



ROYAL INSTITUTE
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Computational Framework for Optimal Robust Beamforming in Coordinated Multicell Systems

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Introduction

- Downlink Coordinated Beamforming
 - N cells with N_t -antenna base stations
 - Each serves K single-antenna users
 - Common narrowband frequency resource
 - Limited by co-user interference

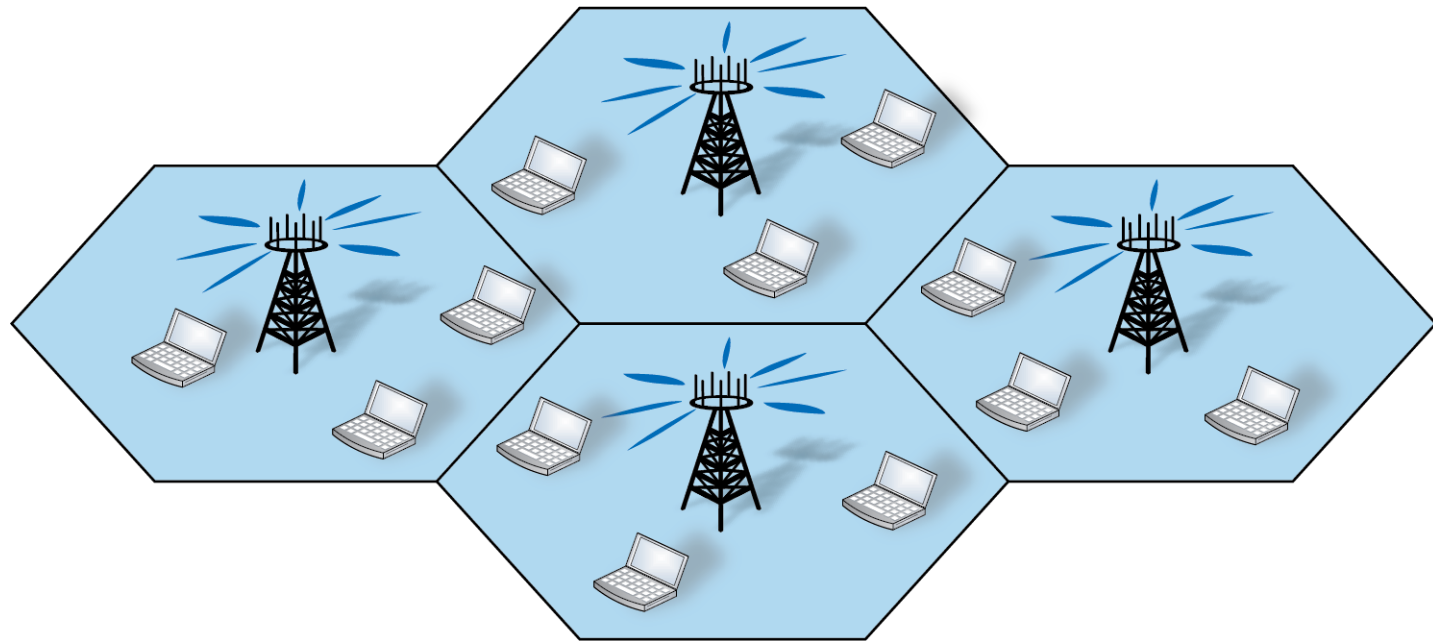
Problem

Compute Optimal
Linear Beamforming

General Conditions

Robustness to
Channel Uncertainty

Generally NP-hard:
Systematic Algorithm



System Model

- Parameters for User j in Cell i

- Linear beamforming vector: $\mathbf{w}_{i,j} \in \mathbb{C}^{N_t \times 1}$
- Channel from cell m : $\mathbf{h}_{m,i,j} \in \mathbb{C}^{N_t \times 1}$
- Signal-to-interference-and-noise ratio (SINR):

$$\text{SINR}_{i,j} = \frac{\overbrace{|\mathbf{h}_{i,i,j}^H \mathbf{w}_{i,j}|^2}^{\text{Useful signal}}}{\underbrace{\sum_{l \neq j} |\mathbf{h}_{i,i,j}^H \mathbf{w}_{i,l}|^2}_{\text{Intra-cell interference}} + \underbrace{\sum_{m \neq i} \|\mathbf{h}_{m,i,j}^H \mathbf{W}_m\|_2^2}_{\text{Inter-cell interference}} + \overbrace{\sigma^2}^{\text{Noise}}}$$

- Notation: $\mathbf{W}_i = [\mathbf{w}_{i,1} \ \dots \ \mathbf{w}_{i,K}]$

System Model (2)

- Arbitrary Power Constraints in Cell i

- Constraints: $\mathcal{W}_i = \left\{ \mathbf{W}_i : \text{tr}\{\mathbf{W}_i^H \mathbf{Q}_{i,k} \mathbf{W}_i\} \leq q_{i,k} \forall k \right\}$

Positive

Positive

- Notation: $\mathbf{W}_i = [\mathbf{w}_{i,1} \dots \mathbf{w}_{i,K}]$ semi-definite

- *Ex:* Per-antenna and per-cell

- Channel State Information (CSI)

