

Task 10.1

Implement the system

$$y_k + a y_{k-1} = b u_{k-1} + e_k$$

where:

- e_k is white Gaussian zero-mean noise with variance λ^2
- the input is computed through a state-feedback law $u_k = -K y_k + r_k$ with r_k a reference signal
- K is so that the closed loop system in the absence of the reference signal is asymptotically stable, and the mode of the system is non-oscillatory
- r_k , for the sake of this assignment, is another white Gaussian zero-mean noise with variance σ^2

```
In [44]: # importing the right packages
import numpy as np
import matplotlib.pyplot as plt
import scipy.optimize as optimize
```

```
In [45]: # Function to simulate the system
def simulate(a, b, K, lambda2, sigma2, y0, N, reference_frequency=0):
    # Storage allocation
    y = np.zeros(N)
    u = np.zeros(N)

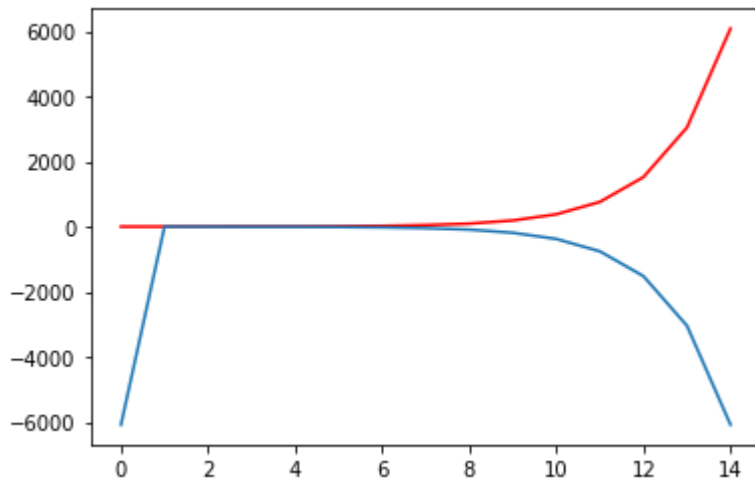
    # system noises
    e = np.random.normal(0, np.sqrt(lambda2), N)
    r = np.random.normal(0, np.sqrt(sigma2), N) + \
        np.sin(reference_frequency * np.arange(N))

    # Saving the initial condition
    y[0] = y0
    u[0] = - K * y0 + r[0]

    # Cycle on the steps
    for t in range(1, N):
        y[t] = b * u[t-1] + e[t] - a * y[t-1]
        u[t] = u[0] = - K * y[t] + r[t]

    return [y, u]

sim = simulate(-1, -1, 1, 10, 0, 0, 15)
plt.plot(sim[0], 'r')
plt.plot(sim[1])
plt.show()
```



```
In [46]: # define also a function for doing poles allocation, considering
# that eventually if the reference is absent then the ODE is
#
#  $y_k + (a + bK) y_{k-1} = e_k$ 
# pole at  $H(q) = 1/A(q)$ ,  $A(q) = (a + bK)q^{-1}$ ,  $\Rightarrow 1 + a + bK = 1 - \text{desired} = 0$ 
def compute_gain(a, b, desired_pole_location):
    K = - (desired_pole_location + a) / b
    return K
```

```
In [47]: # plotting of the impulse response
def plot_impulse_response(a, b, plot_args, figure_number=1000):
    # ancillary quantities
    k = range(0, 50)
    y = b * np.power(-a, k)

    # plotting the various things
    plt.figure(figure_number, **plot_args)
    plt.plot(y, 'r-', label='u')
    plt.xlabel('time')
    plt.title('impulse response relative to a = {} and b = {}'.format(a, b))
```

```
In [39]: # define the system parameters
a = -0.5
b = 2
K = compute_gain(a, b, 0.7)

# noises
lambda2 = 0.1 # on e
sigma2 = 0.1 # on r

# initial condition
y0 = 3

# number of steps
N = 100
```

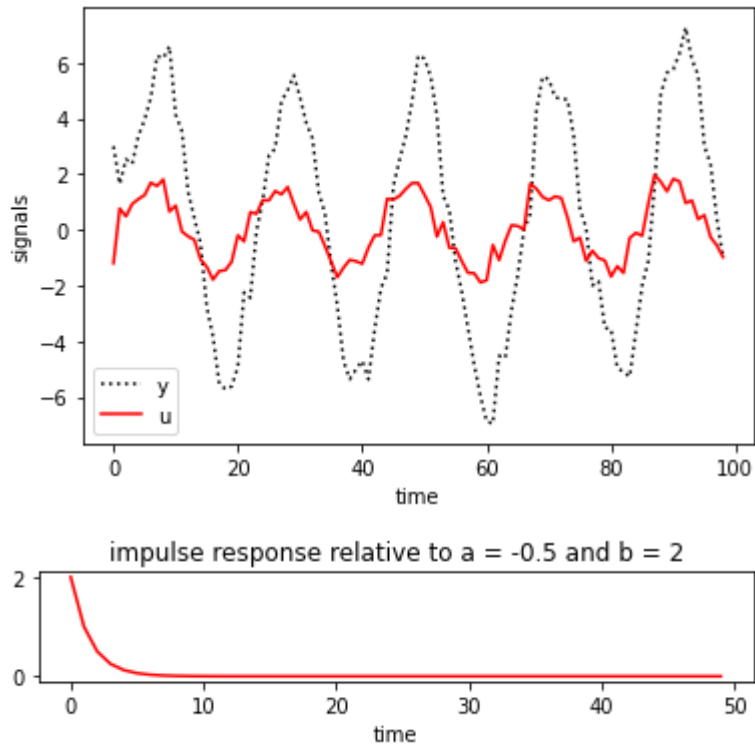
```
In [26]: # DEBUG - check that things work as expected

# run the system
y, u = simulate(a, b, K, lambda2, sigma2, y0, N, 0.3)

# plotting the various things
plt.figure()
plt.plot(y[:-1], 'k:', label='y')
```

```
plt.plot(u[:-1], 'r-', label='u')
plt.xlabel('time')
plt.ylabel('signals')
plt.legend();

plot_impulse_response(a, b, {'figsize': (6.4, 1)})
```



Task 10.2

Implement a PEM-based approach to the estimation of the system, assuming to know the correct model structure but not knowing about the existence of the feedback loop given by $\$K\$$.

```
In [27]: # important: the system is an ARX one, and e_k is Gaussian so PEM = ???
# And given this, how can we simplify things?
```

```
In [41]: # define the function solving the PEM problem asked in the assignment
def PEM_solver(u, y):
    yu_prev = np.zeros((len(y) - 1, 2))
    yu_prev[:, 0] = y[:-1]
    yu_prev[:, 1] = - u[:-1]
    rhs = - np.array(y[1:])
    # Compute the PEM estimate, should have used normal eqs.
    a_hat, b_hat = np.linalg.lstsq(yu_prev, rhs, rcond=None)[0]
    return a_hat, b_hat
```

```
In [36]: # compute the solution
a_hat, b_hat = PEM_solver(u, y)

# assess the performance
MSE = np.linalg.norm([a - a_hat, b - b_hat])**2

# print debug info
```

```
print('MSE: {}'.format(MSE))
print('a, b = {}, {} -- ahat, bhat = {}, {}'.format(a, b, a_hat, b_hat))
```

```
MSE: 0.0003191037492320515
```

```
a, b = -0.5, 2 -- ahat, bhat = -0.510246025584857, 1.9853670676572839
```

Task 10.3

Show from a numerical perspective that for $\lambda^2 = 0.1$ (i.e., a constant variance on the process noise) the estimates are consistent.

