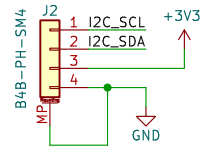


Libre Solar BMS for 3–16 cells

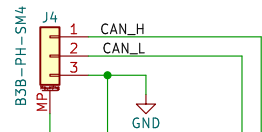
Based on TI bq76952 and ESP32-C3

Development funded by
EnAccess Foundation.
<https://enaccess.org>

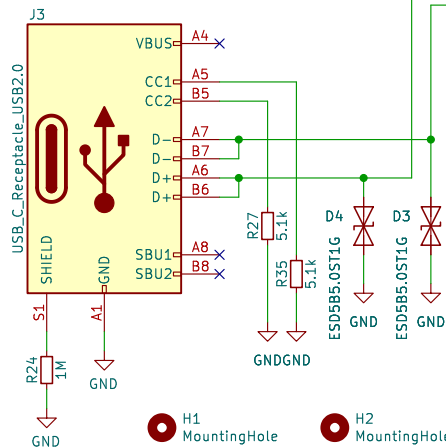
Internal I2C



CAN / RS-485

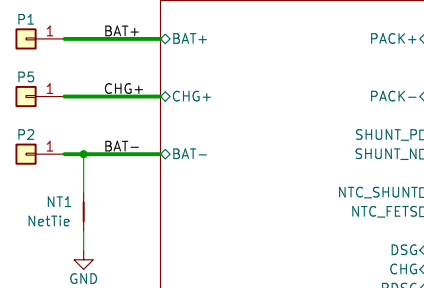


USB



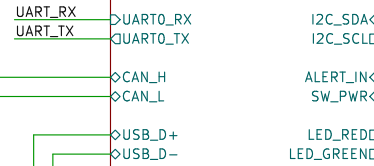
- H1 MountingHole
- H2 MountingHole
- H3 MountingHole
- H4 MountingHole
- H5 MountingHole
- H6 MountingHole

Power Part



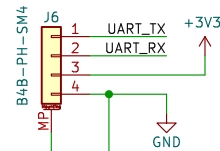
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ESP32-C3 MCU

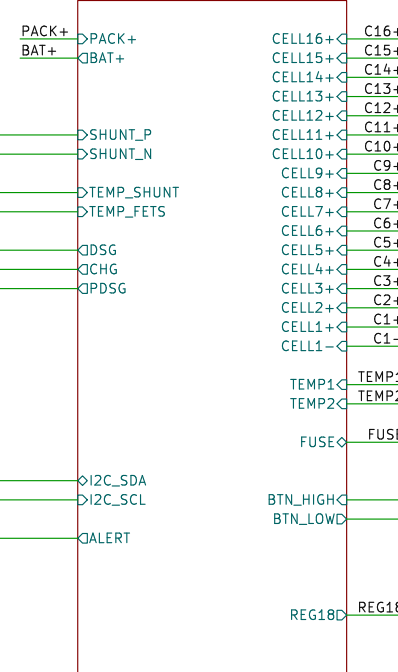


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Serial

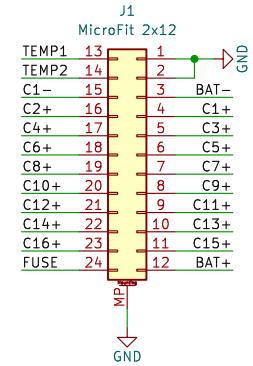


BQ76952



File: bq76952.kicad_sch

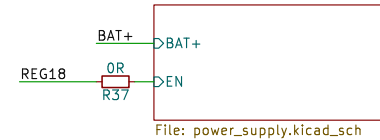
Cell Connector



On/Off button



Power Supply



File: power_supply.kicad_sch

FID1 Fiducial FID2 Fiducial

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Libre Solar Technologies GmbH
Author: Martin Jäger