- Perfect CSI within each cell

- *Uncertain* inter-cell CSI: Ellipsoidal uncertainty set

$$\mathbf{h}_{m,i,j} \in \mathcal{U}_{m,i,j} = \left\{ \hat{\mathbf{h}}_{m,i,j} + \mathbf{B}_{m,i,j} \boldsymbol{\epsilon}_{m,i,j} : \|\boldsymbol{\epsilon}_{m,i,j}\|_2 \leq 1 \right\}$$

Uncertainty
set

Known
estimate

Shape of
ellipsoid

Unknown
error vector

Error Sources

Estimation
Feedback
Delays

*More severe
between cells*

Measures of User Performance

- General Measure of User Performance

- Arbitrary strictly increasing function:

$$g_{i,j}(\text{SINR}_{i,j}) \text{ with } g_{i,j}(0) = 0$$

- *Ex:* Mutual information, Bit error rate, Mean squared error

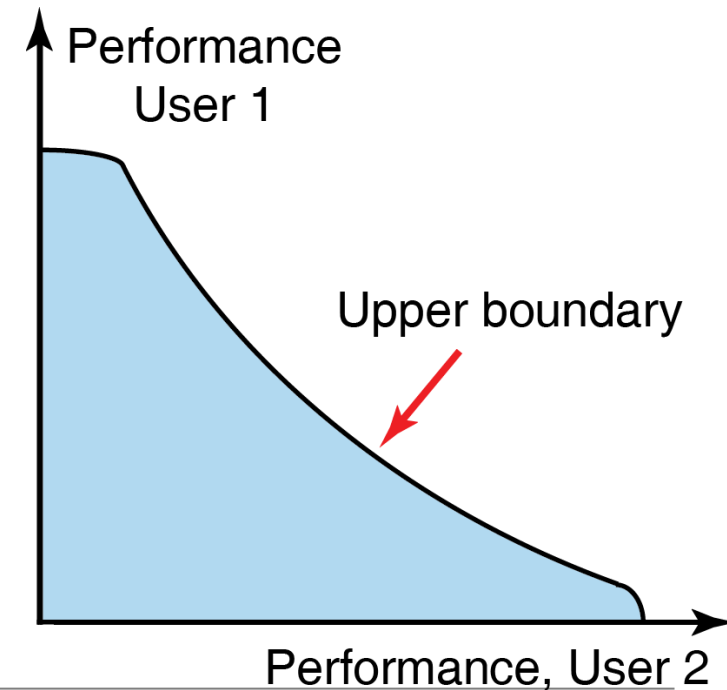
- Worst-Case Robust User Performance

- We will try to maximize:

$$g_{i,j}(\widetilde{\text{SINR}}_{i,j}) \text{ where } \widetilde{\text{SINR}}_{i,j} = \min_{\substack{\mathbf{h}_{m,i,j} \in \mathcal{U}_{m,i,j} \\ \forall m \neq i}} \text{SINR}_{i,j}$$

Measures of User Performance (2)

- Many Users
 - One Performance Measure $g_{i,j}(\widetilde{\text{SINR}}_{i,j})$ per User
- Fairness Dimension
 - Divide power and control co-user interference
- Robust Performance Region \mathcal{R}
 - NK users $\leftrightarrow NK$ dimensions
 - All possible combinations
 - Good points: On upper boundary
 - Unknown shape