In [65]:

```
# the best way to show this is to do a Monte Carlo approach:
# - for each N, compute the distribution of the estimates
# around the true parameters
# - increase N and show that this distribution tends to
# converge to the true parameters

# defining the MC simulation
N_MC_runs = 100
min_order_for_N = 1
max_order_for_N = 4
num_of_N_orders = max_order_for_N - min_order_for_N + 1

# noises and initial condition
lambda2 = 0.1 # on e
sigma2 = 0.1 # on r
y0 = 0

# storage allocation
MSEs = np.zeros((num_of_N_orders, N_MC_runs))
#theta_hats = np.zeros((num_of_sigma2_orders, N_MC_runs, 2))
theta_hats = np.zeros((num_of_N_orders, N_MC_runs, 2))

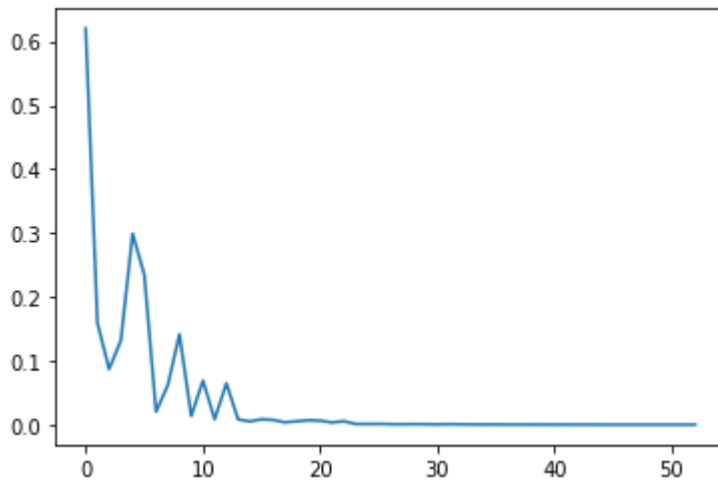
# cycle on the number of samples
for j, N in enumerate(np.logspace(min_order_for_N, max_order_for_N, num_of_N_orders)):
    # MC cycles
    for m in range(N_MC_runs):
        # simulate the system
        y, u = simulate(a, b, K, lambda2, sigma2, y0, int(N), 0.3)
        # compute the solution
        a_hat, b_hat = PEM_solver(u, y)

        # assess the performance
        MSEs[j, m] = np.linalg.norm([a - a_hat, b - b_hat])**2
        # save the results
        theta_hats[j, m, 0] = a_hat
        theta_hats[j, m, 1] = b_hat
```

In [63]:

```
plt.plot([np.mean(MSEs[j, :]) for j in range(MSEs.shape[0])])
```

Out[63]: [

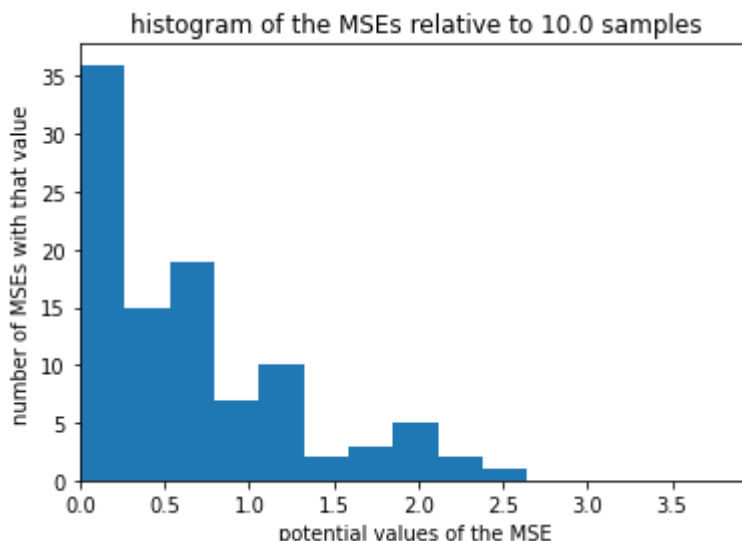


In [66]:

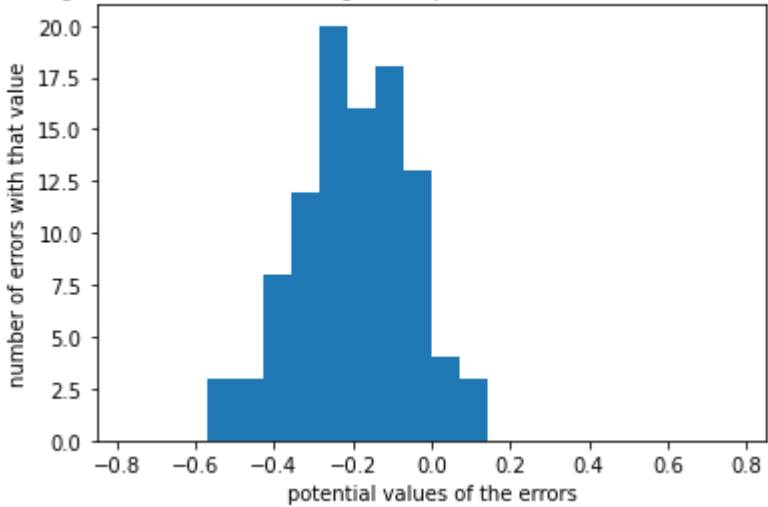
```
# cycle on the number of samples
for j, N in enumerate(np.logspace( min_order_for_N, max_order_for_N, num_of_N)):
    # plot the histogram of the MSEs relative to this number of samples
    plt.figure(j)
    plt.hist(MSEs[j,:])
    plt.xlim(0, 1.5 * np.max(MSEs[j,:]))
    plt.title('histogram of the MSEs relative to {} samples'.format(N))
    plt.xlabel('potential values of the MSE')
    plt.ylabel('number of MSEs with that value')

    # plot the histogram of the errors along the a parameter
    plt.figure(j + 100)
    x_lim = np.max(np.abs(theta_hats[j,:,0] - a))
    plt.hist(theta_hats[j,:,0] - a)
    plt.xlim(-1.5 * x_lim, 1.5 * x_lim)
    plt.title('histogram of the errors along the a parameter relative to {} s'.format(N))
    plt.xlabel('potential values of the errors')
    plt.ylabel('number of errors with that value')

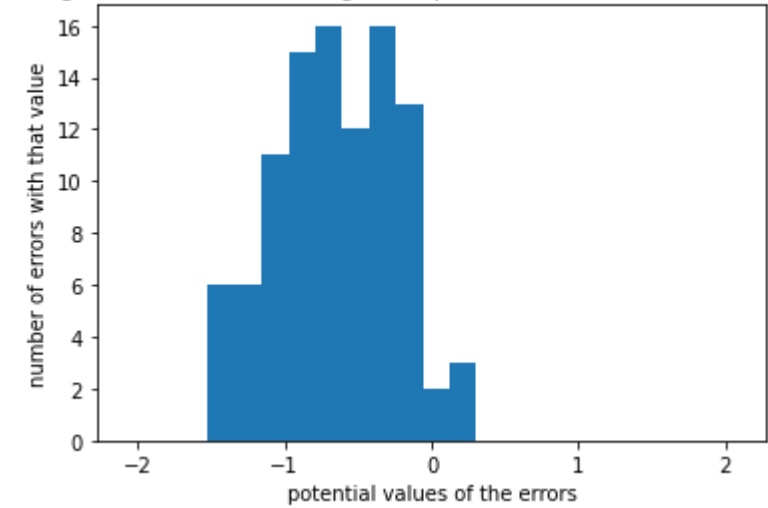
    # plot the histogram of the errors along the b parameter
    plt.figure(j + 200)
    x_lim = np.max(np.abs(theta_hats[j,:,1] - b))
    plt.hist(theta_hats[j,:,1] - b)
    plt.xlim(-1.5 * x_lim, 1.5 * x_lim)
    plt.title('histogram of the errors along the b parameter relative to {} s'.format(N))
    plt.xlabel('potential values of the errors')
    plt.ylabel('number of errors with that value')
```



