

Laboratorium 2

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Wersja implementacji: Podstawowa wersja algorytmu Gillespiego, w którym model jest wpisany w algorytm.

Podczas podstawowego algorytmu Gillespiego każda reakcja jest symulowana osobno, losując czas do kolejnego zdarzenia i wybierając, która z reakcji zajdzie na podstawie aktualnej szybkości.

Pliki wejściowe są w formacie .json.

Kod:

```
import os
import json
import random
import numpy as np
from scipy.stats import poisson

import matplotlib.pyplot as plt

def szybkoosc_reakcji(reaction):
    all_vars = reaction["params"] + reaction["species"]
    lambda_str = f"lambda {' '.join(all_vars)}:"
    {reaction['equation']}
    return eval(lambda_str), all_vars

def algorytm_Gillespiego(model, max_steps, max_time=None):
    sp_names = list(model['species_init'].keys())
    params = model['parameters']
    sp_idx = {name: i for i, name in enumerate(sp_names)}
    n_species = len(sp_names)
    sp_traj = np.zeros((max_steps + 1, n_species))
    for i, name in enumerate(sp_names):
        sp_traj[0, i] = model['species_init'][name]
    t_traj = np.zeros((max_steps + 1))
    rxn_list = []
    for rxn in model['reactions'].values():
        rate_fn, var_names = szybkoosc_reakcji(rxn)
        rxn_list.append({'rate_fn': rate_fn, 'vars': var_names,
            'effects': rxn['effects']})
    steps_done = 0
    for step in range(max_steps):
        now = t_traj[step]
        if max_time is not None and now >= max_time:
            break
        curr_sp = sp_traj[step]
        rates = []
        for rxn in rxn_list:
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        vals = []
        for v in rxn['vars']:
            if v in params:
                vals.append(params[v])
            else:
                vals.append(curr_sp[sp_idx[v]])
        try:
            r = rxn['rate_fn'](*vals)
        except Exception:
            r = 0
        rates.append(max(r, 0))
    total_r = sum(rates)
    if total_r <= 0:
        break
    dt = random.expovariate(total_r)
    t_traj[step + 1] = now + dt
    sp_traj[step + 1] = curr_sp.copy()
    threshold = random.uniform(0, total_r)
    acc = 0
    chosen = -1
    for i, r in enumerate(rates):
        acc += r
        if threshold <= acc:
            chosen = i
            break
    rxn = rxn_list[chosen]
    for sp, eff in rxn['effects'].items():
        idx = sp_idx[sp]
        sp_traj[step + 1][idx] += eff
    steps_done = step + 1
    return t_traj[:steps_done + 1], sp_traj[:steps_done + 1],
sp_names

def main():
    scenarios_dir = os.path.join(os.getcwd(), 'scenariusze')
    plots_dir = os.path.join(os.getcwd(), 'wykresy')
    os.makedirs(plots_dir, exist_ok=True)
    scenarios = {}
    for filename in os.listdir(scenarios_dir):
        if filename.endswith('.json'):
            with open(os.path.join(scenarios_dir, filename), 'r',
encoding='utf-8') as f:
                scenario_name = os.path.splitext(filename)[0]
                scenarios[scenario_name] = json.load(f)
    max_steps = 10000
    max_time = 172800
    for selected, scenario_model in scenarios.items():

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t_direct, sp_direct, sp_names = algorytm_Gillespiego(
    scenario_model, max_steps=1000000, max_time=max_time
)
plt.figure(figsize=(12, 6))
for idx, label in enumerate(sp_names):
    plt.plot(t_direct, sp_direct[:, idx], label=label)
plt.xlabel('Time [s]')
plt.ylabel('Species #')
plt.title(f"{selected} - algorytm Gillespiego")
plt.legend()
plt.tight_layout()
plot_path = os.path.join(plots_dir,
f"{selected}_algorytm_Gillespiego.png")
plt.savefig(plot_path)
plt.close()

if __name__ == "__main__":
    main()

```

Wykresy:



