

Kernel Methods

Kernel Functions

Kernel Ridge Regression

Reproducing Kernel Hilbert Spaces (RKHS) I

Properties of RKHS:

1 Normed Vector Space:

- RKHS is equipped with a well-defined norm $\| \cdot \|$, which satisfies the usual norm properties.

2 Completeness (Banach Space):

- The space is complete, meaning it behaves nicely in the sense that every Cauchy sequence in the space converges to an element within the space.

3 Inner Product Space:

- RKHS has an inner product $\langle \cdot, \cdot \rangle$, and the norm is induced by this inner product, i.e. $\|\mathbf{x}\| = \sqrt{\langle \mathbf{x}, \mathbf{x} \rangle}$. For instance, in \mathbb{R}^N , the inner product between two vectors \mathbf{x} and \mathbf{y} is $\mathbf{x}^T \mathbf{y}$.

Reproducing Kernel Hilbert Spaces (RKHS) II

4 Reproducing Kernel:

- There exists a kernel function $\kappa(\cdot, \mathbf{x})$ that belongs to \mathbb{H} for each $\mathbf{x} \in \mathcal{X}$ and possesses the reproducing property:

$$f(\mathbf{x}) = \langle f, \kappa(\cdot, \mathbf{x}) \rangle \quad \text{for all } f \in \mathbb{H} \text{ and } \mathbf{x} \in \mathcal{X}.$$

- This property implies that the evaluation of any function f at any point \mathbf{x} can be represented as an inner product.

Reproducing Kernel Hilbert Spaces (RKHS) III

Feature Mapping and Kernel Trick:

- *Feature Map*: $\phi(\mathbf{x}) := \kappa(\cdot, \mathbf{x})$ maps each point in \mathcal{X} to a function in \mathbb{H} .
 - Embeds the input data into a higher-dimensional space (potentially infinite-dimensional)
 - Linear algorithms (like inner products) can be applied to solve nonlinear problems in the original space
- The *Kernel Trick* allows inner products in H to be computed as:

$$\langle \phi(\mathbf{x}), \phi(\mathbf{y}) \rangle = \kappa(\mathbf{x}, \mathbf{y})$$

This simplifies computations by replacing inner product calculations with kernel evaluations.

Example

Dimensional Mapping:

- Maps two-dimensional vectors from \mathbb{R}^2 into a three-dimensional space \mathbb{R}^3 .
- Transformation:

$$\phi(\mathbf{x}) = [x_1^2, \sqrt{2}x_1x_2, x_2^2]$$

Inner Product in Transformed Space:

- Inner product between $\phi(\mathbf{x})$ and $\phi(\mathbf{y})$ in \mathbb{R}^3 :

$$\phi(\mathbf{x})^T \phi(\mathbf{y}) = x_1^2 y_1^2 + 2x_1 x_2 y_1 y_2 + x_2^2 y_2^2 = (\mathbf{x}^T \mathbf{y})^2$$

- Shows that the inner product in \mathbb{R}^3 is the square of the inner product in \mathbb{R}^2 .

Examples of Kernel Functions I

- **Gaussian Kernel:**

$$\kappa(\mathbf{x}, \mathbf{y}) = \exp\left(-\frac{\|\mathbf{x} - \mathbf{y}\|^2}{2\sigma^2}\right)$$

- **Polynomial Kernels:**

- *Homogeneous:* $\kappa(\mathbf{x}, \mathbf{y}) = (\mathbf{x}^T \mathbf{y})^r$
- *Inhomogeneous:* $\kappa(\mathbf{x}, \mathbf{y}) = (\mathbf{x}^T \mathbf{y} + c)^r$

- **Laplacian Kernel:**

$$\kappa(\mathbf{x}, \mathbf{y}) = \exp(-t\|\mathbf{x} - \mathbf{y}\|)$$

Kernel Construction:

- Kernels can be combined, modified, or constructed to fit specific needs.

Kernel Ridge Regression in RKHS I

Problem Setup:

- Nonlinear regression task modeled as:

$$y_n = g(\mathbf{x}_n) + \eta_n$$

- Estimate f as:

$$f(\mathbf{x}) = \sum_{n=1}^N \theta_n \kappa(\mathbf{x}, \mathbf{x}_n)$$

Objective Function:

- Minimize the following loss function:

$$J(\boldsymbol{\theta}) = (\mathbf{y} - \mathcal{K}\boldsymbol{\theta})^T (\mathbf{y} - \mathcal{K}\boldsymbol{\theta}) + C\boldsymbol{\theta}^T \mathcal{K}^T \boldsymbol{\theta}$$

where \mathcal{K} is the kernel matrix, C is the regularization parameter.

