## get Markov Equivalent Class

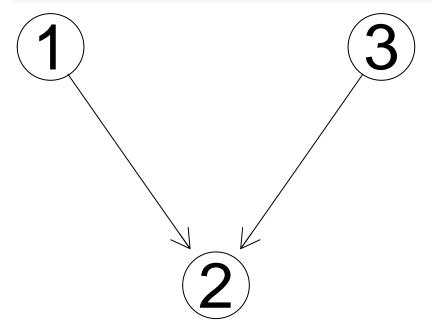
## Obtaining the Markov equivalence class using pealg

A quick document to check if my version of R and pcalg (or other dependencies) is causing a problem. First I create a non-collider 1->2->3 dag structure and a collider structure 1->2<-3.

```
library(pcalg)
p <- 3
# non-collider
(dag_NC_mat \leftarrow matrix(c(0,0,0,1,0,0,0,1,0),p,p))
        [,1] [,2] [,3]
## [1,]
                 1
## [2,]
           0
## [3,]
                 0
                      0
dag_NC <- as(dag_NC_mat, "graphNEL")</pre>
# collider
(dag_C_mat \leftarrow matrix(c(0,0,0,1,0,1,0,0,0),p,p))
##
        [,1] [,2] [,3]
## [1,]
## [2,]
           0
                 0
                      0
## [3,]
           0
                      0
dag_C <- as(dag_C_mat, "graphNEL")</pre>
Lets look at the graphs:
plot(dag_NC)
##
## Attaching package: 'BiocGenerics'
## The following objects are masked from 'package:parallel':
##
##
       clusterApply, clusterApplyLB, clusterCall, clusterEvalQ,
##
       clusterExport, clusterMap, parApply, parCapply, parLapply,
       parLapplyLB, parRapply, parSapply, parSapplyLB
##
## The following objects are masked from 'package:stats':
##
##
       IQR, mad, sd, var, xtabs
## The following objects are masked from 'package:base':
##
##
       anyDuplicated, append, as.data.frame, cbind, colMeans,
##
       colnames, colSums, do.call, duplicated, eval, evalq, Filter,
##
       Find, get, grep, grepl, intersect, is.unsorted, lapply,
##
       lengths, Map, mapply, match, mget, order, paste, pmax,
       pmax.int, pmin, pmin.int, Position, rank, rbind, Reduce,
##
##
       rowMeans, rownames, rowSums, sapply, setdiff, sort, table,
##
       tapply, union, unique, unsplit, which, which.max, which.min
```



plot(dag\_C)



Obtain cpdags corresponding to this generating dags, and then obtain all generated dags corresponding to cpdags.

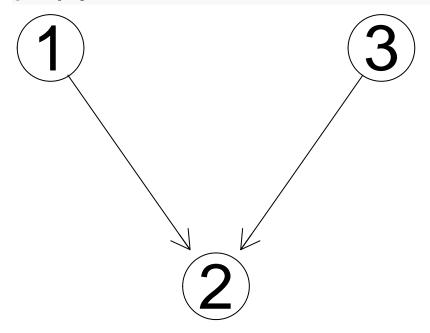
```
cpdag_NC <- dag2cpdag(dag_NC)
cpdag_C <- dag2cpdag(dag_C)</pre>
```

Lets plot the cpdags.

plot(cpdag\_NC)



## plot(cpdag\_C)



Convert to matrices, obtain markov equivalent dags from each.

```
# non-collider
cpdag_NC_Mat <- as(cpdag_NC, "matrix")
(dags_NC_Mat <- pdag2allDags(t(cpdag_NC_Mat))$dags)</pre>
```

```
[,1] [,2] [,3] [,4] [,5] [,6] [,7] [,8] [,9]
##
## [1,]
                          0
                                0
                                     1
                                               0
                                                    0
                1
                     0
                                          0
## [2,]
           0
                1
                     0
                           0
                                0
                                     0
                                               1
                                                     0
## [3,]
           0
                0
                     0
                           1
                                0
                                     0
                                          0
                                               1
```

```
dags_NC_aMat_1 <- matrix(dags_NC_Mat[1,],p,p,byrow=T)
dags_NC_aMat_2 <- matrix(dags_NC_Mat[2,],p,p,byrow=T)
dags_NC_aMat_3 <- matrix(dags_NC_Mat[3,],p,p,byrow=T)

# collider
cpdag_C_Mat <- as(cpdag_C, "matrix")
(dags_C_Mat <- pdag2allDags(t(cpdag_C_Mat))$dags)

## [,1] [,2] [,3] [,4] [,5] [,6] [,7] [,8] [,9]
## [1,] 0 0 0 1 0 1 0 0 0
dags_C_aMat_1 <- matrix(dags_C_Mat[1,],p,p,byrow=T)</pre>
```

As is specified in ?pdag2allDags pdag2allDags returns an adjacency of type "amat.cpdag" which as is specified in ?amatType is coded so that mat[a,b]=0, mat[b,a]=1 implies a->b, so that "from" of arrow is in columns and "to" in rows. This means we have to transpose before converting to graph.