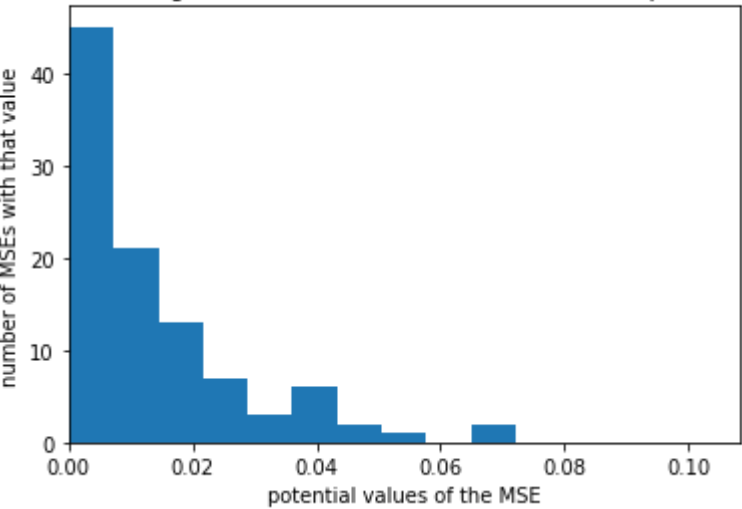
histogram of the errors along the a parameter relative to 10.0 samples



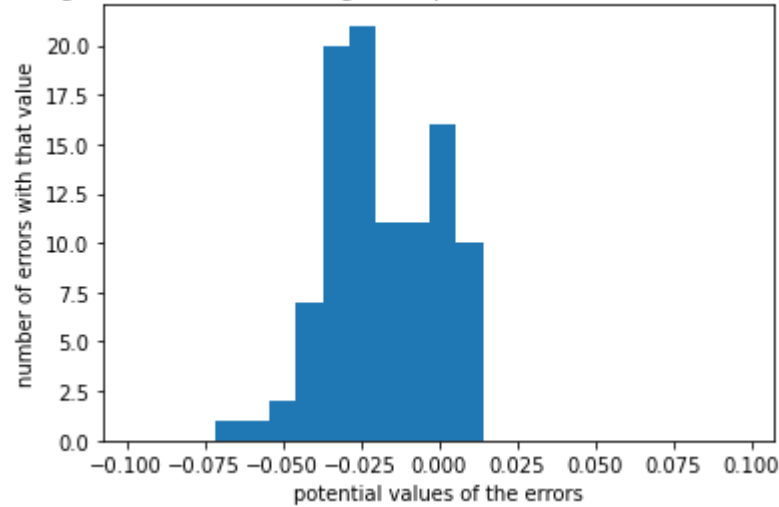
histogram of the errors along the b parameter relative to 10.0 samples



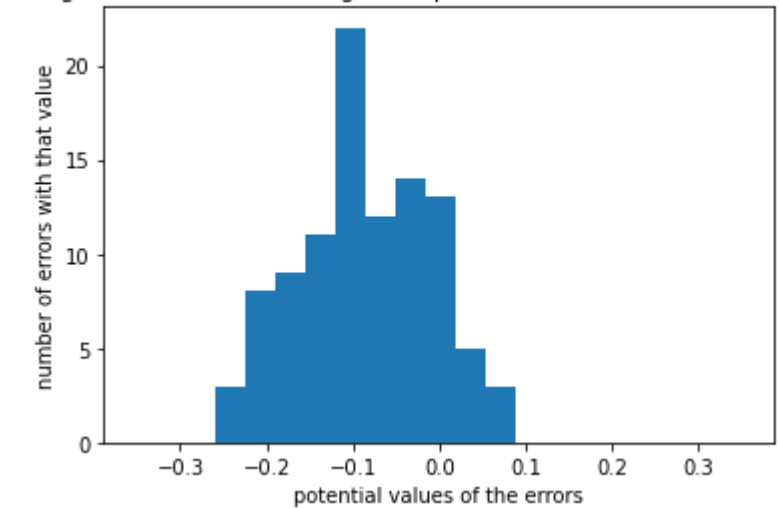
histogram of the MSEs relative to 100.0 samples



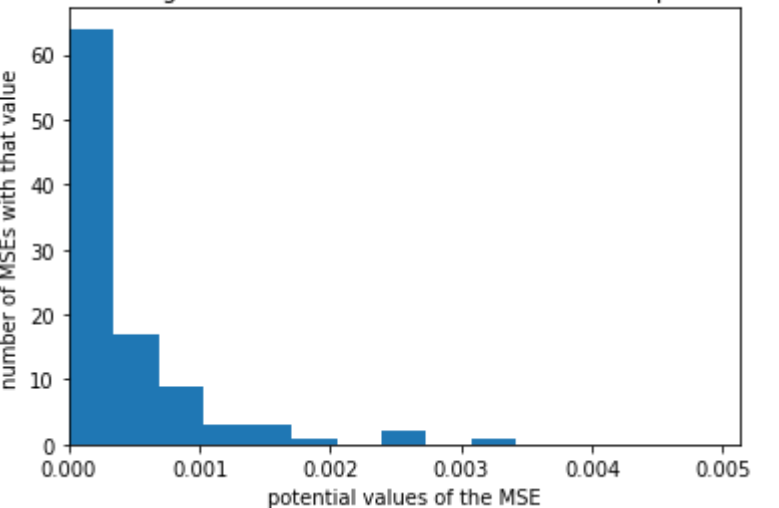
histogram of the errors along the a parameter relative to 100.0 samples



