

Lectures 5

# Schedulability Analysis

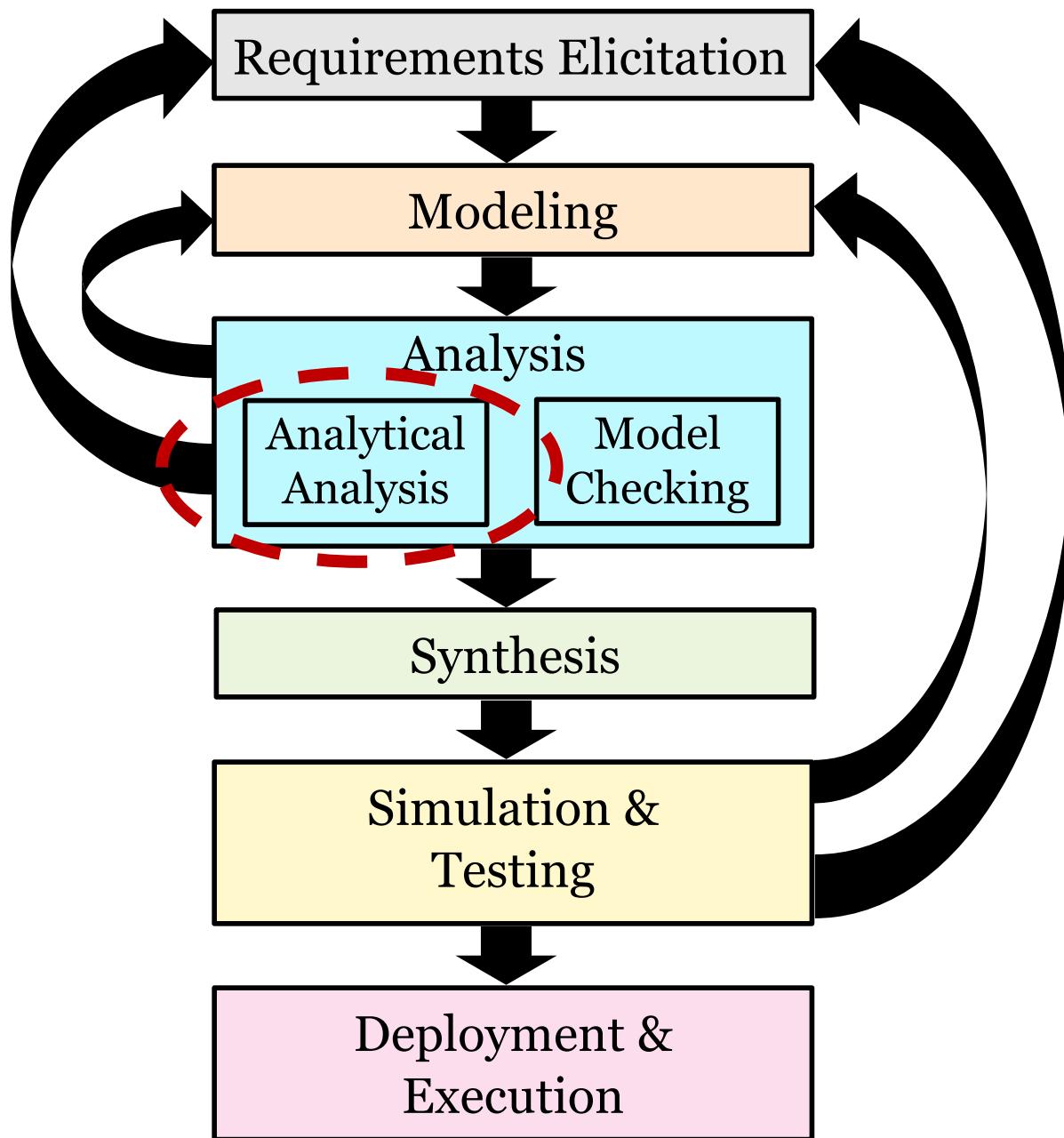
## Part 1

*Saad Mubeen*





# Model-based Software Development Process





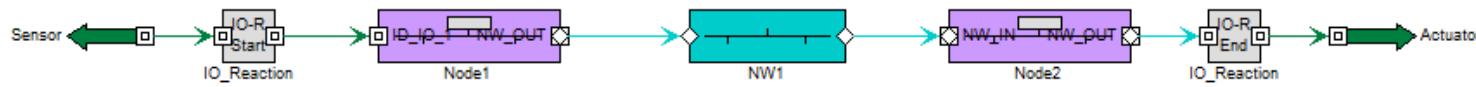
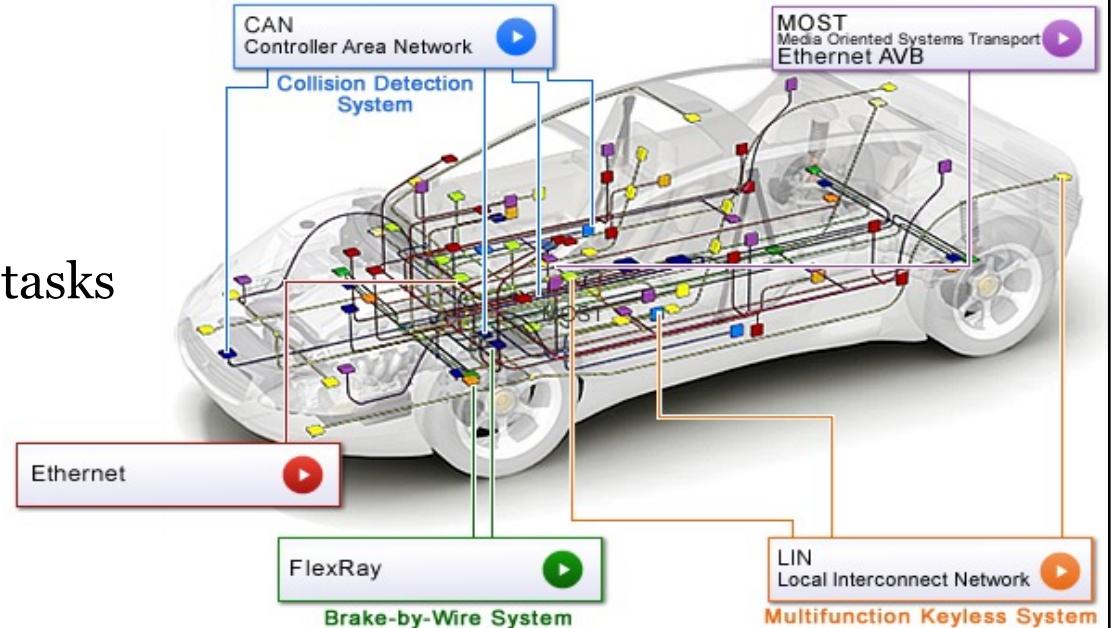
# Learning Objectives of this Lecture

After this set of lectures you should be able to explain and reflect on

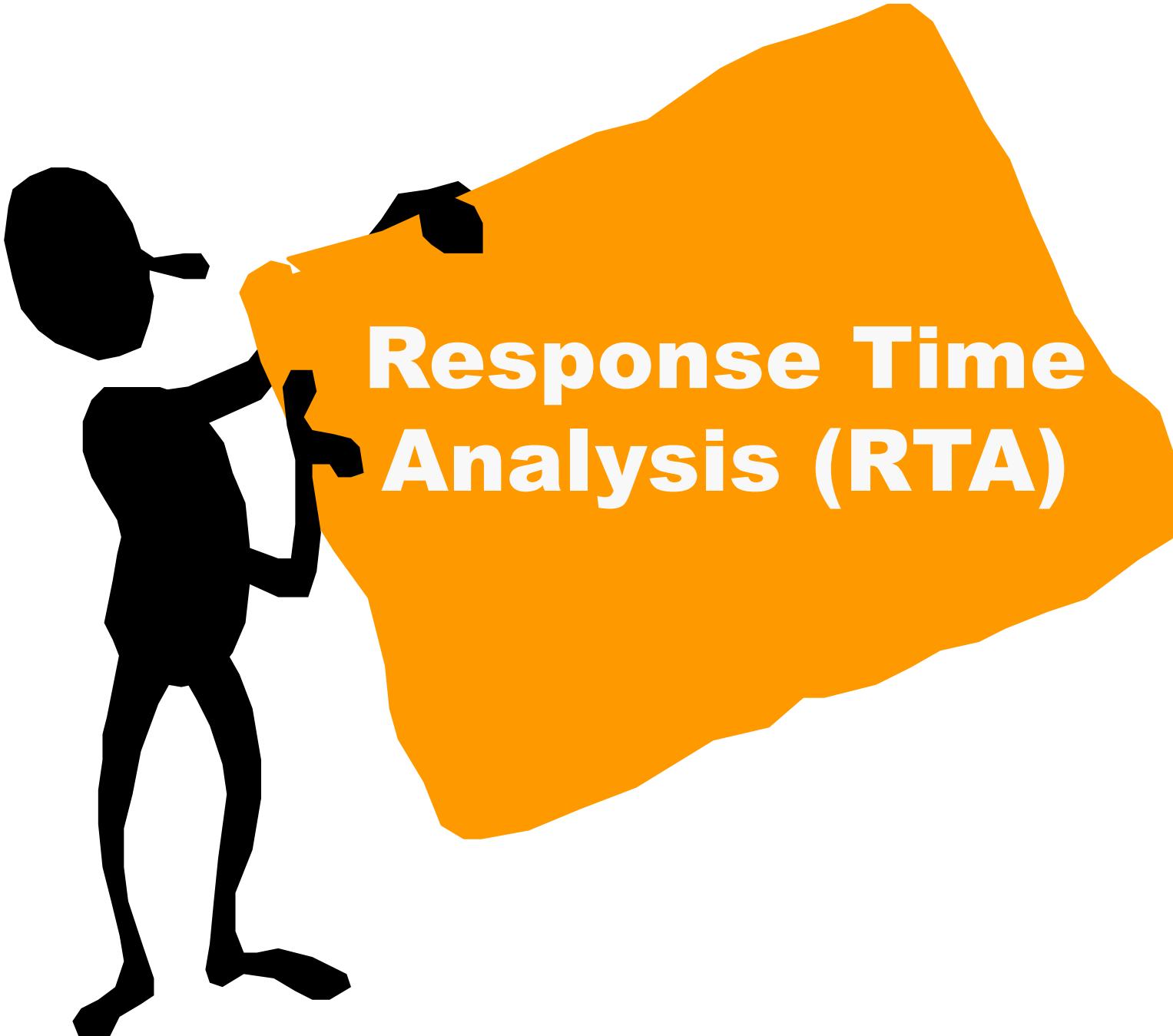
- Predicting the timing behavior of a real-time system without actually running or executing it (i.e., in pre-runtime)?

# Outline

- Response-time analysis (RTA) of tasks
  - Basic RTA
  - RTA with blocking
  - RTA with jitter
  - RTA with Offsets
- RTA of Controller Area Network (CAN) messages
- Practical limitations in CAN Controllers and their effect on RTA for CAN
- Holistic RTA (for distributed systems)
- Data-propagation delay analysis
  - Single node systems
  - Distributed systems (End-to-end data-propagation delay analysis)



Figures courtesy of: <http://www.cvel.clemson.edu/>  
<http://www.renesas.eu>



# **Response Time Analysis (RTA)**

## Response time analysis

### The CPU utilization analysis is not exact!

- Remember for RM: if  $U \leq n(2^{1/n}-1)$  then we cannot conclude if the task set is schedulable or not
- Also does not apply when deadlines are less than periods
  - Deadline Monotonic (DM) has no U-based schedulability test
- We need something else....

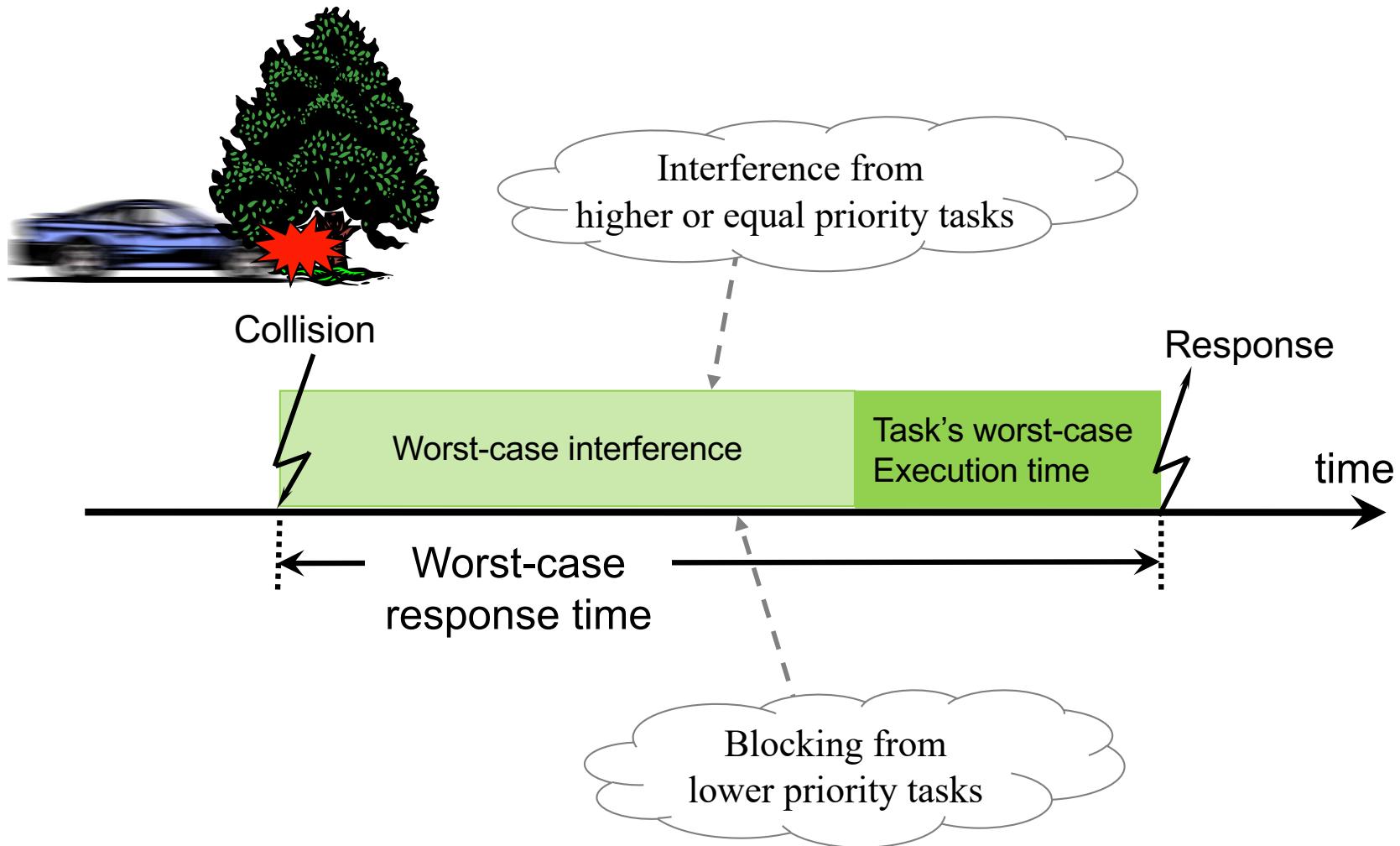
### Response time analysis

- Predicts if all tasks will meet their deadlines
- Works for any static priority assignment (not only RM)
- Exact analysis – **both sufficient and necessary**

# Response times

## Schedulability with Response-Time Analysis (RTA)

- For each task check if response time  $\leq$  deadline



# Tools supporting RTA

Rubus-ICE

CANoe

Network Designer CAN

SymTA/S

CANalyzer

MPS-CAN Analyzer

VNA



RTaW-Sim



KNORR-BREMSE

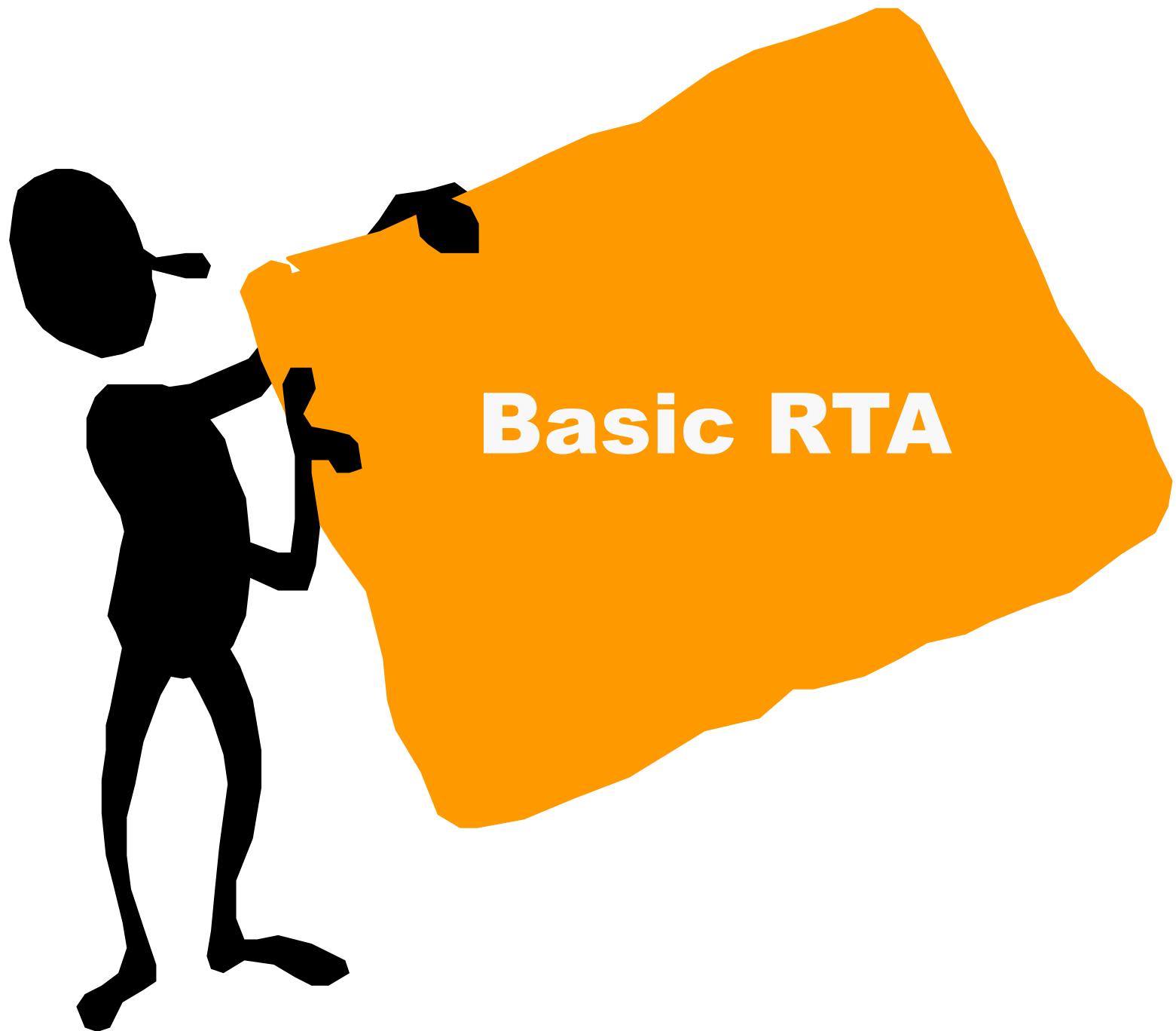


HOERBIGER



Haldex





# Task set assumptions

## **Preemptive priority scheduling**

### **Independent tasks**

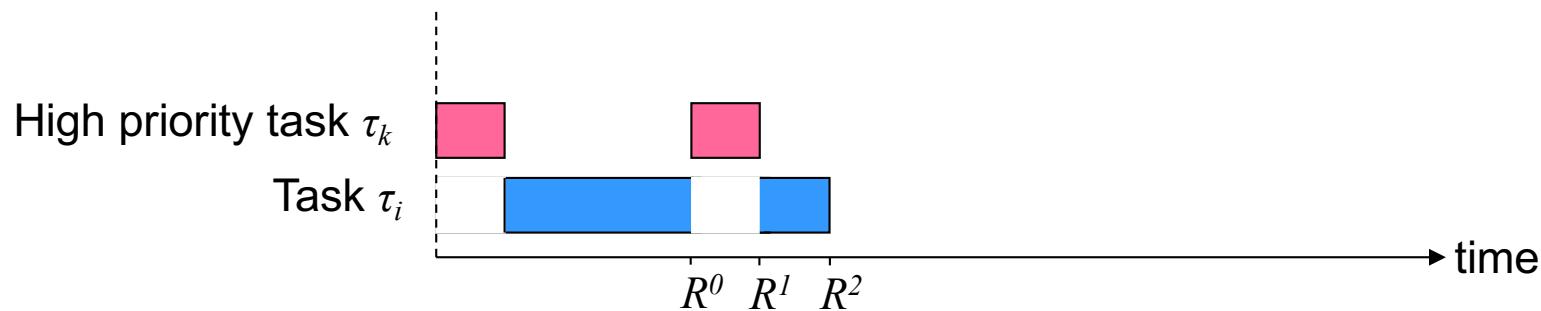
- No resource sharing
- No task synchronisation
- Given parameters: T, C, D, and P (priority)
- Periodic activation

### **No OS overhead**

## Response time analysis

**Response time for a task  $\tau_i$  :**

1. Critical instant,
2. Compute how much task  $\tau_i$  will be delayed by high priority tasks (response time) and compare it to the deadline of  $\tau_i$



# Remember from Lecture 2

## Critical Instant and Critical Time Zone

## Response time analysis

### Response time for a task $\tau_i$ :

1. Critical instant, for a task, is worst-case response time
  - Critical instant is assumed to be at the release of all higher priority tasks.
2. Compute how much task  $\tau_i$  runs (response time) and compare.

**Theorem1:** A critical instant for an arbitrary task is the time at which all higher priority tasks are released at the same time.

Consider a periodic task set

$\Gamma = \{T_1, T_2, T_3, \dots, T_n\}$  ;  
such that  $T_2 > T_1, T_n > T_{n-1}$

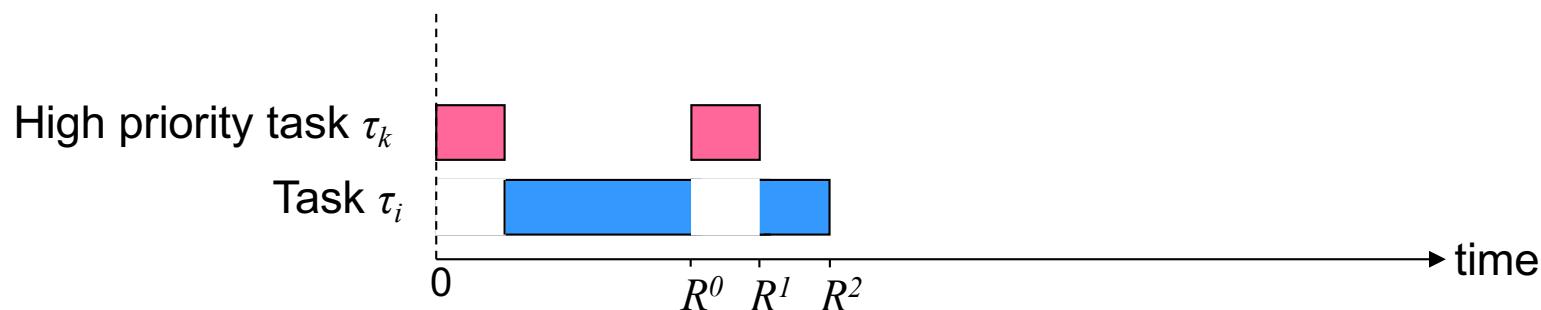
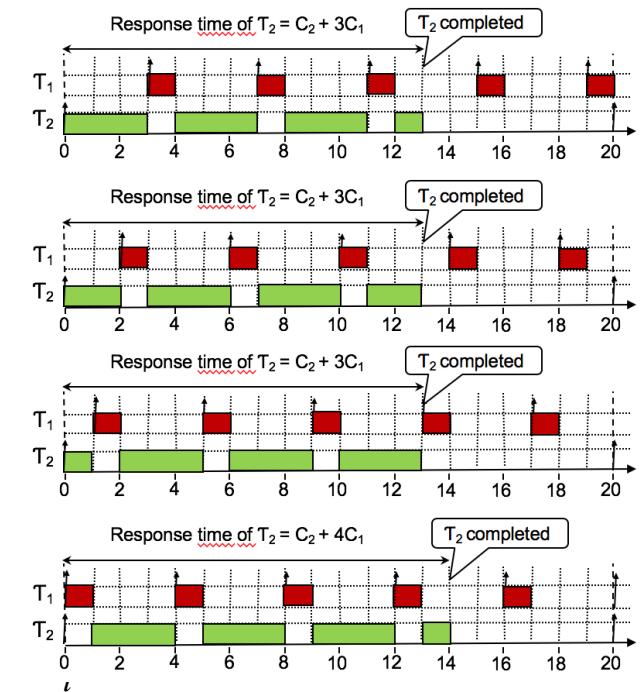
Task	T	C
$T_1$	4	$C_1=1$
$T_2$	20	$C_2=10$

High priority  
Low priority

Hyper period: LCM(4,20)=20

Response time of  $T_2$  is largest when  $T_1$  is released at the same time.

Consequently, response time of  $T_n$  is when  $T_{n-1}, T_{n-2}, \dots, T_2, T_1$  are released at the same time.



## RTA equation

$$R_i^{n+1} = C_i + \sum_{\forall j \in hp(i)} \left\lceil \frac{R_i^n}{T_j} \right\rceil C_j$$

Iteration steps:

1. Assume  $R^0 = C_i$
2. Iterate until  $R^{n+1} = R^n$ , or  $R^{n+1} > D_i$

$R_i$  = (worst-case) response time

$\tau_j$  = higher priority task

$hp$  = a set of tasks that have higher priority than  $\tau_i$

$\lceil R_i/T_j \rceil$  = **maximum number of pre-emptions** of  $\tau_i$  in an interval  $[0, R_i)$  by task  $\tau_j$

$\lceil R_i/T_j \rceil C_j$  = **maximal pre-emption time** of  $\tau_i$  in an interval  $[0, x)$  by task  $\tau_j$

$$R_i^{n+1} = C_i + \sum_{\forall j \in hp(i)} \left\lceil \frac{R_i^n}{T_j} \right\rceil C_j$$

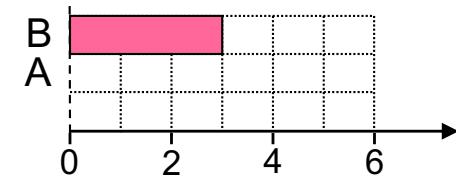
Assume  $R^0 = C_i$   
Iterate until  
 $R^{n+1} = R^n$ , or  $R^{n+1} > D_i$

## RTA – Example 1

Assume 2 tasks A and B with periods 2 and 6, and execution times 1 and 3. Task A has higher priority than B. Calculate B's response time.

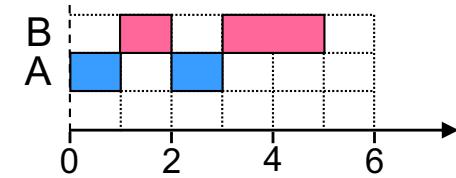
**Step 1:** What is B:s response time if only B executes?

$$R_B^0 = C_B = 3$$



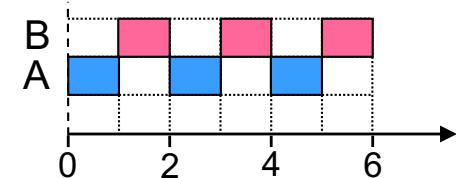
**Step 2:** How much the execution of A within time 0-3 will delay B?

$$R_B^1 = C_B + \left\lceil \frac{R_B^0}{T_A} \right\rceil C_A = 3 + \left\lceil \frac{3}{2} \right\rceil 1 = 3 + 2 = 5$$



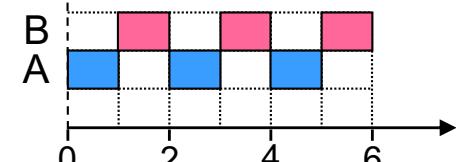
**Step 3:** How much the execution of A within time 0-5 will delay B?

$$R_B^2 = C_B + \left\lceil \frac{R_B^1}{T_A} \right\rceil C_A = 3 + \left\lceil \frac{5}{2} \right\rceil 1 = 3 + 3 = 6$$



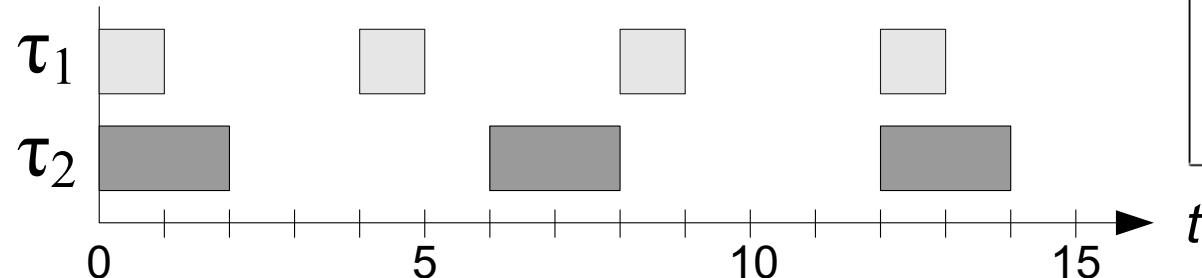
**Step 4:** How much the execution of A within time 0-6 will delay B?

$$R_B^3 = C_B + \left\lceil \frac{R_B^2}{T_A} \right\rceil C_A = 3 + \left\lceil \frac{6}{2} \right\rceil 1 = 3 + 3 = 6$$

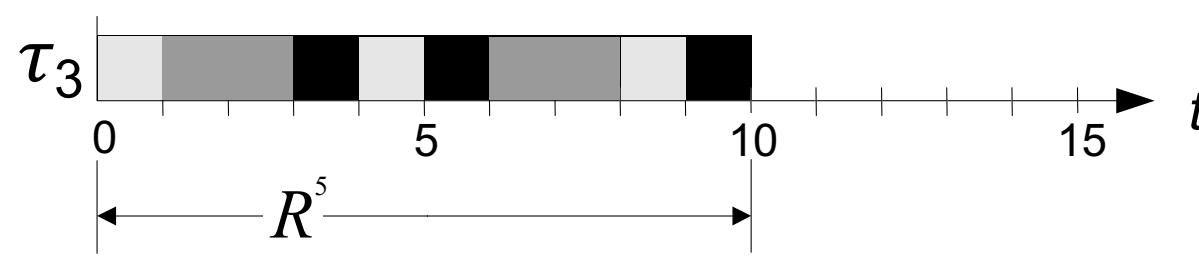


The same result as in previous step → done! ( $R_B=6$ )

## RTA – Example 2



Task	$T_i$	$C_i$	$D_i$	$P_i$
$\tau_1$	4	1	4	H
$\tau_2$	6	2	6	M
$\tau_3$	10	3	10	L



$$R_3^0 = 3$$

$$R_3^1 = 3 + 1 + 2 = 6$$

$$R_3^2 = 3 + 2 + 2 = 7$$

$$R_3^3 = 3 + 2 + 4 = 9$$

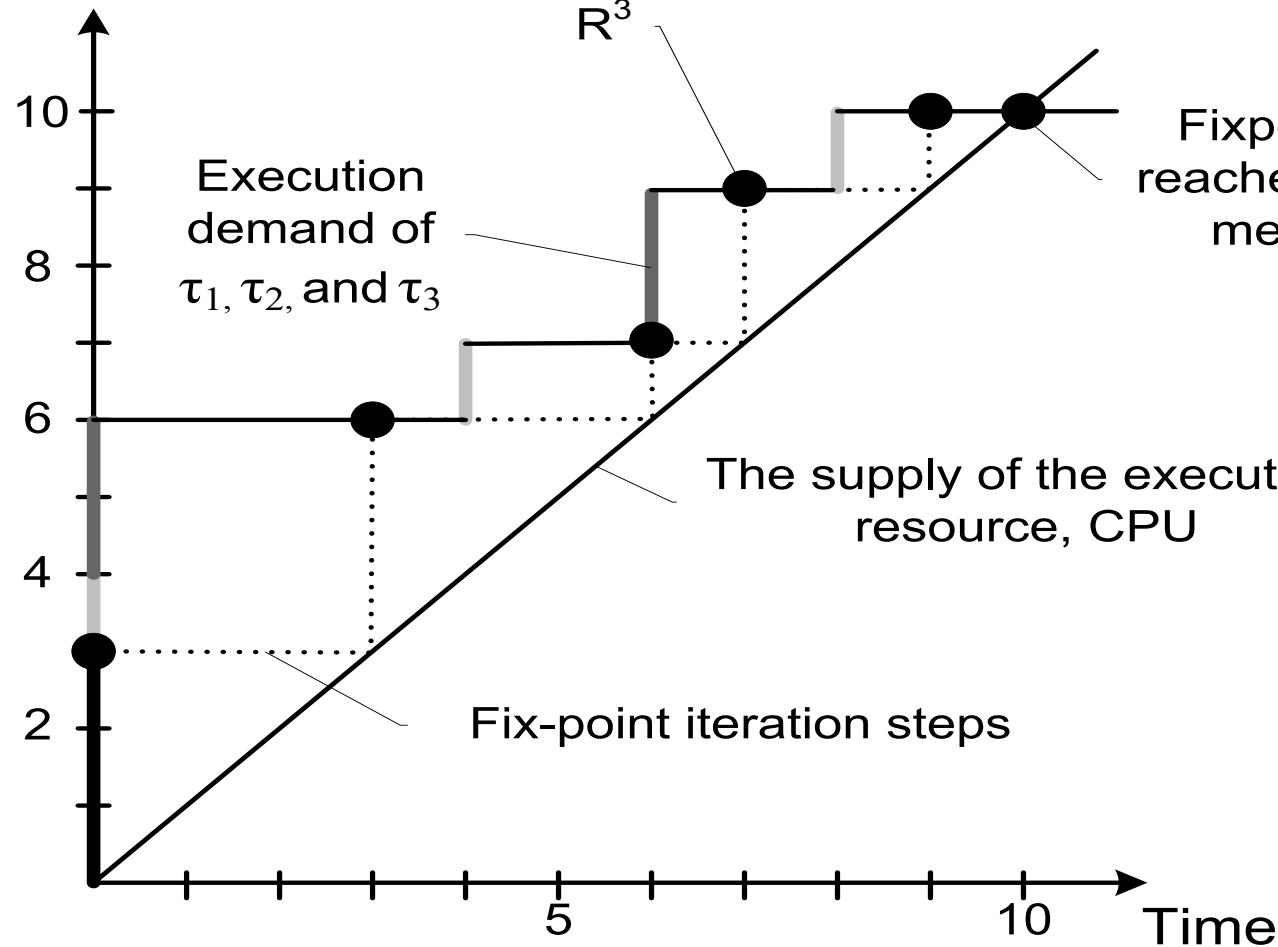
$$R_3^4 = 3 + 3 + 4 = 10$$

$$R_3^5 = 3 + 3 + 4 = 10 = R_3^4$$

$$R_i^{n+1} = C_i + \sum_{\forall j \in hp(i)} \left\lceil \frac{R_i^n}{T_j} \right\rceil C_j$$

## RTA – Example 2 (supply vs. demand)

Execution



Task	$T_i$	$C_i$	$D_i$	$P_i$
$\tau_1$	4	1	4	H
$\tau_2$	6	2	6	M
$\tau_3$	10	3	10	L

$$R_3^0 = 3$$

$$R_3^1 = 3 + 1 + 2 = 6$$

$$R_3^2 = 3 + 2 + 2 = 7$$

$$R_3^3 = 3 + 2 + 4 = 9$$

$$R_3^4 = 3 + 3 + 4 = 10$$

$$R_3^5 = 3 + 3 + 4 = 10 = R_3^4$$

## RTA – Example 3

---

Assume the following task set with priorities according to RM:

Task	T	C
A	3	1
B	6	1
C	5	1
D	10	2

Can we decide if the set is schedulable by using the **approximate** analysis for RM? If not, use the **exact** analysis.

U=0.9, n(..)=0.75

## RTA – Example 3

---

Using the approximate analysis for Rate Monotonic

Task	T	C
A	3	1
B	6	1
C	5	1
D	10	2

$$U = \frac{1}{3} + \frac{1}{6} + \frac{1}{5} + \frac{2}{10} = \frac{27}{30} = 0.9$$

$$n(2^{1/n} - 1) = 4(2^{1/4} - 1) = 0.75$$

$$U \leq n(2^{1/n} - 1) \text{ false!}$$

The condition  $0.9 < 0.75$  is false.

Inconclusive: nothing can be said about the schedulability of the task set with RM. The task set may or may not be schedulable

Remember, the condition is **sufficient**  
but **not necessary!**

## RTA – Example 3

Using the exact analysis (RTA)

$$R_i^{n+1} = C_i + \sum_{\forall j \in hp(i)} \left\lceil \frac{R_i^n}{T_j} \right\rceil C_j$$

Priority = 4  
(highest) ← A      3      1

Priority = 2 ← B      6      1

Priority = 3 ← C      5      1

Priority = 1 ← D      10     2  
(lowest)

Task	T	C
A	3	1
B	6	1
C	5	1
D	10	2

**Response time for task A:**

$$R_A^0 = C_A = 1$$

$$R_A^1 = C_A + \sum_{\forall j \in hp(A)} \left\lceil \frac{R_A^0}{T_j} \right\rceil C_j$$

$$R_A^1 = C_A + 0 = 1 + 0 = 1$$

$$R_A^1 = R_A^0$$

$R_A = 1$

**Response time for task C:**

$$R_C^0 = C_C = 1$$

$$R_C^1 = C_C + \sum_{\forall j \in hp(C)} \left\lceil \frac{R_C^0}{T_j} \right\rceil C_j$$

$$R_C^1 = C_C + \left\lceil \frac{R_C^0}{T_A} \right\rceil C_A$$

$$R_C^1 = 1 + \left\lceil \frac{1}{3} \right\rceil 1 = 2$$

$$R_C^1 \neq R_C^0$$

$$R_C^2 = C_C + \left\lceil \frac{R_C^1}{T_A} \right\rceil C_A$$

$$R_C^2 = 1 + \left\lceil \frac{2}{3} \right\rceil 1 = 2$$

$$R_C^2 = R_C^1$$

$R_C = 2$

**Response time for task B:**

$$R_B^0 = C_B = 1$$

$$R_B^1 = C_B + \sum_{\forall j \in hp(B)} \left\lceil \frac{R_B^0}{T_j} \right\rceil C_j$$

$$R_B^1 = C_B + \left\lceil \frac{R_B^0}{T_A} \right\rceil C_A + \left\lceil \frac{R_B^0}{T_C} \right\rceil C_C$$

$$R_B^1 = 1 + \left\lceil \frac{1}{3} \right\rceil 1 + \left\lceil \frac{1}{5} \right\rceil 1 = 3$$

$$R_B^1 \neq R_B^0$$

$$R_B^2 = C_B + \left\lceil \frac{R_B^1}{T_A} \right\rceil C_A + \left\lceil \frac{R_B^1}{T_C} \right\rceil C_C$$

$$R_B^2 = 1 + \left\lceil \frac{3}{3} \right\rceil 1 + \left\lceil \frac{3}{5} \right\rceil 1 = 3$$

$$R_B^2 = R_B^1$$

$R_B = 3$

## RTA – Example 3

**Response time for task D:**

$$R_D^0 = C_D = 2$$

$$R_D^1 = C_D + \sum_{\forall j \in hp(D)} \left\lceil \frac{R_D^0}{T_j} \right\rceil C_j$$

$$R_D^1 = C_D + \left\lceil \frac{R_D^0}{T_A} \right\rceil C_A + \left\lceil \frac{R_D^0}{T_B} \right\rceil C_B + \left\lceil \frac{R_D^0}{T_C} \right\rceil C_C$$

$$R_D^1 = 2 + \left\lceil \frac{2}{3} \right\rceil 1 + \left\lceil \frac{2}{6} \right\rceil 1 + \left\lceil \frac{2}{5} \right\rceil 1 = 5$$

$$R_D^1 \neq R_D^0$$

$$R_D^2 = C_D + \left\lceil \frac{R_D^1}{T_A} \right\rceil C_A + \left\lceil \frac{R_D^1}{T_B} \right\rceil C_B + \left\lceil \frac{R_D^1}{T_C} \right\rceil C_C$$

$$R_D^2 = 2 + \left\lceil \frac{5}{3} \right\rceil 1 + \left\lceil \frac{5}{6} \right\rceil 1 + \left\lceil \frac{5}{5} \right\rceil 1 = 6$$

$$R_D^2 \neq R_D^1$$

$$R_D^3 = C_D + \left\lceil \frac{R_D^2}{T_A} \right\rceil C_A + \left\lceil \frac{R_D^2}{T_B} \right\rceil C_B + \left\lceil \frac{R_D^2}{T_C} \right\rceil C_C$$

$$R_D^3 = 2 + \left\lceil \frac{6}{3} \right\rceil 1 + \left\lceil \frac{6}{6} \right\rceil 1 + \left\lceil \frac{6}{5} \right\rceil 1 = 7$$

$$R_D^3 \neq R_D^2$$

$$R_D^4 = C_D + \left\lceil \frac{R_D^3}{T_A} \right\rceil C_A + \left\lceil \frac{R_D^3}{T_B} \right\rceil C_B + \left\lceil \frac{R_D^3}{T_C} \right\rceil C_C$$

$$R_D^4 = 2 + \left\lceil \frac{7}{3} \right\rceil 1 + \left\lceil \frac{7}{6} \right\rceil 1 + \left\lceil \frac{7}{5} \right\rceil 1 = 9$$

$$R_D^4 \neq R_D^3$$

$$R_D^5 = C_D + \left\lceil \frac{R_D^4}{T_A} \right\rceil C_A + \left\lceil \frac{R_D^4}{T_B} \right\rceil C_B + \left\lceil \frac{R_D^4}{T_C} \right\rceil C_C$$

$$R_D^5 = 2 + \left\lceil \frac{9}{3} \right\rceil 1 + \left\lceil \frac{9}{6} \right\rceil 1 + \left\lceil \frac{9}{5} \right\rceil 1 = 9$$

$$R_D^5 = R_D^4$$

$$R_D = 9$$

$$R_A(1) \leq D_A(3)$$

$$R_B(3) \leq D_B(6)$$

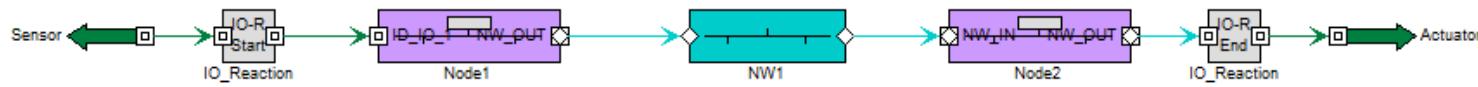
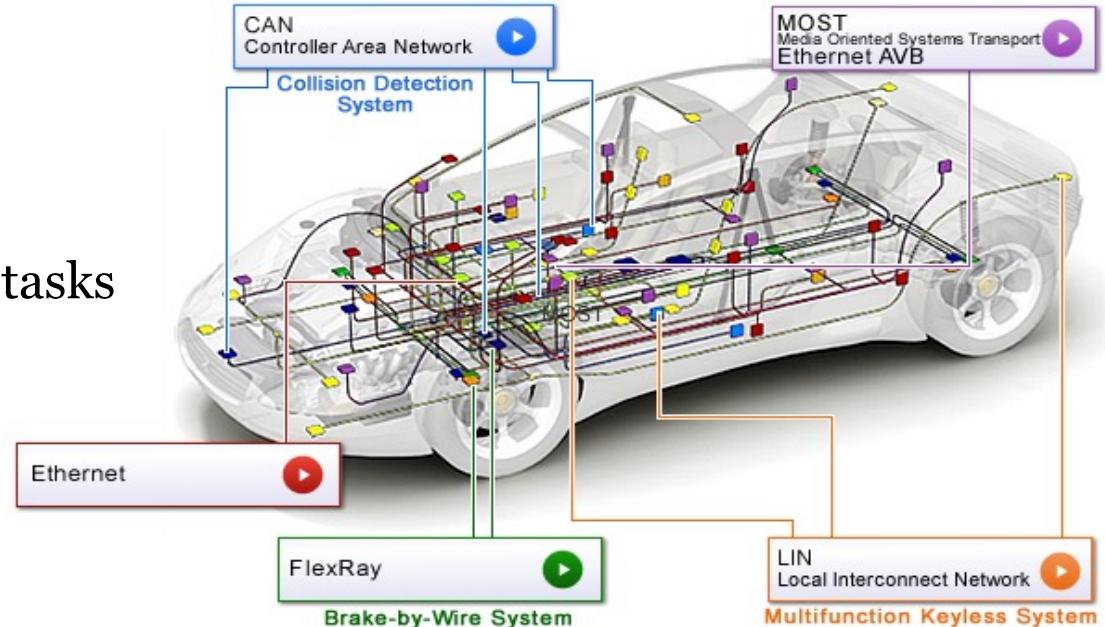
$$R_C(2) \leq D_C(5)$$

$$R_D(9) \leq D_D(10)$$

The task set is  
schedulable

# Outline

- Response-time analysis (RTA) of tasks
  - Basic RTA
  - RTA with blocking
  - RTA with jitter
  - RTA with Offsets
- RTA of Controller Area Network (CAN) messages
- Practical limitations in CAN Controllers and their effect on RTA for CAN
- Holistic RTA (for distributed systems)
- Data-propagation delay analysis
  - Single node systems
  - Distributed systems (End-to-end data-propagation delay analysis)



Figures courtesy of: <http://www.cvel.clemson.edu/>  
<http://www.renesas.eu>

## **RTA with Shared Resources**

---

### **Blocking has a negative effect on schedulability**

- We need to include the blocking times in the analysis
- Blocking time  $B_i$  of a task  $\tau_i$  is the longest time task  $\tau_i$  can be blocked by lower priority tasks

Reminder: critical sections are **properly nested**, so duration of a critical section equals the **outmost** critical section.

**Hence, the blocking time is defined in PCP as:**

$$B_i = \max(CS_j, \dots, CS_k)$$

Where  $CS_j..CS_k$  are the critical sections of all tasks that can block task  $\tau_i$

## Example blocking time

Task	Prio	Semaphore	Critical sect.
A	1	S1	1
B	3	S1	2
C	2	S2	3
D	4	S2	4

1 = lowest prio

4 = highest prio

$$\text{ceil(S1)} = \max( P(A), P(B) ) = \max(1,3) = 3$$

$$\text{ceil(S2)} = \max( P(C), P(D) ) = \max(2, 4) = 4$$

$B_A=?$  A has the lowest priority  $\rightarrow B_A=0$

$B_B=?$   $Ip(B)=\{A, C\}$  ( $Ip(B)$  = all tasks with lower priority than B)

A uses S1,  $prio(B)>\text{ceil}(S1)$ ? No  $\rightarrow$  A can block B!

C uses S2,  $prio(B)>\text{ceil}(S2)$ ? No  $\rightarrow$  C can block B!

$$B_B = \max( CS(A,S1), CS(C,S2) ) = \max(1,3) = 3$$

$B_C=?$   $Ip(C)=\{A\}$

A uses S1,  $prio(C)>\text{ceil}(S1)$ ? No  $\rightarrow$  A can block C  $\rightarrow B_C = CS(A,S1) = 1$

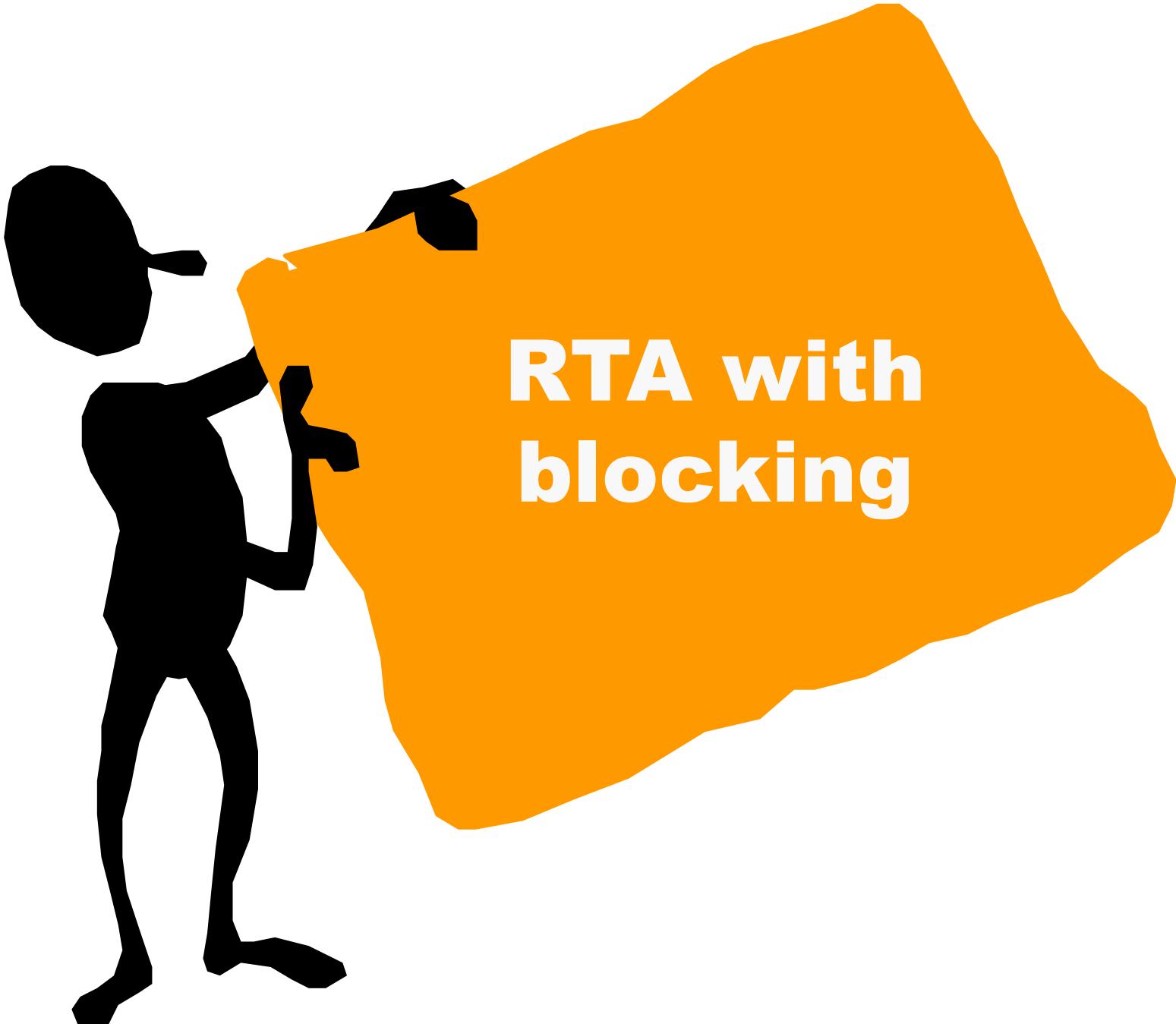
$B_D=?$   $Ip(D)=\{A, B, C\}$

A uses S1,  $prio(D)>\text{ceil}(S1)$ ? Yes  $\rightarrow$  A cannot block D

B uses S1,  $prio(D)>\text{ceil}(S1)$ ? Yes  $\rightarrow$  B cannot block D

C uses S2,  $prio(D)>\text{ceil}(S2)$ ? No  $\rightarrow$  C can block D

$$B_D = CS(C,S2) = 3$$



**RTA with  
blocking**

## Response Time Analysis with blockings

**Reminder:** Response Time Analysis is a method to test the schedulability of static-priority based real-time systems

1. Assume all tasks with the higher priority than  $\tau_i$  are ready at the same time as  $\tau_i$  (critical instant)
2. Compute how much task  $\tau_i$  will be delayed by high priority tasks (response time) and compare it to the  $\tau_i$ 's deadline to see if it can make it or not

**Response Time Analysis with blocking time included:**

$$R_i^{n+1} = C_i + B_i + \sum_{\forall j \in hp(i)} \left\lceil \frac{R_i^n}{T_j} \right\rceil C_j$$

## Response Time Analysis with blockings

Assume the following tasks with respective semaphore accesses:

Task	Period (T)	Execution time (C)	Semaphore	CS
A	100	10	S1	1
B	40	12	S1	2
			S2	1
C	50	6	S1	1

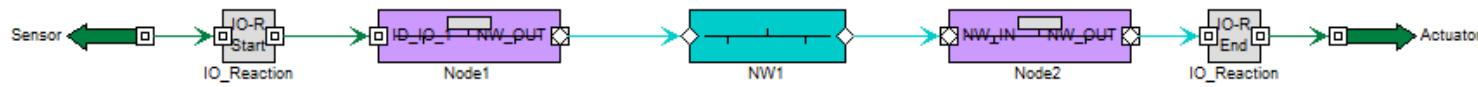
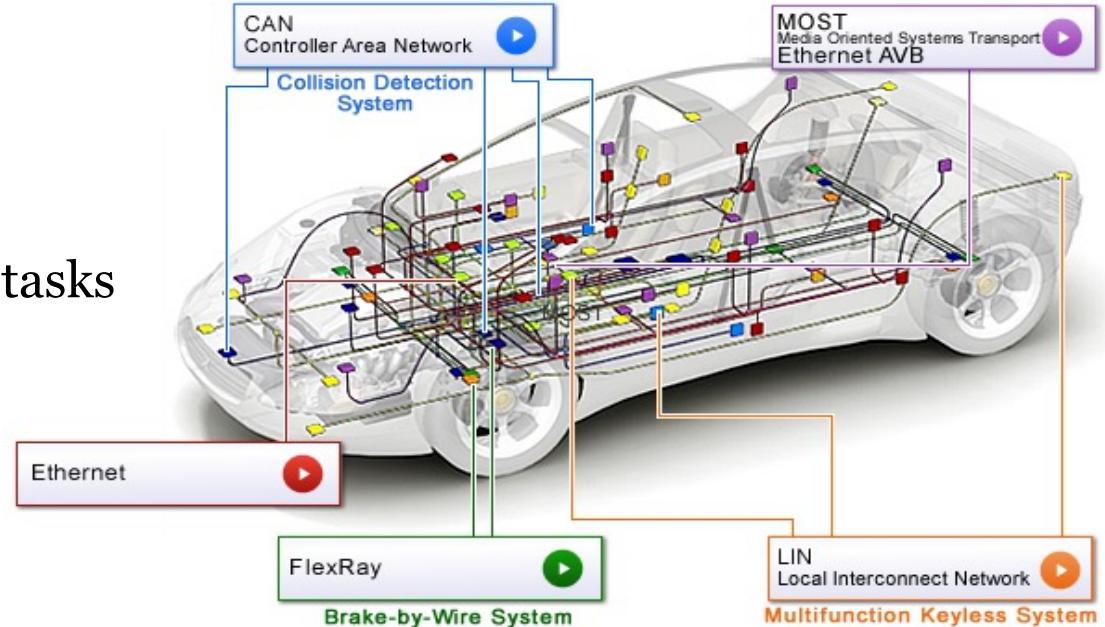
Assume Rate Monotonic priority assignment for the tasks and PCP.

- Calculate priority ceiling for each of the semaphores
- Calculate blocking factors for each of the tasks
- Calculate response times for the tasks

[ Home Practice]

# Outline

- Response-time analysis (RTA) of tasks
  - Basic RTA
  - RTA with blocking
  - RTA with jitter
  - RTA with Offsets
- RTA of Controller Area Network (CAN) messages
- Practical limitations in CAN Controllers and their effect on RTA for CAN
- Holistic RTA (for distributed systems)
- Data-propagation delay analysis
  - Single node systems
  - Distributed systems (End-to-end data-propagation delay analysis)



Figures courtesy of: <http://www.cvel.clemson.edu/>  
<http://www.renesas.eu>

## Response Time Analysis with release jitter

**We assumed until now that tasks get activated with perfect periodicity**

### **Release Jitter (J)**

- The difference between the earliest and the latest point in time a task starts to execute (relatively to the nominal start time)

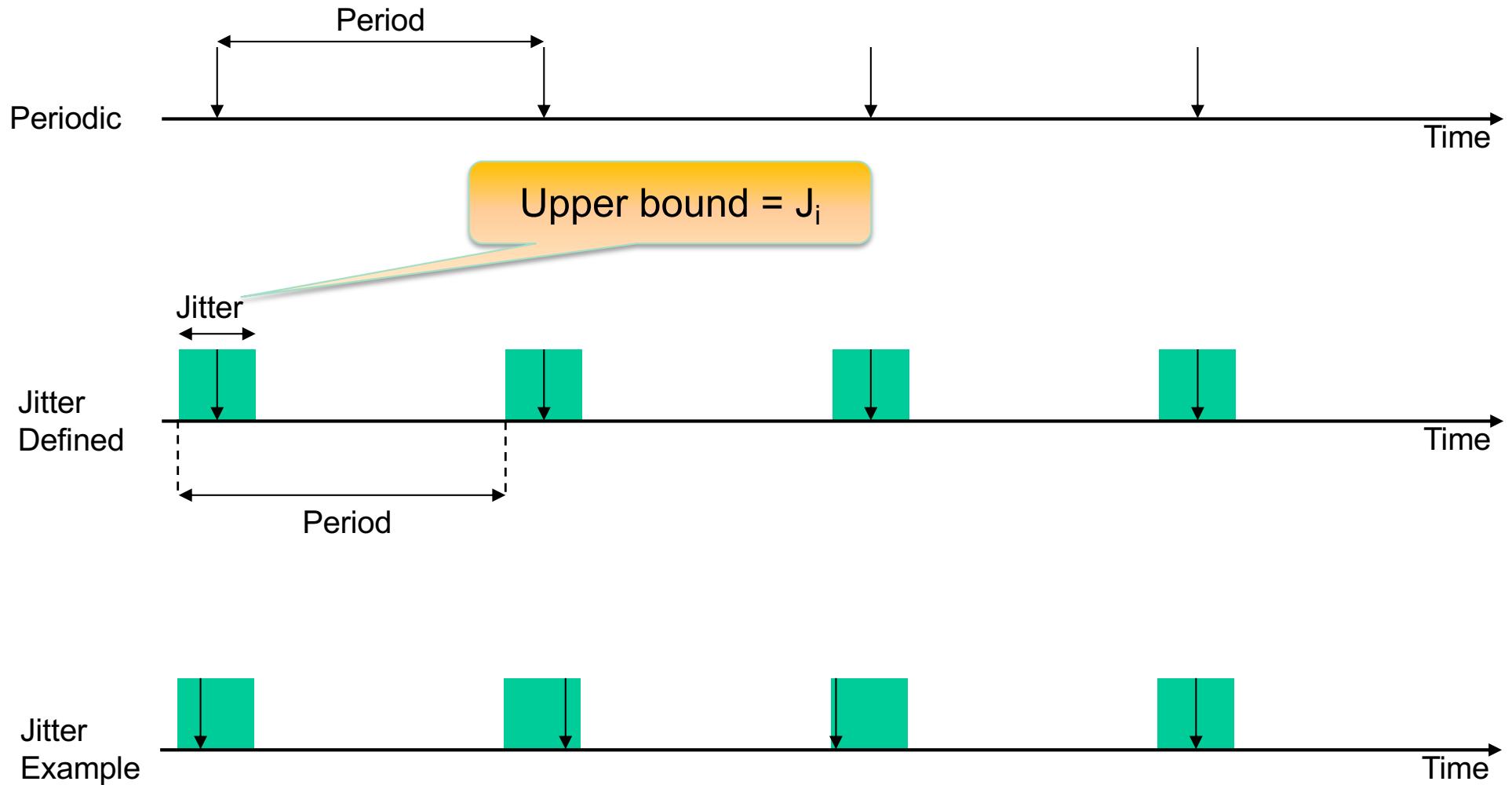
### **Jitter may have different causes**

- Task B is triggered by task A, which means that B's activation time may vary (e.g. A might not use its WCET)
- A sensor at node A triggers a task at node B. The message is sent over a network, and may take a varying amount of time to arrive
- Operating systems: Clock tick at 10ms. Want T=23
  - We want activation at 0, 23, 46, ...
  - OS is able to activate at 0, 30, 50, ...
  - The variation of the actual release times is jitter (0, 7, 4, ...).

### **Problem**

- Temporarily shorter periods → low priority tasks can miss deadline

## Jitter visualized



# Response Time Analysis with release jitter

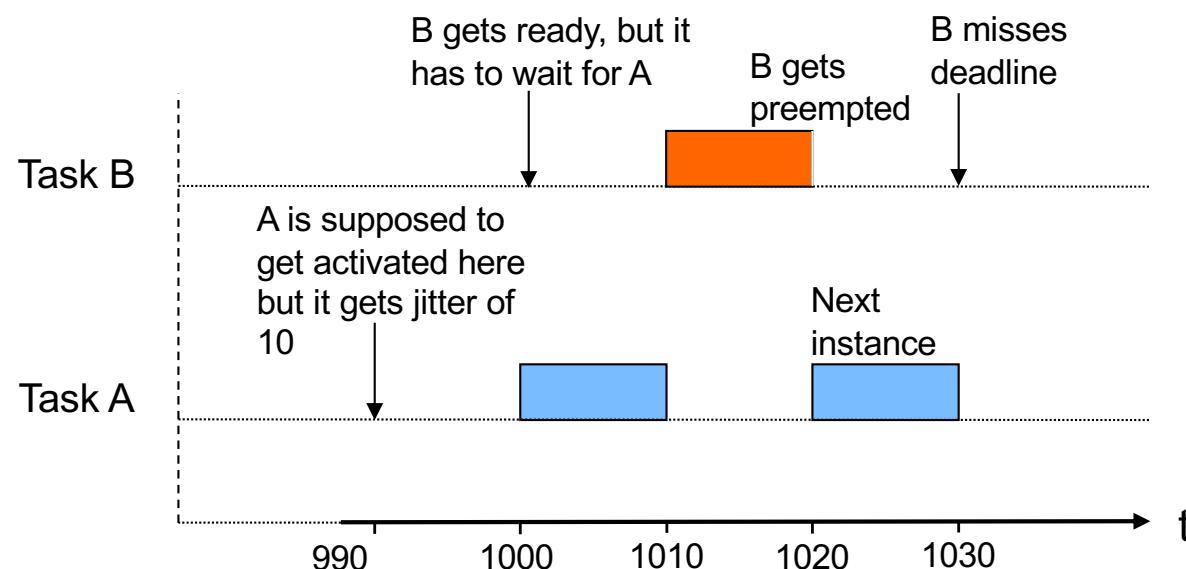
## Example:

Assume the following two tasks with calculated response times:

Task	T	D	C	R
A	30	20	10	10
B	1000	25	15	25

High priority  
Low priority

What happens if A has a release jitter of 10?





**RTA with  
release  
jitter**

## Response Time Analysis with release jitter

**Response time analysis must be updated with a release jitter term:**

$$J_i = J_i^{\max} - J_i^{\min}$$

New equation:

$$w_i^{n+1} = C_i + B_i + \sum_{\forall j \in hp(i)} \left\lceil \frac{w_i^n + J_j}{T_j} \right\rceil C_j$$

$$R_i = w_i + J_i^{\max}$$

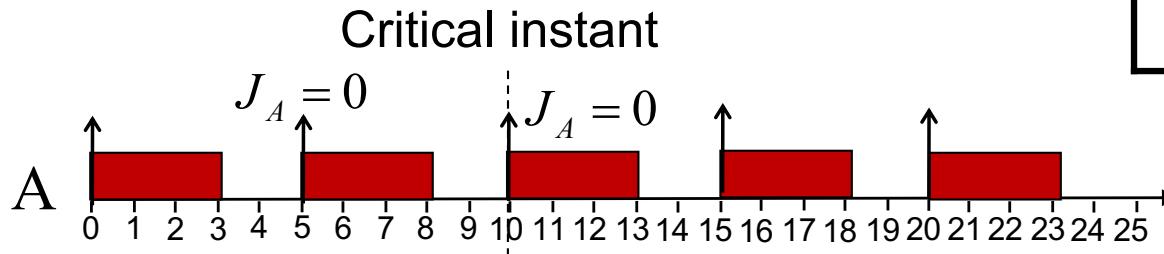
Original version of RM:

- Independent tasks  $\rightarrow J^{\max} = J^{\min} \rightarrow$  no release jitter!

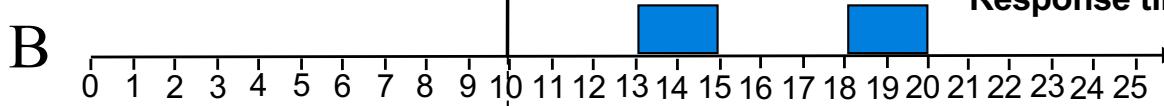
## Response Time Analysis with release jitter

What is the safe assumption about the critical instant?

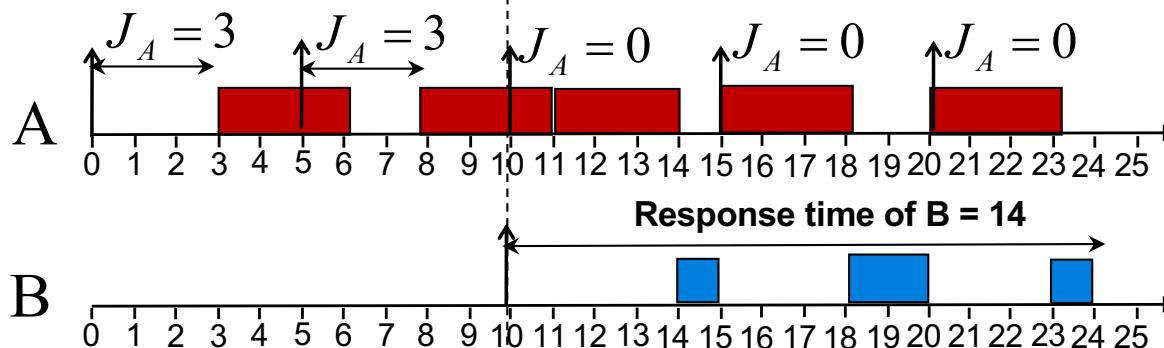
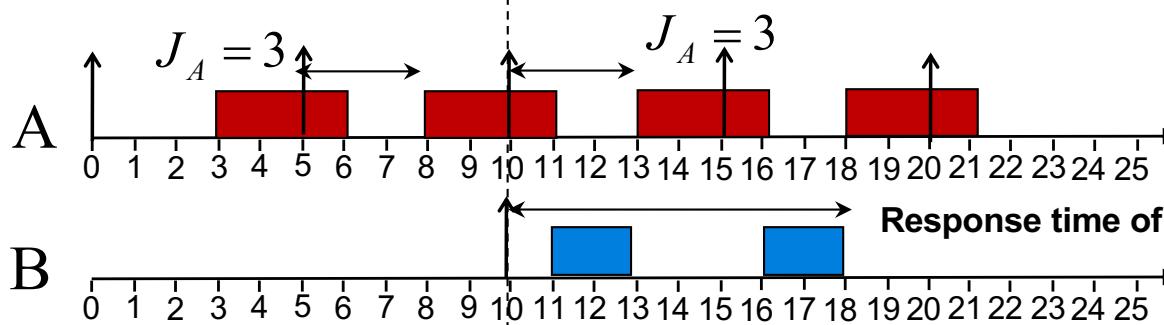
Task	P	C	T	$J_{\max}$	$J_{\min}$
A	High	3	5	3	0
B	Low	4	50	0	0



All instances of task A experience  $J_{\min}$



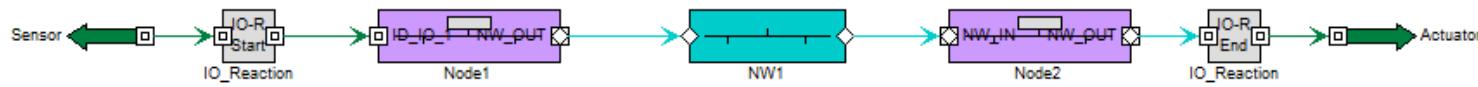
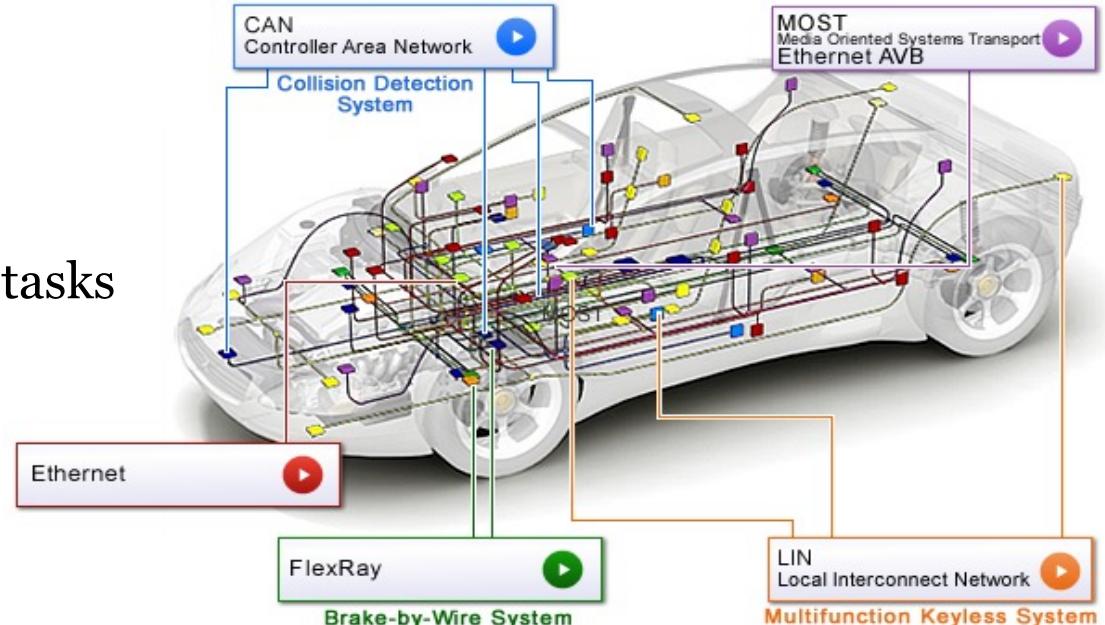
All instances of task A experience  $J_{\max}$



- All instances of task A that occur before the critical instant experience  $J_{\max}$
- All instances of task A that occur at or after the critical instant experience  $J_{\min}$

# Outline

- Response-time analysis (RTA) of tasks
  - Basic RTA
  - RTA with blocking
  - RTA with jitter
  - RTA with Offsets
- RTA of Controller Area Network (CAN) messages
- Practical limitations in CAN Controllers and their effect on RTA for CAN
- Holistic RTA (for distributed systems)
- Data-propagation delay analysis
  - Single node systems
  - Distributed systems (End-to-end data-propagation delay analysis)

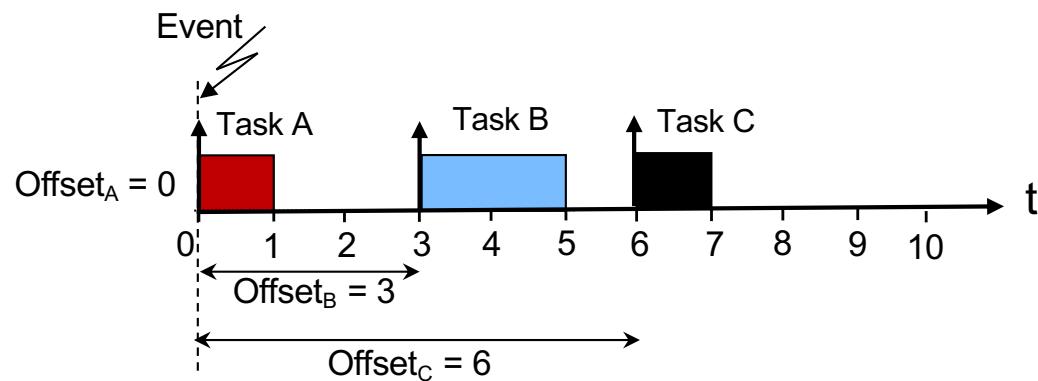


Figures courtesy of: <http://www.cvel.clemson.edu/>  
<http://www.renesas.eu>

# Offsets in real-time scheduling

## What is an offset?

- Externally imposed time interval between the arrival of the triggering event and release of the task.
- A fixed time interval between the arrival of sets of tasks.
  - An offset specifies temporal dependency between releases of tasks
- Example: some task activations are statically scheduled: Time triggered



# Offsets in real-time scheduling

---

## Why offsets?

- What if tasks cannot be released simultaneously?
  - Example: the release of a task  $\tau_i$  will occur  $O$  time units after the release of task  $\tau_j$
  - Everything in the system may not happen at once.
- Response times of tasks (especially with lower priority) increase with the increase in the system load.
  - Response times of lower priority tasks can be reduced if the tasks are scheduled with offsets.
- In order to avoid deadlines violations due to high transient loads, embedded systems are often scheduled with offsets.

# Offsets in real-time scheduling

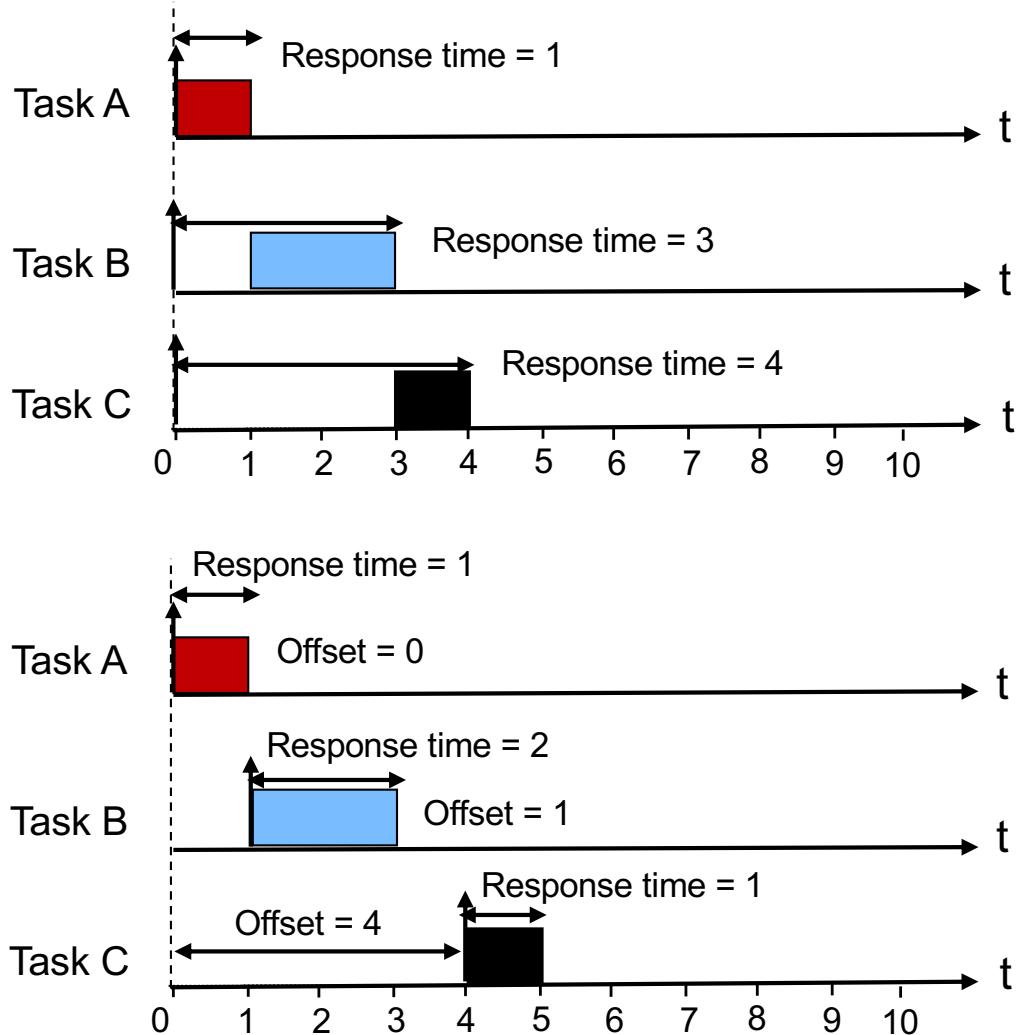
Why offsets?

Example:

No offsets

Task	Prio	T	C
A	High	10	1
B	Medium	10	2
C	Low	10	1

With offsets



## Task model with offsets

---

- Introducing temporal dependencies between tasks
  - Tasks are grouped into transactions and assigned offsets

$$\Gamma = \{\Gamma_1, \Gamma_2, \dots, \Gamma_n\} \quad \Gamma_i = \langle \{\tau_{i1}, \tau_{i2}, \dots, \tau_{in}\}, T_i \rangle \quad \tau_{ij} = \langle C_{ij}, O_{ij}, P_{ij} \rangle$$

### Notations

$\Gamma$  -- System       $\Gamma_i$  -- Transaction "i"       $T_i$  -- Transaction period

$\tau_{ij}$  -- Task "j" belonging to transaction  $\Gamma_i$

$C_{ij}$  -- Worst-case execution time of  $\tau_{ij}$

$O_{ij}$  -- Offset of  $\tau_{ij}$        $P_{ij}$  -- Priority of  $\tau_{ij}$

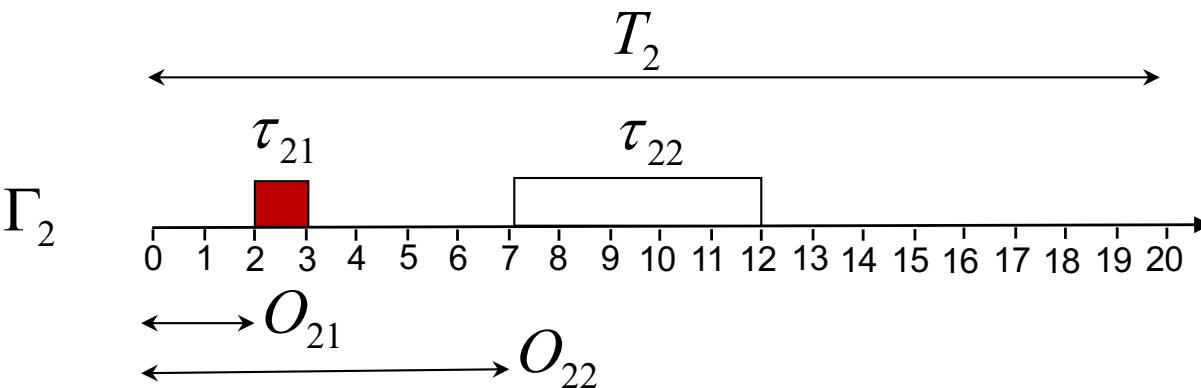
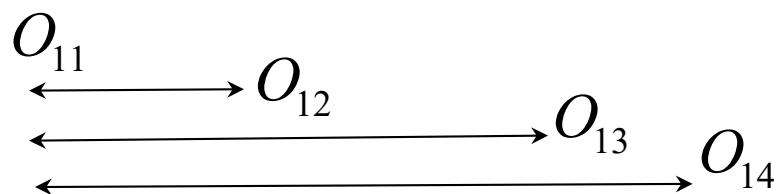
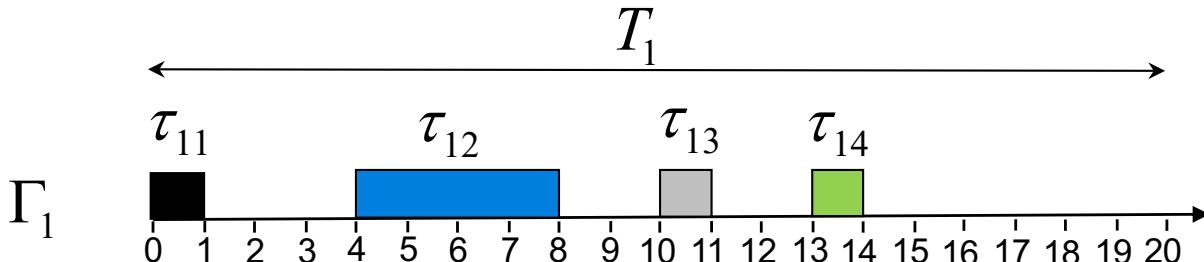
$\tau_{ua}$  -- Task "a" belonging to transaction  $\Gamma_u$

We overload this notation to represent "task under analysis"

$hp_i(\tau_{ua})$  -- All higher priority tasks to  $\tau_{ua}$  in transaction  $\Gamma_i$

# Task model with offsets

## Example of a system with two transactions



$$\Gamma = \{\Gamma_1, \Gamma_2, \dots, \Gamma_n\} \quad \Gamma_i = \langle \{\tau_{i1}, \tau_{i2}, \dots, \tau_{in}\}, T_i \rangle \quad \tau_{ij} = \langle C_{ij}, O_{ij}, P_{ij} \rangle$$

### Notations

$\Gamma$  -- System       $\Gamma_i$  -- Transaction "i"       $T_i$  -- Transaction period

$\tau_{ij}$  -- Task "j" belonging to transaction  $\Gamma_i$

$C_{ij}$  -- Worst-case execution time of  $\tau_{ij}$

$O_{ij}$  -- Offset of  $\tau_{ij}$

$P_{ij}$  -- Priority of  $\tau_{ij}$

$\tau_{ua}$  -- Task "a" belonging to transaction  $\Gamma_u$

We overload this notation to represent "task under analysis"

$hp_i(\tau_{ua})$  -- All higher priority tasks to  $\tau_{ua}$  in transaction  $\Gamma_i$

5



**RTA with  
Offsets**

## Critical Instant assumption in RTA without offsets

---

Response time for a task  $\tau_i$  :

1. Critical instant: Assume all tasks with the higher priority than  $\tau_i$  are **ready at the same time** as  $\tau_i$
2. Critical instant will occur when a task is **released simultaneously** with the release of all higher priority tasks

$$R_i^{n+1} = C_i + \text{interference due to all higher priority tasks}$$

$$R_i^{n+1} = C_i + \sum_{\forall j \in hp(i)} \left\lceil \frac{R_i^n}{T_j} \right\rceil C_j$$

## Critical Instant assumption in RTA with offsets

---

**Is the critical instant assumption still valid?**

- All tasks cannot be released simultaneously

**Assumption in RTA with offsets**

- At least one task out of every transaction coincides with the critical instant of  $\tau_{ua}$
- Only tasks with priority higher than  $\tau_{ua}$  are considered

**However, it is not known which task coincides with (released at) the critical instant**

- Every higher priority task in a transaction must be treated as a candidate to coincide with the critical instant
- Every possible combination of critical instant candidates must be considered including  $\tau_{ua}$

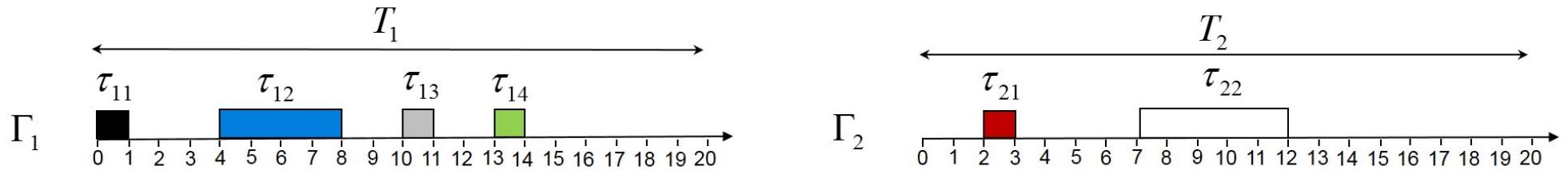
$$R_{uac}^{n+1} = C_i + \text{interference due to all higher priority tasks}$$

$$R_{ua} = \max_{\forall c \text{ combinations}} (R_{uac})$$

## Critical Instant assumption in RTA with offsets

**Example:** Assume priority of  $\tau_{1j}$  are high, priority of  $\tau_{2j}$  are medium

Assume  $\tau_{ua}$  be the task under analysis having the lowest priority.



**Critical Instant (CI) combination 1:** Let  $\tau_{11}, \tau_{21}$  coincide with CI of  $\tau_{ua}$

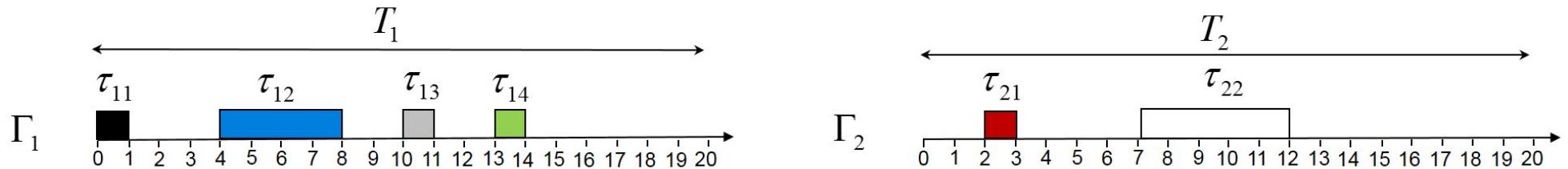
A vertical dashed line marks the Critical Instant (CI) at time 1.

$CI_{\tau_{ua}}$

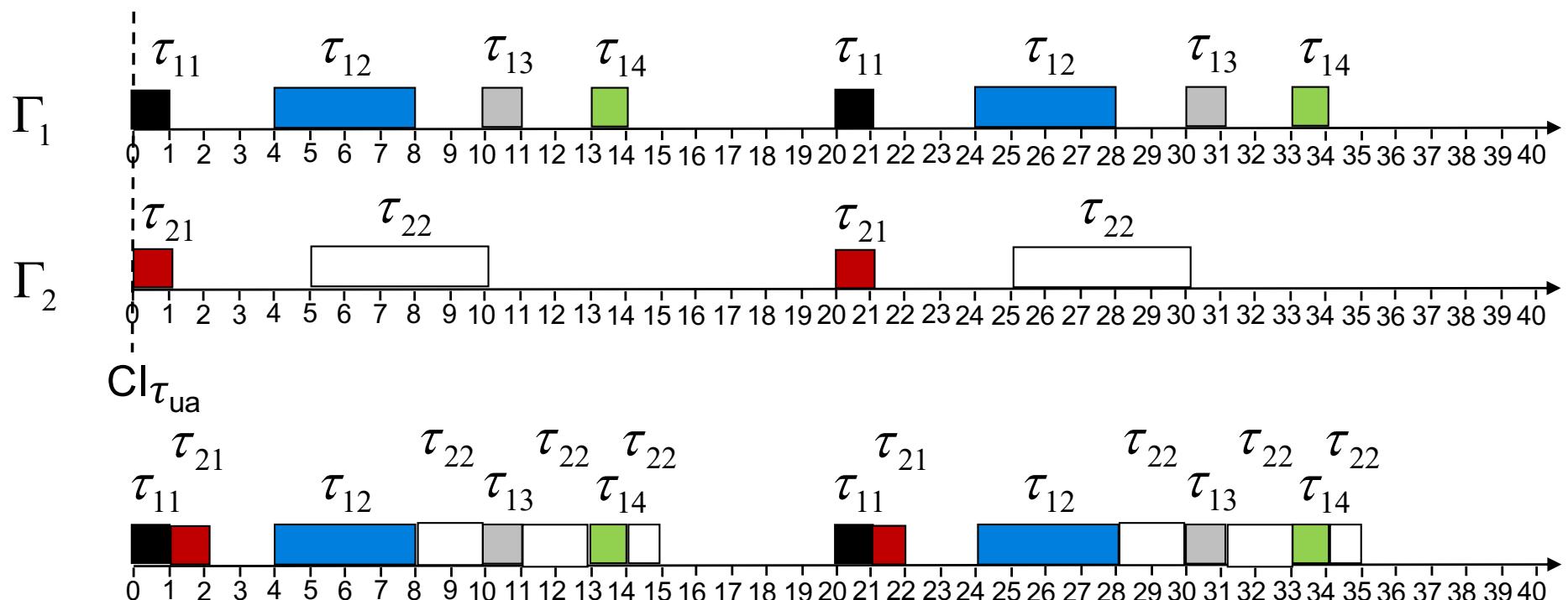
## Critical Instant assumption in RTA with offsets

**Example:** Assume priority of  $\tau_{1j}$  are high, priority of  $\tau_{2j}$  are medium

Assume  $\tau_{ua}$  be the task under analysis having the lowest priority.



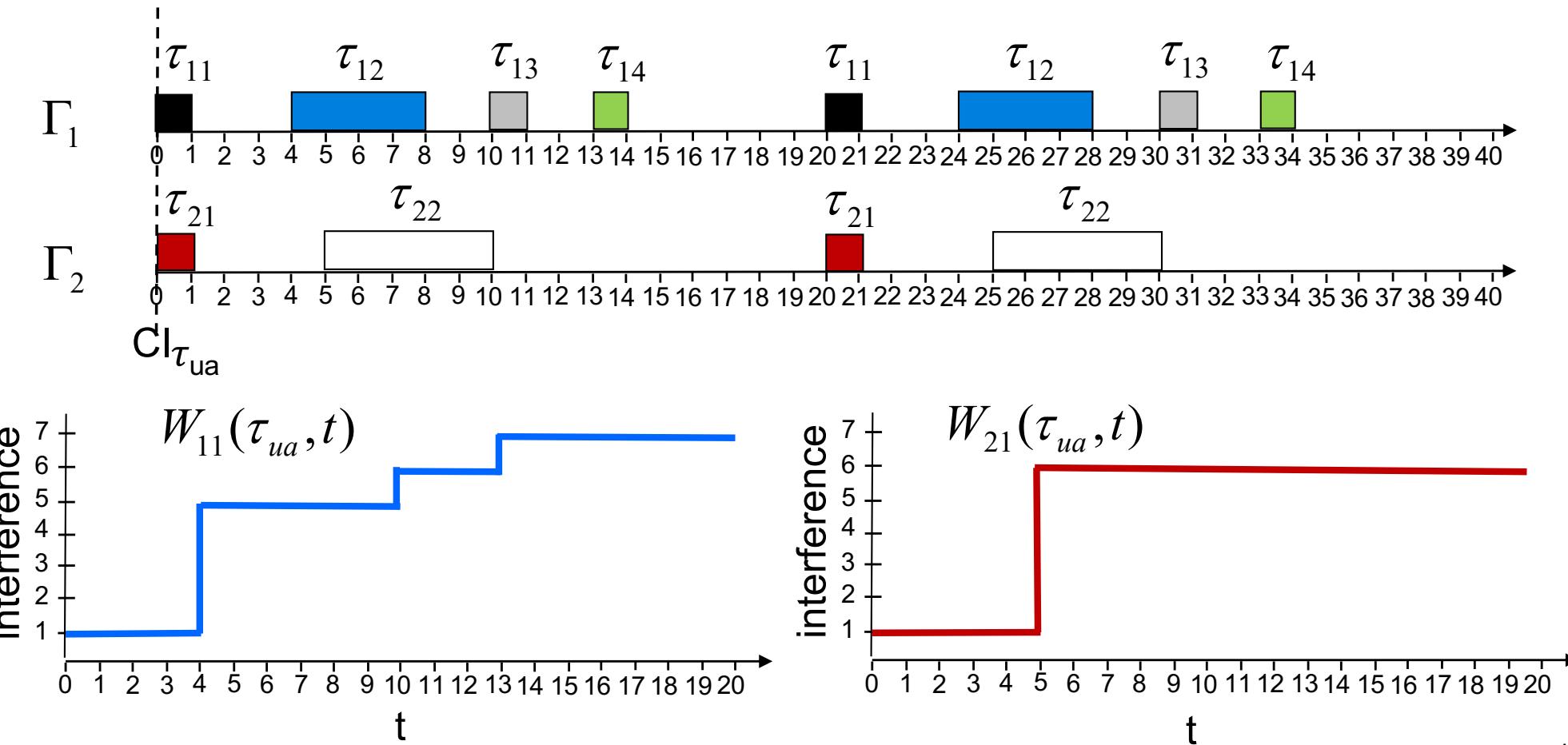
**Critical Instant (CI) combination 1:** Let  $\tau_{11}, \tau_{21}$  coincide with CI of  $\tau_{ua}$



## Critical Instant assumption in RTA with offsets

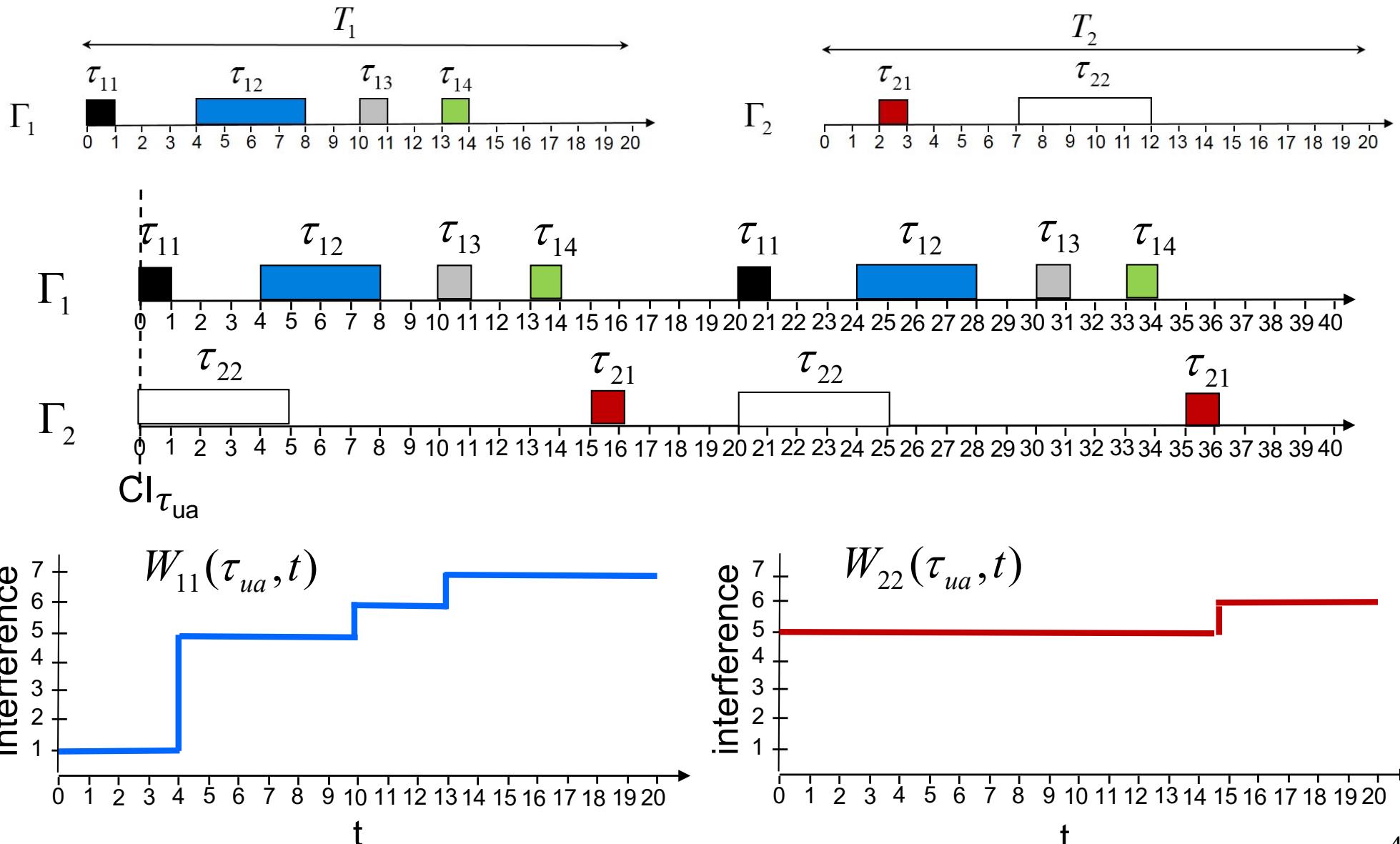
**Critical Instant (CI) combination 1:** Let  $\tau_{11}, \tau_{21}$  coincide with CI of  $\tau_{ua}$

$W_{ic}(\tau_{ua}, t) =$  interference from  $\Gamma_i$  for critical instant candidate  $\tau_{ic}$   
 experienced by a low priority task  $\tau_{ua}$  belonging to  $\Gamma_u$



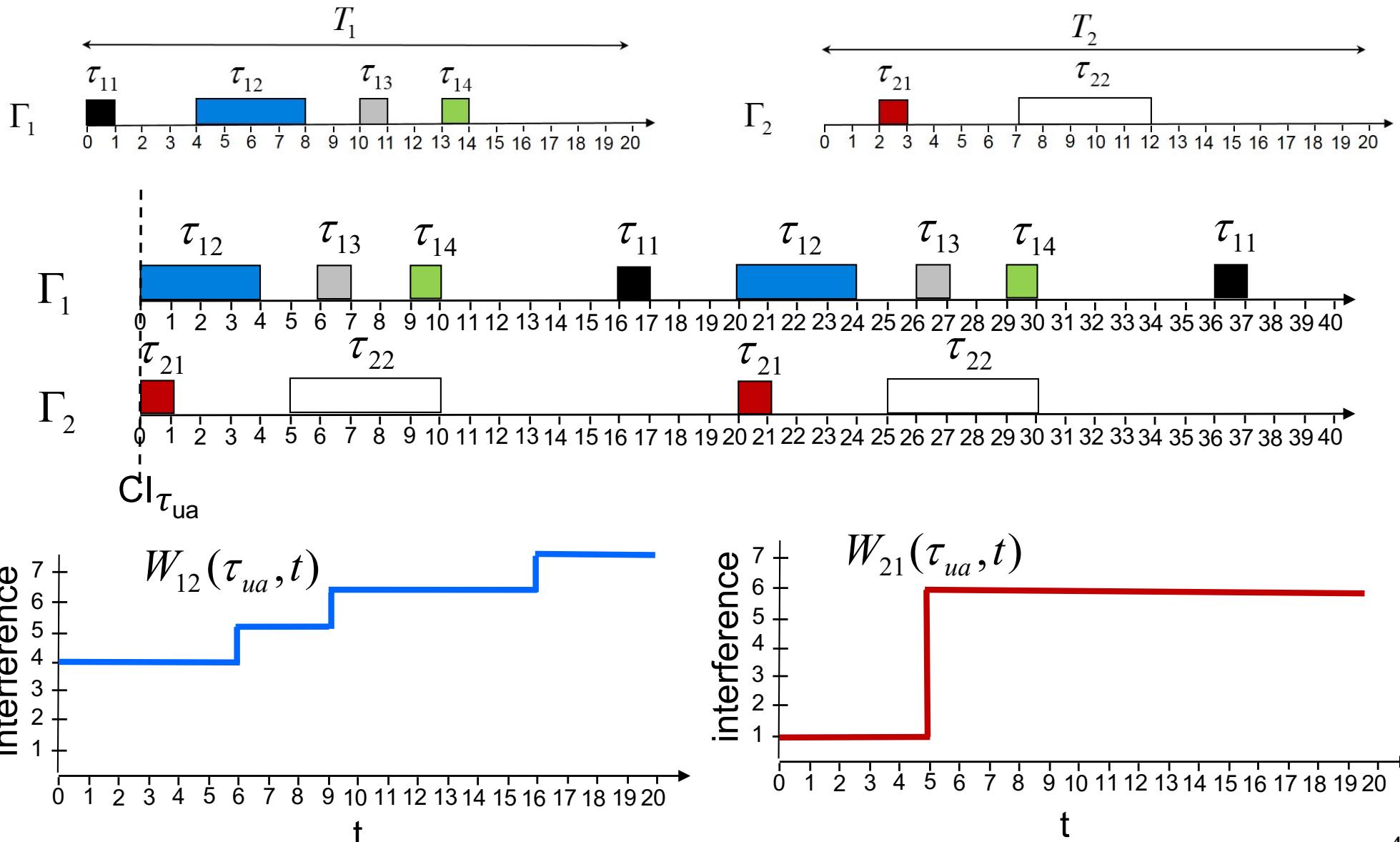
## Critical Instant assumption in RTA with offsets

**Critical Instant (CI) combination 2:** Let  $\tau_{11}, \tau_{22}$  coincide with CI of  $\tau_{ua}$



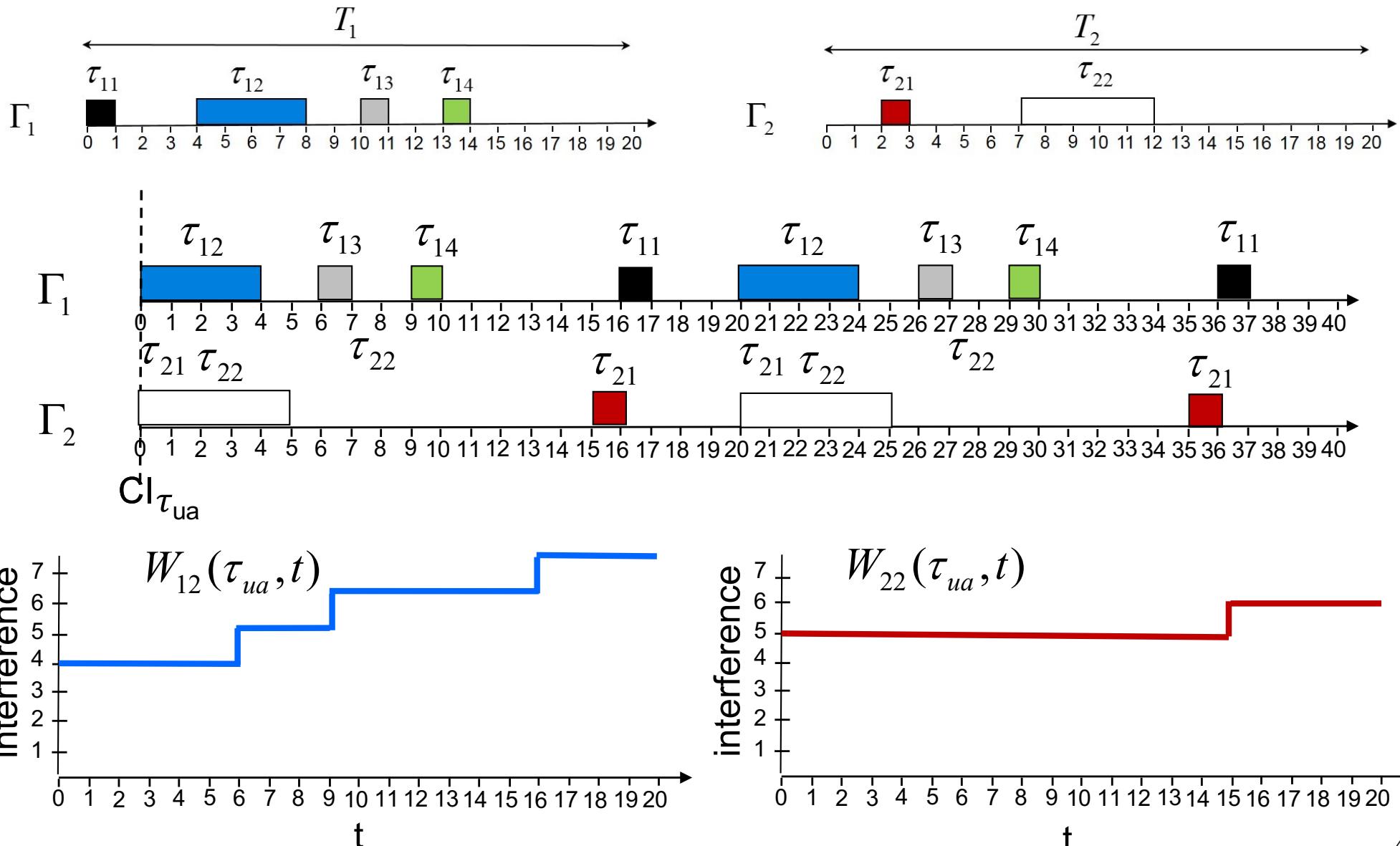
## Critical Instant assumption in RTA with offsets

**Critical Instant (CI) combination 3:** Let  $\tau_{12}, \tau_{21}$  coincide with CI of  $\tau_{ua}$



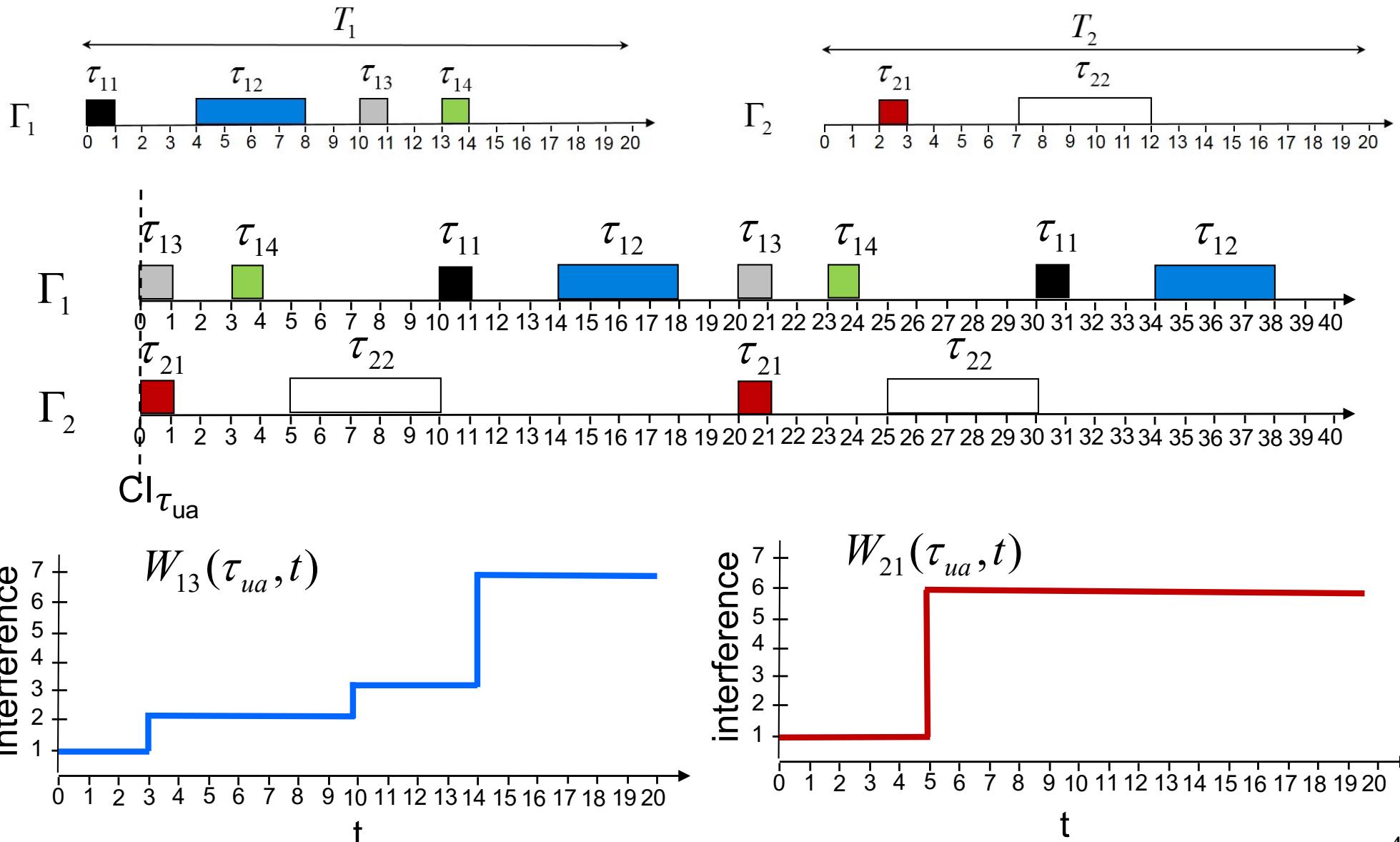
## Critical Instant assumption in RTA with offsets

**Critical Instant (CI) combination 4:** Let  $\tau_{12}, \tau_{22}$  coincide with CI of  $\tau_{ua}$



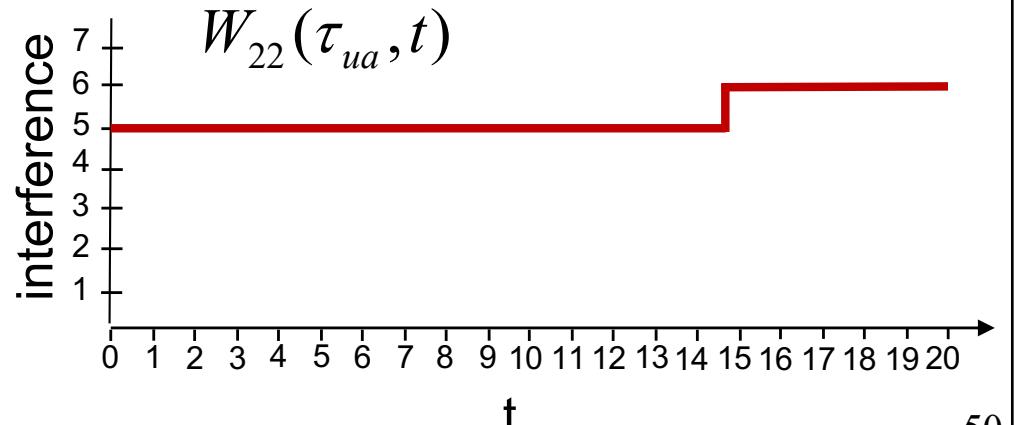
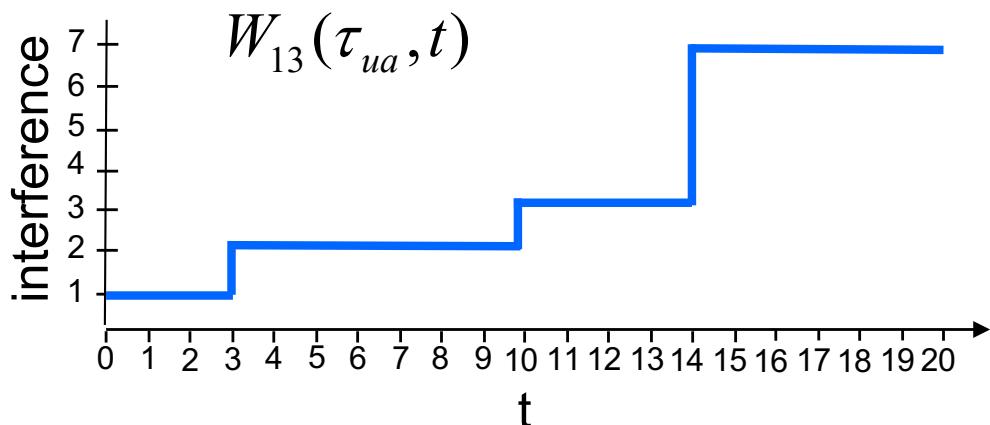
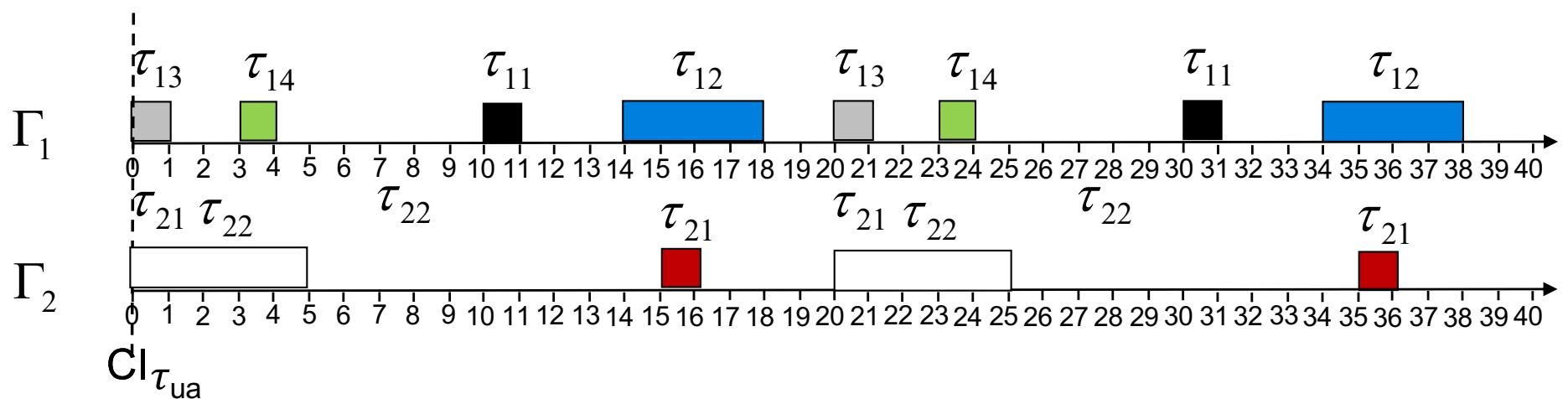
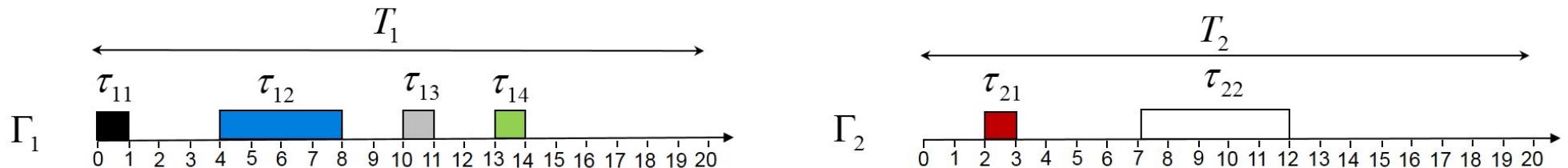
## Critical Instant assumption in RTA with offsets

**Critical Instant (CI) combination 5:** Let  $\tau_{13}, \tau_{21}$  coincide with CI of  $\tau_{ua}$



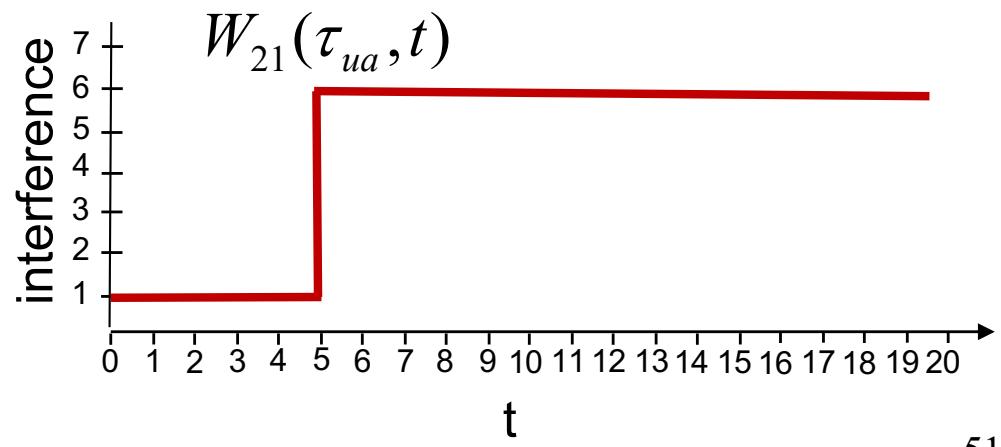
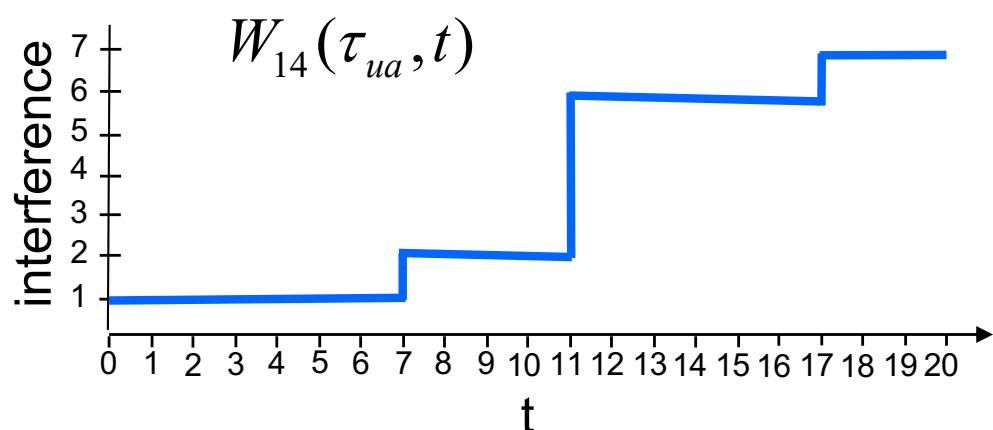
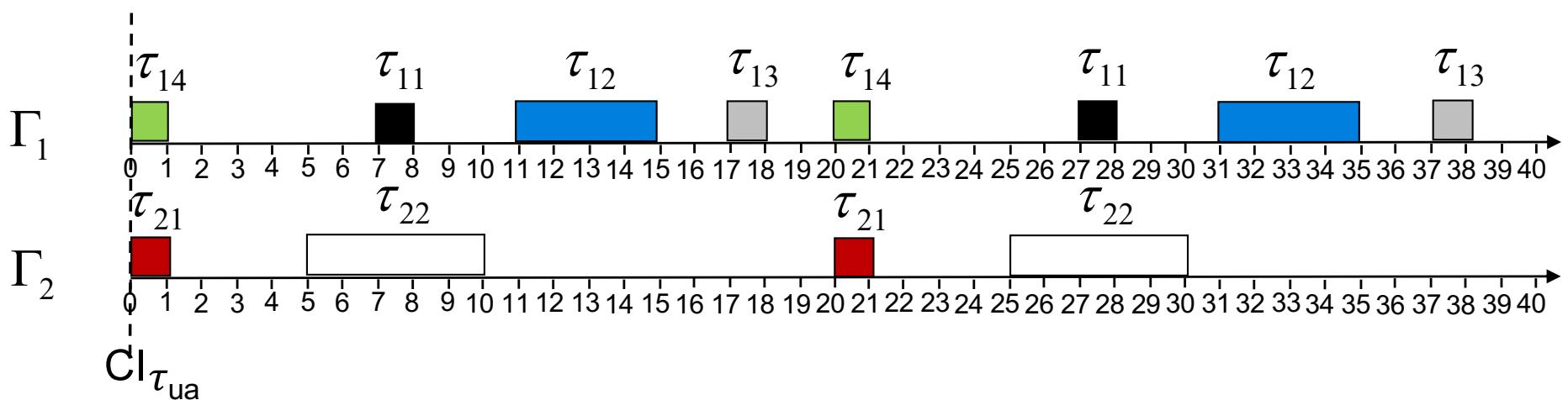
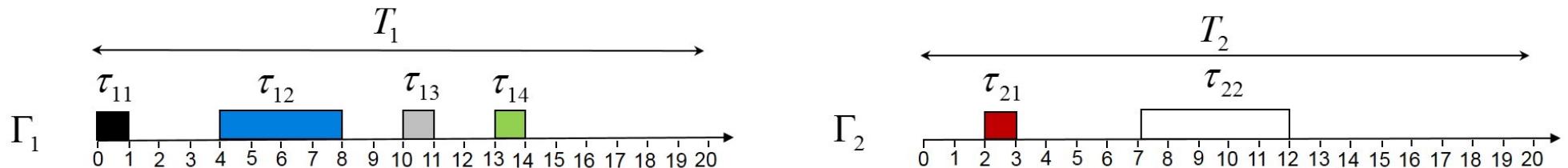
## Critical Instant assumption in RTA with offsets

**Critical Instant (CI) combination 6:** Let  $\tau_{13}, \tau_{22}$  coincide with CI of  $\tau_{ua}$



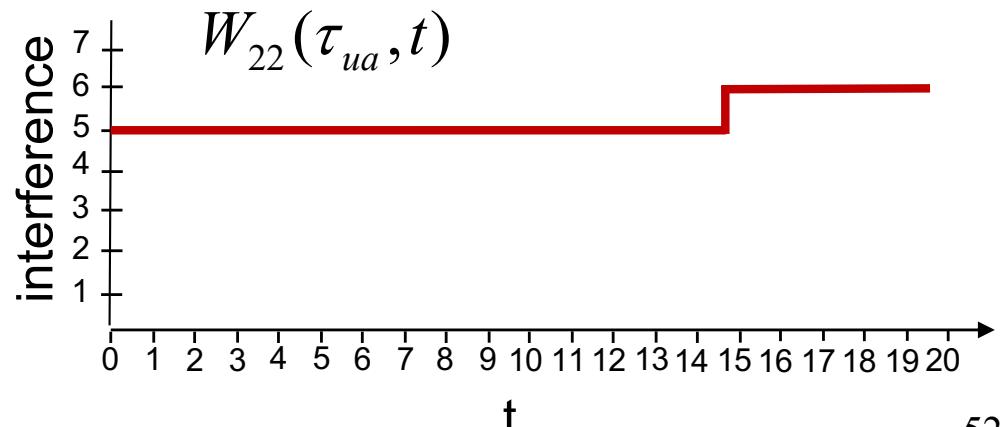
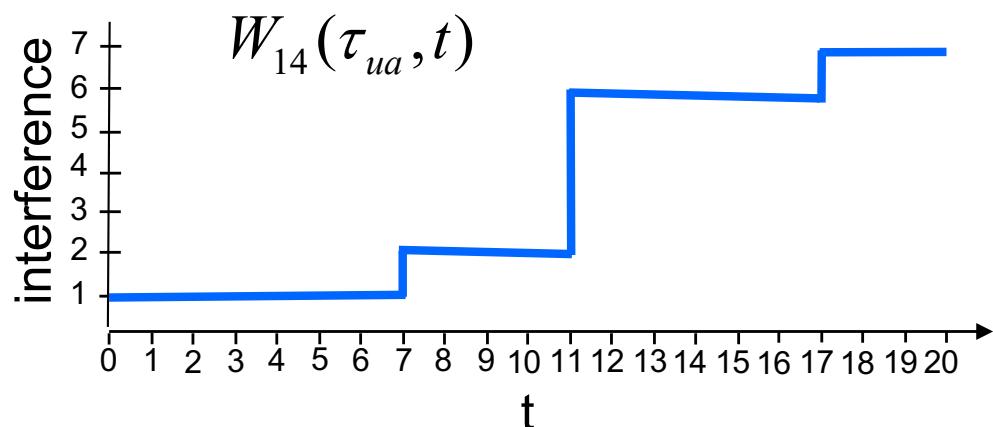
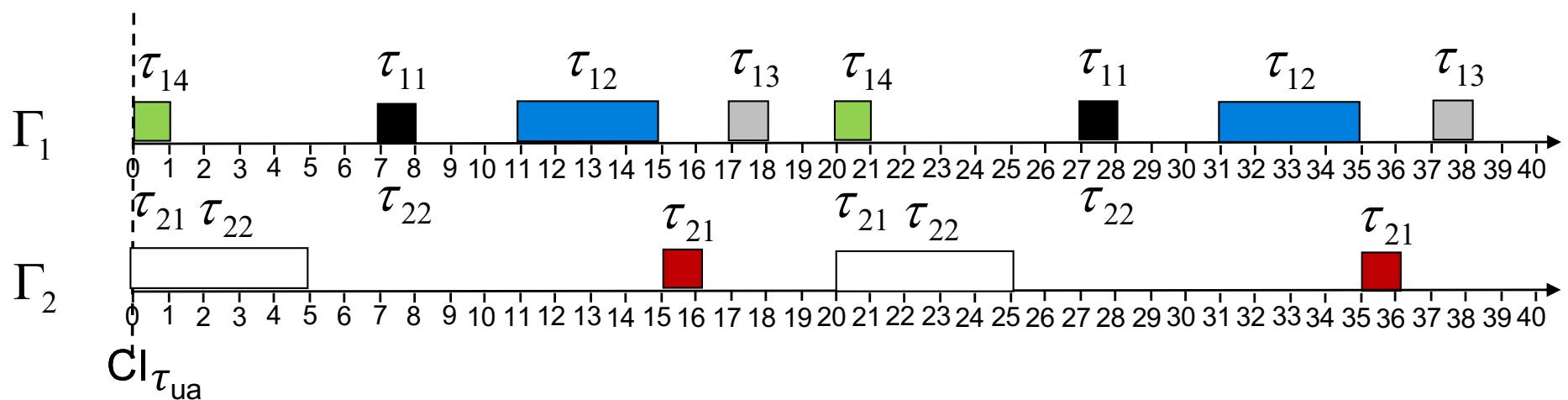
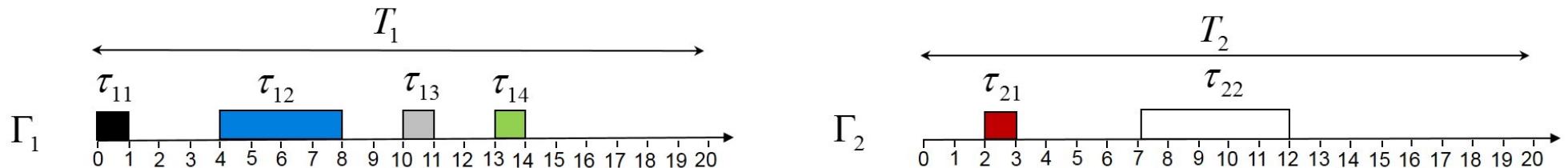
## Critical Instant assumption in RTA with offsets

**Critical Instant (CI) combination 7:** Let  $\tau_{14}, \tau_{21}$  coincide with CI of  $\tau_{ua}$



## Critical Instant assumption in RTA with offsets

**Critical Instant (CI) combination 8:** Let  $\tau_{14}, \tau_{22}$  coincide with CI of  $\tau_{ua}$



## Calculations for the RTA with offsets

---

Calculations for response time of  $\tau_{ua}$  denoted by  $R_{uac}$   
for the Critical Instant combination

$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall i} W_{ic}(\tau_{ua}, R_{uac}^n)$$

$$W_{ic}(\tau_{ua}, t) = \sum_{\forall j \in hp_i(\tau_{ua})} \left\lceil \frac{t - \Phi_{ijc}}{T_i} \right\rceil C_{ij}$$

$$\Phi_{ijc} = (O_{ij} - O_{ic}) \bmod T_i$$

$$R_{ua} = \max_{\forall c \text{ combinations}} (R_{uac})$$

## Exact RTA with offsets VS Approximate RTA with offsets

$$R_{ua} = \max_{\forall c \text{ combinations}} (R_{uac})$$

That is the response time of  $\tau_{ua}$  is the maximum of calculated response times for all critical instant combinations.

**Exact analysis tries every potential critical instant: intractable!**

- In this previous example, 2 transactions with 4 and 2 tasks results in  $4*2= 8$  combinations
- Example: 4 transactions with 3, 10, 5, and 10 tasks results in  $3*10*5*10 = 1500$  combinations

**Approximate approach: build abstraction of each transaction**

$$R_{ua}^{n+1} = C_{ua} + \sum_{\forall i} W_i^*(\tau_{ua}, R_{ua}^n)$$

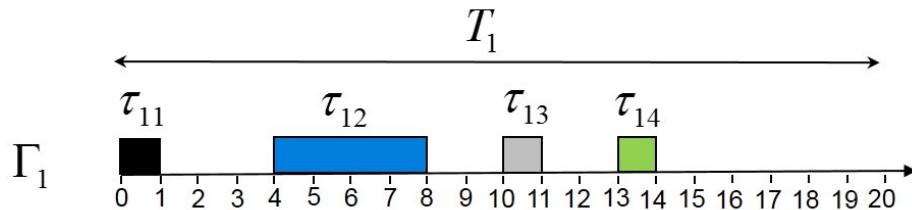
$$W_i^*(\tau_{ua}, R_{ua}^n) = \max_{\forall c} (W_{ic}(\tau_{ua}, R_{ua}^n)) \quad \Phi_{ijc} = (O_{ij} - O_{ic}) \bmod T_i$$

$$W_{ic}(\tau_{ua}, R_{ua}^n) = \sum_{\forall j \in hpi(\tau_{ua})} \left\lceil \frac{R_{ua}^n - \Phi_{ijc}}{T_i} \right\rceil C_{ij}$$

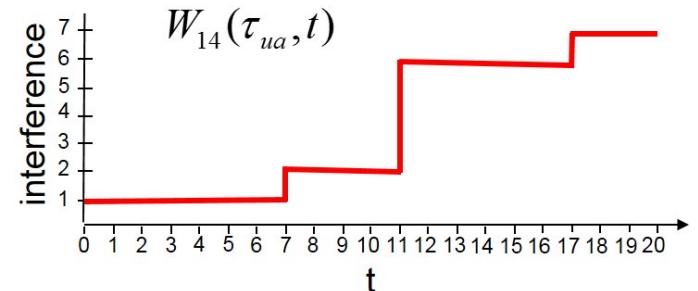
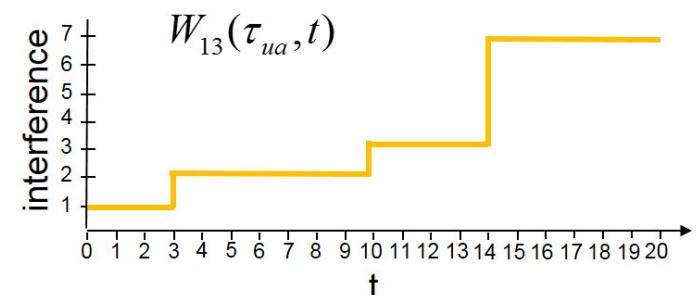
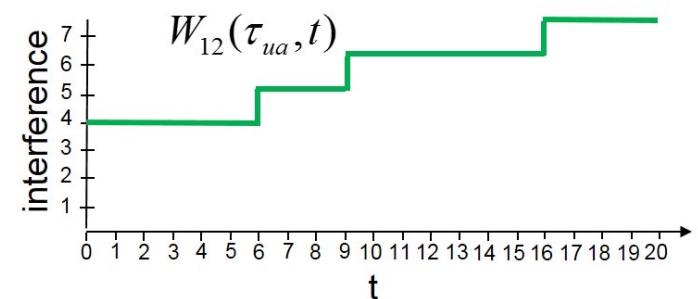
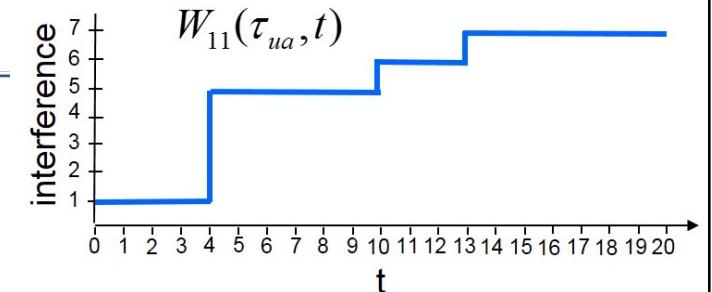
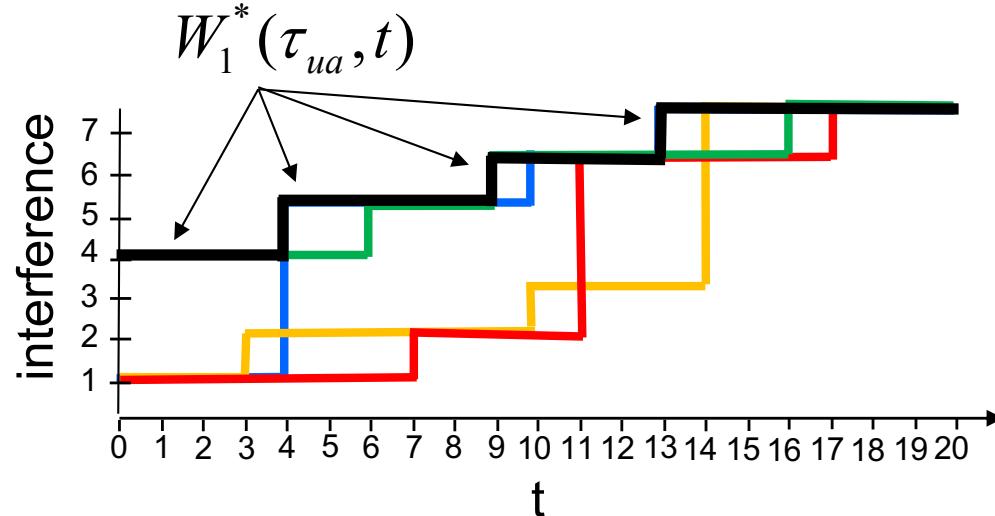
## Approximate RTA with offsets

Approximate analysis considers maximum interference from each transaction

Consider the same example



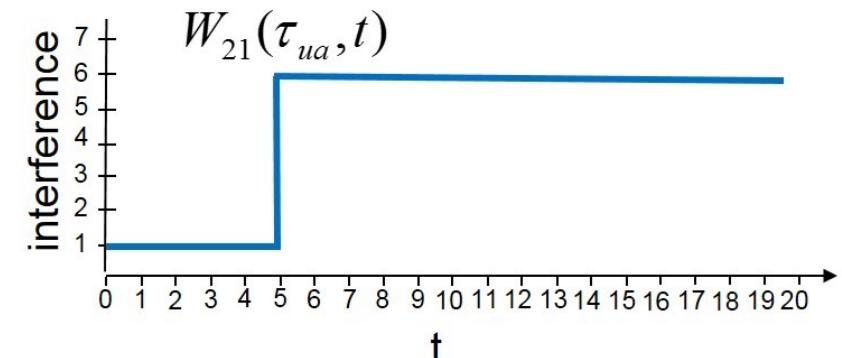
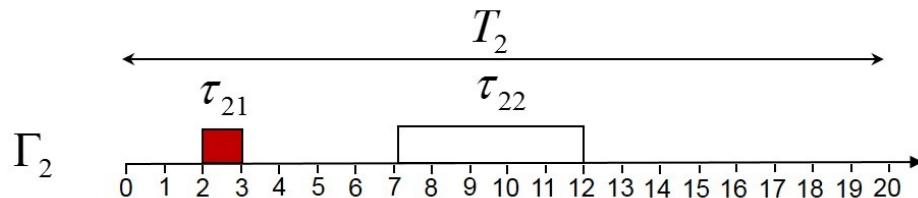
Maximum interference function due to  $\Gamma_1$



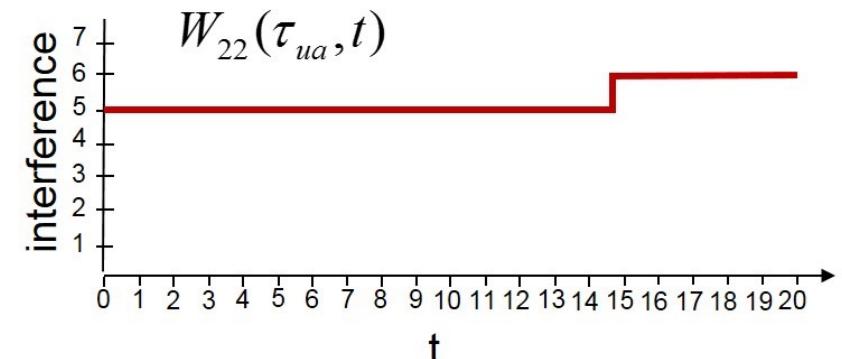
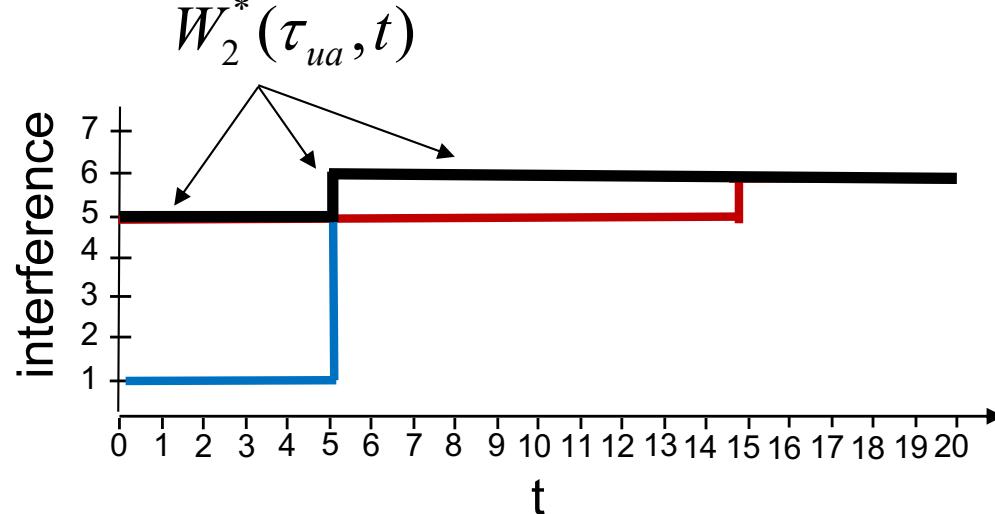
## Approximate RTA with offsets

Approximate analysis considers maximum interference from each transaction

Consider the same example



Maximum interference function due to  $\Gamma_2$



## Example of Response Time Analysis with Offsets

*Saad Mubeen*



## Appendix: Response Time Formulae

### Exact Analysis

Calculations for response time of  $\tau_{ua}$  denoted by  $R_{uac}$   
for the Critical Instant combination

$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall i} W_{ic}(\tau_{ua}, R_{uac}^n)$$

$$W_{ic}(\tau_{ua}, t) = \sum_{\forall j \in hp_i(\tau_{ua})} \left\lceil \frac{t - \Phi_{ijc}}{T_i} \right\rceil C_{ij}$$

$$\Phi_{ijc} = (O_{ij} - O_{ic}) \bmod T_i$$

## Appendix: Response Time Formulae

### Approximate Analysis

Calculations for response time of  $\tau_{ua}$  denoted by  $R_{ua}$

$$R_{ua}^{n+1} = C_{ua} + \sum_{\forall i} W_i^*(\tau_{ua}, R_{ua}^n)$$

$$W_i^*(\tau_{ua}, R_{ua}^n) = \max_{\forall c} (W_{ic}(\tau_{ua}, R_{ua}^n))$$

$$W_{ic}(\tau_{ua}, R_{ua}^n) = \sum_{\forall j \in hpi(\tau_{ua})} \left\lceil \frac{R_{ua}^n - \Phi_{ijc}}{T_i} \right\rceil C_{ij}$$

$$\Phi_{ijc} = (O_{ij} - O_{ic}) \bmod T_i$$

## Example: Response Time Analysis (RTA) with offsets

$$\Gamma = \{\Gamma_1, \Gamma_2, \Gamma_3\} \quad \Gamma_i = \langle \{\tau_{i1}, \tau_{i2}, \dots, \tau_{i2n}\}, T_i \rangle \quad \tau_{ij} = \langle C_{ij}, O_{ij}, P_{ij} \rangle$$

$$\Gamma_1 = \langle \{\tau_{11}, \tau_{12}\}, 10 \rangle \quad \tau_{11} = \langle 2, 2, 5 \rangle \quad \tau_{12} = \langle 1, 5, 4 \rangle \quad \begin{matrix} \text{Prio (5) = Highest} \\ \text{Prio (1) = Lowest} \end{matrix}$$

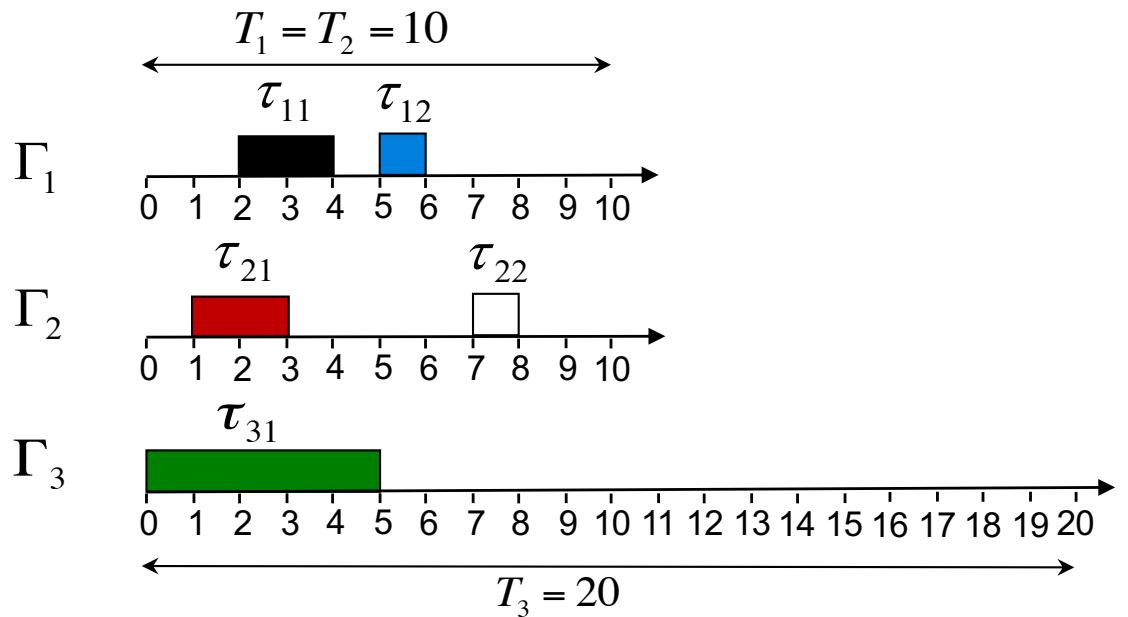
$$\Gamma_2 = \langle \{\tau_{21}, \tau_{22}\}, 10 \rangle \quad \tau_{21} = \langle 2, 1, 3 \rangle \quad \tau_{22} = \langle 1, 7, 2 \rangle$$

$$\Gamma_3 = \langle \{\tau_{31}\}, 20 \rangle \quad \tau_{31} = \langle 5, 0, 1 \rangle$$

**Calculate the response times  
of all tasks using**

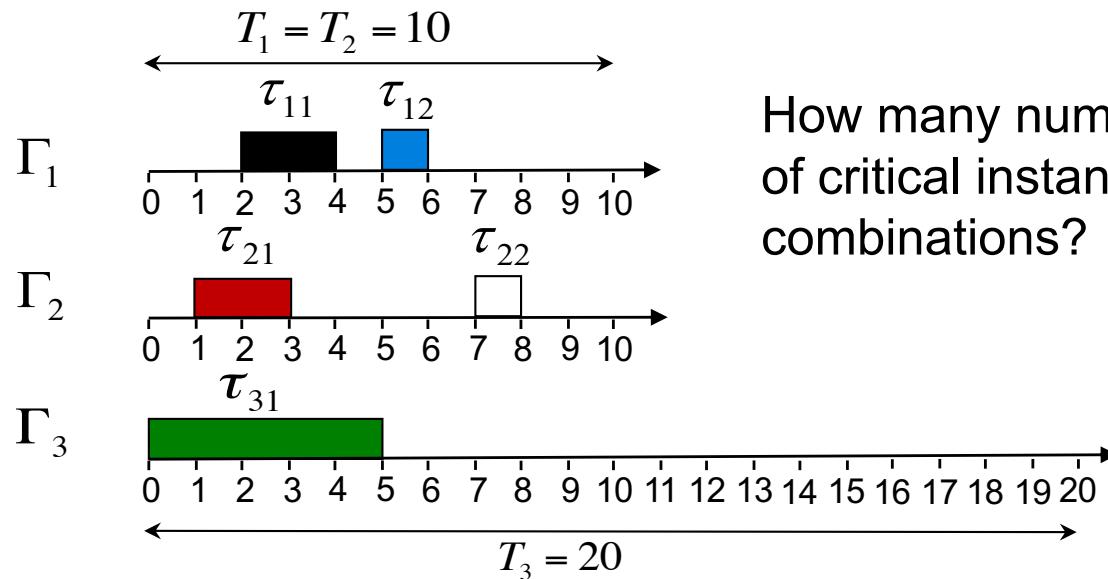
**(a) Exact analysis**

**(b) Approximate analysis**

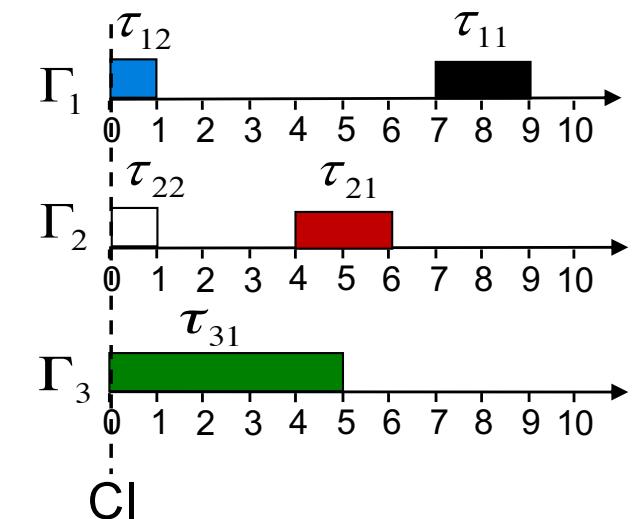
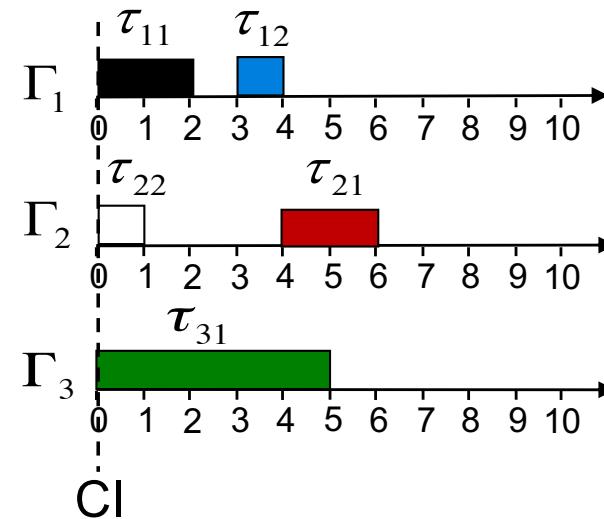
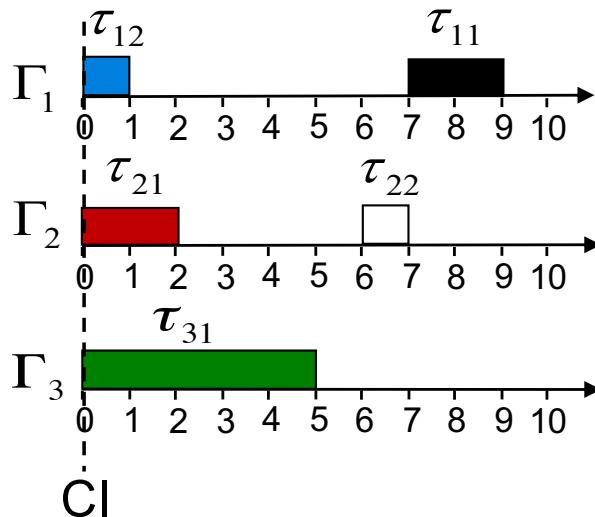
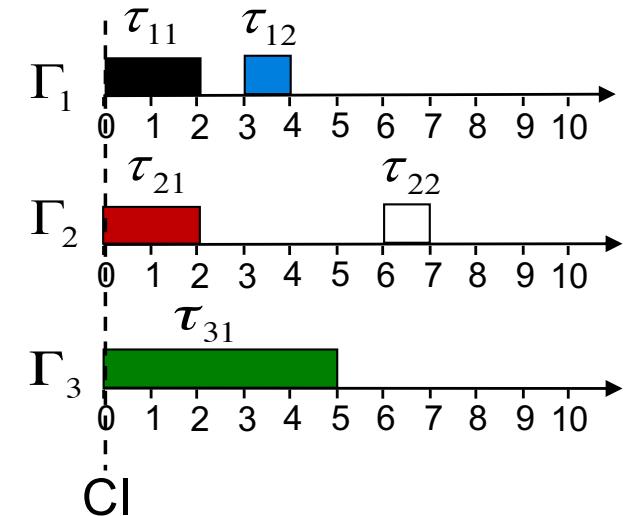


## Example: Response Time Analysis (RTA) with offsets

Let  $\tau_{31}$  be the task under analysis, i.e.,  $\tau_{ua}$



How many number  
of critical instant  
combinations?



## Example: RTA with offsets using Exact Analysis

$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall i} W_{ic}(\tau_{ua}, R_{uac}^n)$$

Let  $\tau_{31}$  be the task under analysis, i.e.,  $\tau_{ua}$

### Critical Instant (CI) combination 1:

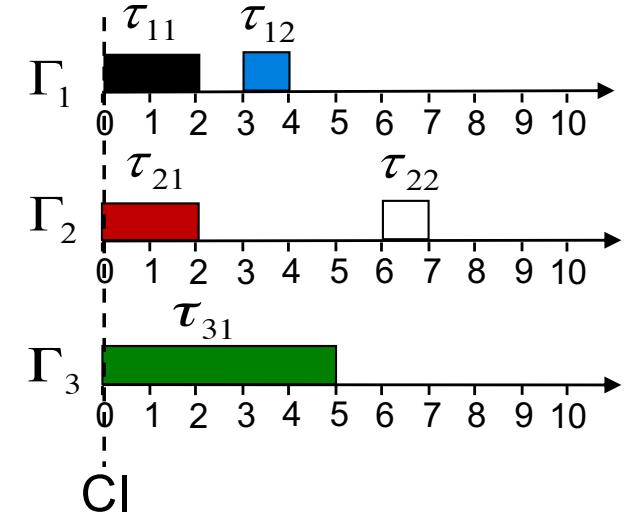
Let  $\tau_{11}, \tau_{21}, \tau_{31}$  coincide with CI.

$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall i} W_{ic}(\tau_{ua}, R_{uac}^n)$$

$$R_{uac}^{n+1} = C_{ua} + W_{11}(\tau_{ua}, R_{uac}^n) + W_{21}(\tau_{ua}, R_{uac}^n)$$

$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall j \in hp_1(\tau_{ua})} \left[ \frac{R_{uac}^n - \Phi_{1j1}}{T_1} \right] C_{1j} + \sum_{\forall j \in hp_2(\tau_{ua})} \left[ \frac{R_{uac}^n - \Phi_{2j1}}{T_2} \right] C_{2j}$$

$$R_{uac}^{n+1} = C_{ua} + \left[ \frac{R_{uac}^n - \Phi_{111}}{T_1} \right] C_{11} + \left[ \frac{R_{uac}^n - \Phi_{121}}{T_1} \right] C_{12} + \left[ \frac{R_{uac}^n - \Phi_{211}}{T_2} \right] C_{21} + \left[ \frac{R_{uac}^n - \Phi_{221}}{T_2} \right] C_{22} \dots\dots (1)$$



## Example: RTA with offsets using Exact Analysis

$$\Phi_{ijc} = (O_{ij} - O_{ic}) \bmod T_i$$

$$\Phi_{111} = (O_{11} - O_{11}) \bmod 10 = (2 - 2) \bmod 10 = 0$$

$$\Phi_{121} = (O_{12} - O_{11}) \bmod 10 = (5 - 2) \bmod 10 = 3$$

$$\Phi_{211} = (O_{21} - O_{21}) \bmod 10 = (1 - 1) \bmod 10 = 0$$

$$\Phi_{221} = (O_{22} - O_{21}) \bmod 10 = (7 - 1) \bmod 10 = 6$$

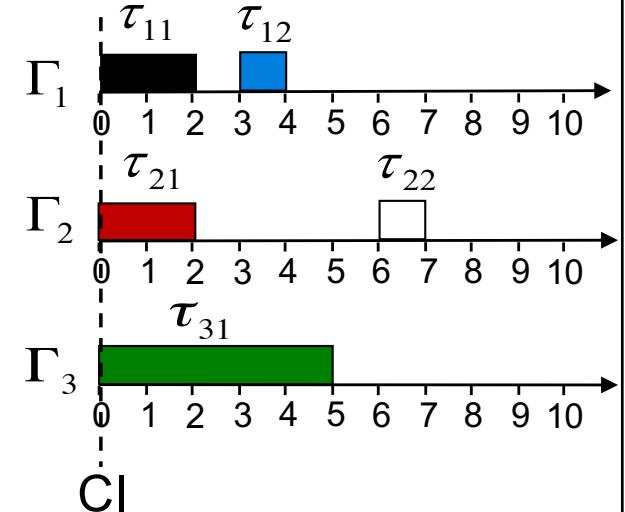
Using all these values in (1)

$$R_{uac}^0 = C_{ua} = 5$$

$$R_{uac}^1 = 5 + \left\lceil \frac{5-0}{10} \right\rceil 2 + \left\lceil \frac{5-3}{10} \right\rceil 1 + \left\lceil \frac{5-0}{10} \right\rceil 2 + \left\lceil \frac{5-6}{10} \right\rceil 1$$

$$R_{uac}^1 = 5 + 2 + 1 + 2 + 0$$

$$R_{uac}^1 = 10$$



## Example: RTA with offsets using Exact Analysis

---

Next iteration

$$R_{uac}^2 = 5 + \left\lceil \frac{10-0}{10} \right\rceil 2 + \left\lceil \frac{10-3}{10} \right\rceil 1 + \left\lceil \frac{10-0}{10} \right\rceil 2 + \left\lceil \frac{10-6}{10} \right\rceil 1$$

$$R_{uac}^2 = 5 + 2 + 1 + 2 + 1$$

$$R_{uac}^2 = 11$$

Next iteration

$$R_{uac}^3 = 5 + \left\lceil \frac{11-0}{10} \right\rceil 2 + \left\lceil \frac{11-3}{10} \right\rceil 1 + \left\lceil \frac{11-0}{10} \right\rceil 2 + \left\lceil \frac{11-6}{10} \right\rceil 1$$

$$R_{uac}^3 = 5 + 4 + 1 + 4 + 1$$

$$R_{uac}^3 = 15$$

## Example: RTA with offsets using Exact Analysis

Next iteration

$$R_{uac}^4 = 5 + \left\lceil \frac{15-0}{10} \right\rceil 2 + \left\lceil \frac{15-3}{10} \right\rceil 1 + \left\lceil \frac{15-0}{10} \right\rceil 2 + \left\lceil \frac{15-6}{10} \right\rceil 1$$

$$R_{uac}^4 = 5 + 4 + 2 + 4 + 1$$

$$R_{uac}^4 = 16$$

Next iteration

$$R_{uac}^5 = 5 + \left\lceil \frac{16-0}{10} \right\rceil 2 + \left\lceil \frac{16-3}{10} \right\rceil 1 + \left\lceil \frac{16-0}{10} \right\rceil 2 + \left\lceil \frac{16-6}{10} \right\rceil 1$$

$$R_{uac}^5 = 5 + 4 + 2 + 4 + 1$$

$$R_{uac}^5 = 16 \quad \Rightarrow R_{uac}^5 = R_{uac}^4 = 16$$

$$\Rightarrow \boxed{R_{uac} = 16}$$

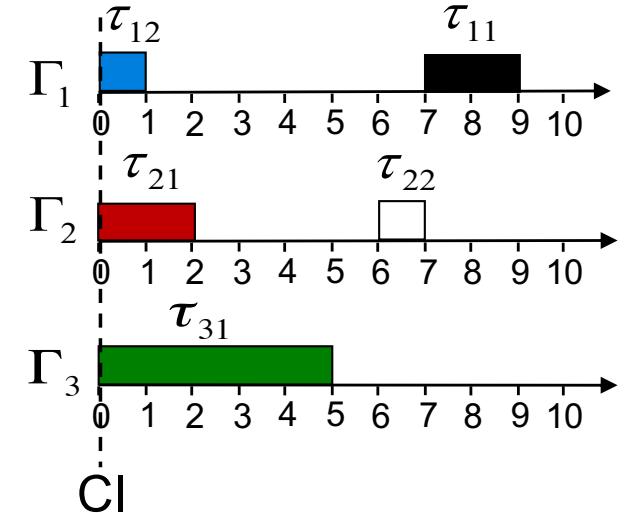
## Example: RTA with offsets using Exact Analysis

### Critical Instant (CI) combination 2:

Let  $\tau_{12}, \tau_{21}, \tau_{31}$  coincide with CI.

$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall i} W_{ic}(\tau_{ua}, R_{uac}^n)$$

$$R_{uac}^{n+1} = C_{ua} + W_{12}(\tau_{ua}, R_{uac}^n) + W_{21}(\tau_{ua}, R_{uac}^n)$$



$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall j \in hp_1(\tau_{ua})} \left[ \frac{R_{uac}^n - \Phi_{1j2}}{T_1} \right] C_{1j} + \sum_{\forall j \in hp_2(\tau_{ua})} \left[ \frac{R_{uac}^n - \Phi_{2j1}}{T_2} \right] C_{2j}$$

$$R_{uac}^{n+1} = C_{ua} + \left[ \frac{R_{uac}^n - \Phi_{112}}{T_1} \right] C_{11} + \left[ \frac{R_{uac}^n - \Phi_{122}}{T_1} \right] C_{12} + \left[ \frac{R_{uac}^n - \Phi_{211}}{T_2} \right] C_{21} + \left[ \frac{R_{uac}^n - \Phi_{221}}{T_2} \right] C_{22} \dots \dots (2)$$

## Example: RTA with offsets using Exact Analysis

$$\Phi_{ijc} = (O_{ij} - O_{ic}) \bmod T_i$$

$$\Phi_{112} = (O_{11} - O_{12}) \bmod 10 = (2 - 5) \bmod 10 = 10 - 3 = 7$$

$$\Phi_{122} = (O_{12} - O_{12}) \bmod 10 = (5 - 5) \bmod 10 = 0$$

$$\Phi_{211} = (O_{21} - O_{21}) \bmod 10 = (1 - 1) \bmod 10 = 0$$

$$\Phi_{221} = (O_{22} - O_{21}) \bmod 10 = (7 - 1) \bmod 10 = 6$$

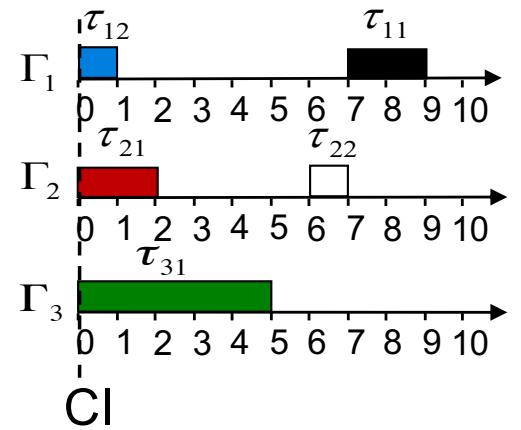
Using all these values in (2)

$$R_{uac}^0 = C_{ua} = 5$$

$$R_{uac}^1 = 5 + \left\lceil \frac{5-7}{10} \right\rceil 2 + \left\lceil \frac{5-0}{10} \right\rceil 1 + \left\lceil \frac{5-0}{10} \right\rceil 2 + \left\lceil \frac{5-6}{10} \right\rceil 1$$

$$R_{uac}^1 = 5 + 0 + 1 + 2 + 0$$

$$R_{uac}^1 = 8$$



## Example: RTA with offsets using Exact Analysis

---

Next iteration

$$R_{uac}^2 = 5 + \left\lceil \frac{8-7}{10} \right\rceil 2 + \left\lceil \frac{8-0}{10} \right\rceil 1 + \left\lceil \frac{8-0}{10} \right\rceil 2 + \left\lceil \frac{8-6}{10} \right\rceil 1$$

$$R_{uac}^2 = 5 + 2 + 1 + 2 + 1$$

$$R_{uac}^2 = 11$$

Next iteration

$$R_{uac}^3 = 5 + \left\lceil \frac{11-7}{10} \right\rceil 2 + \left\lceil \frac{11-0}{10} \right\rceil 1 + \left\lceil \frac{11-0}{10} \right\rceil 2 + \left\lceil \frac{11-6}{10} \right\rceil 1$$

$$R_{uac}^3 = 5 + 2 + 2 + 4 + 1$$

$$R_{uac}^3 = 14$$

## Example: RTA with offsets using Exact Analysis

---

Next iteration

$$R_{uac}^4 = 5 + \left\lceil \frac{14-7}{10} \right\rceil 2 + \left\lceil \frac{14-0}{10} \right\rceil 1 + \left\lceil \frac{14-0}{10} \right\rceil 2 + \left\lceil \frac{14-6}{10} \right\rceil 1$$

$$R_{uac}^4 = 5 + 2 + 2 + 4 + 1$$

$$R_{uac}^4 = 14 \quad \Rightarrow R_{uac}^4 = R_{uac}^3 = 14$$

$$\Rightarrow \boxed{R_{uac} = 14}$$

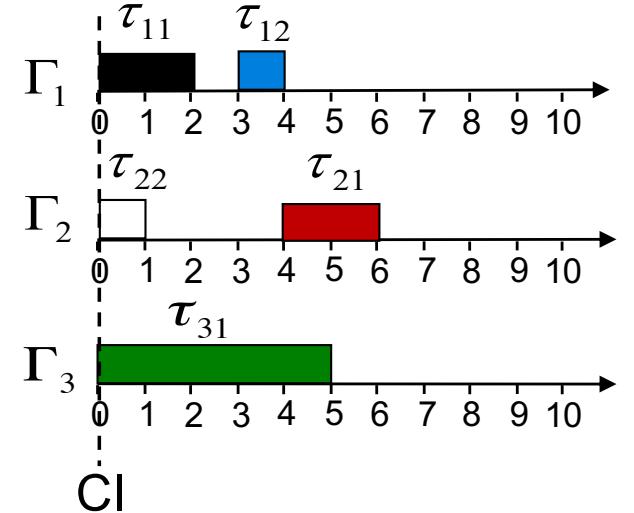
## Example: RTA with offsets using Exact Analysis

### Critical Instant (CI) combination 3:

Let  $\tau_{11}, \tau_{22}, \tau_{31}$  coincide with CI.

$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall i} W_{ic}(\tau_{ua}, R_{uac}^n)$$

$$R_{uac}^{n+1} = C_{ua} + W_{11}(\tau_{ua}, R_{uac}^n) + W_{22}(\tau_{ua}, R_{uac}^n)$$



$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall j \in hp_1(\tau_{ua})} \left[ \frac{R_{uac}^n - \Phi_{1j1}}{T_1} \right] C_{1j} + \sum_{\forall j \in hp_2(\tau_{ua})} \left[ \frac{R_{uac}^n - \Phi_{2j2}}{T_2} \right] C_{2j}$$

$$R_{uac}^{n+1} = C_{ua} + \left[ \frac{R_{uac}^n - \Phi_{111}}{T_1} \right] C_{11} + \left[ \frac{R_{uac}^n - \Phi_{121}}{T_1} \right] C_{12} + \left[ \frac{R_{uac}^n - \Phi_{212}}{T_2} \right] C_{21} + \left[ \frac{R_{uac}^n - \Phi_{222}}{T_2} \right] C_{22} \dots\dots (3)$$

## Example: RTA with offsets using Exact Analysis

$$\Phi_{ijc} = (O_{ij} - O_{ic}) \bmod T_i$$

$$\Phi_{111} = (O_{11} - O_{11}) \bmod 10 = (2 - 2) \bmod 10 = 0$$

$$\Phi_{121} = (O_{12} - O_{11}) \bmod 10 = (5 - 2) \bmod 10 = 3$$

$$\Phi_{212} = (O_{21} - O_{22}) \bmod 10 = (1 - 7) \bmod 10 = 10 - 6 = 4$$

$$\Phi_{222} = (O_{22} - O_{22}) \bmod 10 = (7 - 7) \bmod 10 = 0$$

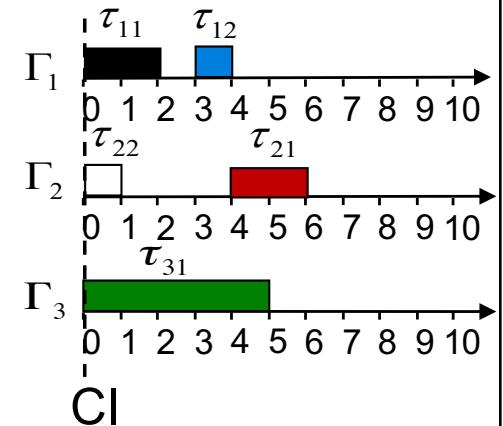
Using all these values in (3)

$$R_{uac}^0 = C_{ua} = 5$$

$$R_{uac}^1 = 5 + \left\lceil \frac{5-0}{10} \right\rceil 2 + \left\lceil \frac{5-3}{10} \right\rceil 1 + \left\lceil \frac{5-4}{10} \right\rceil 2 + \left\lceil \frac{5-0}{10} \right\rceil 1$$

$$R_{uac}^1 = 5 + 2 + 1 + 2 + 1$$

$$R_{uac}^1 = 11$$



## Example: RTA with offsets using Exact Analysis

---

Next iteration

$$R_{uac}^2 = 5 + \left\lceil \frac{11-0}{10} \right\rceil 2 + \left\lceil \frac{11-3}{10} \right\rceil 1 + \left\lceil \frac{11-4}{10} \right\rceil 2 + \left\lceil \frac{11-0}{10} \right\rceil 1$$

$$R_{uac}^2 = 5 + 4 + 1 + 2 + 2$$

$$R_{uac}^2 = 14$$

Next iteration

$$R_{uac}^3 = 5 + \left\lceil \frac{14-0}{10} \right\rceil 2 + \left\lceil \frac{14-3}{10} \right\rceil 1 + \left\lceil \frac{14-4}{10} \right\rceil 2 + \left\lceil \frac{14-0}{10} \right\rceil 1$$

$$R_{uac}^3 = 5 + 4 + 2 + 2 + 2$$

$$R_{uac}^3 = 15$$

## Example: RTA with offsets using Exact Analysis

Next iteration

$$R_{uac}^4 = 5 + \left\lceil \frac{15-0}{10} \right\rceil 2 + \left\lceil \frac{15-3}{10} \right\rceil 1 + \left\lceil \frac{15-4}{10} \right\rceil 2 + \left\lceil \frac{15-0}{10} \right\rceil 1$$

$$R_{uac}^4 = 5 + 4 + 2 + 4 + 2$$

$$R_{uac}^4 = 17$$

Next iteration

$$R_{uac}^5 = 5 + \left\lceil \frac{17-0}{10} \right\rceil 2 + \left\lceil \frac{17-3}{10} \right\rceil 1 + \left\lceil \frac{17-4}{10} \right\rceil 2 + \left\lceil \frac{17-0}{10} \right\rceil 1$$

$$R_{uac}^5 = 5 + 4 + 2 + 4 + 2$$

$$R_{uac}^5 = 17 \quad \Rightarrow R_{uac}^5 = R_{uac}^4 = 17$$

$$\Rightarrow \boxed{R_{uac} = 17}$$

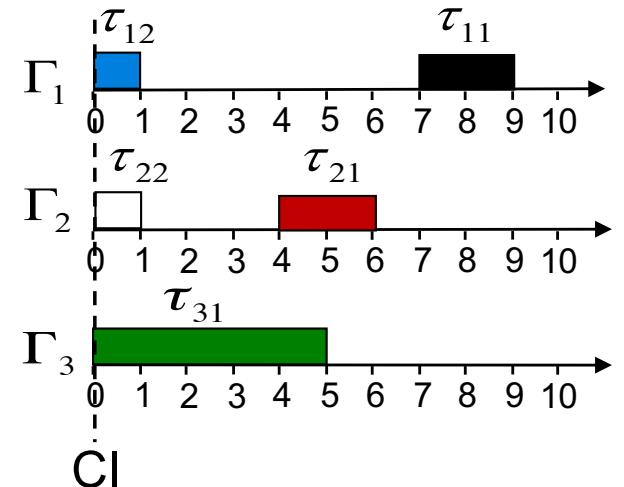
## Example: RTA with offsets using Exact Analysis

### Critical Instant (CI) combination 4:

Let  $\tau_{12}, \tau_{22}, \tau_{31}$  coincide with CI.

$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall i} W_{ic}(\tau_{ua}, R_{uac}^n)$$

$$R_{uac}^{n+1} = C_{ua} + W_{12}(\tau_{ua}, R_{uac}^n) + W_{22}(\tau_{ua}, R_{uac}^n)$$



$$R_{uac}^{n+1} = C_{ua} + \sum_{\forall j \in hp_1(\tau_{ua})} \left[ \frac{R_{uac}^n - \Phi_{1j2}}{T_1} \right] C_{1j} + \sum_{\forall j \in hp_2(\tau_{ua})} \left[ \frac{R_{uac}^n - \Phi_{2j2}}{T_2} \right] C_{2j}$$

$$R_{uac}^{n+1} = C_{ua} + \left[ \frac{R_{uac}^n - \Phi_{112}}{T_1} \right] C_{11} + \left[ \frac{R_{uac}^n - \Phi_{122}}{T_1} \right] C_{12} + \left[ \frac{R_{uac}^n - \Phi_{212}}{T_2} \right] C_{21} + \left[ \frac{R_{uac}^n - \Phi_{222}}{T_2} \right] C_{22} \dots\dots (4)$$

## Example: RTA with offsets using Exact Analysis

$$\Phi_{ijc} = (O_{ij} - O_{ic}) \bmod T_i$$

$$\Phi_{112} = (O_{11} - O_{12}) \bmod 10 = (2 - 5) \bmod 10 = 10 - 3 = 7$$

$$\Phi_{122} = (O_{12} - O_{12}) \bmod 10 = (5 - 5) \bmod 10 = 0$$

$$\Phi_{212} = (O_{21} - O_{22}) \bmod 10 = (1 - 7) \bmod 10 = 10 - 6 = 4$$

$$\Phi_{222} = (O_{22} - O_{22}) \bmod 10 = (7 - 7) \bmod 10 = 0$$

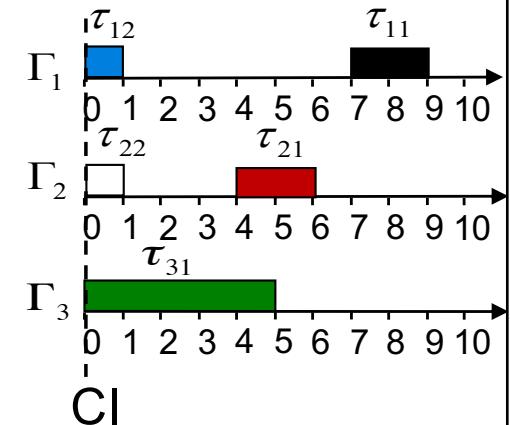
Using all these values in (4)

$$R_{uac}^0 = C_{ua} = 5$$

$$R_{uac}^1 = 5 + \left\lceil \frac{5-7}{10} \right\rceil 2 + \left\lceil \frac{5-0}{10} \right\rceil 1 + \left\lceil \frac{5-4}{10} \right\rceil 2 + \left\lceil \frac{5-0}{10} \right\rceil 1$$

$$R_{uac}^1 = 5 + 0 + 1 + 2 + 1$$

$$R_{uac}^1 = 9$$



## **Example: RTA with offsets using Exact Analysis**

---

Next iteration

$$R_{uac}^2 = 5 + \left\lceil \frac{9-7}{10} \right\rceil 2 + \left\lceil \frac{9-0}{10} \right\rceil 1 + \left\lceil \frac{9-4}{10} \right\rceil 2 + \left\lceil \frac{9-0}{10} \right\rceil 1$$

$$R_{uac}^2 = 5 + 2 + 1 + 2 + 1$$

$$R_{uac}^2 = 11$$

Next iteration

$$R_{uac}^3 = 5 + \left\lceil \frac{11-7}{10} \right\rceil 2 + \left\lceil \frac{11-0}{10} \right\rceil 1 + \left\lceil \frac{11-4}{10} \right\rceil 2 + \left\lceil \frac{11-0}{10} \right\rceil 1$$

$$R_{uac}^3 = 5 + 2 + 2 + 2 + 2$$

$$R_{uac}^3 = 13$$

## Example: RTA with offsets using Exact Analysis

Next iteration

$$R_{uac}^4 = 5 + \left\lceil \frac{13-7}{10} \right\rceil 2 + \left\lceil \frac{13-0}{10} \right\rceil 1 + \left\lceil \frac{13-4}{10} \right\rceil 2 + \left\lceil \frac{13-0}{10} \right\rceil 1$$

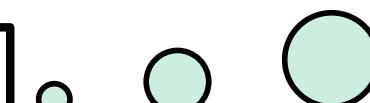
$$R_{uac}^4 = 5 + 2 + 2 + 2 + 2$$

$$R_{uac}^4 = 13 \quad \Rightarrow R_{uac}^4 = R_{uac}^3 = 13 \quad \Rightarrow \boxed{R_{uac} = 13}$$

$$R_{ua} = \max_{\forall c \text{ combinations}} (R_{uac})$$

$$R_{ua} = \max(16, 14, 17, 13) = 17$$

$$\boxed{R_{ua} = R_{31} = 17}$$



Response times of other tasks can be calculated in a similar way

## Example: RTA with offsets using Approximate Analysis

$$R_{ua}^{n+1} = C_{ua} + \sum_{\forall i} W_i^*(\tau_{ua}, R_{ua}^n)$$

Where,  $W_i^*(\tau_{ua}, R_{ua}^n) = \max_{\forall c} (W_{ic}(\tau_{ua}, R_{ua}^n))$

$$W_{ic}(\tau_{ua}, R_{ua}^n) = \sum_{\forall j \in hpi(\tau_{ua})} \left\lceil \frac{R_{ua}^n - \Phi_{ijc}}{T_i} \right\rceil C_{ij}$$

$$R_{ua}^{n+1} = C_{ua} + W_1^*(\tau_{ua}, R_{ua}^n) + W_2^*(\tau_{ua}, R_{ua}^n)$$

$$R_{ua}^{n+1} = C_{ua} + \max_{\forall c} (W_{1c}(\tau_{ua}, R_{ua}^n)) + \max_{\forall c} (W_{2c}(\tau_{ua}, R_{ua}^n))$$

$$R_{ua}^{n+1} = C_{ua} + \max((W_{11}(\tau_{ua}, R_{ua}^n), W_{12}(\tau_{ua}, R_{ua}^n)))$$

$$+ \max((W_{21}(\tau_{ua}, R_{ua}^n), W_{22}(\tau_{ua}, R_{ua}^n)))$$

## Example: RTA with offsets using Approximate Analysis

$$\begin{aligned}
R_{ua}^{n+1} = & C_{ua} + \max \left( \sum_{\forall j \in hp_1(\tau_{ua})} \left| \frac{R_{ua}^n - \Phi_{1j1}}{T_1} \right| C_{1j} , \sum_{\forall j \in hp_1(\tau_{ua})} \left| \frac{R_{ua}^n - \Phi_{1j2}}{T_1} \right| C_{1j} \right) \\
& + \max \left( \sum_{\forall j \in hp_2(\tau_{ua})} \left| \frac{R_{ua}^n - \Phi_{2j1}}{T_2} \right| C_{2j} , \sum_{\forall j \in hp_2(\tau_{ua})} \left| \frac{R_{ua}^n - \Phi_{2j2}}{T_2} \right| C_{2j} \right) \\
R_{ua}^{n+1} = & C_{ua} + \max \left( \left| \frac{R_{ua}^n - \Phi_{111}}{T_1} \right| C_{11} + \left| \frac{R_{ua}^n - \Phi_{121}}{T_1} \right| C_{12} , \left| \frac{R_{ua}^n - \Phi_{112}}{T_1} \right| C_{11} + \left| \frac{R_{ua}^n - \Phi_{122}}{T_1} \right| C_{12} \right) \\
& + \max \left( \left| \frac{R_{ua}^n - \Phi_{211}}{T_2} \right| C_{21} + \left| \frac{R_{ua}^n - \Phi_{221}}{T_2} \right| C_{22} , \left| \frac{R_{ua}^n - \Phi_{212}}{T_2} \right| C_{21} + \left| \frac{R_{ua}^n - \Phi_{222}}{T_2} \right| C_{22} \right) \dots \dots (5)
\end{aligned}$$

## **Example: RTA with offsets using Approximate Analysis**

---

$$\Phi_{ijc} = (O_{ij} - O_{ic}) \bmod T_i$$

$$\Phi_{111} = (O_{11} - O_{11}) \bmod 10 = (2 - 2) \bmod 10 = 0$$

$$\Phi_{121} = (O_{12} - O_{11}) \bmod 10 = (5 - 2) \bmod 10 = 3$$

$$\Phi_{112} = (O_{11} - O_{12}) \bmod 10 = (2 - 5) \bmod 10 = 10 - 3 = 7$$

$$\Phi_{122} = (O_{12} - O_{12}) \bmod 10 = (5 - 5) \bmod 10 = 0$$

$$\Phi_{211} = (O_{21} - O_{21}) \bmod 10 = (1 - 1) \bmod 10 = 0$$

$$\Phi_{221} = (O_{22} - O_{21}) \bmod 10 = (7 - 1) \bmod 10 = 6$$

$$\Phi_{212} = (O_{21} - O_{22}) \bmod 10 = (1 - 7) \bmod 10 = 10 - 6 = 4$$

$$\Phi_{222} = (O_{22} - O_{22}) \bmod 10 = (7 - 7) \bmod 10 = 0$$

Using all these values in (5)

## **Example: RTA with offsets using Approximate Analysis**

$$R_{uac}^0 = C_{ua} = 5$$

$$R_{ua}^1 = 5 + \max\left(\left\lceil \frac{5-0}{10} \right\rceil 2 + \left\lceil \frac{5-3}{10} \right\rceil 1, \left\lceil \frac{5-7}{10} \right\rceil 2 + \left\lceil \frac{5-0}{10} \right\rceil 1\right)$$

$$+ \max\left(\left\lceil \frac{5-0}{10} \right\rceil 2 + \left\lceil \frac{5-6}{10} \right\rceil 1, \left\lceil \frac{5-4}{10} \right\rceil 2 + \left\lceil \frac{5-0}{10} \right\rceil 1\right)$$

$$R_{ua}^1 = 5 + \max(2+1, 0+1) + \max(2+0, 2+1)$$

$$R_{ua}^1 = 5 + \max(3, 1) + \max(2, 3)$$

$$R_{ua}^1 = 5 + 3 + 3$$

$$R_{ua}^1 = 11$$

## **Example: RTA with offsets using Approximate Analysis**

Next iteration

$$R_{ua}^2 = 5 + \max\left(\left\lceil \frac{11-0}{10} \right\rceil_2 + \left\lceil \frac{11-3}{10} \right\rceil_1, \left\lceil \frac{11-7}{10} \right\rceil_2 + \left\lceil \frac{11-0}{10} \right\rceil_1\right)$$

$$+ \max\left(\left\lceil \frac{11-0}{10} \right\rceil_2 + \left\lceil \frac{11-6}{10} \right\rceil_1, \left\lceil \frac{11-4}{10} \right\rceil_2 + \left\lceil \frac{11-0}{10} \right\rceil_1\right)$$

$$R_{ua}^2 = 5 + \max(4+1, 2+2) + \max(4+1, 2+2)$$

$$R_{ua}^2 = 5 + \max(5, 4) + \max(5, 4)$$

$$R_{ua}^2 = 5 + 5 + 5$$

$$R_{ua}^2 = 15$$

## Example: RTA with offsets using Approximate Analysis

Next iteration

$$R_{ua}^3 = 5 + \max\left(\left\lceil \frac{15-0}{10} \right\rceil 2 + \left\lceil \frac{15-3}{10} \right\rceil 1, \left\lceil \frac{15-7}{10} \right\rceil 2 + \left\lceil \frac{15-0}{10} \right\rceil 1\right)$$

$$+ \max\left(\left\lceil \frac{15-0}{10} \right\rceil 2 + \left\lceil \frac{15-6}{10} \right\rceil 1, \left\lceil \frac{15-4}{10} \right\rceil 2 + \left\lceil \frac{15-0}{10} \right\rceil 1\right)$$

$$R_{ua}^3 = 5 + \max(4+2, 2+2) + \max(4+1, 4+2)$$

$$R_{ua}^3 = 5 + \max(6, 4) + \max(5, 6)$$

$$R_{ua}^3 = 5 + 6 + 6$$

$$R_{ua}^3 = 17$$

## Example: RTA with offsets using Approximate Analysis

Next iteration

$$R_{ua}^4 = 5 + \max\left(\left\lceil \frac{17-0}{10} \right\rceil_2 + \left\lceil \frac{17-3}{10} \right\rceil_1, \left\lceil \frac{17-7}{10} \right\rceil_2 + \left\lceil \frac{17-0}{10} \right\rceil_1\right)$$

$$+ \max\left(\left\lceil \frac{17-0}{10} \right\rceil_2 + \left\lceil \frac{17-6}{10} \right\rceil_1, \left\lceil \frac{17-4}{10} \right\rceil_2 + \left\lceil \frac{17-0}{10} \right\rceil_1\right)$$

$$R_{ua}^4 = 5 + \max(4+2, 2+2) + \max(4+2, 4+2)$$

$$R_{ua}^4 = 5 + \max(6, 4) + \max(6, 6)$$

$$R_{ua}^4 = 5 + 6 + 6$$

$$R_{ua}^4 = 17 = R_{ua}^3$$

$$R_{ua} = R_{31} = 17$$



Response times of other tasks can be calculated in a similar way