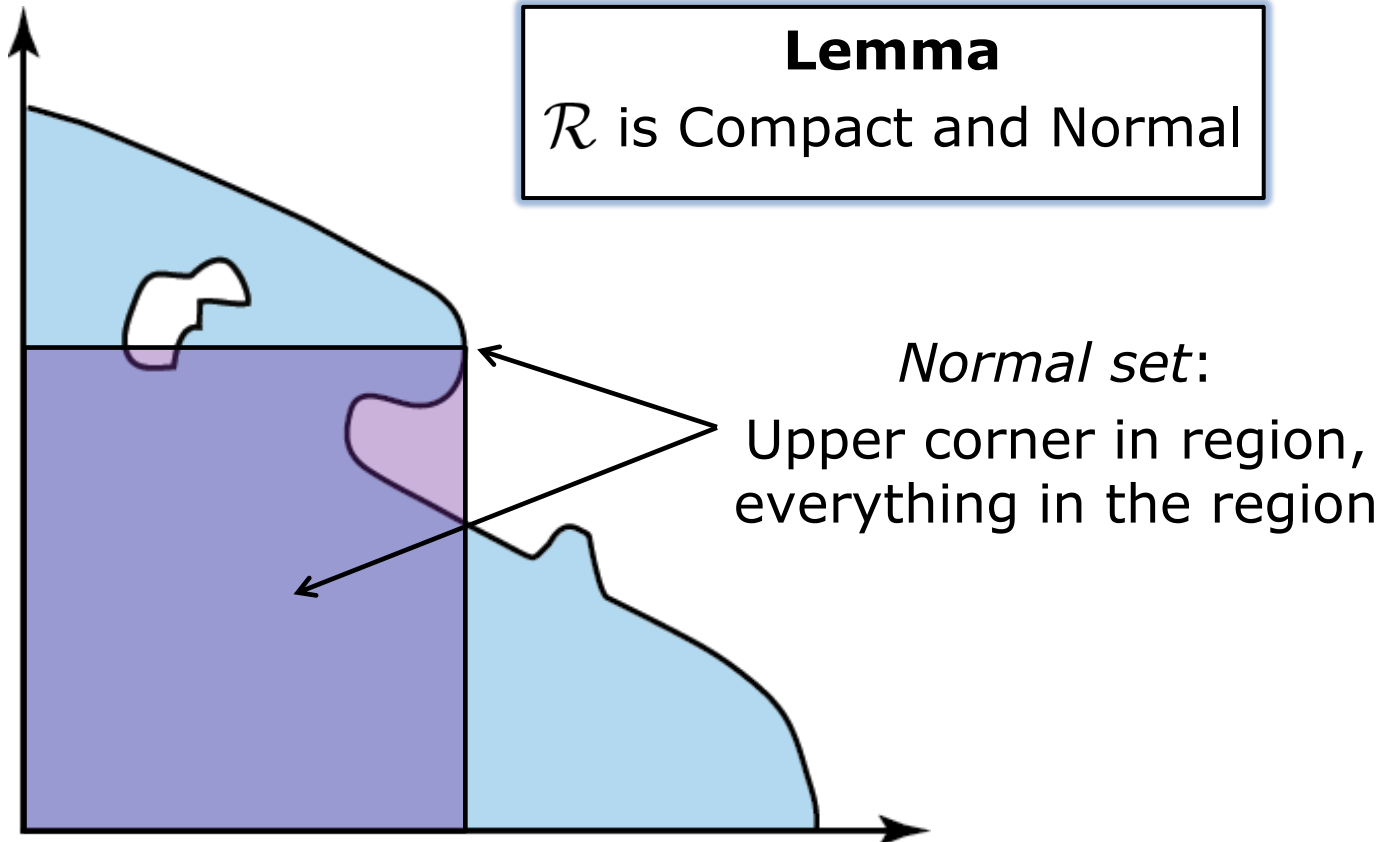


Measures of User Performance (3)

- Can it have any shape?
 - Can be non-convex!
- No!

Lemma

\mathcal{R} is Compact and Normal



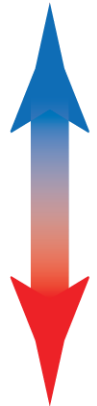
System Performance

- Which Point in \mathcal{R} to Select?
- System Performance Function $f : \mathcal{R} \rightarrow \mathbb{R}$
 - Strictly increasing and Lipschitz continuous

- *Examples*

- Sum performance: $f(\mathbf{g}) = \sum_{i,j} g_{i,j}$
- Proportional fairness: $f(\mathbf{g}) = \prod_{i,j} g_{i,j}$
- Harmonic mean: $f(\mathbf{g}) = NK(\sum_{i,j} g_{i,j}^{-1})^{-1}$
- Max-min fairness: $f(\mathbf{g}) = \min_{i,j} g_{i,j}$
- Can be modified with weights

Accumulated
performance



User
fairness

Problem Formulation

- Optimize System Performance

$$\underset{\mathbf{W}_i \in \mathcal{W}_i \forall i}{\text{maximize}} \quad f\left(g_{1,1}(\widetilde{\text{SINR}}_{1,1}), \dots, g_{N,K}(\widetilde{\text{SINR}}_{N,K})\right) \quad (1)$$

- Lemma: Optimum on upper boundary of \mathcal{R}
- Generally NP-hard: Exponential complexity
- Only suboptimal strategies in practice

- Goal: Computational Framework for Solving (1)
 - Enable benchmarking and study properties

- Approach

- Solve a special case of $f()$
- Exploit it to solve (1) for general $f()$

Special Case Fairness-Profile Optimization

- Maximize Performance with Fairness Constraints
 - Generalization of classic max-min fairness:

$$\begin{aligned} & \underset{\mathbf{W}_i \in \mathcal{W}_i \forall i}{\text{maximize}} && \min_{i,j} \frac{g_{i,j}(\widetilde{\text{SINR}}_{i,j}) - a_{i,j}}{\alpha_{i,j}} \\ & \text{s.t.} && g_{i,j}(\widetilde{\text{SINR}}_{i,j}) \geq a_{i,j} \quad \forall i, j \end{aligned}$$

- Lowest acceptable performance level: $g_{i,j} \geq a_{i,j} \geq 0$
- Users get a portion of exceeding resources: $\alpha_{i,j} \geq 0$

Lemma

- Solved by line-search in \mathcal{R} (bisection)
- Exploiting that \mathcal{R} is normal and compact