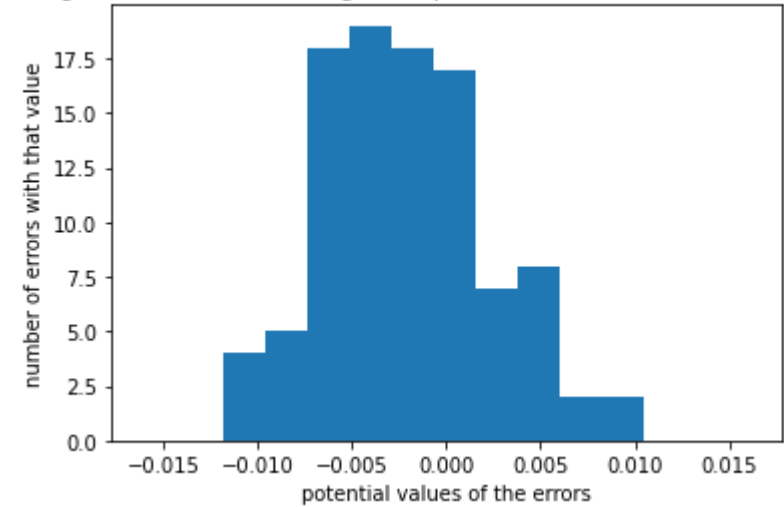
histogram of the errors along the b parameter relative to 100.0 samples



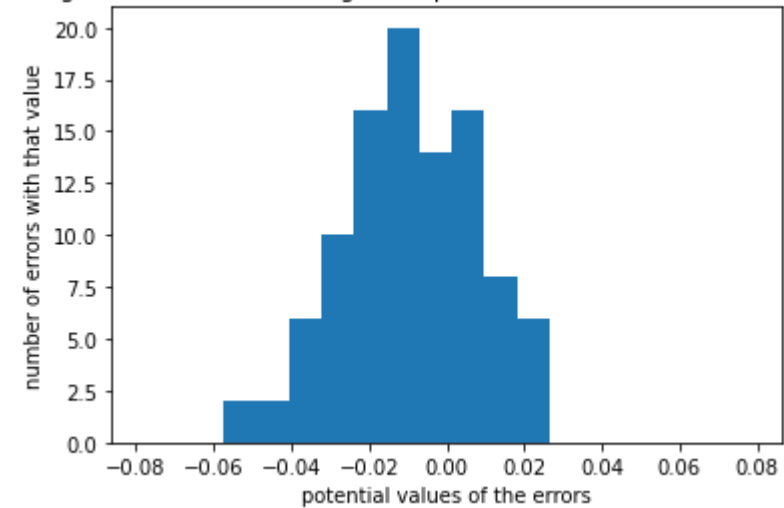
histogram of the MSEs relative to 1000.0 samples



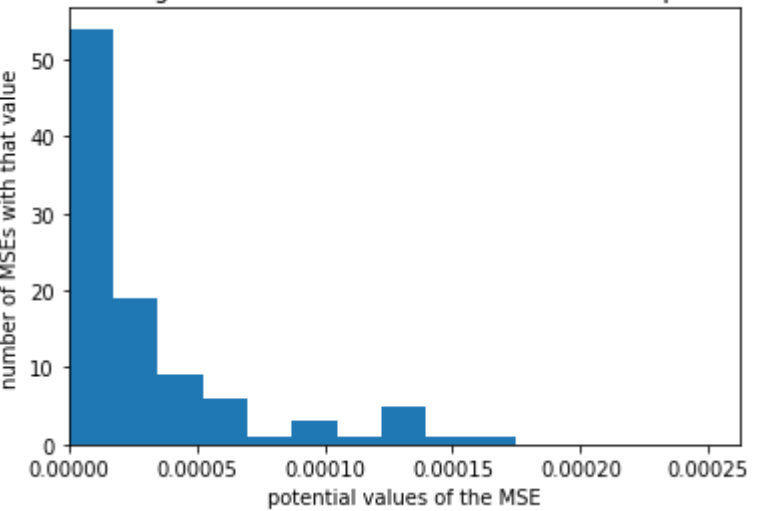
histogram of the errors along the a parameter relative to 1000.0 samples



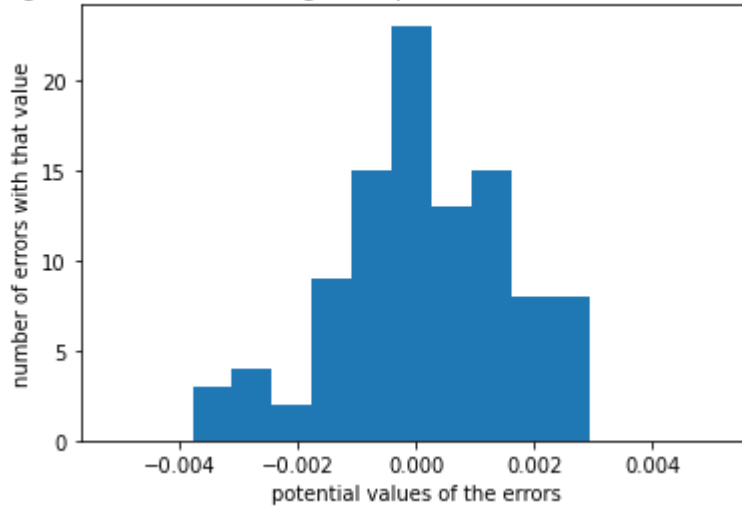
histogram of the errors along the b parameter relative to 1000.0 samples