Website: <https://libre.solar>



Sheet:
File: bms-c1.kicad_sch

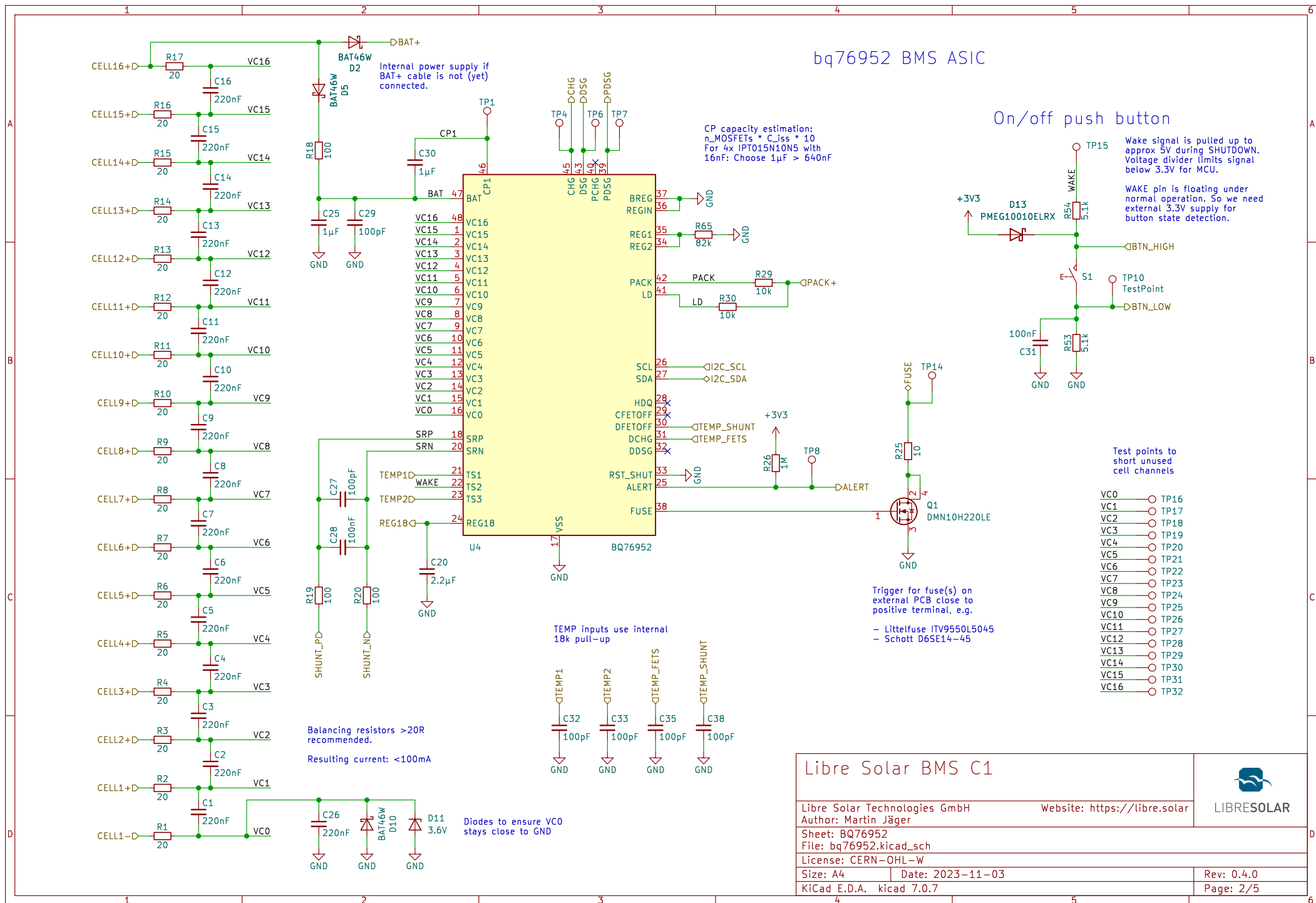
License: CERN-OHL-W

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Size: A4 Date: 2023-11-03

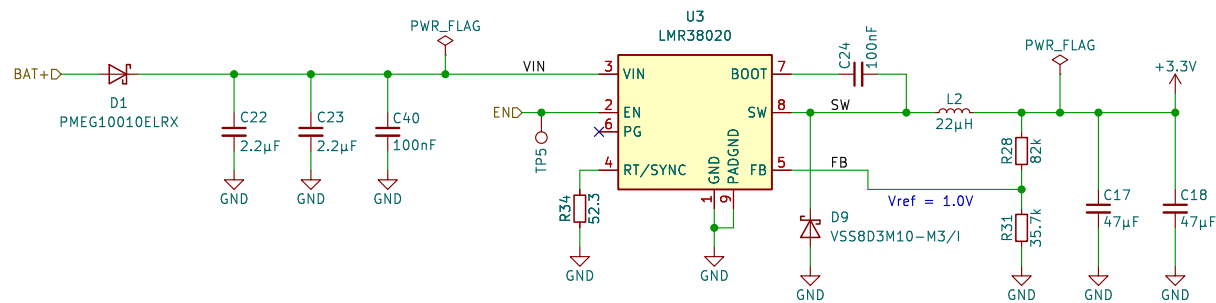
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Battery to 3.3V (SMPS)