Special Case

Fairness-Profile Optimization

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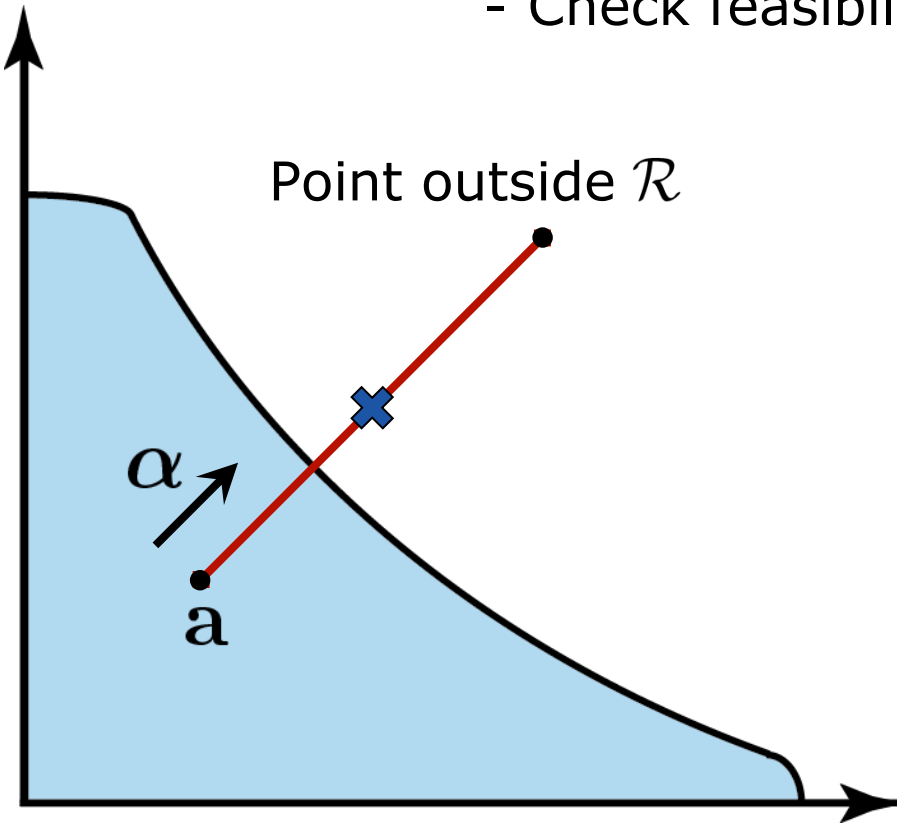
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Lemma

- Solved by line-search in \mathcal{R} (bisection)
- Exploiting that \mathcal{R} is normal and compact

Special Case Fairness-Profile Optimization (2)

- Geometrical Interpretation
 - Bisection: Fast convergence
 - Check feasibility at midpoint \mathbf{c} :



Theorem

- Feasibility checked as convex problem
- CSI uncertainty handled using S-lemma

find $\mathbf{W}_i \in \mathcal{W}_i, \lambda_{m,i,j} \geq 0, b_{m,i,j} \geq 0 \forall i, j, m \neq i$

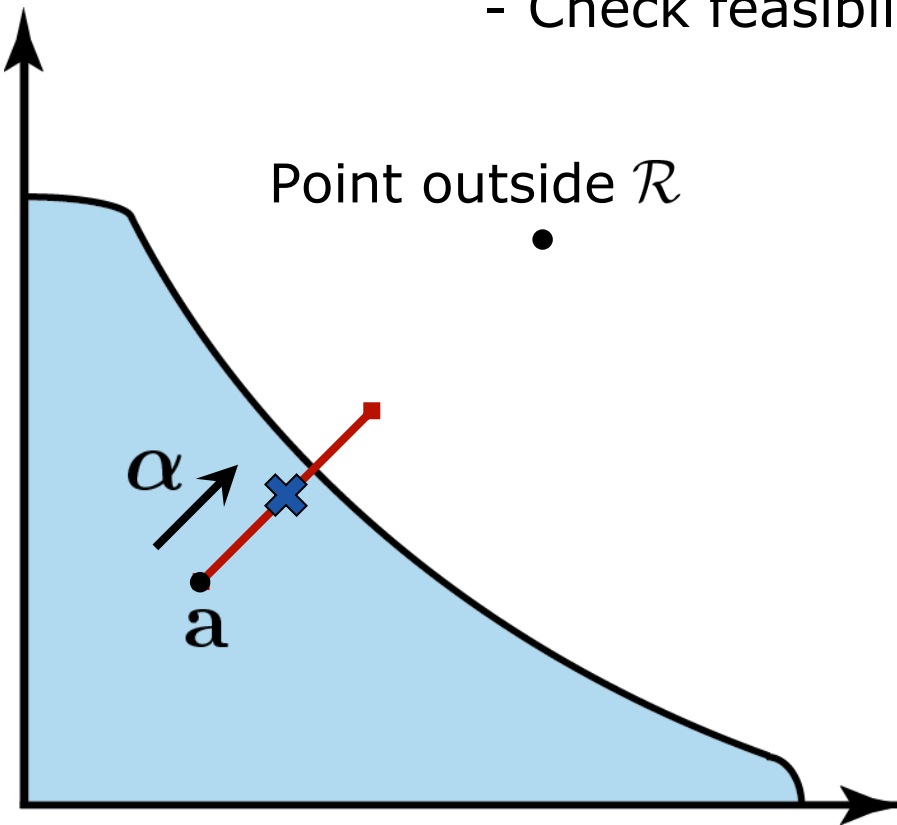
$$\text{s.t.} \begin{bmatrix} b_{m,i,j} - \lambda_{m,i,j} \hat{\mathbf{h}}_{m,i,j}^H \mathbf{W}_m & 0 \\ \mathbf{W}_m^H \hat{\mathbf{h}}_{m,i,j} & b_{m,i,j} \mathbf{I}_K & \mathbf{W}_m^H \mathbf{B}_{m,i,j} \\ 0 & \mathbf{B}_{m,i,j}^H \mathbf{W}_m & \lambda_{m,i,j} \mathbf{I}_{N_t} \end{bmatrix} \succeq 0 \quad \forall i, j, m \neq i$$

$$\sqrt{1 + \frac{1}{c_{i,j}} \mathbf{h}_{i,i,j}^H \mathbf{w}_{i,j}} \geq \sqrt{\|\mathbf{h}_{i,i,j}^H \mathbf{W}_i\|_2^2 + \sum_{m \neq i} b_{m,i,j}^2 + \sigma^2} \quad \forall i, j$$

