

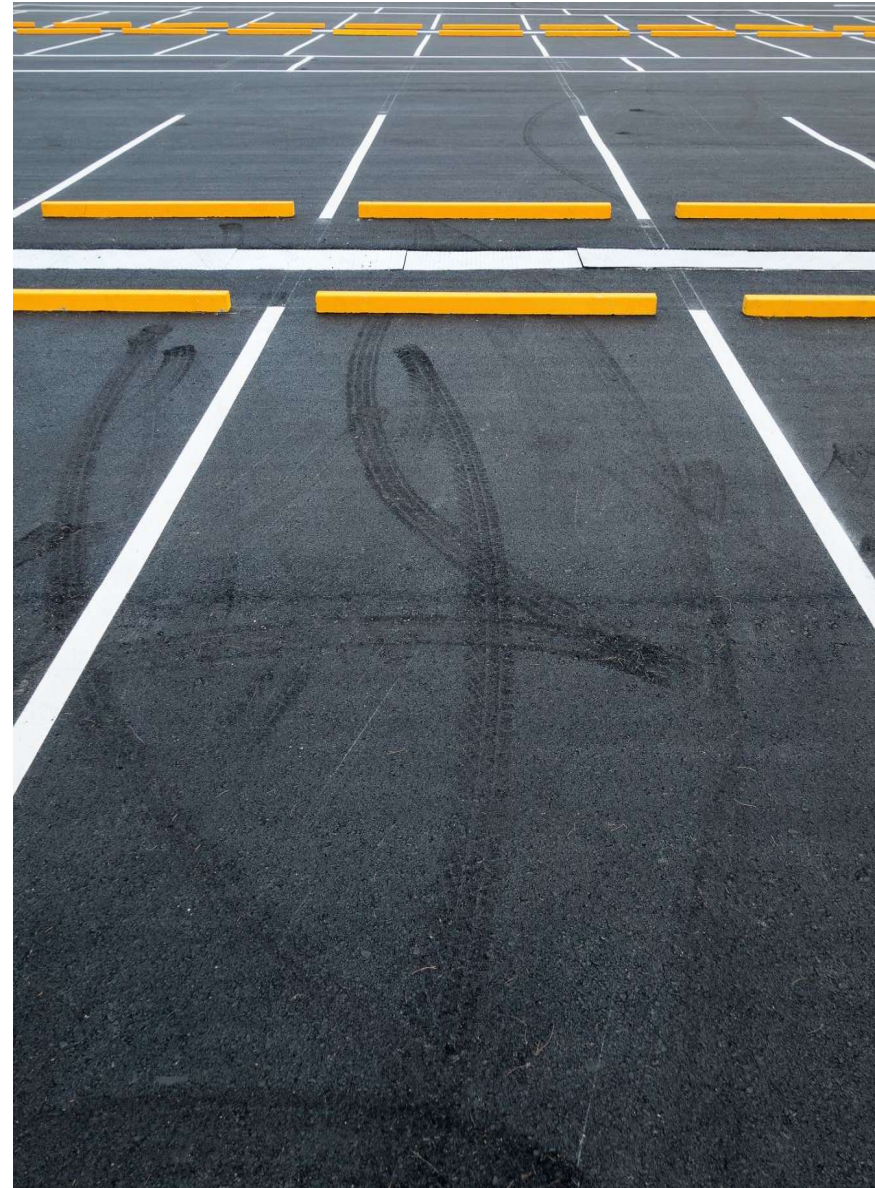
PARKING AVAILABILITY SYSTEM

BETA PRESENTATION MILESTONE

The ParKings

Erik Meurrens
Benjamin Simonson
Ryan Jalloul
Evan Tobon
Samer Khatib

CEN4908C – Computer Engineering Design 2



Context

UF lacks easily available parking resources

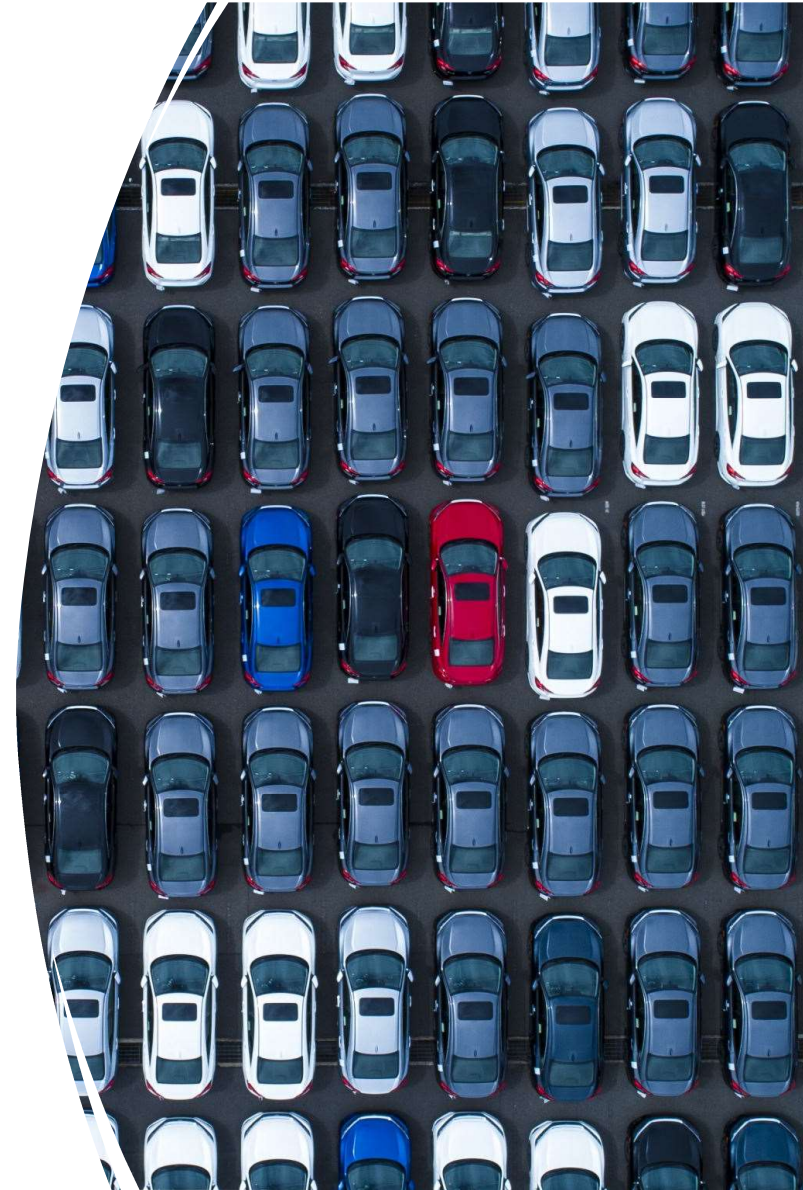
Parking difficulties cause drivers stress and frustration, wastes time, and creates traffic congestion.

Parking Availability System (PAS)

A low-cost, hardware/software system for parking information for facilities on campus