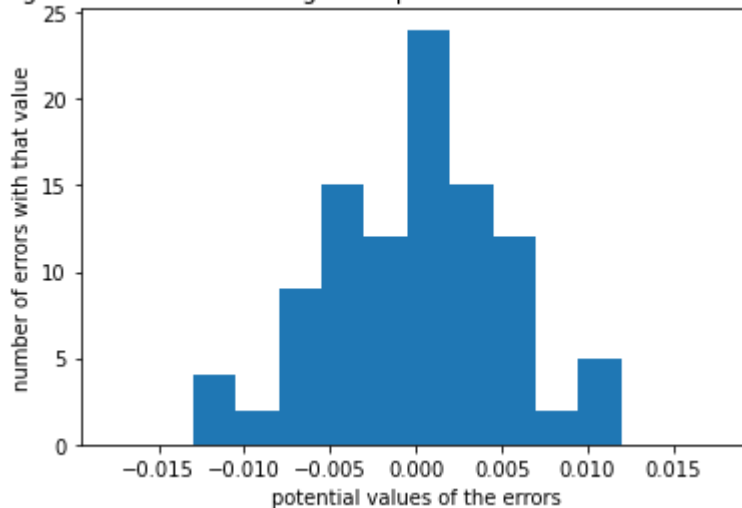
histogram of the MSEs relative to 10000.0 samples



histogram of the errors along the a parameter relative to 10000.0 samples



histogram of the errors along the b parameter relative to 10000.0 samples



Task 10.3

Show that the variances of the estimates though will tend to infinity as $\sigma^2 \rightarrow 0$, i.e., the reference becomes a deterministic known signal.

```
In [84]: # again the best way to show this is to do a Monte Carlo approach:
# - for each sigma2, compute the distribution of the estimates
#   around the true parameters
# - diminish sigma2 and show that this distribution tends to
#   diverge

# defining the MC simulation
N = 100
N_MC_runs = 100
min_order_for_sigma2 = -10
max_order_for_sigma2 = 10
num_of_sigma2_orders = max_order_for_sigma2 - min_order_for_sigma2 + 1

# noises and initial condition
lambda2 = 0.1 # on e
y0 = 0

# storage allocation
MSEs = np.zeros((num_of_sigma2_orders, N_MC_runs))
theta_hats = np.zeros((num_of_sigma2_orders, N_MC_runs, 2))
```

```

# cycle on the variance of the measurement noise
for j, sigma2 in enumerate(np.logspace(min_order_for_sigma2, max_order_for_sigma2, N_MC_runs)):
    # MC cycles
    for m in range(N_MC_runs):
        # simulate the system
        y, u = simulate(a, b, K, lambda2, sigma2, y0, N, 0.3)
        # compute the solution
        a_hat, b_hat = PEM_solver(u, y)
        # assess the performance
        MSEs[j, m] = np.linalg.norm([a - a_hat, b - b_hat])**2
        # save the results
        theta_hats[j, m, 0] = a_hat
        theta_hats[j, m, 1] = b_hat
    print('sigma^2: {}, mean MSE: {}'.format(sigma2, np.mean(MSEs[j, :])))

```

```

sigma^2: 1e-10, mean MSE: 0.015564968610855765
sigma^2: 1e-09, mean MSE: 0.014281251170752862
sigma^2: 1e-08, mean MSE: 0.01465343419593655
sigma^2: 1e-07, mean MSE: 0.015459301646150789
sigma^2: 1e-06, mean MSE: 0.015481844746281453
sigma^2: 1e-05, mean MSE: 0.012057170858130779
sigma^2: 0.0001, mean MSE: 0.01696524395496719
sigma^2: 0.001, mean MSE: 0.016762080444981925
sigma^2: 0.01, mean MSE: 0.01515164840405222
sigma^2: 0.1, mean MSE: 0.013155274666114925
sigma^2: 1.0, mean MSE: 0.003349299554562071
sigma^2: 10.0, mean MSE: 0.0015481262567580531
sigma^2: 100.0, mean MSE: 0.0022939907841216804
sigma^2: 1000.0, mean MSE: 0.0020069557037689094
sigma^2: 10000.0, mean MSE: 0.0011657358052547208
sigma^2: 100000.0, mean MSE: 0.001472325270924003
sigma^2: 1000000.0, mean MSE: 0.0019061305105055484
sigma^2: 10000000.0, mean MSE: 0.001248338832911906
sigma^2: 100000000.0, mean MSE: 0.0014276196260910518
sigma^2: 1000000000.0, mean MSE: 0.0020755373746351572
sigma^2: 10000000000.0, mean MSE: 0.00342740898455812

```

In [83]:

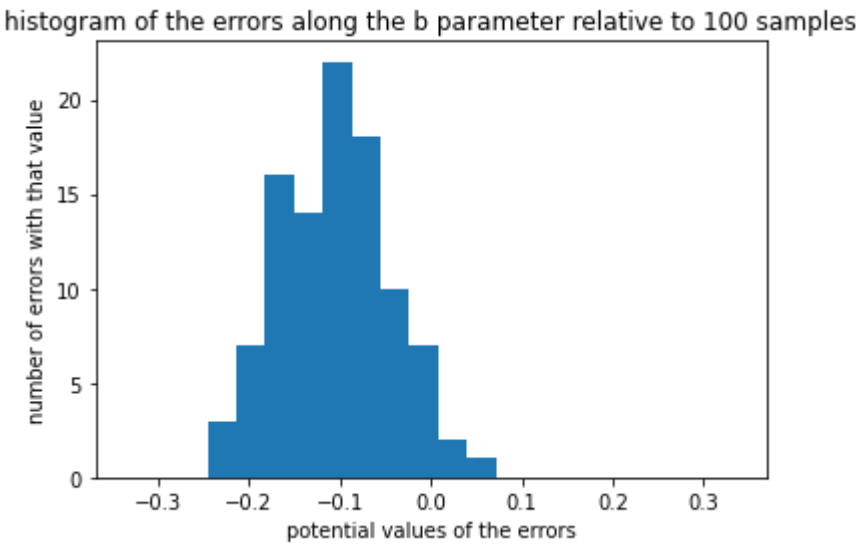
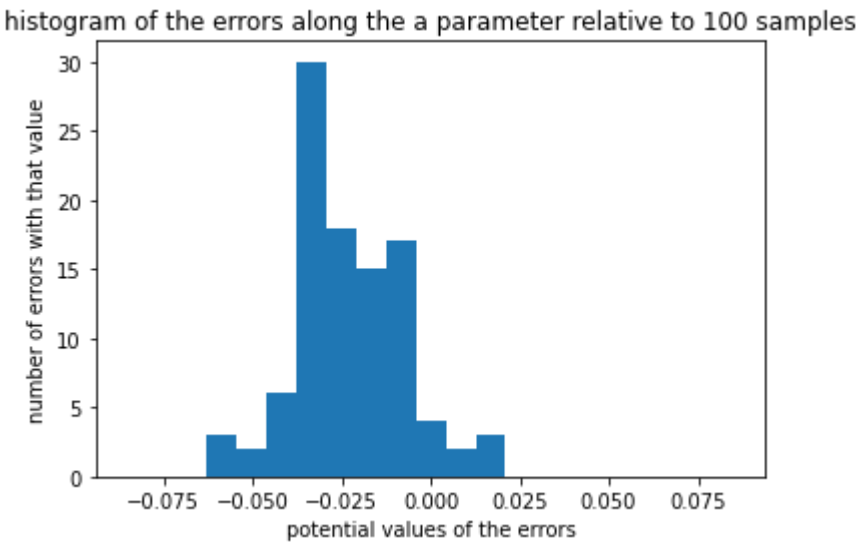
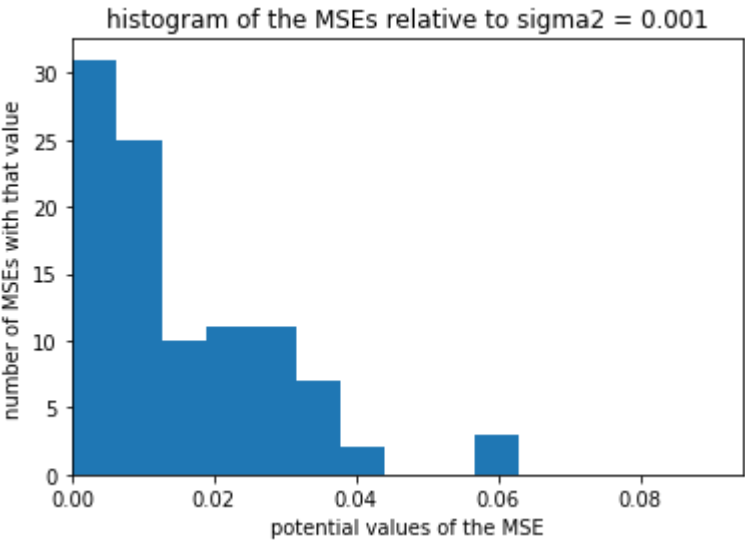
```

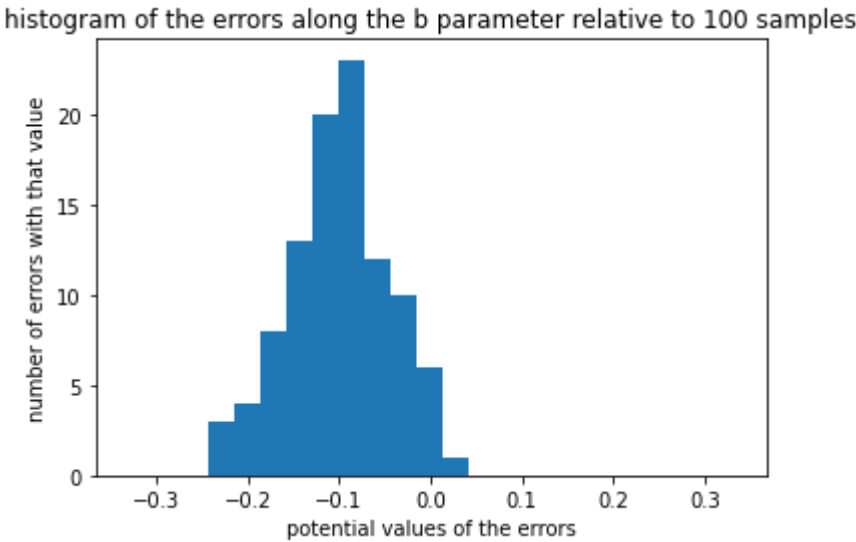
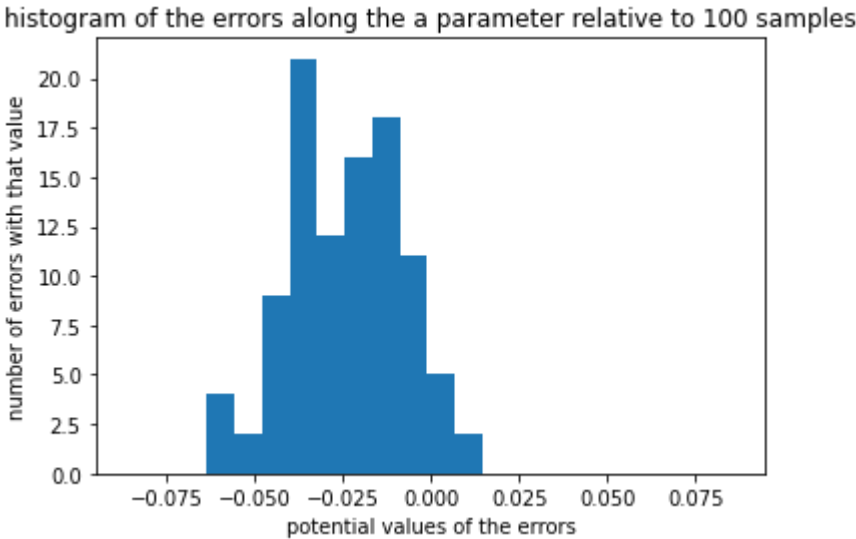
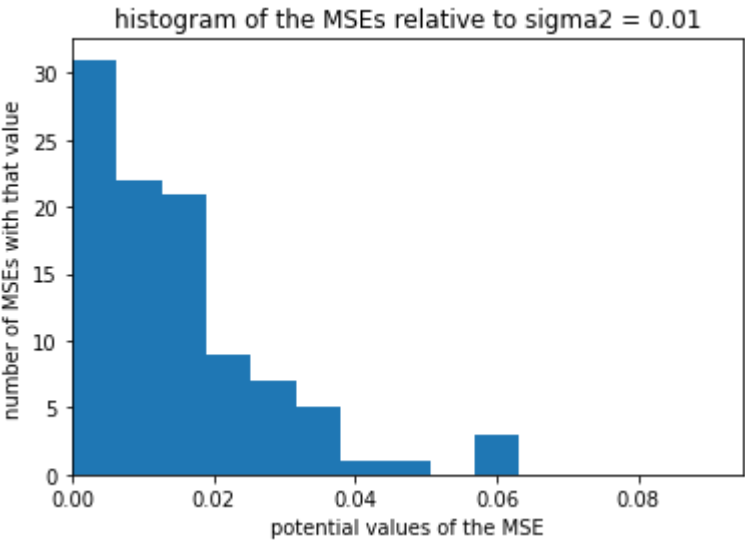
# cycle on the variance of the measurement noise
for j, sigma2 in enumerate(np.logspace(min_order_for_sigma2, max_order_for_sigma2, N_MC_runs)):
    # plot the histogram of the MSEs relative to this number of samples
    plt.figure(j)
    plt.hist(MSEs[j,:])
    plt.xlim(0, 1.5 * np.max(MSEs[j,:]))
    plt.title('histogram of the MSEs relative to sigma2 = {}'.format(sigma2))
    plt.xlabel('potential values of the MSE')
    plt.ylabel('number of MSEs with that value')

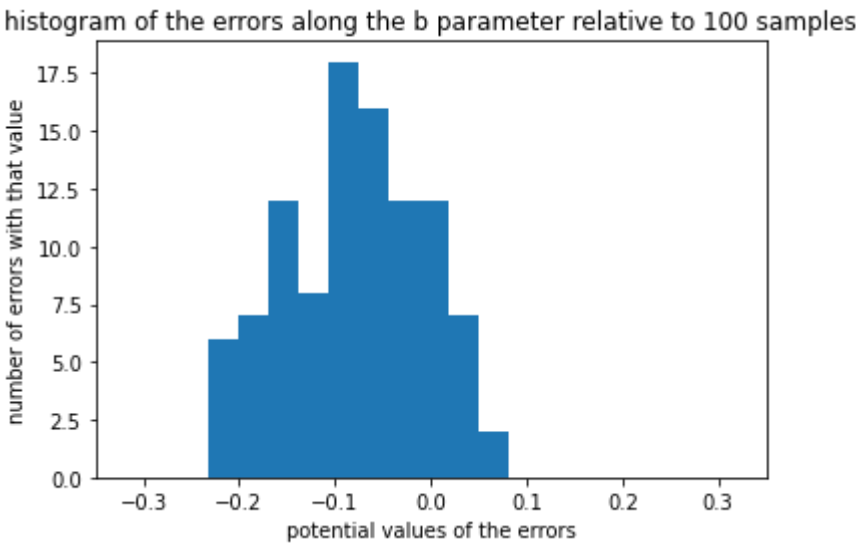
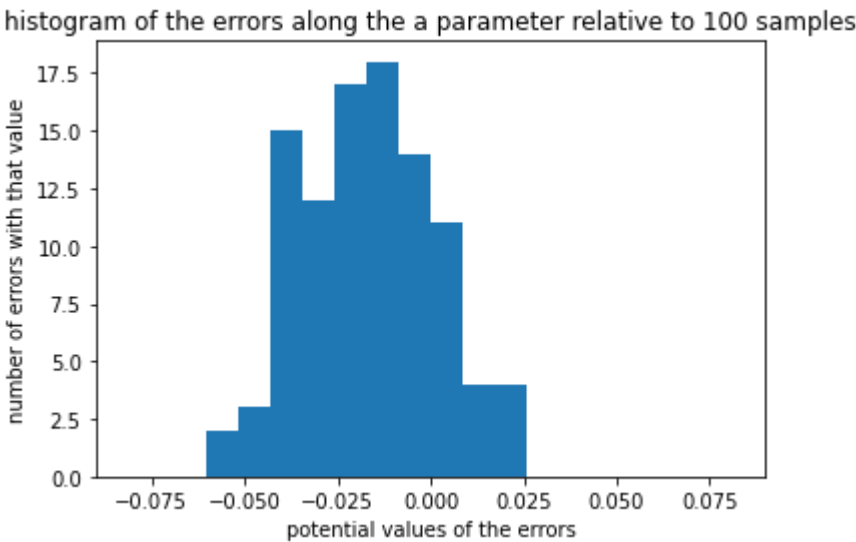
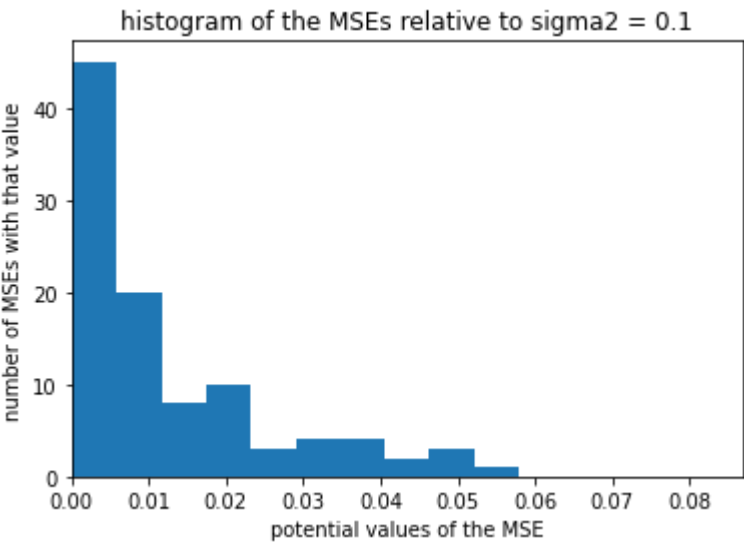
    # plot the histogram of the errors along the a parameter