Conclusion: Fairness-profile opt is quasi-convex (*solved in polynomial time*)

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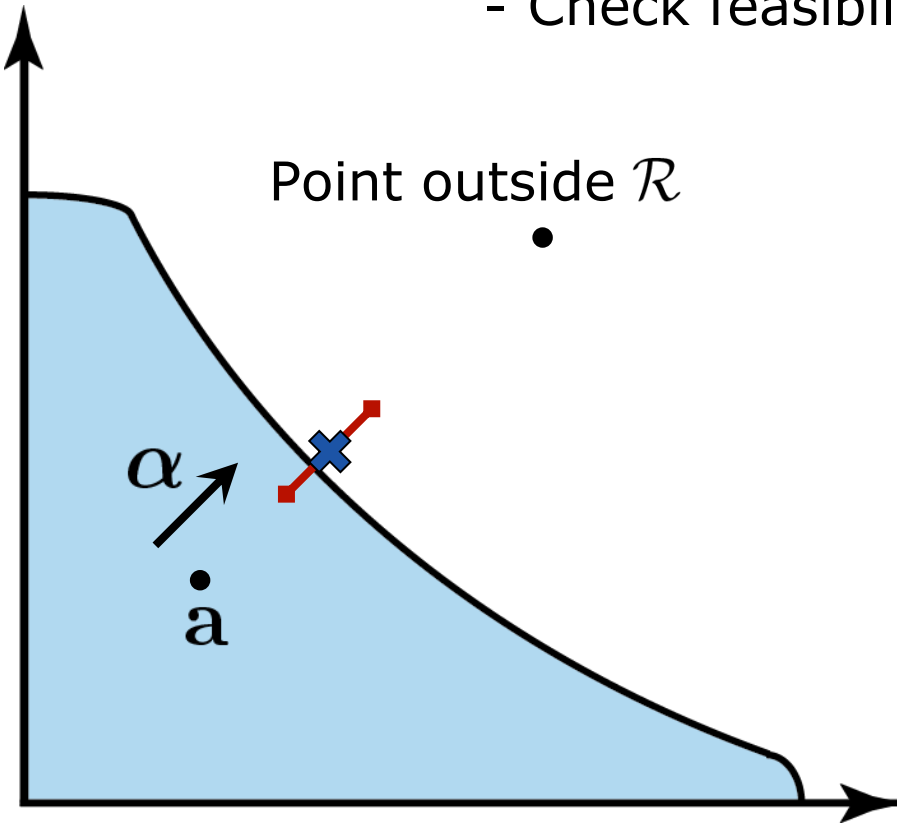
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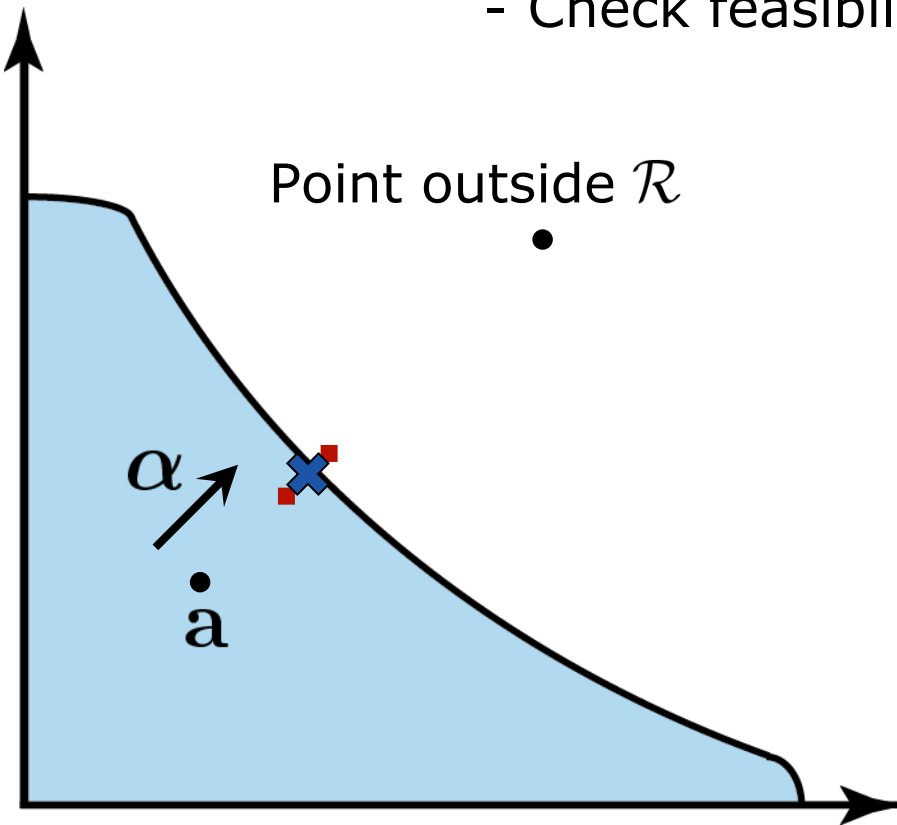
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Framework for General Case

