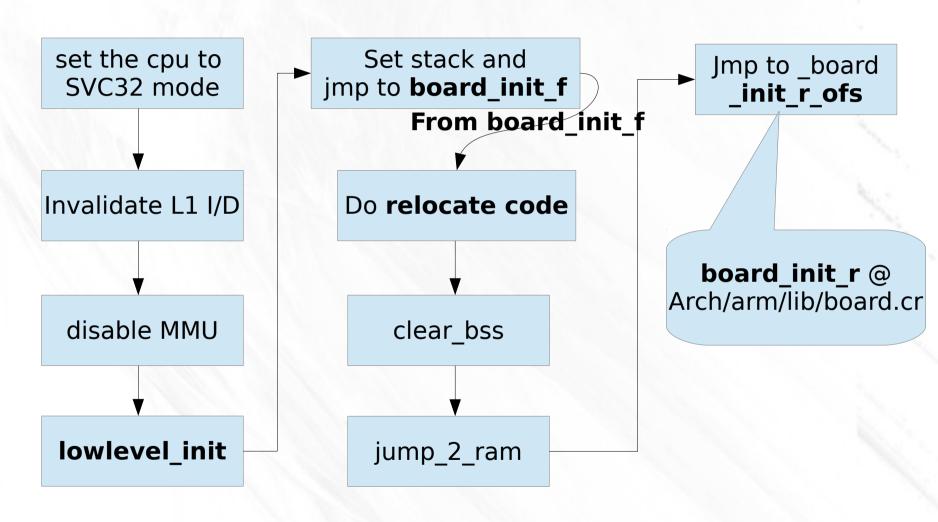
Exynos 4412 Booting Sequence



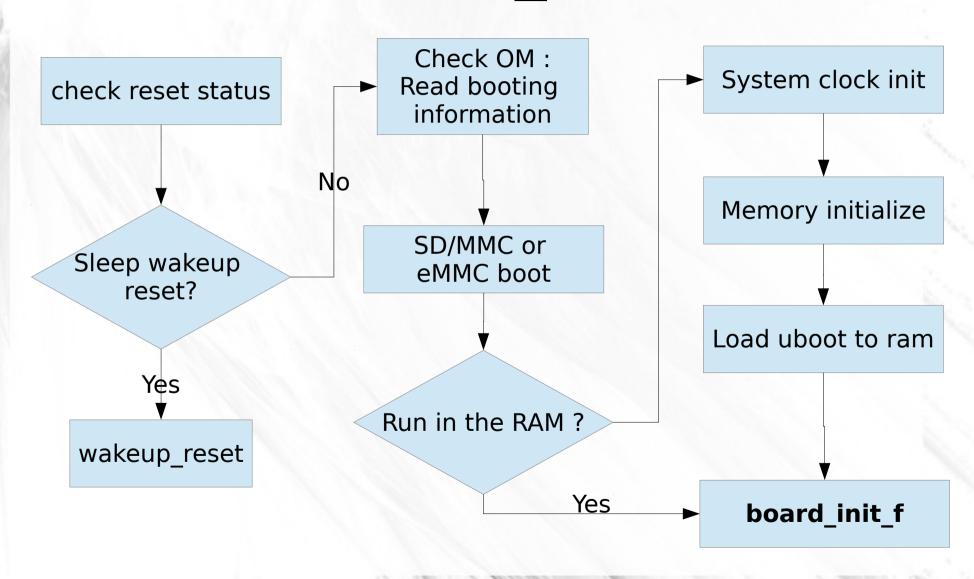
OM (Operating Mode) pin

U-boot initialize sequence

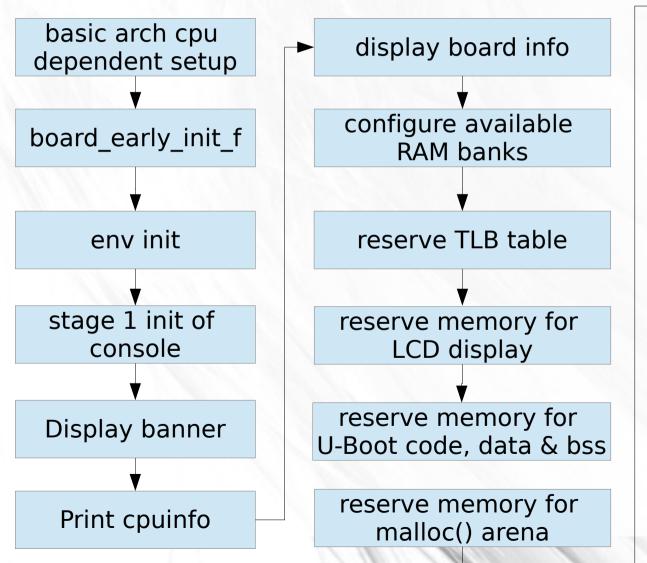
U-boot start up sequence

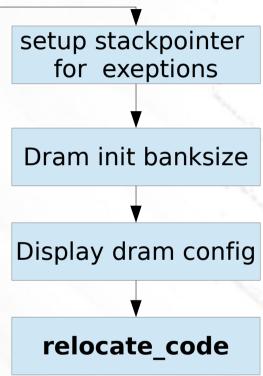


lowlevel_init

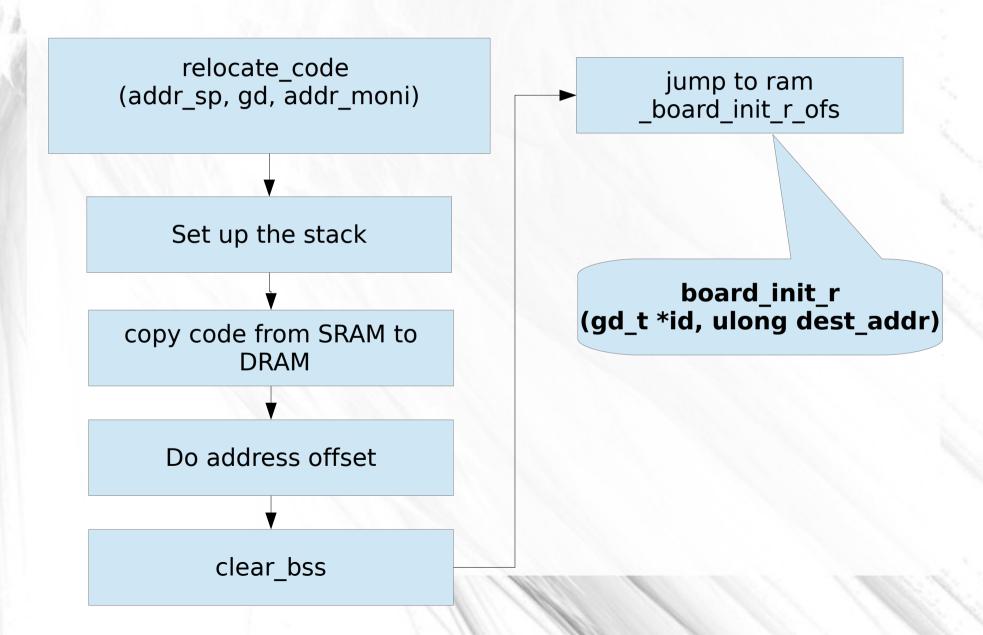


board_init_f



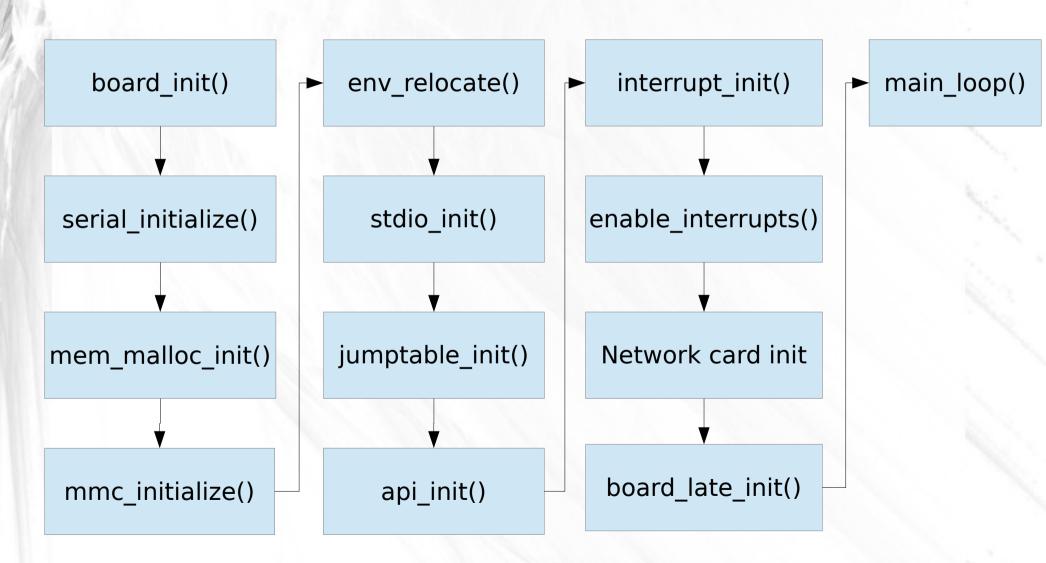


relocate code



board_init_r

board_init_r



Operating U-boot

Operating U-boot

- Understand and use command
- Understand and modify parameters
- Run Application

Add Feature

- Add command
 - common/
- Add driver
 - driver
- Add application
 - example
- boards.cfg

Add Command

How to create a command?

- Directory
 - common/
 - cmd_mmc.c, cmd_bootm.c, cmd_help.c
- U_BOOT_CMD(name,maxargs,rep,cmd,usage,help)
 - include/command.h

Add application

- How to add a application
- Directory
 - example
- Api
- Standalone
- arch/arm/config.mk
 - STANDALONE_LOAD_ADDR

Add a driver

- How to add a driver
- Directory
 - driver/
