```
응 {
SPACIAL 2D GAUSSIAN FILTER
function [qaussianFilterList] = spacial2DGaussianFilter(imqList,
ssigma)
   (ssigma^2)));
   Gy = @(y) 1 / sqrt(2 * pi * (ssigma^2)) * exp(-1 * y^2 / (2 *
 (ssigma^2)));
   imgListSize = size(imgList);
   xDir = imqListSize(2);
   yDir = imgListSize(1);
   zDir = imgListSize(3);
   boxSize = ceil(((ssigma * 5) + 1)/2)*2 - 1;
   startPixel = boxSize - floor(boxSize/2);
   endPixelX = xDir - floor(boxSize/2);
   endPixelY = yDir - floor(boxSize/2);
   gaussianFilterList = imgList;
   gaussianFilterHorizontal = zeros(1, boxSize);
   for i = 1:boxSize
       x = i - ceil(boxSize/2);
       gaussianFilterHorizontal(i) = Gx(x);
   end
   gaussianFilterVertical = transpose(gaussianFilterHorizontal);
   qaussianFilterSumX = sum(qaussianFilterHorizontal);
   gaussianFilterSumY = sum(gaussianFilterVertical);
   gaussianFilterSum = gaussianFilterSumX * gaussianFilterSumY;
   for k = 1:zDir
       gaussianFilterList(startPixel:endPixelY,
startPixel:endPixelX, k) = (1/gaussianFilterSum) *
(conv2(conv2(imgList(:,:,k), gaussianFilterHorizontal, 'valid'),
gaussianFilterVertical, 'valid'));
   end
end
```

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