ESP32-C3 requires power supply with at least 500 mA



Layout for 500 kHz, 1A output

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Author: Martin Jäger

Website: <https://libre.solar>



Sheet: Power Supply
File: power_supply.kicad_sch

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Size: A4 Date: 2023-11-03

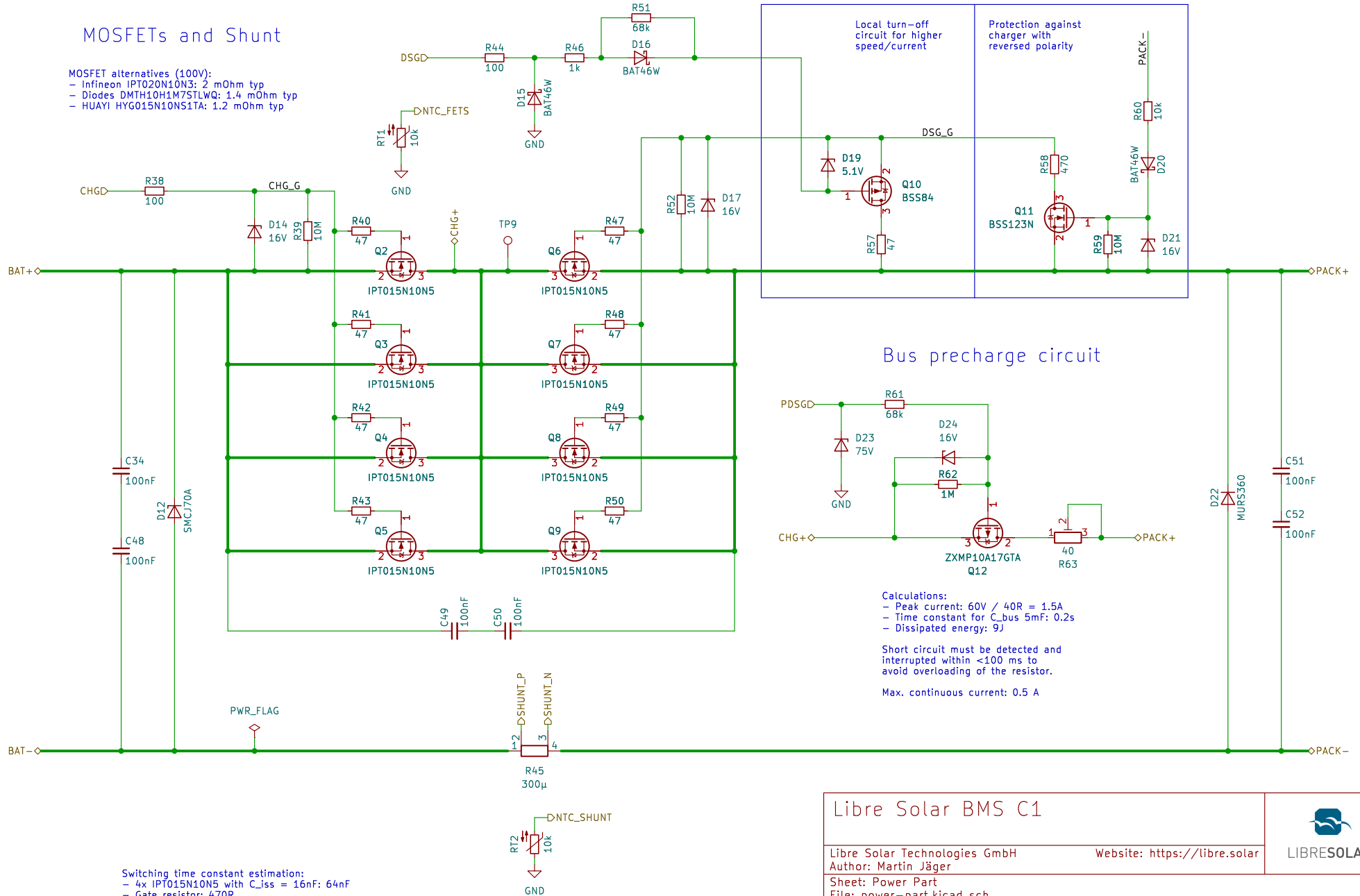
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MOSFETs and Shunt