 - drivers/gpio/s5p_gpio.c

Boot Linux kernel

Boot Linux kernel

- Boot command
 - Bootm
 - common/cmd_boot.c
- ulmage
 - Tool: mkimage
- Linux kernel ATAG

ulmage

tools/mkimage

```
Usage: tools/mkimage -l image
      -I ==> list image header information
    tools/mkimage [-x] -A arch -O os -T type -C comp -a addr -e
ep -n name -d data file[:data file...] image
      -A ==> set architecture to 'arch'
      -O ==> set operating system to 'os'
      -T ==> set image type to 'type'
      -C ==> set compression type 'comp'
      -a ==> set load address to 'addr' (hex)
      -e ==> set entry point to 'ep' (hex)
      -n ==> set image name to 'name'
      -d ==> use image data from 'datafile'
      -x ==> set XIP (execute in place)
    tools/mkimage [-D dtc options] -f fit-image.its fit-image
```

ulmage

- ./mkimage
- -A arm
- -O linux
- -T kernel
- -C none
- -a **60008040**
- -е **60008000**
- -d zImage\$output name

How to jump to kernel

- Use boot command
 - common/cmd bootm.c
 - command entry
 - int do_bootm (...)
 - boot os fn *boot fn;
- do_bootm_linux(...)
 - arch/arm/lib/bootm.c
- kernel_entry(0, machid, bd->bi_boot_params);
 - 0
 - Mach ID
 - atag

Linux Atag

Kernel parameters

Tag name	Value	Size	Description
ATAG_NONE	0x00000000	2	Empty tag used to end list
ATAG_CORE	0x54410001	5 (2 if empty)	First tag used to start list
ATAG_MEM	0x54410002	4	Describes a physical area of memory
ATAG_VIDEOTEXT	0x54410003	5	Describes a VGA text display
ATAG_RAMDISK	0x54410004	5	Describes how the ramdisk will be used in kernel
ATAG_INITRD2	0x54420005	4	Describes where the compressed ramdisk image is placed in memory
ATAG_SERIAL	0x54410006	4	64 bit board serial number
ATAG_REVISION	0x54410007	3	32 bit board revision number
ATAG_VIDEOLFB	0x54410008	8	Initial values for vesafb-type framebuffers
ATAG_CMDLINE	0x54410009	2 + ((length_of_cmdline + 3) / 4)	Command line to pass to kernel



Build u-boot

- Clean
 - #make distclean
- modify configure
 - include/configs/tiny4412.h
- Do EVB configure
 - #make tiny4412_defconfig

Download and boot kernel