- Systematic Algorithm with Minimal Search Space

- Search in \mathcal{R} and concentrate on important parts
- Improve lower/upper bounds on optimum:

$$f_{\min} \leq f_{\text{opt}} \leq f_{\max}$$

- Continue until $f_{\max} - f_{\min} < \varepsilon$

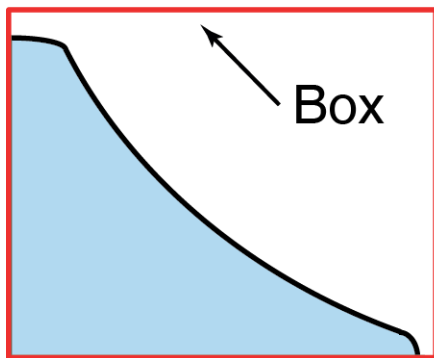
- Iterations in Polynomial Time

- Fairness-profile optimization

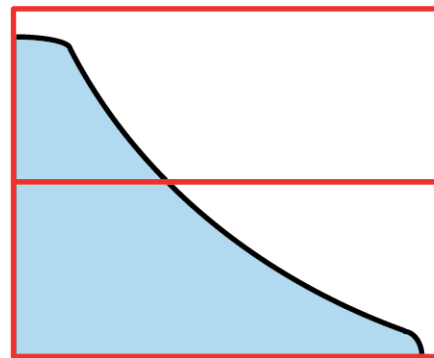
Framework for General Case (2)

- Branch-Reduce-Bound (BRB) Algorithm

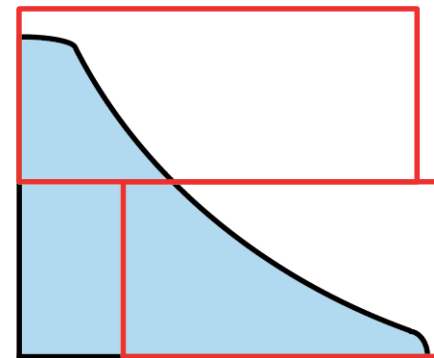
1. Cover \mathcal{R} with a box
2. Divide the box into two sub-boxes
3. Remove parts with no solutions in $[f_{\min}, f_{\max}]$
4. Search for solutions to improve bounds (Fairness-profile optimization)
5. Continue with sub-box with largest value



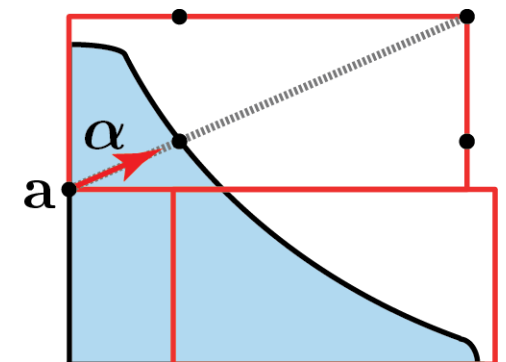
1) Cover region \mathcal{R}



2) Branch (Divide)