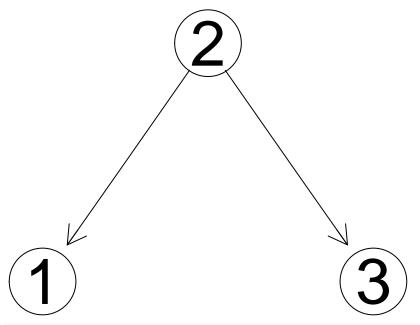
```
# non-collider
dags_NC_1 <- as(t(dags_NC_aMat_1), "graphNEL")
dags_NC_2 <- as(t(dags_NC_aMat_2), "graphNEL")
dags_NC_3 <- as(t(dags_NC_aMat_3), "graphNEL")
# collider
dags_C_1 <- as(t(dags_C_aMat_1), "graphNEL")</pre>
```

Lets plot non-collider generated dags.

plot(dags\_NC\_1)



plot(dags\_NC\_2)

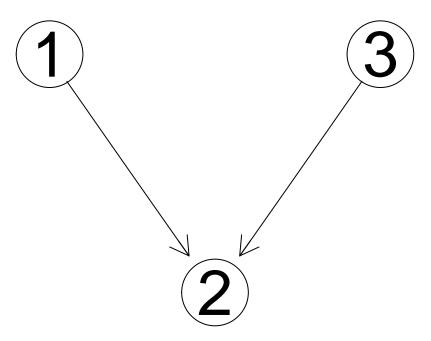


plot(dags\_NC\_3)



This is fine! Now lets plot collider generated dags.

plot(dags\_C\_1)



The collider structure was converted into a non-collider structure in the process.

This code, using the following packages, is returning a v-structure as one of the dags belonging to a Markov Equivalence class that was generated from a non-v-structure.

## sessionInfo()

```
## R version 3.4.3 (2017-11-30)
## Platform: x86_64-pc-linux-gnu (64-bit)
## Running under: Ubuntu 16.04.1 LTS
## Matrix products: default
## BLAS: /home/soulivanh/R-3.4.3/lib/libRblas.so
## LAPACK: /home/soulivanh/R-3.4.3/lib/libRlapack.so
##
## locale:
   [1] LC_CTYPE=en_US.UTF-8
                                   LC NUMERIC=C
##
   [3] LC TIME=en US.UTF-8
                                   LC COLLATE=en US.UTF-8
##
   [5] LC_MONETARY=en_US.UTF-8
                                   LC_MESSAGES=en_US.UTF-8
##
   [7] LC_PAPER=en_US.UTF-8
                                   LC NAME=C
   [9] LC_ADDRESS=C
                                   LC_TELEPHONE=C
##
## [11] LC MEASUREMENT=en US.UTF-8 LC IDENTIFICATION=C
##
## attached base packages:
## [1] grid
                 parallel stats
                                     graphics grDevices utils
                                                                    datasets
## [8] methods
                 base
##
## other attached packages:
## [1] Rgraphviz_2.22.0
                                               BiocGenerics_0.24.0
                           graph_1.56.0
## [4] pcalg_2.6-0
##
## loaded via a namespace (and not attached):
   [1] igraph 1.2.2
                          Rcpp 1.0.0
                                            cluster 2.0.6
   [4] knitr_1.20
                          magrittr_1.5
                                            MASS_7.3-48
##
   [7] sfsmisc_1.1-1
                          clue_0.3-54
                                            ggm_2.3
```

```
## [10] dagitty_0.2-2
                          stringr_1.3.1
                                            tools_3.4.3
## [13] corpcor_1.6.9
                          htmltools_0.3.6
                                            abind_1.4-5
## [16] yaml_2.2.0
                          RBGL_1.54.0
                                            rprojroot_1.3-2
## [19] digest_0.6.18
                          bdsmatrix_1.3-3
                                            curl_3.2
                                            rmarkdown_1.10
## [22] robustbase_0.93-3 evaluate_0.11
## [25] V8_1.5
                          fastICA_1.2-1
                                            stringi_1.2.4
                         DEoptimR_1.0-8
## [28] compiler_3.4.3
                                            backports_1.1.2
## [31] boot_1.3-20
                          stats4_3.4.3
                                            jsonlite_1.5
## [34] pkgconfig_2.0.2
```