Kernel Ridge Regression in RKHS II

Solution:

- The solution to the minimization problem is given by:

$$(\mathcal{K}^T \mathcal{K} + C \mathcal{K}^T) \hat{\boldsymbol{\theta}} = \mathcal{K}^T \mathbf{y}$$

$$(\mathcal{K} + C I) \hat{\boldsymbol{\theta}} = \mathbf{y}$$

Prediction:

- For an unknown vector $\mathbf{x} \in R^l$, the prediction is:

$$\hat{\mathbf{y}} = \hat{\boldsymbol{\theta}}^T \kappa(\mathbf{x})$$

$$\hat{\mathbf{y}}(\mathbf{x}) = \mathbf{y}^T (\mathcal{K} + C I)^{-1} \kappa(\mathbf{x})$$

Exercise 12I

- 1 Generate points for two classes
- 2 Apply non-linear transformation
 - `PHI = np.vstack((X[:, 0]**2, 2**0.5*X[:, 0]*X[:, 1], X[:, 1]**2)).T`
- 3 Calculate the homogeneous polynomial kernel matrix
 - ```
for i in range(2*N):
 for j in range(2*N):
 K[i, j] = (X[i, :] @ X[j, :])**r
```
- 4 Apply representer theorem with  $\theta = \mathbf{0}$

# Exercise 12 II

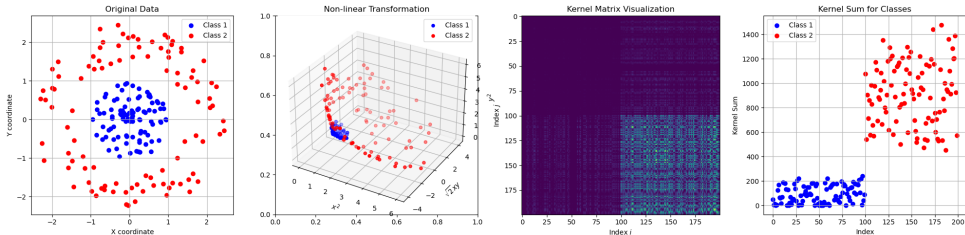


Figure: Homogeneous polynomial kernel

# Exercise 12 III

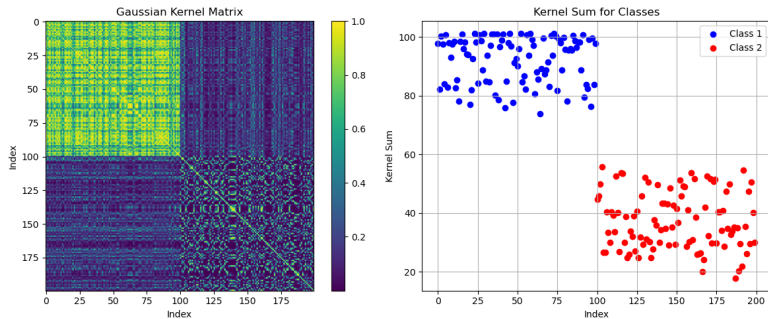


Figure: Gaussian kernel  $\sigma = 1$

# Exercise 12 IV

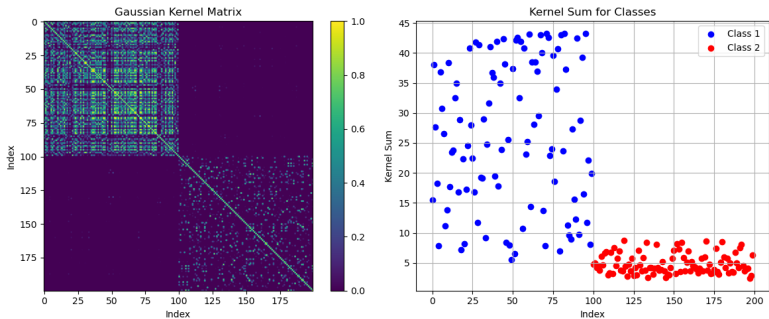


Figure: Gaussian kernel  $\sigma = 0.1$