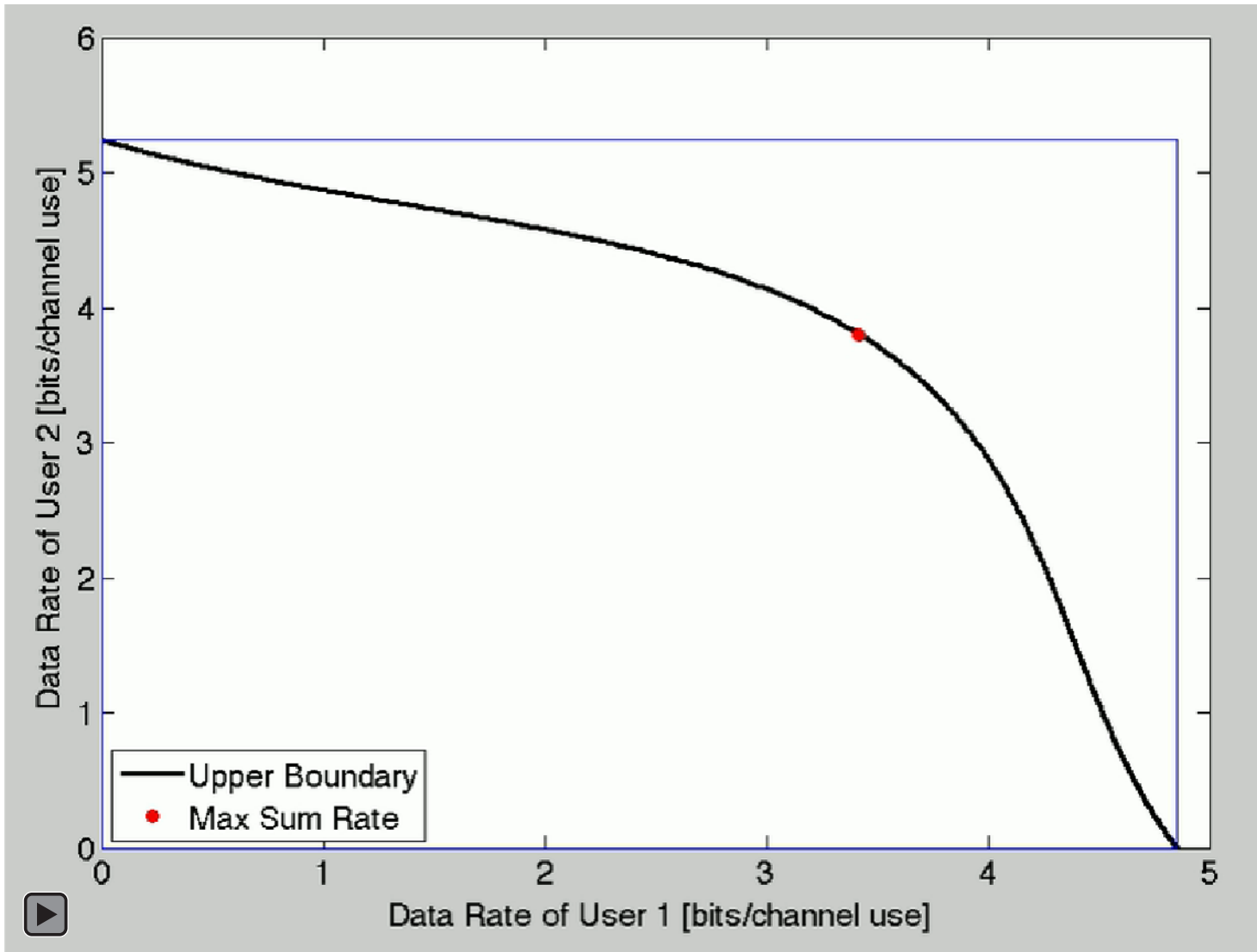


3) Reduce using bounds



4) Improve bounds

Framework for General Case (3)



Theorem

- Global Convergence
- Accuracy $\varepsilon > 0$ in finitely many iterations
- Exponential complexity *only* in NK
- Polynomial complexity in N_t and #constraints
- Any accuracy of fairness-profile opt

Numerical Illustrations

2 Cells and 2 User/Cell

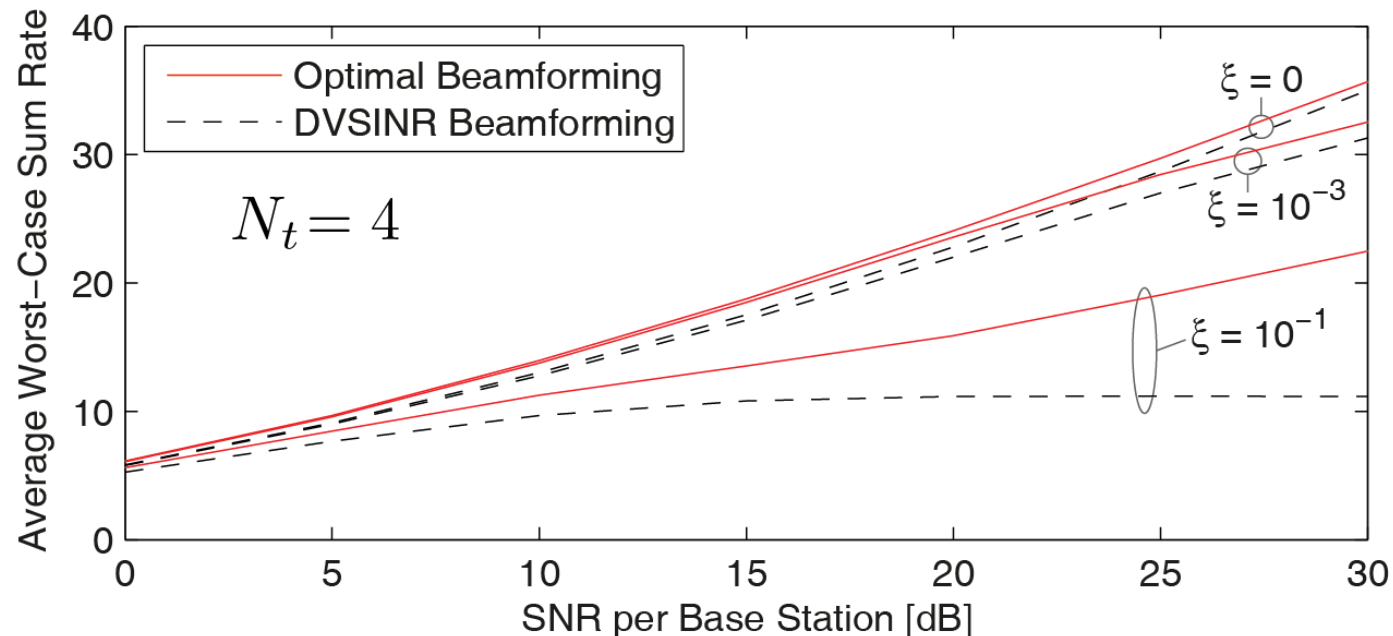
Per-base station constraints

Uncorrelated Rayleigh fading: $\mathbb{E}\{\|\mathbf{h}_{i,i,j}\|^2\} = 2\mathbb{E}\{\|\hat{\mathbf{h}}_{m,i,j}\|^2\}$

Spherical uncertainty sets: $\mathbf{B}_{m,i,j} = \sqrt{\xi}\mathbf{I}_{N_t}$

• Robustness of Heuristic Beamforming

- DVSINR beamforming [Björnson et al., 2010]
- Robust to small intercell uncertainties
- Highly suboptimal at higher uncertainties



Numerical Illustrations (2)

2 Cells and 2 User/Cell

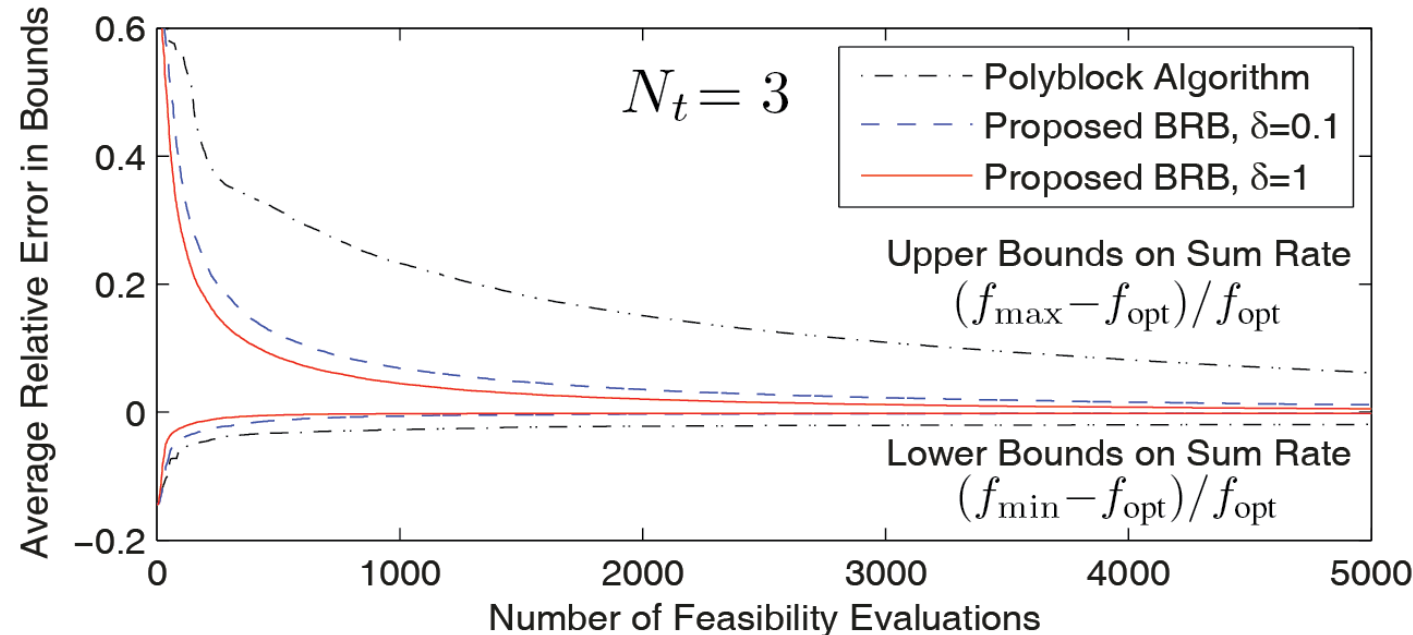
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Spherical uncertainty sets: $\mathbf{B}_{m,i,j} = \sqrt{\xi}\mathbf{I}_{N_t}$

• Convergence of Lower/Upper Bounds

- Compared with *Polyblock algorithm*
- Plot relative error of lower/upper bounds
- BRB algorithm has faster convergence
- Accurate fairness-profile not necessary



Summary

- Robust Coordinated Beamforming
 - Generally NP-hard \leftrightarrow Suboptimal strategies in practice
- Contribution: Computational Framework
 - Enables benchmarking and analysis
 - Robustness and general performance measures/constraints
- Fairness-Profile Optimization
 - Special case solved in polynomial time: Even with robustness
 - Subproblem of general algorithm
- Branch-Reduce-and-Bound Algorithm
 - Systematic algorithm for the general problem
 - Guaranteed to find global solution
 - More general and better convergence than previous work

Extensions

- Journal Article

- E. Björnson, G. Zheng, M. Bengtsson, B. Ottersten, *"Robust Monotonic Optimization Framework for Multicell MISO Systems,"* IEEE Transactions on Signal Processing, Under Minor Revision, arXiv:1104.5240v2.
- Contains all mathematical details
- Extension 1: All channels can be uncertain
- Extension 2: Applicable whenever subproblem can be solved efficiently

Thank You for Listening!

Questions?

Papers and Presentations Available:
<http://www.ee.kth.se/~emilbjo>