    plt.figure(j + 100)
    x_lim = np.max(np.abs(theta_hats[j,:,0] - a))
    plt.hist(theta_hats[j,:,0] - a)
    plt.xlim(-1.5 * x_lim, 1.5 * x_lim)
    plt.title('histogram of the errors along the a parameter relative to {} samples'.format(N))
    plt.xlabel('potential values of the errors')
    plt.ylabel('number of errors with that value')

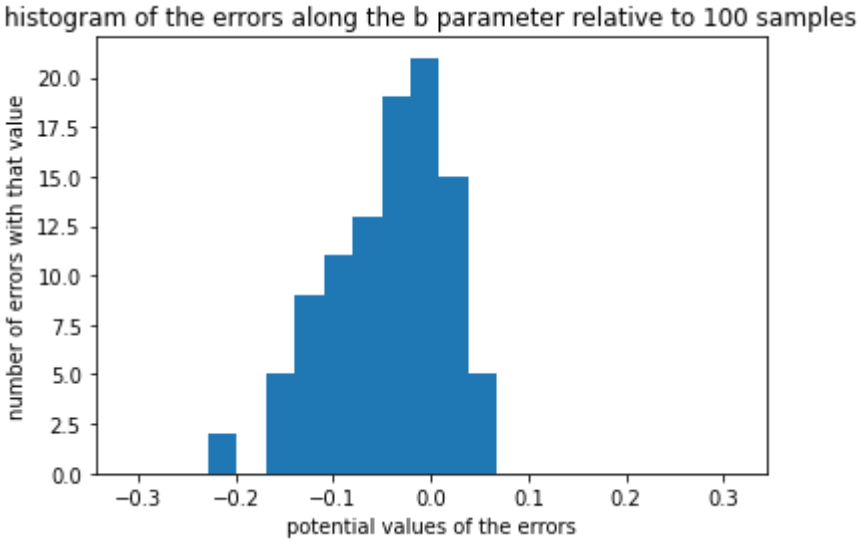
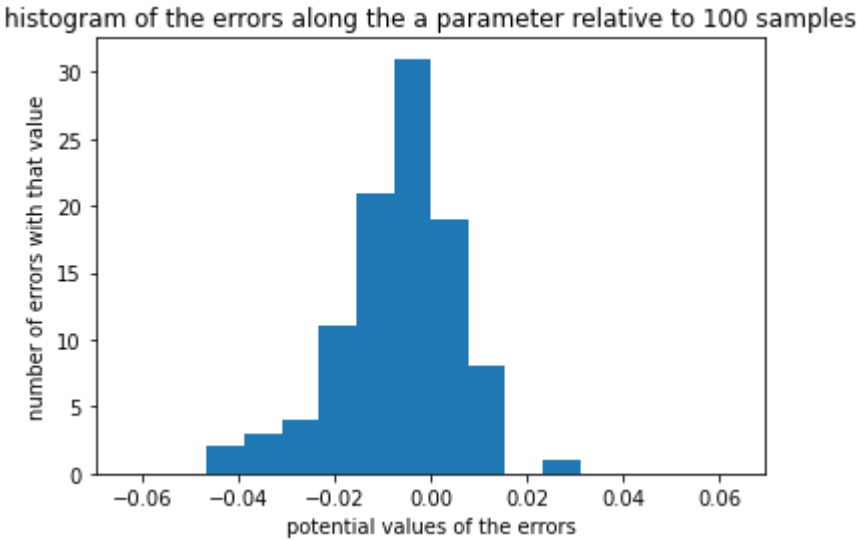
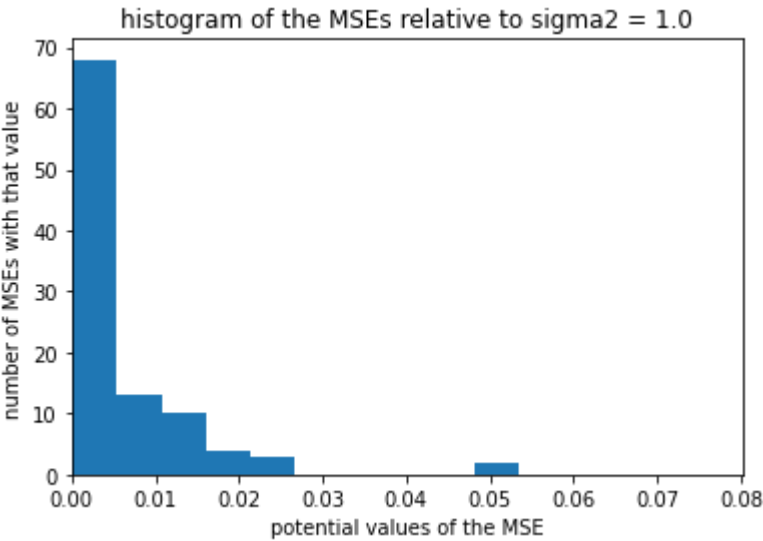
    # plot the histogram of the errors along the b parameter
    plt.figure(j + 200)
    x_lim = np.max(np.abs(theta_hats[j,:,1] - b))
    plt.hist(theta_hats[j,:,1] - b)
    plt.xlim(-1.5 * x_lim, 1.5 * x_lim)
    plt.title('histogram of the errors along the b parameter relative to {} samples'.format(N))
    plt.xlabel('potential values of the errors')
    plt.ylabel('number of errors with that value')

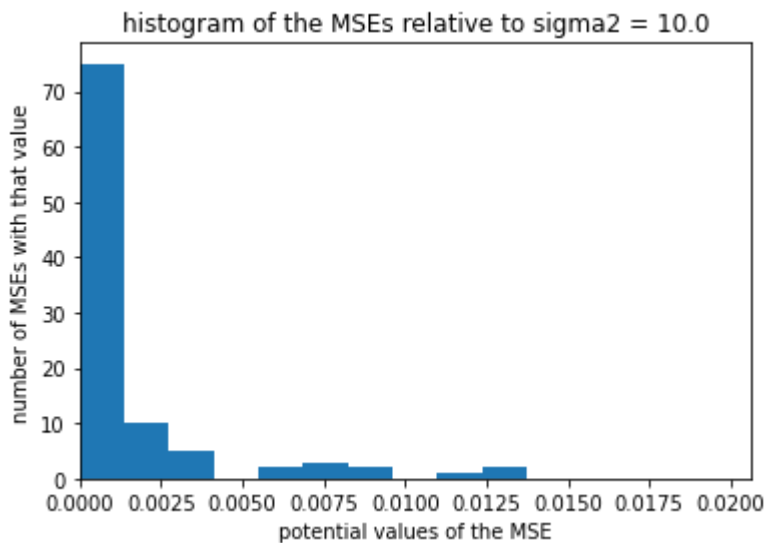
```



