



INSTITUTO POLITÉCNICO NACIONAL
ESCUELA SUPERIOR DE CÓMPUTO



INTRODUCCIÓN A LOS MICROCONTROLADORES

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“INTERRUPCIONES INT0, INT1 E INT2”

GRUPO: 3CM10

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1 | DIAGRAMAS

2 | CÓDIGO

```
.include "m8535def.inc"
.def d = R16

rjmp main
rjmp m1
rjmp m2
.org $12
rjmp m3

main:
    ldi d, low(ramend)
    out spl,d
    ldi d, high(ramend)
    out sph,d
    ser d
    out ddrc,d
    out ddra,d
    out portb,d
    out portd,d
    ldi d,2
    out mcucr,d
    ldi d,$e0
    out gicr,d
    sei
    ldi d,$76 ; -
    mov r0,d ; -H
    ldi d,$86
    mov r5,d ; -I
    ldi d,$3F ; - O
    mov r4,d
    ldi d,$38 ; - L
    mov r3,d
    ldi d,$38 ; - L
    mov r2,d
    ldi d,$79 ; - E
    mov r1,d
    clr zh
```

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barre:
    ldi z1,5
    ldi d,$20
sigue:
    out portc,d
    ld r17,z
    out porta, r17
    rcall delay
    out porta,zh
    in d,pinc
    lsr d
    dec z1
    brpl sigue
    rjmp barre
m1:
    ldi d,$30 ;-- -
    mov r0,d ; -I
    ldi d,$08
    mov r5,d ; -
    ldi d,$6D ; -S
    mov r4,d
    ldi d,$30 ; -I
    mov r3,d
    ldi d,$08 ; _
    mov r2,d
    ldi d,$78 ; -T
    mov r1,d
    reti
m2:
    ldi d,$08 ; -
    mov r0,d ; _
    mov r5,d ; _
    ldi d,$79 ; E
    mov r4,d
    ldi d,$54 ; -M
    mov r3,d
    ldi d,$74 ; -M
    mov r2,d
    ldi d,$08 ; _
    mov r1,d
    reti

```

```

m3:
    ldi d,$77 ;-- -
    mov r0,d ; -A
    ldi d,$86
    mov r5,d ; -I
    ldi d,$79 ; -E
    mov r4,d
    ldi d,$38 ; - L
    mov r3,d
    ldi d,$79 ; _E
    mov r2,d
    ldi d,$5E ; -D
    mov r1,d
    reti

```

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delay:

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```

    ldi r17,$0b
p0:
    ldi r18,$d3
p1:
    dec r18
    brne p1
    dec r17
    brne p0
    ldi r17,$01
p2:
    dec r17
    brne p2
    nop
ret

```