MOSFET alternatives (100V):
 - Infineon IPT020N10N3: 2 mOhm typ
 - Diodes DMTH10H1M75TLWQ: 1.4 mOhm typ
 - HUAYI HYG015N10NS1TA: 1.2 mOhm typ



Switching time constant estimation:
 - 4x IPT015N10N5 with C_{iss} = 16nF: 64nF
 - Gate resistor: 470R
 - Time constant: R*C = 30us

Calculations:
 - Peak current: 60V / 40R = 1.5A
 - Time constant for C_{bus} 5mF: 0.2s
 - Dissipated energy: 9J

Short circuit must be detected and interrupted within <100 ms to avoid overloading of the resistor.

Max. continuous current: 0.5 A

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ESP32-C3 module

U5
ESP32-C3-MINI-1

ESP32-C3-MINI-1

EN/CHIP_PU

GPIO2/ADC1_CH2

GPIO3/ADC1_CH3

GPIO0/ADC1_CH0/XTAL_32K_P

GPIO1/ADC1_CH1/XTAL_32K_N

GPIO10

GPIO4/ADC1_CH4

GPIO5/ADC2_CH0

GPIO6

GPIO7

GPIO8

GPIO9

GPIO18/USB_D-

GPIO19/USB_D+

GPIO20/U0RXD

GPIO21/U0TXD

3V3

NRST

ALERT_IND

SW_PWRD

LED_GREEN

LED_RED

CAN_STB

CAN_RX

CAN_TX

RS485_DE

RS485_RE

I2C_SDA

I2C_SCL

USB_D-

USB_D+

UART0_RXD

UART0_TXD

TP12 TestPoint

TP13 TestPoint

I2C_SDA

I2C_SCL

TP2

TP3

D8 PESD2CANFD

RS-485 Transceiver

U2 SN65HVD75

CAN_RX

RS485_RE

RS485_DE

CAN_TX

CAN_L

CAN_H

Libre Solar BMS C1

Libre Solar Technologies GmbH

Author: Martin Jäger

Sheet: ESP32-C3 MCU

File: esp32-c3.kicad_sch

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Date: 2023-11-03

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LIBRESOLAR

The schematic diagram illustrates a CAN transceiver circuit. At the top, a +3.3V supply is connected to a 100nF capacitor (C36) and then to ground (GND). The transceiver IC, U1 (SN65HVD230), is powered by a +3.3V supply connected to its VCC pin (pin 3). Its GND pin (pin 2) is connected to ground. The IC's D pin (pin 1) is connected to CAN_TX, and its R pin (pin 4) is connected to CAN_RX. The RS pin (pin 5) is connected to CAN_STB through a resistor R21. The IC's CANH pin (pin 7) and CANL pin (pin 6) are connected to the CAN bus lines. The CANH line is connected to a 62Ω resistor (R56) and a 62Ω resistor (R64) in series with a 100nF capacitor (C37) to ground. The CANL line is connected to a 62Ω resistor (R56) and a 62Ω resistor (R64) in series with a 100nF capacitor (C37) to ground. The CANH line is also connected to a terminal block labeled TP2 and CAN_H. The CANL line is also connected to a terminal block labeled TP3 and CAN_L. The IC's Vref pin (pin 8) is connected to ground. The IC's SHDN pin (pin 9) is connected to ground through a diode (D8, PESD2CANFD) and a 100nF capacitor (C37) to ground. The SHDN pin is also connected to a terminal block labeled TP3 and CAN_L.

Rs can be used for slope-control, configured using the CAN_STB series resistor.

TCAN334 can be used as an alternative part: Pin 5 of TCAN334 is used for SHDN, but has an internal pull-down and can be left floating.

TCAN334 can be used as an alternative part:
Pin 5 of TCAN334 is used for SHDN, but has
an internal pull-down and can be left floating.

RS-485 Transceiver

Re-uses MCU pins and bus from CAN -> only CAN or RS-485 can be used in one application.

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