Features:

- Vehicle Detection
- License Plate Recognition
- Database with Lot and Car Information
- Real-time Parking Information on Mobile App



Alpha Completed Work

Alpha Build (01/10/2025 - 01/28/2025)

Researching, planning and deciding on a solution to resolve WiFi dead zone in pilot garage:

- ESP32 repeater
- USB WiFi modem for Raspberry Pi

Implemented YOLOv11n license plate detection model on Raspberry Pi

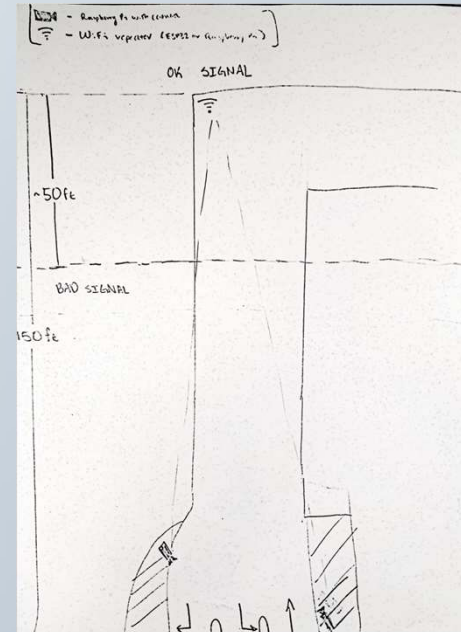
Implemented API communication between Raspberry Pi and AWS