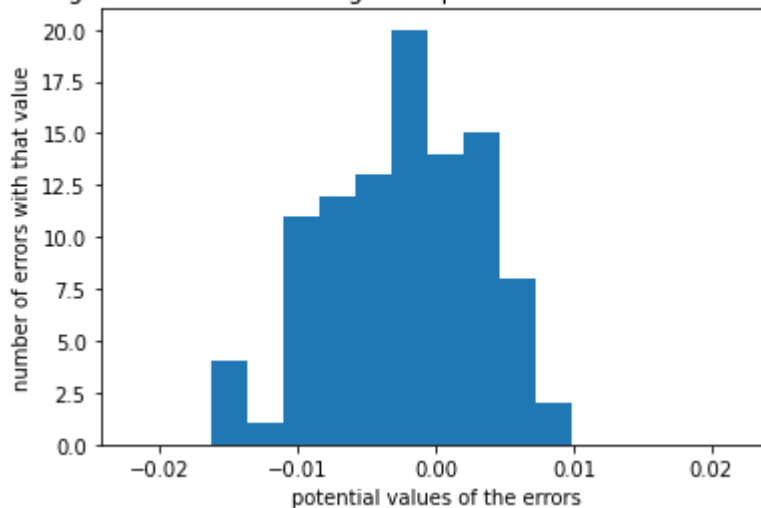




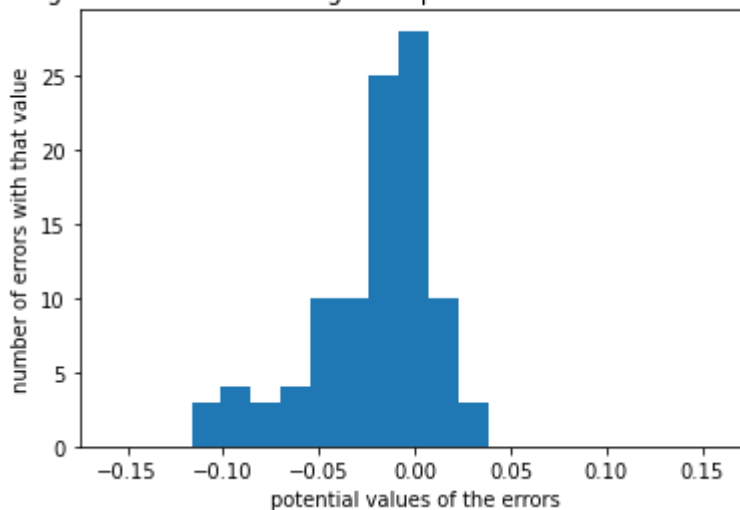




histogram of the errors along the a parameter relative to 100 samples



histogram of the errors along the b parameter relative to 100 samples



Task 10.4

Comment what you think is a remarkable fact relative to the simulations above.

The variance of the estimates does not approach infinity when $\sigma^2 \rightarrow 0$, but might have the potential to converge to infinity at sufficiently small σ^2 . Notice the minimum and maximum values MSE recorded:

σ^2 : 1000000000.0, mean MSE: 0.00342740898455812

σ^2 : 1e-10, mean MSE: 0.015564968610855765

These MSEs are not close to 0 or ∞ , but shows that large values for σ^2 gives lower MSE than small values for σ^2

In []: