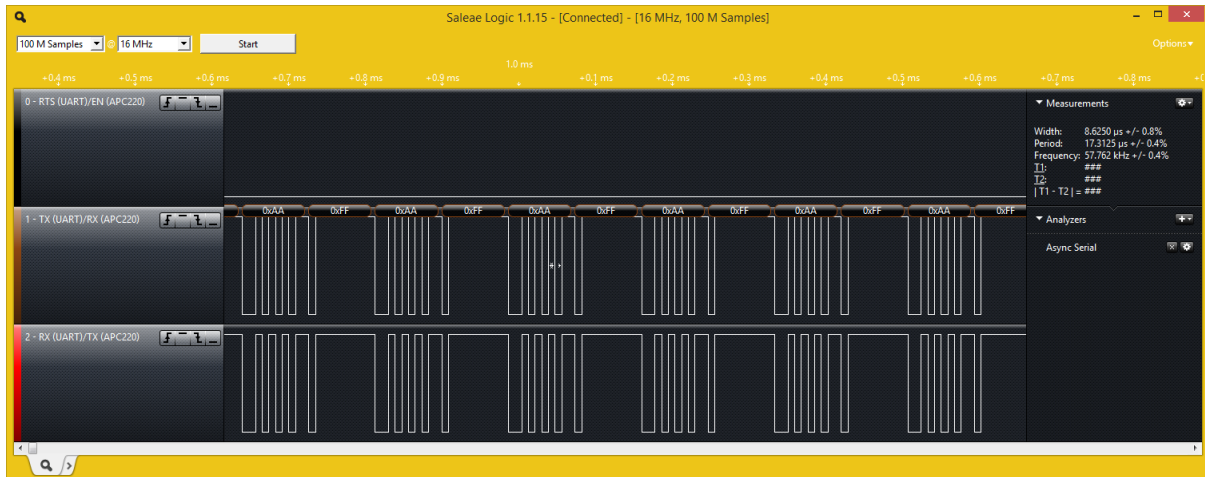


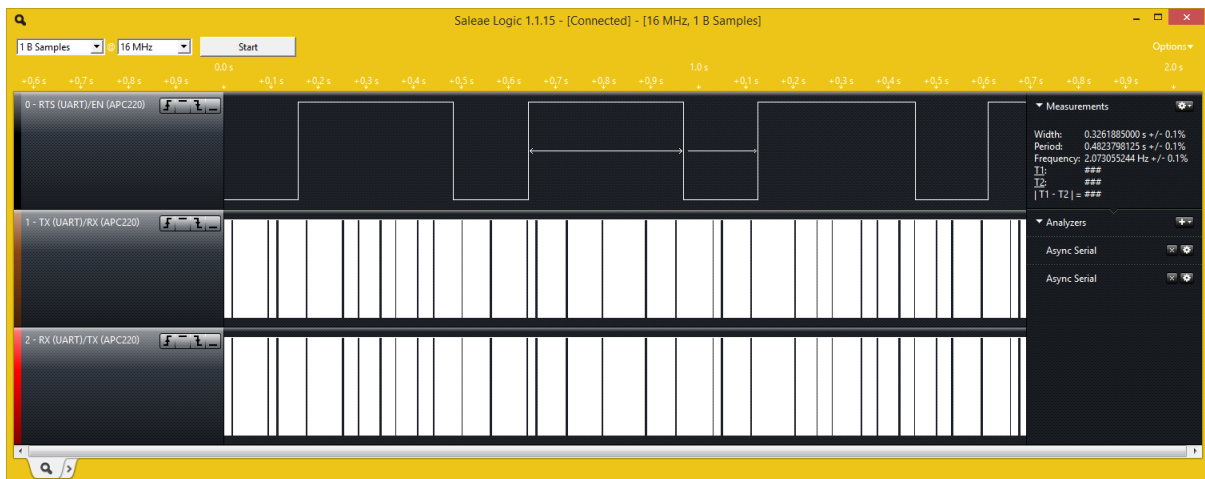
# Analysis of APC220 RF Magic

## No APC200 Radio Connected

With no APC220 radio connected to the UART and RF Magic running, we get this:-



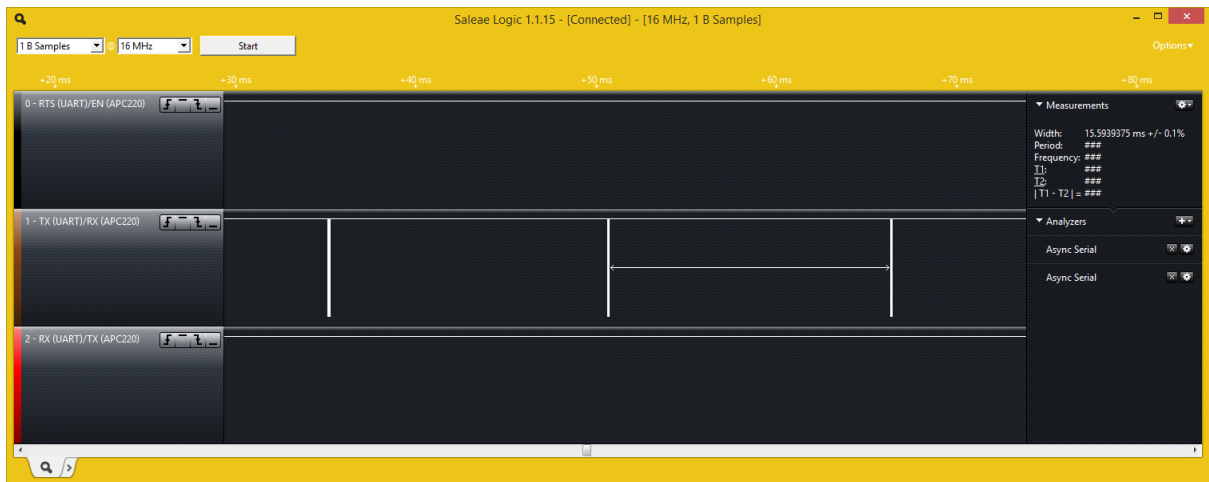
- Sending 0xAA 0xFF at 115,200 baud full line rate
- The signal on the UART RX channel is just crosstalk
- RTS pin on UART alternating 326ms on/156ms off:-



## APC220 Radio Connected and Detected by RF Magic

- As soon as APC220 radio is connected and detected, RTS stays high





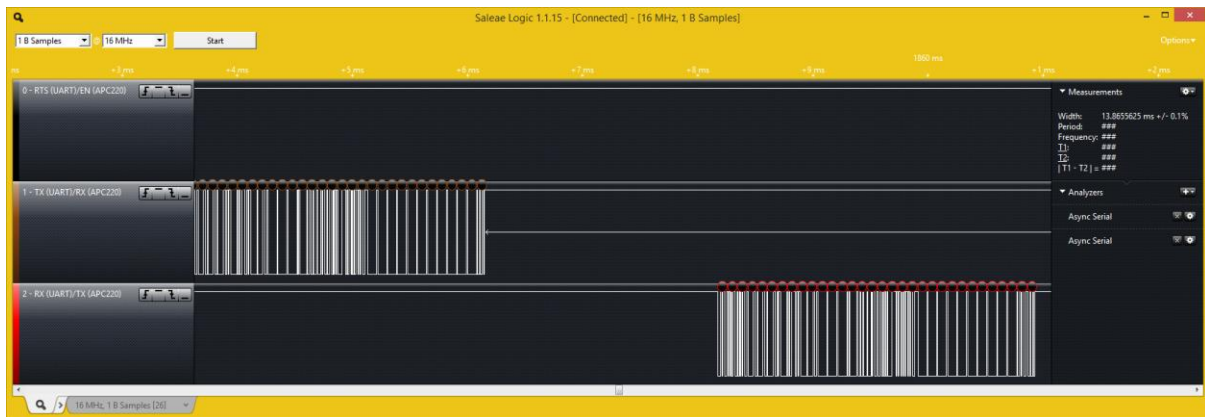
## Commands

### Read

To read the current radio settings, send a single byte of 0xCC. The APC220 will respond with a block of 32 bytes as follows:-