Preliminary configuration script implementation for Raspberry Pi set up:

- System packages
- Python virtual environment

Developed test plan for testing license plate recognition, backend API functionality, mobile app functionality, hardware performance, network connectivity

| lotid [UUID] | latitude [NUMERIC] | longitude [NUMERIC] | name [VARCHAR] | address [VARCHAR] | open [TIME] | close [TIME] | days [VARCHAR] | details [VARCHAR] |
|-----------------------------------|--------------------|---------------------|---------------------------|-------------------|-------------|--------------|----------------|----------------------------|
| 0210feeb-cf1d-42a7-95f-29.647802 | -82.359249 | | Fraternity Row 2 | | 08:30:00 | 15:30:00 | (M,T,W,R,F) | (parkAndRide,red1,disab |
| 0226350f-5dc0-433e-af-0.407479 | 0.345672 | | test name | 5678 Elm St | 12:35:22 | 12:35:22 | (M,T) | (Red,Green) |
| 02bf2c6a-1810-4fe2-90f-29.645655 | -82.337330 | | Parking Garage 8 | | 08:30:00 | 15:30:00 | (M,T,W,R,F) | (orange,red1,red3,disab |
| 0405bddc-778a-4de7-9f-29.639044 | -82.346679 | | Parking Garage 2 | | 07:30:00 | 17:30:00 | (M,T,W,R,F) | (gold,silver,visitor,disab |
| 060dc221-bd70-408a-af-29.649438 | -82.339431 | | Tigert Hall/13th Street M | | 07:30:00 | 16:30:00 | (M,T,W,R,F) | (motorcycleScooter) |
| 06fa4bf0-3ecb-4ef7-adf-29.645198 | -82.348377 | | UF Bookstore & Welcome | | 07:30:00 | 16:30:00 | (M,T,W,R,F) | (gold,silver,disabledEmp |
| 09549251-14f3-44ab-9f-29.645754 | -82.352848 | | Flavet Field | | 08:30:00 | 15:30:00 | (M,T,W,R,F) | (green) |
| 1114af86-d158-4b14-b4f-29.640779 | -82.341599 | | Parking Garage 10 | | 08:30:00 | 15:30:00 | (M,T,W,R,F) | (visitor,motorcycleScoot |
| 11945155-ac9e-45c7-8e-29.647512 | -82.342973 | | Inner Road Motorcycle | | 07:30:00 | 16:30:00 | (M,T,W,R,F) | (motorcycleScooter) |
| 1284e0bd-fe3f-4156-84f-0.083723 | 0.871200 | | test name | 1234 Main St | 12:38:42 | 12:38:42 | (M,T) | (Red,Green) |
| 128ce783-f724-4a47-bee-29.639699 | -82.356552 | | IFAS Parking 3 | | 08:30:00 | 15:30:00 | (M,T,W,R,F) | (orange,motorcycleScoo |
| 1429020c-9ba3-4662-a-29.646837 | -82.350160 | | East Hall | | 08:30:00 | 15:30:00 | (M,T,W,R,F) | (orange,motorcycleScoo |
| 18a4bda1-b294-47a9-af-29.634154 | -82.351701 | | Veterinary Medicine Wes | | 08:30:00 | 15:30:00 | (M,T,W,R,F) | (parkAndRide,green) |
| 18a9b8f3-7f9c-41bc-actf-29.637907 | -82.367623 | | Southwest Rec Center | | 08:30:00 | 15:30:00 | (M,T,W,R,F) | (parkAndRide,disabledSt |



Beta Completed Work

Beta Build (02/02/2025 - 02/21/2025)

Designing and printing of the second Raspberry Pi housing iteration

- Smaller size, better ventilation, persistent power (no battery, wall wart power supply)

Work on ESP32 network repeater access point

Completion of Raspberry Pi configuration script:

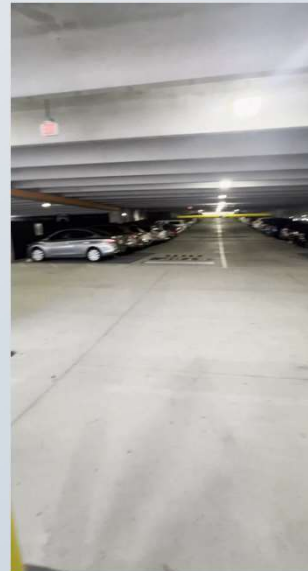
- Documentation, eduroam network onboarding, system packages, WiFi modem drivers, system settings, virtual environment, script error control

Preliminary car detection algorithm direction configuration

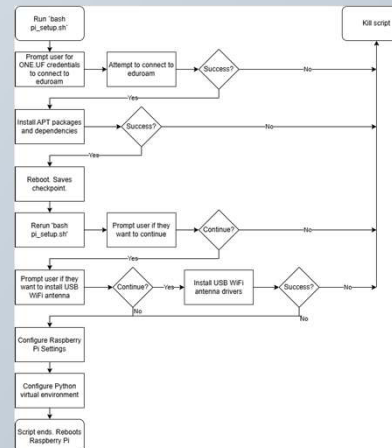
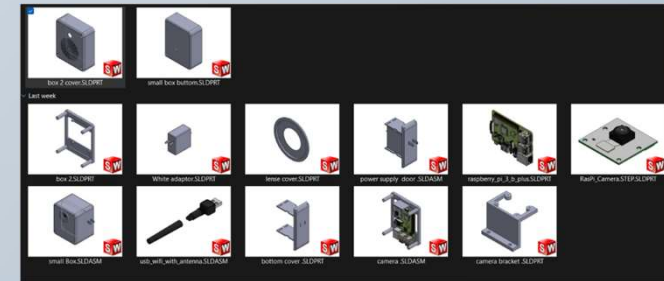
Testing USB WiFi modem, on-board modem, and network connectivity

Testing license plate detection inference speed and real-world functionality on Raspberry Pi

Adjustments to testing plan



| Input Size | MinTime | MeanTime | MaxTime | MaxFPS | MeanFPS | MinFPS |
|------------------|---------|-------------------------|----------------------|--|---------|--------|
| 640x384 | 203.4 | 271.14 | 373.4 | 4.916 | 3.688 | 2.678 |
| Modem Type | | Average Bit Rate (Mb/s) | Average Link Quality | Average Received Signal Strength (dBm) | | |
| On-board (5 GHz) | | 54.53333 | 79% | -55 | | |
| Antenna (5 GHz) | | 115.175 | 91% | -46.3333 | | |



```
{
  "occupancy": 3,
  "capacity": 16,
  "notes": "",
  "ev_charging": false,
  "updated_at": "2025-02-25T04:00:02.318946Z",
  "created_at": "2025-01-29T13:55:00Z"
}

(CarDetectionEnvironment) pi@rasp:~/parking-availability-system/Desktop $ python car_detector.py
super welcome model loaded
Updated:
{
  "id": "6cb52ad-ac30-41f7-b996-82d73ae31b73",
  "latitude": 41.786359,
  "longitude": 44.786625,
  "name": "ЖК Титан",
  "address": "28 Ямал Кочера, Квартал 36, Т6васе, Грыма",
  "open": "0000-01-01T07:30:00Z",
  "close": "0000-01-01T16:30:00Z",
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    "M",
    "T",
    "W",
    "T",
    "F",
    "S",
    "S"
  ],
  "details": [
    "visitor"
  ],
  "occupancy": 4,
  "capacity": 16,
  "notes": "",
  "ev_charging": false,
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}

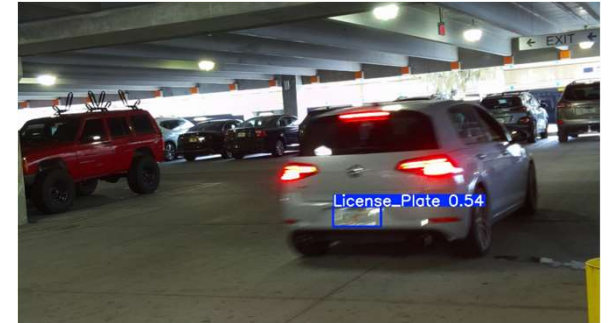
(CarDetectionEnvironment) pi@rasp:~/parking-availability-system/Desktop $
```

In-Progress Work

Continued Testing

- More robust connectivity tests for modem(s), ESP32 repeater, and stability at pilot garage
- More robust license plate detection performance tests
 - Logging
 - Inference speed and accuracy scores
 - Augmenting camera configuration to enhance functionality
- Mobile app user testing

ESP32 Repeater



🟡 In progress 0 Estimate: 41 ⋮

This is actively being worked on

🟢 parking-availability-system #66

ESP32 Network Access Point / Repeater

P0 25 XL

🟢 parking-availability-system #63

Benchmark and Test RPi Object Detection Performance

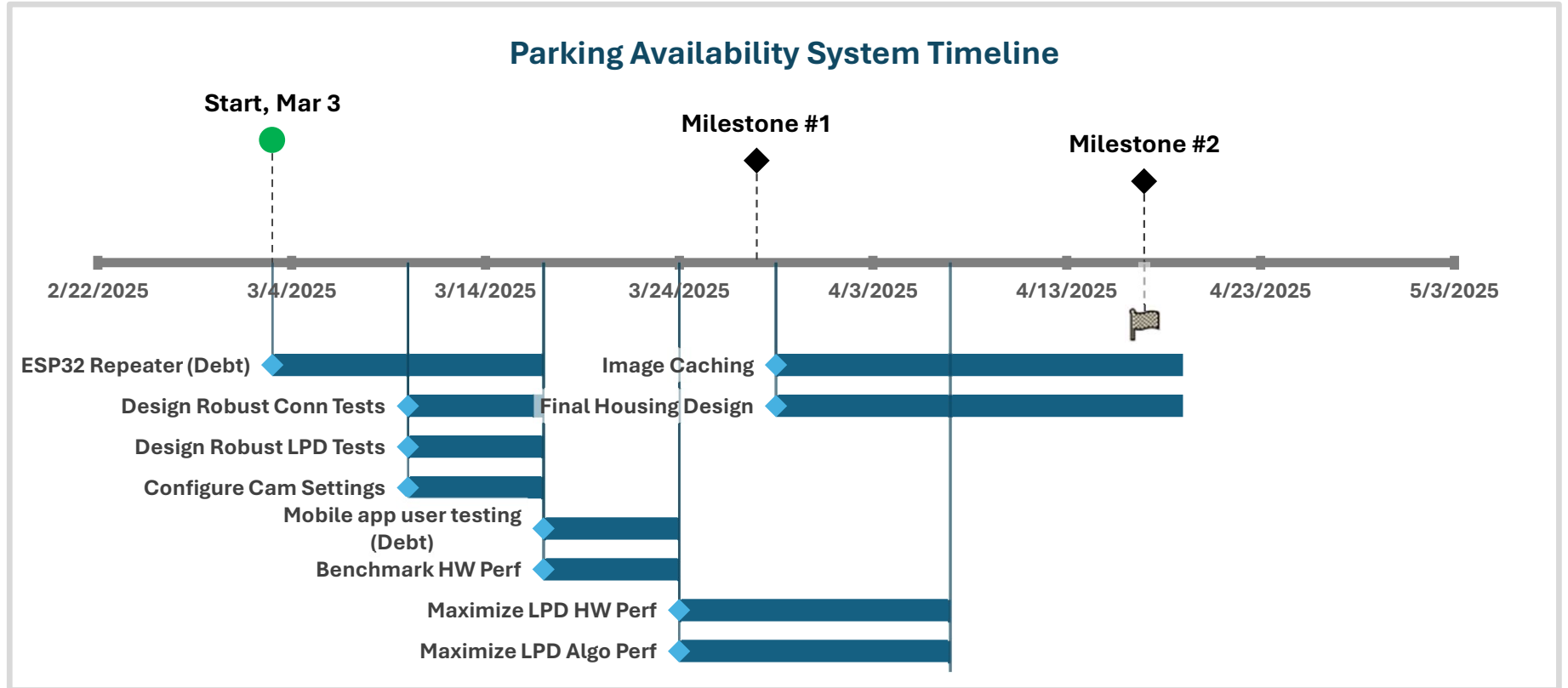
P0 8 L

🟢 parking-availability-system #64

Benchmark and Test Hardware Performance

P0 8 L

Future Work



Deliverable Plan

Demonstration

Questions?