0	Frequency in KHz, ASCII-encoded
1	
2	
3	
4	
5	
6	Radio baud rate (sometimes an ASCII value, sometimes a binary value ☹; 0=1200, 1=2400, 2=4800, 3=9600, 4=19200)
7	RF power (ASCII value, 0...9)
8	Serial baud rate (ASCII value, 0=1200, 1=2400, 2=4800, 3=9600, 4=19200, 5=38400, 6=57600)
9	Serial parity (ASCII value, 0=none, 1=odd, 2=even)
10	Always 0
11	Always 0
12	Network ID (16 bits, 12=MSB, 13=LSB)
13	
14	Node ID (MSB -> LSB)
15	
16	
17	
18	





## Notes

- The fact that the first 10 bytes of the response to a Read command are ASCII (i.e. high nybble=3) and indeed the very first byte is always 0x34 is useful: it can be used to reliably detect the start of a the command response if it is not possible to reliably flush the serial buffer after issuing the Read command (0xCC)

## The EN pin

- The EN pin on the APC220 **must** be pulled high during normal operation. If it is low, it will neither transmit nor receive data.
- Problem is that most terminal clients will leave it low if RTS/CTS flow-control is disabled. Need to either
  - Separate the EN pin out and pull it high
  - Use custom communications software that allows RTS (which is the pin on the UART that connects to EN) to be set high
- When it is low, the APC220 is in “programming mode” which allows AT-type commands to be sent to it to program it (less capable than RF Magic, though)

## Python version of RF Magic

- Requires Python version  $\geq 2.7$
- Requires pyserial module
  - “easy\_install pyserial” or “pip pyserial”, depending on platform

## Read

```
C:\CanSat\rfmagic>python rfmagic.py read com3
Detected APC220 radio. Reading current settings...
```

```
Read():
Frequency      = 418.000
Radio Baud Rate = 9600
RF Power       = 9
Serial Baud Rate = 9600
Serial Parity   = None
```

done!

```
C:\CanSat\rfmagic>python rfmagic.py read -v com3
Detected APC220 radio. Reading current settings...
```

```
Read():
Frequency      = 450.000
Radio Baud Rate = 2400
RF Power       = 9
Serial Baud Rate = 2400
Serial Parity   = None
Network ID     = 0x0001
Node ID        = 0x12345678abcd
Radio ID (fixed) = 0x9a
```

done!

```
C:\CanSat\rfmagic>python rfmagic.py write -h
```

```
usage: rfmagic.py write [-h]
                        writeserialport frequency {0,1,2,3,4,5,6,7,8,9}
                        {1200,2400,4800,9600,19200}

positional arguments:
  writeserialport      Serial port
  frequency            Frequency (NNN.N : 418.0 - 455.0 in 200KHz steps)
  {0,1,2,3,4,5,6,7,8,9}
                      RF power
  {1200,2400,4800,9600,19200}
                      Baud rate (line and radio)
```

```
optional arguments:
  -h, --help            show this help message and exit
```

```
C:\CanSat\rfmagic>python rfmagic.py write com3 450.0 9 2400
```

```
Detected APC220 radio. Reading current settings...
```

```
Read():
Frequency      = 418.000
Radio Baud Rate = 9600
RF Power       = 9
Serial Baud Rate = 9600
Serial Parity   = None
```

Writing new settings to radio...these are the values returned during the "write" process:

```
Write(): f=450.000MHz, radio baud=2400, power=9, serial baud=2400, parity=None
Frequency      = 450.000
Radio Baud Rate = 2400
```

```
RF Power      = 9
Serial Baud Rate = 2400
Serial Parity  = None

Reading (hopefully) updated settings from radio...
Read():
Frequency      = 450.000
Radio Baud Rate = 2400
RF Power      = 9
Serial Baud Rate = 2400
Serial Parity  = None

done!
```